



MITSUBISHI

PROGRAMMABLE CONTROLLERS
MELSEC-F

Changes for the Better

Additional Product Support Version

- FX3U Series
 - Inverter Communication
(F700/A700/E700 Series)
-
- N:N Network
 - Parallel Link
 - Computer Link
 - Inverter Communication
 - Non-Protocol Communication
 - Programming Communication
 - Remote Maintenance

USER'S MANUAL - Data Communication Edition

FX SERIES PROGRAMMABLE CONTROLLERS



RS-232C Interface

FX3U-232-BD
FX3U-232ADP(-MB)
FX2N-232-BD
FX2NC-232ADP
FX1N-232-BD
FX0N-232ADP
FX-232ADP
FX2N-232IF

RS-485 Interface

FX3U-485-BD
FX3U-485ADP(-MB)
FX2N-485-BD
FX2NC-485ADP
FX1N-485-BD
FX0N-485ADP
FX-485ADP

RS-485/232C Converter

FX-485PC-IF

RS-422 Interface

FX3U-422-BD
FX2N-422-BD
FX1N-422-BD



USB Interface



FX3U-USB-BD


Safety Precautions

(Read these precautions before use.)

Before installation, operation, maintenance or inspection of this product, thoroughly read through and understand this manual and all of the associated manuals. Also, take care to handle the module properly and safely.

This manual classifies the safety precautions into two categories:  **DANGER** and  **CAUTION**.


| | |
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|  DANGER | Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury. |
|  CAUTION | Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight personal injury or physical damage. |


Depending on the circumstances, procedures indicated by  **CAUTION** may also cause severe injury.

It is important to follow all precautions for personal safety.

Store this manual in a safe place so that it can be taken out and read whenever necessary. Always forward it to the end user.

1. DESIGN PRECAUTIONS

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|  DANGER |
| <ul style="list-style-type: none">• Make sure to have the following safety circuits outside of the PLC to ensure safe system operation even during external power supply problems or PLC failure. Otherwise, malfunctions may cause serious accidents.<ol style="list-style-type: none">1) Most importantly, have the following: an emergency stop circuit, a protection circuit, an interlock circuit for opposite movements (such as normal vs. reverse rotation), and an interlock circuit (to prevent damage to the equipment at the upper and lower positioning limits).2) Note that when the PLC CPU detects an error, such as a watchdog timer error, during self-diagnosis, all outputs are turned off. Also, when an error that cannot be detected by the PLC CPU occurs in an input/output control block, output control may be disabled. External circuits and mechanisms should be designed to ensure safe machinery operation in such a case.3) Note that the output current of the service power supply for sensors varies depending on the model and the absence/presence of extension blocks. If an overload occurs, the voltage automatically drops, inputs in the PLC are disabled, and all outputs are turned off. External circuits and mechanisms should be designed to ensure safe machinery operation in such a case.4) Note that when an error occurs in a relay, triac or transistor output device, the output could be held either on or off. For output signals that may lead to serious accidents, external circuits and mechanisms should be designed to ensure safe machinery operation in such a case. |

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|  CAUTION |
| <ul style="list-style-type: none">• Do not bundle the control line together with or lay it close to the main circuit or power line. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or power line. Noise may cause malfunctions.• Install module so that excessive force will not be applied to the built-in programming port, power connectors, I/O connectors, communication connectors, or communication cables. Failure to do so may result in wire damage/breakage or PLC failure. |

Safety Precautions

(Read these precautions before use.)

2. WIRING PRECAUTIONS

DANGER

- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to attach the terminal cover, offered as an accessory, before turning on the power or initiating operation after installation or wiring work. Failure to do so may cause electric shock.

CAUTION

- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to abnormal data written to the PLC under the influence of noise:
 - 1) Do not bundle the main circuit line together with or lay it close to the main circuit, high-voltage line or load line. Otherwise, noise disturbance and/or surge induction are likely to take place. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or high-voltage line.
 - 2) Ground the shield wire or shield of the shielded cable at one point on the PLC. However, do not use grounding with heavy electrical systems.
- Make sure to properly wire the FX0N/FX2N Series extension equipment in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should follow the specifications in this manual.
- Make sure to properly wire to the European terminal board in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should be follow the specifications in this manual.
 - Twist the end of strand wire and make sure that there are no loose wires.
 - Do not solder-plate the electric wire ends.
 - Do not connect more than the specified number of wires or electric wires of unspecified size.
 - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

3. STARTUP AND MAINTENANCE PRECAUTIONS

DANGER

- Do not touch any terminal while the PLC's power is on. Doing so may cause electric shock or malfunctions.
- Before cleaning or retightening terminals, cut off all phases of the power supply externally. Failure to do so may cause electric shock.
- Before modifying or disrupting the program in operation or running the PLC, carefully read through this manual and the associated manuals and ensure the safety of the operation. An operation error may damage the machinery or cause accidents.
- Do not change the program in the PLC from two or more peripheral equipment devices at the same time. (i.e. from a programming tool and a GOT) Doing so may cause destruction or malfunction of the PLC program.

CAUTION

- Do not disassemble or modify the PLC. Doing so may cause fire, equipment failures, or malfunctions. For repair, contact your local Mitsubishi Electric distributor.
- Turn off the power to the PLC before connecting or disconnecting any extension cable. Failure to do so may cause equipment failures or malfunctions.
- Turn of the power to the PLC before attaching or detaching the peripheral devices, expansion boards, special adapters, and expansion memory cassette. Failure to do so may cause equipment failures or malfunctions.

FX Series Programmable Controllers

User's Manual [Data Communication Edition]

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|-----------------|-------------|
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| Date | 11/2007 |

Foreword

This manual explains the "serial communication" provided for MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit. Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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| <p>This manual confers no industrial property rights or any rights of any other kind, nor does it confer any patent licenses. Mitsubishi Electric Corporation cannot be held responsible for any problems involving industrial property rights which may occur as a result of using the contents noted in this manual.</p> |
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Outline Precautions

- This manual provides information for the use of the FX3U Series Programmable Controllers. The manual has been written to be used by trained and competent personnel. The definition of such a person or persons is as follows:
 - 1) Any engineer who is responsible for the planning, design and construction of automatic equipment using the product associated with this manual should be of a competent nature, trained and qualified to the local and national standards required to fulfill that role. These engineers should be fully aware of all aspects of safety aspects regarding to automated equipment.
 - 2) Any commissioning or maintenance engineer must be of a competent nature, trained and qualified to the local and national standards required to fulfill the job. These engineers should also be trained in the use and maintenance of the completed product. This includes being familiar with all associated manuals and documentation for the product. All maintenance should be carried out in accordance with established safety practices.
 - 3) All operators of the completed equipment should be trained to use that product in a safe and coordinated manner in compliance with established safety practices. The operators should also be familiar with documentation that is connected with the actual operation of the completed equipment.
- **Note:** the term 'completed equipment' refers to a third party constructed device that contains or uses the product associated with this manual
- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi Electric.
- This product has been manufactured under strict quality control. However when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions into the system.
- When combining this product with other products, please confirm the standards and codes of regulation to which the user should follow. Moreover, please confirm the compatibility of this product with the system, machines, and apparatuses to be used.
- If there is doubt at any stage during installation of the product, always consult a professional electrical engineer who is qualified and trained in the local and national standards. If there is doubt about the operation or use, please consult the nearest Mitsubishi Electric distributor.
- Since the examples within this manual, technical bulletin, catalog, etc. are used as reference; please use it after confirming the function and safety of the equipment and system. Mitsubishi Electric will not accept responsibility for actual use of the product based on these illustrative examples.
- The content, specification etc. of this manual may be changed for improvement without notice.
- The information in this manual has been carefully checked and is believed to be accurate; however, if you notice any doubtful point, error, etc., please contact the nearest Mitsubishi Electric distributor.

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1. Introduction

This manual explains the communication types supported by FX PLCs.
This chapter explains the serial communication (in accordance with RS-232C, RS-485/RS-422), various link communication types, etc. and states the applicable FX PLCs.

1.1 Communication Types

The table below shows the communication types supported by the FX Series.

| Link | | | Reference subsection |
|--------------------------------------|-------------|--|----------------------|
| CC-Link | Function | <ul style="list-style-type: none"> Connects FX PLCs as remote device stations to the CC-Link system whose master station is a MELSEC A/QnA/Q PLC. Constructs a CC-Link system whose master station is an FX PLC. | 1.2.1 |
| | Application | Line control in the decentralized or centralized method and information transfer from/to the host network. | |
| N:N Network | Function | Easily enables data link between FX PLCs. | 1.2.2 |
| | Application | Line control in the decentralized or centralized method. | |
| Parallel link | Function | Easily enables data link between FX PLCs. | 1.2.3 |
| | Application | Line control in the decentralized or centralized method. | |
| Computer link | Function | Connects a personal computer or another computer as the master station, and connects FX PLCs as slave stations. Protocols in a computer support computer link protocol formats 1 and 4. | 1.2.4 |
| | Application | Data acquisition and centralized control. | |
| Inverter communication | Function | Communicates with and controls Mitsubishi inverter FREQROL. | 1.2.5 |
| | Application | Operation monitoring, writing of control values, referencing and changing parameters, etc. | |
| General-purpose serial communication | | | Reference subsection |
| Non-protocol communication | Function | Receives and sends data from/to various pieces of equipment with an RS-232C or RS-485 interface in non-protocol procedures. | 1.2.6 |
| | Application | Data reception and sending from/to a personal computer, bar code reader, printer and other various measuring instruments. | |
| Sequence program | | | Reference subsection |
| Programming communication | Function | Adds an RS-232C and an RS-422 port in addition to the provided RS-422 port in PLCs. | 1.2.7 |
| | Application | Simultaneously connection of two display units, programming tools, etc. | |
| Remote maintenance | Function | Connects with a PLC located in a remote location through a modem and telephone line to enable program transfer and remote monitoring access. | 1.2.8 |
| | Application | Maintenance of sequence programs in FX PLCs. | |

| I/O link | | | Reference subsection |
|---|-------------|--|----------------------|
| CC-Link/LT (built in FX3UC-32MT-LT) | Function | Constructs a CC-Link/LT system whose master station is an FX PLC. | 1.2.9 |
| | Application | Wire-conserving network inside control panel and unit. | |
| AS-i system | Function | Constructs an AS-i (Actuator Sensor Interface) system whose master block is an FX PLC. | 1.2.10 |
| | Application | Wire-conserving network inside control panel and unit | |
| MELSEC I/O link | Function | Installs remote I/O units near I/O equipment in remote locations to conserve wiring. | — |
| | Application | ON/OFF control of I/O equipment in a remote location. | |
| Electronic mail sending | | | Reference subsection |
| Internet mail | Function | Sends internet mail to personal computers and cellular phones using the RS-232C communication in PLCs. | 1.2.11 |
| | Application | Monitoring of unmanned facilities, facilities located in remote locations and facilities inside factories. | |
| Short mail | Function | Sends short mails to cellular phones in the NTT DoCoMo network. | 1.2.12 |
| | Application | Notice of material shortage, error contents, operating time, etc. | |

1.2 Outline and Features of Communication Types

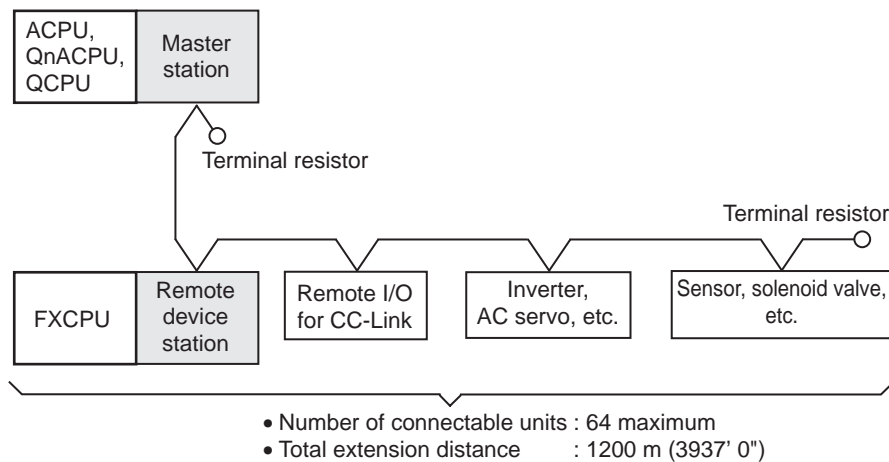
This section outlines the communication types supported by FX PLCs.

1.2.1 CC-Link Network

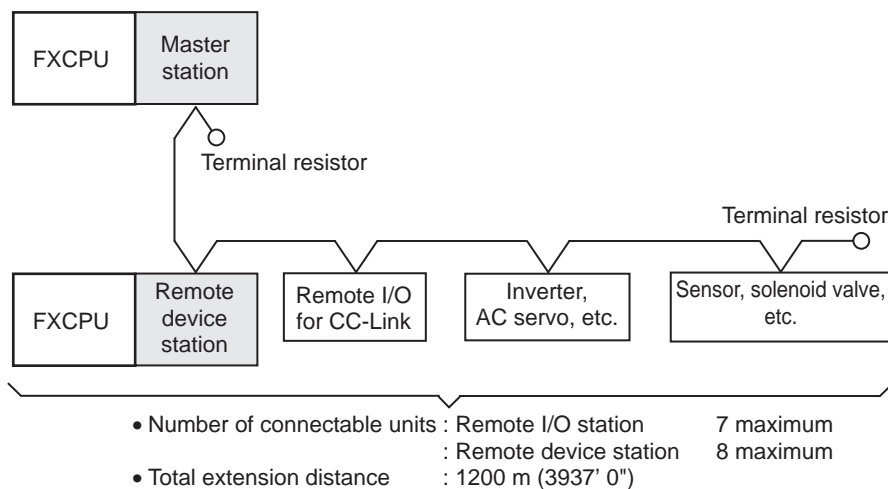
→ Refer to the manual of each special function product.

1. Outline

- 1) When the master station is an A/QnA/Q PLC



- 2) When the master station is an FX PLC



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2c | FX0N | FX1S | FX1N | FX1NC | FX2N,FX2NC | FX3U,FX3UC |
|-----------------------|--------------|------|------|--------------------------|-------|--------------------------|------------|
| Master station | — | — | — | ✓ (Ver.1.10 or later) | ✓ | ✓ (Ver.2.20 or later) | ✓ |
| Remote device station | — | ✓ | — | ✓ | ✓ | ✓ | ✓ |

3. Communication targets

Equipment operating in accordance with the CC-Link standard

4. Function

This network allows connection of inverters, AC servos, sensors, solenoid valves, etc. supporting the CC-Link network to achieve data link.

FX PLCs are classified as master stations or remote device stations.

5. Applications

Decentralized or centralized control of the line, reception and sending of information from/to the host network, etc.

6. Detailed information on CC-Link

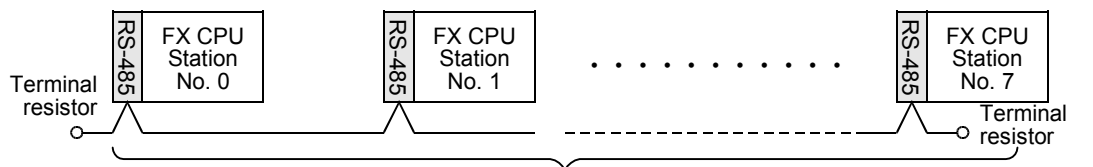
For details on CC-Link and connectable equipment, refer to the CC-Link Partner Association's homepage or catalogues (issued by the CC-Link Partner Association).

→ **CC-Link Partner Association's homepage:** <http://www.cc-link.org/>

1.2.2 N:N Network

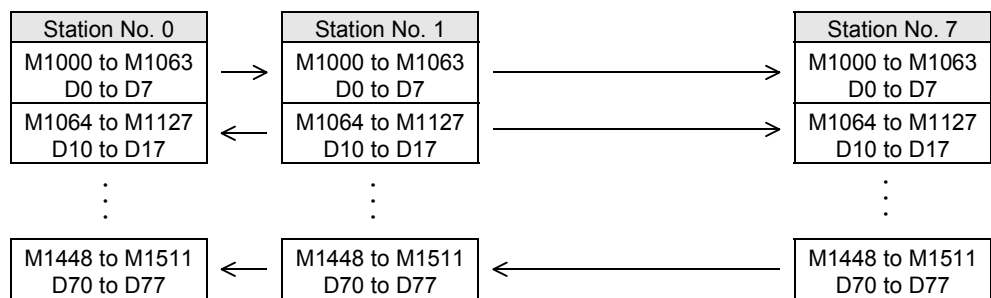
→ Refer to the "N:N Network" section.

1. Outline



- Number of connectable FX PLCs : 8 maximum (station Nos. 0 to 7)
- Total extension distance : 500 m (1640' 5") [50 m (164' 0") when 485BD is connected]

For FX3U PLC (pattern 2)



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)

—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|--------------------------|-----------------|--------------------------|-------|------------|
| Communication applicability | — | ✓ (Ver.2.00 or later) | ✓ | ✓ (Ver.2.00 or later) | ✓ | ✓ |

3. Communication targets

Between FX1S, FX0N, FX1N, FX2N, FX3U, FX1NC, FX2NC, and FX3UC Series PLCs

4. Function

This network allows up to eight connected FX PLCs to automatically transfer data among the connected PLCs.

In the network, data can be transferred among PLCs for devices determined in the refresh range, and those devices can be monitored by every PLC.

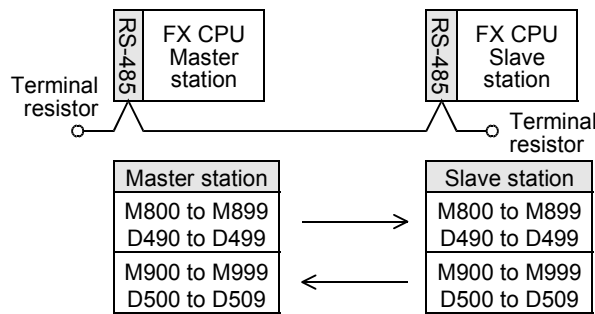
5. Applications

By this network, data link can be achieved in a small-scale system, and the machine information can be transferred between machines.

1.2.3 Parallel Link

→ Refer to the "Parallel Link" section.

1. Outline



100 bit devices (M) and 10 word devices (D)

• Number of connectable FX PLCs: 2

• Total extension distance: 500 m (1640' 5") [50 m (164' 0") when 485BD is connected]*1

*1 The distance is different for the FX2-40AW/AP.

2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|--------------------------|-----------------|--------------------------|-------|------------|
| Communication applicability | ✓ | ✓ (Ver.1.20 or later) | ✓ | ✓ (Ver.1.04 or later) | ✓ | ✓ |

3. Communication targets

Between FX2(FX), FX2C, FX1S, FX0N, FX1N, FX2N, FX3U, FX1NC, FX2NC, and FX3UC Series PLCs

4. Function

This network automatically transfers data for 100 bit devices (M) and 10 data registers (D) between two PLCs of the same series.

Between PLCs in the FX0N or FX1S Series, data can be transferred for 50 bit devices (M) and 10 data registers (D).

5. Applications

Information can be transferred between two FX PLCs.

(It is recommended to use the N:N Network when connecting two PLCs of the same series among the FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC, and FX3UC Series. N:N Network functionality supports linking of up to eight FX PLC units, therefore it offers excellent future expandability options.)

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (FSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

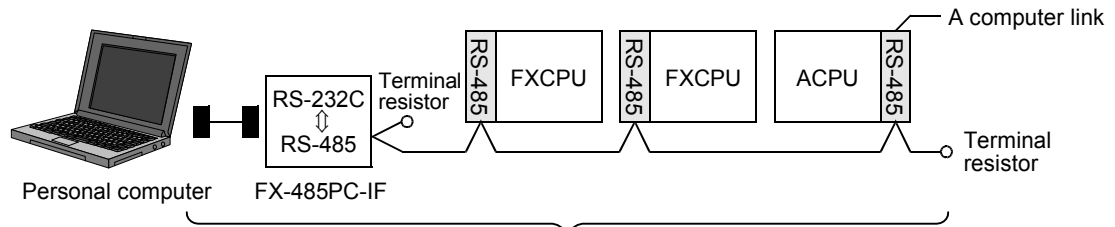
Discontinued models

1.2.4 Computer Link

→ Refer to the "Computer Link" section.

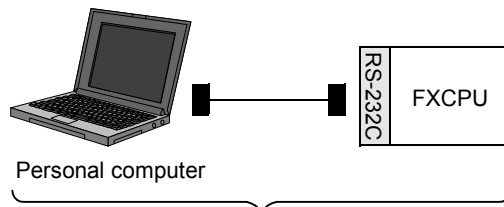
1. Outline

1) 1-to-N connection (RS-485)



- Number of connectable FX/A PLCs : 16 maximum
- Total extension distance : 500 m (1640' 5") [50 m (164' 0") when 485BD is connected]

2) 1-to-1 connection (RS-232C)



- Number of connectable FX PLCs : 1
- Total extension distance : 15 m (49' 2")

2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------------------|--------------------------|-----------------|--------------------------|-------|------------|
| Communication applicability | ✓ (Ver.3.30 or later) | ✓ (Ver.1.20 or later) | ✓ | ✓ (Ver.1.06 or later) | ✓ | ✓ |

3. Communication targets

Between FX2(FX), FX2C, FX1S, FX0N, FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC Series PLCs, A Series PLCs and personal computers

4. Function

This link allows connection of up to sixteen FX or A (including A1FX CPU) PLCs to a personal computer for data transfer when the personal computer directly specifies devices in the connected PLCs.

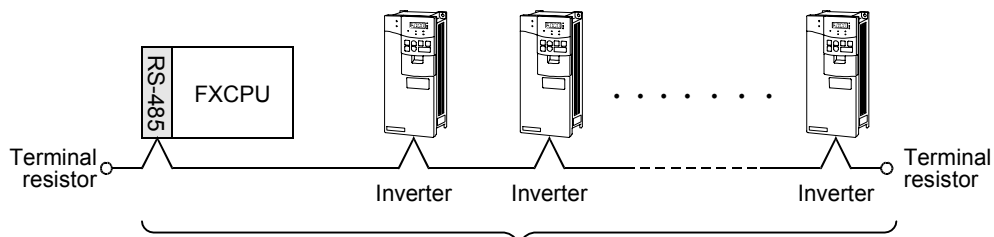
5. Applications

By this link, production, inventory, etc. can be controlled.

1.2.5 Inverter Communication

→ Refer to the "Inverter Communication" section.

1. Outline



- Number of connectable inverters : 8 maximum
- Total extension distance : 500 m (1640' 5") [50 m (164' 0") when 485BD is connected]

2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|-----------------|--------------------------|--------------------------|------------|
| Communication applicability | — | — | — | ✓ (Ver.3.00 or later) | ✓ (Ver.3.00 or later) | ✓ |

3. Communication targets

- For FX2N or FX2NC PLC
FREQROL Series (S500, E500 and A500) inverters
 - For FX3U or FX3UC PLC
FREQROL Series (S500, E500, A500, F500, V500, E700*2, F700*1 and A700*1) inverters
- *1. F700 and A700 Series inverters are supported in FX3U and FX3UC PLCs Ver. 2.20 and later.
*2. E700 Series inverters are supported in FX3U and FX3UC PLCs Ver. 2.32 and later.

4. Function

This communication allows the connection of inverters (computer link) in accordance with RS-485 to control operations and change parameters.

5. Applications

Operations with up to eight inverters can be controlled from a PLC.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

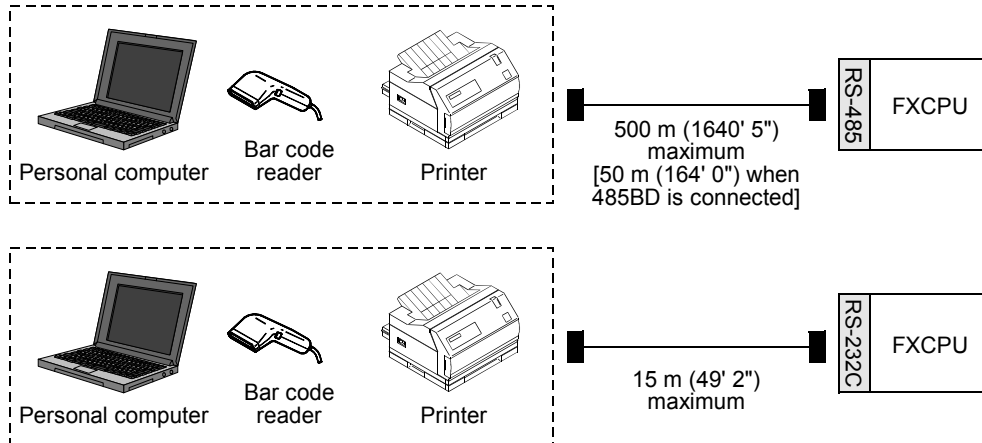
Apx.

Discontinued models

1.2.6 Non-protocol Communication

→ Refer to the "Non-protocol Communication (RS/RS2 instruction)" section.
→ Refer to the "Non-protocol Communication (FX2N-232IF)" section.

1. Outline



2. Applicable PLCs

1) Non-protocol communication (RS instruction)

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------------------|--------------------------|-----------------|--------------------------|-------|------------|
| Communication applicability | ✓ (Ver.3.00 or later) | ✓ (Ver.1.20 or later) | ✓ | ✓ (Ver.1.06 or later) | ✓ | ✓ |

2) Non-protocol communication (RS2 instruction)

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|-----------------|------|-------|------------|
| Communication applicability | — | — | — | — | — | ✓ |

3) Non-protocol communication (FX2N-232IF)

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|-----------------|------|-------|------------|
| Communication applicability | — | — | — | ✓ | ✓ | ✓ |

3. Communication targets

Bar code readers, printers, personal computers (micro computer boards), measuring instruments, etc.

4. Function

This communication allows non-protocol serial communication between equipment with an RS-232C or RS-422/RS-485 interface.

5. Applications

Communication with a bar code reader, printer, personal computer (micro computer board), measuring instrument, etc.

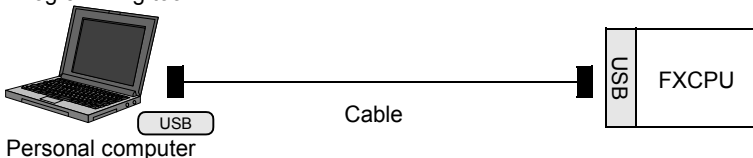
1.2.7 Programming Communication

→ Refer to the "Programming Communication" section.

1. Outline

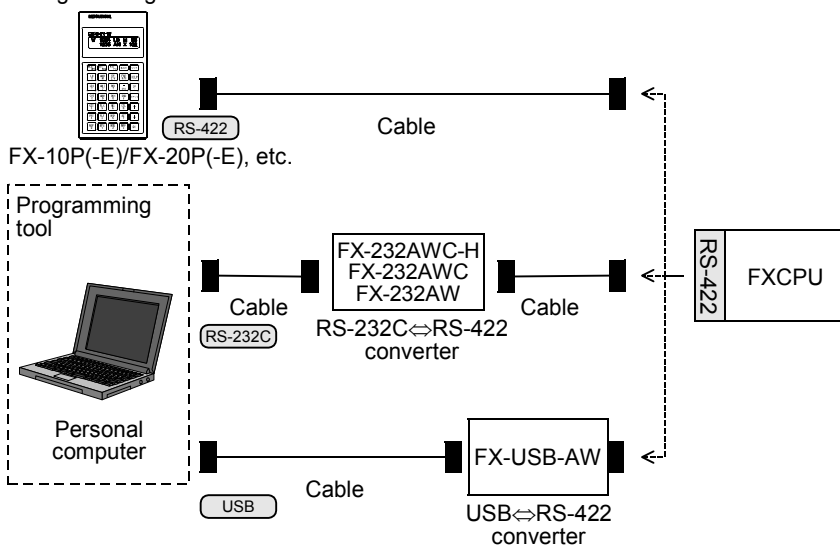
- 1) Communication equipment operating in accordance with USB (personal computer)

Programming tool



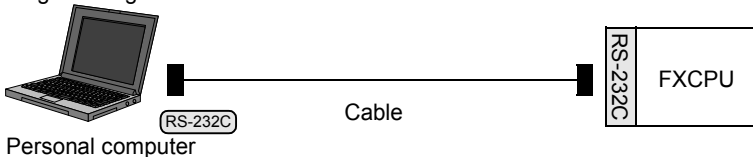
- 2) Communication equipment operating in accordance with RS-422 (programming tool or personal computer)

Programming tool



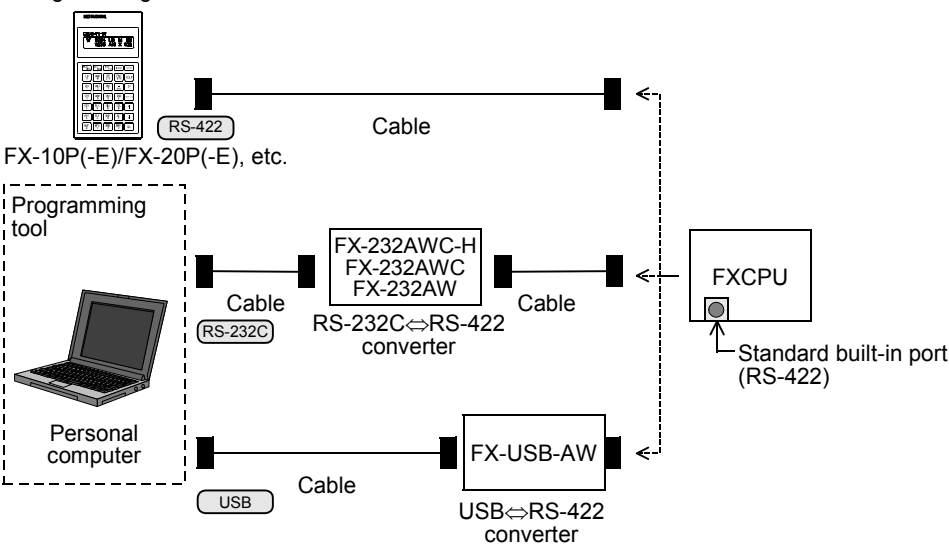
- 3) Communication equipment operating in accordance with RS-232C (personal computer)

Programming tool



- 4) Standard built-in port in accordance with RS422 (programming tool or personal computer)

Programming tool



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | | FX2(FX), FX2C | FX0N | FX1S, FX1N | FX1NC | FX2N | FX2NC | FX3U | FX3uc(D, DSS) | FX3uc(LT) |
|--|-------|------------------|------|---------------|-------|------|-------|------|---------------|-----------|
| Communication equipment operating in accordance with USB(-BD)*1 | | — | — | — | — | — | — | ✓ | — | ✓ |
| Communication equipment operating in accordance with RS-422(-BD) | | — | — | ✓ | — | ✓ | — | ✓ | — | ✓ |
| Communication equipment operating in accordance with RS-232C | (-BD) | — | — | ✓ | — | ✓ | — | ✓ | — | ✓ |
| | (ADP) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| Standard built-in port in accordance with RS-422 | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

*1. When using USB communication with a model that does not support USB communication equipment (-BD), use the FX-USB-AW.
However, FX2 (FX) and FX2C PLCs do not support the FX-USB-AW.

3. Communication targets

Personal computer and programming tool

4. Function

This communication allows connection of a personal computer or programming tool to a standard port built in a PLC or optional connector to execute sequence programs.

5. Applications

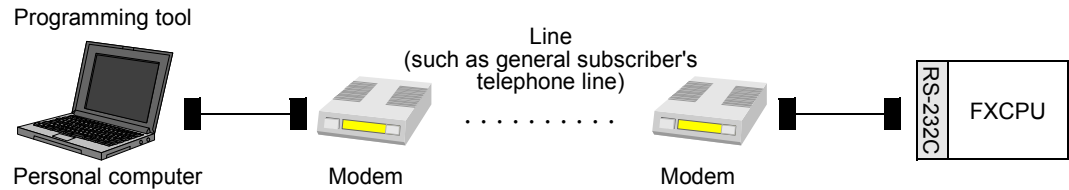
- 1) Programs can be changed and monitored using a personal computer or programming tool.
- 2) A personal computer (for changing programs) can be directly connected in accordance with RS-232C.
- 3) While the standard programming connector built in an FX PLC is used for connecting a display unit, a personal computer or programming tool can be connected at the same time for monitoring and transferring data.

1.2.8 Remote Maintenance

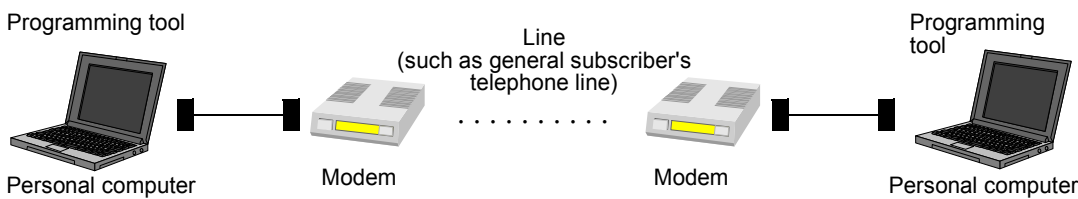
→ Refer to the "Remote Maintenance" section.

1. Outline

- 1) Remote access (GX Developer or FXGP/WIN)



- 2) File transfer (FXGP/WIN)



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S,FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|-----------------|------|-------|------------|
| Communication applicability | — | — | ✓ | ✓ | ✓ | ✓ |

3. Communication target

Personal computer (GX Developer or FXGP/WIN)

4. Function

This communication allows connection between a modem on the PLC side and a modem on the personal computer side through a line (cellular phone or general subscriber's telephone line) for PLC monitoring or transferring from the personal computer.

The FXGP/WIN allows transfer of file data between personal computers.

5. Applications

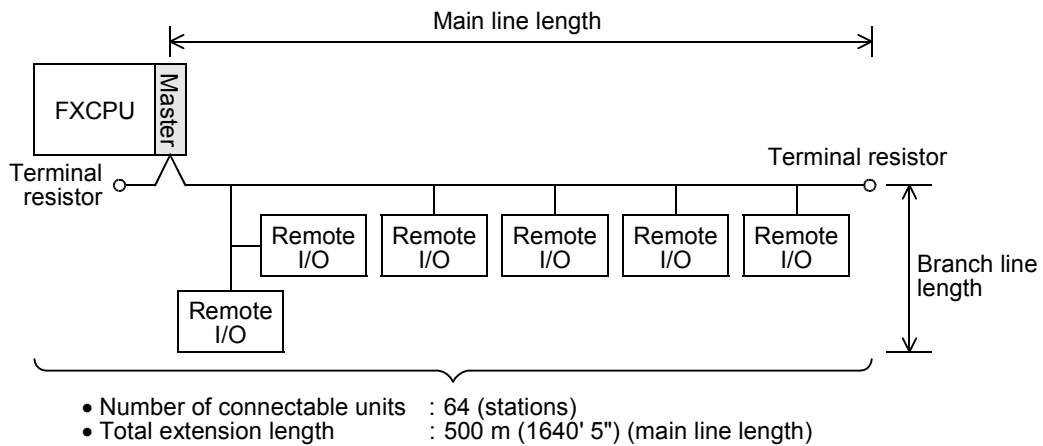
By this communication, programs in a PLC located in a remote location can be changed and maintained.

| | |
|------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/R2S Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

1.2.9 CC-Link/LT Network

→ For FX3uc-32MT-LT built-in CC-Link/LT master, refer to FX3uc Hardware Edition.
→ For the FX2N-64CL-M, refer to the product manual.

1. Outline



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S | FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|------|------------|------|-------|------------|
| Communication applicability | — | — | — | ✓ | ✓ | ✓ | ✓ |

3. Communication target

Equipment operating in accordance with the CC-Link/LT network standard

4. Function

This network allows remote control of I/O information for sensors, lamps, etc.
Input (X) numbers and output (Y) numbers can be handled, and I/O points can be assigned continuously even if 2-point or 4-point type remote I/O units are being used.

5. Applications

Wire conservation for inputs and outputs.

6. Detailed information on CC-Link/LT

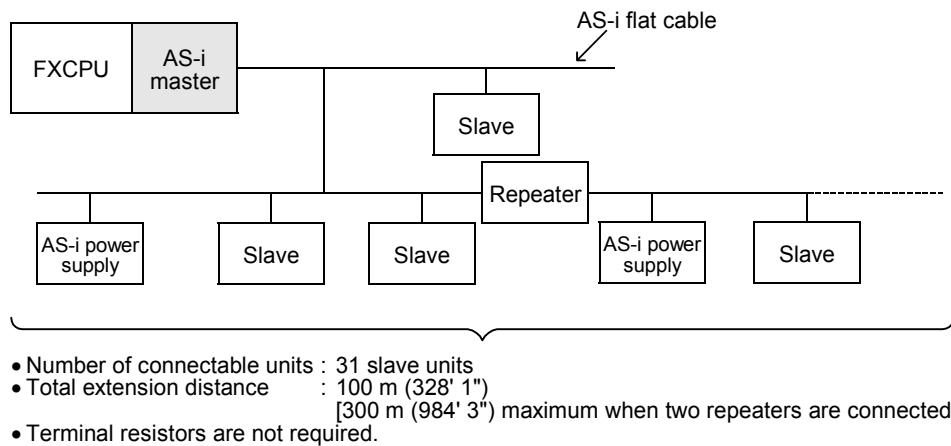
For product information on CC-Link, refer to the CC-Link Partner Association's homepage or catalogues (issued by the CC-Link Partner Association).

→ **CC-Link Partner Association's homepage:** <http://www.cc-link.org/>

1.2.10 AS-i system

→ For details, refer to the FX2N-32ASI-M User's Manual.

1. Outline



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S | FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|------|------------|------|-------|------------|
| Communication applicability | — | ✓ | — | ✓ | ✓ | ✓*1 | ✓ |

*1. FX2NC-□MT-D/UL and FX2NC-□M□-DSS(-T-DS) PLCs are not applicable.

3. Communication targets

Slave units (sensors and actuators) for AS-i

4. Function

This network allows remote control of I/O information for sensors and actuators (slave units). The automatic address assignment function enables easy replacement of a slave unit when it has failed.

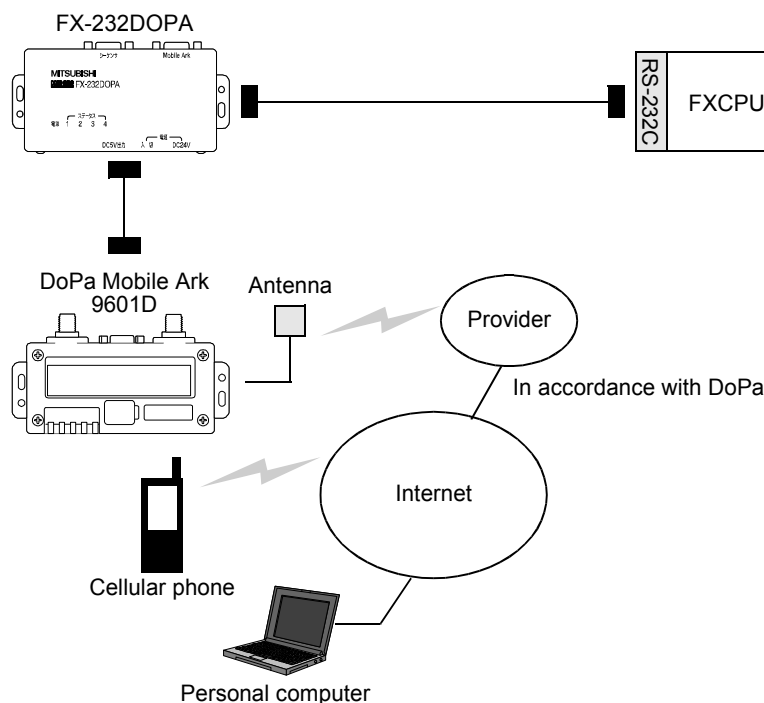
5. Applications

Wire conservation for inputs and outputs.

1.2.11 Internet Mail Sending

→ For the details, refer to the **FX-232DOPA USERS MANUAL**.
(Only Japanese manual is available for this product.)

1. Outline



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S | FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|------|------------|------|-------|------------|
| Communication applicability | — | — | ✓ | ✓ | ✓ | ✓ | ✓ |

3. Communication targets

Personal computer and cellular phone which can receive internet mails

4. Function

This setting sends an electronic mail from a PLC to notify the facility operation status, etc. to a personal computer or cellular phone which can receive electronic mails.

This function is applicable through dial-up connection to a mail server using a combination of FX-232DOPA and DoPa Mobile Ark9601D by NTT DoCoMo.

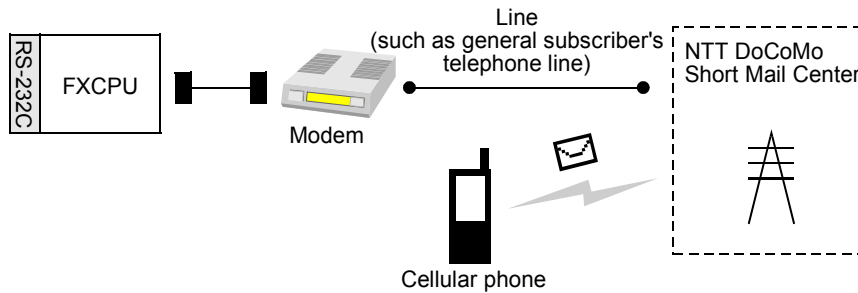
5. Applications

Monitoring of unmanned facilities, monitoring of facilities located in distant places, monitoring of facilities inside factories and distribution of logging data

1.2.12 Short Mail Sending

→ For details, refer to the FX1S/FX1N/FX2N/FX1NC/FX2NC PLC PROGRAMMING MANUAL II.

1. Outline



2. Applicable PLCs

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | FX2(FX),FX2C | FX0N | FX1S | FX1N,FX1NC | FX2N | FX2NC | FX3U,FX3UC |
|-----------------------------|--------------|------|------|------------|--------------------------|--------------------------|------------|
| Communication applicability | — | — | — | — | ✓ (Ver.3.00 or later) | ✓ (Ver.3.00 or later) | — |

3. Communication targets

Cellular phones by NTT DoCoMo with a contract for i-mode or short mail

4. Function

This function sends a short mail from a PLC to notify the facility operation status, etc. to a cellular phone by NTT DoCoMo which can receive short mails.

This function is applicable through connection in a line to a Short Mail Center of NTT DoCoMo.

5. Applications

Monitoring of unmanned facilities, monitoring of facilities located in distant places and monitoring of facilities in factories

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

MEMO

2. Communication Types and Communication Equipment

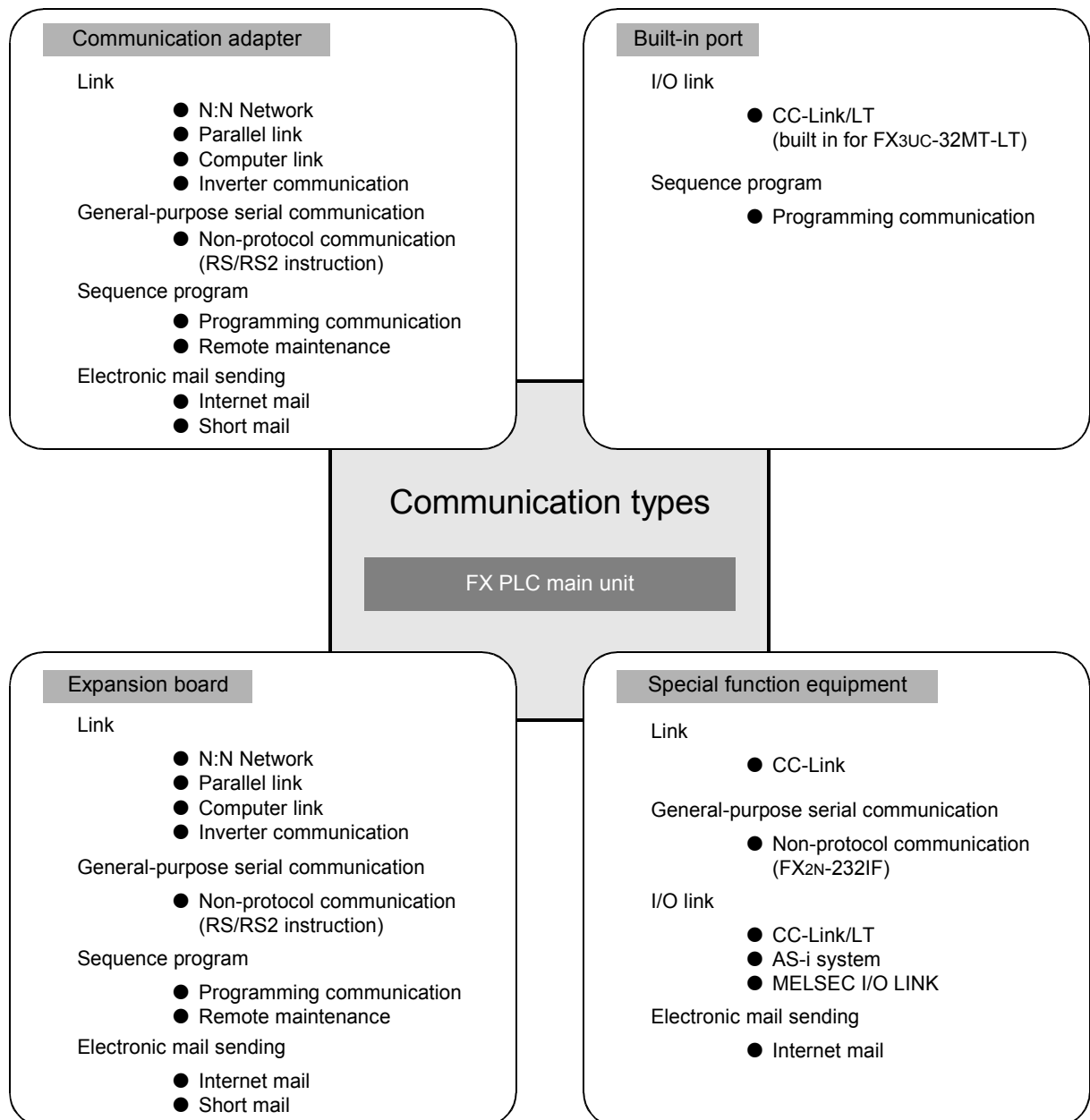
This chapter explains which communication types are supported by serial ports of communication equipment and connectors of networks.

For the communication equipment required in the system configuration, refer to a description later.

→ Refer to "2.3 Combination of Communication Equipment (Block Diagram)".

2.1 Relationship between Equipment and Communication Types

The figure below shows the relationship between communication equipment and communication types:



2.2 Communication Equipment Applicability Map

The table below shows the communication types applicable in each FX Series and includes the supporting communication equipment. The communication types can be used when a built-in port or piece of communication equipment is connected, but some of them may not be applicable at the same time.

2.2.1 FX3U and FX3UC (D, DSS) PLCs

| PLC | Communication equipment Product inside () is essential. | Communication specifications | Link | | | | |
|--|---|---------------------------------|-------------------|----------------|----------------|------------------|--|
| | | | CC-Link | N:N Network | Parallel link | Computer link | |
| Manual name (Obtain manuals if necessary.) → | | | Product manual | This manual | This manual | This manual | |
| FX3U PLC | FX3U-USB-BD | USB | | — | — | — | |
| | FX3U-232-BD | RS-232C | | — | — | ✓ | |
| | FX3U-232ADP(-MB) (expansion board) | | | — | — | ✓ | |
| | FX2N-232IF | | | — | — | — | |
| | FX3U-485-BD | RS-485 | | ✓*1 | ✓*1 | ✓ | |
| | FX3U-485ADP(-MB) (expansion board) | | | ✓*1 | ✓*1 | ✓ | |
| | FX3U-422-BD | RS-422 | | — | — | — | |
| | Standard built-in port | | | — | — | — | |
| | FX2N-16CCL-M | — | ✓*4 | | | | |
| | FX2N-32CCL | | ✓ | | | | |
| | FX2N-64CL-M | | — | | | | |
| | FX2N-32ASI-M | | — | | | | |
| | FX2N-16LNK-M | | — | | | | |
| FX3UC (D,DSS) PLC | FX3U-232ADP(-MB) | RS-232C | | — | — | ✓ | |
| | FX2N-232IF (FX2NC-CNV-IF or FX3UC-1PS-5V) | | | — | — | — | |
| | FX3U-485ADP(-MB) | RS-485 | | ✓*1 | ✓*1 | ✓ | |
| | Standard built-in port | RS-422 | | — | — | — | |
| | FX2N-16CCL-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | — | ✓*3 | | | | |
| | FX2N-32CCL (FX2NC-CNV-IF or FX3UC-1PS-5V) | | ✓ | | | | |
| | FX2N-64CL-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | | — | | | | |
| | FX2N-32ASI-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | | — | | | | |
| | FX2N-16LNK-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | | — | | | | |

- *1. Two channels cannot be set at the same time in N:N Network and parallel link.
N:N Network and parallel link cannot be used together.
*2. Two channels cannot be set at the same time in remote maintenance.
*3. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

| Link | | General-purpose communication | I/O link | | | Sequence program | | Mail sending |
|------|------------------------|-------------------------------|----------------|----------------|-----------------|------------------|--------------------|--------------------------|
| | Inverter communication | Non-protocol communication | CC-Link/LT | AS-i system | MELSEC-I/O LINK | Program-ming | Remote maintenance | Internet mail sending |
| | This manual | This manual | Product manual | Product manual | Product manual | This manual | This manual | FX-232DOPA User's Manual |
| | — | — | | | | ✓ | — | — |
| | — | ✓ | | | | ✓ | ✓*2 | ✓ |
| | — | ✓ | | | | ✓ | ✓*2 | ✓ |
| | — | ✓ | | | | — | — | ✓ |
| | ✓ | ✓ | | | | — | — | — |
| | ✓ | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | — | — | | | | ✓ | — | — |
| | | | — | — | — | | | |
| | | | — | — | — | | | |
| | | | ✓ | — | — | | | |
| | | | — | ✓*3 | — | | | |
| | | | — | — | ✓ | | | |
| | — | ✓ | | | | ✓ | ✓*2 | ✓ |
| | — | ✓ | | | | — | — | ✓ |
| | ✓ | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | | | — | — | — | | | |
| | | | — | — | — | | | |
| | | | ✓ | — | — | | | |
| | | | — | ✓*3 | — | | | |
| | | | — | — | ✓ | | | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2.2.2 FX3UC-32MT-LT PLCs

| PLC | Communication equipment Product inside () is essential. | Communication specifications | Link | | | | |
|--|---|------------------------------|----------------|-------------|---------------|---------------|--|
| | | | CC-Link | N:N Network | Parallel link | Computer link | |
| Manual name (Obtain manuals if necessary.) → | | | Product manual | This manual | This manual | This manual | |
| FX3UC-32MT-LT PLC | FX3U-USB-BD | USB | | — | — | — | |
| | FX3U-232-BD | RS-232C | | — | — | ✓ | |
| | FX3U-232ADP(-MB) (expansion board) | | | — | — | ✓ | |
| | FX2N-232IF (FX2NC-CNV-IF or FX3UC-1PS-5V) | | | — | — | — | |
| | FX3U-485-BD | RS-485 | | ✓*1 | ✓*1 | ✓ | |
| | FX3U-485ADP(-MB) (expansion board) | | | ✓*1 | ✓*1 | ✓ | |
| | FX3U-422-BD | RS-422 | | — | — | — | |
| | Standard built-in port | | | — | — | — | |
| | FX2N-16CCL-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | — | ✓*4 | | | | |
| | FX2N-32CCL (FX2NC-CNV-IF or FX3UC-1PS-5V) | | ✓ | | | | |
| | FX2N-64CL-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | | — | | | | |
| | Built-in type CC-Link/LT master | | — | | | | |
| | FX2N-32ASI-M (FX2NC-CNV-IF or FX3UC-1PS-5V) | | — | | | | |

- *1. Two channels cannot be set at the same time in N:N Network and parallel link.
N:N Network and parallel link cannot be used together.
- *2. For the FX2N-64CL-M, refer to FX2N-64CL-M User's Manual.
For FX3UC built-in CC-Link/LT master, refer to FX3UC Hardware Edition.
- *3. Two channels cannot be set at the same time in remote maintenance.
- *4. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

| Link | | General-purpose communication | I/O link | | | Sequence program | | Mail sending |
|------|------------------------|-------------------------------|----------------|----------------|-----------------|------------------|--------------------|--------------------------|
| | Inverter communication | Non-protocol communication | CC-Link/LT | AS-i system | MELSEC-I/O LINK | Program-ming | Remote maintenance | Internet mail sending |
| | This manual | This manual | Product manual | Product manual | Product manual | This manual | This manual | FX-232DOPA User's Manual |
| | — | — | | | | ✓ | — | — |
| | — | ✓ | | | | ✓ | ✓*3 | ✓ |
| | — | ✓ | | | | ✓ | ✓*3 | ✓ |
| | — | ✓ | | | | — | — | ✓ |
| | ✓ | ✓ | | | | — | — | — |
| | ✓ | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | — | — | | | | ✓ | — | — |
| | | | — | — | — | | | |
| | | | — | — | — | | | |
| | | | ✓*2 | — | — | | | |
| | | | ✓*2 | — | — | | | |
| | | | — | ✓*4 | — | | | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (FSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2.2.3 FX2N and FX2NC PLCs

| PLC | Communication equipment Product inside () is essential. | Communication specifications | Link | | | | | |
|--|---|---------------------------------|-------------------|----------------|----------------|------------------|--|--|
| | | | CC-Link | N:N Network | Parallel link | Computer link | | |
| Manual name (Obtain manuals if necessary.) → | | | Product manual | This manual | This manual | This manual | | |
| FX2N PLC | FX2N-232-BD | RS-232C | | — | — | ✓ | | |
| | FX2NC-232ADP(FX2N-CNV-BD) | | | — | — | ✓ | | |
| | FX0N-232ADP(FX2N-CNV-BD) | | | — | — | ✓*1 | | |
| | FX2N-232IF | | | — | — | — | | |
| | FX2N-485-BD | RS-485 | | ✓ | ✓ | ✓ | | |
| | FX2NC-485ADP(FX2N-CNV-BD) | | | ✓ | ✓ | ✓ | | |
| | FX0N-485ADP(FX2N-CNV-BD) | | | ✓ | ✓ | ✓ | | |
| | FX2N-422-BD | RS-422 | | — | — | — | | |
| | Standard built-in port | | | — | — | — | | |
| | FX2N-16CCL-M | — | | ✓*3 | | | | |
| | FX2N-32CCL | | | ✓ | | | | |
| | FX2N-64CL-M | | | — | | | | |
| | FX2N-32ASI-M | | | — | | | | |
| | FX2N-16LNK-M | | | — | | | | |
| FX2NC PLC | FX2NC-232ADP | RS-232C | | — | — | ✓ | | |
| | FX0N-232ADP | | | — | — | ✓*1 | | |
| | FX2N-232IF(FX2NC-CNV-IF) | | | — | — | — | | |
| | FX2NC-485ADP | RS-485 | | ✓ | ✓ | ✓ | | |
| | FX0N-485ADP | | | ✓ | ✓ | ✓ | | |
| | Standard built-in port | RS-422 | | — | — | — | | |
| | FX2N-16CCL-M(FX2NC-CNV-IF) | — | | ✓*3 | | | | |
| | FX2N-32CCL(FX2NC-CNV-IF) | | | ✓ | | | | |
| | FX2N-64CL-M(FX2NC-CNV-IF) | | | — | | | | |
| | FX2N-32ASI-M(FX2NC-CNV-IF) | | | — | | | | |
| FX2N-16LNK-M(FX2NC-CNV-IF) | — | | | | | | | |

*1. It is recommended to use a connector or thin type FX2NC-232ADP (9-pin D-Sub).

*2. The FX2NC Series main unit does not support connection of the FX2NC-□MT-D/UL and FX2NC-□M□-DSS(-T-DS).

*3. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

| Link | | General-purpose communication | I/O link | | | Sequence program | | Mail sending | |
|------|------------------------|-------------------------------|----------------|-------------------|-----------------|------------------|--------------------|--------------------------|---|
| | Inverter communication | Non-protocol communication | CC-Link/LT | AS-i system | MELSEC-I/O LINK | Programming | Remote maintenance | Internet mail sending | Short mail sending |
| | This manual | This manual | Product manual | Product manual | Product manual | This manual | This manual | FX-232DOPA User's Manual | FX1S, FX1N, FX2N, FX1NC, FX2NC Programming Manual |
| | — | ✓ | | | | ✓ | ✓ | ✓ | ✓ |
| | — | ✓ | | | | ✓ | ✓ | ✓ | ✓ |
| | — | ✓ ^{*1} | | | | ✓ ^{*1} | ✓ ^{*1} | ✓ ^{*1} | ✓ ^{*1} |
| | — | ✓ | | | | — | — | ✓ | — |
| | ✓ | ✓ | | | | — | — | — | — |
| | ✓ | ✓ | | | | — | — | — | — |
| | ✓ | ✓ | | | | — | — | — | — |
| | — | — | | | | ✓ | — | — | — |
| | — | — | | | | ✓ | — | — | — |
| | | | — | — | — | | | | |
| | | | — | — | — | | | | |
| | | | ✓ | — | — | | | | |
| | | | — | ✓ ^{*3} | — | | | | |
| | | | — | — | ✓ | | | | |
| | — | ✓ | | | | ✓ | ✓ | ✓ | ✓ |
| | — | ✓ ^{*1} | | | | ✓ ^{*1} | ✓ ^{*1} | ✓ ^{*1} | ✓ ^{*1} |
| | — | ✓ | | | | — | — | ✓ | — |
| | ✓ | ✓ | | | | — | — | — | — |
| | ✓ | ✓ | | | | — | — | — | — |
| | — | — | | | | ✓ | — | — | — |
| | | | — | — | — | | | | |
| | | | — | — | — | | | | |
| | | | ✓ | — | — | | | | |
| | | | — | ✓ ^{*2*3} | — | | | | |
| | | | — | — | ✓ | | | | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RSRS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

2.2.4 FX1S, FX1N, and FX1NC PLCs

| PLC | Communication equipment Product inside () is essential. | Communication specifications | Link | | | | | |
|--|---|---------------------------------|-------------------|----------------|----------------|------------------|--|--|
| | | | CC-Link | N:N Network | Parallel link | Computer link | | |
| Manual name (Obtain manuals if necessary.) → | | | Product manual | This manual | This manual | This manual | | |
| FX1S PLC | FX1N-232-BD | RS-232C | | — | — | ✓ | | |
| | FX2NC-232ADP(FX1N-CNV-BD) | | | — | — | ✓ | | |
| | FX0N-232ADP(FX1N-CNV-BD) | | | — | — | ✓*1 | | |
| | FX1N-485-BD | RS-485 | | ✓ | ✓ | ✓ | | |
| | FX2NC-485ADP(FX1N-CNV-BD) | | | ✓ | ✓ | ✓ | | |
| | FX0N-485ADP(FX1N-CNV-BD) | | | ✓ | ✓ | ✓ | | |
| | FX1N-422-BD | RS-422 | | — | — | — | | |
| | Standard built-in port | | | — | — | — | | |
| FX1N PLC | FX1N-232-BD | RS-232C | | — | — | ✓ | | |
| | FX2NC-232ADP(FX1N-CNV-BD) | | | — | — | ✓ | | |
| | FX0N-232ADP(FX1N-CNV-BD) | | | — | — | ✓*1 | | |
| | FX1N-485-BD | RS-485 | | ✓ | ✓ | ✓ | | |
| | FX2NC-485ADP(FX1N-CNV-BD) | | | ✓ | ✓ | ✓ | | |
| | FX0N-485ADP(FX1N-CNV-BD) | | | ✓ | ✓ | ✓ | | |
| | FX1N-422-BD | RS-422 | | — | — | — | | |
| | Standard built-in port | | | — | — | — | | |
| | FX2N-16CCL-M | — | | ✓*2 | | | | |
| | FX2N-32CCL | | | ✓ | | | | |
| | FX2N-64CL-M | | | — | | | | |
| | FX2N-32ASI-M | | | — | | | | |
| | FX2N-16LNK-M | | | — | | | | |
| FX1NC PLC | FX2NC-232ADP | RS-232C | | — | — | ✓ | | |
| | FX0N-232ADP | | | — | — | ✓*1 | | |
| | FX2NC-485ADP | RS-485 | | ✓ | ✓ | ✓ | | |
| | FX0N-485ADP | | | ✓ | ✓ | ✓ | | |
| | Standard built-in port | RS-422 | | — | — | — | | |
| | FX2N-16CCL-M(FX2NC-CNV-IF) | — | | ✓*2 | | | | |
| | FX2N-32CCL(FX2NC-CNV-IF) | | | ✓ | | | | |
| | FX2N-64CL-M(FX2NC-CNV-IF) | | | — | | | | |
| | FX2N-32ASI-M(FX2NC-CNV-IF) | | | — | | | | |
| | FX2N-16LNK-M(FX2NC-CNV-IF) | | | — | | | | |

*1. It is recommended to use a connector or thin type FX2NC-232ADP (9-pin D-Sub).

*2. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

| Link | | General-purpose communication | I/O link | | | Sequence program | | Mail sending |
|------|------------------------|-------------------------------|----------------|----------------|-----------------|------------------|--------------------|--------------------------|
| | Inverter communication | Non-protocol communication | CC-Link/LT | AS-i system | MELSEC-I/O LINK | Program-ming | Remote maintenance | Internet mail sending |
| | This manual | This manual | Product manual | Product manual | Product manual | This manual | This manual | FX-232DOPA User's Manual |
| | — | ✓ | | | | ✓ | ✓ | ✓ |
| | — | ✓ | | | | ✓ | ✓ | ✓ |
| | — | ✓*1 | | | | ✓*1 | ✓*1 | ✓*1 |
| | — | ✓ | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | — | — | | | | ✓ | — | — |
| | — | ✓ | | | | ✓ | ✓ | ✓ |
| | — | ✓ | | | | ✓ | ✓ | ✓ |
| | — | ✓*1 | | | | ✓*1 | ✓*1 | ✓*1 |
| | — | ✓ | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | — | — | | | | ✓ | — | — |
| | | | — | — | — | | | |
| | | | — | — | — | | | |
| | | | ✓ | — | — | | | |
| | | | — | ✓*2 | — | | | |
| | | | — | — | ✓ | | | |
| | — | ✓ | | | | ✓ | ✓ | ✓ |
| | — | ✓*1 | | | | ✓*1 | ✓*1 | ✓*1 |
| | — | ✓ | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | | | — | — | — | | | |
| | | | — | — | — | | | |
| | | | ✓ | — | — | | | |
| | | | — | ✓*2 | — | | | |
| | | | — | — | ✓ | | | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RSRS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

2.2.5 FX0N PLCs

| PLC | Communication equipment Product inside () is essential. | Communication specifications | Link | | | | |
|--|---|---------------------------------|-------------------|----------------|----------------|------------------|--|
| | | | CC-Link | N:N Network | Parallel link | Computer link | |
| Manual name (Obtain manuals if necessary.) → | | | Product manual | This manual | This manual | This manual | |
| FX0N PLC | FX2NC-232ADP | RS-232C | | — | — | ✓ | |
| | FX0N-232ADP | | | — | — | ✓*1 | |
| | FX2NC-485ADP | RS-485 | | ✓ | ✓ | ✓ | |
| | FX0N-485ADP | | | ✓ | ✓ | ✓ | |
| | Standard built-in port | RS-422 | | — | — | — | |
| | FX2N-16CCL-M | — | — | | | | |
| | FX2N-32CCL | | ✓ | | | | |
| | FX2N-64CL-M | | — | | | | |
| | FX2N-32ASI-M | | — | | | | |
| | FX2N-16LNK-M | | — | | | | |

*1. It is recommended to use a connector or thin type FX2NC-232ADP (9-pin D-Sub).

*2. Only Japanese manual is available for this product.

2.2.6 FX0, FX0s, FX2(FX), FX2c, and FX1 PLCs (reference)

| PLC | Communication equipment Product inside () is essential. | Communication specifications | Link | | | | |
|--|---|---------------------------------|-------------------|----------------|----------------|------------------|--|
| | | | CC-Link | N:N Network | Parallel link | Computer link | |
| Manual name (Obtain manuals if necessary.) → | | | Product manual | This manual | This manual | This manual | |
| FX0 PLC | Standard built-in port | RS-422 | | — | — | — | |
| FX0S PLC | Standard built-in port | RS-422 | | — | — | — | |
| FX2C PLC FX2(FX) PLC | FX-232ADP | RS-232C | | — | — | ✓ | |
| | FX-485ADP | RS-485 | | — | — | ✓ | |
| | FX-40AW | — | | — | ✓ | — | |
| | FX-40AP | Optical communication | | — | ✓ | — | |
| | Standard built-in port | RS-422 | | — | — | — | |
| FX1 PLC | Standard built-in port | RS-422 | | — | — | — | |

*1. Only Japanese manual is available for this product.

| Link | | General-purpose communication | I/O link | | | Sequence program | | Mail sending |
|------|------------------------|-------------------------------|----------------|----------------|-----------------|------------------|--------------------|----------------------------|
| | Inverter communication | Non-protocol communication | CC-Link/LT | AS-i system | MELSEC-I/O LINK | Program-ming | Remote maintenance | Internet mail sending |
| | This manual | This manual | Product manual | Product manual | Product manual | This manual | This manual | FX-232DOPA User's Manual*2 |
| | — | ✓ | | | | — | — | — |
| | — | ✓*1 | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | ✓ | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | | | — | — | — | | | |
| | | | — | — | — | | | |
| | | | ✓ | — | — | | | |
| | | | — | ✓ | — | | | |
| | | | — | — | ✓ | | | |

| Link | | General-purpose communication | I/O link | | | Sequence program | | Mail sending |
|------|------------------------|-------------------------------|----------------|----------------|-----------------|------------------|--------------------|----------------------------|
| | Inverter communication | Non-protocol communication | CC-Link/LT | AS-i system | MELSEC-I/O LINK | Program-ming | Remote maintenance | Internet mail sending |
| | This manual | This manual | Product manual | Product manual | Product manual | This manual | This manual | FX-232DOPA User's Manual*1 |
| | — | — | | | | ✓ | — | — |
| | — | — | | | | ✓ | — | — |
| | — | ✓ | | | | — | — | — |
| | — | — | | | | — | — | — |
| | — | — | | | | — | — | — |
| | — | — | | | | — | — | — |
| | — | — | | | | ✓ | — | — |
| | — | — | | | | ✓ | — | — |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

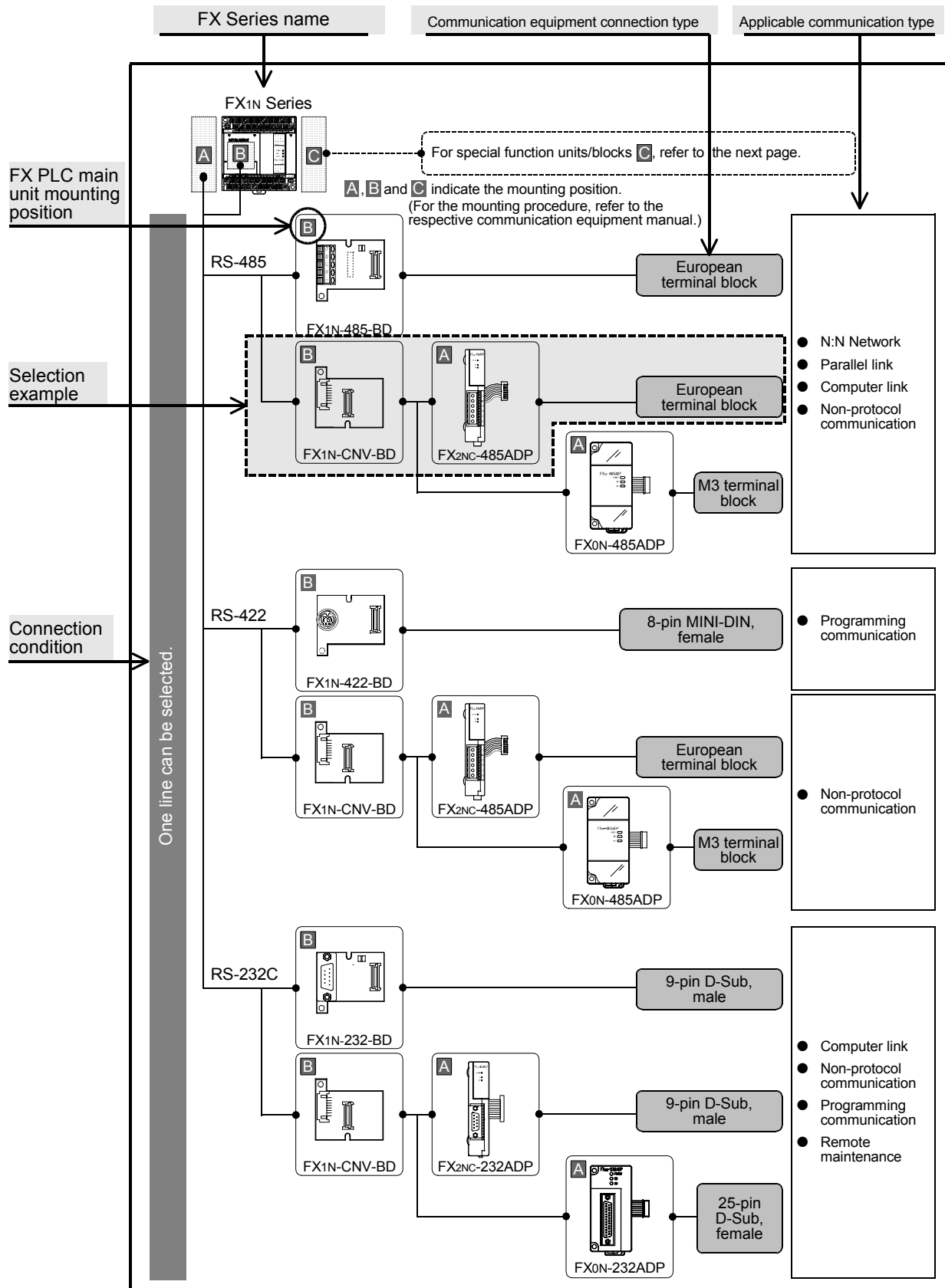
Apx.

Discontinued models

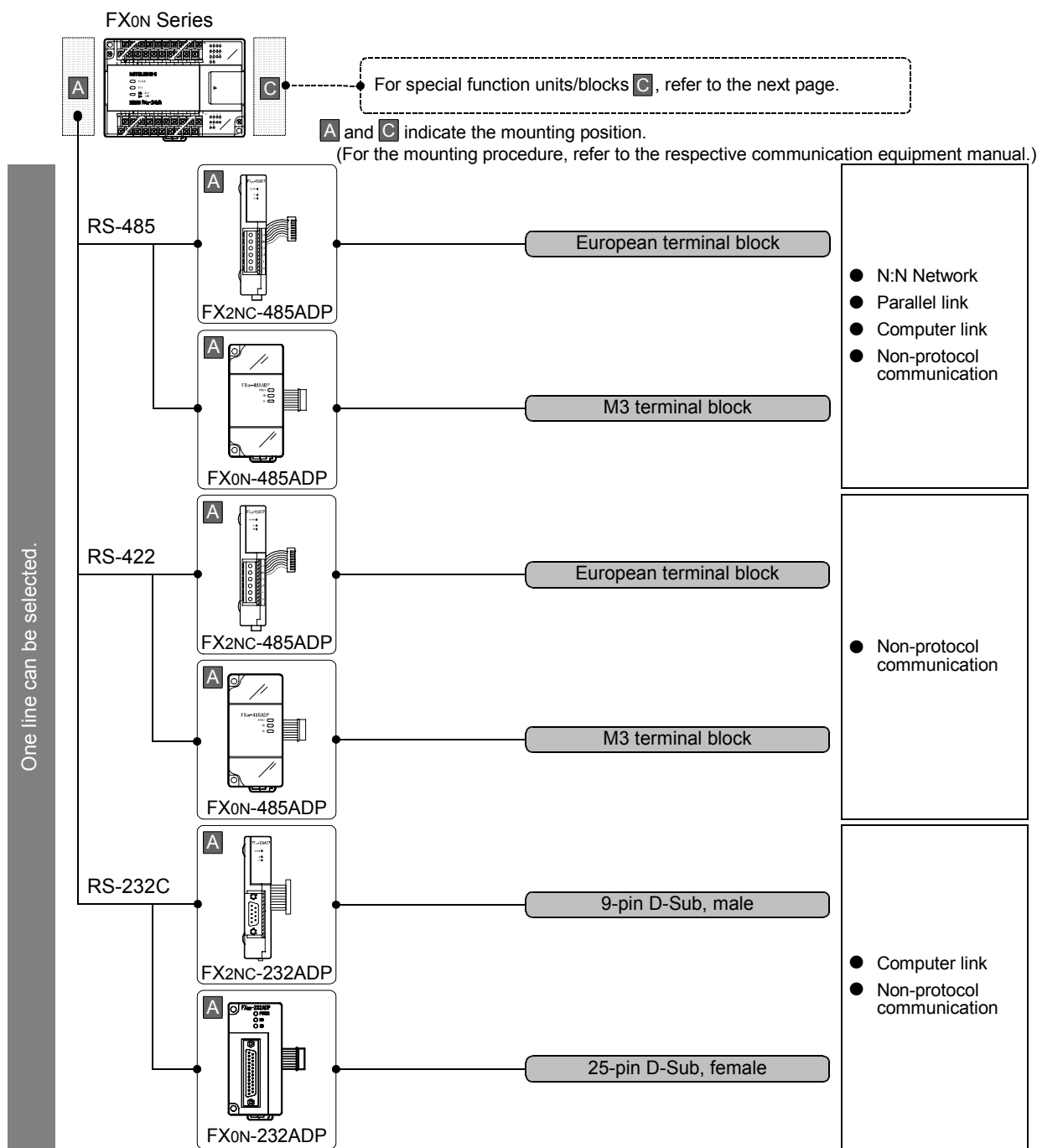
2.3 Combination of Communication Equipment (Block Diagram)

The block diagram below shows combinations of optional communication equipment applicable in each FX Series.

2.3.1 How to look at combination pages



2.3.2 For FX0N Series



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

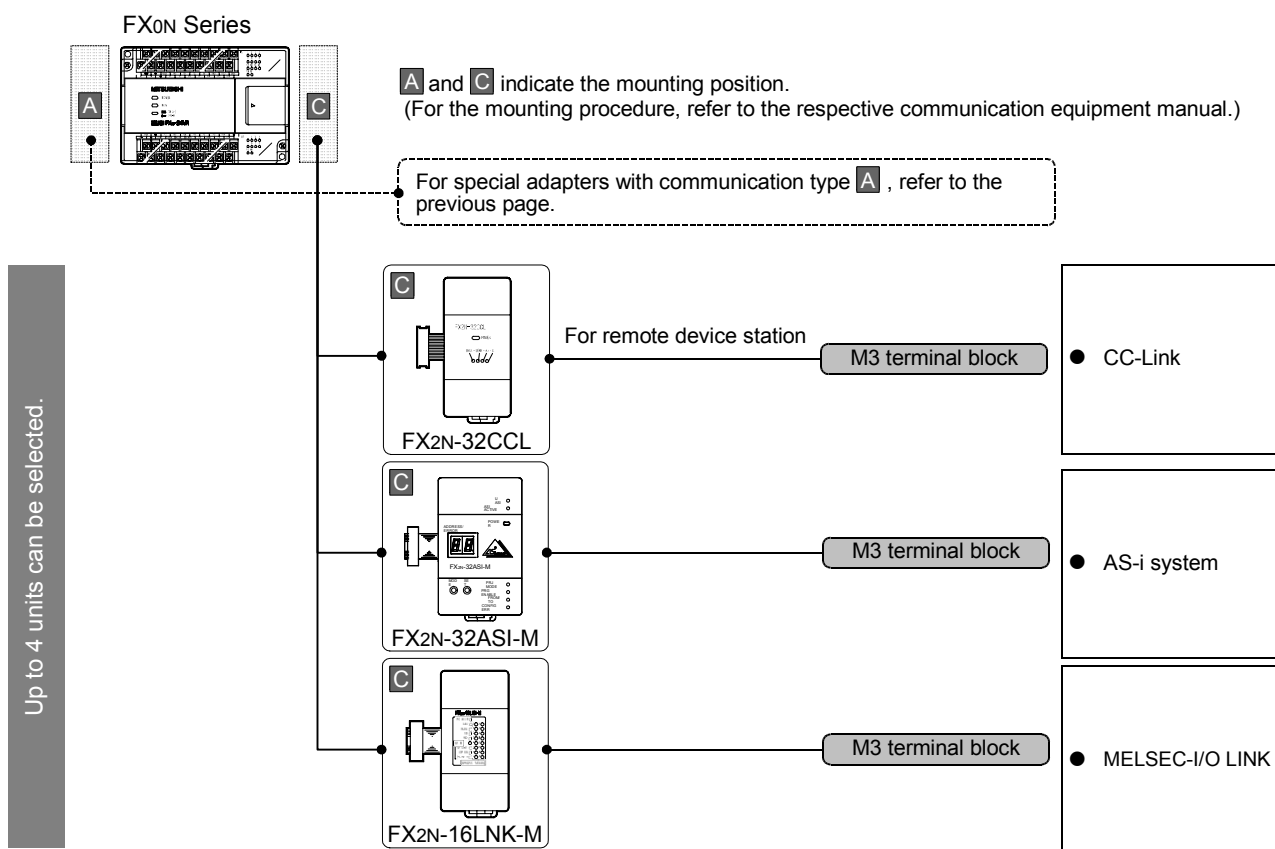
Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

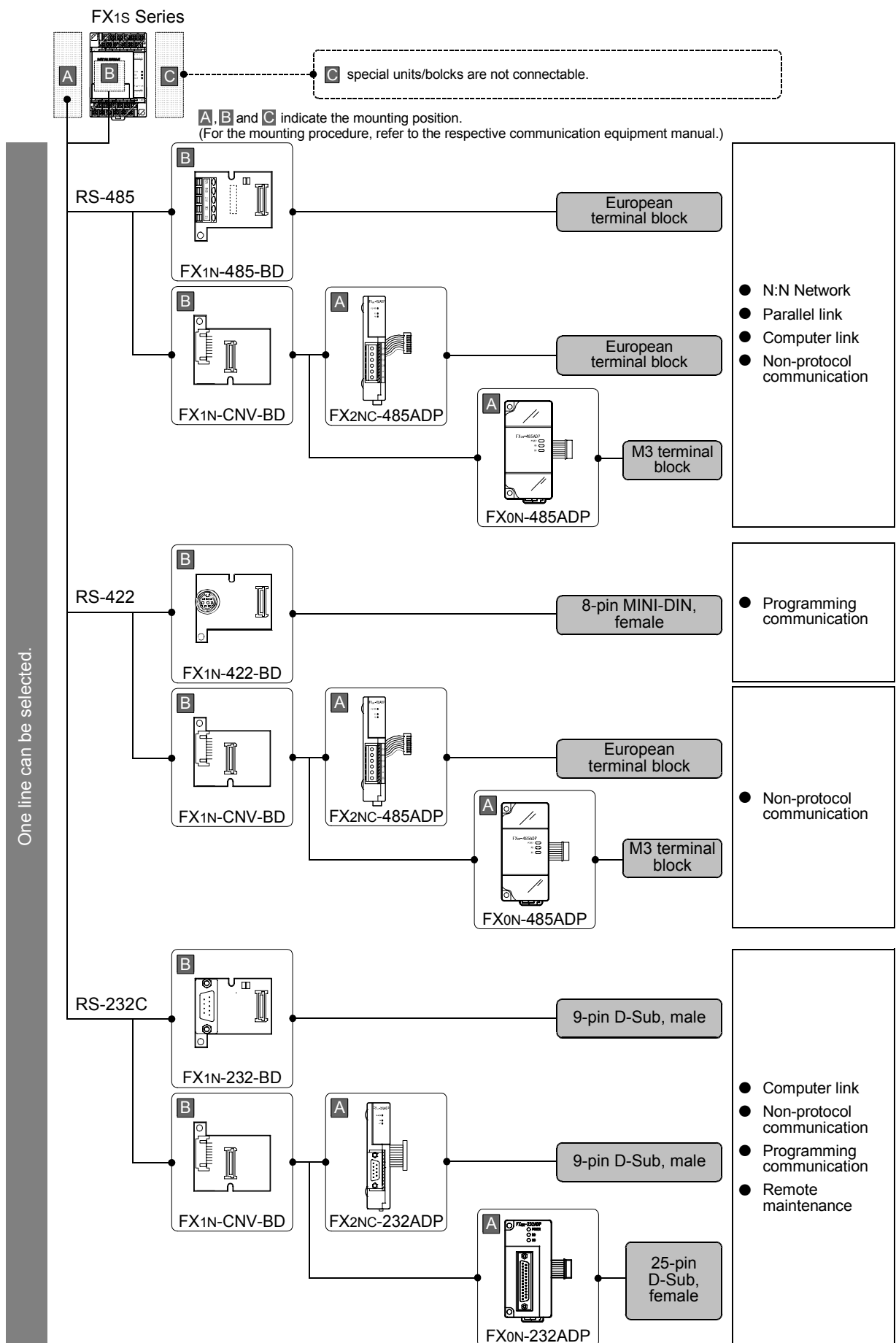


Limitation in the number of connectable units

Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Therefore, the total current consumption larger than the plc current capacity reduces the number of connectable units.

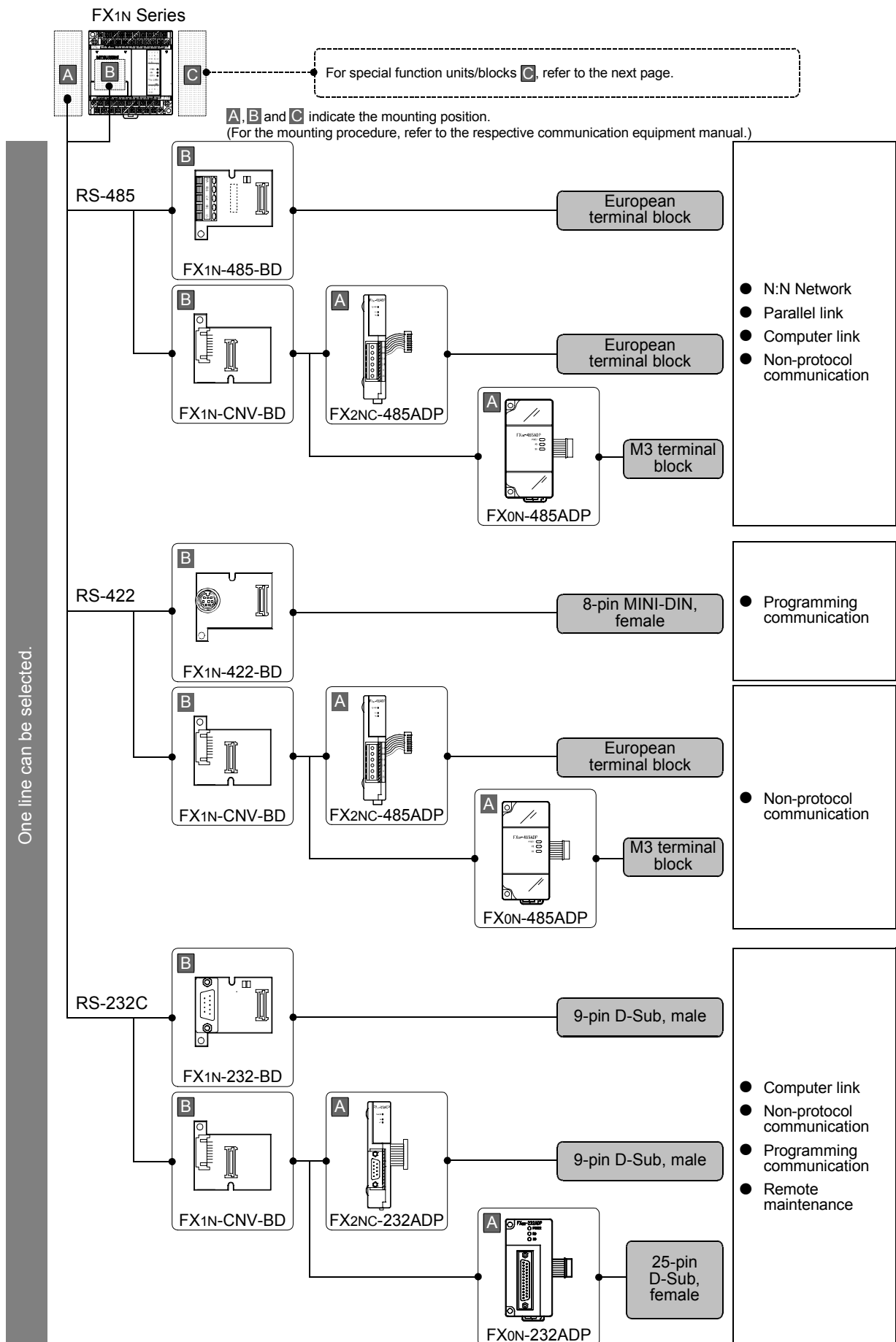
→ For details, refer to the respective FX PLC manual.

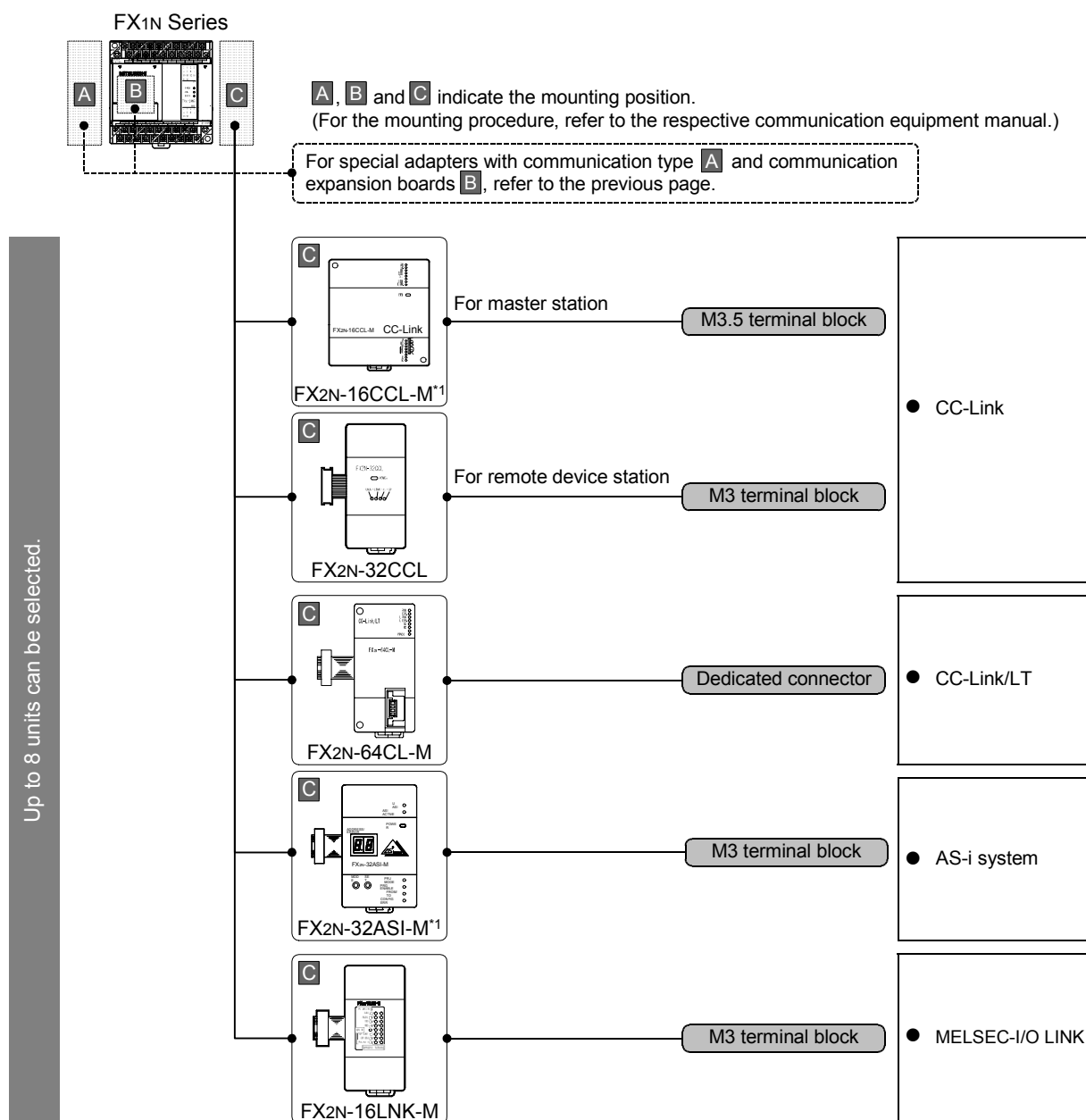
2.3.3 For FX1s Series



| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS485 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

2.3.4 For FX1N Series





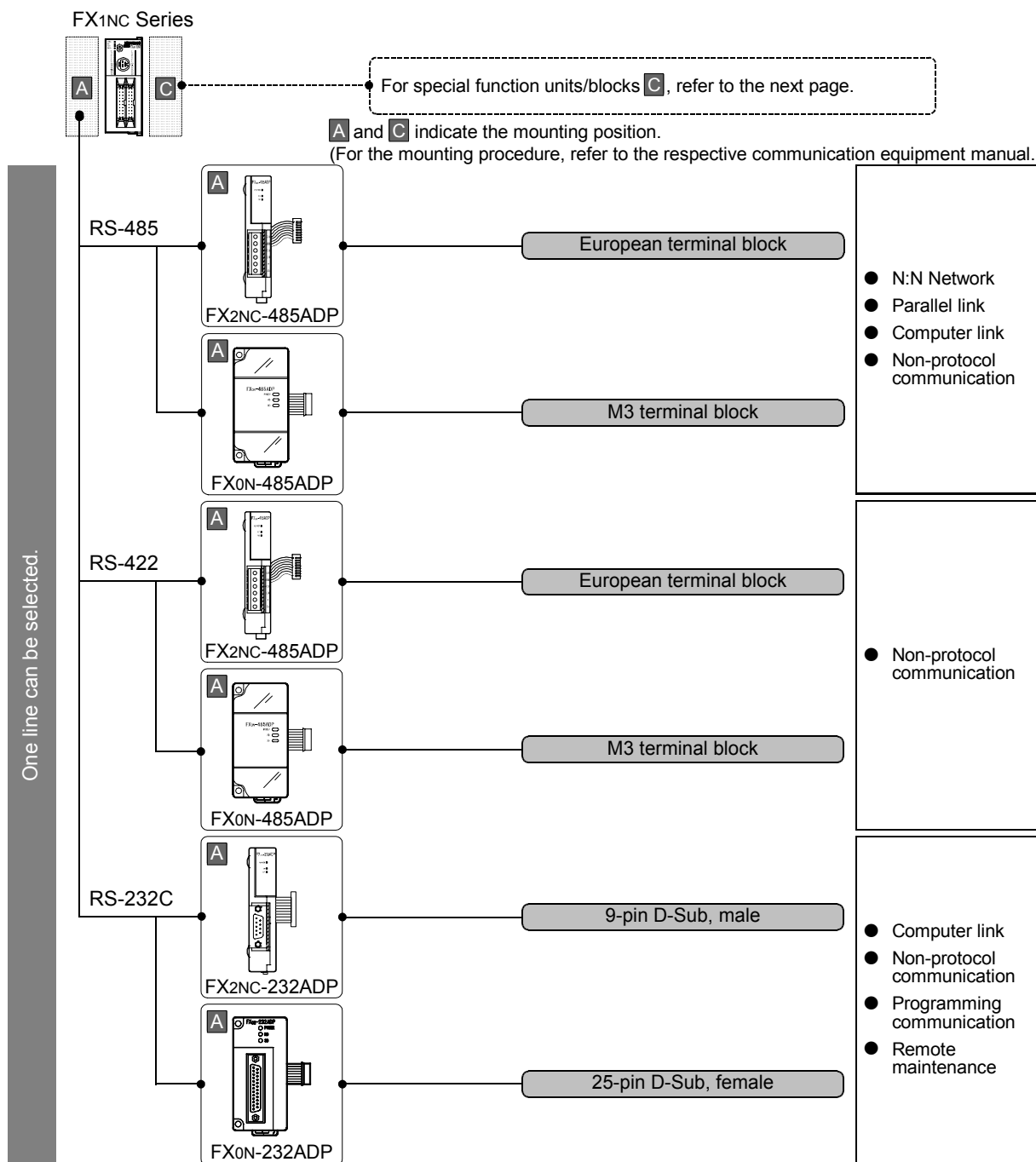
*1. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

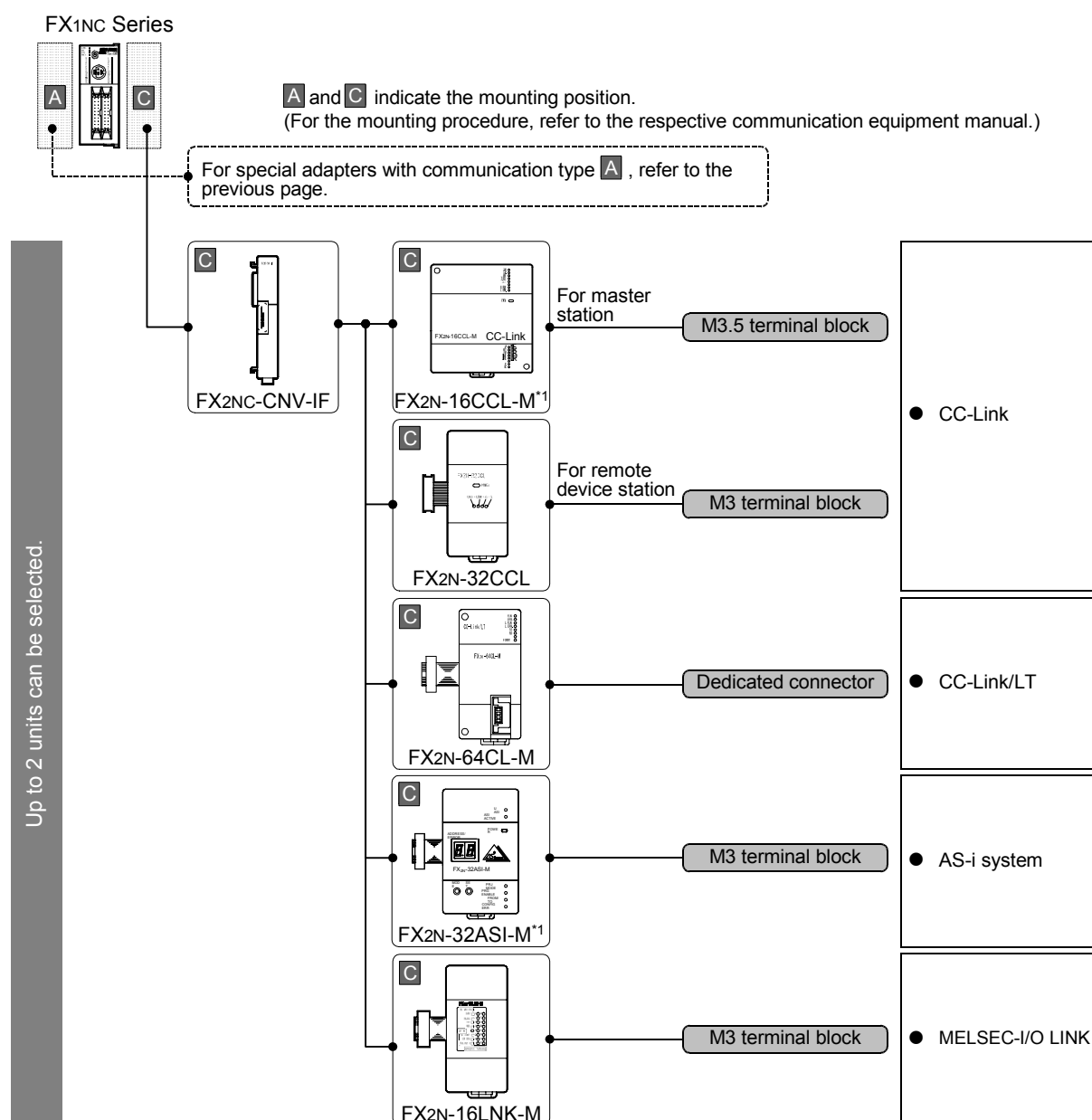
Limitation in the number of connectable units

Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Accordingly, the number of connectable units depends on the system configuration.

→ For details, refer to the respective FX PLC manual.

2.3.5 For FX1NC Series





*1. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

Limitation in the number of connectable units

Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Accordingly, the number of connectable units depends on the system configuration.

→ For details, refer to the respective FX PLC manual.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

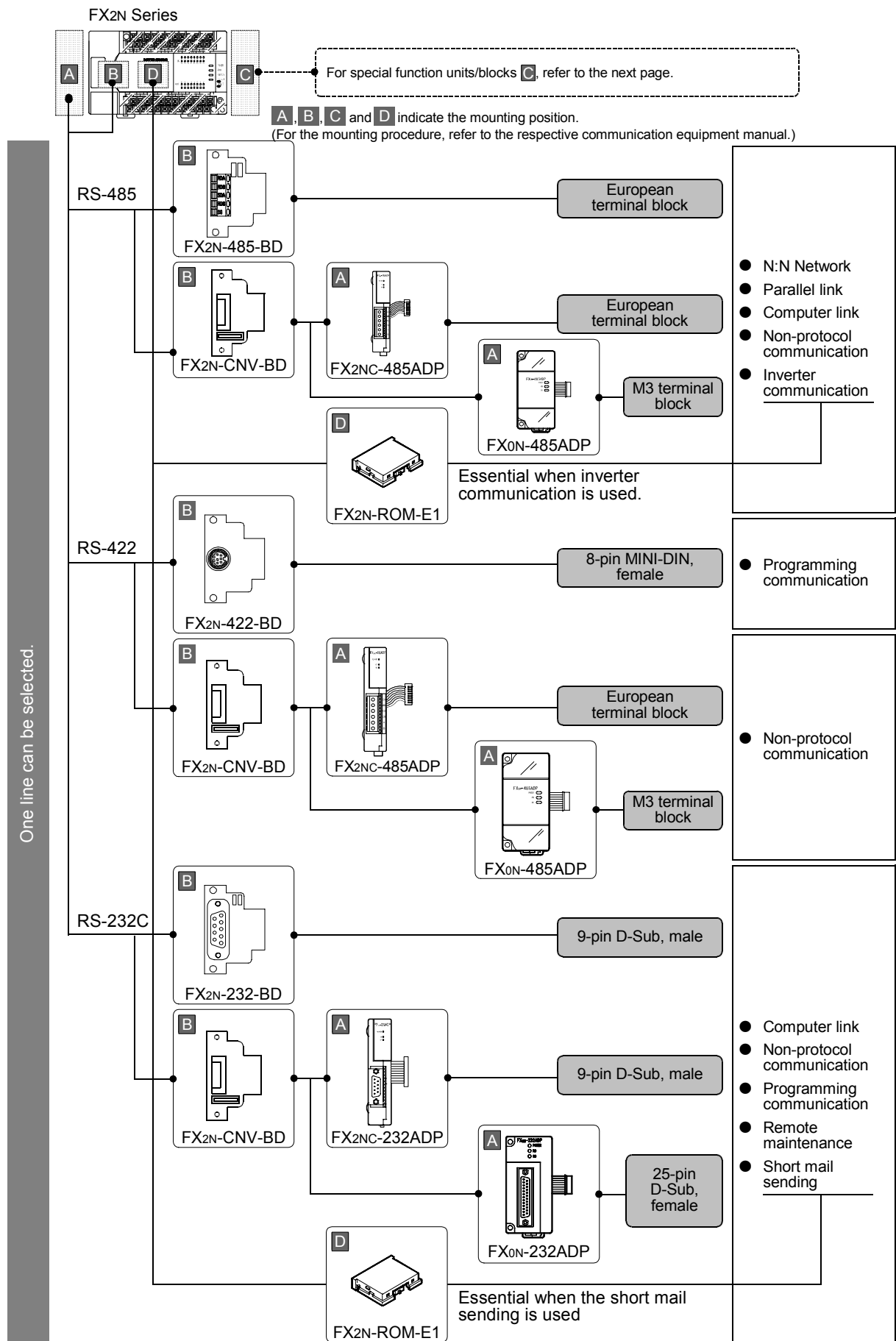
I

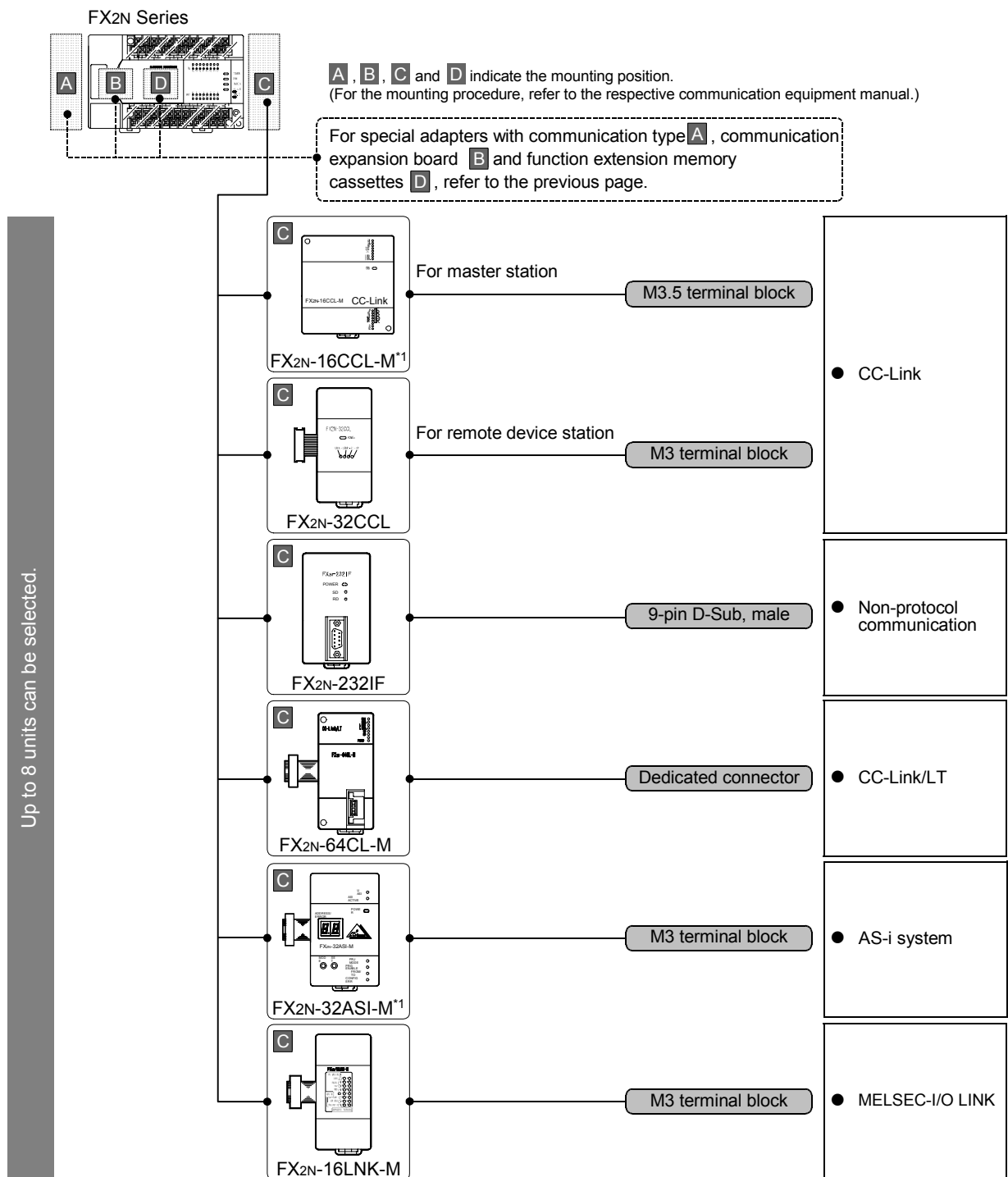
Remote Maintenance

Apx.

Discontinued models

2.3.6 For FX2N Series





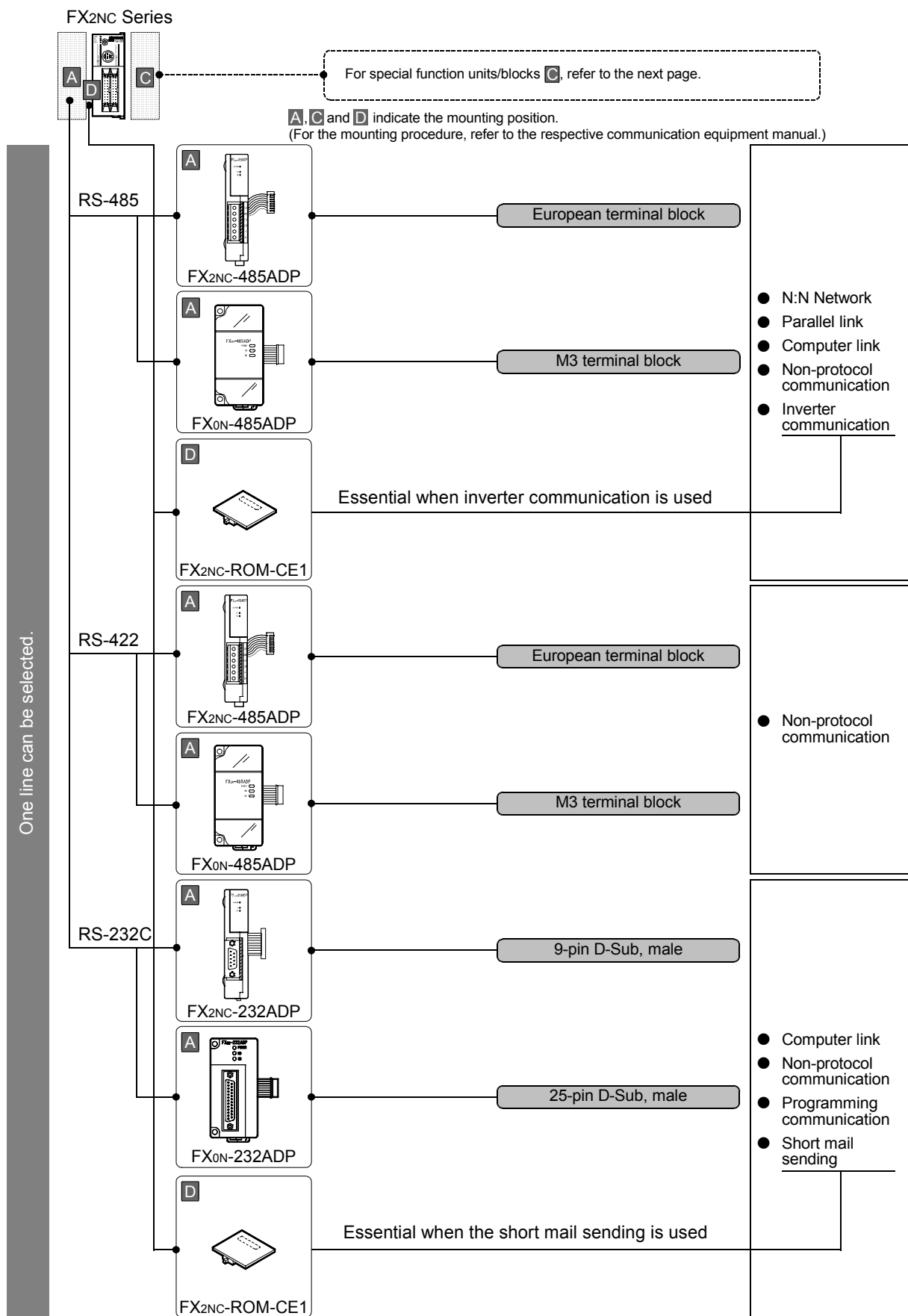
*1. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

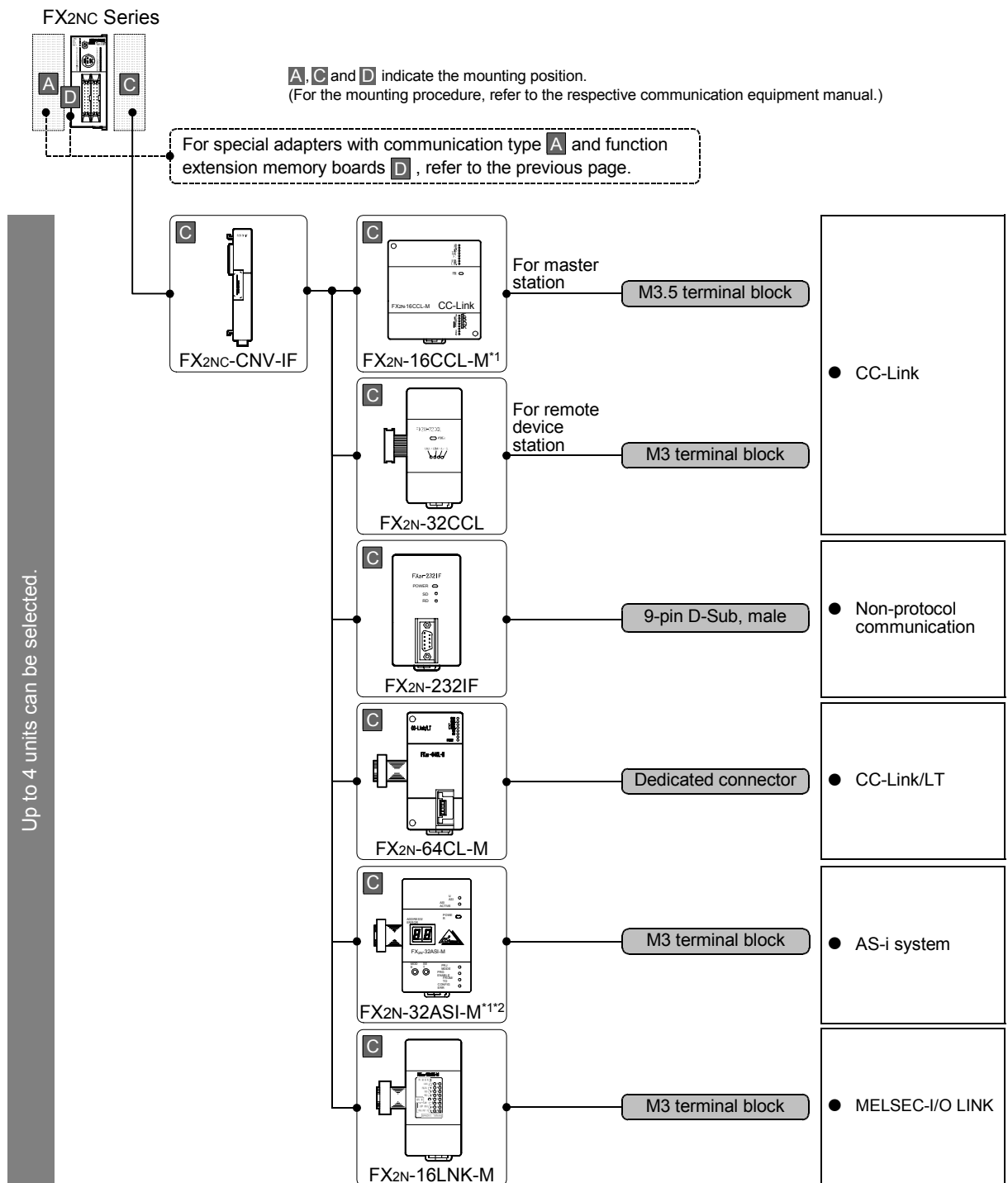
Limitation in the number of connectable units

Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Therefore, the total current consumption larger than the PLC current capacity reduces the number of connectable units.

→ For details, refer to the respective FX PLC manual.

2.3.7 For FX2NC Series





*1. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

*2. The FX2NC-□MT-D/UL and FX2NC-□M□-DSS(-T-DS) are not supported.

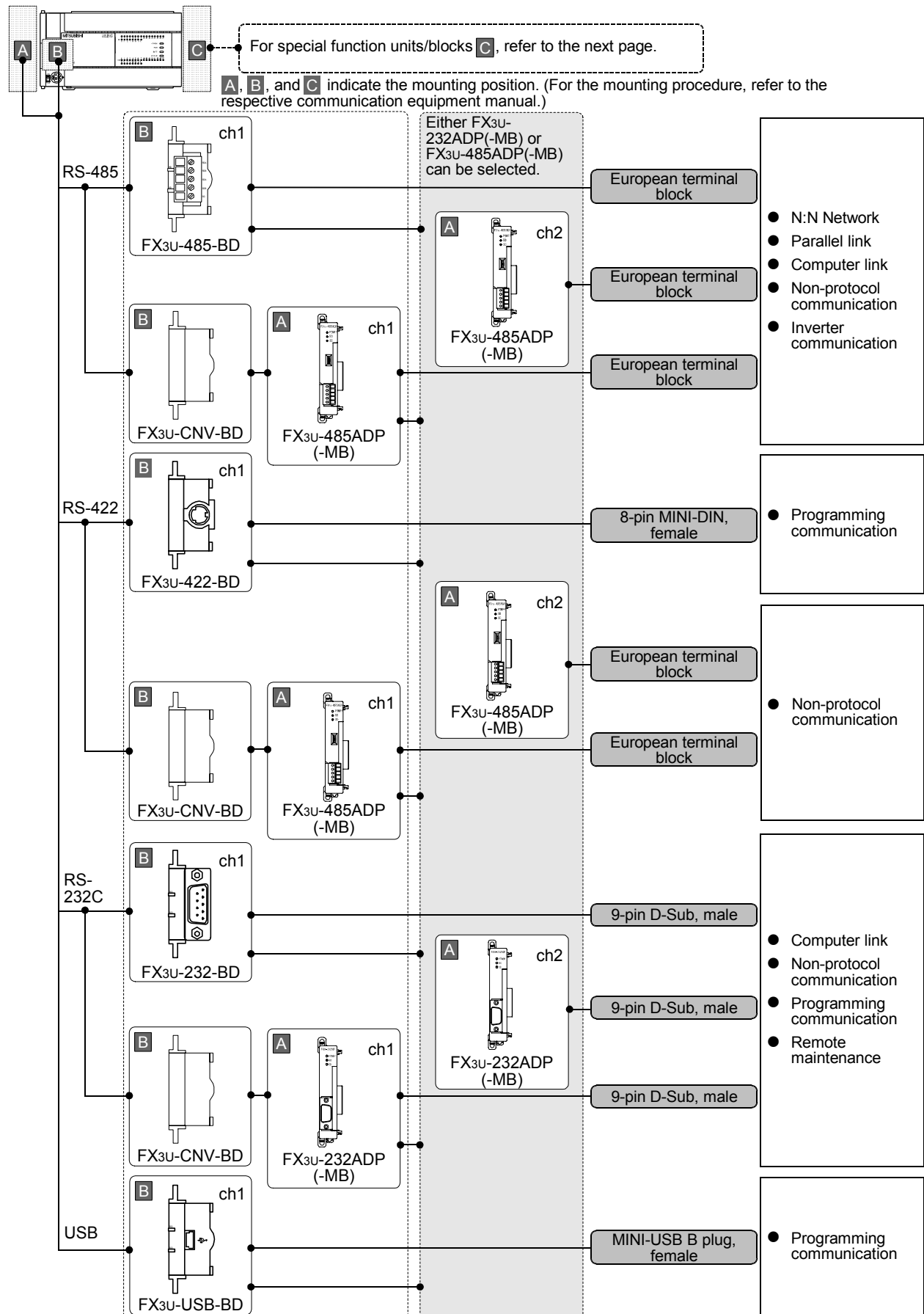
Limitation in the number of connectable units

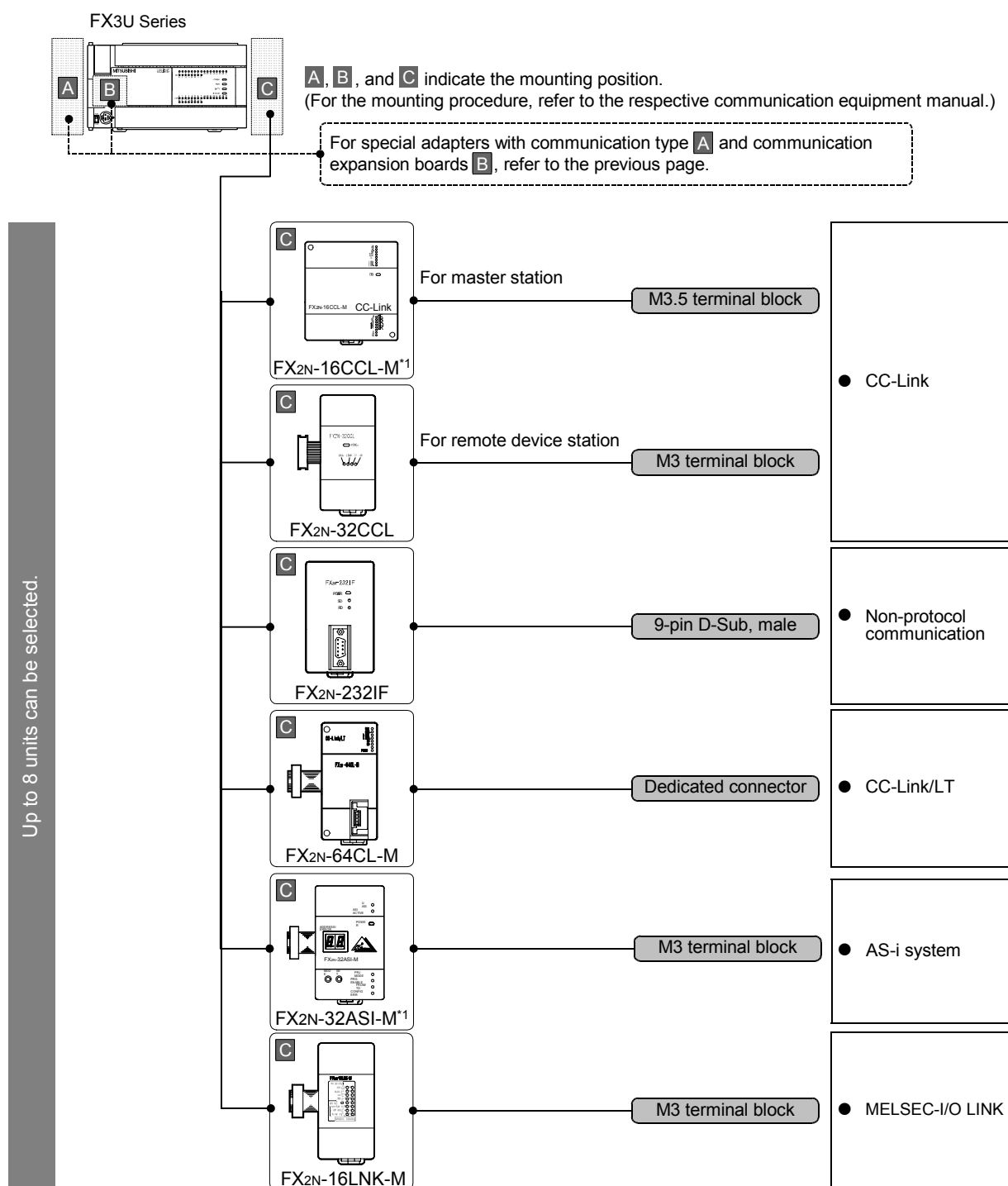
Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Therefore, the total current consumption larger than the plc current capacity reduces the number of connectable units.

→ For details, refer to the respective FX PLC manual.

2.3.8 For FX3U Series

FX3U Series





*1. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

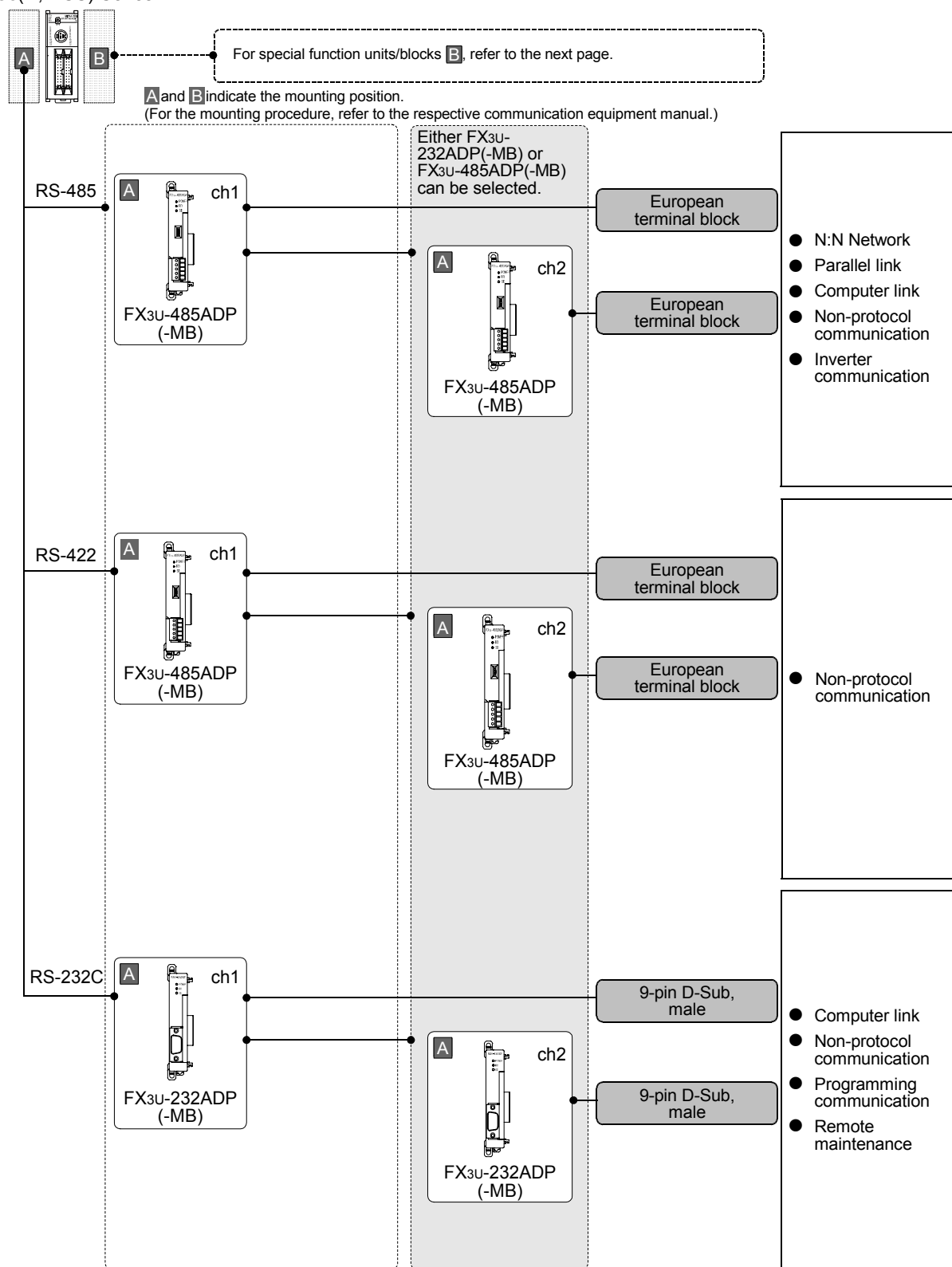
Limitation in the number of connectable units

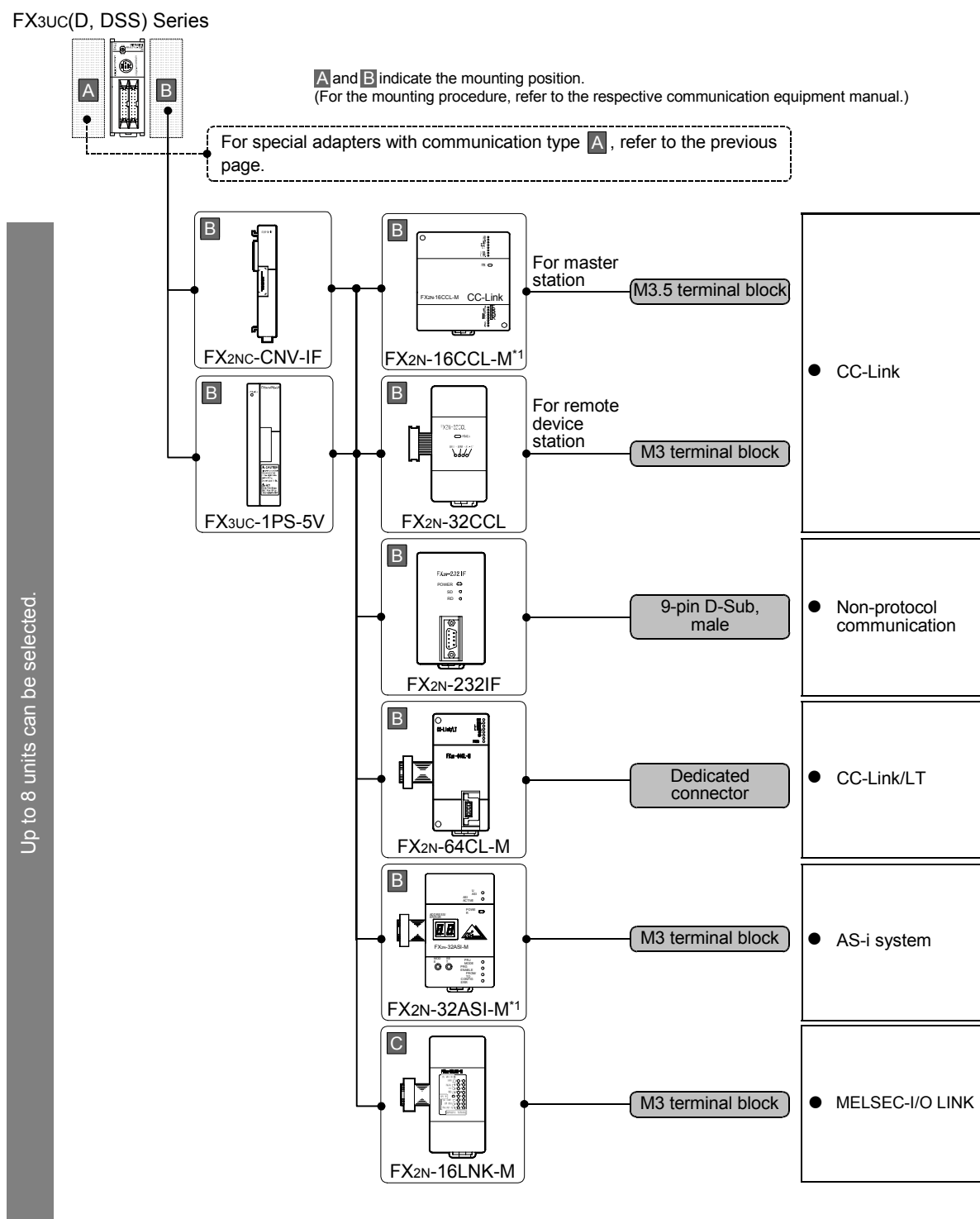
Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Therefore, the total current consumption larger than the plc current capacity reduces the number of connectable units.

→ For details, refer to the respective FX PLC manual.

2.3.9 For FX3uc(D, DSS) Series

FX3uc(D, DSS) Series





*1. The FX2N-16CCL-M and FX2N-32ASI-M cannot be used at the same time.

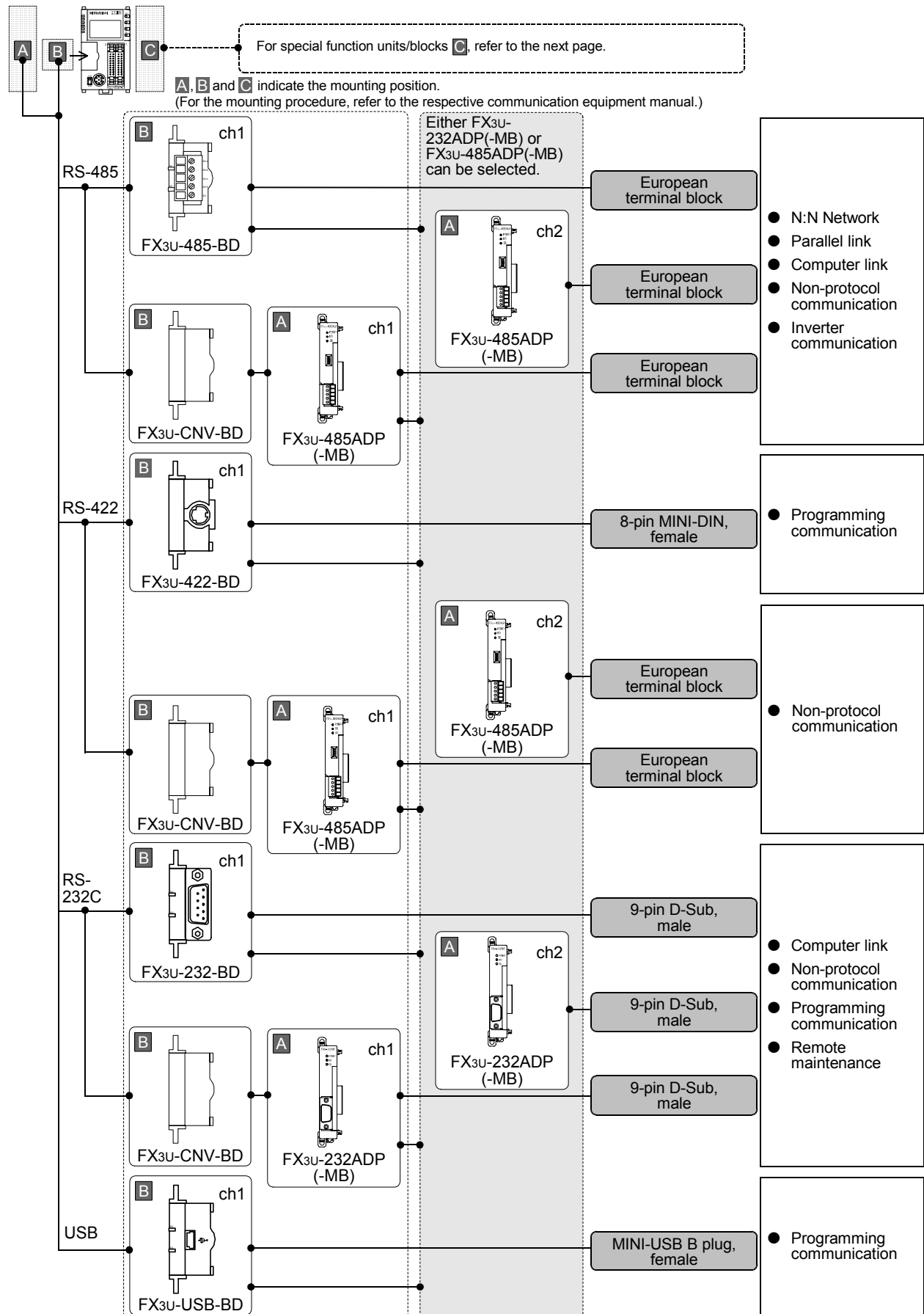
Limitation in the number of connectable units

Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Accordingly, when the total current consumption is larger than the current capacity of the PLC, it is necessary to add the power block FX3UC-1PS-5V.

→ For details, refer to the respective FX PLC manual.

2.3.10 For FX3UC-32MT-LT

FX3UC-32MT-LT

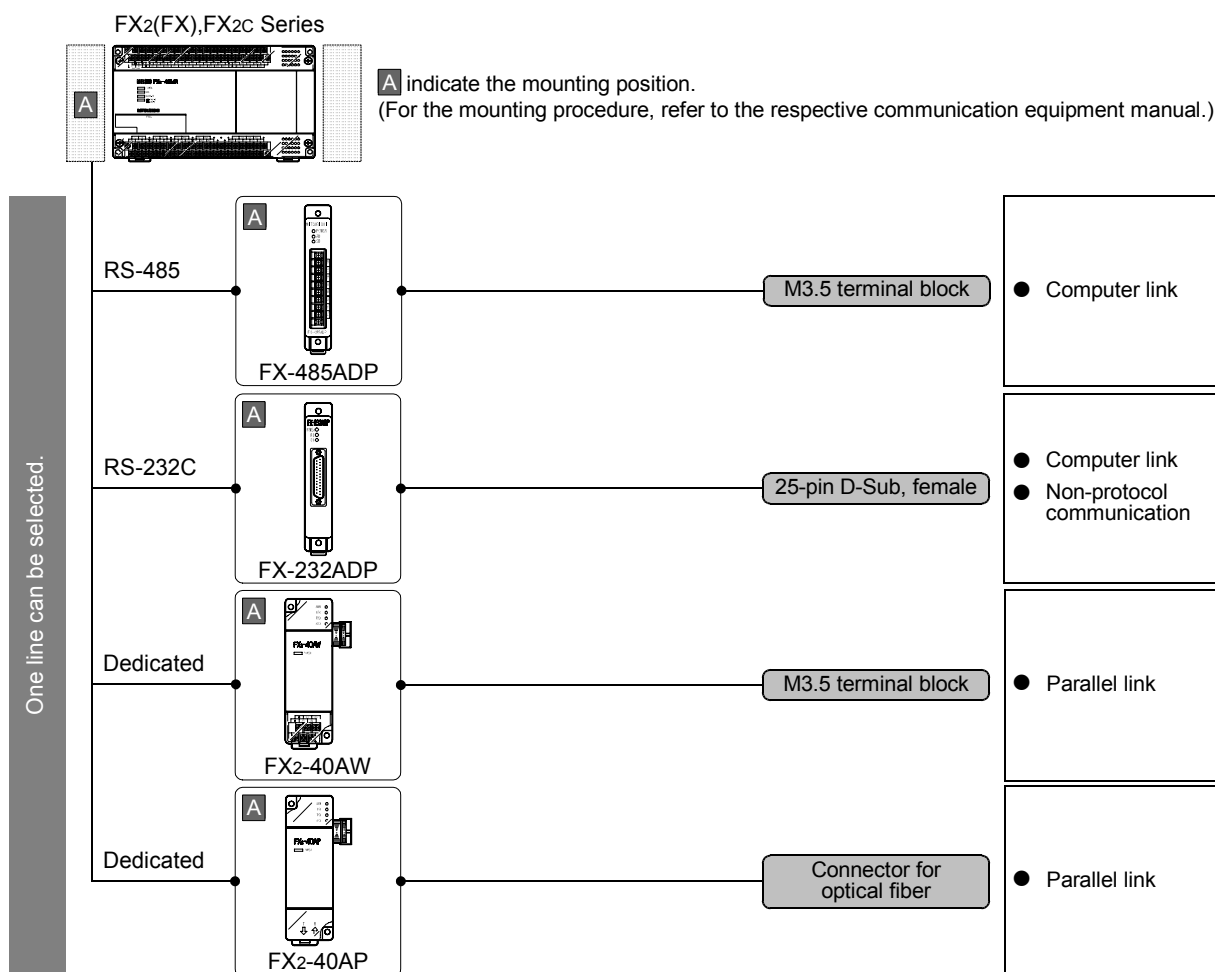




Connected special function units/blocks operate using the 24V DC or 5V DC power supply of the PLC. Accordingly, when the total current consumption is larger than the current capacity of the PLC, it is necessary to add the power block FX3UC-1PS-5V.

→ For details, refer to the respective FX PLC manual.

2.3.11 For FX2(FX) and FX2c Series (reference)



3. Outline of Communication Setting in the FX Series

This chapter describes which communication parameters can be changed for each communication type and provides methods on how to change them.

3.1 Setting Method

The following two communication setting methods are available for FX PLCs. Either method can be used, but the method using parameters is recommended.

1. Setting methods

- 1) Specify the settings using parameters in the sequence programming software
Register the settings in parameters, transfer it to the PLC and turn the PLC's power OFF and then ON.
(This method is not available in FX2(FX), FX2C, and FX0N PLCs.)
- 2) Directly specify the settings in a sequence program
Prepare a sequence program which sets the communication format, station number and time-out time setting, and then transfer the program to the PLC.

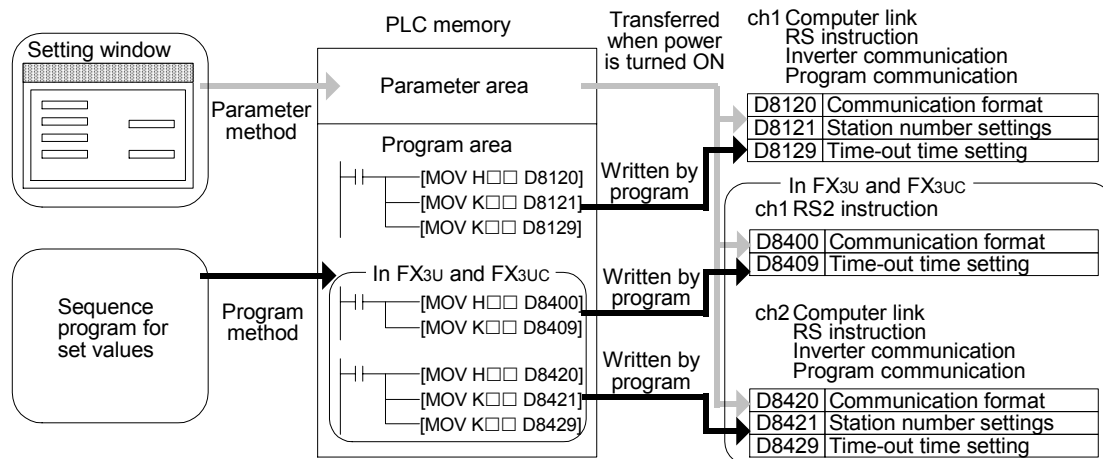
Caution

Regardless of the method chosen above, a PLC operates the same way. If both methods are selected, priority is given to the method using parameters.

2. Communication setting method availability in each FX PLC

| FX Series | FX2(FX),FX2C | FX0N | FX1S | FX1N,FX1NC | FX2N,FX2NC | FX3U,FX3UC |
|------------------|--------------|------|------|------------|------------|------------|
| Parameter method | — | — | ✓ | ✓ | ✓ | ✓ |
| Program method | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

3. Setting flow



4. Time at which the settings become valid

- 1) Specifying the settings using parameters in the sequence programming software:
When the PLC power is turned ON, the contents of the parameters are automatically transferred to the PLC.
As soon as the parameters are transferred to the PLC, the settings become valid.
- 2) Directly specifying the settings in a sequence program:
To enable the settings, write data after turning the PLC mode to RUN from STOP, and then reboot the PLC's power.

3.2 Communication Setting Using Parameter Method (GX Developer)

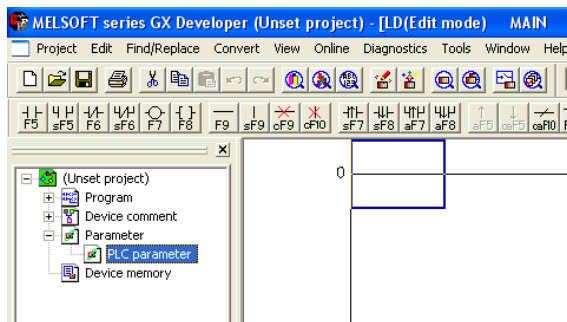
Communication settings may be changed by the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with GX Developer.

3.2.1 Operating procedure

With GX Developer open, follow the steps in this section for activating the serial communication setting method.

1 Opening the parameter setting window

Double-click [Parameter] - [PLC parameter] from the project tree.

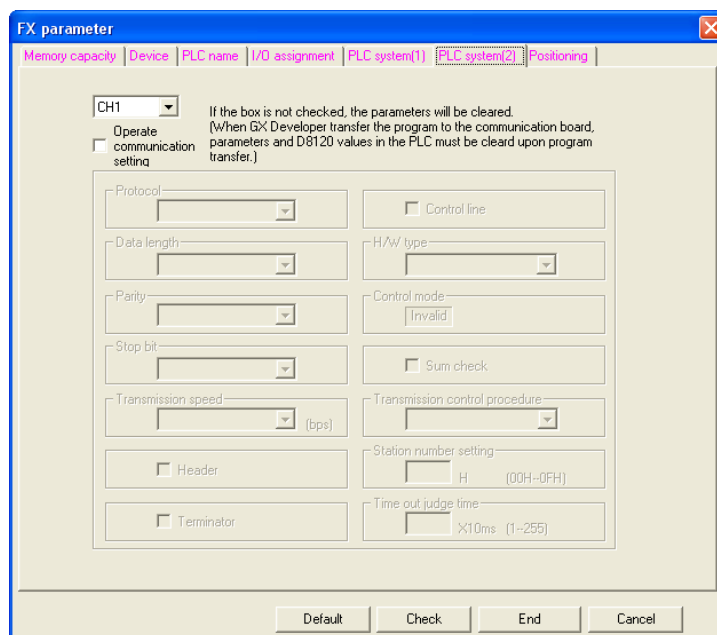


If the project tree is not displayed, select [View] - [Project data list] from the toolbar (to display a check mark on the left side).

2 Setting the serial communication (parameters)

Click the [PLC system(2)] tab on the dialog box.

- When using programming communication, parallel link, N:N Network or remote maintenance, do not check the "Operate communication setting" box.
- When using computer link, inverter communication or non-protocol communication (RS/RS2 instruction) function, check the "Operate communication setting" box, and then set each item.



3 Writing parameters to the PLC

Select [Online] - [Write to PLC] from the toolbar, put a check mark next to "Parameter", and then click [Execute].

3.2.2 Correspondence between parameter setting and each communication type

The table below shows the communication types and set items which can be set using parameters:

| Set item | Contents | CC-Link network | N:N Network | Parallel link | Computer link | Inverter communication | Non-protocol communication (RS/RS2 instruction) | Non-protocol communication (FX2N-232IF) | Short mail sending | Internet mail sending | CC-Link/LT network | AS-i system | Programming communication | Remote maintenance | Remarks | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
|--------------------------------|----------------------------|---|---|---|---------------|------------------------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|--|
| Protocol | Non-protocol communication | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | — | ✓ | ✓ | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Dedicated protocol | | | | ✓ | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Data length | 7-bit | | | | ✓ | ✓ | ✓ | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 8-bit | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Parity | None | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Odd | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | Even | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Stop bit | 1-bit | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 2-bit | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Transmission speed (bps) | 19200 | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 9600 | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 4800 | | | | ✓ | ✓ | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 2400 | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 1200 | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 600 | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | 300 | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Header | Invalid/valid | | | | — | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Terminator | Invalid/valid | | | | — | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Control cable | Invalid/valid | | | | — | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Hardware type | Regular/RS-232C | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | RS-485 | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Control mode | Invalid | | | | — | — | — | | | | | | | | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | | | | | | | | | | |
| Sum check | Invalid/valid | | | | ✓ | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Transmission control procedure | Format 1 | | | | ✓ | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | | | | | | | | | | |
| | Format 4 | | | | ✓ | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Station number settings | 00 to 0F | | | | ✓ | — | — | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | |
| Time-out time setting | 1 to 255 | | | | ✓ | — | ✓ | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| Reference page | | — | B | C | D | E | F | G | — | — | — | I | H | I | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |

| | |
|-------------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RS2 instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

3.3 Communication Setting in Parameter Method (FXGP/WIN)

Communication settings may be changed by the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with FXGP/WIN.
Ch 2 cannot be set using FXGP/WIN.

3.3.1 Operating procedure

This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

1 Adjusting serial setting (parameter)

Select [Option] - [Serial setting (parameter)] from the toolbar.

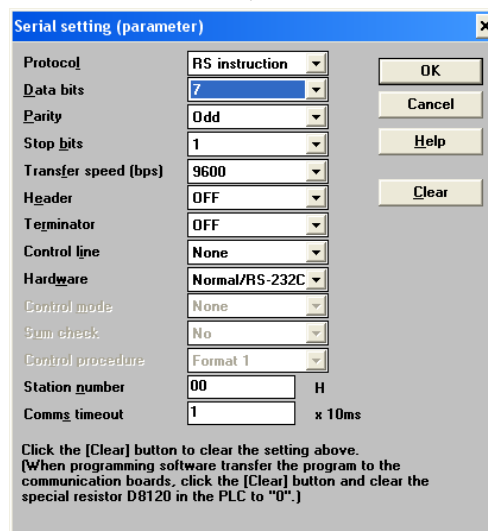
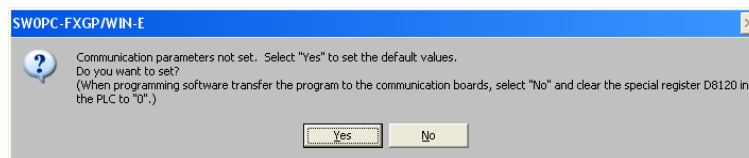
The following dialog appears according to absence/presence of parameter settings.

1. When there are no parameter settings

There is no communication setting.

When using the programming communication, parallel link, N:N Network or remote maintenance, click the [No] button.

When using computer link, inverter communication, or non-protocol communication (RS instruction) function, click the [Yes] button.



2. When there are already parameter settings

There is communication setting. Confirm the setting contents.
When using programming communication, parallel link, N:N Network or remote maintenance, click the [Clear] button.

Serial setting (parameter)

Protocol

RS instruction

OK

Data bits

7

Cancel

Parity

Odd

Help

Stop bits

1

Clear

Transfer speed (bps)

9600

Header

OFF

Terminator

OFF

Control line

None

Hardware

Normal/RS-232C

Control mode

None

Sum check

No

Control procedure

Format 1

Station number

00

H

Comms timeout

1

x 10ms

Click the [Clear] button to clear the setting above.

(When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".)

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/R52 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

3.3.2 Correspondence between parameter setting and each communication type

The table below shows the communication types and items which can be set using parameters:

| Set item | Contents | CC-Link network | N:N Network | Parallel link | Computer link | Inverter communication | Non-protocol communication (RS instruction) | Non-protocol communication (FX2N-232IF) | Short mail sending | Internet mail sending | CC-Link/LT network | AS-i system | Programming communication | Remote maintenance | Remarks |
|--------------------------------|----------------------------|---|---|---|---------------|------------------------|---|---|---|---|---|---|---|---|---|
| Protocol | Non-protocol communication | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | — | ✓ | ✓ | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. | This communication is not executed in this setting. |
| | Dedicated protocol | | | | ✓ | — | — | | | | | | | | |
| Data length | 7-bit | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | 8-bit | | | | ✓ | ✓ | ✓ | | | | | | | | |
| Parity | None | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | Odd | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | Even | | | | ✓ | ✓ | ✓ | | | | | | | | |
| Stop bit | 1-bit | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | 2-bit | | | | ✓ | ✓ | ✓ | | | | | | | | |
| Baud rate (bps) | 19200 | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | 9600 | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | 4800 | | | | ✓ | ✓ | ✓ | | | | | | | | |
| | 2400 | | | | ✓ | — | ✓ | | | | | | | | |
| | 1200 | | | | ✓ | — | ✓ | | | | | | | | |
| | 600 | | | | ✓ | — | ✓ | | | | | | | | |
| | 300 | | | | ✓ | — | ✓ | | | | | | | | |
| Header | Invalid/valid | | | | — | — | ✓ | | | | | | | | |
| Terminator | Invalid/valid | | | | — | — | ✓ | | | | | | | | |
| Control cable | Invalid/valid | | | | — | — | ✓ | | | | | | | | |
| Hardware type | Regular/RS-232C | | | | ✓ | — | ✓ | | | | | | | | |
| | RS-485 | | | | ✓ | ✓ | ✓ | | | | | | | | |
| Control mode | Invalid | | | | — | — | — | | | | | | | | Not selectable |
| Sum check | Invalid/valid | | | | ✓ | — | — | | | | | | | | |
| Transmission control procedure | Format 1 | | | | ✓ | — | — | | | | | | | | |
| | Format 4 | | | | ✓ | — | — | | | | | | | | |
| Station number settings | 00 to 0F | | | | ✓ | — | — | | | | | | | | |
| Time-out time setting | 1 to 255 | | | | ✓ | — | ✓ | | | | | | | | |
| Reference page | | — | B | C | D | E | F | G | — | — | — | — | H | I | |

3.4 Extension of Ports (FX3U, FX3UC)

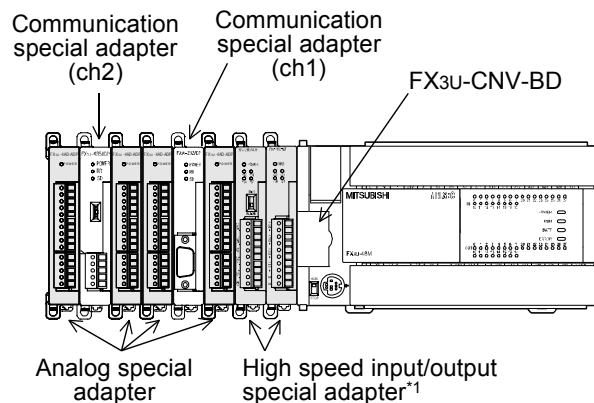
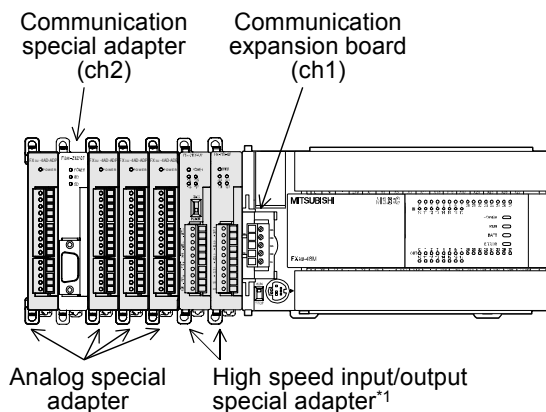
In FX3U and FX3UC PLCs, up to two channels of communication ports can be connected to the main unit. When a communication expansion board and communication special adapter are used, the board is handled as ch 1 and the adapter is handled as ch 2.

When connecting two communication special adapters using the FX3U-CNV-BD*1, the one closer to the main unit is handled as ch 1 and the farther one is handled as ch 2.

*1. When using the FX3UC(D,DSS) PLC, the FX3U-CNV-BD is not required.

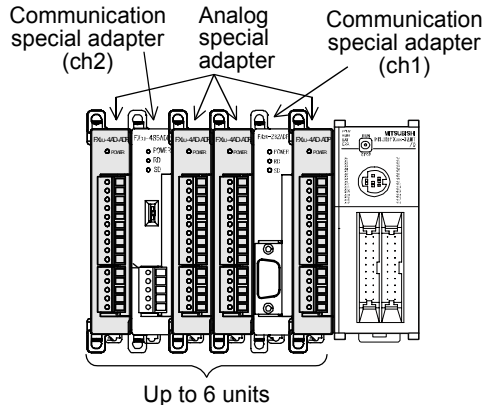
1. For FX3U PLC

- When using a communication expansion board and a communication special adapter together
- When using two communication special adapters



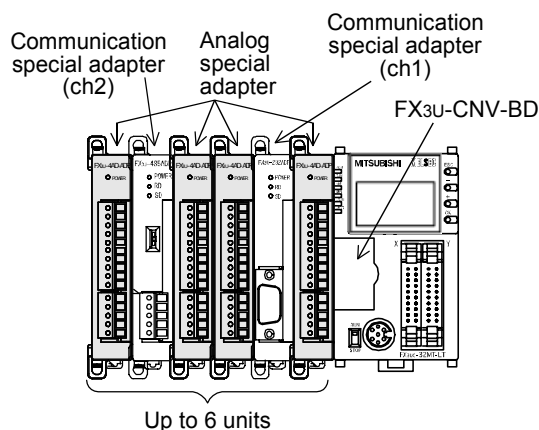
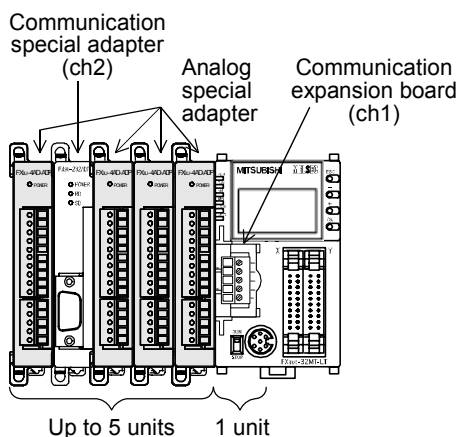
*1. When using high speed special input/output adapters, make sure to connect them to the PLC main unit first before connecting communication special adapters and analog special adapters.

2. For FX3UC(D,DSS) PLC



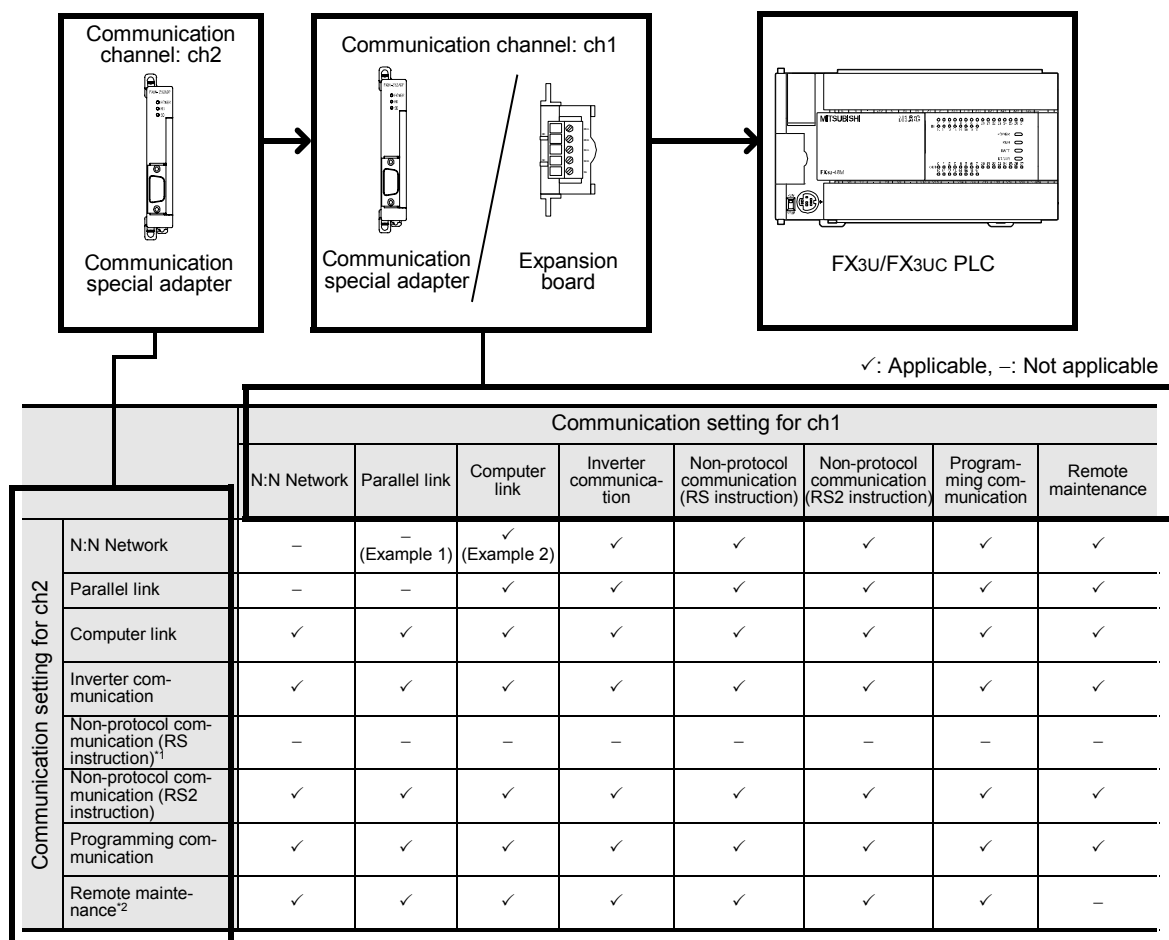
3. For FX3UC-32MT-LT PLC

- When using a communication expansion board and a communication special adapter together
- When using two communication special adapters



3.4.1 Limitation when ch1 and ch2 are used at the same time

When using ch1 and ch2 at the same time, available communication type combinations are limited. For details, refer to the table below.



*1. Ch2 cannot be set for non-protocol communication (RS instruction).

*2. When using remote maintenance on ch2, use the GX Developer Ver. 8.18U or later.

Example 1:

When "parallel link" is set for ch1, the "N:N Network" cannot be set for ch2.

Example 2:

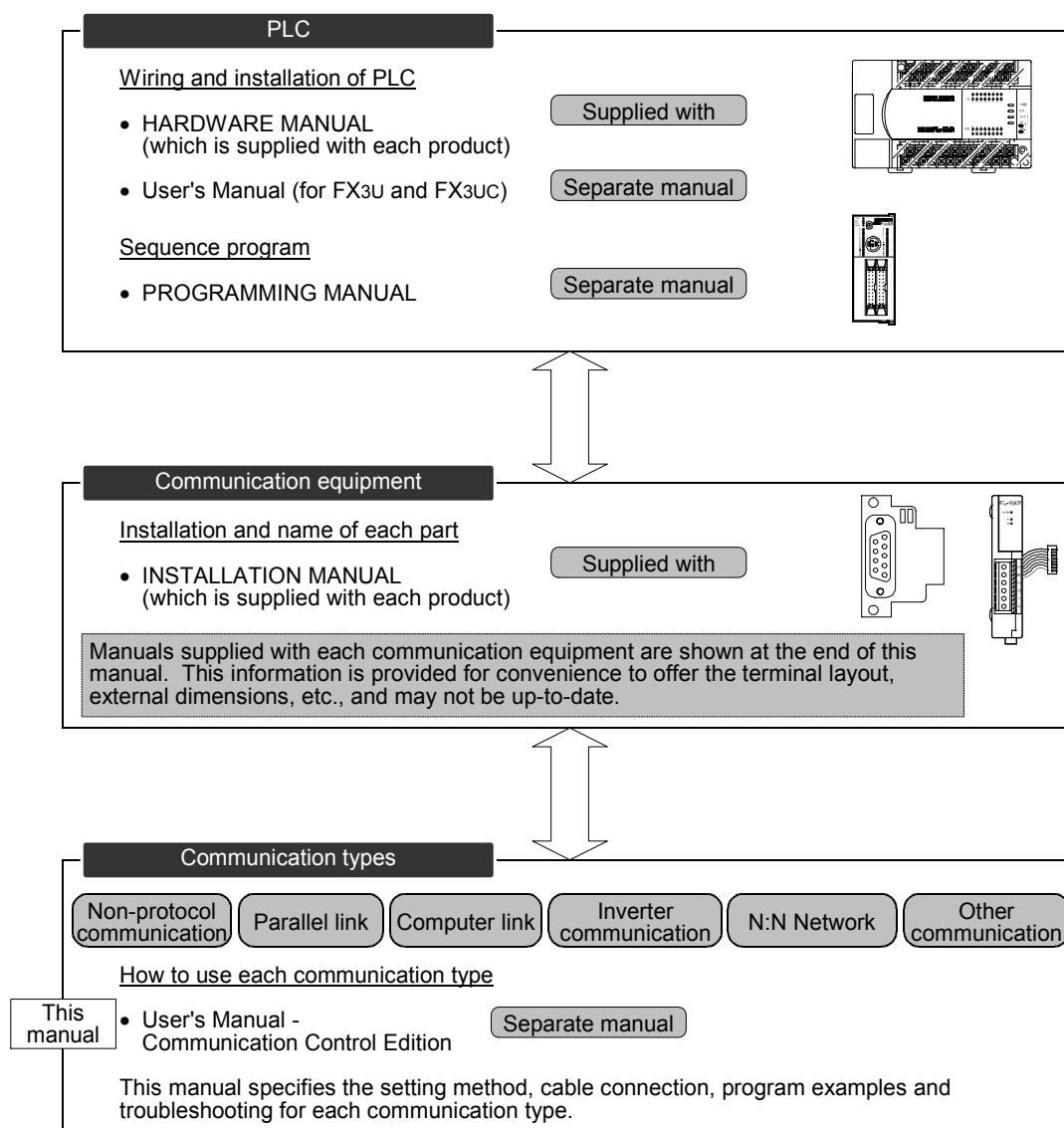
When "computer link" is set for ch1, the "N:N Network" can be set for ch2.

4. Introduction of Manuals (Type, Reading Method and Acquisition Method)

This chapter specifies the manuals related to PLC main units for each communication type.

4.1 Rank and Use Method of This Manual

When communication equipment is connected, an FX PLC can offer various communication options.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

4.2 Introduction of Related Manuals

This section shows major manuals required to use the communication types.
Manuals for PLC main units and manuals for communication equipment are classified separately.
"Separate manual" shown in the "Included/separate manual" column indicates that the manual is supplied separately. "Included" indicates that the manual is included with each product.

4.2.1 Manual for communication types in FX PLCs

| Manual name | Manual number | Included/separate document | Contents |
|---|---------------|-------------------------------|--|
| FX Series | | | |
| FX Series User's Manual - Data Communication Edition | JY997D16901 | Separate manual (this manual) | Describes the contents of communication types supported by FX Series PLCs. |
| FX3U Series User's Manual - MODBUS Serial Communication Edition | JY997D26201 | Separate manual | Explains the MODBUS serial communication network in FX3U PLCs. |

4.2.2 Manuals related to FX PLCs

For instructions used in sequence programs, refer to the PROGRAMMING MANUAL.
For hardware specifications and wiring of the PLC, refer to the HANDY MANUAL or USERS MANUAL.

| Manual name | Manual number | Included/separate document | Contents |
|---|---------------|----------------------------|--|
| FX3U Series | | | |
| FX3U Series Hardware Manual | JY997D18801 | Included | Describes the contents of the FX3U PLC main unit hardware including the specifications, wiring and installation procedure. |
| FX3U Series User's Manual - Hardware Edition | JY997D16501 | Separate manual | Describes the contents of the FX3U PLC main unit and extension unit hardware including specifications, wiring and installation procedure. |
| FX3U/FX3UC Programming Manual - Basic & Applied Instruction Edition | JY997D16601 | Separate manual | Explains basic instructions and applied instructions available in the FX3U/3UC PLC. |
| FX3UC Series | | | |
| FX3UC(D, DSS) Series Hardware Manual | JY997D28601 | Included | Describes the contents of the FX3UC(D, DSS) PLC main unit hardware including the specifications, wiring and installation procedure. |
| FX3UC Series User's Manual - Hardware Edition | JY997D28701 | Separate manual | Describes the contents of the FX3UC PLC main unit and extension unit hardware including specifications, wiring and installation procedure. |
| FX3U/FX3UC Programming Manual - Basic & Applied Instruction Edition | JY997D16601 | Separate manual | Explains basic instructions and applied instructions available in the FX3U/3UC PLC. |
| FX2NC Series | | | |
| FX2NC HARDWARE MANUAL | JY992D76401 | Included | Describes the contents of the FX2NC PLC hardware including the specifications, wiring and installation procedure. |
| FX1S,FX1N,FX2N,FX1NC,FX2NC PROGRAMMING MANUAL | JY992D88101 | Separate manual | Explains instructions applicable in the FX1S, FX1N, FX2N, FX1NC and FX2NC PLCs. |

| Manual name | Manual number | Included/separate document | Contents |
|--|---------------|----------------------------|---|
| FX1NC Series*1 | | | |
| FX1NC HANDY MANUAL | JY992D92101 | Included | Describes the contents of the FX1NC PLC hardware including the specifications, wiring and installation procedure. |
| FX1S,FX1N,FX2N,FX1NC,FX2NC PROGRAMMING MANUAL | JY992D88101 | Separate manual | Explains instructions available in the FX1S, FX1N, FX2N, FX1NC and FX2NC PLCs. |
| FX2N Series | | | |
| FX2N HARDWARE MANUAL | JY992D66301 | Included | Describes the contents of the FX2N PLC hardware including the specifications, wiring and installation procedure. |
| FX1S,FX1N,FX2N,FX1NC,FX2NC PROGRAMMING MANUAL | JY992D88101 | Separate manual | Explains instructions available in the FX1S, FX1N, FX2N, FX1NC and FX2NC PLCs. |
| FX1N Series | | | |
| FX1N HARDWARE MANUAL | JY992D89301 | Included | Describes the contents of the FX1N PLC hardware including the specifications, wiring and installation procedure. |
| FX1S,FX1N,FX2N,FX1NC,FX2NC PROGRAMMING MANUAL II | JY992D88101 | Separate manual | Explains instructions available in the FX1S, FX1N, FX2N, FX1NC and FX2NC PLCs. |
| FX1S Series | | | |
| FX1S HARDWARE MANUAL | JY992D83901 | Included | Describes the contents of the FX1S PLC hardware including the specifications, wiring and installation procedure. |
| FX1S,FX1N,FX2N,FX1NC,FX2NC PROGRAMMING MANUAL II | JY992D88101 | Separate manual | Explains instructions available in the FX1S, FX1N, FX2N, FX1NC and FX2NC PLCs. |
| FX0N Series | | | |
| FX0N HARDWARE MANUAL | JY992D47501 | Included | Describes the contents of the FX0N PLC hardware including the specifications, wiring and installation procedure. |
| FX0,FX0S,FX0N,FX1,FX2(FX),FX2C PROGRAMMING MANUAL | JY992D48301 | Separate manual | Explains instructions available in the FX0, FX0S, FX0N, FX1, FX2(FX), FX2C PLCs. |
| FX2(FX) Series | | | |
| FX2(FX) HARDWARE MANUAL | JY992D47401 | Included | Describes the contents of the FX2(FX) PLC hardware including the specifications, wiring and installation procedure. |
| FX0,FX0S,FX0N,FX1,FX2(FX),FX2C PROGRAMMING MANUAL | JY992D48301 | Separate manual | Explains instructions available in the FX0, FX0S, FX0N, FX1, FX2(FX), FX2C PLCs. |
| FX2C Series*2 | | | |
| FX2C HANDY MANUAL | JY992D59001 | Included | Describes the contents of the FX2C PLC hardware including the specifications, wiring and installation procedure. |
| FX0,FX0S,FX0N,FX1,FX2(FX),FX2C PROGRAMMING MANUAL | JY992D48301 | Separate manual | Explains instructions available in the FX0, FX0S, FX0N, FX1, FX2(FX), FX2C PLCs. |

*1. FX1NC Series PLC Manual is available only in Japanese.

*2. FX2C Series PLC Manual is available only in Japanese.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

4.2.3 Communication equipment (option)

The table below specifies the manuals for communication equipment operating in accordance with RS-232C, RS-422 and RS-485.

| Manual name | Manual number | Included/separate document | Contents |
|--|---------------|----------------------------|---|
| For communication in accordance with RS-232C | | | |
| FX3U-232-BD INSTALLATION MANUAL | JY997D12901 | Included | Describes the contents of the RS-232C communication expansion board, FX3U-232-BD hardware including the specifications and installation procedure. |
| FX3U-232ADP INSTALLATION MANUAL | JY997D13701 | Included | Describes the contents of the RS-232C communication special adapter, FX3U-232ADP hardware including the specifications and installation procedure. |
| FX3U-232ADP-MB INSTALLATION MANUAL | JY997D26401 | Included | Handling procedures of the RS-232C communication special adapter. For the MODBUS serial communication network, refer to the FX3U Series User's Manual - MODBUS Serial Communication Edition. For computer link or non-protocol communication by RS and RS2 instructions, refer to the FX Series User's Manual - Data Communication Edition. |
| FX-232ADP USER'S GUIDE | JY992D48801 | Included | Describes the contents of the RS-232C communication special adapter, FX-232ADP hardware including the specifications and installation procedure. |
| FX0N-232ADP INSTALLATION MANUAL | JY992D51201 | Included | Describes the contents of the RS-232C communication special adapter, FX0N-232ADP hardware including the specifications and installation procedure. |
| FX2NC-232ADP INSTALLATION MANUAL | JY997D01101 | Included | Describes the contents of the RS-232C communication special adapter, FX2NC-232ADP hardware including the specifications and installation procedure. |
| FX2N-232-BD USER'S GUIDE | JY992D63201 | Included | Describes the contents of the RS-232C communication expansion board, FX2N-232-BD hardware including the specifications and installation procedure. |
| FX1N-232-BD USER'S GUIDE | JY992D84401 | Included | Describes the contents of the RS-232C communication expansion board, FX1N-232-BD hardware including the specifications and installation procedure. |
| FX2N-232IF HARDWARE MANUAL | JY992D73501 | Included | Describes the contents of the RS-232C communication special extension block, FX2N-232IF hardware including the specifications and installation procedure. |
| For communication in accordance with RS-422 | | | |
| FX3U-422-BD INSTALLATION MANUAL | JY997D13101 | Included | Describes the contents of the RS-422 communication expansion board, FX3U-422-BD hardware including the specifications and installation procedure. |
| FX2N-422-BD USER'S GUIDE | JY992D66101 | Included | Describes the contents of the RS-422 communication expansion board, FX2N-422-BD hardware including the specifications and installation procedure. |
| FX1N-422-BD USER'S MANUAL | JY992D84101 | Included | Describes the contents of the RS-422 communication expansion board, FX1N-422-BD hardware including the specifications and installation procedure. |

| Manual name | Manual number | Included/separate document | Contents |
|--|---------------|----------------------------|---|
| For communication in accordance with RS-485(422) | | | |
| FX3U-485-BD INSTALLATION MANUAL | JY997D13001 | Included | Describes the contents of the RS-485 communication special expansion board, FX3U-485-BD hardware including the specifications and installation procedure. |
| FX3U-485ADP INSTALLATION MANUAL | JY997D13801 | Included | Describes the contents of the RS-485 communication special adapter, FX3U-485-ADP hardware including the specifications and installation procedure. |
| FX3U-485ADP-MB INSTALLATION MANUAL | JY997D26301 | Included | Handling procedures of the RS-485 communication special adapter. For the MODBUS serial communication network, refer to the FX3U Series User's Manual - MODBUS Serial Communication Edition. For N:N link, parallel link, computer link or non-protocol communication by RS and RS2 instructions, refer to the FX Series User's Manual - Data Communication Edition. |
| FX0N-485ADP INSTALLATION MANUAL | JY992D53101 | Included | Describes the contents of the RS-485 communication special adapter, FX0N-485-ADP hardware including the specifications and installation procedure. |
| FX2NC-485ADP INSTALLATION MANUAL | JY997D01201 | Included | Describes the contents of the RS-485 communication special adapter, FX2NC-485-ADP hardware including the specifications and installation procedure. |
| FX2N-485-BD HARDWARE MANUAL | JY992D73401 | Included | Describes the contents of the RS-485 communication expansion board, FX2N-485-BD including the specifications and installation procedure. |
| FX1N-485-BD USER'S GUIDE | JY992D84201 | Included | Describes the contents of the RS-485 communication expansion board, FX1N-485-BD hardware including the specifications and installation procedure. |
| For communication in accordance with USB | | | |
| FX3U-USB-BD USER'S MANUAL | JY997D13501 | Included | Describes the contents of the USB communication expansion board, FX3U-USB-BD hardware including the specifications and installation procedure. |

4.2.4 Related options for communication

The table below specifies the manuals for products required to use the options above in the system configuration.

| Manual name | Manual number | Included/separate document | Contents |
|--|---------------|----------------------------|---|
| Connector conversion board | | | |
| FX3U-CNV-BD INSTALLATION MANUAL | JY997D13601 | Included | Describes the contents of the FX3U-CNV-BD special adapter connection board hardware including the installation procedure. |
| FX2N-CNV-BD | JY992D63601 | Included | Describes the contents of the FX2N-CNV-BD special adapter connection board hardware including the installation procedure. |
| FX1N-CNV-BD | JY992D84701 | Included | Describes the contents of the FX1N-CNV-BD special adapter connection board hardware including the installation procedure. |
| RS-485/RS-232C converter for computer link communication | | | |
| FX-485-PC-IF-SET HARDWARE MANUAL | JY992D81801 | Included | Describes the contents of the FX-485-PC-IF-SET interface unit hardware including the specifications and installation procedure. |

5. Abbreviations, Generic Names and Terms Used in This Manual

The table below shows abbreviations, generic names and terms used in this manual.

1. Programmable controllers

| Abbreviation/ generic name | Name |
|---------------------------------|--|
| Programmable controllers | |
| FX PLC or FX CPU | Generic name of FX0, FX0S, FX1S, FX0N, FX1N, FX1, FX2(FX), FX2C, FX2N, FX3U, FX1NC, FX2NC, and FX3UC Series PLCs |
| FX3U Series | Generic name of FX3U Series PLCs |
| FX3U PLC or main unit | Generic name of FX3U Series PLC main units |
| FX3UC Series | Generic name of FX3UC Series PLCs |
| FX3UC PLC or main unit | Generic name of FX3UC Series PLC main units |
| FX2N Series | Generic name of FX2N Series PLCs |
| FX2N PLC or main unit | Generic name of FX2N Series PLC main units |
| FX2NC Series | Generic name of FX2NC Series PLCs |
| FX2NC PLC or main unit | Generic name of FX2NC-□M□(-T), FX2NC-□MT-D/UL, and FX2NC-□M□-DSS(-T-DS) Series PLC main units |
| FX2NC-□M□(-T) PLC | FX2NC-16MR-T, FX2NC-16MT, FX2NC-32MT, FX2NC-64MT, and FX2NC-96MT |
| FX2NC-□MT-D/UL PLC | FX2NC-16MT-D/UL, FX2NC-32MT-D/UL, FX2NC-64MT-D/UL, and FX2NC-96MT-D/UL |
| FX2NC-□M□-DSS (-T-DS) PLC | FX2NC-16MR-T-DS, FX2NC-16MT-DSS, FX2NC-32MT-DSS, FX2NC-64MT-DSS, and FX2NC-96MT-DSS |
| FX1N Series | Generic name of FX1N Series PLCs |
| FX1N PLC or main unit | Generic name of FX1N Series PLC main units |
| FX1NC Series | Generic name of FX1NC Series PLCs |
| FX1NC PLC or main unit | Generic name of FX1NC Series PLC main units Only Japanese manual is available for this product. |
| FX1S Series | Generic name of FX1S Series PLCs |
| FX1S PLC or main unit | Generic name of FX1S Series PLC main units |
| FX2(FX) Series | Generic name of FX2(FX) Series PLCs |
| FX2(FX) PLC or main unit | Generic name of FX2(FX) Series PLC main units |
| FX2C Series | Generic name of FX2C Series PLCs |
| FX2C PLC or main unit | Generic name of FX2C Series PLC main units |
| FX1 Series | Generic name of FX1 Series PLCs |
| FX1 PLC or main unit | Generic name of FX1 Series PLC main units Only Japanese manual is available for this product. |
| FX0N Series | Generic name of FX0N Series PLCs |
| FX0N PLC or main unit | Generic name of FX0N Series PLC main units |
| FX0 Series | Generic name of FX0 Series PLCs |
| FX0 PLC or main unit | Generic name of FX0 Series PLC main units |

| Abbreviation/ generic name | Name |
|-------------------------------|---|
| FX0s Series | Generic name of FX0s Series PLCs |
| FX0s PLC or main unit | Generic name of FX0s Series PLC main units |
| Q PLC | Generic name of CPU units QCPU (Q mode) and QCPU (A mode) |
| QCPU (Q mode) | Generic name of CPU units Q00JCPU, Q00CPU, Q01CPU, Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU, and Q25HCPU |
| QCPU (A mode) | Generic name of CPU units Q02CPU-A, Q02HCPU-A, and Q06HCPU-A |
| QnA PLC | Generic name of CPU units QnACPU (large type) and QnACPU (small type) |
| QnACPU (large type) | Generic name of CPU units Q2ACPU, Q2ACPU-S1, Q3ACPU, Q4ACPU, and Q4ARCPU |
| QnACPU (small type) | Generic name of CPU units Q2ASCPU, Q2ASCPU-S1, Q2ASHCPU, and Q2ASHCPU-S1 |
| A PLC | Generic name of CPU units ACPU (large type), ACPU (small type), and A1FXCPU |
| ACPU (large type) | Generic name of CPU units AnUCPU, AnACPU, AnNCPU, and A0J2(H)CPU |
| ACPU (small type) | Generic name of CPU units A2US(H)CPU, AnS(H)CPU, and A1SJ(H)CPU |
| A1FXCPU | Generic name of CPU unit A1FXCPU |

2. Expansion boards and special adapters

| Abbreviation/ generic name | Name |
|--|--|
| Expansion board | |
| Expansion board | Generic name of communication expansion boards and special adapter connection boards |
| Communication expansion board or communication board | Generic name of communication expansion boards |
| 232BD | FX3U-232-BD, FX2N-232-BD, and FX1N-232-BD |
| 422BD | FX3U-422-BD, FX2N-422-BD, and FX1N-422-BD |
| 485BD | FX3U-485-BD, FX2N-485-BD, and FX1N-485-BD |
| USBBD | FX3U-USB-BD |
| Special adapter connection board or connector conversion board | Generic name of CNVBD |
| CNVBD | FX3U-CNV-BD, FX2N-CNV-BD, and FX1N-CNV-BD |
| Special adapters | |
| Special adapter | Generic name of high speed input/output special adapters, communication special adapters and analog special adapters |
| High speed input/output special adapter | Generic name of high speed input/output special adapters |
| 2HSY-ADP | FX3U-2HSY-ADP |
| 4HSX-ADP | FX3U-4HSX-ADP |
| Communication special adapter or communication adapter | Generic name of communication special adapters |
| 232ADP | FX3U-232ADP(-MB), FX2NC-232ADP, FX0N-232ADP, and FX-232ADP |
| 485ADP | FX3U-485ADP(-MB), FX2NC-485ADP, FX0N-485ADP, and FX-485ADP |

3. Extension equipment

| Abbreviation/ generic name | Name |
|-------------------------------|---|
| Extension equipment | |
| Extension equipment | Generic name of extension blocks, powered extension units, special function blocks and special function units |
| Special function unit | Generic name of special function units |
| Special function block | Generic name of special function block |
| 232IF | Generic name of FX2N-232IF |

4. Networks

| Abbreviation/ generic name | Name |
|--|--|
| Open field networks CC-Link and CC-Link/LT | |
| CC-Link equipment | Generic name of CC-Link master station and CC-Link remote device stations |
| CC-Link master (station) | Generic name of CC-Link master station with model name FX2N-16CCL-M |
| CC-Link remote station | Generic name of remote I/O stations and remote device stations |
| CC-Link/LT equipment | Generic name of CC-Link/LT master station, CC-Link/LT remote I/O stations, power supply adapters, and dedicated power supplies |
| CC-Link/LT master | Generic name of built-in type CC-Link/LT master and (additional) CC-Link/LT master |
| Built-in type CC-Link/LT master | Generic name of built-in type CC-Link/LT master built in to the FX3UC-32MT-LT |
| (Additional) CC-Link/LT master | Generic name of CC-Link/LT master station with model name FX2N-64CL-M |
| Power supply adapter | Generic name of units connecting the power supply to the CC-Link/LT system |
| Dedicated power supply | Generic name of power supplies connected to the CC-Link/LT system |
| AS-i system | |
| AS-i master | Generic name of AS-i system master station with model name FX2N-32ASI-M |
| MESEC I/O LINK | |
| MELSEC I/O LINK master | Generic name of MELSEC I/O LINK master station with model name FX2N-16LNK-M |

5. Peripheral equipment

| Abbreviation/ generic name | Name |
|-------------------------------|---|
| Peripheral equipment | |
| Peripheral equipment | Generic name of programming software, handy programming panels, and display units |
| Programming tools | |
| Programming tool | Generic name of programming software and handy programming panels |
| Programming software | Generic name of programming software |
| GX Developer | Generic name of programming software packages SW□D5C-GPPW-J and SW□D5C-GPPW-E |
| FXGP/WIN | Generic name of programming software packages FX-PCS/WIN and FX-PCS/WIN-E |
| Handy programming panel (HPP) | Generic name of FX-20P(-E) and FX-10P(-E) |
| RS-232C/RS-422 converter | FX-232AW, FX-232AWC, and FX-232AWC-H |
| RS-232C/RS-485 converter | FX-485PC-IF-SET and FX-485PC-IF |

| Abbreviation/ generic name | Name |
|------------------------------------|--|
| Display units | |
| GOT1000 Series | Generic name of GT15, GT11 and GT10 |
| GOT-900 Series | Generic name of GOT-A900 and GOT-F900 Series |
| GOT-A900 Series | Generic name of GOT-A900 Series |
| GOT-F900 Series | Generic name of GOT-F900 Series |
| Internet mail sending tools | |
| Mail sending units | Generic name of FX-232DOPA mail sending units |
| FX-232DOPA | FX-232DOPA mail sending main units Only Japanese manual is available for this product. These products can only be used in Japan. |

6. Others

| Abbreviation/ generic name | Name |
|--|--|
| Inverters | |
| FREQROL inverter | Generic name of Mitsubishi F700, A700, V500, F500, A500, E500, and S500 Series inverters |
| Communication | |
| Communication equipment | Generic name of communication equipment operating in accordance with RS-232C, communication equipment operating in accordance with RS-422, communication equipment operating in accordance with RS-485, and communication equipment operating in accordance with USB |
| Communication equipment operating in accordance with RS-232C | Generic name of 232BD, 232ADP, and 232IF |
| Communication equipment operating in accordance with RS-422 | Generic name of 422BD |
| Communication equipment operating in accordance with RS-485 | Generic name of 485BD and 485ADP |
| Communication equipment operating in accordance with USB | Generic name of USB BD |
| Personal computers | |
| Personal computer | Personal computers supporting Windows in which GX Developer or FXGP/WIN is installed |
| Windows | Generic name of Windows95, Windows98, WindowsMe, WindowsNT4.0, Windows2000, and WindowsXP |
| Windows95 | Abbreviation of Microsoft® Windows® 95 |
| Windows98 | Abbreviation of Microsoft® Windows® 98 |
| WindowsMe | Abbreviation of Microsoft® Windows® Millennium Edition |
| WindowsNT4.0 | Abbreviation of Microsoft® WindowsNT®4.0 Workstation |
| Windows2000 | Abbreviation of Microsoft® Windows® 2000 Professional |
| WindowsXP | Abbreviation of Microsoft® Windows® XP Professional and Microsoft® Windows® XP Home Edition |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

MEMO

FX Series Programmable Controllers

User's Manual [N:N Network]

Foreword

This manual explains the "N:N Network" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit.
Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS485 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

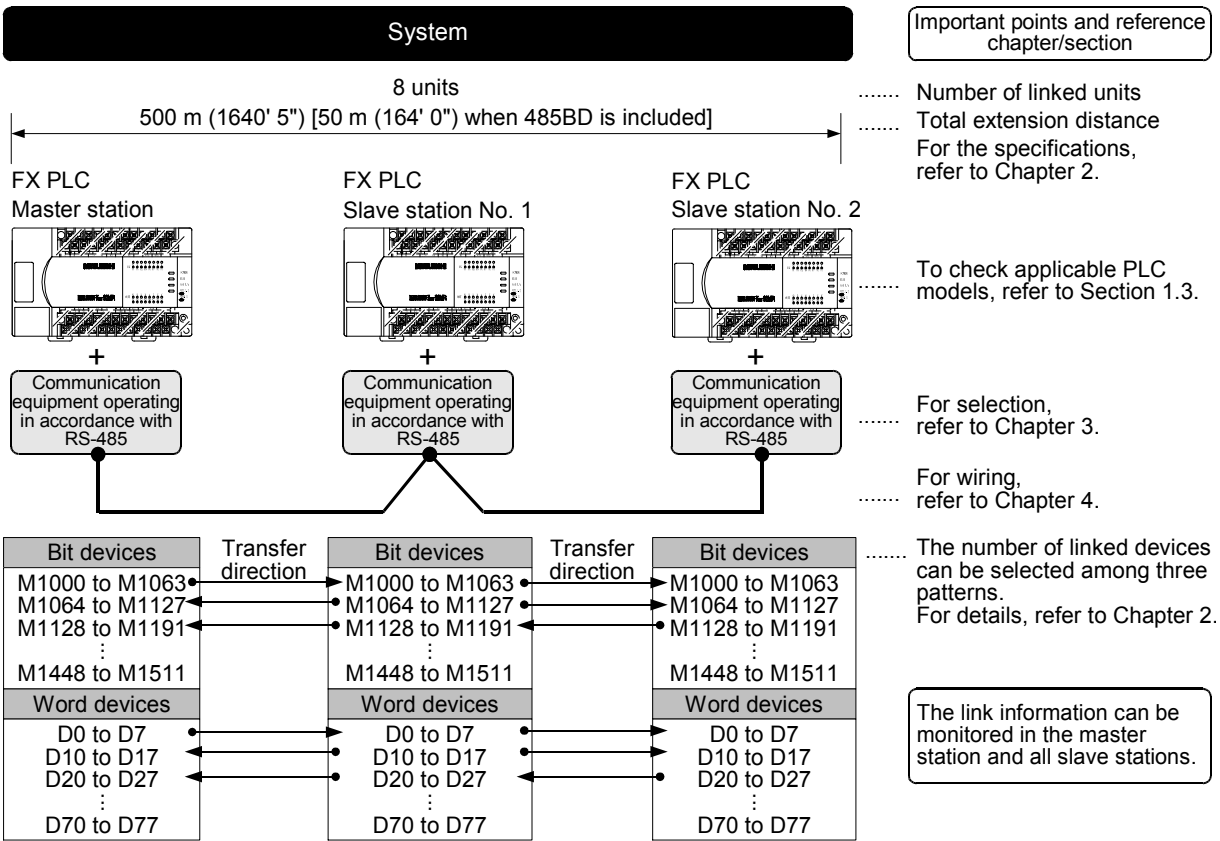
1. Outline

This chapter explains the N:N Network.

1.1 Outline of System

The N:N Network allows connection of up to eight FX PLCs via mutually linked devices through communication in accordance with RS-485.

- 1) One of three patterns can be selected according to the number of devices to be linked (except FX1S and FX0N PLCs).
- 2) Data link is automatically updated among a maximum of eight FX PLCs.
- 3) The available total extension distance is 500 m (1640' 5") maximum (when only the 485ADP is used in the configuration).

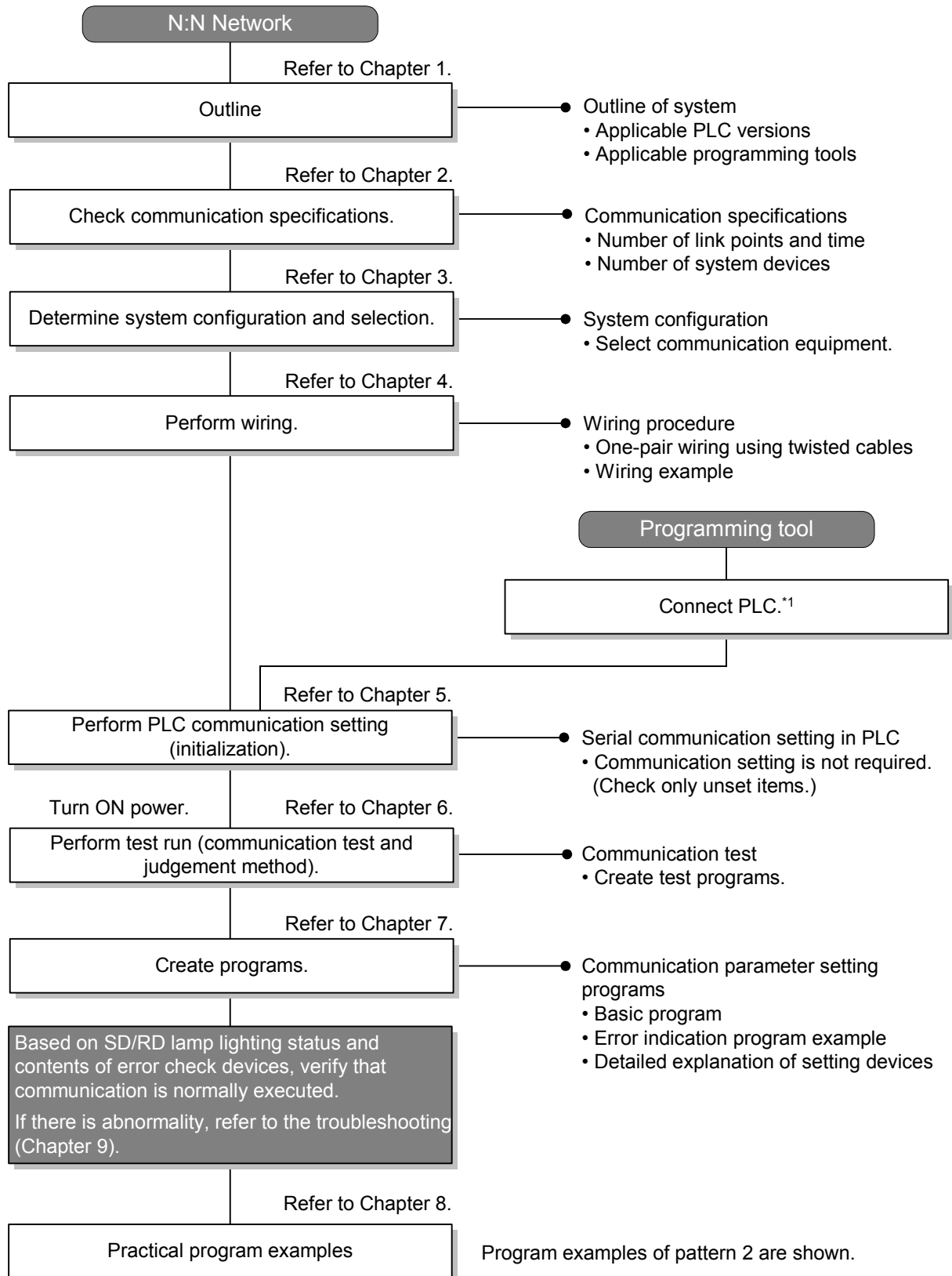


The figure above shows the maximum number of linked devices. There are differences in the specifications and limitations depending on the selected link pattern and FX Series.

| | |
|------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RJ2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

1.2 Procedures Before Operation

The flow chart below shows the N:N Network setting procedures up until data link:



*1 For the method to connect a programming tool to a PLC, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operating procedures, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

The communication type is applicable in the following versions.

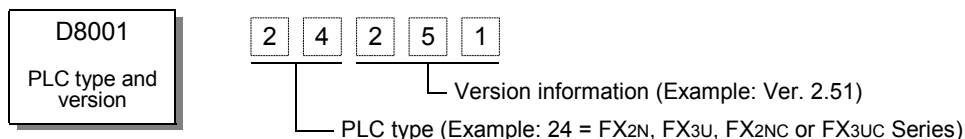
✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|------------------------------------|-------------------------------------|
| FX3UC Series | ✓ | |
| FX3U Series | ✓ | |
| FX2NC Series | ✓ | |
| FX2N Series | ✓ (Ver. 2.00 or later)*1 | |
| FX1NC Series | ✓ | |
| FX1N Series | ✓ | |
| FX1S Series | ✓ | The link device range is limited. |
| FX0N Series | ✓ (Ver. 2.00 or later)*1 | The link device range is limited. |
| FX0S Series | — | N:N Network option is not provided. |
| FX0 Series | — | N:N Network option is not provided. |
| FX2C Series | — | N:N Network option is not provided. |
| FX2(FX) Series | — | N:N Network option is not provided. |
| FX1 Series | — | N:N Network option is not provided. |

*1. Applicable in products manufactured in October, 1997 and later (manufacturer's serial No.: 7X**** and later).

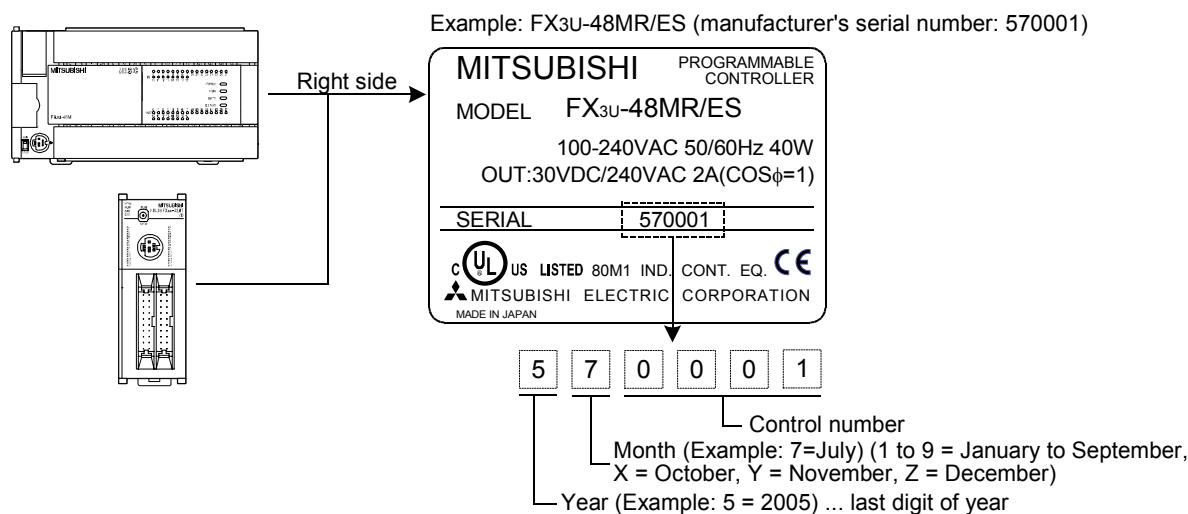
1. Version check

The D8001(decimal) special data register contains information for determining the PLC version.



2. How to look at the manufacturer's serial number

The year and month of production of product can be seen from the Manufacturer's serial number "SERIAL" indicated on the label adhered to the right side of the product.



1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description on system configuration, etc. in this manual for maintenance.

| FX Series | Date when production was stopped | Remarks |
|----------------|----------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2c Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the following version:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC". |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC". |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.00 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXC | ✓ (Ver. 4.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC". |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 5.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXD | ✓ (Ver. 5.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3u and FX3uc PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC". |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC". |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXC-E | ✓ (Ver. 3.00 or later) | |
| FX-10P-E | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC". |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXD-E | ✓ (Ver. 4.00 or later) | |
| FX-10P-E | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |

1.4.2 For non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set. In this case, however, programming is enabled only in the function ranges provided for the alternative PLC model such as instructions and program size.

| Model to be programmed | Model to be set | Priority: High → Low | | | |
|------------------------|-----------------|----------------------|---------|---|---------|
| FX3UC Series | FX3UC | → | FX2N | → | FX2(FX) |
| FX3U Series | FX3UC, FX3U | → | FX2N | → | FX2(FX) |
| FX2NC Series | FX2NC, FX2N | → | FX2(FX) | | |
| FX2N Series | FX2N | → | FX2(FX) | | |
| FX1NC Series | FX1NC, FX1N | → | FX2N | → | FX2(FX) |
| FX1N Series | FX1N | → | FX2N | → | FX2(FX) |
| FX1S Series | FX1S | → | FX2(FX) | | |
| FX0N Series | FX0N | → | FX2(FX) | | |
| FX0S Series | FX0S | → | FX2(FX) | | |
| FX0 Series | FX0 | → | FX2(FX) | | |
| FX2C Series | FX2C, FX2(FX) | → | FX2(FX) | | |
| FX2(FX) Series | FX2(FX) | → | FX2(FX) | | |
| FX1 Series | FX1 | | | | |

2. Specifications

This chapter explains the communication specifications and performance.

2.1 Communication Specifications (Reference)

Communication is executed according to the (fixed) specifications shown in the table below. Specification items such as baud rate cannot be changed.

| Item | Specifications | Remarks |
|----------------------------------|---|--|
| Number of connectable units | 8 maximum | |
| Transmission standard | RS-485 standard | |
| Maximum total extension distance | 500 m (1640' 5") or less [50 m (164' 0") or less when 485BD is included in system] | Distance varies depending on communication equipment type. |
| Protocol type | N:N Network | |
| Control procedure | — | |
| Communication method | Half-duplex, bidirectional communication | |
| Baud rate | 38400 bps | |
| Character format | Fixed | |
| Start bit | | |
| Data bit | | |
| Parity bit | | |
| Stop bit | | |
| Header | Fixed | |
| Terminator | | |
| Control line | — | |
| Sum check | Fixed | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2.2 Link Specifications

2.2.1 Link patterns and number of link points in each FX Series

The number of occupied link points varies depending on the number of slave stations used.
For example, when three slave stations are connected in "Pattern 1", M1000 to M1223 and D0 to D33 are occupied, and unoccupied devices can be used as general devices for control.
(Link devices for unconnected slave stations can be used as general devices for control, but it is recommended to leave them in the unoccupied status if slave stations may be added in the future.)

✓: Applicable
—: Not applicable

| PLC Series | Pattern 0 | Pattern 1 | Pattern 2 |
|--------------|-----------|-----------|-----------|
| FX3UC Series | ✓ | ✓ | ✓ |
| FX3U Series | ✓ | ✓ | ✓ |
| FX2NC Series | ✓ | ✓ | ✓ |
| FX2N Series | ✓ | ✓ | ✓ |
| FX1NC Series | ✓ | ✓ | ✓ |
| FX1N Series | ✓ | ✓ | ✓ |
| FX1S Series | ✓ | — | — |
| FX0N Series | ✓ | — | — |

| Station No. | | Pattern 0 | | Pattern 1 | | Pattern 2 | |
|----------------|---------------|----------------|-------------------|--------------------|-------------------|--------------------|-------------------|
| | | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) |
| | | 0 | 4 in each station | 32 in each station | 4 in each station | 64 in each station | 8 in each station |
| Master station | Station No. 0 | — | D 0 to D 3 | M1000 to M1031 | D 0 to D 3 | M1000 to M1063 | D 0 to D 7 |
| Slave stations | Station No. 1 | — | D10 to D13 | M1064 to M1095 | D10 to D13 | M1064 to M1127 | D10 to D17 |
| | Station No. 2 | — | D20 to D23 | M1128 to M1159 | D20 to D23 | M1128 to M1191 | D20 to D27 |
| | Station No. 3 | — | D30 to D33 | M1192 to M1223 | D30 to D33 | M1192 to M1255 | D30 to D37 |
| | Station No. 4 | — | D40 to D43 | M1256 to M1287 | D40 to D43 | M1256 to M1319 | D40 to D47 |
| | Station No. 5 | — | D50 to D53 | M1320 to M1351 | D50 to D53 | M1320 to M1383 | D50 to D57 |
| | Station No. 6 | — | D60 to D63 | M1384 to M1415 | D60 to D63 | M1384 to M1447 | D60 to D67 |
| | Station No. 7 | — | D70 to D73 | M1448 to M1479 | D70 to D73 | M1448 to M1511 | D70 to D77 |

2.2.2 Link time

The link time indicates the cycle time in which link devices are updated.

The link time varies depending on the number of linked units (master station and slave stations) and the number of linked devices as shown in the table below.

Unit: ms

| Number of linked stations | Pattern 0 | Pattern 1 | Pattern 2 |
|---------------------------------|---------------------------------|----------------------------------|----------------------------------|
| | 0 bit-devices 4 word-devices | 32 bit-devices 4 word-devices | 64 bit-devices 8 word-devices |
| 2 | 18 | 22 | 34 |
| 3 | 26 | 32 | 50 |
| 4 | 33 | 42 | 66 |
| 5 | 41 | 52 | 83 |
| 6 | 49 | 62 | 99 |
| 7 | 57 | 72 | 115 |
| 8 | 65 | 82 | 131 |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

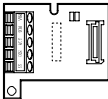
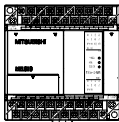
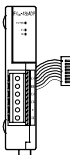
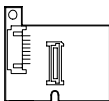
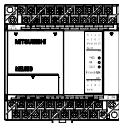
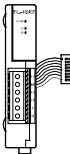
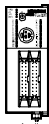
3. System Configuration and Equipment Selection

This chapter explains the configuration of the communication equipment operating in accordance with RS-485 and the system selection required by FX PLCs.

3.1 System Configuration

This section outlines the system configuration required to use the N:N Network.
Connect (optional) equipment operating in accordance with RS-485 to the FX PLC main unit.

1, **2** and **3** indicate the communication equipment combination patterns.

| Communication equipment operating in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|--|---|---|---------------------------------|
| <div>1</div> <div></div> <div>Communication board</div> | <div>+</div> <div></div> | <div>This is the communication board built into the PLC, reducing the installation area.</div> | <div>50 m (164' 0")</div> |
| <div>2</div> <div></div> <div>Communication adapter</div> | <div>+</div> <div></div> <div>Special adapter connection board</div> <div>+</div> <div></div> | <div>Attach the special adapter connection board to the main unit, and then attach the communication adapter to the left side of the main unit.</div> | <div>500 m (1640' 5")</div> |
| <div>3</div> <div></div> <div>Communication adapter</div> | <div>+</div> <div></div> | <div>Attach the communication adapter to the left side of the main unit.</div> | <div>500 m (1640' 5")</div> |

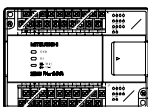
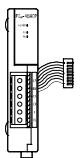
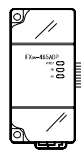

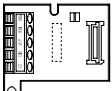
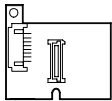
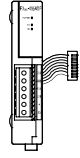
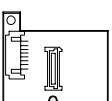
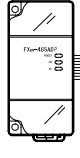

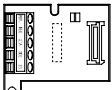
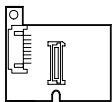
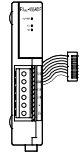
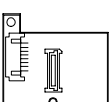
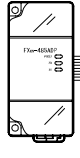
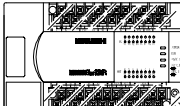
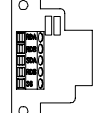
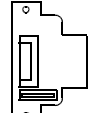
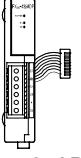
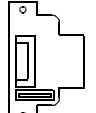



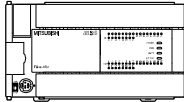
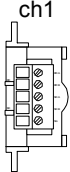

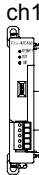


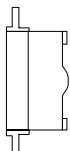
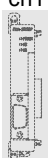

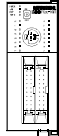
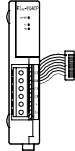
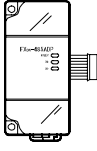
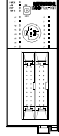
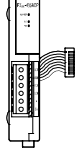
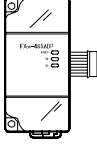
For communication equipment combinations for each FX Series, refer to the next page.

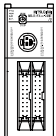



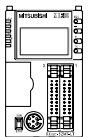
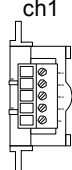







3.2 Applicable FX PLC and Communication Equipment

Select a (optional) communication equipment combination, and put a check mark in the "Check" column. During selection, pay attention to the following:

- In the table below, only the external dimensions are different between the units shown in "FX2NC-485ADP/FX0N-485ADP". Select either one.
- N:N Network is not provided for the FX0, FX0S, FX1, FX2(FX) and FX2C Series.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX0N |  /  FX2NC-485ADP (European terminal block) FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX1S |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP FX1N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX1N |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP FX1N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX2N |  FX2N-485-BD | 50 m (164' 0") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-485ADP FX2N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX1NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX2NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|---|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |   ch1 + ch2 FX3U-□ADP(-MB) (Where □ represents 232 and 485). + FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX3UC-32MT-LT | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |   FX3U-CNV-BD + FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485, and USB). | 500 m (1640' 5") | |
| |  ch2 FX3U-485ADP(-MB) (European terminal block) | | |
| |    FX3U-CNV-BD + FX3U-□ADP(-MB) (Where □ represents 232 and 485). + FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RSS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

4. Wiring

This chapter explains the wiring.

WIRING PRECAUTIONS



DANGER

- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to attach the terminal cover, offered as an accessory, before turning on the power or initiating operation after installation or wiring work. Failure to do so may cause electric shock.

WIRING PRECAUTIONS



CAUTION

- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to abnormal data written to the PLC under the influence of noise:
 - 1) Do not bundle the main circuit line together with or lay it close to the main circuit, high-voltage line or load line. Otherwise, noise disturbance and/or surge induction are likely to take place. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or high-voltage line.
 - 2) Ground the shield wire or shield of the shielded cable at one point on the PLC. However, do not use grounding with heavy electrical systems.
- Make sure to properly wire the FX0N/FX2N Series extension equipment in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should follow the specifications in this manual.
- Make sure to properly wire to the European terminal board in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should be follow the specifications in this manual.
 - Twist the end of strand wire and make sure that there are no loose wires.
 - Do not solder-plate the electric wire ends.
 - Do not connect more than the specified number of wires or electric wires of unspecified size.
 - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

4.1 Wiring Procedure

1 Preparing for wiring

Prepare cables and terminal resistors required for wiring.

→ For details, refer to Section 4.2.

2 Turning OFF the power to the PLC

Before starting any wiring work, make sure that the PLC power is OFF.

3 Connecting the power supply (FX0N-485ADP only)

Connect the power supply to the 24V DC power terminal.

4 Wiring communication equipment

Connect communication equipment operating in accordance with RS-485.

→ For details, refer to Section 4.3.

4.2 Selecting Cables and Terminal Resistors

Select cables using the procedure described below.

4.2.1 Twisted pair cable

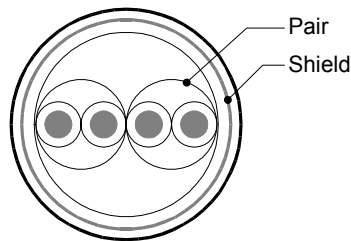
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows recommended model names and manufacturers of cables used for wiring.

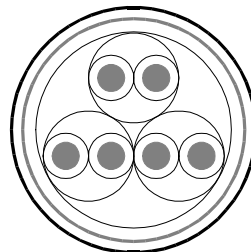
1. Recommended cables

| Manufacturer | Model name | Remarks |
|---------------------------------------|----------------------------------|---|
| Mitsubishi Cable Industries, Ltd. | SPEV(SB)-0.2-2P | Two-pair cable of 0.2 mm ² |
| | SPEV(SB)-MPC-0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | SPEV(SB)-0.5-2P | Two-pair cable of 0.5 mm ² |
| Showa Electric Wire & Cable Co., Ltd. | KMPEV-SB CWS-178 0.2SQ × 2P | Two-pair cable of 0.2 mm ² |
| | KMPEV-SB CWS-178 0.5SQ × 2P | Two-pair cable of 0.5 mm ² |
| Sumitomo Electric Industries, Ltd. | DPEV SB 0.3 × 3P | Three-pair cable of 0.3 mm ² |
| | DPEV SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| The Furukawa Electric Co., Ltd. | D-KPEV-SB 0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | D-KPEV-SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| Fujikura Ltd. | IPEV-SB 2P × 0.3 mm ² | Two-pair cable of 0.3 mm ² |
| | IPEV-SB 2P × 0.5 mm ² | Two-pair cable of 0.5 mm ² |

2. Cable structural drawing (reference)



Two-pair cable structural drawing example



Three-pair cable structural drawing example

4.2.2 Connecting cables

1. European type terminal block

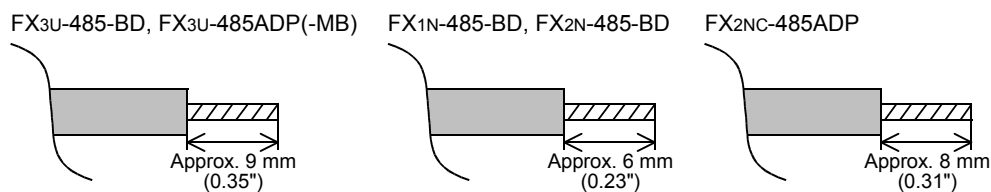
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows applicable cables and tightening torques.

| | Cable size when one cable is connected | Cable size when two cables are connected | Cable size for bar terminal with insulating sleeve | Tightening torque | Tool size | |
|----------------------------------|--|--|--|-------------------|-------------|-------------|
| | | | | | A | B |
| FX3U-485-BD FX3U-485ADP (-MB) | AWG22 to AWG20 | AWG22 | AWG22 to AWG20 | 0.22 to 0.25 N·m | 0.4 (0.01") | 2.5 (0.09") |
| FX2N-485-BD FX1N-485-BD | AWG26 to AWG16 | | — | 0.6 N·m | 0.6 (0.03") | 3.5 (0.14") |
| FX2NC-485ADP | AWG26 to AWG16 | AWG26 to AWG20 | — | 0.4 to 0.5 N·m | 0.6 (0.03") | 3.5 (0.14") |

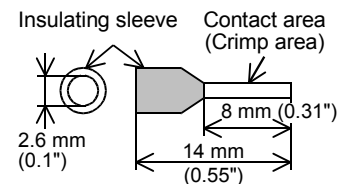
With regard to the cable end treatment, use a stranded cable or solid cable as it is, or use a bar terminal with insulating sleeve.

- When using a stranded cable or solid cable as it is
 - Twist the end of a stranded cable so that wires do not get barbed.
 - Do not plate the end of the cable.



- When using a bar terminal with insulating sleeve
Because it is difficult to insert a cable into an insulating sleeve depending on the thickness of the cable sheath, select the proper cable according to the outline drawing.

| Manufacturer | Model name | Caulking tool |
|-----------------|------------|-------------------------------------|
| Phoenix Contact | AI 0.5-8WH | CRIMPFOX ZA 3 (or CRIMPFOX UD 6) |

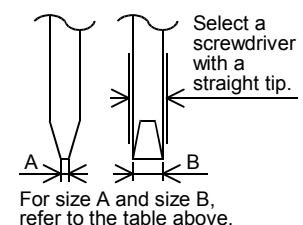


- Tool
 - When tightening a terminal on the European terminal block, use a small commercial straight shape screwdriver whose tip is shown in the figure to the right.

Note:

If the diameter of screwdriver grip is too small, tightening torque will not be able to be achieved. Use the following recommended screwdriver or an appropriate replacement (grip diameter: approximately 25mm).

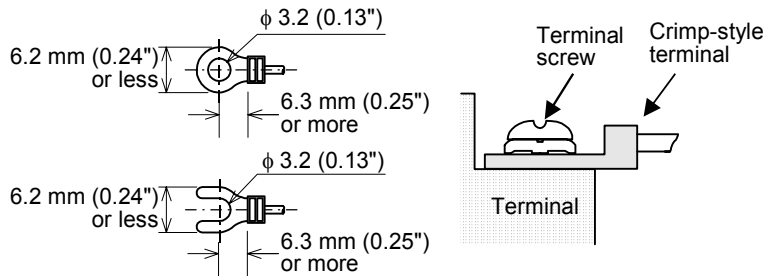
| Manufacturer | Model name |
|-----------------|---------------|
| Phoenix Contact | SZS 0.4 × 2.5 |



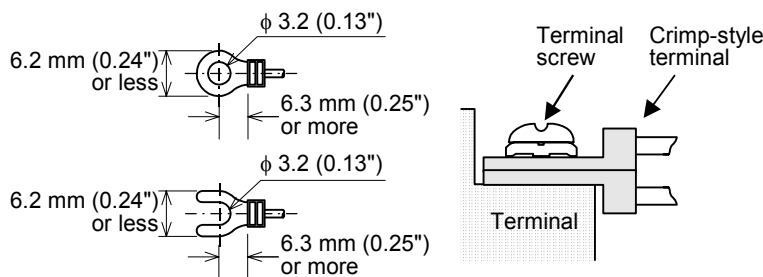
2. Terminal block

In the FX0N-485ADP and FX-485ADP, the terminal screw size is "M3".
Make sure to use a crimp-style terminal with the following sizes.
Make sure that the tightening torque is 0.5 to 0.8 N·m.

- When wiring one cable to one terminal



- When wiring two cables to one terminal

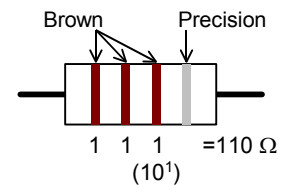


4.2.3 Connecting terminal resistors

Make sure to provide a terminal resistor at the end of each line.
In the case of one-pair wiring, connect a terminal resistor to the RDA-RDB signal terminal of the communication equipment.

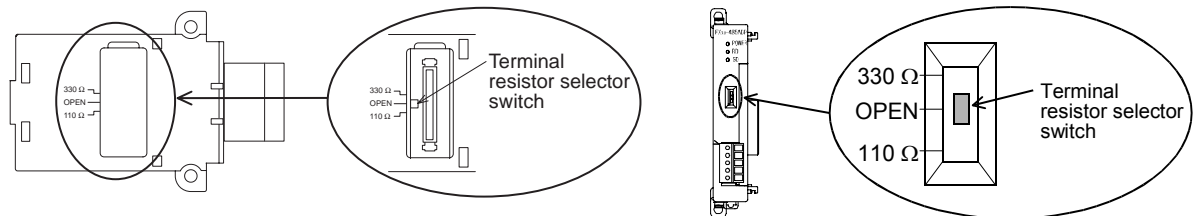
1. Terminal resistor type

Use two terminal resistors of 110 Ω , 1/2 W.
Among the terminal resistors supplied with the communication equipment, select ones with the color codes shown to the right.



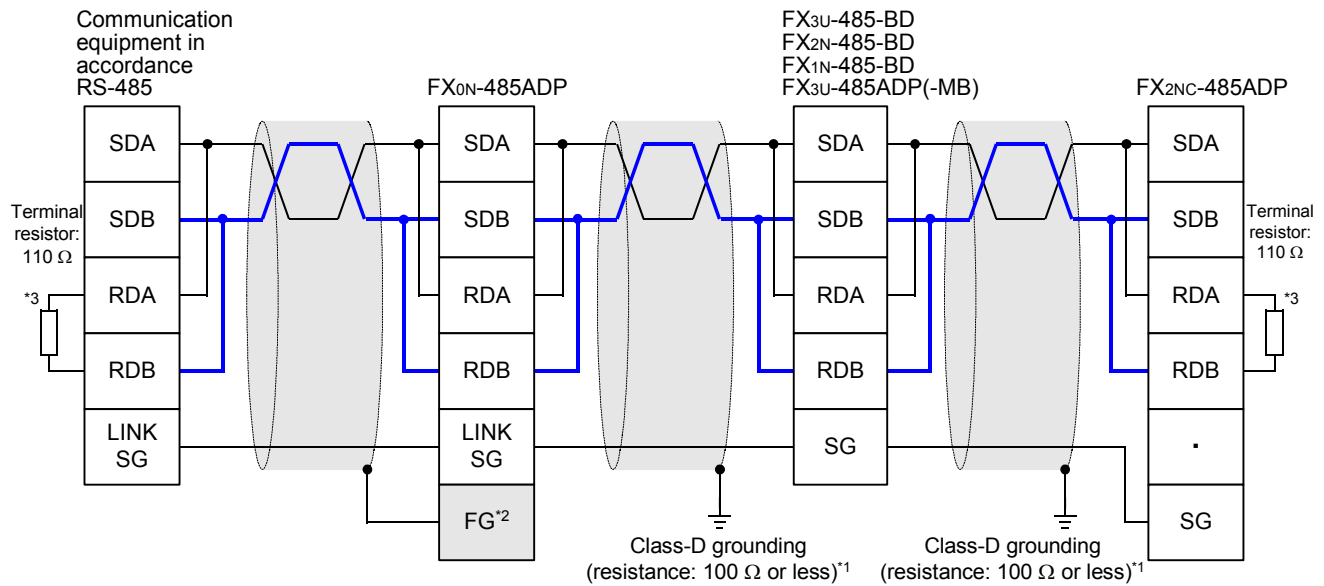
2. When using the FX3U-485-BD or FX3U-485ADP(-MB)

The FX3U-485-BD and FX3U-485ADP(-MB) have built-in terminal resistors.
Set the terminal resistor selector switch accordingly.




4.3 Connection Diagram

Use one-pair wiring for an N:N Network.



*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD, FX3U-485-BD, FX2NC-485-ADP or FX3U-485ADP(-MB).

*2 Make sure to connect the **FG** terminal to the  (grounding) terminal in the PLC requiring Class-D grounding. If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.

*3 Make sure to provide a terminal resistor at the end of each line.

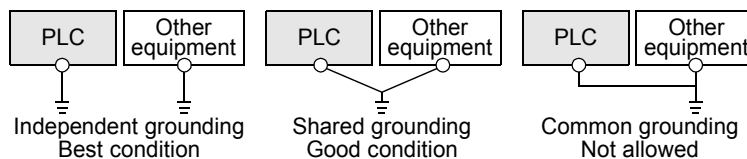
- The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor. Set the terminal resistor selector switch accordingly.
- The FX0N-485ADP, FX2NC-485ADP, FX2N-485-BD and FX1N-485-BD are supplied together with terminal resistors.

4.4 Grounding

Grounding should be performed as stated below.

- The grounding resistance should be 100Ω or less.
- Independent grounding should be performed for best results. When independent grounding can not be performed, perform "shared grounding" as shown in the following figure.

→ For details, refer to the Hardware Edition of each series.



- The grounding wire size should be AWG 14 (2 mm²) or larger.
- The grounding point should be close to the PLC, and all grounding wires should be as short as possible.

5. Communication Setting (Initialization) in FX Programmable Controller

The communication setting is not required in FX PLCs for the N:N network.
Using the following procedure, verify that the communication setting is not specified for another communication type and verify that the setting is correct.
When using the N:N Network in ch2 in an FX3U or FX3UC PLC, check D8420 using the following procedure.

5.1 Check Procedure

1 Monitoring D8120

Turn ON the power to the PLC while it is in STOP mode, and monitor D8120.

1. **When the value of D8120 is "0"**
The communication setting is not provided.
2. **When the value of D8120 is any value other than "0"**
The communication setting is provided.

2 Checking absence/presence of parameter setting

Check for the absence/presence using the GX Developer or FXGP/WIN.

- 1) GX Developer operating procedure (For details, refer to Section 5.2.)
- 2) FXGP/WIN operating procedure (For details, refer to Section 5.3.)

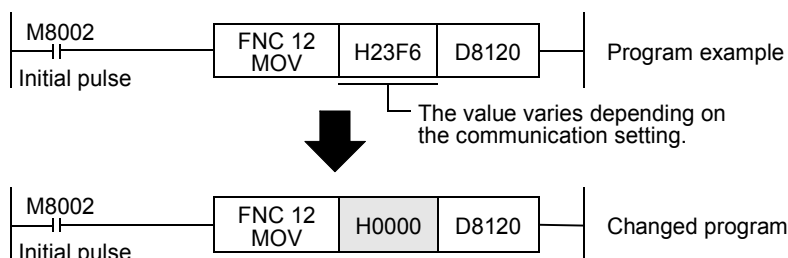
3 Checking absence/presence of sequence program setting

Check whether or not a write instruction is programmed for D8120.

1. **When such an instruction is programmed**

Program example:

Change the program as shown below, and then change the PLC mode from STOP to RUN.



2. **When such an instruction is not programmed**
Proceed to the next step.

4 Monitoring D8120 again, and confirming that its value is "0"

5.2 Communication Setting Using Parameter Method (GX Developer)

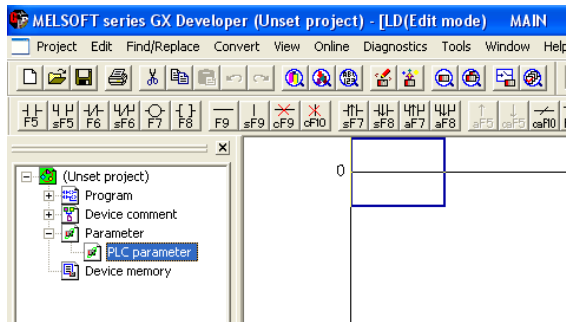
Communication setting may be changed using the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with GX Developer.

5.2.1 Operating procedure

With GX Developer open, follow the steps in this section for activating the serial communication setting method.

1 Opening the parameter setting window

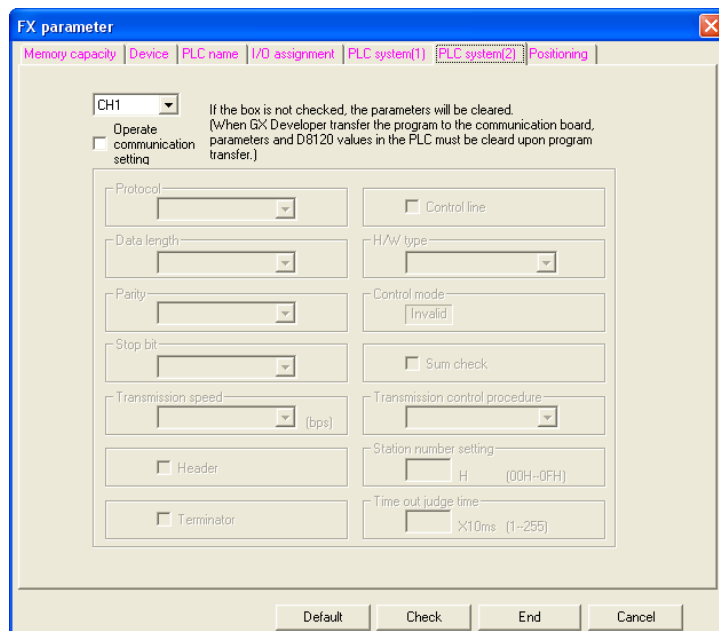
Double-click [Parameter] - [PLC parameter] from the project tree.



If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Setting the serial communication (parameters)

Select a channel to be used, and click the [PLC system(2)] tab on the dialog box. Make sure that the "Operate communication setting" check box is clear. If a check mark is there, clear it.



3 Writing parameters and program to the PLC

Select [Online] - [Write to PLC] from the toolbar, put a check mark next to "Parameter" and "Program", and then click [Execute].

5.3 Communication Settings Using Parameter Method (FXGP/WIN)

Communication setting may be changed using the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with FXGP/WIN.
Ch2 cannot be set using FXGP/WIN.

5.3.1 Operating procedure

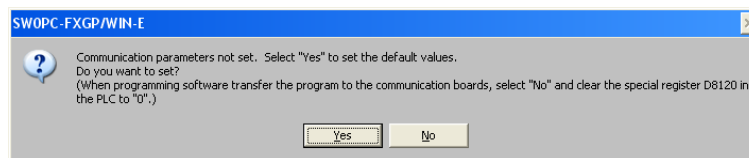
This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

1 Adjusting serial setting (parameter)

Double-click [Option]-[Serial setting (parameter)] from the toolbar.
The following dialog box appears according to absence/presence of parameter settings.

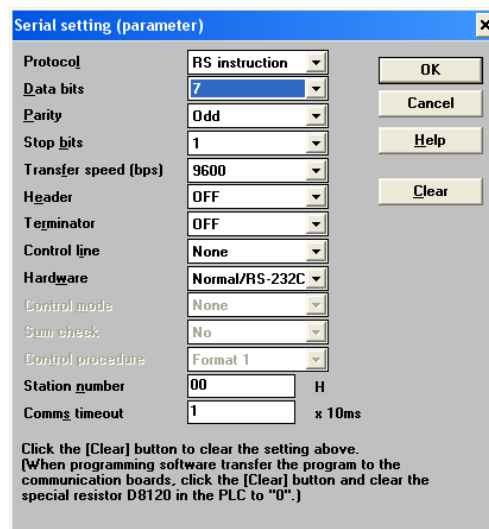
1. When there are no parameter settings

The dialog box shown below appears to indicate that there are no communication settings.
Click the [No] button.
In this case, the next step is not required.



2. When there are already parameter settings

The dialog box shown below appears to indicate that there are communication settings.
Click the [Clear] button to delete the communication settings from parameters.
Transfer parameters to the PLC using the following step.



2 Writing a sequence program (parameters) to the PLC

Select [PLC] - [Transfers] - [Write] from the toolbar, and click [OK].

6. Test Run (Communication Test)

This chapter explains the communication test procedures for the N:N Network.

It is recommended to first wire the master station and slave stations, initialize communication settings in the FX PLCs, and then execute the communication test using the following procedure to confirm proper operation.

6.1 Test Procedure

1 Creating programs for the communication test

Create new programs for the communication test for the master station and slave stations.

→ For program examples, refer to Section 6.2.

2 Transferring the program to each PLC

Turn ON the power to each PLC, and transfer the program.

3 Validating the communication setting

When the PLC is in RUN mode, set it to STOP mode once, and then set it to RUN mode again.

Or turn OFF the power of the master station and all slave stations in communication, and then turn ON the power of these stations at the same time.

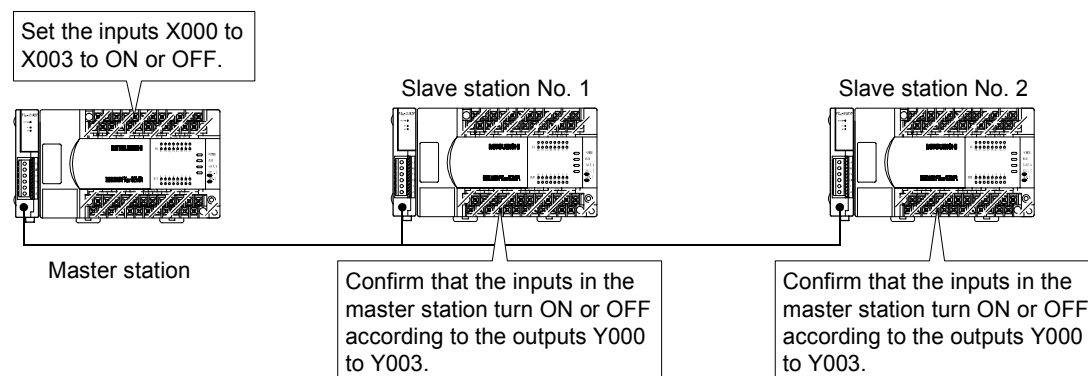
4 Confirming flashing of the communication status indicator lamps (SD and RD)

Confirm that the built-in SD and RD lamps of the communication equipment are flashing.

If they are off, take proper action while referring to the troubleshooting procedures described later.

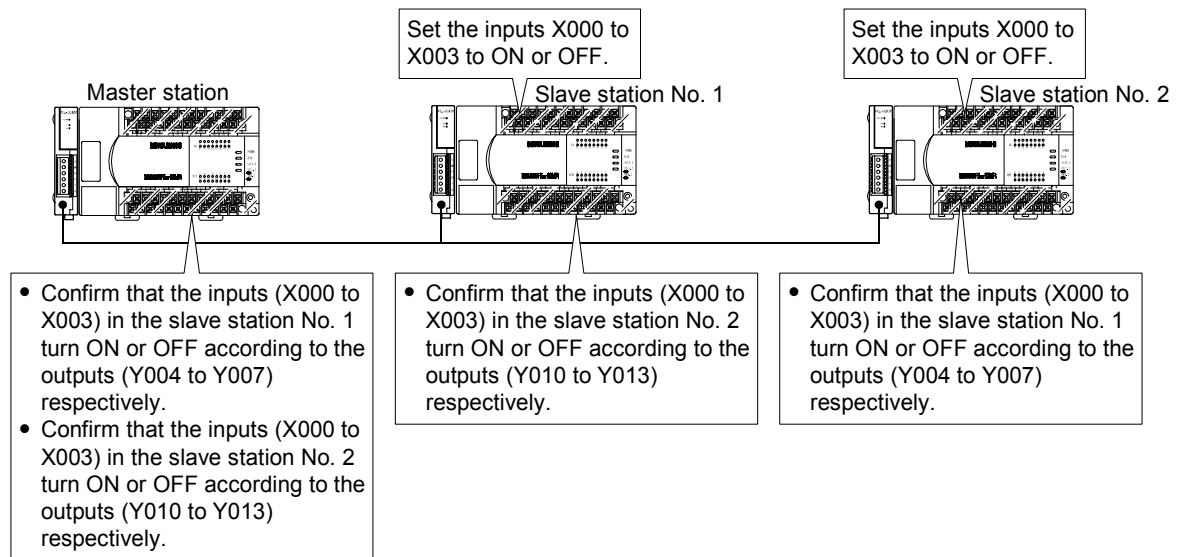
5 Confirming the link of the master station

Set the PLC inputs (X000 to X003) to ON or OFF in the master station, and confirm that the outputs (Y000 to Y003) turn ON or OFF in each slave station.



6 Confirming the link of slave stations

Set the PLC inputs (X000 to X003) to ON or OFF in each slave station, and confirm that the outputs (Y004 to Y007, Y010 to Y013, Y014 to Y017... Y030 to Y033) turn ON or OFF in each slave station.



→ If unable to establish link, refer to "Chapter 9. Troubleshooting."

Assignment of inputs and outputs (link devices)

The table below shows devices used in the test programs shown later:

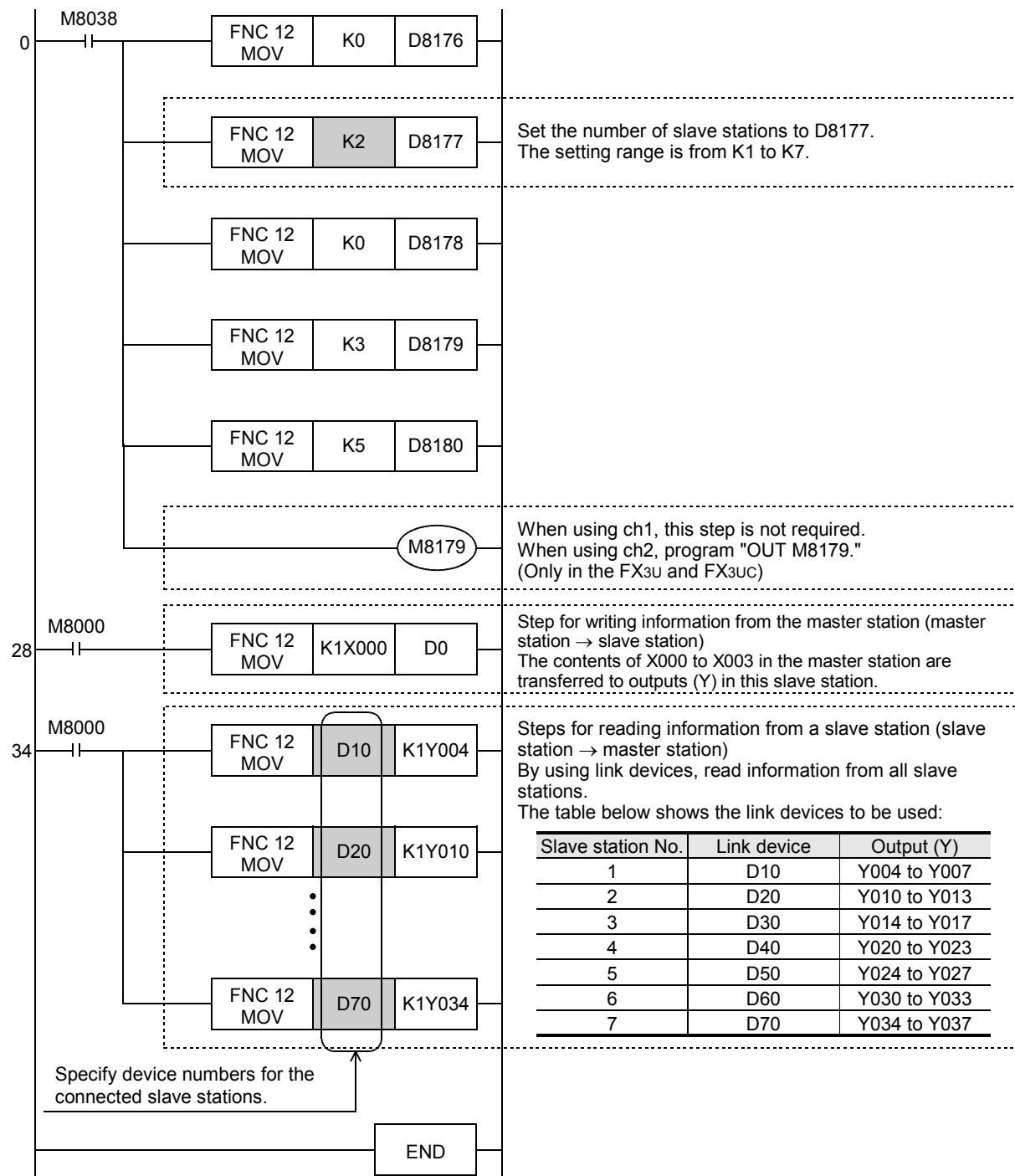
| Station No. | | Input (X) | Link device | Output (Y) |
|-------------|---------------------|--------------|-------------|--------------|
| 0 | Master station | X000 to X003 | D0 | Y000 to Y003 |
| 1 | Slave station No. 1 | X000 to X003 | D10 | Y004 to Y007 |
| 2 | Slave station No. 2 | X000 to X003 | D20 | Y010 to Y013 |
| 3 | Slave station No. 3 | X000 to X003 | D30 | Y014 to Y017 |
| 4 | Slave station No. 4 | X000 to X003 | D40 | Y020 to Y023 |
| 5 | Slave station No. 5 | X000 to X003 | D50 | Y024 to Y027 |
| 6 | Slave station No. 6 | X000 to X003 | D60 | Y030 to Y033 |
| 7 | Slave station No. 7 | X000 to X003 | D70 | Y034 to Y037 |

6.2 Creating Programs for the Communication Testing

Create the programs shown below for the master station and each slave station.
(In the communication test, set the refresh range to pattern 0.)

6.2.1 Creating a program for the master station

Create the program shown below for the communication test. (This program is not required during actual operation.)



Cautions

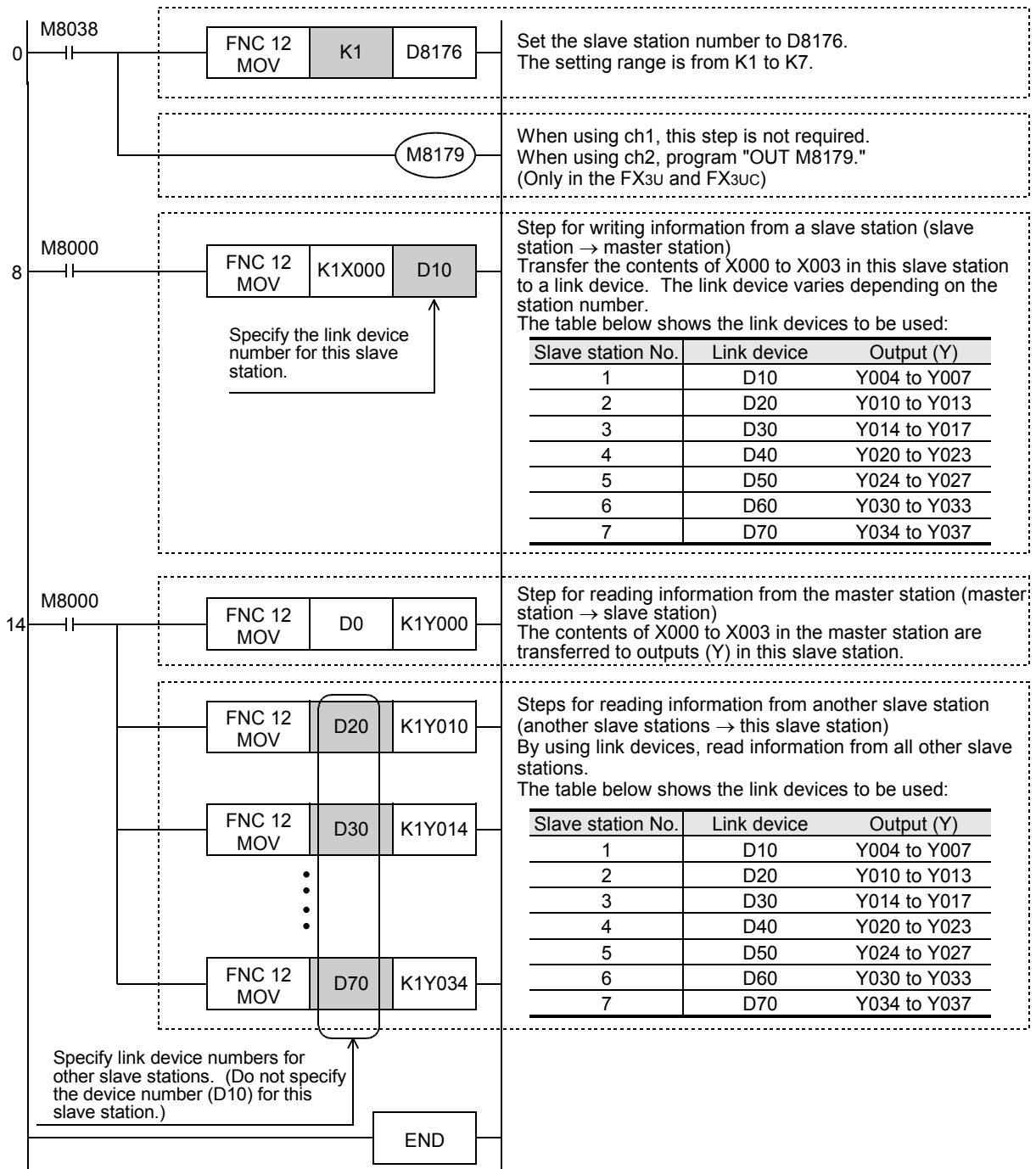
- When using a PLC (such as an FX1S Series PLC) with a small number of outputs, transfer information from slave stations to auxiliary relays (M), etc., and then monitor the auxiliary relays using a programming tool. (Example: Change "K1Y004" to "K1M4".)
- In the circuit from step 34, create a program for link devices (MOV instruction) for all connected slave stations.

6.2.2 Creating a program for each slave station.

Create the program shown below for the communication test. (This program is not required during actual operation.)

Determine the station number of each slave station, and then transfer a program corresponding to the station number to each slave station.

Assign station numbers from "1" in the ascending order. (Use one station number only once. Do not skip station numbers.)



Cautions

- When using a PLC (such as an FX1S Series PLC) with a small number of outputs, transfer information from slave stations to auxiliary relays (M), etc., and then monitor the auxiliary relays using a programming tool. (Example: Change "K1Y004" to "K1M4".)
- In the circuit from step 14, specify link devices for other slave stations.

7. Creating Programs

This chapter explains how to set the N:N Network and how to create programs.

In N:N Network, pattern 0, 1 or 2 can be set according to the refresh range value. The number of used devices varies depending on the pattern.

In N:N Network using (including) the FX0N or FX1S Series, only pattern 0 is applicable.

7.1 Checking Contents of Related Devices

The tables below show the devices used by the N:N Network.

1. Devices for setting the N:N Network

These devices are used for setting the N:N Network. Setting these devices is essential for using N:N Network.

| Device | Name | Description | Set value |
|--------|--------------------------------|---|-----------|
| M8038 | Parameter setting | This device is a flag for setting communication parameters, and is used to check for absence/presence of N:N Network program also. Do not set this device to ON in the sequence program. | |
| M8179 | Channel setting | Set the channel of the communication port to be used (in the FX3U and FX3UC). When "OUT M8179" program does not exist: ch 1 When "OUT M8179" program exists: ch 2 | |
| D8176 | Station number settings | Set the station number used in the N:N Network. Master station: 0, slave station: 1 to 7 [Initial value: 0] | 0 to 7 |
| D8177 | Slave station quantity setting | Set the total number of slave stations. This setting is not required in PLCs working as slave stations. [Initial value: 7] | 1 to 7 |
| D8178 | Refresh range setting | Select the desired pattern of device points used for communication. This setting is not required in PLCs working as slave stations. [Initial value: 0] Only pattern 0 is applicable when a FX0N or FX1S Series is included. | 0 to 2 |
| D8179 | Number of retries | When a response is not given even after communication is repeated the specified number of times, it is regarded as an error. Errors in other stations can be checked. This setting is not required in PLCs working as slave stations. [Initial value: 3] | 0 to 10 |
| D8180 | Monitoring time | Set the time (50 to 2550 ms) for communication error in 10 ms units. This setting is not required in PLCs working as slave stations. [Initial value: 5] | 5 to 255 |

2. Devices for determining errors in the N:N Network

These devices are used for determining errors in the N:N Network. Use them to output link errors to the outside and interlock sequence programs.
Different devices are used between the FX1S/FX0N Series and the FX1N/FX2N/FX3U/FX1NC/FX2NC/FX3UC Series. Use devices according to the PLCs used.

| Device | | Name | Description |
|----------------------------|--|---|--|
| FX0N FX1S | FX1N, FX2N, FX3U FX1NC, FX2NC, FX3UC | | |
| M504 | M8183 | Master station data transfer sequence error | This device turns ON when a data transfer sequence error occurs in the master station. |
| M505 to M511 ^{*1} | M8184 to M8190 ^{*1} | Slave station data transfer sequence error | This device turns ON when a data transfer sequence error occurs in a slave station. |
| M503 | M8191 | Data transfer sequence ON | This device remains ON while the N:N Network is operating. |

^{*1}. For FX0N and FX1S PLCs
Station No. 1: M505, Station No. 2: M506, Station No. 3: M507... Station No. 7: M511
For FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC PLCs
Station No. 1: M8184, Station No. 2: M8185, Station No. 3: M8186... Station No. 7: M8190

3. Link devices

These devices are used for sending and receiving information among the PLCs. The device numbers used and number of devices vary depending on the station number set in D8176 (station number settings) and the pattern set in D8178 (refresh range setting).

- 1) In the case of pattern 0

| Station No. | 0 (master station) | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|--|--------------------|------------|------------|------------|------------|------------|------------|------------|
| Word device (4 points for each station) | D0 to D3 | D10 to D13 | D20 to D23 | D30 to D33 | D40 to D43 | D50 to D53 | D60 to D63 | D70 to D73 |

- 2) In the case of pattern 1

| Station No. | 0 (master station) | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|--------------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| Bit devices (32 points for each station) | M1000 to M1031 | M1064 to M1095 | M1128 to M1159 | M1192 to M1223 | M1256 to M1287 | M1320 to M1351 | M1384 to M1415 | M1448 to M1479 |
| Word device (4 points for each station) | D0 to D3 | D10 to D13 | D20 to D23 | D30 to D33 | D40 to D43 | D50 to D53 | D60 to D63 | D70 to D73 |

- 3) In the case of pattern 2

| Station No. | 0 (master station) | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|--------------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| Bit devices (64 points for each station) | M1000 to M1063 | M1064 to M1127 | M1128 to M1191 | M1192 to M1255 | M1256 to M1319 | M1320 to M1383 | M1384 to M1447 | M1448 to M1511 |
| Word device (8 points for each station) | D0 to D7 | D10 to D17 | D20 to D27 | D30 to D37 | D40 to D47 | D50 to D57 | D60 to D67 | D70 to D77 |

Caution

When creating a program, do not change the information in devices used by other stations. If such information is changed, other stations will not operate normally.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232JF)

H

Programming Communication

I

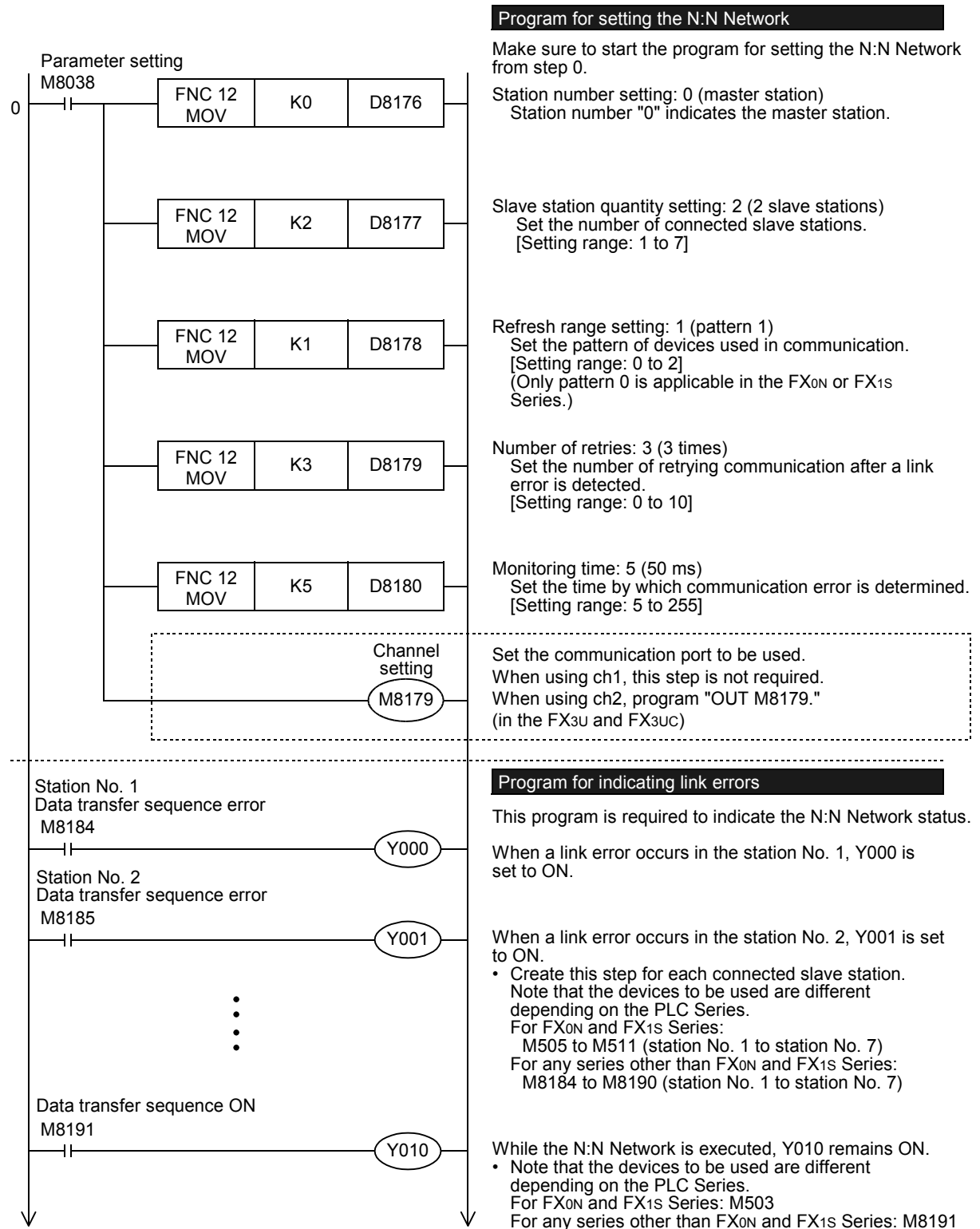
Remote Maintenance

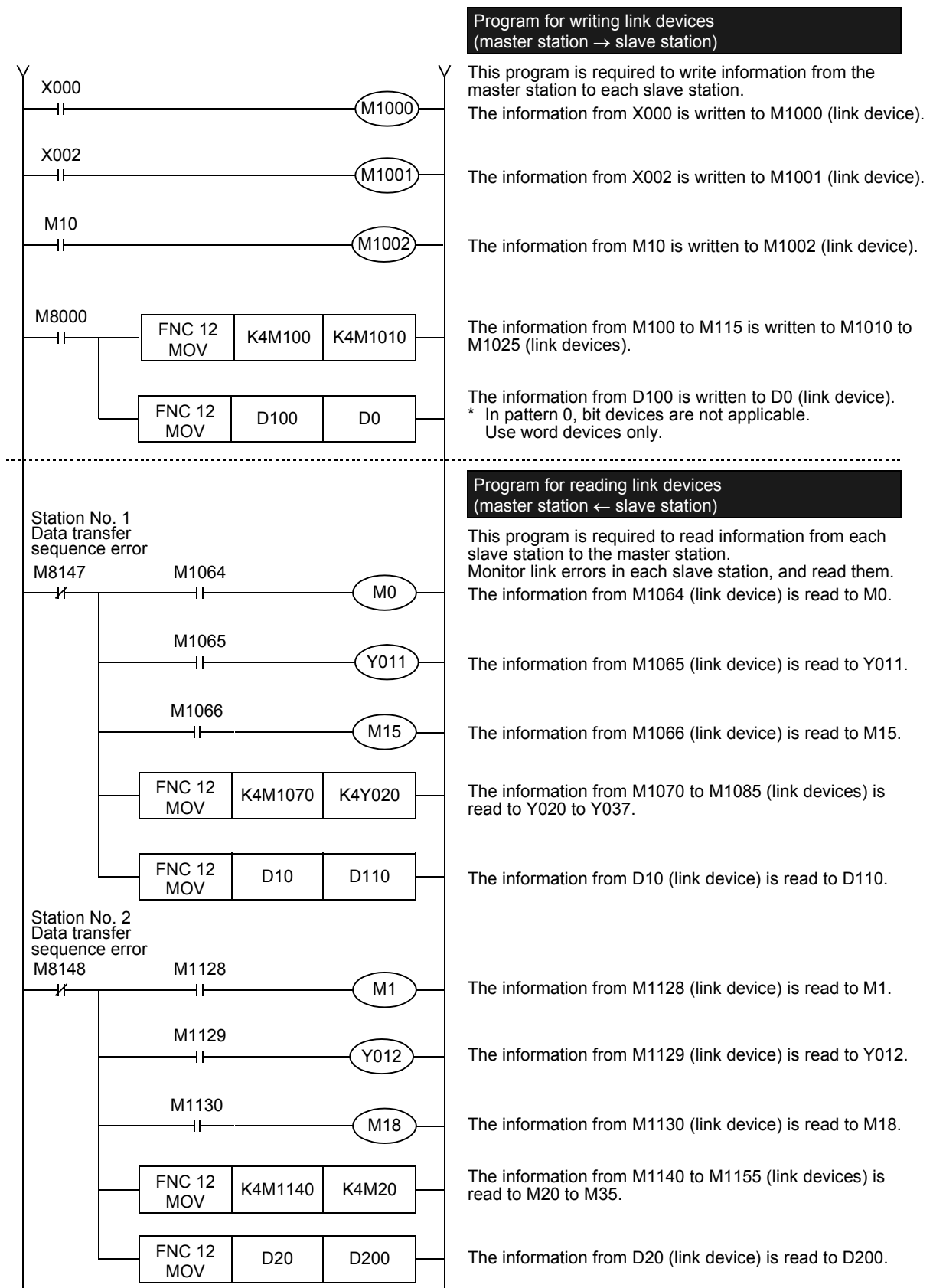
Apx.

Discontinued models

7.2 Creating Programs for Master Station (Station No. 0)

Create programs for the master station.
Arbitrarily create programs for reading and writing link devices.

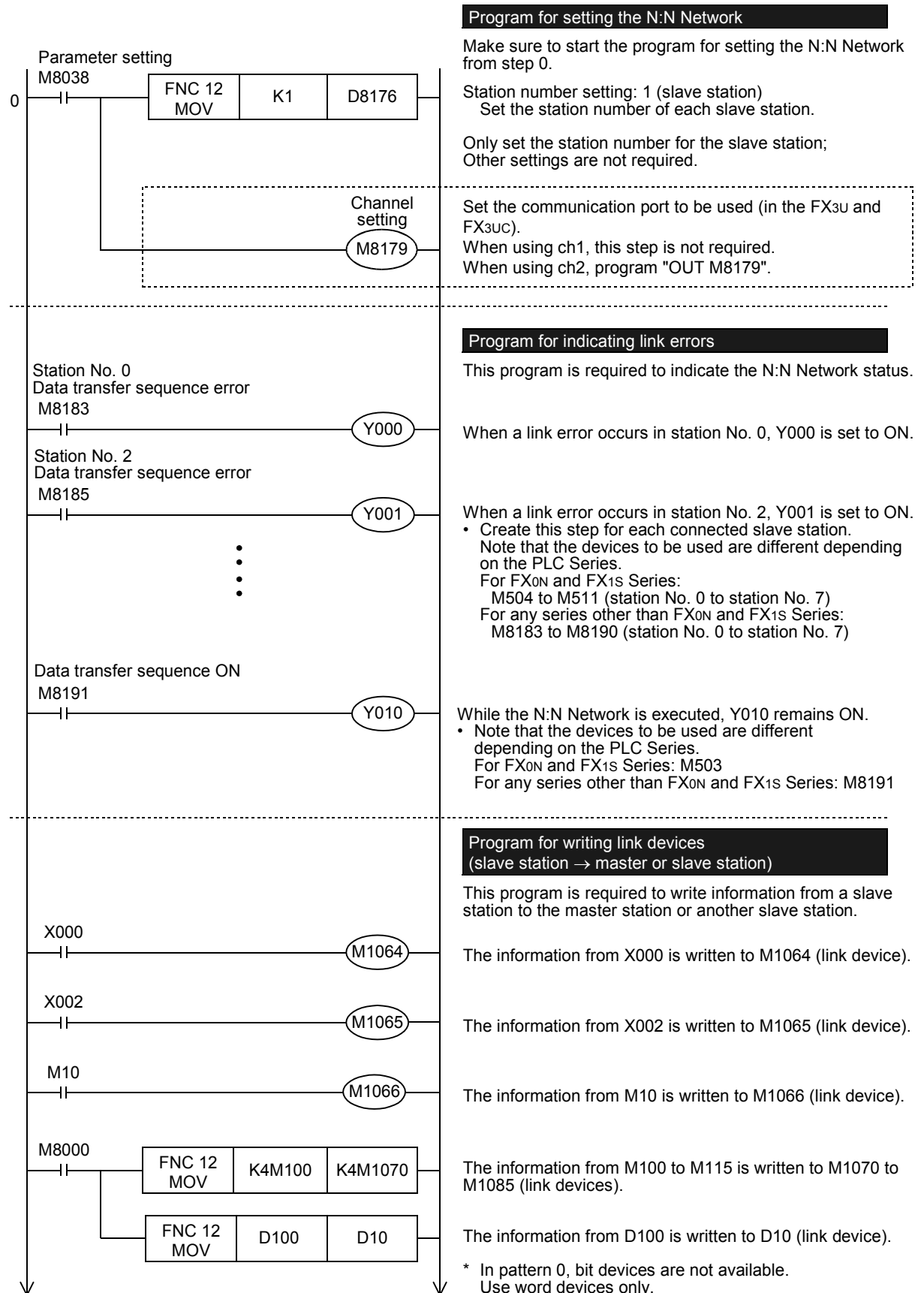


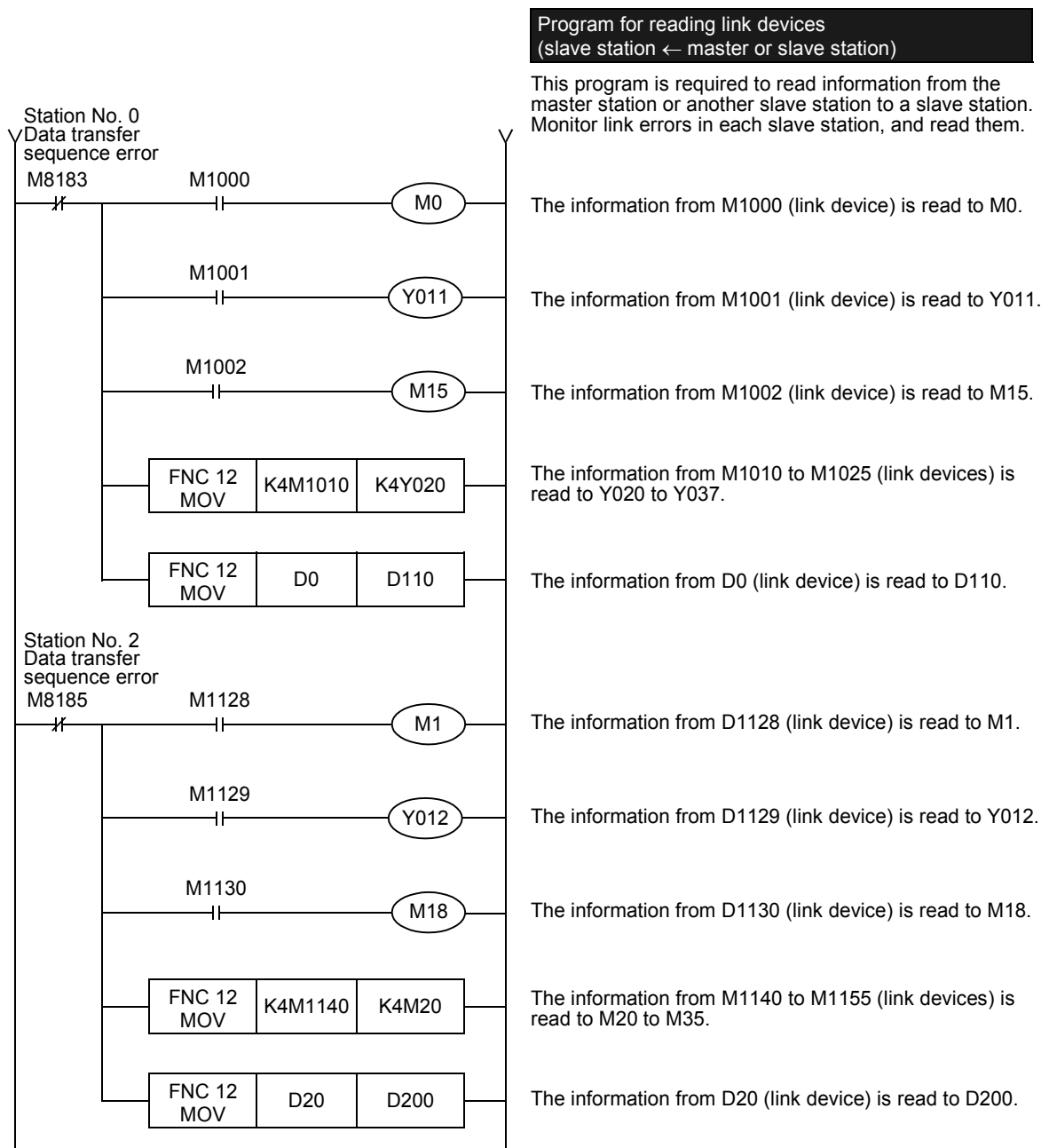


→ For details on link devices, refer to Section 7.1.
→ For cautions on program creation, refer to Section 7.4.

7.3 Creating Programs for Slave Station (Station No. "n")

Create programs for the slave stations.
Arbitrarily create programs for reading and writing link devices.





→ For details on link devices, refer to Section 7.1.
→ For cautions on program creation, refer to Section 7.4.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

7.4 Cautions on Program Creation

1. Effect on the operation cycle

When the N:N Network is used, the operation cycle in each PLC becomes longer by about 10% regardless of the number of linked stations and adopted communication patterns.

2. Program for setting the N:N Network

- 1) Make sure to create a program for setting the N:N Network from step 0 using M8038 (drive contact). Otherwise, the N:N Network is disabled.
- 2) Do not set M8038 to ON using a program or programming tool.
- 3) Set station numbers consecutively. If a station number that is used twice or more is skipped, link will not be achieved normally.

3. Program for reading link devices

Do not change the contents of link devices at other stations.

- 1) When a link error (data transfer sequence error) occurs, the link device information is held in the status just before occurrence of the link error.
Create a fail-safe program which does not cause abnormality even if a link error occurs.

4. Cautions on using FX1S/FX0N PLCs

- 1) Link pattern when FX1S/FX0N PLCs are used or included
When FX1S/FX0N PLCs are included in the system, make sure to set pattern 0 in D8178 (refresh range setting).
If any other pattern is set, data transfer error occurs in all FX1S/FX0N PLCs included in the system, and the link time becomes longer.
- 2) When user devices are occupied as system devices
In FX1S/FX0N PLCs, M503 to M511 and D201 to D255 are handled as devices dedicated to the N:N Network, and cannot be handled as general devices any more. Do not set these devices to ON or OFF using a user program, display unit or programming tool.
If these devices are set to ON or OFF, the N:N Network may malfunction.

5. Cautions on using FX3U/FX3UC PLCs

- 1) Only ch 1 or ch 2 can be set in the N:N Network.
- 2) Do not use the N:N Network and parallel link at the same time.
(For example, it is not allowed to use ch1 for the N:N Network and use ch2 for parallel link.)

8. Practical Program Examples

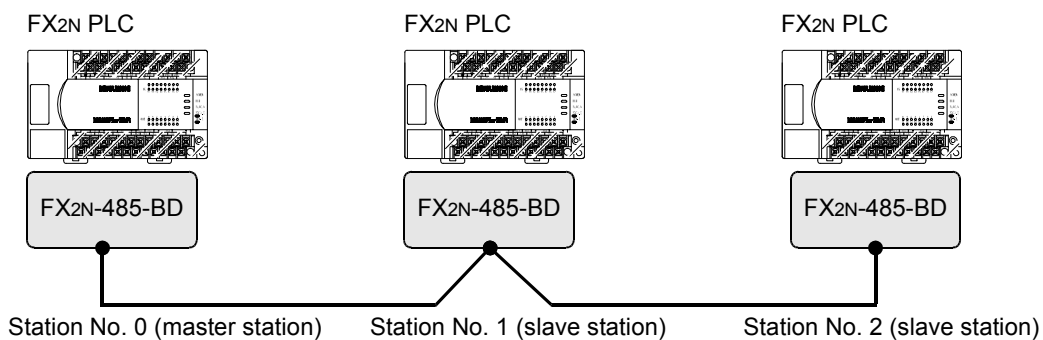
This chapter shows practical programs.

8.1 Practical Example 1 (Pattern 2)

This program example adopts pattern 2 which uses the maximum number of link devices. When an FX0N or FX1S PLC is included, however, only pattern 0 is applicable.

8.1.1 System configuration example

The example below shows a system configuration in which three FX PLCs are linked.



- Refresh range: 64-bit devices and 8 word devices (pattern 2)
- Number of retries: 5
- Monitoring time: 70 ms

8.1.2 Contents of operations and corresponding program numbers

The program examples shown later execute the data processing shown in the table below. The operation No. corresponds to the operation [1] (for example) indicated in the programs shown later.

| Operation No. | Data source | | Data change destination and contents | |
|------------------|---------------------|--------------------------------------|--------------------------------------|--|
| Bit device link | | | | |
| [1] | Master station | Inputs X000 to X003 (M1000 to M1003) | Slave station No. 1 | Outputs Y010 to Y013 |
| | | | Slave station No. 2 | Outputs Y010 to Y013 |
| [2] | Slave station No. 1 | Inputs X000 to X003 (M1064 to M1067) | Master station | Outputs Y014 to Y017 |
| | | | Slave station No. 2 | Outputs Y014 to Y017 |
| [3] | Slave station No. 2 | Inputs X000 to X003 (M1128 to M1131) | Master station | Outputs Y020 to Y023 |
| | | | Slave station No. 1 | Outputs Y020 to Y023 |
| Word device link | | | | |
| [4] | Master station | Data register D1 | Slave station No. 1 | Set value of counter C1 |
| | Slave station No. 1 | Contact of counter C1 (M1070) | Master station | Output Y005 |
| [5] | Master station | Data register D2 | Slave station No. 1 | Set value of counter C2 |
| | Slave station No. 1 | Contact of counter C2 (M1140) | Master station | Output Y006 |
| [6] | Slave station No. 1 | Data register D10 | Master station | Slave station No. 1 (D10) + Slave station No. 2 (D20) is stored to D3. |
| | Slave station No. 2 | Data register D20 | | |
| [7] | Master station | Data register D0 | Slave station No. 1 | Master station (D0) + Slave station No. 2 (D20) is stored to D11. |
| | Slave station No. 2 | Data register D20 | | |
| [8] | Master station | Data register D0 | Slave station No. 2 | Master station (D0) + Slave station No. 1 (D10) is stored to D21. |
| | Slave station No. 1 | Data register D10 | | |

8.1.3 Setting contents

The program examples shown later adopt the following communication parameters:

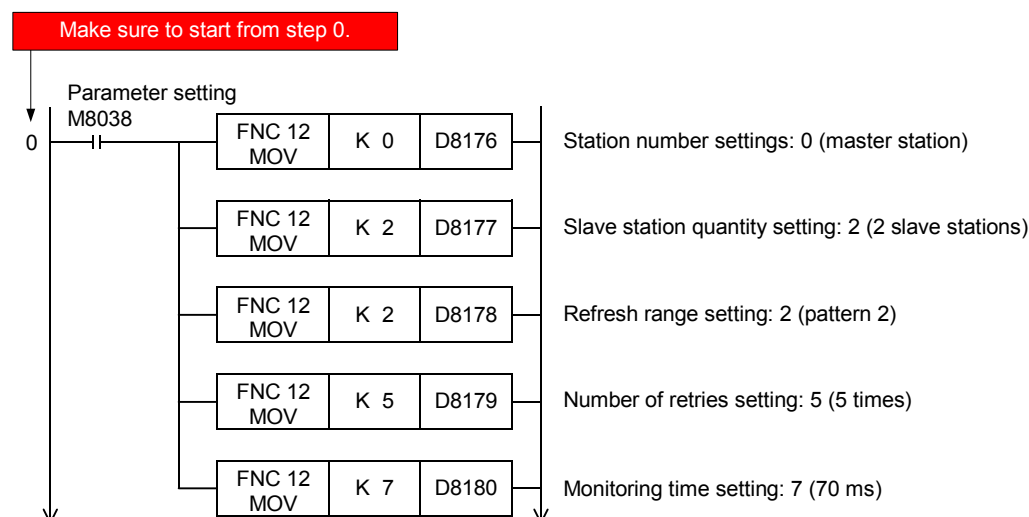
| System device | Master station | Station No. 1 | Station No. 2 | Contents |
|---------------|----------------|---------------|---------------|-----------------------------------|
| D8176 | K 0 | K 1 | K 2 | Station number settings |
| D8177 | K 2 | — | — | Total number of slave stations: 2 |
| D8178 | K 2 | — | — | Refresh range: Pattern 2 |
| D8179 | K 5 | — | — | Number of retries: 5 |
| D8180 | K 7 | — | — | Monitoring time: 70 ms |

8.1.4 Setting program for master station

For the master station setting program, refer to the program shown below.

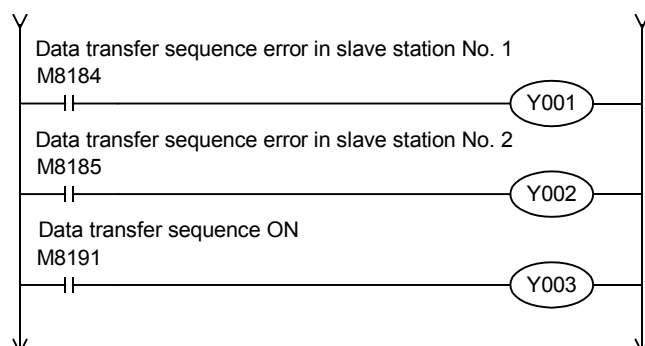
The program shown below consists of three blocks, "parameter setting program," "error indication program" and "operation program."

1. Parameter setting program

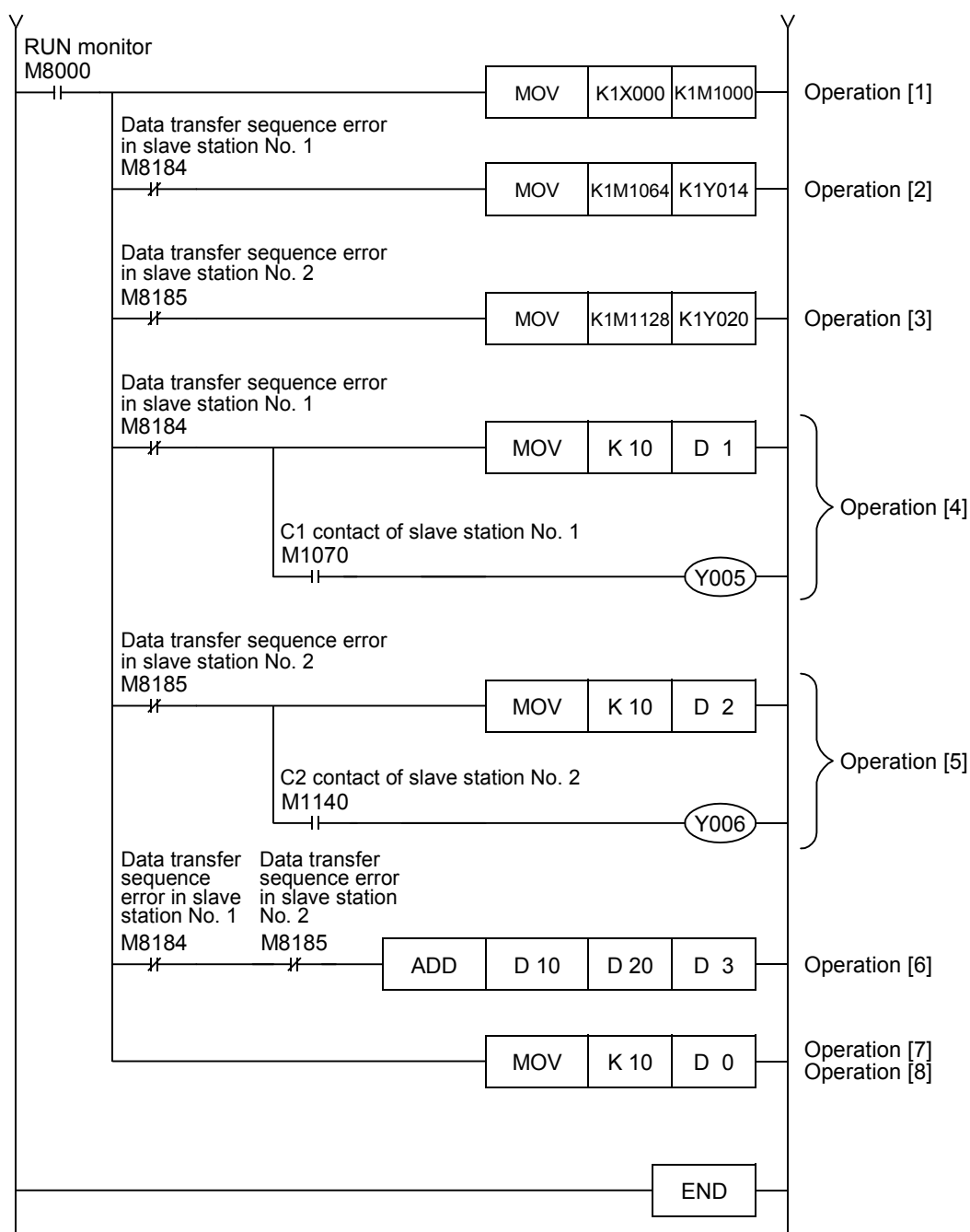


2. Error indication program

Because the master station does not recognize errors within itself (the master station), programs for errors within itself are not required.



3. Operation program



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

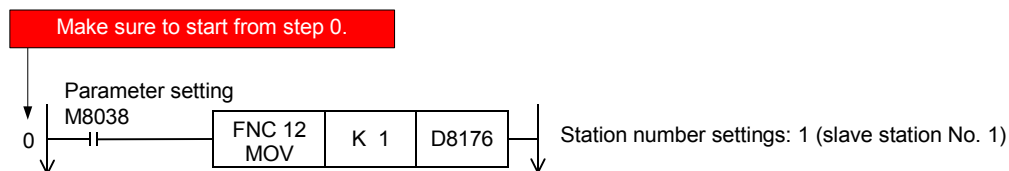
Discontinued models

8.1.5 Setting program for slave station (No. 1)

For the slave station setting program, refer to the program shown below.

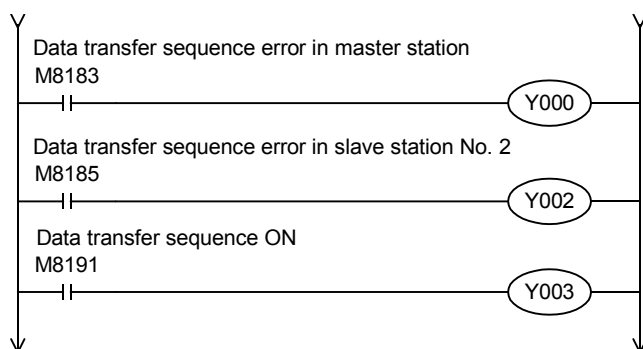
The program shown below consists of three blocks, "parameter setting program," "error indication program" and "operation program."

1. Parameter setting program

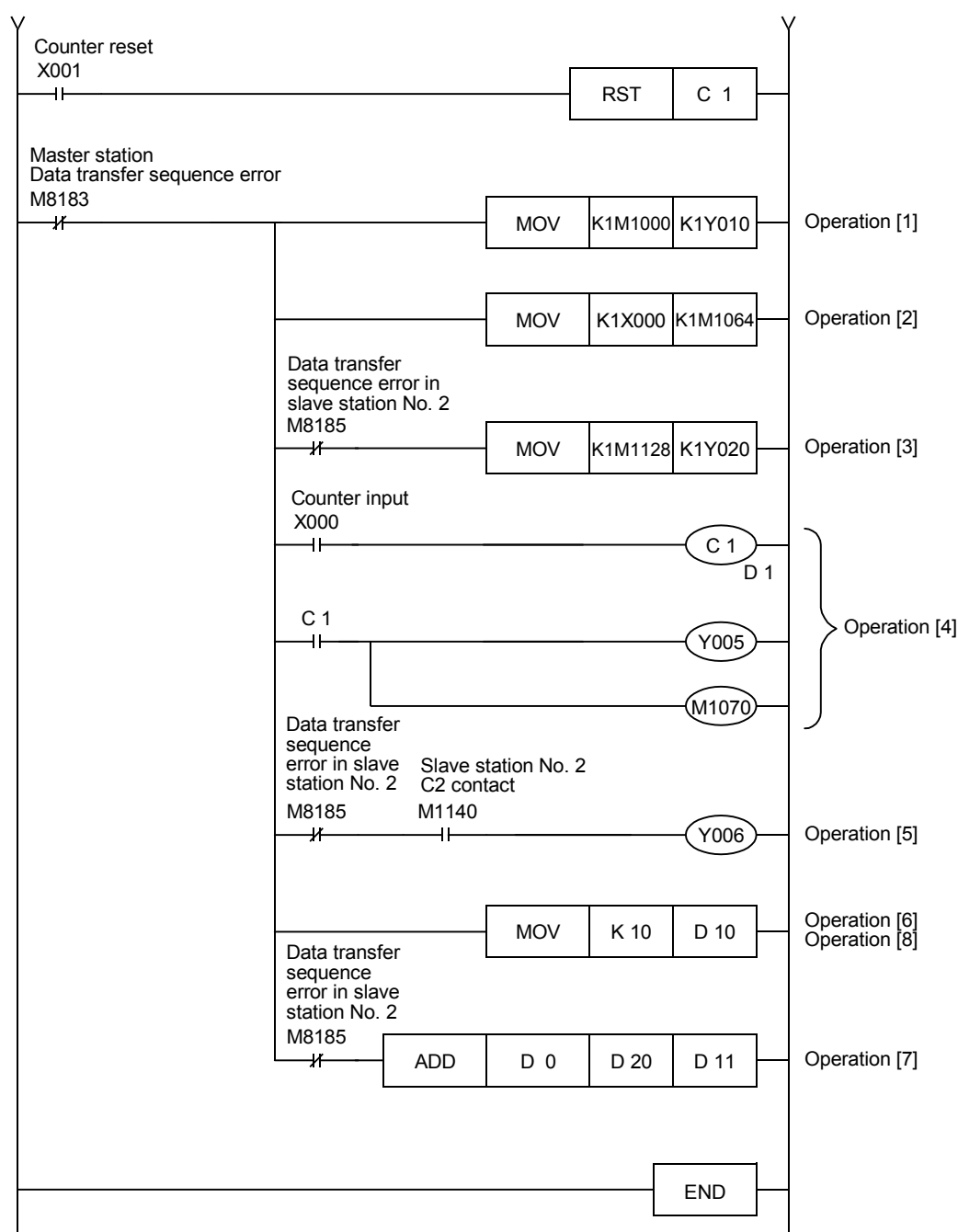


2. Error indication program

Because slave station No. 1 does not recognize errors within itself (slave station No. 1), programs for errors within itself are not required.



3. Operation program



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

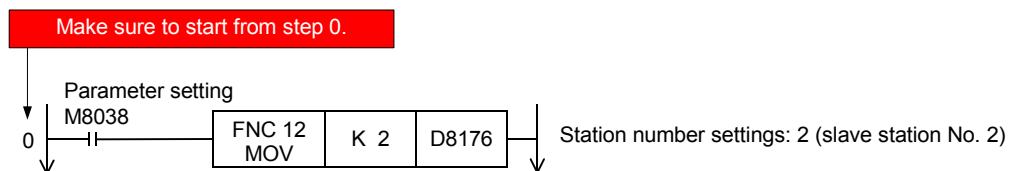
Discontinued models

8.1.6 Setting program for slave station (No. 2)

For the slave station setting program, refer to the program shown below.

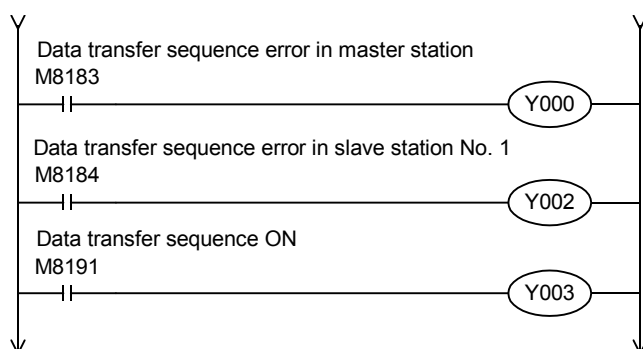
The program shown below consists of three blocks, "parameter setting program," "error indication program" and "operation program."

1. Parameter setting program

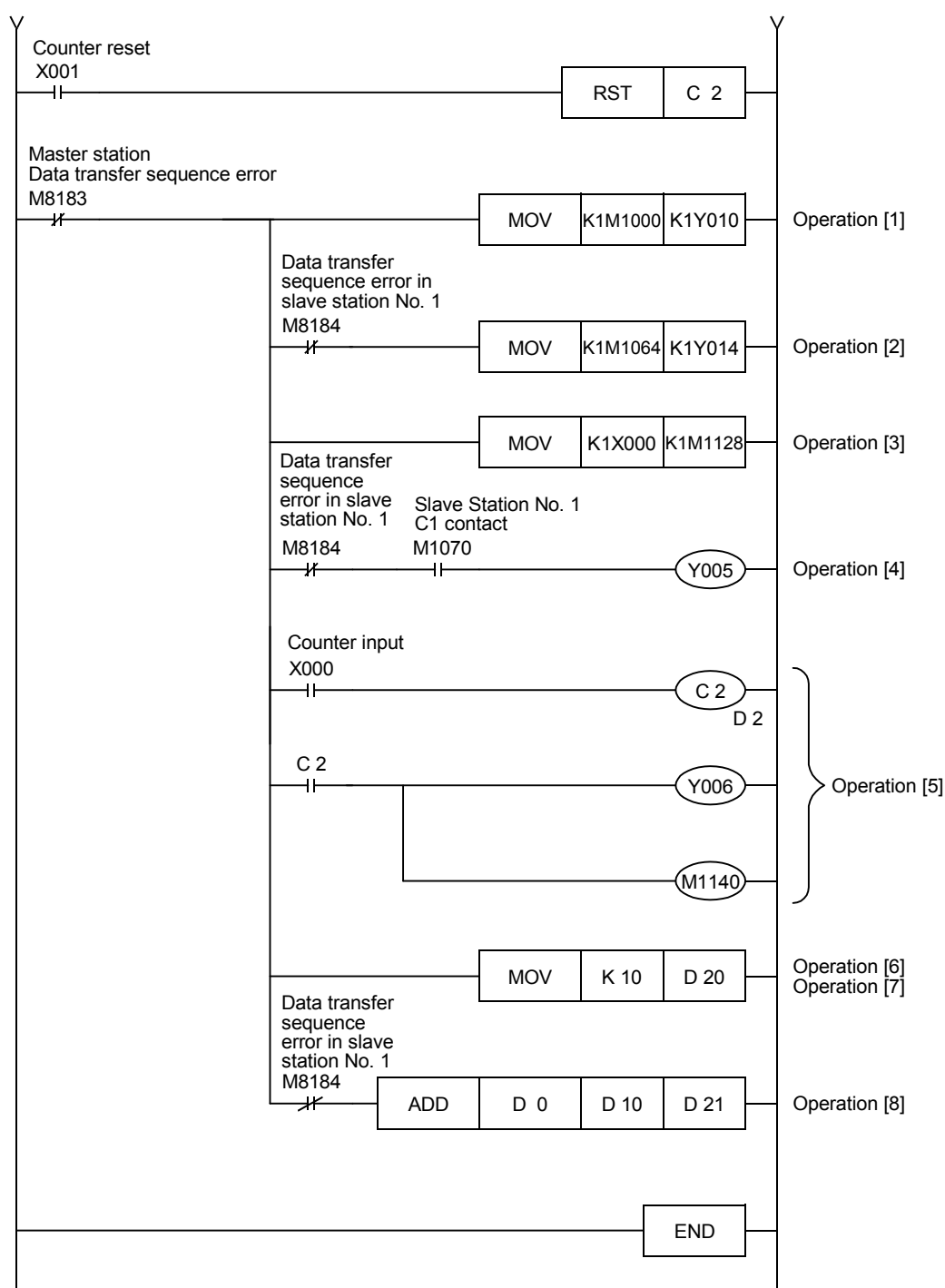


2. Error indication program

Because slave station No. 2 does not recognize errors within itself (slave station No. 2), programs for errors within itself are not required.



3. Operation program



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9. Troubleshooting

This chapter explains troubleshooting.

9.1 Checking FX PLC Version Applicability

Verify that the FX Series PLC main unit is an applicable version.

→ For the version applicability check, refer to Section 1.3.

9.2 Checking Communication Status Based on LED Indication

Check the status of the "RD" and "SD" indicator LEDs provided in the optional equipment.

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RD | SD | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received. |
| Off | Off | Data is not sent nor received. |

While the N:N Network is executed normally, both LEDs flash brightly.

If they do not flash, check the wiring and the communication setting in the master and slave stations.

9.3 Checking Installation and Wiring

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ For mounting method, refer to the respective communication equipment manual.

2. Power supply (For FX0N-485ADP)

The FX0N-485ADP requires a driving power supply. Verify that the power supply is correctly provided.

3. Wiring

Verify that the wiring to all communication equipment is correct. If the communication equipment is wired incorrectly, communication is not possible.

→ For wiring method check, refer to Chapter 4.

9.4 Checking Sequence Program

1. Communication setting in the sequence program

Verify that the parallel link is not set. Using both the parallel link and the N:N Network at the same time is not allowed.

Verify that the communication format (D8120 and D8420) is set correctly. Communication is not possible if a communication port is set twice or more.

After changing any setting, make sure to reboot the PLC's power.

→ For communication setting, refer to Chapter 5.

2. Communication setting using parameters

Verify that the communication settings using parameters are suitable for use. Do not set parameters for the N:N Network. If the communication settings are not suitable for use, communication will not function correctly. After changing a setting, make sure to reboot the PLC's power.

→ For the communication setting, refer to Chapter 5.

3. Presence of VRRD and VRSC instructions (except FX3U and FX3UC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program.
If these instructions are used, delete them, reboot the PLC's power.

4. Presence of RS instruction (except FX3U and FX3UC PLCs)

Verify that the RS instruction is not used in the program.
If this instruction is used, delete it, reboot the PLC's power.

5. Presence of RS and RS2 instructions (in FX3U and FX3UC PLCs)

Verify that the RS and RS2 instructions are not being used for the same channel.
If these instructions are used for the same channel, delete them, reboot the PLC's power.

6. Presence of EXTR instruction (in FX2N and FX2NC PLCs)

Verify that the EXTR instruction is not used in the program.
If this instruction is used, delete it, then reboot the PLC's power.

7. Presence of IVCK, IVDR, IVRD, IVWR, and IVBWR instructions (in FX3U and FX3UC PLCs)

Verify that the IVCK, IVDR, IVRD, IVWR and IVBWR instructions are not being used for the same channel.
If these instructions are used for the same channel, delete them, reboot the PLC's power.

9.5 Checking Setting Contents and Errors

1. Checking the setting contents

Verify that the N:N Network is set correctly.

Each FX PLC has devices for checking the setting. Verify that the correct contents are stored in the devices shown in the table below.

| Device | Name | Description |
|--------|---------------------------------------|---|
| D8173 | Station number settings status | Provided to check the station number. |
| D8174 | Slave station quantity setting status | Provided to check the number of slave stations. |
| D8175 | Refresh range setting status | Provided to check the refresh range. |

If the correct contents are not stored in the devices above, check the sequence program.

2. Checking setting errors (only in FX3U and FX3UC PLCs)

1) Error flags

If the parameter setting includes an error, the serial communication error flag turns ON.

Verify that the devices shown in the table below are ON.

| Device | Name | Description |
|--------|-------------------------------------|--|
| M8063 | Serial communication error 1 (ch 1) | Turns ON when abnormality occurs during serial communication using ch 1. |
| M8438 | Serial communication error 2 (ch 2) | Turns ON when abnormality occurs during serial communication using ch 2. |

When using the N:N Network on ch 1, check M8063.

When using the N:N Network on ch 2, check M8438.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2) Error codes

When the serial communication error flag turns ON, the error code is stored in the device specified in the table below.

| Device | Name | Error code | Description |
|--------|--|------------|-------------------------------------|
| D8063 | Serial communication error code 1 (ch 1) | 6308 | N:N Network parameter setting error |
| D8438 | Serial communication error code 2 (ch 2) | 3808 | |

9.6 Checking Absence/Presence of Data Transfer Errors

Verify that link errors have not occurred in the master station and slave stations. Link errors can be checked using the flags specified below.

9.6.1 Check while data transfer sequence is being executed

While the N:N Network is being executed, the data transfer sequence ON flag remains ON.
Verify that the device specified in the table below is ON.

| FX Series | Device | Name | Description |
|--|--------|--------------------------------|---|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | M8191 | Data transfer sequence ON flag | Remains ON while data transfer is being executed. |
| FX0N, FX1S | M503 | | |

9.6.2 Checking data transfer sequence errors

When a link error occurs in the master station or slave station, the data transfer sequence error flag turns ON. The data transfer sequence error flag varies depending on the FX Series and station number. Refer to the table below.

| FX Series | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | M8183 | M8184 | M8185 | M8186 | M8187 | M8188 | M8189 | M8190 |
| FX0N, FX1S | M504 | M505 | M506 | M507 | M508 | M509 | M510 | M511 |

9.6.3 Checking error codes

When a data transfer sequence error occurs, the corresponding data transfer sequence error flag turns ON, and the error code is stored in the corresponding data register.

→ For error codes, refer to the next page.

1. Error storing device

The data register used to store the data transfer error code varies depending on the FX Series and station number. Refer to the table below.

| FX Series | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | D8211 | D8212 | D8213 | D8214 | D8215 | D8216 | D8217 | D8218 |
| FX0N, FX1S | D211 | D212 | D213 | D214 | D215 | D216 | D217 | D218 |

2. Error code list

The data register for storing the data transfer error code stores the corresponding error code. When a data transfer sequence error occurs, refer to the error code list shown below, and confirm the check points.

| Error code | Error name | Station in which error occurred | Station which detected error | Contents of error | Check point |
|------------|---------------------------------|---------------------------------|------------------------------|--|--|
| 01H | Monitoring timeout | L | M | Slave station did not respond to the sending request from the master station within the monitoring time. | Wiring and power supply |
| 02H | Station number error | L | M | An unexpected slave station responded to the sending request by the master station. | Wiring |
| 03H | Counter error | L | M | The counter value included in the parameter data is different from the counter value given by a slave station. | Wiring |
| 04H | Message format error | L | M, L | The message given by the slave station is incorrect. | Wiring, power supply and station number settings |
| 11H | Monitoring timeout | M | L | The master station did not give a sending request to the next slave station within the monitoring timer. | Wiring and power supply |
| 14H | Message format error | M | L | The message from the master station is incorrect. | Wiring, power supply and station number settings |
| 21H | Slave station no response error | L | L*1 | The specified slave station does not exist. | Wiring, power supply and station number settings |
| 22H | Station number error | L | L*1 | An unexpected slave station responded to the sending request by the master station. | Wiring |
| 23H | Counter error | L | L*1 | The counter value included in the parameter data is different from the counter value given by a slave station. | Wiring |
| 31H | Parameter not received | L | L*2 | Before parameters had been received, sending request was received from the master station. | Wiring and power supply |

M: Master station, L: Slave station

- *1. Any slave station other than the slave station in which error occurred
- *2. Station in which error occurred

10. Related Data

10.1 Related Device List

10.1.1 For FX1N, FX2N, FX3U, FX1NC, FX2NC, and FX3UC PLCs

1. Bit devices

| Device number | Name | Description | Initial value | Detection | R/W | |
|--|-------------------------------------|--|---------------|-----------|-----|--|
| Devices for communication setting | | | | | | |
| M8038 | Parameter setting | Communication parameter setting flag | — | M, L | R | |
| M8179 | Channel setting | Sets the communication port channel to be used (in the FX3U and FX3UC). | — | M, L | R/W | |
| Devices for checking communication status | | | | | | |
| M8063 | Serial communication error 1 (ch 1) | Turns ON when abnormality occurs in serial communication using ch 1 (in the FX3U and FX3UC). | — | M, L | R | |
| M8438 | Serial communication error 2 (ch 2) | Turns ON when abnormality occurs in serial communication using ch 2 (in the FX3U and FX3UC). | — | M, L | R | |
| M8183 | Data transfer sequence error | Turns ON when a data transfer sequence error occurs in the master station. | — | L | R | |
| M8184 to M8190 | Data transfer sequence error | Turns ON when a data transfer sequence error occurs in a slave station. However, data transfer sequence errors within the slave station itself cannot be detected. | — | M, L | R | |
| M8191 | Data transfer sequence ON | Remains ON while data transfer is being executed. | — | M, L | R | |

R : Read only (used as a contact in program)

R/W : Read or Write

M : Master station (station No. 0)

L : Slave station (station No. 1 to 7)

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (FSRS2 Institution) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | — | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | M8184 | M8185 | M8186 | M8187 | M8188 | M8189 | M8190 |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

2. Word devices (data registers)

| Device number | Name | Description | Initial value | Detection | R/W | |
|--|--|---|---------------|-----------|-----|--|
| Devices for checking | | | | | | |
| D8173 | Corresponding station number settings status | Provided to check the station number. | — | M, L | R | |
| D8174 | Slave station quantity setting status | Provided to check the number of slave stations. | — | M, L | R | |
| D8175 | Refresh range setting status | Provided to check the refresh range. | — | M, L | R | |
| D8063 | Serial communication error code 1 (ch 1) | Stores the serial communication error code for ch. 1 (in the FX3U and FX3UC). | — | M, L | R | |
| D8438 | Serial communication error code 2 (ch 2) | Stores the serial communication error code for ch. 2 (in the FX3U and FX3UC). | — | M, L | R | |
| Devices for communication setting | | | | | | |
| D8176 | Corresponding station number settings | Provided to set the station number. | 0 | M, L | R/W | |
| D8177 | Slave station quantity setting | Provided to set the number of slave stations used in communication. | 7 | M | R/W | |
| D8178 | Refresh range setting | Provided to set the refresh range. | 0 | M | R/W | |
| D8179 | Number of retries | Provided to set the number of retry times. | 3 | M | R/W | |
| D8180 | Monitoring time | Provided to set the no-response monitoring time. | 5 | M | R/W | |
| Devices for checking communication status | | | | | | |
| D8201 | Present link scan time | Current value of the network cycle time | — | M | R | |
| D8202 | Maximum link scan time | Maximum value of the network cycle time | — | M | R | |
| D8203 | Data transfer sequence error count | Amount of data sequence errors that occurred in the master station | — | L | R | |
| D8204 to D8210 | Data transfer sequence error count | Amount of data sequence errors that occurred in a slave station. However, data sequence errors occurring within the slave station itself cannot be counted. | — | M, L | R | |
| D8211 | Data transmission error code | Stores the error code for the master station. | — | L | R | |
| D8212 to D8218 | Data transmission error code | Stores the error code for a slave station. However, data sequence errors occurring within the slave station itself cannot be counted. | — | M, L | R | |

R : Read only (used as a contact in program)

R/W : Read or Write

M : Master station (station No. 0)

L : Slave station (station No. 1 to 7)

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol
(RS/R2 Instruction)

G

Non-Protocol
(FX2N-232IF)

H

Programming
Communication

I

Remote
Maintenance

Apx.

Discontinued
models

| | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | — | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | D8204 | D8205 | D8206 | D8207 | D8208 | D8209 | D8210 |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | D8212 | D8213 | D8214 | D8215 | D8216 | D8217 | D8218 |

10.1.2 For FX1s and FX0N PLCs

1. Bit devices

| Device number | Name | Description | Initial value | Detection | R/W | |
|--|------------------------------|--|---------------|-----------|-----|--|
| Devices for communication setting | | | | | | |
| M8038 | Parameter setting | Communication parameter setting flag | — | M, L | R | |
| Devices for checking communication status | | | | | | |
| M504 | Data transfer sequence error | Turns ON when a data transfer sequence error occurs in the master station. | — | L | R | |
| M505 to M511 | Data transfer sequence error | Turns ON when a data transfer sequence error occurs in a slave station. However, data transfer sequence errors within the slave station itself cannot be detected. | — | M, L | R | |
| M503 | Data transfer sequence ON | Remains ON while data transfer is being executed. | — | M, L | R | |

R: Read only (used as a contact in program)

M: Master station (station No. 0) L: Slave station (station No. 1 to 7)

2. Word devices (data registers)

| Device number | Name | Description | Initial value | Detection | R/W | |
|--|--|---|---------------|-----------|-----|--|
| Devices for checking | | | | | | |
| D8173 | Corresponding station number settings status | Provided to check the station number. | — | M, L | R | |
| D8174 | Slave station quantity setting status | Provided to check the number of slave stations. | — | M, L | R | |
| D8175 | Refresh range setting status | Provided to check the refresh range. | — | M, L | R | |
| Devices for communication setting | | | | | | |
| D8176 | Corresponding station number settings | Provided to set the station number. | 0 | M, L | R/W | |
| D8177 | Slave station quantity setting | Provided to set the number of slave stations used in communication. | 7 | M | R/W | |
| D8178 | Refresh range setting | Provided to set the refresh range. | 0 | M | R/W | |
| D8179 | Number of retries | Provided to set the number of retries. | 3 | M | R/W | |
| D8180 | Monitoring time | Provided to set the no-response monitoring time. | 5 | M | R/W | |
| Devices for checking communication status | | | | | | |
| D201 | Present link scan time | Stores the current value of the network cycle time. | — | M | R | |
| D202 | Maximum link scan time | Stores the maximum value of the network cycle time. | — | M | R | |
| D203 | Data transfer sequence error count | Stores the amount of data sequence errors that occurred in the master station. | — | L | R | |
| D204 to D210 | Data transfer sequence error count | Amount of data sequence errors that occurred in a slave station. However, data sequence errors that occurred within the slave station itself cannot be counted. | — | M, L | R | |
| D211 | Data transmission error code | Stores the error code for the master station. | — | L | R | |
| D212 to D218 | Data transmission error code | Stores the error code for a slave station. However, data sequence errors that occurred within the slave station itself cannot be counted. | — | M, L | R | |
| D219 to D255 | Not applicable | Provided for the internal processing. | — | — | — | |

R: Read only (used as a contact in program) R/W: Read or Write

M: Master station (station No. 0) L: Slave station (station No. 1 to 7)

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS485 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

| | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | — | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | M505 | M506 | M507 | M508 | M509 | M510 | M511 |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

| | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | — | — | — | — | — | — | — |
| | — | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| | ✓ | D204 | D205 | D206 | D207 | D208 | D209 | D210 |
| | ✓ | — | — | — | — | — | — | — |
| | ✓ | D212 | D213 | D214 | D215 | D216 | D217 | D218 |
| | — | — | — | — | — | — | — | — |

10.2 Details of Related Devices

The devices described below are used in the N:N Network.

10.2.1 Parameter setting [M8038]

This device works as the communication parameter setting flag.

1. Stations requiring program setting

Setting is required for the master station and slave stations.

2. Detailed contents

"LD M8038" provided in step 0 starts the parameter setting, and the last instruction in this circuit block finishes the setting.

(This sequence program is not executed in every scan cycle.)

3. Cautions on use

Do not set this device to ON using a program or programming tool.

10.2.2 Channel setting [M8179]

This device works as the channel setting flag (in the FX3U and FX3UC).

1. Stations requiring program setting

Setting is required for the master station and slave stations.

2. Detailed contents

When using ch 2 as the communication port, set this device to ON in the sequence program.

When using ch 1, the sequence program is not required.

10.2.3 Serial communication error [M8063 and M8438]

These devices turn ON when an error is included in the parameters used to set the N:N Network. (M8438 is available in the FX3U and FX3UC.)

1. Stations requiring program setting

Setting is required for the master station and slave stations to check the communication status.

2. Detailed contents

M8063 turns ON when an error is included in the parameters used to set N:N Network using ch 1.

M8438 turns ON when an error is included in the parameters used to set N:N Network using ch 2.

3. Cautions on use

Do not set these devices to ON using a program or programming tool.

10.2.4 Data transfer sequence error [M8138 to M8190] [M504 to M511]

These devices turn ON when a data transfer sequence error occurs in the master station or a slave station.

1. Stations requiring program setting

Setting is required for the master station and slave stations.
However, setting for the station itself is not required.

2. Detailed contents

A used device varies depending on the FX Series.

| FX Series | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|---------------------------------------|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | M8183 | M8184 | M8185 | M8186 | M8187 | M8188 | M8189 | M8190 |
| FX0N, FX1S | M504 | M505 | M506 | M507 | M508 | M509 | M510 | M511 |

3. Cautions on use

Data transfer sequence errors in a station itself cannot be detected.
Do not set these devices to ON using a program or programming tool.

10.2.5 Data transfer sequence ON [M8191] [M503]

This device remains ON while data transfer is being from or to in the master station or slave station.

1. Stations requiring program setting

Setting is required for the master station and slave stations.

2. Detailed contents

The device used varies depending on the FX Series.

| FX Series | Data transfer sequence ON |
|---------------------------------------|---------------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | M8191 |
| FX0N, FX1S | M503 |

3. Cautions on use

Do not set this device to ON using a program or programming tool.

10.2.6 Serial communication error code [D8063 and D8438]

These devices store the serial communication error code (in the FX3U and FX3UC).

1. Stations requiring program setting

Setting is required for the master station and slave stations to check the error code.

2. Detailed contents

The error code of the serial communication error that occurred in ch 1 is stored in D8063.
If an error is included in the parameters used for the N:N Network, "6308" is stored.
The error code of the serial communication error that occurred in ch 2 is stored in D8438.
If an error is included in the parameters used for the N:N Network, "3808" is stored.

3. Cautions on use

Serial communication errors are not cleared even after communication has recovered its normal status. To clear them, switch the PLC mode from STOP to RUN.

10.2.7 Corresponding station number settings status [D8173]

This device is used to check the station's own station number settings status.

1. Stations requiring program setting

Setting is required for the master station and slave stations to check the setting status.

2. Detailed contents

The contents stored in the corresponding station number settings device D8176 are stored in D8173.

3. Cautions on use

Do not change the preset numeric value using a program or programming tool.

10.2.8 Slave station quantity setting status [D8174]

Use this device to check the number of slave stations set in the master station.

1. Stations requiring program setting

Setting is required for the master station and slave stations to check the setting status.

2. Detailed contents

The contents stored in the slave station quantity setting device D8177 in the master station are stored in D8174.

3. Cautions on use

Do not change a preset numeric value using a program or programming tool.

10.2.9 Refresh range setting status [D8175]

Use this device to check the refresh range set in the master station.

1. Stations requiring program setting

Setting is required for the master station and slave stations to check the setting status.

2. Detailed contents

The contents stored in the refresh range setting device D8178 in the master station are stored in D8175.

3. Cautions on use

Do not change a preset numeric value using a program or programming tool.

10.2.10 Station number settings [D8176]

Set a value ranging from 0 to 7 to the special data register D8176 (initial value: 0).

1. Stations requiring program setting

The master and slave stations require program setting.

2. Detailed contents

| Set value | Description |
|-----------|--|
| 0 | Master station |
| 1 to 7 | Slave station number Examples: "1" → Station No. 1, "5" → Station No. 5 |

10.2.11 Slave station quantity setting [D8177]

Set a value ranging from 1 to 7 to the special data register D8177 (initial value: 7).

1. Stations requiring program setting

The master station requires program setting, and slave stations do not require program setting.

2. Detailed contents

| Set value | Description |
|-----------|-------------------------------------|
| 0 | Not applicable |
| 1 | One slave station is connected. |
| 2 | Two slave stations are connected. |
| 3 | Three slave stations are connected. |

| Set value | Description |
|-----------|-------------------------------------|
| 4 | Four slave stations are connected. |
| 5 | Five slave stations are connected. |
| 6 | Six slave stations are connected. |
| 7 | Seven slave stations are connected. |

10.2.12 Refresh range setting [D8178]

Set a value ranging from 0 to 2 to the special data register D8178 (initial value: 0).

1. Stations requiring program setting

The master station requires program setting, and slave stations do not require program setting.

2. Pattern applicability in FX PLC

| Pattern (set value) | Pattern 0 (0) | Pattern 1 (1) | Pattern 2 (2) |
|---------------------|---------------|----------------|----------------|
| FX0N PLC | ✓ | Not applicable | Not applicable |
| FX1S PLC | ✓ | Not applicable | Not applicable |
| FX1N PLC | ✓ | ✓ | ✓ |
| FX2N PLC | ✓ | ✓ | ✓ |
| FX3U PLC | ✓ | ✓ | ✓ |
| FX1NC PLC | ✓ | ✓ | ✓ |
| FX2NC PLC | ✓ | ✓ | ✓ |
| FX3UC PLC | ✓ | ✓ | ✓ |

3. Number and assignment of link devices

The number of link devices varies depending on the selected pattern, but the head device number remains the same.

It is recommended to leave unused numbers in the unused status to enable pattern change in the future.

| Station No. | Pattern 0 | | Pattern 1 | | Pattern 2 | |
|-------------|----------------|-------------------|--------------------|-------------------|--------------------|-------------------|
| | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) |
| | 0 | 4 in each station | 32 in each station | 4 in each station | 64 in each station | 8 in each station |
| 0 | — | D 0 to D 3 | M1000 to M1031 | D 0 to D 3 | M1000 to M1063 | D 0 to D 7 |
| 1 | — | D10 to D13 | M1064 to M1095 | D10 to D13 | M1064 to M1127 | D10 to D17 |
| 2 | — | D20 to D23 | M1128 to M1159 | D20 to D23 | M1128 to M1191 | D20 to D27 |
| 3 | — | D30 to D33 | M1192 to M1223 | D30 to D33 | M1192 to M1255 | D30 to D37 |
| 4 | — | D40 to D43 | M1256 to M1287 | D40 to D43 | M1256 to M1319 | D40 to D47 |
| 5 | — | D50 to D53 | M1320 to M1351 | D50 to D53 | M1320 to M1383 | D50 to D57 |
| 6 | — | D60 to D63 | M1384 to M1415 | D60 to D63 | M1384 to M1447 | D60 to D67 |
| 7 | — | D70 to D73 | M1448 to M1479 | D70 to D73 | M1448 to M1511 | D70 to D77 |

4. Cautions on use

- 1) Cautions on using FX1S and FX0N PLCs
When FX1S and/or FX0N PLCs are included in the system, make sure to set the refresh range to pattern 0.
If any other pattern is selected, data transfer error will occur in all FX1S and FX0N PLCs included in the system, and the link time will become longer.
- 2) Occupied devices
The devices used in each pattern are occupied for the N:N Network in all stations.
Make sure that such devices are not used in general programs.

10.2.13 Number of retries [D8179]

Set a value ranging from 0 to 10 to the special data register D8179 (initial value: 3).

1. Stations requiring program setting

The master station requires program setting, and slave stations do not require program setting.

2. Detailed contents

When any response is not given after the specified number of retries, the unresponsive station is regarded as having a data transfer sequence error by other stations.

10.2.14 Monitoring time setting [D8180]

Set a value ranging from 5 to 255 to the special data register D8180 in "10 ms" units (initial value: 5 [50 ms]).

1. Stations requiring program setting

The master station requires program setting, and slave stations do not require program setting.

2. Detailed contents

If data transfer between the master station and a slave station requires time longer than the monitoring time set here, the master station or slave station is regarded as abnormal.

10.2.15 Present link scan time [D8201] [D201]

This device stores the current value of the network cycle in the N:N Network (unit: 0.1 ms).

1. Stations requiring program setting

The master station requires program setting.

2. Detailed contents

The device used varies depending on the FX Series.

| FX Series | Data transfer sequence ON |
|--|---------------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | D8201 |
| FX0N, FX1S | D201 |

3. Cautions on use

Do not change the preset numeric value using a program or programming tool.

10.2.16 Maximum link scan time [D8202] [D202]

This device stores the maximum value of the network cycle in the N:N Network (unit: 0.1 ms).

1. Stations requiring program setting

The master station requires program setting.

2. Detailed contents

The device used varies depending on the FX Series.

| FX Series | Data transfer sequence ON |
|--|---------------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | D8202 |
| FX0N, FX1S | D202 |

3. Cautions on use

Do not change the preset numeric value using a program or programming tool.

10.2.17 Data transfer sequence error count [D8203 to D8210] [D203 to D210]

These devices store the amount of data transfer sequence errors that occurred in the master station and slave stations.

1. Stations requiring program setting

The master and slave stations require program setting.
However, setting for the station itself is not required.

2. Detailed contents

The device used varies depending on the FX Series.

| FX Series | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|--|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | D8203 | D8204 | D8205 | D8206 | D8207 | D8208 | D8209 | D8210 |
| FX0N, FX1S | D203 | D204 | D205 | D206 | D207 | D208 | D209 | D210 |

3. Cautions on use

Data transfer sequence errors that occurred within the station itself cannot be detected.
Do not change a preset numeric value using the program or programming tool.

10.2.18 Data transfer error code [D8211 to D8218] [D211 to D218]

These devices store the error code in the master station and slave stations.

1. Stations requiring program setting

The master station requires program setting.
However, this setting for the station itself is not required.

2. Detailed contents

1) The device used varies depending on the FX Series.

| FX Series | Master station | Slave station No. 1 | Slave station No. 2 | Slave station No. 3 | Slave station No. 4 | Slave station No. 5 | Slave station No. 6 | Slave station No. 7 |
|---------------------------------------|----------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|---------------------|
| FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | D8211 | D8212 | D8213 | D8214 | D8215 | D8216 | D8217 | D8218 |
| FX0N, FX1S | D211 | D212 | D213 | D214 | D215 | D216 | D217 | D218 |

2) Error code list

| Error code | Error name | Station in which error occurred | Station which detected error | Contents of error | Check point |
|------------|---------------------------------|---------------------------------|------------------------------|--|--|
| 01H | Monitoring timeout | L | M | Slave station did not respond to the sending request from the master station within the monitoring time. | Wiring and power supply |
| 02H | Station number error | L | M | An unexpected slave station responded to the sending request by the master station. | Wiring |
| 03H | Counter error | L | M | The counter value included in the parameter data is different from the counter value given by a slave station. | Wiring |
| 04H | Message format error | L | M, L | The message given by the slave station is incorrect. | Wiring, power supply and station number settings |
| 11H | Monitoring timeout | M | L | The master station did not give a sending request to the next slave station within the monitoring timer. | Wiring and power supply |
| 14H | Message format error | M | L | The message from the master station is incorrect. | Wiring, power supply and station number settings |
| 21H | Slave station no response error | L | L*1 | The specified slave station does not exist. | Wiring, power supply and station number settings |
| 22H | Station number error | L | L*1 | An unexpected slave station responded to the sending request by the master station. | Wiring |
| 23H | Counter error | L | L*1 | The counter value included in the parameter data is different from the counter value given by a slave station. | Wiring |
| 31H | Parameter not received | L | L*2 | Before parameters had been received, sending request was received from the master station. | Wiring and power supply |

M: Master station, L: Slave station

*1. Any slave station other than the slave station in which error occurred

*2. Station in which error occurred

3. Cautions on use

Data transfer sequence errors that occurred within the station itself cannot be detected.
Do not change the preset numeric value using a program or programming tool.

FX Series Programmable Controllers

User's Manual [Parallel Link]

Foreword

This manual explains "parallel link" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit.
Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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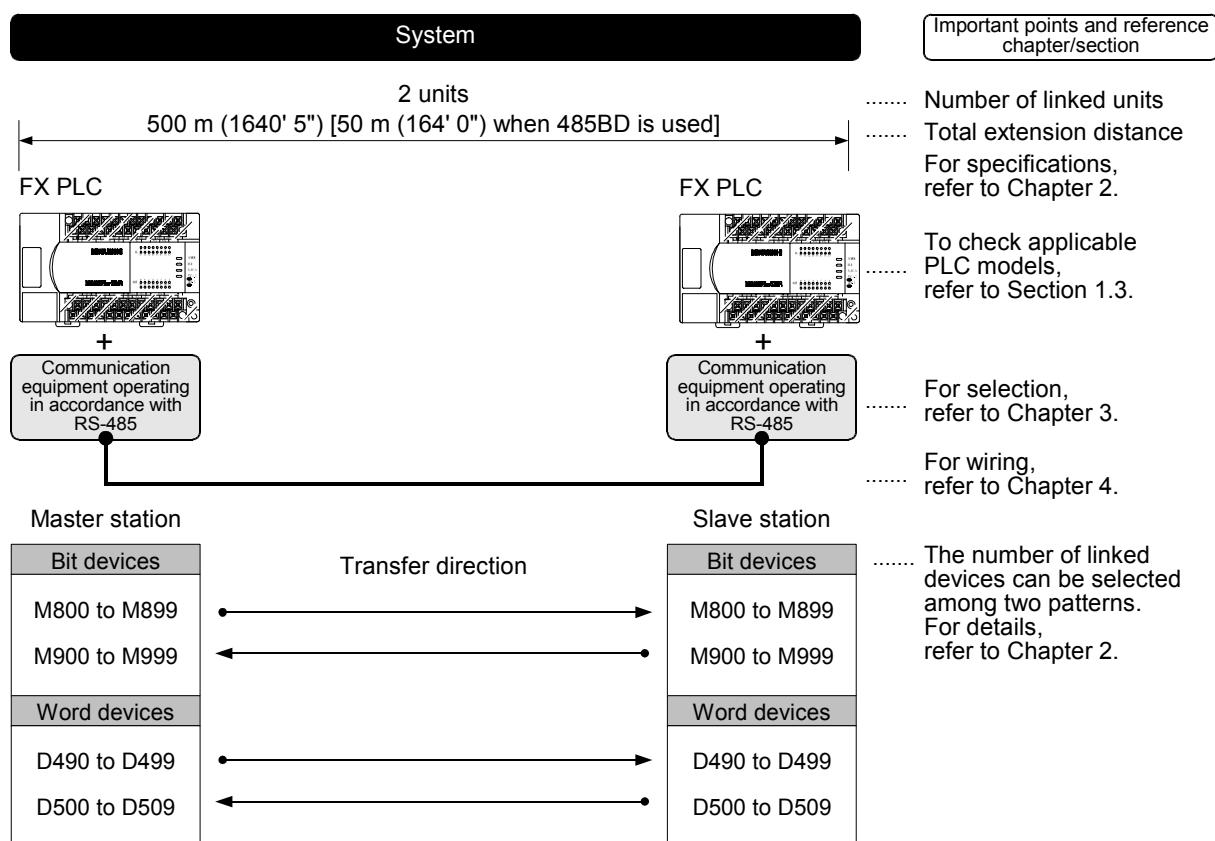
1. Outline

This chapter explains the parallel link.

1.1 Outline of System

The parallel link allows connection between two FX PLCs of the same series to mutually link devices.

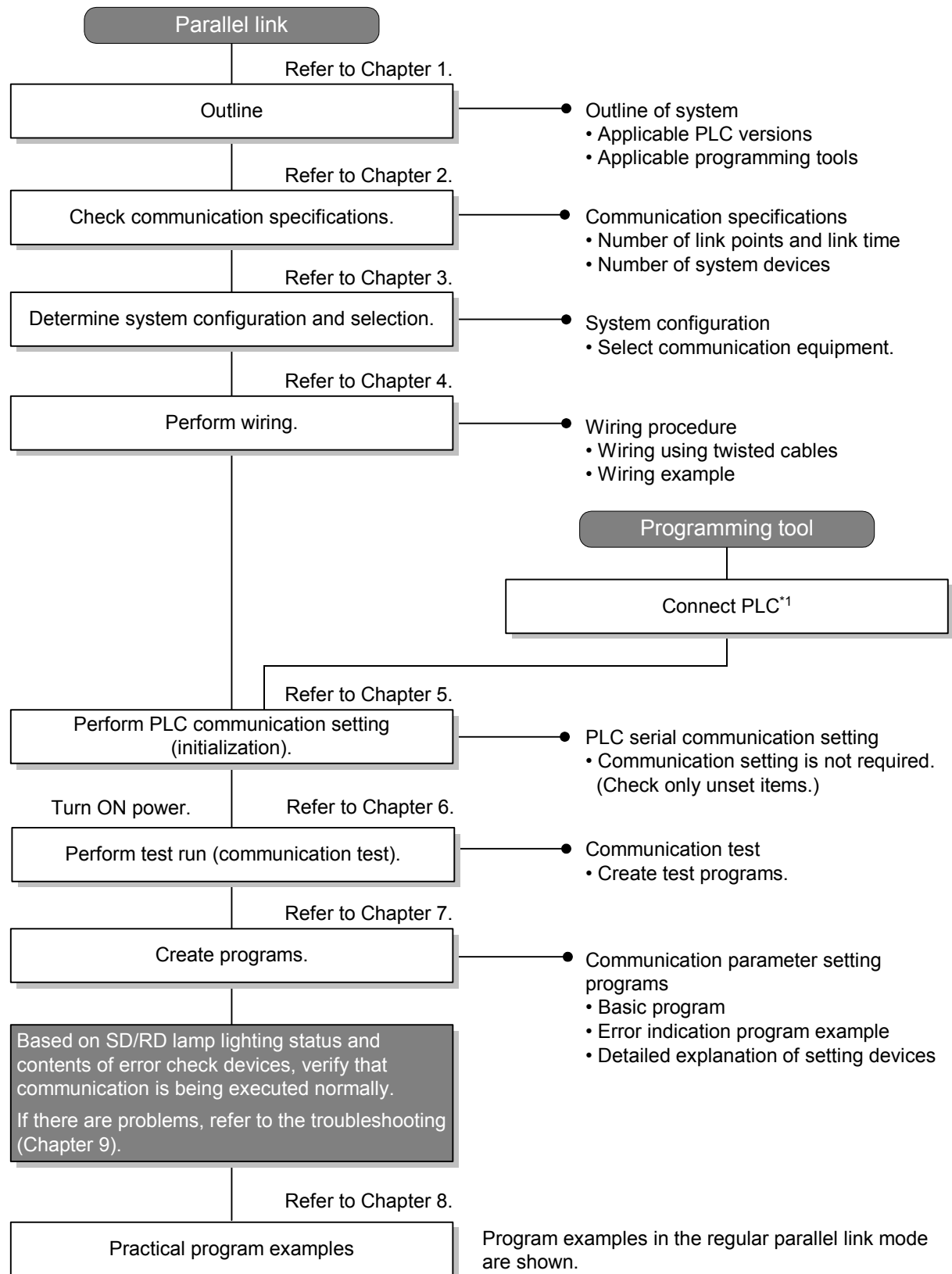
- 1) According to the number of devices to be linked, either pattern can be selected between the regular mode and the high speed mode.
- 2) Data link is automatically updated between up to two FX PLCs.
- 3) The total extension distance is 500 m (1640' 5") maximum (when only the 485ADPs are used except, when the 485BDs are used with FX2(FX)/FX2C PLCs).



The figure above shows the maximum number of linked devices. There are differences in the specifications and limitation depending on the selected link pattern and FX Series.

1.2 Procedures Before Operation

The flow chart below shows the Parallel Link setting procedures up until data link:



*1 For the programming tool to PLC connection procedure, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operating procedures, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

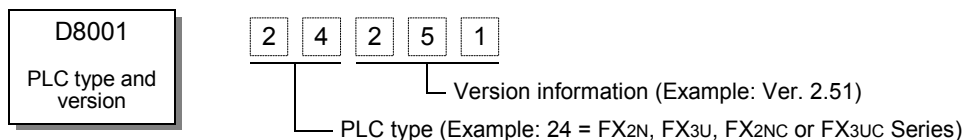
The communication types are applicable in the following versions.

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|------------------------------------|---|
| FX3UC Series | ✓ | |
| FX3U Series | ✓ | |
| FX2NC Series | ✓ | |
| FX2N Series | ✓ (Ver. 1.04 or later) | |
| FX1NC Series | ✓ | |
| FX1N Series | ✓ | |
| FX1S Series | ✓ | The link device range is limited. |
| FX0N Series | ✓ (Ver. 1.20 or later) | The link device range is limited. |
| FX0S Series | — | N:N Network is not provided. |
| FX0 Series | — | N:N Network is not provided. |
| FX2C Series | ✓ | The high speed link mode is supported in Ver. 3.07 and later. |
| FX2(FX) Series | ✓ | The high speed link mode is supported in Ver. 3.07 and later. |
| FX1 Series | — | N:N Network is not provided. |

1. Version check

The D8001(decimal) special data register contains information for determining the PLC version.



1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description on system configuration, etc. in this manual for maintenance.

| PLC | Date when production was stopped | Remarks |
|----------------|----------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2C Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the following version:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC". |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC". |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.00 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXC | ✓ (Ver. 4.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC". |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 5.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXD | ✓ (Ver. 5.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3u and FX3uc PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC". |
| FX2N and FX2Nc PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC". |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXC-E | ✓ (Ver. 3.00 or later) | |
| FX-10P-E | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC". |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXD-E | ✓ (Ver. 4.00 or later) | |
| FX-10P-E | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |

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Non-Protocol Communication (FX2N-232IF)

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Remote Maintenance

Apx.

Discontinued models

1.4.2 For non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set. In this case, however, programming is enabled only in the function ranges provided for the alternative PLC model such as instructions and program size.

| Model to be programmed | Model to be set | Priority: High → Low | | | |
|------------------------|-----------------|----------------------|---------|---|---------|
| FX3UC Series | FX3UC | → | FX2N | → | FX2(FX) |
| FX3U Series | FX3UC, FX3U | → | FX2N | → | FX2(FX) |
| FX2NC Series | FX2NC, FX2N | → | FX2(FX) | | |
| FX2N Series | FX2N | → | FX2(FX) | | |
| FX1NC Series | FX1NC, FX1N | → | FX2N | → | FX2(FX) |
| FX1N Series | FX1N | → | FX2N | → | FX2(FX) |
| FX1S Series | FX1S | → | FX2(FX) | | |
| FX0N Series | FX0N | → | FX2(FX) | | |
| FX0S Series | FX0S | → | FX2(FX) | | |
| FX0 Series | FX0 | → | FX2(FX) | | |
| FX2C Series | FX2C, FX2(FX) | → | FX2(FX) | | |
| FX2(FX) Series | FX2(FX) | → | FX2(FX) | | |
| FX1 Series | FX1 | | | | |

2. Specifications

This chapter explains the communication specifications and performance of the parallel link.

2.1 Communication Specifications (Reference)

The parallel link is executed using the (fixed) communication specifications shown in the table below. Specification items such as baud rate cannot be changed.

| Item | Specifications | Remarks |
|----------------------------------|---|--|
| Number of connectable units | 2 maximum (1:1) | |
| Transmission standard | RS-485 or RS-422 standard | |
| Maximum total extension distance | 500 m (1640' 5") or less [50 m (164' 0") or less when 485BD is included in system] | |
| FX3UC Series | | |
| FX3U Series | | |
| FX2NC Series | | |
| FX2N Series | | |
| FX1NC Series | | |
| FX1N Series | | |
| FX1S Series | | |
| FX0N Series | | |
| FX2C Series | Wire link: 10 m (32' 9") or less Optical fiber: 50 m (164' 0") or less | Wire link: FX2-40AW Optical fiber: FX2-40AP |
| FX2(FX) Series | | |
| Protocol type | Parallel link | |
| Control procedure | — | |
| Communication method | Half-duplex, bidirectional communication | |
| Baud rate | Fixed | |
| Character format | Fixed | |
| Start bit | | |
| Data bit | | |
| Parity bit | | |
| Stop bit | | |
| Header | Fixed | |
| Terminator | | |
| Control line | — | |
| Sum check | Fixed | |

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Computer Link

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Non-Protocol Communication (RS/R2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2.2 Link Specifications

2.2.1 PLC communication type applicability status

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Regular parallel link mode applicability (applicable version) | High speed parallel link mode applicability (applicable version) |
|----------------|--|---|
| FX3UC Series | ✓ | ✓ |
| FX3U Series | ✓ | ✓ |
| FX2NC Series | ✓ | ✓ |
| FX2N Series | ✓ (Ver. 1.04 or later) | ✓ (Ver. 1.04 or later) |
| FX1NC Series | ✓ | ✓ |
| FX1N Series | ✓ | ✓ |
| FX1S Series | ✓ | ✓ |
| FX0N Series | ✓ (Ver. 1.20 or later) | ✓ (Ver. 1.20 or later) |
| FX0S Series | — | — |
| FX0 Series | — | — |
| FX2C Series | ✓ | ✓ (Ver. 3.07 or later) |
| FX2(FX) Series | ✓ | ✓ (Ver. 3.07 or later) |

2.2.2 Link time

The link time indicates the cycle time in which link devices are updated.
The link time varies depending on the link mode as shown in the tables below.

1. For FX3U and FX3UC Series

| Link mode | Time |
|-------------------------------|--|
| Regular parallel link mode | 15 ms + Master station operation cycle (ms) + Slave station operation cycle (ms) |
| High speed parallel link mode | 5 ms + Master station operation cycle (ms) + Slave station operation cycle (ms) |

2. For FX2(FX), FX2C, FX0N, FX1S, FX1N, FX2N, FX1NC and FX2NC Series

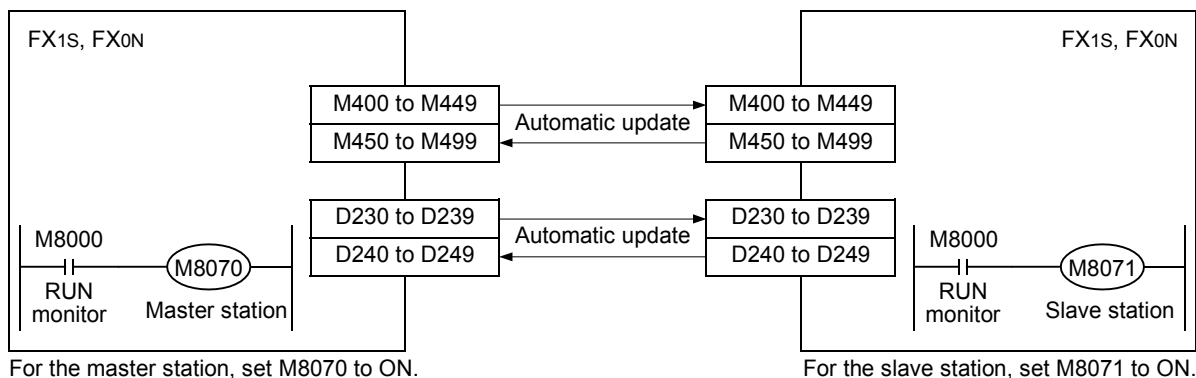
| Link mode | Time |
|-------------------------------|--|
| Regular parallel link mode | 70 ms + Master station operation cycle (ms) + Slave station operation cycle (ms) |
| High speed parallel link mode | 20 ms + Master station operation cycle (ms) + Slave station operation cycle (ms) |

2.3 Link Device Numbers and Number of Points

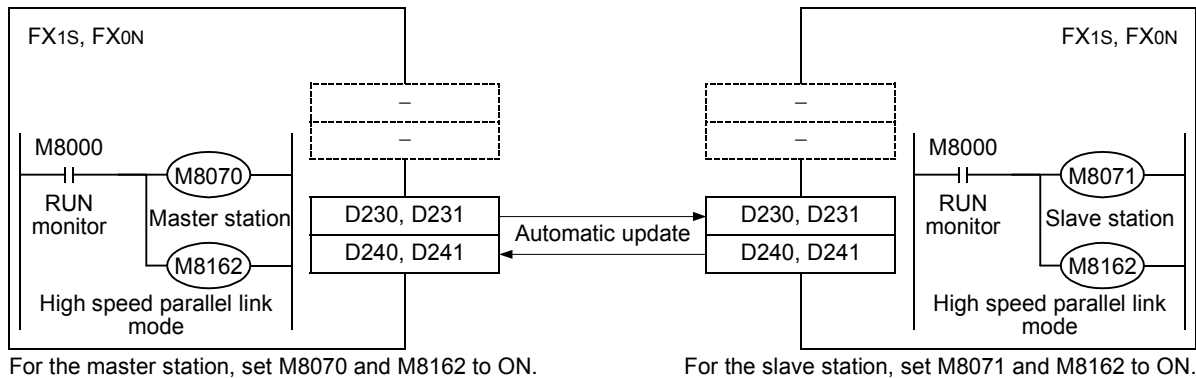
2.3.1 For FX1S and FX0N Series

| Mode | Regular parallel link mode | | High speed parallel link mode | |
|----------------|----------------------------|--------------------|-------------------------------|-------------------|
| | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) |
| Type | 50 in each station | 10 in each station | 0 | 2 in each station |
| Master station | M400 to M449 | D230 to D239 | — | D230, D231 |
| Slave station | M450 to M499 | D240 to D249 | — | D240, D241 |

1. Regular parallel link mode



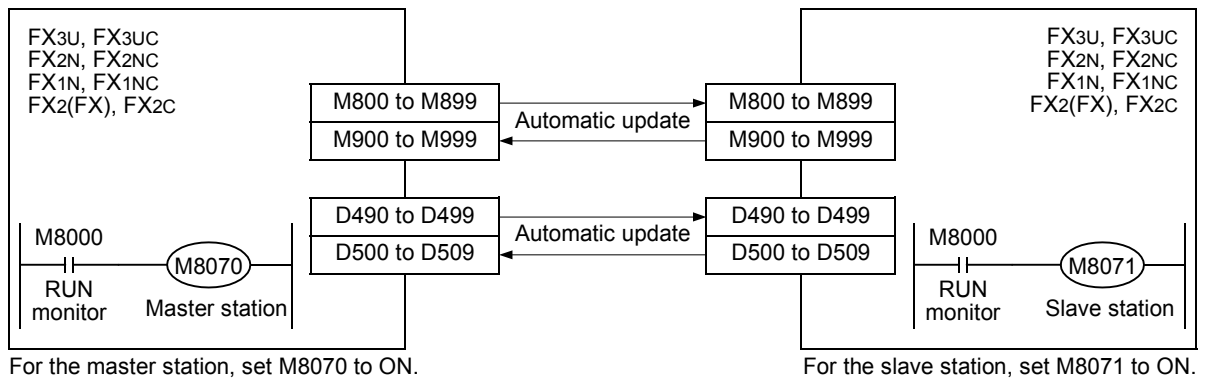
2. High speed parallel link mode



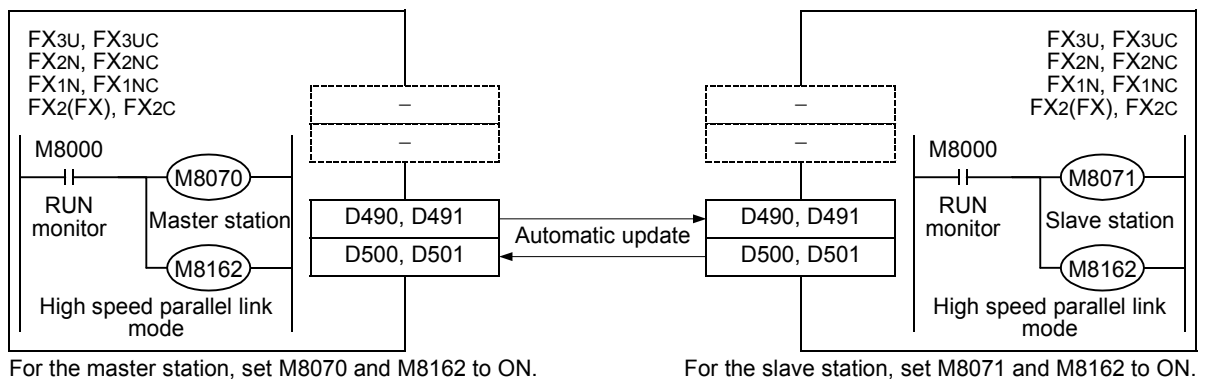
2.3.2 For FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC Series

| Mode | Regular parallel link mode | | High speed parallel link mode | |
|----------------|----------------------------|--------------------|-------------------------------|-------------------|
| | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) |
| Type | 100 in each station | 10 in each station | 0 | 2 in each station |
| Master station | M800 to M899 | D490 to D499 | — | D490, D491 |
| Slave station | M900 to M999 | D500 to D509 | — | D500, D501 |

1. Regular parallel link mode



2. High speed parallel link mode



3. System Configuration and Selection

This chapter explains the configuration of communication equipment operating in accordance with RS-485 and the system selection required by FX PLCs.

3.1 System Configuration

This section outlines the system configuration required to use the parallel link.
Add (optional) communication equipment operating in accordance with RS-485 to an FX PLC main unit.

3.1.1 Rule for connection

When using the parallel link, PLCs in the same group can be connected as shown in the table below.

| Group | PLC Series |
|-------|-------------------------|
| 1 | FX3U and FX3UC Series |
| 2 | FX2N and FX2NC Series |
| 3 | FX1N and FX1NC Series |
| 4 | FX1S Series |
| 5 | FX0N Series |
| 6 | FX2(FX) and FX2C Series |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

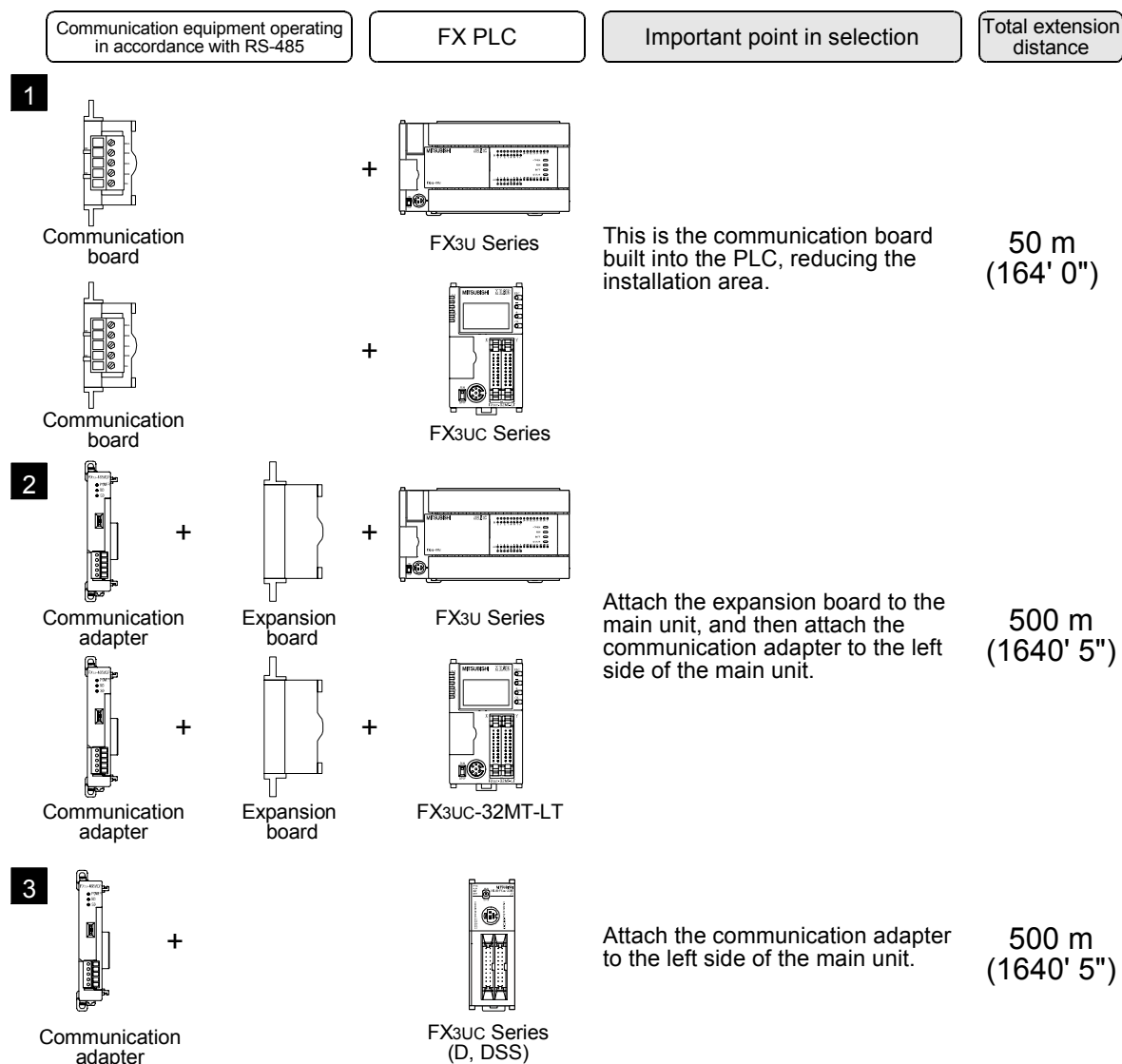
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Discontinued models

3.2 Configuration of Each Group

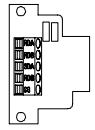
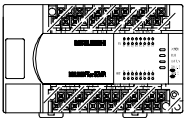
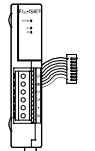
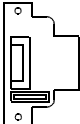
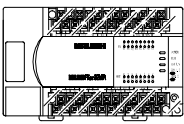
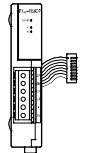
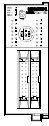

1, **2** and **3** indicate the communication equipment combination patterns.

1. Group 1 (FX3U and FX3UC Series)

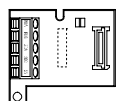

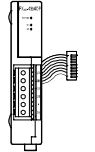
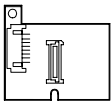

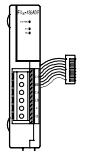
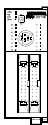



➡ For communication equipment combinations for each FX Series, refer to the next section.

2. Group 2 (FX2N and FX2NC Series)

| Communication equipment operating in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|---|--|---|---|
| 1  Communication board | +  FX2N Series | This is the communication board built into the PLC, reducing the installation area. | 50 m (164' 0") |
| 2  Communication adapter | +  Special adapter connection board | +  FX2N Series | Attach the special adapter connection board to the main unit, and then attach the communication adapter to the left side of the main unit. 500 m (1640' 5") |
| 3  Communication adapter | +  FX2NC Series | Attach the communication adapter to the left side of the main unit. | 500 m (1640' 5") |
|  For communication equipment combinations for each FX Series, refer to the next section. | | | |

3. Group 3 (FX1N and FX1NC Series)

| Communication equipment operating in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|---|--|---|---|
| 1  Communication board | +  FX1N Series | This is the communication board built into the PLC, reducing the installation area. | 50 m (164' 0") |
| 2  Communication adapter | +  Special adapter connection board | +  FX1N Series | Attach the special adapter connection board to the main unit, and then attach the communication adapter to the left side of the main unit. 500 m (1640' 5") |
| 3  Communication adapter | +  FX1NC Series | Attach the communication adapter to the left side of the main unit. | 500 m (1640' 5") |
|  For communication equipment combinations for each FX Series, refer to the next section. | | | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

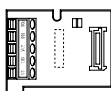

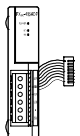
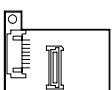


I

Remote Maintenance

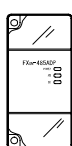
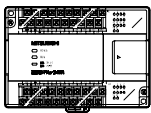

Apx.

Discontinued models


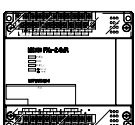

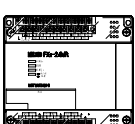

4. Group 4 (FX1S Series)

| Communication equipment operating in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|--|--|--|--------------------------|
| 1  Communication board |  FX1S Series | This is the communication board built into the PLC, reducing the installation area. | 50 m (164' 0") |
| 2  +  Communication adapter Special adapter connection board |  FX1S Series | Attach the special adapter connection board to the main unit, and then attach the communication adapter to the left side of the main unit. | 500 m (1640' 5") |
|  For communication equipment combinations for each FX Series, refer to the next section. | | | |

5. Group 5 (FX0N Series)

| Communication equipment operating in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|---|---|---|--------------------------|
| 1  Communication adapter |  FX0N Series | Attach the communication adapter to the left side of the main unit. | 500 m (1640' 5") |
|  For communication equipment combinations for each FX Series, refer to the next section. | | | |

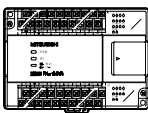
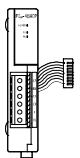
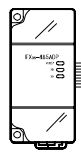

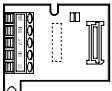
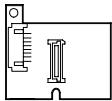
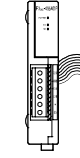
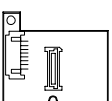
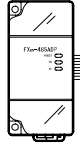
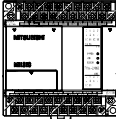
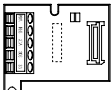
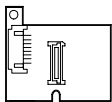
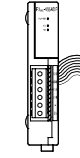
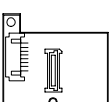
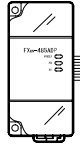
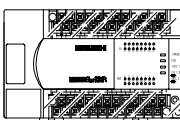
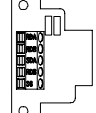
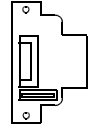
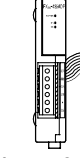
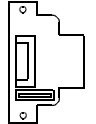

6. Group 6 (FX2(FX) and FX2c Series)

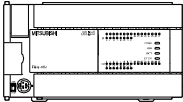
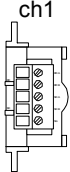
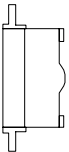
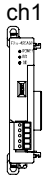

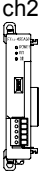
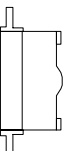
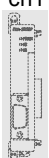
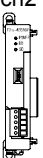
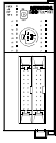
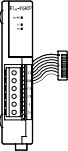
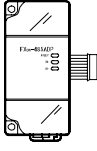
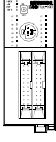
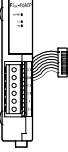
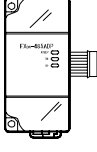
| Communication equipment using optical fiber or in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|---|--|--|--------------------------|
| 1  Communication adapter |  FX2(FX)/FX2c Series | Attach the communication adapter to the left side of the main unit. Perform wiring using optical fiber cables. | 50 m (164' 0") |
| 2  Communication adapter |  FX2(FX)/FX2c Series | Attach the communication adapter to the left side of the main unit. Perform wiring using twisted pair cables. | 10 m (32' 9") |
|  For communication equipment combinations for each FX Series, refer to the next section. | | | |

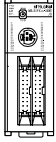
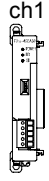


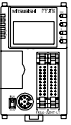
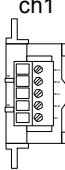
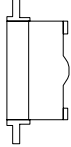
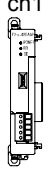

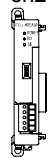
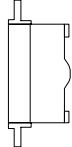

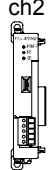
3.3 Applicable FX PLC and Communication Equipment

Select a (optional) communication equipment combination, and put a check mark in the "Check" column. During selection, pay attention to the following:

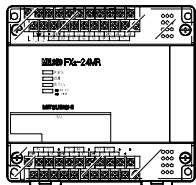

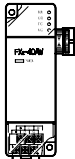
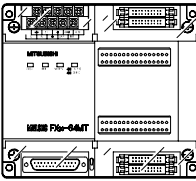


- In the table below, only the external dimensions are different between the units shown in "FX2NC-485ADP/FX0N-485ADP". Select either one.
- The parallel link is not provided for the FX0, FX0s and FX1 Series.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX0N |  /  FX2NC-485ADP (European terminal block) FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX1S |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP FX1N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX1N |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP FX1N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX2N |  FX2N-485-BD | 50 m (164' 0") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-485ADP FX2N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX1NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX2NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1) | | |
| |  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX3UC-32MT-LT | When using channel 1 (ch 1) | | |
| |  FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RSS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX2(FX) |  FX2-40AP (for optical fiber) | 50 m (164' 0") | |
| |  FX2-40AW (for wire link) | 10 m (32' 9") | |
|  FX2C |  FX2-40AP (for optical fiber) | 50 m (164' 0") | |
| |  FX2-40AW (for wire link) | 10 m (32' 9") | |

4. Wiring

This chapter explains the wiring.

WIRING PRECAUTIONS



- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to attach the terminal cover, offered as an accessory, before turning on the power or initiating operation after installation or wiring work. Failure to do so may cause electric shock.

WIRING PRECAUTIONS



- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to abnormal data written to the PLC under the influence of noise:
 - 1) Do not bundle the main circuit line together with or lay it close to the main circuit, high-voltage line or load line. Otherwise, noise disturbance and/or surge induction are likely to take place. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or high-voltage line.
 - 2) Ground the shield wire or shield of the shielded cable at one point on the PLC. However, do not use grounding with heavy electrical systems.
- Make sure to properly wire the FX0N/FX2N Series extension equipment in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should follow the specifications in this manual.
- Make sure to properly wire to the European terminal board in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should be follow the specifications in this manual.
 - Twist the end of strand wire and make sure that there are no loose wires.
 - Do not solder-plate the electric wire ends.
 - Do not connect more than the specified number of wires or electric wires of unspecified size.
 - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

4.1 Wiring Procedure

1 Preparing for wiring

Prepare cables and terminal resistors required for wiring.

→ For details, refer to Section 4.2.

2 Turning OFF the power to the PLC

Before starting any wiring work, make sure that the power to the PLC is OFF.

3 Connecting the power supply (FX0N-485ADP only)

Connect the power supply to the 24V DC power terminal.

4 Wiring communication equipment

Connect communication equipment operating in accordance with RS-485.

→ For details, refer to Section 4.3.

4.2 Selecting Cables and Terminal Resistors

Select cables using the procedure described below.

4.2.1 Twisted pair cable

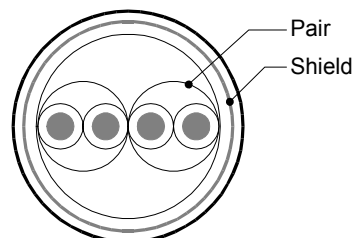
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows recommended model names and manufacturers of cables used for wiring.

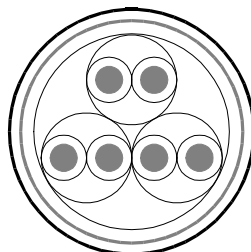
1. Recommended cables

| Manufacturer | Model name | Remarks |
|---------------------------------------|----------------------------------|---|
| Mitsubishi Cable Industries, Ltd. | SPEV(SB)-0.2-2P | Two-pair cable of 0.2 mm ² |
| | SPEV(SB)-MPC-0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | SPEV(SB)-0.5-2P | Two-pair cable of 0.5 mm ² |
| Showa Electric Wire & Cable Co., Ltd. | KMPEV-SB CWS-178 0.2SQ × 2P | Two-pair cable of 0.2 mm ² |
| | KMPEV-SB CWS-178 0.5SQ × 2P | Two-pair cable of 0.5 mm ² |
| Sumitomo Electric Industries, Ltd. | DPEV SB 0.3 × 3P | Three-pair cable of 0.3 mm ² |
| | DPEV SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| The Furukawa Electric Co., Ltd. | D-KPEV-SB 0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | D-KPEV-SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| Fujikura Ltd. | IPEV-SB 2P × 0.3 mm ² | Two-pair cable of 0.3 mm ² |
| | IPEV-SB 2P × 0.5 mm ² | Two-pair cable of 0.5 mm ² |

2. Cable structural drawing (reference)



Two-pair cable structural drawing example



Three-pair cable structural drawing example

4.2.2 Connecting cables

1. European type terminal block

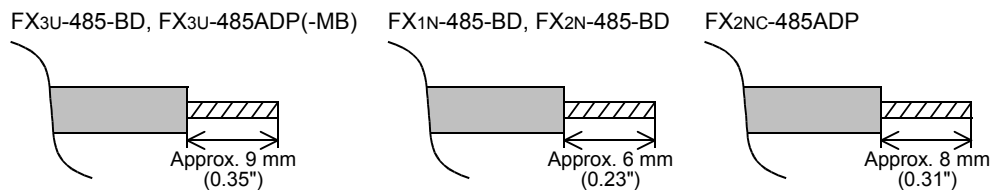
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows applicable cables and tightening torques.

| | Cable size when one cable is connected | Cable size when two cables are connected | Cable size for bar terminal with insulating sleeve | Tightening torque | Tool size | |
|----------------------------------|--|--|--|-------------------|-------------|-------------|
| | | | | | A | B |
| FX3U-485-BD FX3U-485ADP (-MB) | AWG22 to AWG20 | AWG22 | AWG22 to AWG20 | 0.22 to 0.25 N·m | 0.4 (0.01") | 2.5 (0.09") |
| FX2N-485-BD FX1N-485-BD | AWG26 to AWG16 | | — | 0.6 N·m | 0.6 (0.03") | 3.5 (0.14") |
| FX2NC-485ADP | AWG26 to AWG16 | AWG26 to AWG20 | — | 0.4 to 0.5 N·m | 0.6 (0.03") | 3.5 (0.14") |

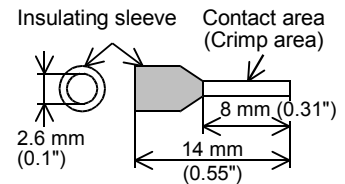
With regard to the cable end treatment, use a stranded cable or solid cable as it is, or use a bar terminal with insulating sleeve.

- When using a stranded cable or solid cable as it is
 - Twist the end of a stranded cable so that wires do not get barbed.
 - Do not plate the end of the cable.



- When using a bar terminal with insulating sleeve
Because it is difficult to insert a cable into an insulating sleeve depending on the thickness of the cable sheath, select the proper cable according to the outline drawing.

| Manufacturer | Model name | Caulking tool |
|-----------------|------------|----------------------------------|
| Phoenix Contact | AI 0.5-8WH | CRIMPFOX ZA 3 (or CRIMPFOX UD 6) |

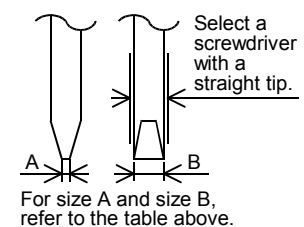


- Tool
 - When tightening a terminal on the European terminal block, use a small commercial straight shape screwdriver whose tip is shown in the figure to the right.

Note:

If the diameter of screwdriver grip is too small, tightening torque will not be able to be achieved. Use the following recommended screwdriver or an appropriate replacement (grip diameter: approximately 25mm).

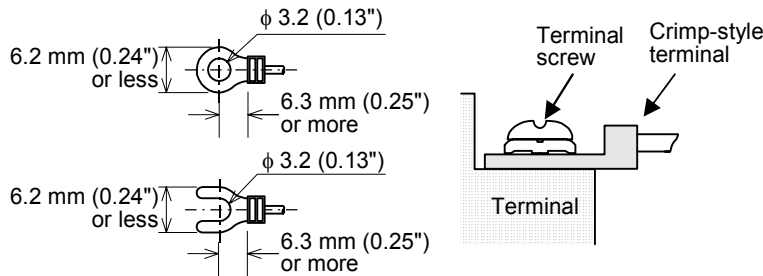
| Manufacturer | Model name |
|-----------------|---------------|
| Phoenix Contact | SZS 0.4 × 2.5 |



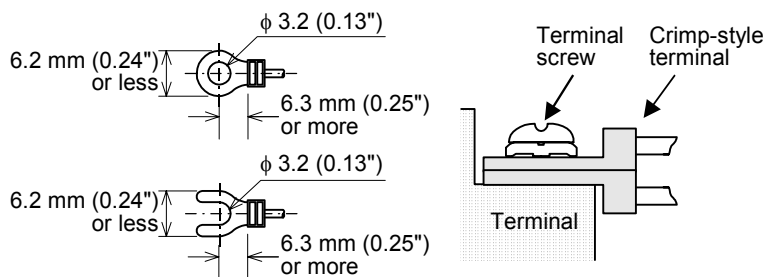
2. Terminal block

In the FX0N-485ADP and FX-485ADP, the terminal screw size is "M3".
Make sure to use a crimp-style terminal with the following sizes.
Make sure that the tightening torque is 0.5 to 0.8 N·m.

- When wiring one cable to one terminal



- When wiring two cables to one terminal



4.2.3 Optical fiber cable

Two optical fiber cables are required.

1. Cable types

| Cable | Length | Remarks |
|-----------|----------------|--|
| F-OFC-M10 | 10 m (32' 9") | Optical connector CA9104AP manufactured by Hitachi is already connected. |
| F-OFC-M30 | 30 m (98' 5") | Optical connector CA9104AP manufactured by Hitachi is already connected. |
| F-OFC-M50 | 50 m (164' 0") | Optical connector CA9104AP manufactured by Hitachi is already connected. |

2. Cautions on wiring

Separate the optical connector from strong electric cables as much as possible.
Connect devices with the smallest load to the output terminals Y000 to Y003 which are located near the optical connector.

4.2.4 Connecting terminal resistors

In the case of one-pair wiring, connect a terminal resistor to the RDA-RDB signal terminal of the communication equipment.

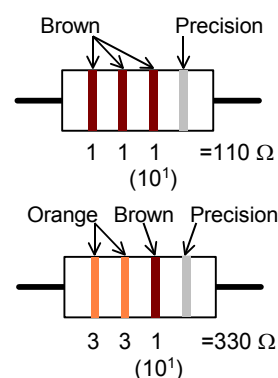
In the case of two-pair wiring, connect a terminal resistor to the RDA-RDB signal terminal and SDA-SDB terminal of the communication equipment.

1. Terminal resistor type

In the case of one-pair wiring, use two terminal resistors of $110\ \Omega$, $1/2\ \text{W}$.

In the case of two-pair wiring, use four terminal resistors of $330\ \Omega$, $1/4\ \text{W}$.

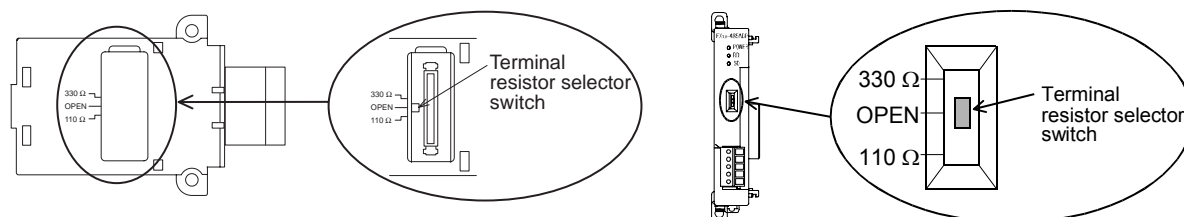
Among the terminal resistors supplied with the communication equipment, select ones with the color codes shown to the right.



2. When using the FX3U-485-BD or FX3U-485ADP(-MB)

The FX3U-485-BD and FX3U-485ADP have built-in terminal resistors.

Set the terminal resistor selector switch accordingly.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

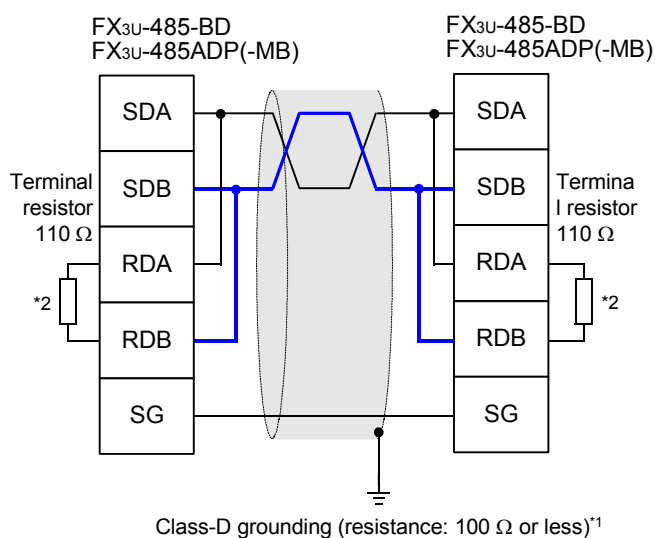
Apx.

Discontinued models

4.3 Connection Diagram

4.3.1 For FX3U and FX3UC PLCs

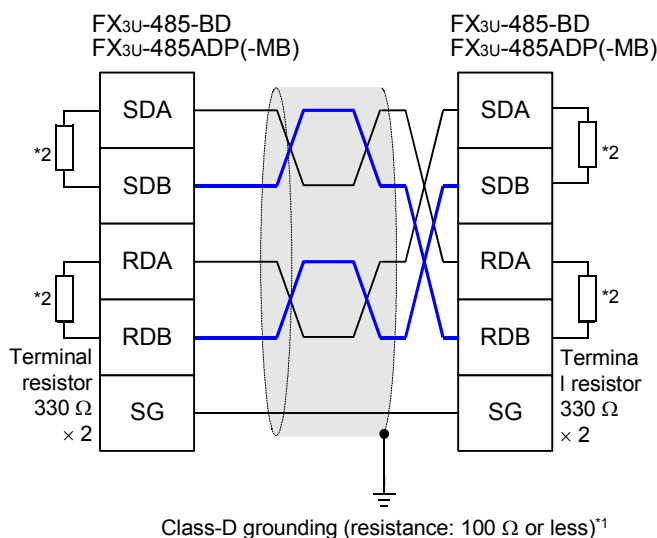
1. In the case of one-pair wiring



*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX3U-485-BD or FX3U-485ADP(-MB).

*2 The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor. Set the terminal resistor selector switch to 110 Ω .

2. In the case of two-pair wiring

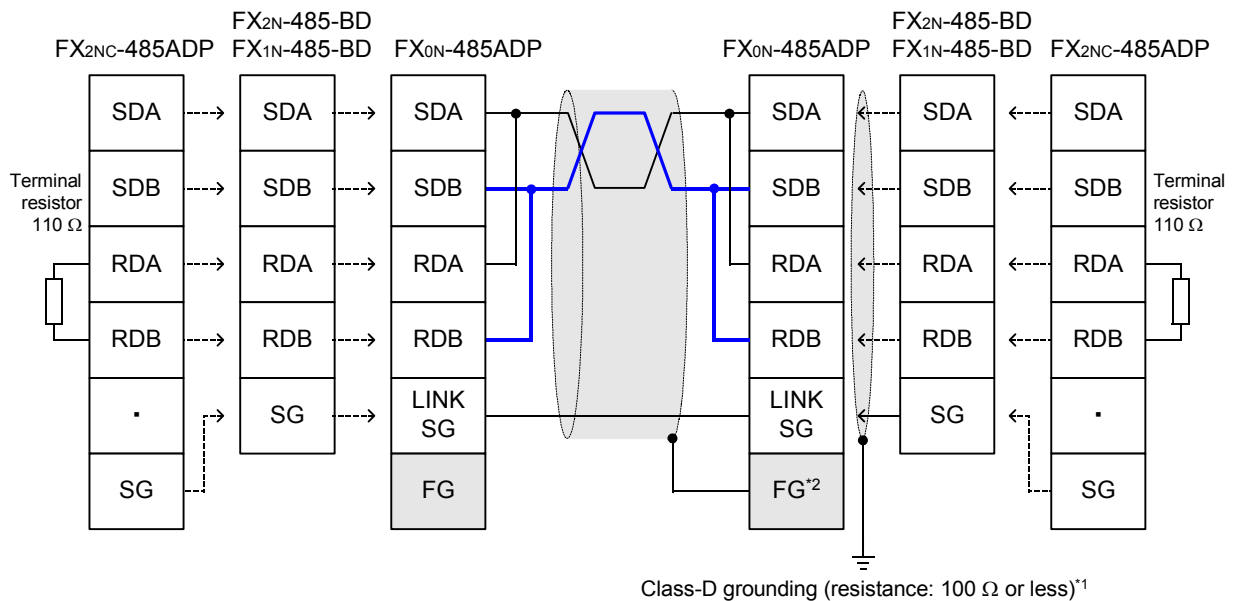


*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX3U-485-BD or FX3U-485ADP(-MB).

*2 The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor. Set the terminal resistor selector switch to 330 Ω .

4.3.2 For FX1S, FX1N, FX1NC, FX2N and FX2NC PLCs

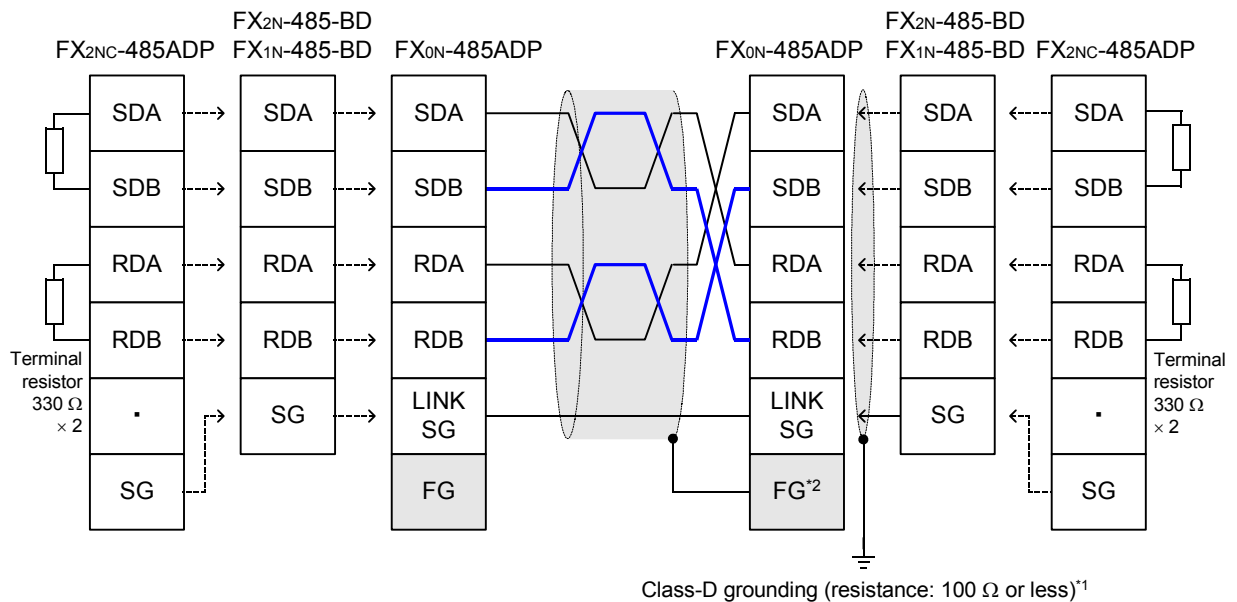
1. In the case of one-pair wiring



*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD or FX2NC-485-ADP.

*2 Make sure to connect the **FG** terminal to the **⏏** (grounding) terminal in the PLC requiring Class-D grounding. If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.

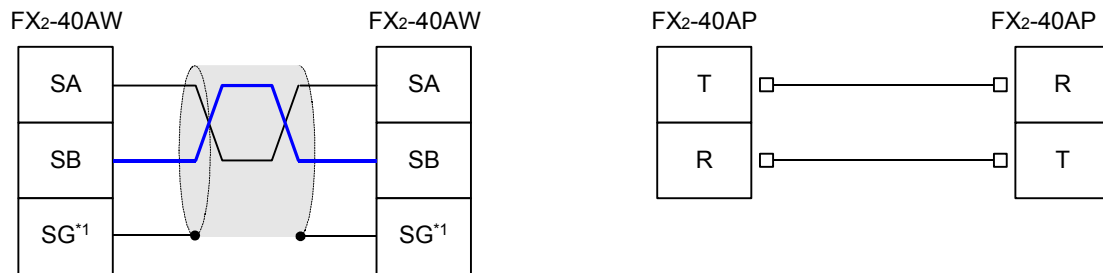
2. In the case of two-pair wiring



*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD or FX2NC-485-ADP.

*2 Make sure to connect the **FG** terminal to the **⏏** (grounding) terminal in the PLC requiring Class-D grounding. If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.

4.3.3 For FX2(FX) and FX2c PLCs



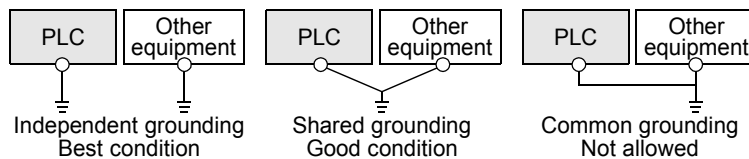
*1 Connect the **SG** terminal to the **SG** terminal in each PLC (main unit).

4.4 Grounding

Grounding should be performed as stated below.

- The grounding resistance should be 100Ω or less.
- Independent grounding should be performed for best results.
When independent grounding can not be performed, perform "shared grounding" as shown in the following figure.

→ For details, refer to the Hardware Edition of each series.



- The grounding wire size should be AWG 14 (2 mm^2) or larger.
- The grounding point should be close to the PLC, and all grounding wires should be as short as possible.

5. Communication Setting (Initialization) in FX Programmable Controller

The communication setting is not required in FX PLCs for parallel link.

If the communication setting is already provided for another communication type or for checking the existing communication setting, perform the following procedure.

When executing the parallel link in ch2 in an FX3U or FX3UC PLC, check D8420 using the following procedure.

5.1 Check Procedure

1 Monitoring D8120

Turn ON the power to the PLC while it is in STOP mode, and monitor D8120.

1. When the value of D8120 is "0"

The communication setting is not provided.

2. When the value of D8120 is any value other than "0"

The communication setting is provided.

2 Checking absence/presence of parameter setting

Check absence/presence using the GX Developer or FXGP/WIN.

- 1) GX Developer operating procedure (For details, refer to Section 5.2.)
- 2) FXGP/WIN operating procedure (For details, refer to Section 5.3.)

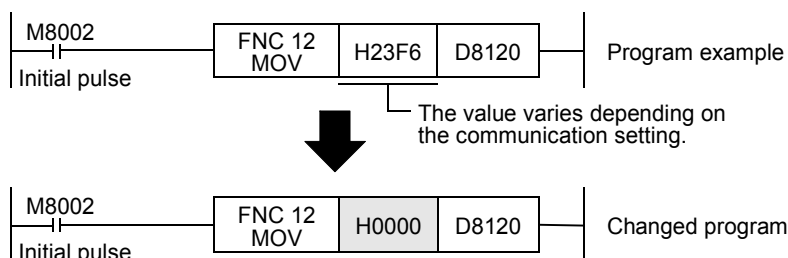
3 Checking absence/presence of sequence program setting

Check whether or not a write instruction is programmed for D8120.

1. When such an instruction is programmed

Program example:

Change the program as shown below, and then change the PLC mode from STOP to RUN.



2. When such an instruction is not programmed

Proceed to the next step.

4 Monitoring D8120 again, and confirming that its value is "0"

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

5.2 Communication Setting Using Parameter Method (GX Developer)

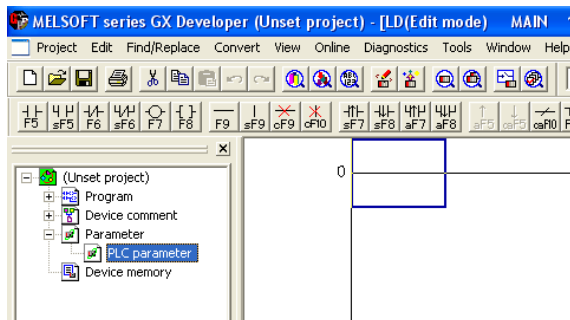
Communication settings may be changed using the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with GX Developer.

5.2.1 Operating procedure

With GX Developer open, follow the steps in this section to utilize the serial communication setting method.

1 Opening the parameter setting window

Double-click [Parameter]-[PLC parameter] from the project tree.



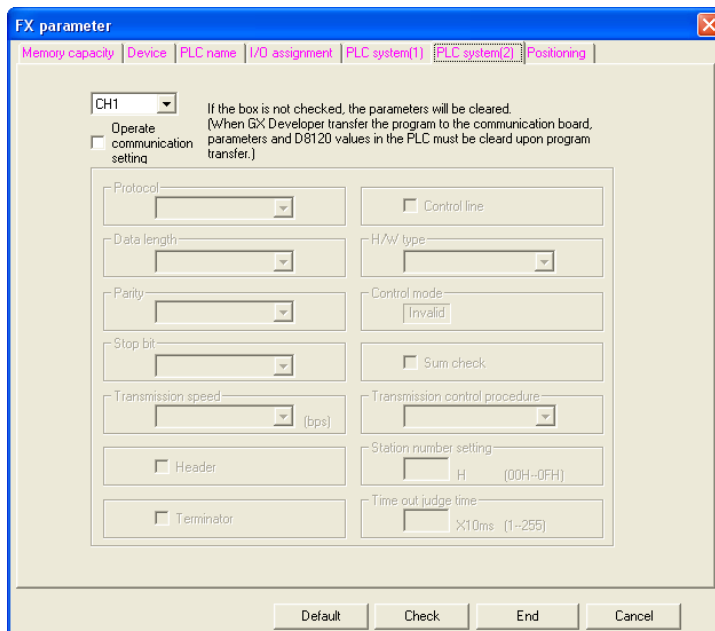
If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Setting the serial communication (parameters)

Click the [PLC system(2)] tab in the dialog box.

Select a channel to be used, and make sure that the "Operate communication setting" box is cleared.

If a check mark is there, clear it.



3 Writing parameters and program to the PLC

Select [Online] - [Write to PLC] from the toolbar, put a check mark (✓) in "Parameter" and "Program", and then click [Execute].

5.3 Communication Setting Using Parameter Method (FXGP/WIN)

Communication settings may be changed using the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with FXGP/WIN.
Ch2 cannot be set using FXGP/WIN.

5.3.1 Operating procedure

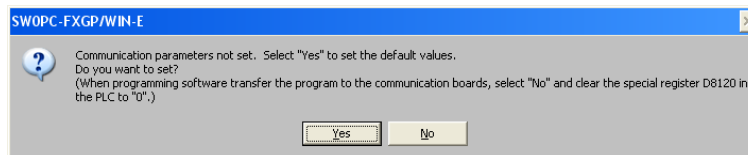
This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

1 Adjusting serial setting (parameter)

Double-click [Option] - [Serial setting (parameter)] from the toolbar.
The following dialog box appears according to absence/presence of parameter settings.

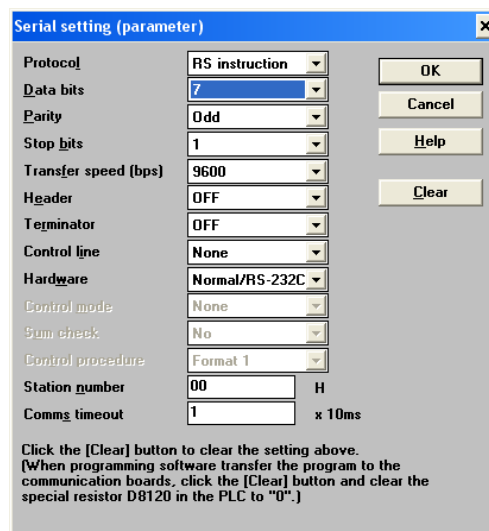
1. When there are no parameter settings

The dialog box shown below appears to indicate that there are no communication settings.
Click the [No] button.
In this case, the next step is not required.



2. When there are already parameter settings

The dialog box shown below appears to indicate that there are communication settings.
Click the [Clear] button to delete the communication settings from parameters.
Transfer parameters to the PLC using the following step.



2 Writing a sequence program (parameters) to the PLC

Select [PLC] - [Transfers] - [Write] from the toolbar, and click [OK].

6. Test Run (Communication Test)

This chapter explains the communication test procedures for the parallel link. It is recommended to wire the master station and slave station, initialize communication settings in the FX PLCs, and then execute the communication test using the following procedure to confirm the proper operation.

6.1 Test Procedure

1 Creating programs for the communication test

Create new programs for the communication test for the master station and slave station.

→ For program examples, refer to Section 6.2.

2 Transferring the program to each PLC

Turn ON the power to each PLC, and transfer the program.

3 Validating the communication setting

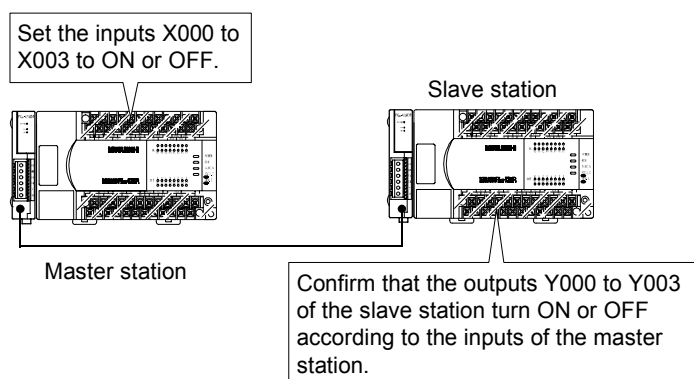
When the PLC is in RUN mode, set it to STOP mode once, and then set it to RUN mode again. Or turn OFF the power of the master station and slave station, and then turn ON the power to both stations at the same time.

4 Confirming flashing of the communication status indicator lamps (SD and RD)

Confirm that the built-in SD and RD lamps of the communication equipment are flashing. If they are off, take proper action while referring to the troubleshooting procedures described later.

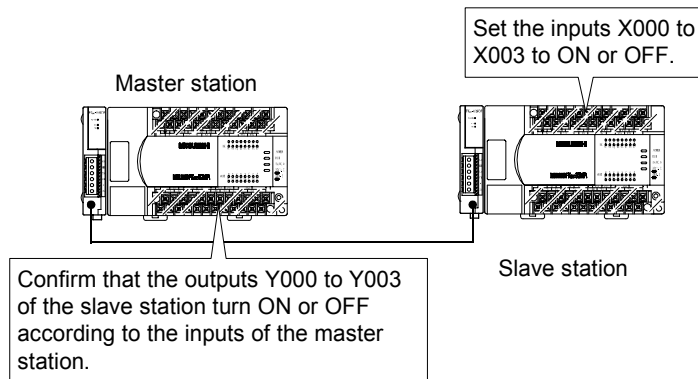
5 Confirming the link of the master station

Set the PLC inputs (X000 to X003) to ON or OFF in the master station, and confirm that the outputs (Y000 to Y003) turn ON or OFF in the slave station.



6 Confirming the link of the slave station

Set the PLC inputs (X000 to X003) to ON or OFF in the slave station, and confirm that the outputs (Y000 to Y003) turn ON or OFF in the master station.



→ If unable to establish link, refer to "9. Troubleshooting."

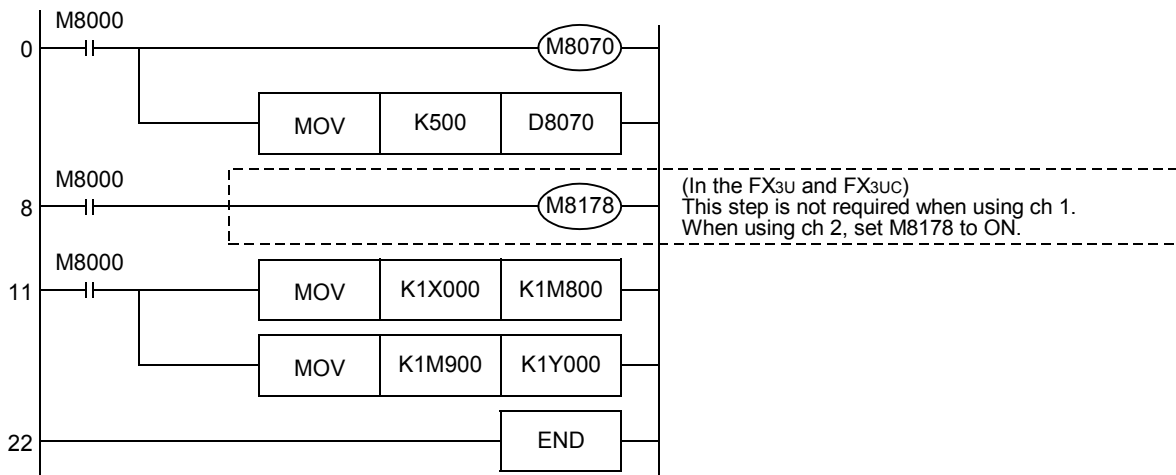
6.2 Creating Programs for the Communication Test

Create the programs shown below for the master station and slave station.

6.2.1 For FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC or FX3UC Series

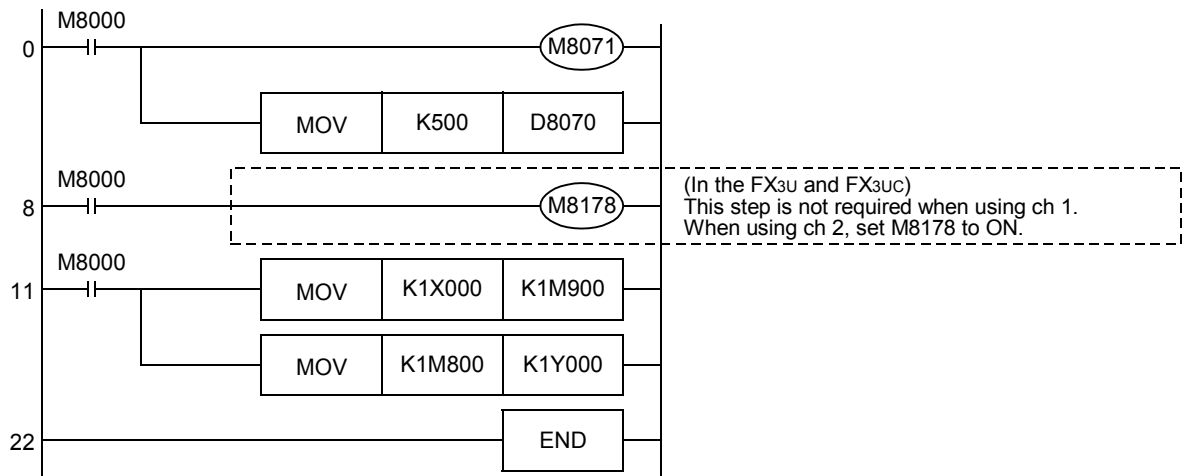
1. Program for communication test (for the master station)

Create the program shown below for the communication test. (This program is not required during actual operation.)



2. Program for communication test (for the slave station)

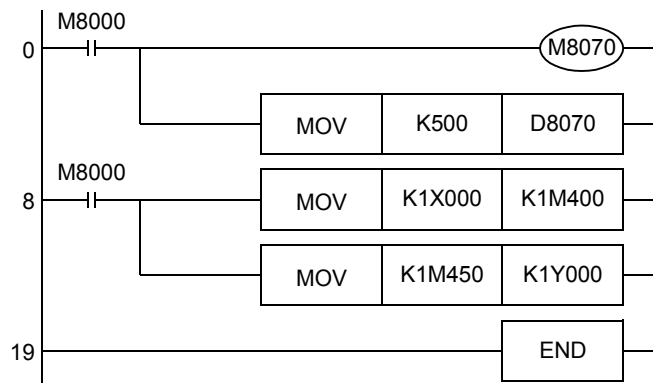
Create the program shown below for the communication test. (This program is not required during actual operation.)



6.2.2 For FX1s or FX0N Series

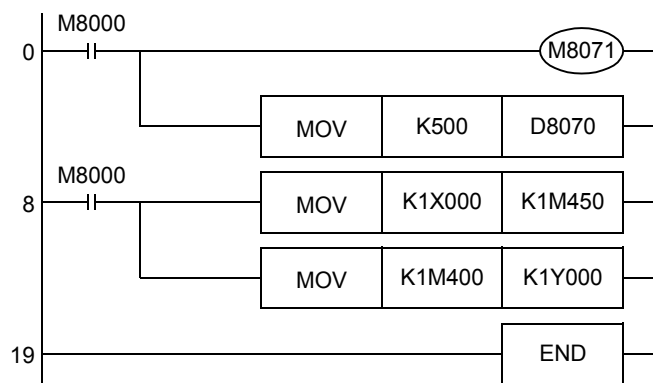
1. Master station communication test program

Create the program shown below for the communication test. (This program is not required during actual operation.)



2. Slave station communication test program

Create the program shown below for the communication test. (This program is not required during actual operation.)



7. Creating Programs

The parallel link has two modes, regular parallel link mode and high speed parallel link mode. Program settings and the number of device to be used are different in each mode. When connecting FX PLCs in the parallel link, use the same mode in both PLCs.

7.1 Regular Parallel Link Mode

This section explains the program setting method in the regular parallel link mode.

7.1.1 Checking contents of related devices

The tables below show devices used in the parallel link.

1. Devices for setting the parallel link

These devices are used for setting the parallel link. The setting of these devices is essential to use the parallel link.

| Device | Name | Description |
|--------|--------------------------------------|--|
| M8070 | Parallel link master station setting | Set this device to ON when linking a PLC as the master station. |
| M8071 | Parallel link slave station setting | Set this device to ON when linking a PLC as the slave station. |
| M8178 | Channel setting | Set the channel of communication port to be used (in the FX3U and FX3UC). When this device is OFF: ch1 When this device is ON: ch2 |
| D8070 | Error judgement time (ms) | Set the time for judging error in the parallel link data communication. [Initial value: 500] |

2. Devices for judging errors in the parallel link

These devices are used for judging errors in the parallel link. Use them to output link errors to the outside and interlock sequence programs.

| Device | Name | Description |
|--------|------------------------------------|--|
| M8072 | Parallel link ON | This device remains ON while the parallel link is executed. |
| M8073 | Master/slave station setting error | This device turns ON when there is an error in the setting of the master station or slave station. |
| M8063 | Link error | This device turns ON when a communication error occurs. |

3. Link devices

1) Sending devices for the master station

These devices are used for sending the information from the master station to the slave station.
To prevent malfunctions, do not change the setting of these devices in the slave station.

The device numbers used and number of devices vary depending on the PLC type. For applicable devices, refer to the tables below.

a) For FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC or FX3UC Series

| Device | | Number of devices | Description |
|-------------|--------------|-------------------|--|
| Bit device | M800 to M899 | 100 | The devices in the slave station are automatically updated to the status of devices in the master station. |
| Word device | D490 to D499 | 10 | |

b) For FX1S or FX0N Series

| Device | | Number of devices | Description |
|-------------|--------------|-------------------|--|
| Bit device | M400 to M449 | 50 | The devices in the slave station are automatically updated to the status of devices in the master station. |
| Word device | D230 to D239 | 10 | |

2) Sending devices for the slave station

These devices are used for sending the information from the slave station to the master station.
To prevent malfunctions, do not change the setting of these devices in the master station.

The device numbers used and number of devices vary depending on the PLC type. For applicable devices, refer to the tables below.

a) For FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC or FX3UC Series

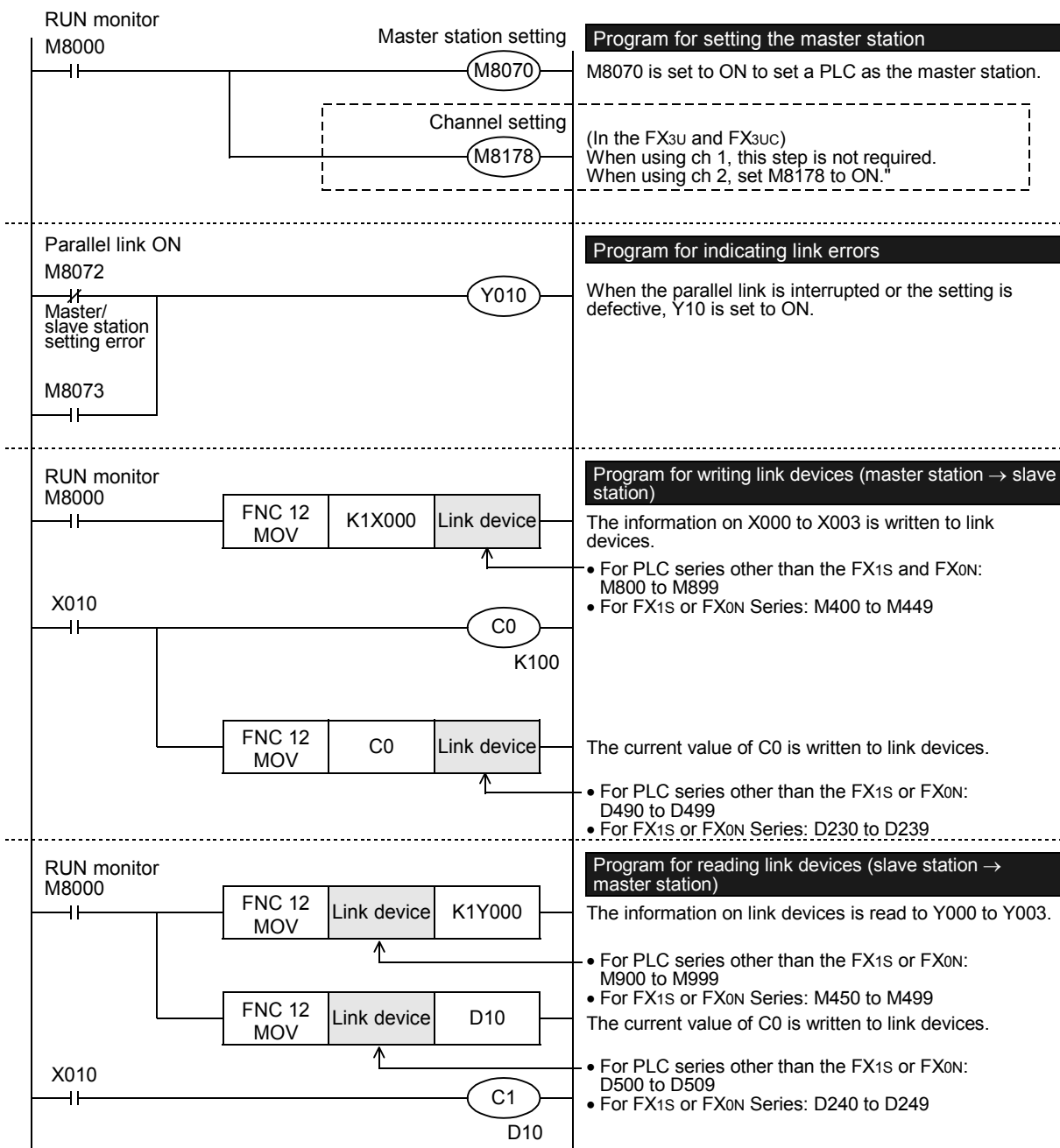
| Device | | Number of devices | Description |
|-------------|--------------|-------------------|--|
| Bit device | M900 to M999 | 100 | The devices in the master station are automatically updated to the status of devices in the slave station. |
| Word device | D500 to D509 | 10 | |

b) For FX1S or FX0N Series

| Device | | Number of devices | Description |
|-------------|--------------|-------------------|--|
| Bit device | M450 to M499 | 50 | The devices in the master station are automatically updated to the status of devices in the slave station. |
| Word device | D240 to D249 | 10 | |

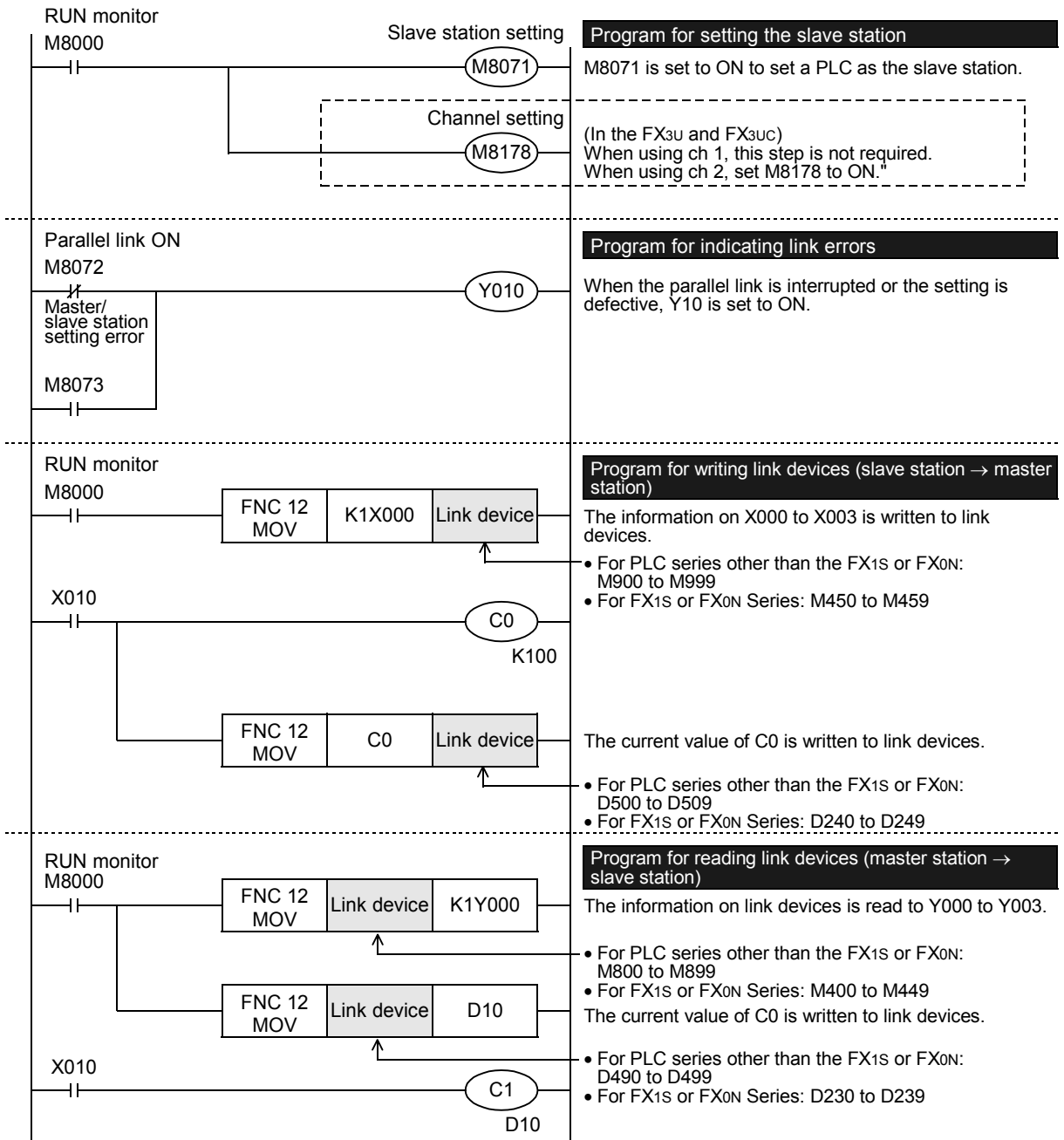
7.1.2 Creating programs for master station

Create programs for the master station.



7.1.3 Creating programs for slave station

Create programs for the slave station.



7.2 High Speed Parallel Link Mode

This section explains the program setting method in the high speed parallel link mode.

7.2.1 Checking contents of related devices

The tables below show devices used in the parallel link.

1. Devices for setting the parallel link

These devices are used for setting the parallel link. Setting of these devices is essential in using the parallel link.

| Device | Name | Description |
|--------|--------------------------------------|--|
| M8070 | Parallel link master station declare | Set this device to ON when linking a PLC as the master station. |
| M8071 | Parallel link slave station declare | Set this device to ON when linking a PLC as the slave station. |
| M8162 | High speed parallel link mode | Set this device to ON when using the high speed parallel link mode. |
| M8178 | Channel setting | Set the channel of communication port to be used (in the FX3U and FX3UC). When this device is OFF: ch1 When this device is ON: ch2 |
| D8070 | Error judgement time (ms) | Set the time for judging error in the parallel link data communication. [Initial value: 500] |

2. Devices for judging errors in the parallel link

These devices are used for judging errors in the parallel link. Use them to output link errors to the outside and interlock sequence programs.

| Device | Name | Description |
|--------|------------------------------------|--|
| M8072 | Parallel link ON | This device remains ON while the parallel link is executed. |
| M8073 | Master/slave station setting error | This device turns ON when there is an error in the setting of the master station or slave station. |
| M8063 | Link error | This device turns ON when a communication error occurs. |

3. Link devices

1) Sending devices for the master station

These devices are used for sending the information from the master station to the slave station.

To prevent malfunctions, do not change the setting of these devices in the slave station.

The device numbers used and number of devices vary depending on the PLC type. For applicable devices, refer to the tables below.

a) For FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC or FX3UC Series

| Device | Number of devices | Description |
|---------------------------|-------------------|--|
| Word device D490, D491 | 2 | The devices in the slave station are automatically updated to the status of devices in the master station. |

b) For FX1S or FX0N Series

| Device | Number of devices | Description |
|---------------------------|-------------------|--|
| Word device D230, D231 | 2 | The devices in the slave station are automatically updated to the status of devices in the master station. |

2) Sending devices for the slave station

These devices are used for sending the information from the slave station to the master station.

To prevent malfunctions, do not change the setting of these devices in the master station.

The device numbers used and number of devices vary depending on the PLC type. For applicable devices, refer to the tables below.

a) For FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC or FX3UC Series

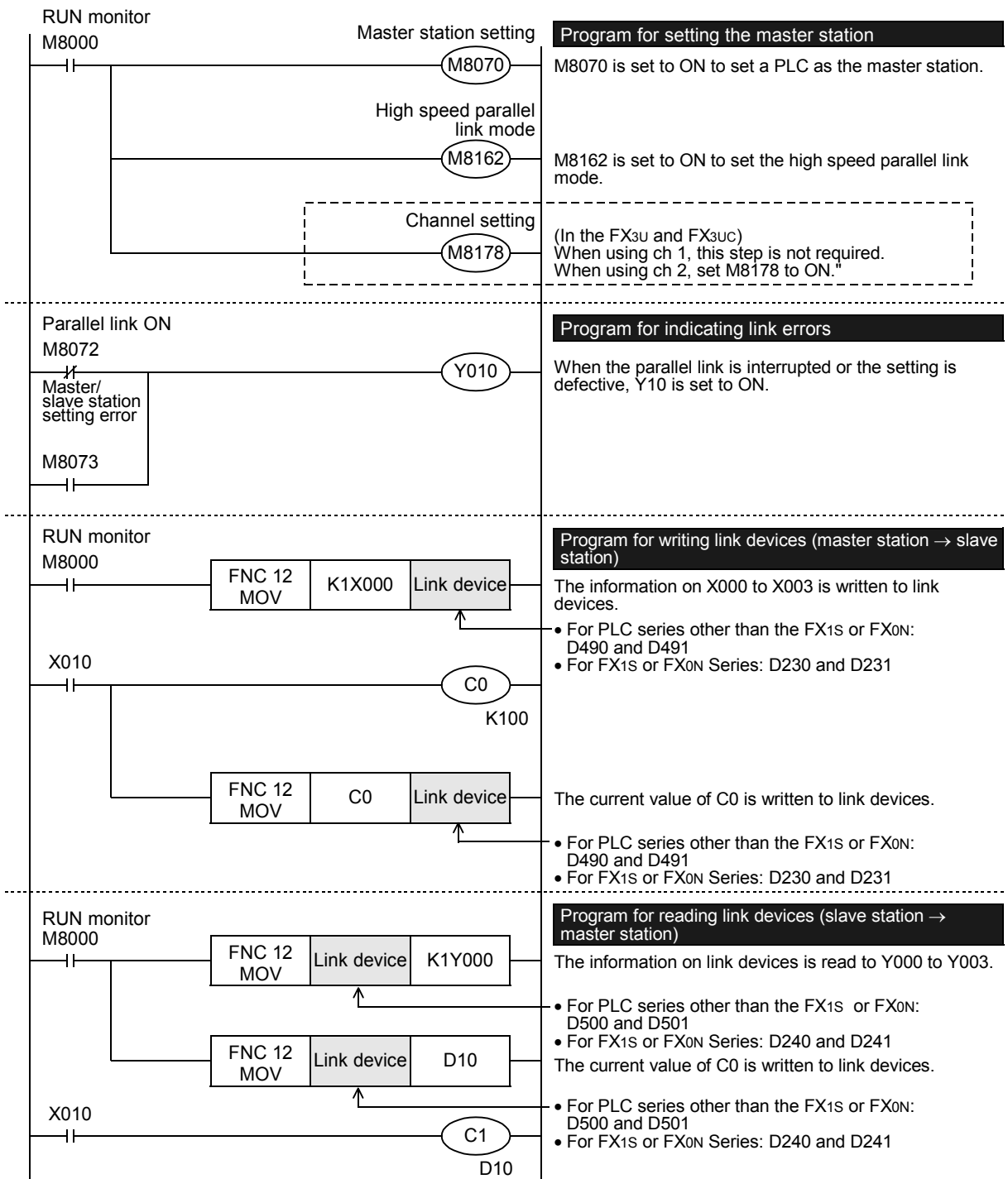
| Device | | Number of devices | Description |
|-------------|------------|-------------------|--|
| Word device | D500, D501 | 2 | The devices in the master station are automatically updated to the status of devices in the slave station. |

b) For FX1S or FX0N Series

| Device | | Number of devices | Description |
|-------------|------------|-------------------|--|
| Word device | D240, D241 | 2 | The devices in the master station are automatically updated to the status of devices in the slave station. |

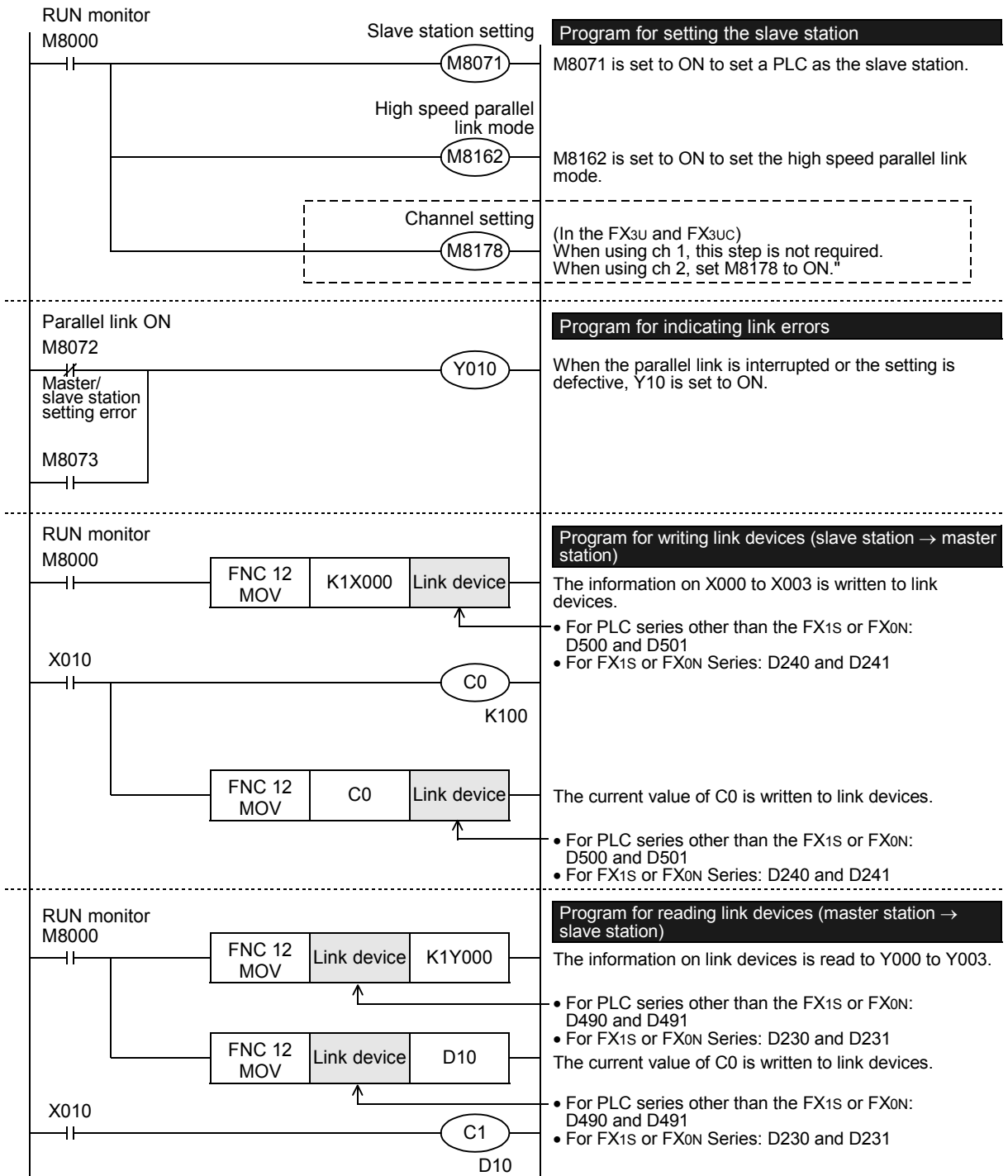
7.2.2 Creating programs for master station

Create programs for the master station.



7.2.3 Creating programs for slave station

Create programs for the slave station.



7.3 Cautions on Program Creation

1. Program for reading link devices

- 1) Do not change the contents of link devices for the other station.
- 2) When a link error occurs, the link device information remains the same as the status just before the error. Create a fail-safe program which does not cause abnormality even if a link error occurs.

2. Cautions on using FX3U/FX3UC PLCs

- 1) Only ch1 or ch2 can be set in the parallel link.
- 2) Do not use the N:N Network and the parallel link at the same time.
(For example, it is not allowed to use ch1 for the N:N Network and simultaneously use ch2 for the parallel link.)

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

8. Practical Program Examples

This chapter shows practical programs examples.

8.1 Practical Example 1 (Regular Parallel Link Mode)

When many link devices are required, use the regular parallel link mode.

8.1.1 System configuration example

The example below shows a system configuration in which two FX2N PLCs are linked.



- Link range: 100-bit devices and 10-word devices (regular parallel link mode)
- Error judgement time: 500 ms

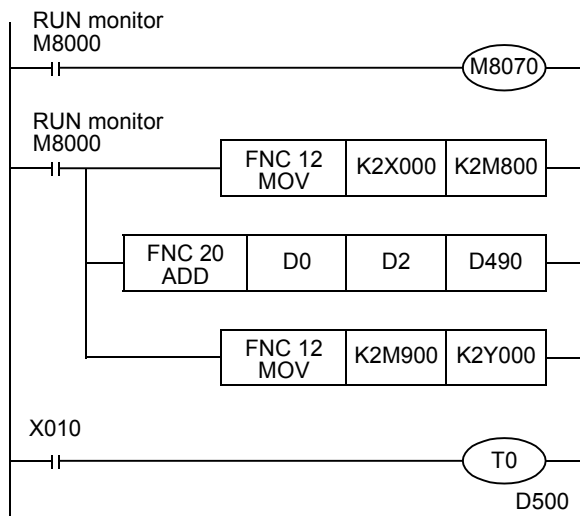
8.1.2 Setting contents

The program examples shown later adopt the following communication parameters:

| Device | Description |
|--------|--------------------------------------|
| M8070 | Parallel link master station setting |
| M8071 | Parallel link slave station setting |
| D8070 | Communication error judgement time |

8.1.3 Program for master station

For the master station, refer to the program shown below.



The ON/OFF status of inputs X000 to X007 in the master station is output to Y000 to Y007 in the slave station.

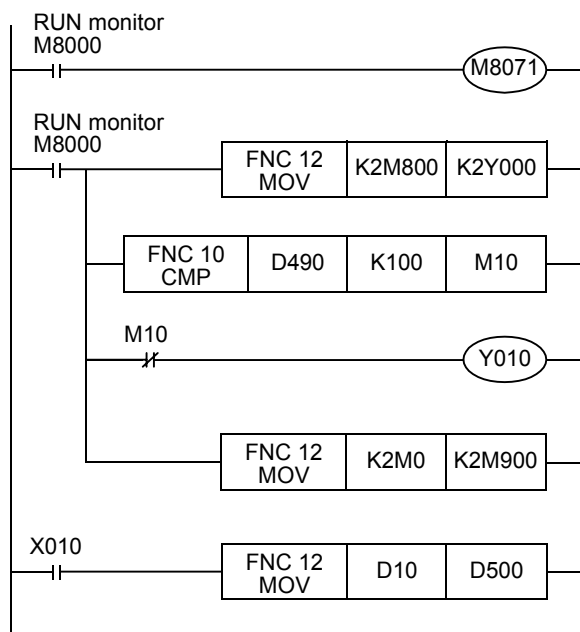
When the calculation result ($D0 + D2$) in the master station is moved to D490 of the slave station.

The ON/OFF status of M0 to M7 in the slave station is output to Y000 to Y007 in the master station.

The value of D10 in the slave station is stored to the timer setting (T0) in the master station.

8.1.4 Program for slave station

For the slave station, refer to the program shown below.



The ON/OFF status of inputs X000 to X007 in the master station is output to Y000 to Y007 in the slave station.

When the calculation result ($D0 + D2$) in the master station is 100 or less, Y010 is set to ON in the slave station.

The ON/OFF status of M0 to M7 in the slave station is output to Y000 to Y007 in the master station.

The value of D10 in the slave station stored to the timer setting (T0) in the master station.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9. Troubleshooting

This chapter explains troubleshooting.

9.1 Checking FX PLC Version Applicability

Verify that the FX PLC main unit is an applicable version.

→ For the version applicability check, refer to Section 1.3.

9.2 Checking Communication Status Based on LED Indication

Check the status of the "RD" and "SD" indicator LEDs provided in the optional equipment.

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RD | SD | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received. |
| Off | Off | Data is not sent or received. |

While the parallel link is executed normally, both LEDs flash brightly.

If they do not flash, check the wiring and the communication setting in the master and slave stations.

9.3 Checking Installation and Wiring

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ For the mounting method, refer to the respective communication equipment manual.

2. Power supply (for FX0N-485ADP)

The FX0N-485ADP requires a driving power supply. Verify that the power supply is correctly provided.

3. Wiring

Verify that the wiring to all communication equipment is correct. If the communication equipment is wired incorrectly, communication is not possible.

→ For wiring method check, refer to Chapter 4.

9.4 Checking Sequence Program

1. Communication setting in the sequence program

Verify that N:N Network (D8173 to D8180) is not set. Using both the parallel link and N:N Network at the same time is not allowed.

Verify that the communication format (D8120 and D8420) is set correctly. Communication is not possible if a communication port is set twice or more.

After changing any setting, make sure to cycle power to the PLC.

→ For communication setting, refer to Chapter 5.

2. Communication setting using parameters

Verify that the communication settings using parameters are suitable for use. If the communication settings are not suitable for the purpose of use, communication will not function correctly.

After changing any setting, make sure to reboot the PLC's power.

→ For communication setting, refer to Chapter 5.

3. Presence of VRRD and VRSC instructions (except FX3U and FX3UC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program.
If these instructions are used, delete them, reboot the PLC's power.

4. Presence of RS instruction (except FX3U and FX3UC PLCs)

Verify that the RS instruction is not used in the program.
If this instruction is used, delete it, reboot the PLC's power.

5. Presence of RS/RS2 instruction (in FX3U and FX3UC PLCs)

Verify that the RS and RS2 instructions are not being used for the same channel.
If these instructions are used for the same channel, delete them, reboot the PLC's power.

6. Presence of EXTR instruction (in FX2N and FX2NC PLCs)

Verify that the EXTR instruction is not used in the program.
If this instruction is used, delete it, then reboot the PLC's power.

7. Presence of IVCK, IVDR, IVRD, IVWR, and IVBWR instructions (in FX3U and FX3UC PLCs)

Verify that the IVCK, IVDR, IVRD, IVWR and IVBWR instructions are not being used for the same channel.
If these instructions are used for the same channel, delete them, reboot the PLC's power.

9.5 Checking Absence/Presence of Errors

Verify that errors have not occurred in the master station and slave station. Errors can be checked using the flags shown below.

1. Checking the device M8072

While the parallel link is established, M8072 remains ON.
If M8072 is OFF, an error has occurred in the parallel link setting or communication.

2. Checking the device M8073

If the parallel link is not set correctly, M8073 turns ON.
If M8073 is ON, verify that the master station and slave station are set correctly in sequence programs.

3. Devices for checking link errors

- 1) Checking the error flags M8063 and M8438 (in the FX3U and FX3UC)
If a communication error occurs in the parallel link, the serial communication error flag turns ON.
When ch1 is used, M8063 turns ON. When ch2 is used in the FX3U and FX3UC, M8438 turns ON.
When the serial communication error flag turns ON, the error code is stored in D8063 or D8438.
- 2) Checking the error code
When a communication error occurs in parallel link using ch 1, the error code is stored in D8063.
When a communication error occurs in parallel link using ch 2, the error code is stored in D8438.
The table below shows the details of error codes.

| Device | Error code | Description | Action |
|------------------------------|------------|----------------------------------|--|
| D8063 | 0000 | No error | Verify that the parallel link setting programs are set correctly. Check the wiring also. |
| | 6312 | Character error in parallel link | |
| | 6313 | Sum check error in parallel link | |
| | 6314 | Format error in parallel link | |
| D8438 (in FX3U and FX3UC) | 0000 | No error | |
| | 3812 | Character error in parallel link | |
| | 3813 | Sum check error in parallel link | |
| | 3814 | Format error in parallel link | |

Caution

The devices for checking link errors are not cleared even after communication errors are reset.
They are cleared when the PLC mode is changed from STOP to RUN.

10. Related Data

10.1 Related Device List

1. Bit devices

| Device number | Name | Description | Initial value | Detection | R/W |
|--|--------------------------------------|--|---------------|-----------|-----|
| Devices for communication setting | | | | | |
| M8070 | Parallel link master station setting | Links a PLC as the master station when it turns ON. | – | M | W |
| M8071 | Parallel link slave station setting | Links a PLC as the slave station when it turns ON. | – | L | W |
| M8162 | High speed parallel link mode | Turns ON when two-word device communication mode is selected. | – | M, L | W |
| M8178 | Channel setting | Sets the communication port to be used (in the FX3U and FX3UC). OFF: ch1, ON: ch2 | – | M, L | W |
| Devices for checking communication status | | | | | |
| M8072 | Parallel link ON | Remains ON while the parallel link is being executed. | – | M, L | R |
| M8073 | Parallel link setting error | Turns ON when an error is included in the setting contents of the master station or slave station. | – | M, L | R |
| M8063 | Serial communication error 1 (ch 1) | Turns ON when an error occurs in serial communication using ch 1. | – | M, L | R |
| M8438 | Serial communication error 2 (ch 2) | Turns ON when an error occurs in serial communication using ch 2 (in the FX3U and FX3UC). | – | M, L | R |

R: Read only (used as a contact in program)

W: Write only

M: Master station

L: Slave station

2. Word devices (data registers)

| Device number | Name | Description | Initial value | Detection | R/W |
|--|--|--|---------------|-----------|-----|
| Devices for communication setting | | | | | |
| D8070 | Error judgement time | Sets the error judgement time for data communication in the parallel link. | 500 | M, L | W |
| Devices for checking communication status | | | | | |
| D8063 | Serial communication error code (ch 1) | Stores the error code when an error occurs in serial communication using ch 1. | 0000 | M, L | R |
| D8438 | Serial communication error code (ch 2) | Stores the error code when an error occurs in serial communication using ch 2 (in the FX3U and FX3UC). | 0000 | M, L | R |

R: Read only (used as a contact in program)

W: Write only

M: Master station

L: Slave station

10.2 Details of Related Devices

The devices described below are used in parallel link.

10.2.1 Parallel link master station declare [M8070]

When this device is set to ON, the PLC is handled as the master station in the parallel link.

1. Applicable stations

The master station requires program setting.

2. Detailed contents

In the FX PLC to be handled as the master station, set M8070 to "normally ON" using M8000.

3. Cautions on use

Set this device to ON in a sequence program.

10.2.2 Channel setting [M8178]

This device works as the channel setting flag (in the FX3U and FX3UC).

1. Applicable stations

The master and slave station require program setting.

2. Detailed contents

When using ch 2 as the communication port, set this device to ON in the sequence program.
When using ch 1, the sequence program is not required.

10.2.3 Parallel link slave station declare [M8071]

When this device is set to ON, the PLC is handled as the slave station in the started communication.

1. Applicable stations

The slave station requires program setting.

2. Detailed contents

In the FX PLC to be handled as a slave station, set M8071 to "normally ON" using M8000.

3. Cautions on use

Set this device to ON using a sequence program.

10.2.4 High speed parallel link mode [M8162]

When M8162 turns OFF, the regular parallel link mode is selected. When M8162 turns ON, the high speed parallel link mode is selected.

1. Applicable stations

The master and slave station require program setting.

2. Detailed contents

The table below shows the number of link devices.

| PLC | Regular parallel link mode | | High speed parallel link mode | |
|--|----------------------------|--------------------|-------------------------------|-------------------|
| | Bit device (M) | Word device (D) | Bit device (M) | Word device (D) |
| FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | 100 in each station | 10 in each station | 0 | 2 in each station |
| FX1S, FX0N | 50 in each station | 10 in each station | 0 | 2 in each station |

3. Cautions on use

Set this device to ON using a sequence program.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

10.2.5 Parallel link ON [M8072]

This device is provided to verify that the parallel link is being executed.

1. Applicable stations

The master and slave station may check parallel link status.

2. Detailed contents

M8072 remains ON while the parallel link is being executed normally, and remains OFF while the parallel link is not being executed normally.

10.2.6 Parallel link setting error [M8073]

This device is provided to verify that the setting is correct in the master station and slave station in the parallel link.

1. Applicable stations

The master and slave station may check parallel link status.

2. Detailed contents

M8073 remains OFF when the setting is correct in the master station or slave station, and turns ON when the setting is incorrect.

10.2.7 Serial communication error [M8063 and M8438]

These devices are provided to check communication errors. (M8438 is available only in the FX3U and FX3UC.)

1. Applicable stations

The master and slave station may check parallel link status.

2. Detailed contents

M8063 turns ON when an error occurs using parallel link on ch 1. When M8063 turns ON, the error code is stored in D8063.

M8438 turns ON when an error occurs using parallel link on ch 2. When M8438 turns ON, the error code is stored in D8438.

3. Cautions on use

These devices do not turn OFF even after the communication error is reset. They turn OFF when the PLC mode is changed from STOP to RUN.

10.2.8 Error judgement time setting [D8070]

This device is provided to set the error judgment time (initial value: 500 ms).

1. Applicable stations

The master and slave station may check parallel link status.

2. Detailed contents

When data transmission requires more time than the time set here, it is regarded as error.

10.2.9 Serial communication error code [D8063 and D8438]

These devices store the serial communication error code. (D8438 is available only in the FX3U and FX3UC.)

1. Applicable stations

The master and slave station may check the serial communication error code.

2. Detailed contents

The table below shows the details of error codes.

| Device | Error code | Description | Action |
|-----------------|------------|----------------------------------|--|
| D8063 (ch 1) | 0000 | No error | Verify that the parallel link setting programs are correct, and check the wiring also. |
| | 6312 | Character error in parallel link | |
| | 6313 | Sum check error in parallel link | |
| | 6314 | Format error in parallel link | |
| D8438 (ch 2) | 0000 | No error | |
| | 3812 | Character error in parallel link | |
| | 3813 | Sum check error in parallel link | |
| | 3814 | Format error in parallel link | |

3. Cautions on use

The error code is not cleared after the communication error is reset.
It is only cleared when the PLC mode is changed from STOP to RUN.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

MEMO

FX Series Programmable Controllers

User's Manual [Computer Link]

Foreword

This manual explains "computer link" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit.
Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

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Remote Maintenance

Apx.
Discontinued models

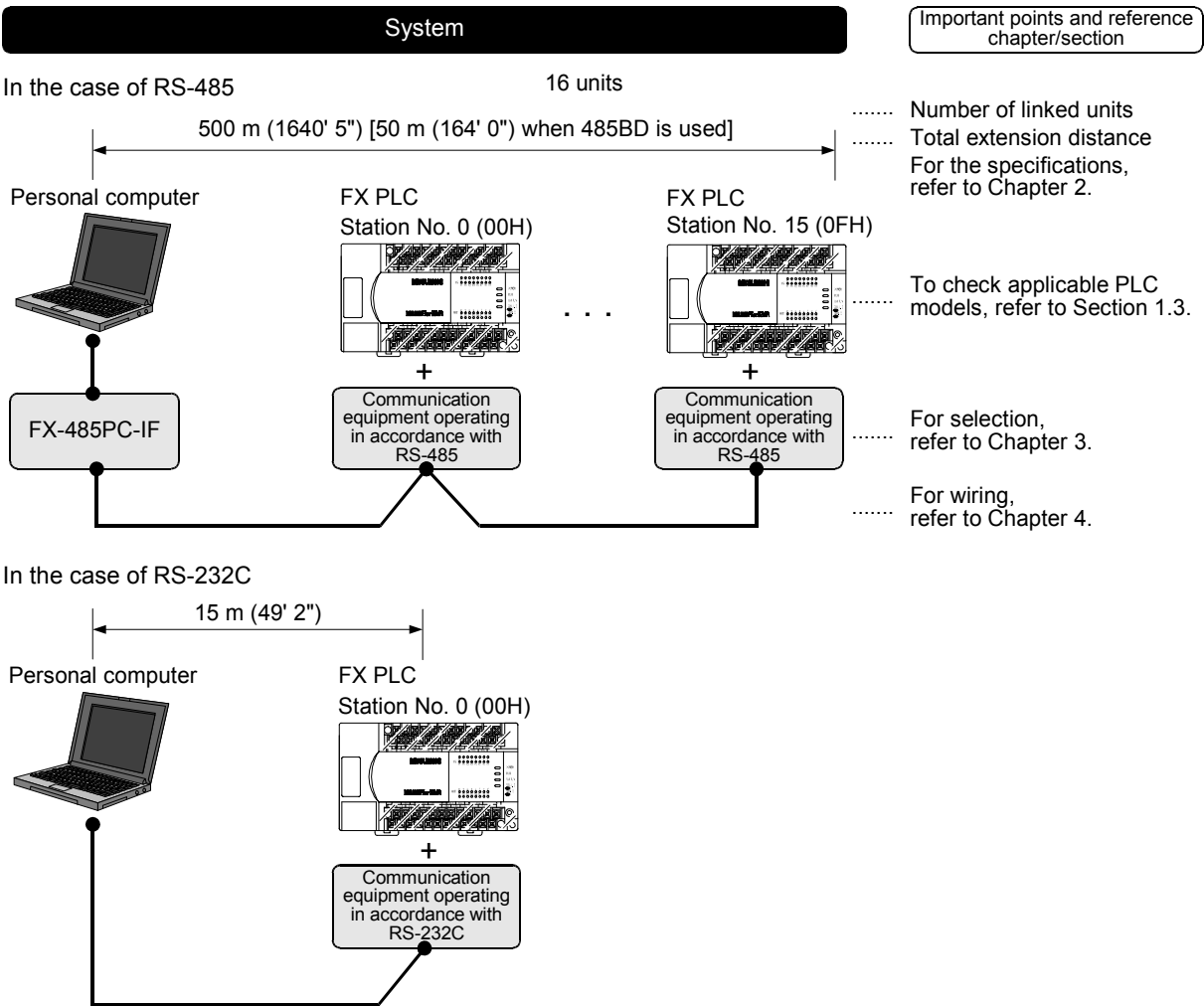
1. Outline

This chapter explains computer link.

1.1 Outline of System

Computer link allows connection of up to sixteen FX PLCs and A PLCs to a personal computer working as the master station to link data.

- 1) Up to sixteen PLCs can be connected in computer link.
- 2) Applicable computer link protocols are the same as dedicated supported computer link protocols units in the A Series PLC. (But the supported formats and commands are limited.)

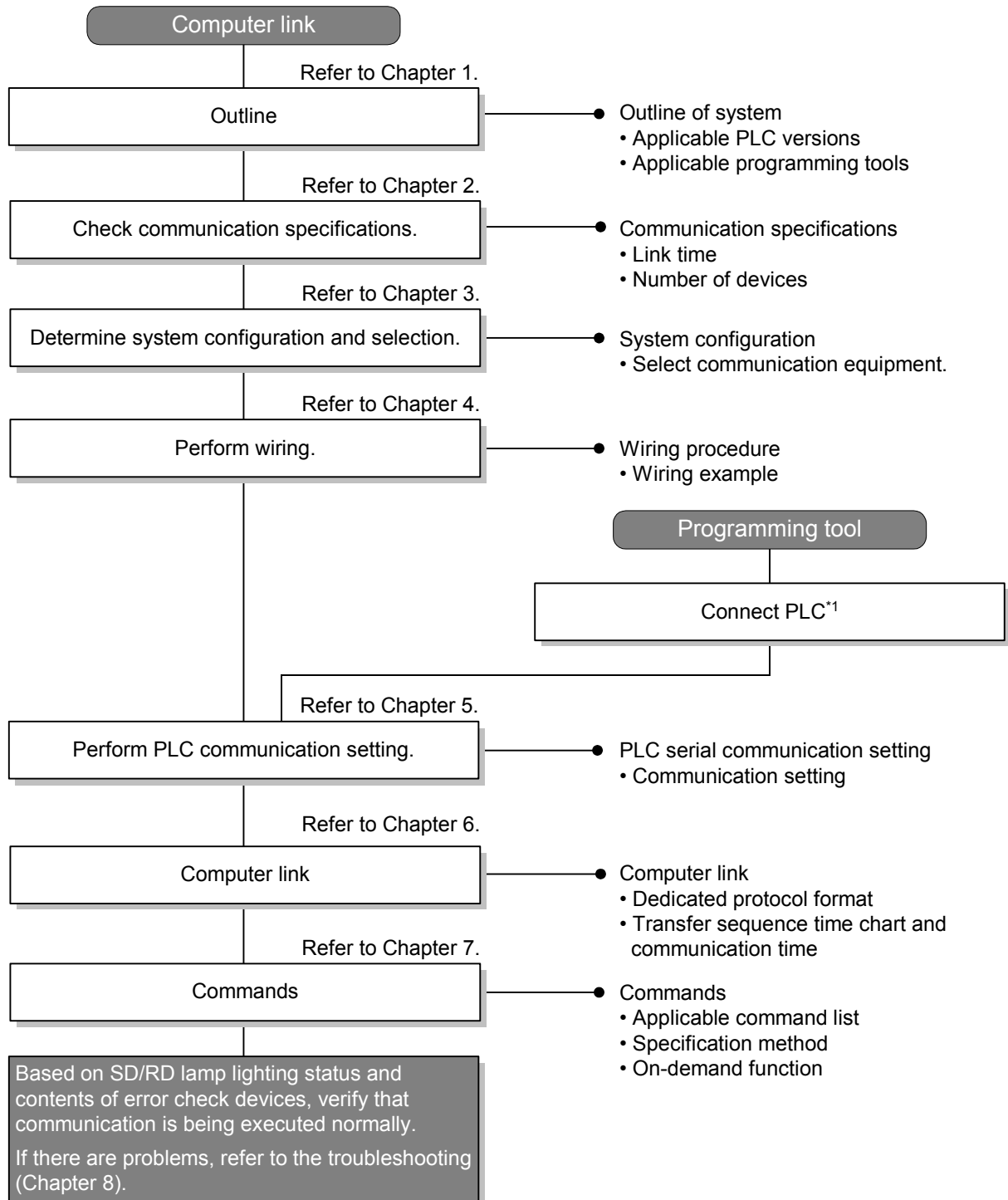


The number of devices handled all at once varies depending on the command and the types of devices.

| | |
|------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/R2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

1.2 Procedures Before Operation

The flow chart below shows the Computer Link setting procedures up until data link.



*1 For the programming tool to PLC connection procedure, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operating procedures, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

The communication type is applicable in the following versions.

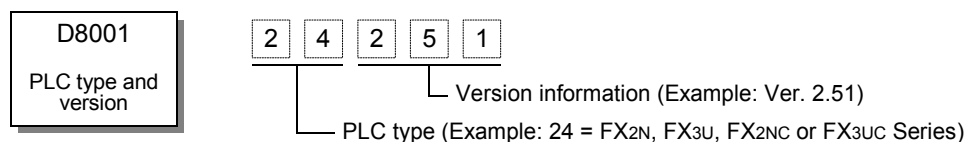
✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|--------------------------------------|---|
| FX3UC Series | ✓ | |
| FX3U Series | ✓ | |
| FX2NC Series | ✓ | |
| FX2N Series | ✓ (Ver. 1.06 or later) | The version can be checked by monitoring D8001. |
| FX1NC Series | ✓ | |
| FX1N Series | ✓ | |
| FX1S Series | ✓ | |
| FX0N Series | ✓ (Ver. 1.20 or later) | The version can be checked by monitoring D8001. |
| FX0S Series | — | Computer link is not provided. |
| FX0 Series | — | Computer link is not provided. |
| FX2C Series | ✓ (Ver. 3.30 or later)* ¹ | |
| FX2(FX) Series | ✓ (Ver. 3.30 or later)* ¹ | |
| FX1 Series | — | Computer link is not provided. |

*1. Applicable in products manufactured in June, 1996 and later (manufacturer's serial No.: 66**** and later).

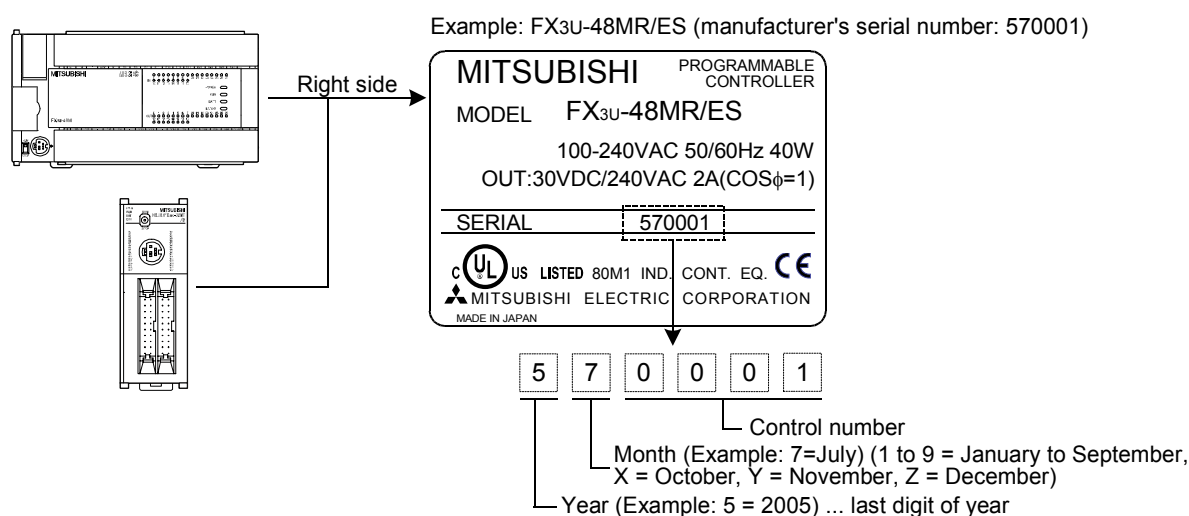
1. Version check

The D8001(decimal) special data register contains information for determining the PLC version.



2. How to look at the manufacturer's serial number

The year and month of production of product can be seen from the Manufacturer's serial number "SERIAL" indicated on the label adhered to the right side of the product.



1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description on system configuration, etc. in this manual for maintenance.

| PLC | Date when production was stopped | Remarks |
|----------------|----------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2c Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the following version shown:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC". |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC". |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.00 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXC | ✓ (Ver. 4.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC". |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 5.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXD | ✓ (Ver. 5.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC". |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC". |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXC-E | ✓ (Ver. 3.00 or later) | |
| FX-10P-E | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC". |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXD-E | ✓ (Ver. 4.00 or later) | |
| FX-10P-E | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |

1.4.2 For non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set. In this case, however, programming is enabled only in the function ranges provided for the alternative PLC model such as instructions and program size.

| Model to be programmed | Model to be set | Priority: High → Low | | | |
|------------------------|-----------------|----------------------|---------|---|---------|
| FX3UC Series | FX3UC | → | FX2N | → | FX2(FX) |
| FX3U Series | FX3U, FX3UC | → | FX2N | → | FX2(FX) |
| FX2NC Series | FX2NC, FX2N | → | FX2(FX) | | |
| FX2N Series | FX2N | → | FX2(FX) | | |
| FX1NC Series | FX1NC, FX1N | → | FX2N | → | FX2(FX) |
| FX1N Series | FX1N | → | FX2N | → | FX2(FX) |
| FX1S Series | FX1S | → | FX2(FX) | | |
| FX0N Series | FX0N | → | FX2(FX) | | |
| FX0S Series | FX0S | → | FX2(FX) | | |
| FX0 Series | FX0 | → | FX2(FX) | | |
| FX2C Series | FX2C, FX2 | → | FX2(FX) | | |
| FX2(FX) Series | FX2(FX) | → | FX2(FX) | | |
| FX1 Series | FX1 | | | | |

2. Specifications

This chapter explains the communication specifications and performance.

2.1 Communication Specifications (Reference)

Communication is executed within the specifications shown in the table below. The baud rate, etc. can be changed in the parameter settings of a programming tool or in a sequence program.

| Item | Specifications | Remarks |
|----------------------------------|---|--|
| Number of connectable units | 16 maximum | |
| Transmission standard | RS-485 or RS-232C standard | |
| Maximum total extension distance | RS-485: 500 m (1640' 5") or less [50 m (164' 0") or less when 485BD is included in system] RS-232C: 15 m (49' 2") or less | Distance varies depending on communication equipment type. |
| Protocol type | Computer link (dedicated protocol) | Formats 1 and 4 are applicable. |
| Control procedure | — | |
| Communication method | Half-duplex, bidirectional communication | |
| Baud rate | 300, 600, 1200, 2400, 4800, 9600 or 19200 bps | |
| Character format | — | |
| Start bit | Fixed | |
| Data bit | 7 or 8-bit | |
| Parity bit | None, odd or even | |
| Stop bit | 1 or 2-bit | |
| Header | Fixed | |
| Terminator | Fixed | |
| Control line | Fixed | |
| Sum check | Provided or not provided | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2.2 Link Specifications

2.2.1 Applicable commands and number of device points

| Name | | | Command | | Contents of processing | Number of points processed in one-time update | | |
|----------------|-----------------------------|---------------|------------------|---------------|---|--|--|--|
| | | | Sym- bol | ASCII code | | FX1S, FX0N | FX2(FX), FX2C, FX2N, FX1N, FX2NC, FX1NC | FX3U, FX3UC |
| Device memory | Batch reading | Unit: Bit | BR | 42H, 52H | Reads bit devices in 1 point units. | 54 | 256 | 256 |
| | | Unit: Word | WR | 57H, 52H | Reads bit devices in 16 point units. | 13 words 208 points | 32 words 512 points | 32 words 512 points |
| | | | | | Read word devices in 1 point units. | 13 ^{*4} | 64 ^{*2} | 64 ^{*2} |
| | | | QR ^{*1} | 51H, 52H | Reads bit devices in 16 point units. | — | — | 32 words 512 points |
| | | | | | Read word devices in 1 point units. | — | — | 64 ^{*2} |
| | Batch writing | Unit: Bit | BW | 42H, 57H | Writes bit devices in 1 point units. | 46 | 160 | 160 |
| | | Unit: Word | WW | 57H, 57H | Writes bit devices in 16 point units. | 10 words 160 points | 10 words 160 points | 10 words 160 points |
| | | | | | Writes word devices in 1 point units. | 11 ^{*5} | 64 ^{*2} | 64 ^{*2} |
| | | | QW ^{*1} | 51H, 57H | Writes bit devices in 16 point units. | — | — | 10 words 160 points |
| | | | | | Writes word devices in 1 point units. | — | — | 64 ^{*2} |
| | Test (random writing) | Unit: Bit | BT | 42H, 54H | Specifies bit devices arbitrarily in 1 point units, and sets or resets them. | 10 | 20 | 20 |
| | | Unit: Word | WT | 57H, 54H | Specifies bit devices arbitrarily in 16 point units, and sets or resets them. | 6 words 96 points | 10 words 160 points | 10 words 160 points |
| | | | | | Specifies word devices arbitrarily in 1 point units, and writes them. | 6 ^{*3} | 10 ^{*3} | 10 ^{*3} |
| | | | QT ^{*1} | 51H, 54H | Specifies bit devices arbitrarily in 16 point units, and sets or resets them. | — | — | 10 words 160 points |
| | | | | | Specifies word devices arbitrarily in 1 point units, and writes them. | — | — | 10 ^{*3} |
| PLC | Remote RUN | | RR | 52H, 52H | — | — | — | |
| | Remote STOP | | RS | 52H, 53H | | | | |
| | PLC model name reading | | PC | 50H, 43H | | | | Reads PLC model name. |
| Global | | | GW | 47H, 57H | Turns global signal ON or OFF (M8126 in FX Series) in all PLCs connected in computer link. | 1 | 1 | 1 |
| On-demand | | | — | — | Set the sending request flag to ON in PLC (only when 1-to-1 connection is adopted in system configuration). | Maximum quantity specified in sequence program: 13 words | Maximum quantity specified in sequence program: 64 words | Maximum quantity specified in sequence program: 64 words |
| Loop-back test | | | TT | 54H, 54H | Returns recieved characters back to the computer as they are. | 25 characters | 254 characters | 254 characters |

*1. Available only in FX3U and FX3UC PLCs.

*2. 32 points when 32-bit counters (C200 to C255) are specified.

*3. 32-bit counters (C200 to C255) are not applicable.

*4. 6 points when 32-bit counters (C200 to C255) are specified.

*5. 5 points when 32-bit counters (C200 to C255) are specified.

2.2.2 Applicable device ranges

The tables below show devices and device number ranges applicable for the device memory access.

- Construct each of the BR, BW, BT, WR, WW, and WT commands in five characters.

$$\left(\begin{array}{c} \text{Device} \\ \text{1 character} \\ \text{2 characters for timer or counter} \end{array} \right) + \left(\begin{array}{c} \text{Device number} \\ \text{4 characters} \\ \text{3 characters for timer or counter} \end{array} \right) = 5 \text{ characters}$$

- Construct each of the QR, QW, and QT commands in seven characters.

$$\left(\begin{array}{c} \text{Device} \\ \text{1 character} \\ \text{2 characters for timer or counter} \end{array} \right) + \left(\begin{array}{c} \text{Device number} \\ \text{6 characters} \\ \text{5 characters for timer or counter} \end{array} \right) = 7 \text{ characters}$$

1. Bit devices

FX PLCs do not support timer coils (TC) and counter coils (CC).

| Device | Device number range (character) | | | | | | Device number expression Decimal/ Octal | Available commands | | |
|-----------------------------|----------------------------------|----------------------------------|------------------|----------------|----------------|--------------------|---|--------------------|---------------|---------------|
| | FX1S | FX0N | FX2(FX), FX2C | FX1N, FX1NC | FX2N, FX2NC | FX3U, FX3UC | | BR, BW, BT | WR, WW, WT | QR, QW, QT |
| Input relay (X) | X0000 to X0017 | X0000 to X0177 | X0000to X0267 | X0000 to X0177 | X0000 to X0337 | X0000 to X0377 | Octal | ✓ | ✓ | — |
| | — | | | | | X000000 to X000377 | | — | — | ✓ |
| Output relay (Y) | Y0000 to Y0015 | Y0000 to Y0177 | Y0000to Y0267 | Y0000 to Y0177 | Y0000 to Y0337 | Y0000 to Y0377 | | ✓ | ✓ | — |
| | — | | | | | Y000000 to Y000377 | | — | — | ✓ |
| Auxiliary relay (M) | M0000 to M0511 | | M0000 to M1535 | | M0000 to M3071 | M0000 to M7679 | Decimal | ✓ | ✓ | — |
| | — | | | | | M000000 to M007679 | | — | — | ✓ |
| State relay (S) | S0000 to S0127 | | S0000 to S0999 | | | S0000 to S4095 | | ✓ | ✓ | — |
| | | | | | | S000000 to S004095 | | — | — | ✓ |
| Special auxiliary relay (M) | M8000 to M8254 | | M8000 to M8255 | | | M8000 to M8511 | | ✓ | ✓ | — |
| | — | | | | | M008000 to M008511 | | — | — | ✓ |
| Timer contact (T) | TS000 to TS063 | | TS000 to TS255 | | | TS000 to TS511 | | ✓ | — | — |
| | — | | | | | TS00000 to TS00511 | | — | — | — |
| Counter contact (C) | CS000 to CS031 CS235 to CS255 | CS000 to CS031 CS235 to CS254 | CS000 to CS255 | | | CS000 to CS255 | | ✓ | — | — |
| | — | | | | | CS00000 to CS00255 | | — | — | — |

2. Word devices

| Device | Device number range (character) | | | | | | Device number expression Decimal/ Octal | Available commands | | |
|---------------------------|----------------------------------|----------------------------------|------------------|----------------|----------------|--------------------|---|--------------------|---------------|---------------|
| | FX1S | FX0N | FX2(FX), FX2C | FX1N, FX1NC | FX2N, FX2NC | FX3U, FX3UC | | BR, BW, BT | WR, WW, WT | QR, QW, QT |
| Timer current value (T) | TN000 to TN063 | | TN000 to TN255 | | | TN000 to TN511 | Decimal | — | ✓ | — |
| | — | | | | | TN00000 to TN00511 | | | — | ✓ |
| Counter current value (C) | CN000 to CN031 CN235 to CN255 | CN000 to CN031 CN235 to CN254 | CN000 to CN255 | | | CN000 to CN255 | | | ✓*1 | — |
| | — | | | | | CN00000 to CN00255 | | | — | ✓*1 |
| Data register (D) | D0000 to D0255 | | D0000 to D0999 | D0000 to D7999 | | D0000 to D7999 | | | ✓ | — |
| | — | | | | | D000000 to D007999 | | | — | ✓ |
| File register (D) | — | D1000 to D2499 | D1000 to D2999 | — | | — | | | ✓ | — |
| | — | | | | | — | | | — | — |
| RAM file register (D) | — | | D6000 to D7999 | — | | — | | | ✓ | — |
| | — | | | | | — | | | — | — |
| Extension register (R) | — | | | | | R0000 to R9999 | | | ✓ | — |
| | — | | | | | R000000 to R032767 | | | — | ✓ |
| Special data register (D) | D8000 to D8255 | | D8000 to D8255 | | | D8000 to D8511 | | | ✓ | — |
| | — | | | | | D008000 to D008511 | | | — | ✓ |

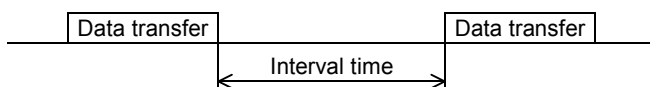
*1. The WT and QT commands do not support 32-bit counters (C200 to C255).

Cautions

- When using bit devices in a command requiring specification in 1-word units, make sure that the head device number is a multiple of "8".
- Special auxiliary relays and special data registers are classified into ones for read only, write only and ones for system only.
If data is written to any range in which writing is not allowed, an error may occur in the PLC.
For details on special auxiliary relays and special data registers, refer to the manual of the PLC.
- In FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC PLCs, the PLCs cannot access the program area (in the built-in RAM and memory cassette) when users set file registers (D).
In FX3U and FX3UC PLCs, extension registers (R) cannot access extension file registers (ER) in a mounted memory cassette.

2.2.3 Link time

1. Data transfer



2. Data transfer time

Time to read continuous word devices (timers, counters or data registers) in one station = $(21^{*1} + 4 \times \text{Number of read points}^{*2}) \times \text{Time to send or receive 1 character (ms)} + \text{Interval time} + \text{Maximum scan time (special data register D8012) in PLC} \times 3 + \text{Message waiting time}$

Time to write continuous word devices (timers, counters or data registers) in one station = $(20^{*1} + 4 \times \text{Number of written points}^{*2}) \times \text{Time to send or receive 1 character (ms)} + \text{Interval time} + \text{Maximum scan time (special data register D8012) in PLC} + \text{Message waiting time}$

- *1. This is the number of characters when the protocol format 1 is used and the sum check is not provided.
When the protocol format 4 is used, add "4" to this value.
When the sum check is provided, add "4" to this value also.
- *2. The number of points is counted in 1-word units.

3. Time to send or receive one character

The table below shows the time required to send or receive one character when the start bit is 1-bit, the data length is 7-bit, the parity is 1-bit, and the stop bit is 1-bit.

| Transmission speed (baud rate) (bps) | Time to send or receive 1 character (ms) |
|--------------------------------------|--|
| 300 | 33.34 |
| 600 | 16.67 |
| 1200 | 8.34 |
| 2400 | 4.17 |
| 4800 | 2.08 |
| 9600 | 1.04 |
| 19200 | 0.52 |

The tables below show the data transfer times depending on the number of continuously read or written word devices at the transmission speeds of 9600 bps and 19200 bps when the message waiting time is 0 ms^{*1}, the maximum scan time is 20 ms, and the interval time is 100 ms.

<When the transmission speed is 9600 bps> Unit: sec

| Number of data points | Number of stations | | |
|-----------------------|--------------------|-----|-----|
| | 1 | 8 | 16 |
| 10 | 0.3 | 1.9 | 3.7 |
| 32 | 0.4 | 2.6 | 5.2 |
| 64 | 0.5 | 3.7 | 7.3 |

<When the transmission speed is 19200 bps> Unit: sec

| Number of data points | Number of stations | | |
|-----------------------|--------------------|-----|-----|
| | 1 | 8 | 16 |
| 10 | 0.2 | 1.6 | 3.2 |
| 32 | 0.3 | 2.0 | 3.9 |
| 64 | 0.4 | 2.5 | 5.0 |

When the types of read or written devices increase, "Data transfer time shown in above table × Number of device types" is required.

When the number of read or written points exceeds "64"^{*2}, the transfer time increase.

Accordingly, for achieving efficient data transfer, it is recommended to decrease the number of types of transferred devices and use as many continuous device numbers as possible.

- *1. The message waiting time is "0" when the RS-485 interface and two-pair wiring are used.
The message waiting time is "0" also when the RS-232C interface is used.
When one-pair wiring is adopted, a message waiting time of 70 to 150 ms is required for each transfer.
Add this message waiting time.
- *2. The maximum number of points is 64 for the FX2(FX), FX2C, FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC Series. The maximum number of points is as follows for the FX0N and FX1S Series:
Maximum number of read points : 13
Maximum number of written points: 11

3. System Configuration and Equipment Selection

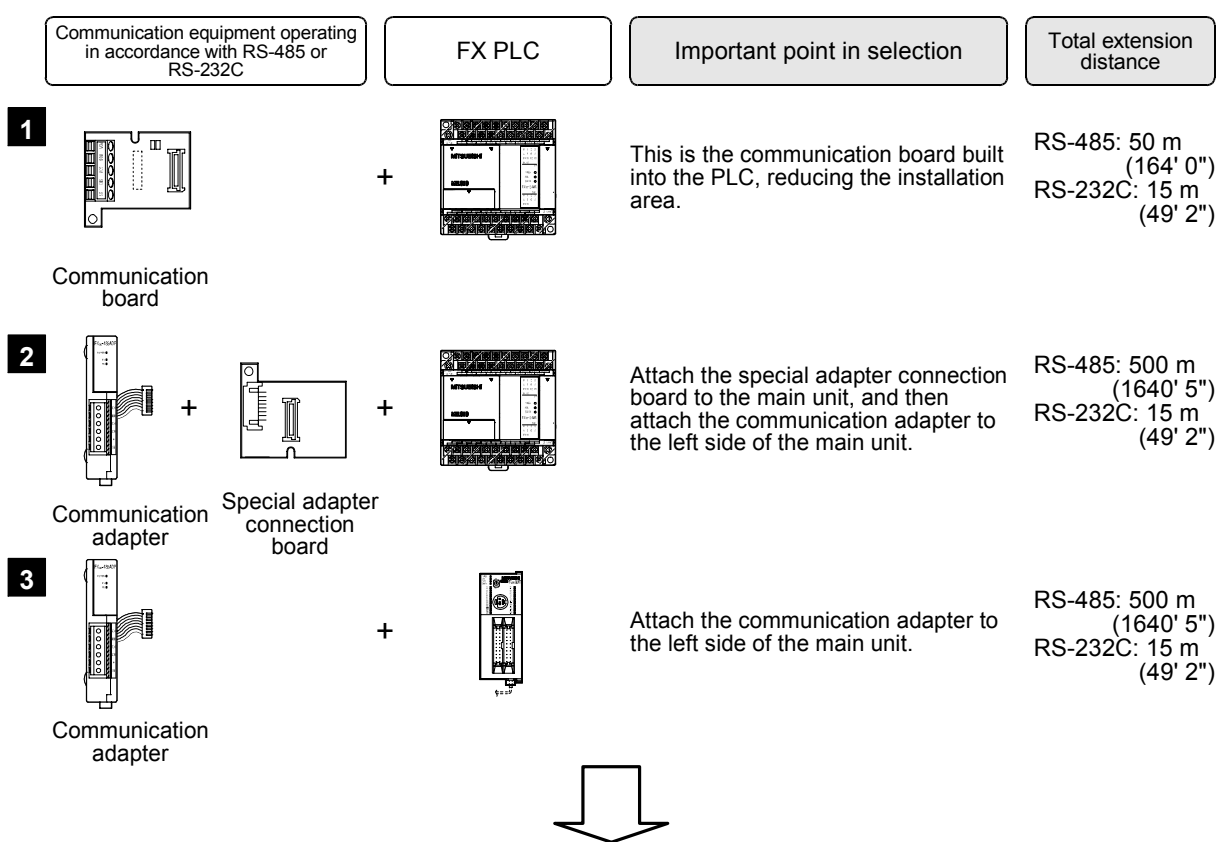
This chapter explains the system configuration and communication equipment selection operating in accordance with RS-485 or RS-232C required by FX PLCs.

3.1 System Configuration

This section outlines the system configuration required to use computer link.

Connect (optional) equipment operating in accordance with RS-485 or RS-232C to the FX PLC main unit.

1, **2** and **3** indicate the communication equipment combination patterns.



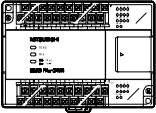
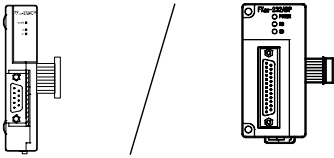

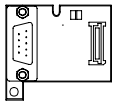
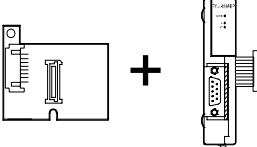
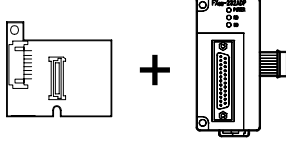
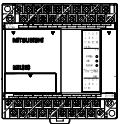
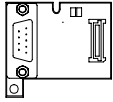
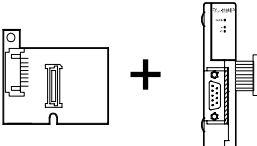
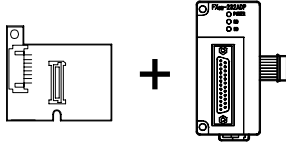
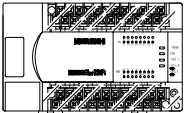
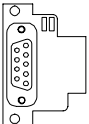
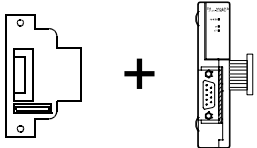
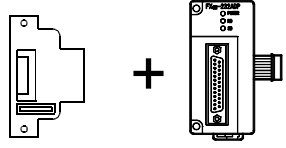
For communication equipment combinations for each FX Series, refer to the next page.


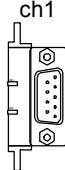

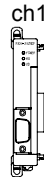

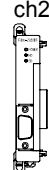
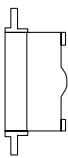


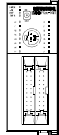
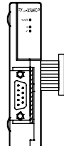
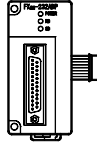
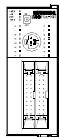
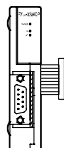
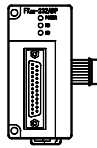
3.2 Applicable FX PLC and Communication Equipment

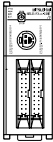



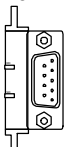


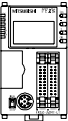





Select a (optional) communication equipment combination, and put a check mark in the "Check" column.
During selection, pay attention to the following:

- Computer link is not provided for the FX0, FX0S, or FX1 Series.

3.2.1 For communication in accordance with RS-232C

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX0N |  FX2NC-232ADP (9-pin D-Sub, male) / FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX1S |  FX1N-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |   FX1N-CNV-BD + FX2NC-232ADP (9-pin D-Sub, male) / FX1N-CNV-BD + FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX1N |  FX1N-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |   FX1N-CNV-BD + FX2NC-232ADP (9-pin D-Sub, male) / FX1N-CNV-BD + FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX2N |  FX2N-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |   FX2N-CNV-BD + FX2NC-232ADP (9-pin D-Sub, male) / FX2N-CNV-BD + FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|---|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  ch1 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485 and USB) +  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485) +  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX1NC |  FX2NC-232ADP (9-pin D-Sub, male) /  FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX2NC |  FX2NC-232ADP (9-pin D-Sub, male) /  FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1)  ch1 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2)  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485)  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 1 (ch 1)  ch1 FX3U-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD  ch1 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX3UC-32MT-LT | When using channel 2 (ch 2)  ch1 FX3U-□-BD (Where □ represents 232, 422, 485 and USB)  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485)  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

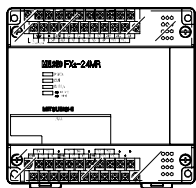
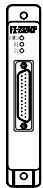
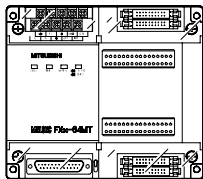
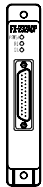
Programming Communication

I

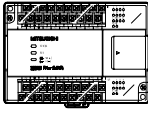
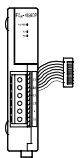
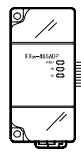

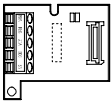
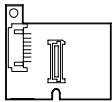
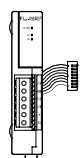
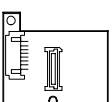
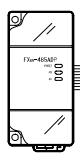

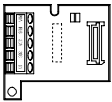
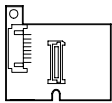
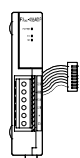
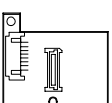
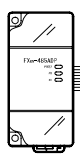
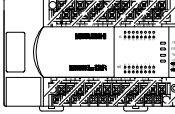
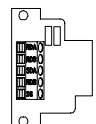
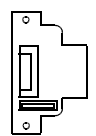
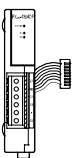
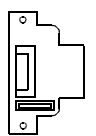

Remote Maintenance

Apx.

Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|---|--------------------------|-------|
|  <p>FX2(FX)</p> |  <p>FX-232ADP (25-pin D-Sub, female)</p> | 15 m (49' 2") | |
|  <p>FX2C</p> |  <p>FX-232ADP (25-pin D-Sub, female)</p> | 15 m (49' 2") | |

3.2.2 For communication in accordance with RS-485.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX0N |  /  FX2NC-485ADP (European terminal block) FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX1S |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP (European terminal block) FX1N-CNV-BD FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX1N |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP (European terminal block) FX1N-CNV-BD FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX2N |  FX2N-485-BD | 50 m (164' 0") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-485ADP (European terminal block) FX2N-CNV-BD FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

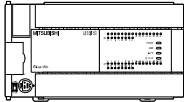
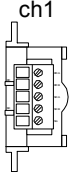

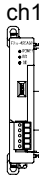


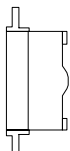
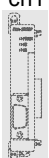

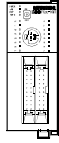
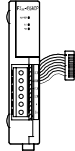
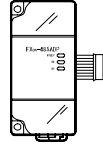
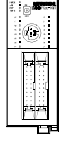
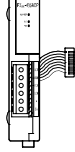
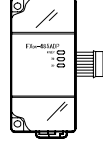
Programming Communication

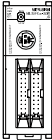



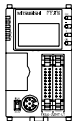
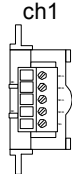

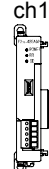



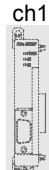
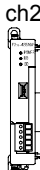
I

Remote Maintenance

Apx.

Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX1NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX2NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1) | | |
| |  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX3UC-32MT-LT | When using channel 1 (ch 1) | | |
| |  FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

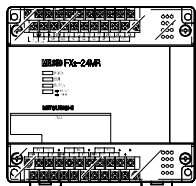

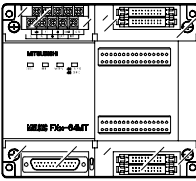

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  <p>FX2</p> |  <p>FX-485ADP (Terminal block)</p> | 500 m (1640' 5") | |
|  <p>FX2C</p> |  <p>FX-485ADP (Terminal block)</p> | 500 m (1640' 5") | |

4. Wiring

This chapter explains the wiring.

WIRING PRECAUTIONS



- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to attach the terminal cover, offered as an accessory, before turning on the power or initiating operation after installation or wiring work. Failure to do so may cause electric shock.

WIRING PRECAUTIONS



- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to abnormal data written to the PLC under the influence of noise:
 - 1) Do not bundle the main circuit line together with or lay it close to the main circuit, high-voltage line or load line. Otherwise, noise disturbance and/or surge induction are likely to take place. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or high-voltage line.
 - 2) Ground the shield wire or shield of the shielded cable at one point on the PLC. However, do not use grounding with heavy electrical systems.
- Make sure to properly wire the FX0N/FX2N Series extension equipment in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should follow the specifications in this manual.
- Make sure to properly wire to the European terminal board in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should be follow the specifications in this manual.
 - Twist the end of strand wire and make sure that there are no loose wires.
 - Do not solder-plate the electric wire ends.
 - Do not connect more than the specified number of wires or electric wires of unspecified size.
 - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

4.1 Wiring Procedure

1 Selecting the connection method

Select the wiring method suitable to the application.

→ For details, refer to Section 4.2.

2 Preparing for wiring

Prepare cables and terminal resistors required for wiring.

→ For details, refer to Section 4.3.

3 Turning OFF the PLC power

Before starting any wiring work, make sure that the PLC power is OFF.

4 Connecting the power supply (FX0N-485ADP only)

Connect the power supply to the 24V DC power terminal.

5 Wiring communication equipment

Connect communication equipment operating in accordance with RS-485 or RS-232C.

→ For communication in accordance with RS-232C, refer to Section 4.4.

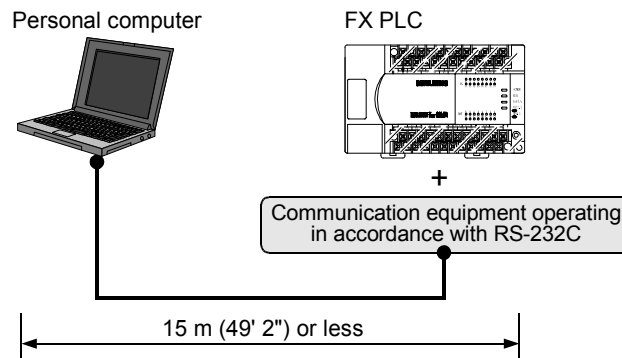
→ For communication in accordance with RS-485, refer to Section 4.5.

4.2 Selecting Connection Method

When using computer link, communication can be achieved in accordance with RS-232C or RS-485 (422). In FX3U and FX3UC PLCs, computer link is applicable in up to two channels at the same time. In such a case, communication can be achieved in accordance with RS-232C on both channels, in accordance with RS-485 on both channels, or in accordance with RS-232C on one channel and RS-485 on the other channel.

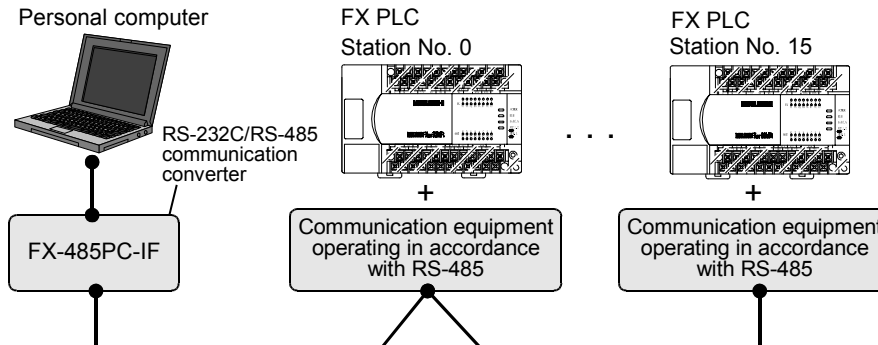
4.2.1 For communication in accordance with RS-232C (1-to-1 connection)

With communication in accordance with RS-232C, 1-to-1 connection is applicable. Make sure that the total extension distance is 15 m (49' 2") or less.



4.2.2 For communication in accordance with RS-485 (RS-422) (1-to-N connection)

With communication in accordance with RS-485 (RS-422), up to 16 PLCs can be connected. Make sure that the total extension distance is 500 m (1640' 5") or less [50 m (164' 0") or less when 485BD is included].



One-pair wiring and two-pair wiring are applicable for communication in accordance with RS-485 (RS-422). The wiring method is determined for each application. Refer to the table below, and perform suitable wiring.

| | | One-pair wiring | Two-pair wiring |
|-----------------------------|---|-----------------|-----------------|
| Computer link ^{*1} | When the message waiting time ^{*2} should be 70 ms or less | — | ✓ |
| | When the message waiting time ^{*2} may be more than 70 ms | ◎ ^{*3} | ✓ |
| | When the on-demand function is used | — | ✓ |

◎: Recommended wiring method, ✓: Applicable wiring method, —: Non-applicable wiring method

- *1. When computer link is added to an existing system, adopt the wiring method used in the existing system.
- *2. For the message waiting time, refer to Subsection 6.4.3.
- *3. "Echo transfer" is generated when the FX-485PC-IF is used in the one-pair wiring. Take proper countermeasures in the computer so that the echo transfer can be ignored.

4.3 Selecting Cables and Terminal Resistors (RS-485)

Select cables using the procedure described below.

4.3.1 Twisted pair cable

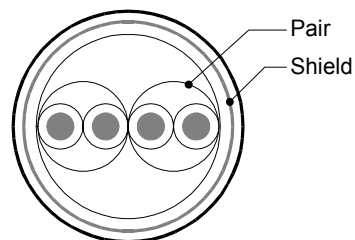
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows recommended model names and manufacturers of cables used in wiring.

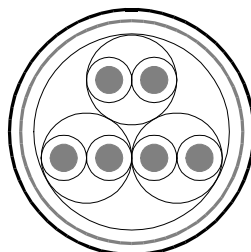
1. Recommended cables

| Manufacturer | Model name | Remarks |
|---------------------------------------|----------------------------------|---|
| Mitsubishi Cable Industries, Ltd. | SPEV(SB)-0.2-2P | Two-pair cable of 0.2 mm ² |
| | SPEV(SB)-MPC-0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | SPEV(SB)-0.5-2P | Two-pair cable of 0.5 mm ² |
| Showa Electric Wire & Cable Co., Ltd. | KMPEV-SB CWS-178 0.2SQ × 2P | Two-pair cable of 0.2 mm ² |
| | KMPEV-SB CWS-178 0.5SQ × 2P | Two-pair cable of 0.5 mm ² |
| Sumitomo Electric Industries, Ltd. | DPEV SB 0.3 × 3P | Three-pair cable of 0.3 mm ² |
| | DPEV SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| The Furukawa Electric Co., Ltd. | D-KPEV-SB 0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | D-KPEV-SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| Fujikura Ltd. | IPEV-SB 2P × 0.3 mm ² | Two-pair cable of 0.3 mm ² |
| | IPEV-SB 2P × 0.5 mm ² | Two-pair cable of 0.5 mm ² |

2. Cable structural drawing (reference)



Two-pair cable structural drawing example



Three-pair cable structural drawing example

4.3.2 Connecting cables

1. European type terminal block

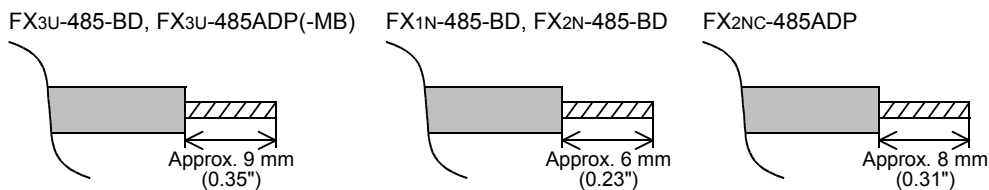
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows applicable cables and tightening torques.

| | Cable size when one cable is connected | Cable size when two cables are connected | Cable size for bar terminal with insulating sleeve | Tightening torque | Tool size | |
|----------------------------------|--|--|--|-------------------|-------------|-------------|
| | | | | | A | B |
| FX3U-485-BD FX3U-485ADP (-MB) | AWG22 to AWG20 | AWG22 | AWG22 to AWG20 | 0.22 to 0.25 N·m | 0.4 (0.01") | 2.5 (0.09") |
| FX2N-485-BD FX1N-485-BD | AWG26 to AWG16 | | — | 0.6 N·m | 0.6 (0.03") | 3.5 (0.14") |
| FX2NC-485ADP | AWG26 to AWG16 | AWG26 to AWG20 | — | 0.4 to 0.5 N·m | 0.6 (0.03") | 3.5 (0.14") |

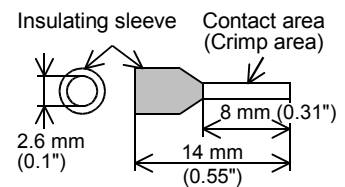
With regard to the cable end treatment, use a stranded cable or solid cable as it is, or use a bar terminal with insulating sleeve.

- When using a stranded cable or solid cable as it is
 - Twist the end of a stranded cable so that wires do not get barbed.
 - Do not plate the end of the cable.



- When using a bar terminal with insulating sleeve
Because it is difficult to insert a cable into an insulating sleeve depending on the thickness of the cable sheath, select the proper cable according to the outline drawing.

| Manufacturer | Model name | Caulking tool |
|-----------------|------------|----------------------------------|
| Phoenix Contact | AI 0.5-8WH | CRIMPFOX ZA 3 (or CRIMPFOX UD 6) |

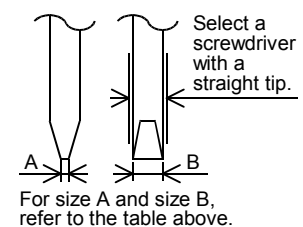


- Tool
 - When tightening a terminal on the European terminal block, use a small commercial straight shape screwdriver whose tip is shown in the figure to the right.

Note:

If the diameter of screwdriver grip is too small, tightening torque will not be able to be achieved. Use the following recommended screwdriver or an appropriate replacement (grip diameter: approximately 25mm).

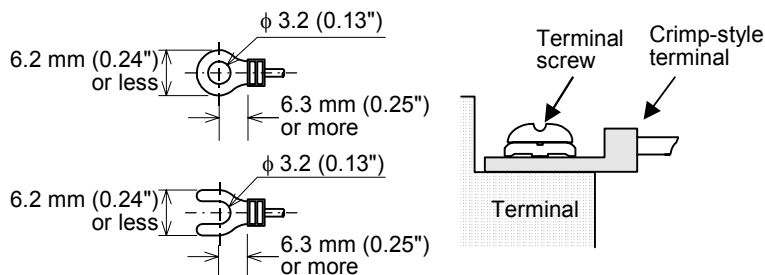
| Manufacturer | Model name |
|-----------------|---------------|
| Phoenix Contact | SZS 0.4 × 2.5 |



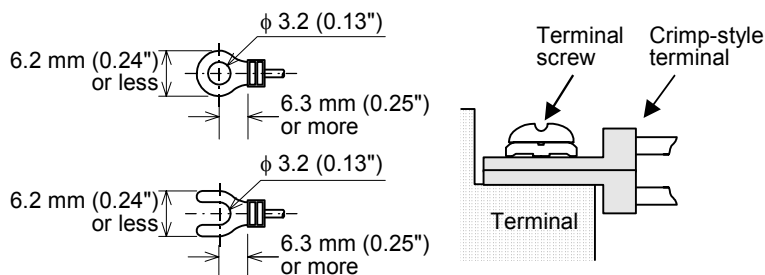
2. Terminal block

In the FX0N-485ADP and FX-485ADP, the terminal screw size is "M3".
Make sure to use a crimp-style terminal with the following sizes.
Make sure that the tightening torque is 0.5 to 0.8 N·m.

- When wiring one cable to one terminal



- When wiring two cables to one terminal

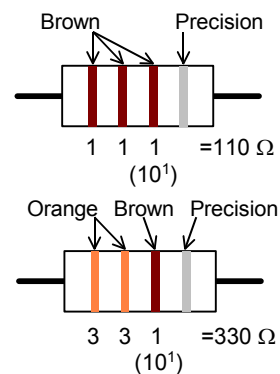


4.3.3 Connecting terminal resistors

Make sure to provide a terminal resistor at the end of each line.
In the case of one-pair wiring, connect a terminal resistor to the RDA-RDB signal terminal of the communication equipment.
In the case of two-pair wiring, connect a terminal resistor to the RDA-RDB signal terminal and SDA-SDB terminal of the communication equipment.

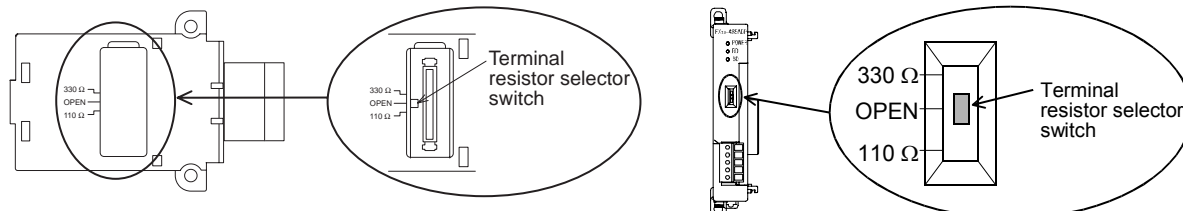
1. Terminal resistor type

In the case of one-pair wiring, use two terminal resistors of 110 Ω , 1/2 W.
In the case of two-pair wiring, use four terminal resistors of 330 Ω , 1/4 W.
Among the terminal resistors supplied with the communication equipment, select ones with the color codes shown to the right.



2. When using the FX3U-485-BD or FX3U-485ADP(-MB)

The FX3U-485-BD and FX3U-485ADP(-MB) have built-in terminal resistors.
Set the terminal resistor selector switch accordingly.



4.4 Connection Diagram for RS-232C

Representative wiring examples are shown in this section. When pin numbers in the external equipment are different, wire the pins as shown below.

4.4.1 Connection diagram between FX PLC and personal computer

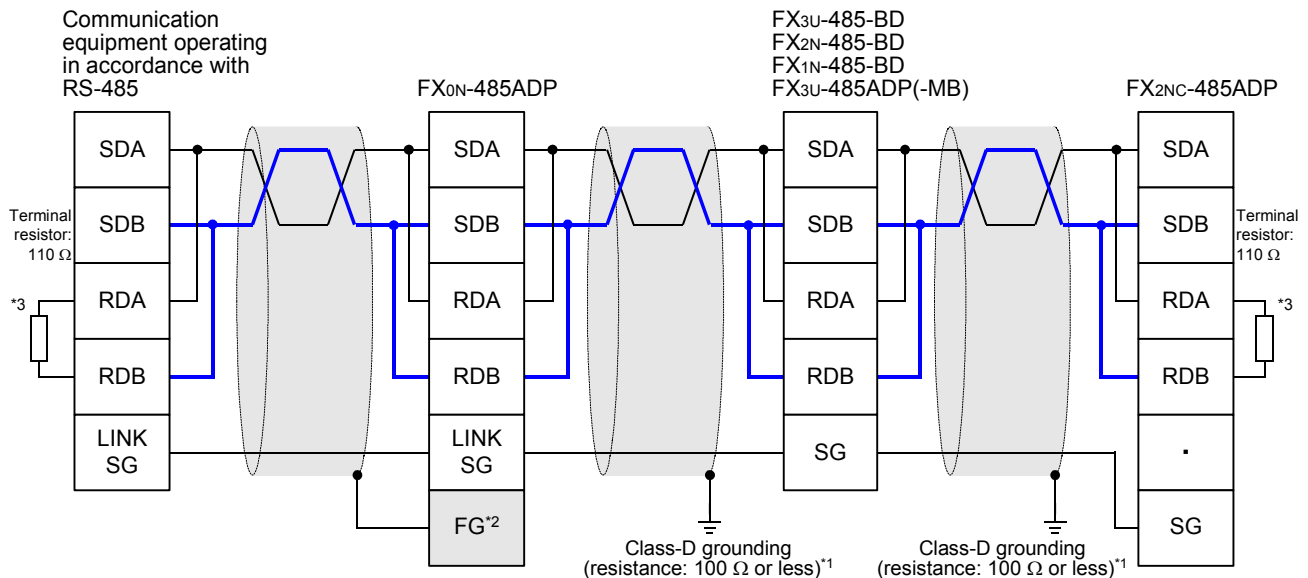
| PLC side | | | | | External equipment operating in accordance with RS-232C | | | | | |
|----------|---|--------------|-------------|-----------|---|-------------------------|--------------|---------|-------------------------|--------------|
| Name | FX3U-232-BD FX2N-232-BD FX1N-232-BD FX3U-232ADP(-MB) | FX2NC-232ADP | FX0N-232ADP | FX-232ADP | Name | When CS and RS are used | | Name | When DR and ER are used | |
| | | | | | | 9-pin D-Sub | 25-pin D-Sub | | 9-pin D-Sub | 25-pin D-Sub |
| FG | — | | | 1 | FG | — | 1 | FG | — | 1 |
| RD(RXD) | 2 | | 3 | | RD(RXD) | 2 | 3 | RD(RXD) | 2 | 3 |
| SD(TXD) | 3 | | 2 | | SD(TXD) | 3 | 2 | SD(TXD) | 3 | 2 |
| ER(DTR) | 4 | | 20 | | RS(RTS) | 7 | 4 | ER(DTR) | 4 | 20 |
| SG(GND) | 5 | | 7 | | SG(GND) | 5 | 7 | SG(GND) | 5 | 7 |
| DR(DSR) | 6 | | 6 | | CS(CTS) | 8 | 5 | DR(DSR) | 6 | 6 |


4.4.2 Connection diagram between FX-485PC-IF and personal computer

| 485PC-IF | | Personal computer | |
|-------------|---------|-------------------|--|
| Signal name | Pin No. | Signal name | |
| SD (TXD) | 2 | SD (TXD) | |
| RD (RXD) | 3 | RD (RXD) | |
| RS (RTS) | 4 | RS (RTS) | |
| CS (CTS) | 5 | CS (CTS) | |
| DR (DSR) | 6 | DR (DSR) | |
| SG (GND) | 7 | SG (GND) | |
| ER (DTR) | 20 | ER (DTR) | |

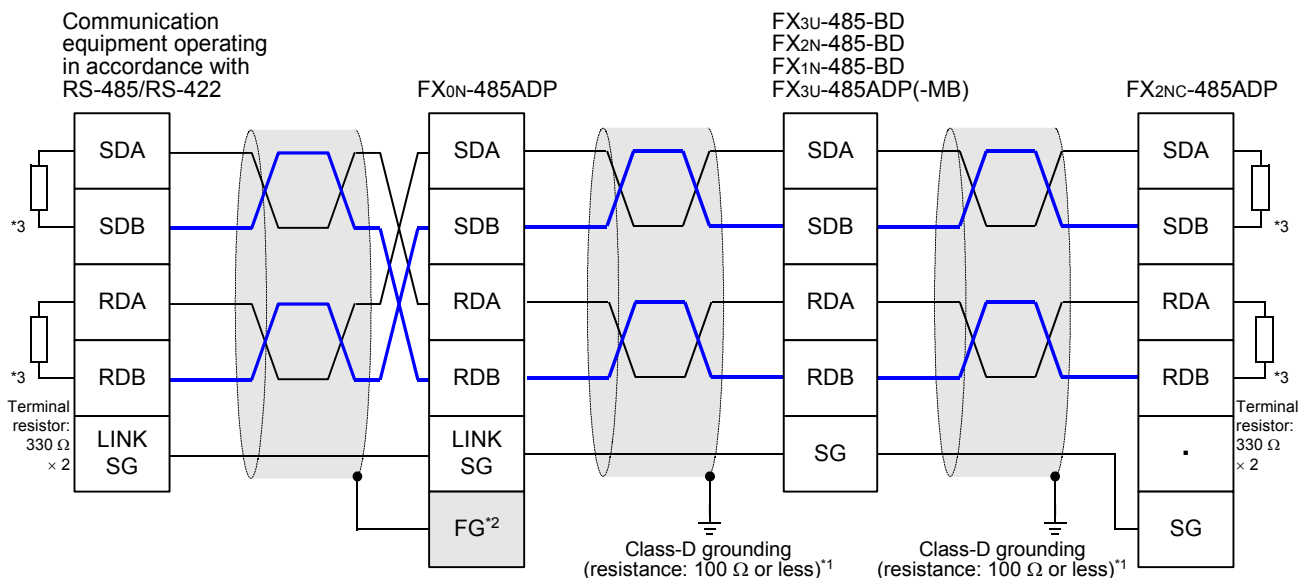
4.5 Connection Diagram for RS-485 and RS-422


4.5.1 One-pair wiring



- ^{*1} Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD, FX3U-485-BD, FX2NC-485-ADP or FX3U-485ADP(-MB).
- ^{*2} Make sure to connect the **FG** terminal to the  (grounding) terminal in the PLC requiring Class-D grounding. If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.
- ^{*3} Make sure to provide a terminal resistor at the end of each line.
- The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor. Set the terminal resistor selector switch accordingly.
 - The FX0N-485ADP, FX2NC-485ADP, FX2N-485-BD and FX1N-485-BD are supplied together with terminal resistors.

4.5.2 Two-pair wiring



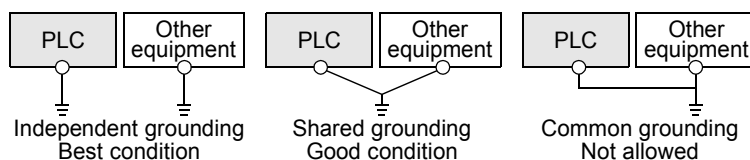
- ^{*1} Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD, FX3U-485-BD, FX2NC-485-ADP or FX3U-485ADP(-MB).
- ^{*2} Make sure to connect the **FG** terminal to the  (grounding) terminal in the PLC requiring Class-D grounding. If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.
- ^{*3} Make sure to provide a terminal resistor at the end of each line.
- The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor. Set the terminal resistor selector switch accordingly.
 - The FX0N-485ADP, FX2NC-485ADP, FX2N-485-BD and FX1N-485-BD are supplied together with terminal resistors.

4.6 Grounding

Grounding should be performed as stated below.

- The grounding resistance should be 100Ω or less.
- Independent grounding should be performed for best results.
When independent grounding can not be performed, perform "shared grounding" as shown in the following figure.

→ For details, refer to the Hardware Edition of each series.



- The grounding wire size should be AWG 14 (2 mm²) or larger.
- The grounding point should be close to the PLC, and all grounding wires should be as short as possible.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

5. Communication Setting in FX Programmable Controller

This chapter explains the communication setting method types and setting methods for computer link.

5.1 Communication Setting Methods

This section explains the communication setting methods and setting procedures in FX PLCs.

1. Setting method types

- 1) Specifying the setting using parameters in the sequence programming software:
Register the setting as parameters by executing communication setting on the personal computer screen using the sequence programming software, and transfer them to a PLC.
(This method using parameters is not available for FX2(FX), FX2C, or FX0N PLCs.)
- 2) Specifying the setting by writing data to special data registers:
Create a sequence program specifying the communication format, station number settings and time-out time setting, and then transfer the sequence program to a PLC.

Caution

A PLC operates in the same way regardless of the selected method shown above. If both methods are selected, priority is given to the method using parameters.

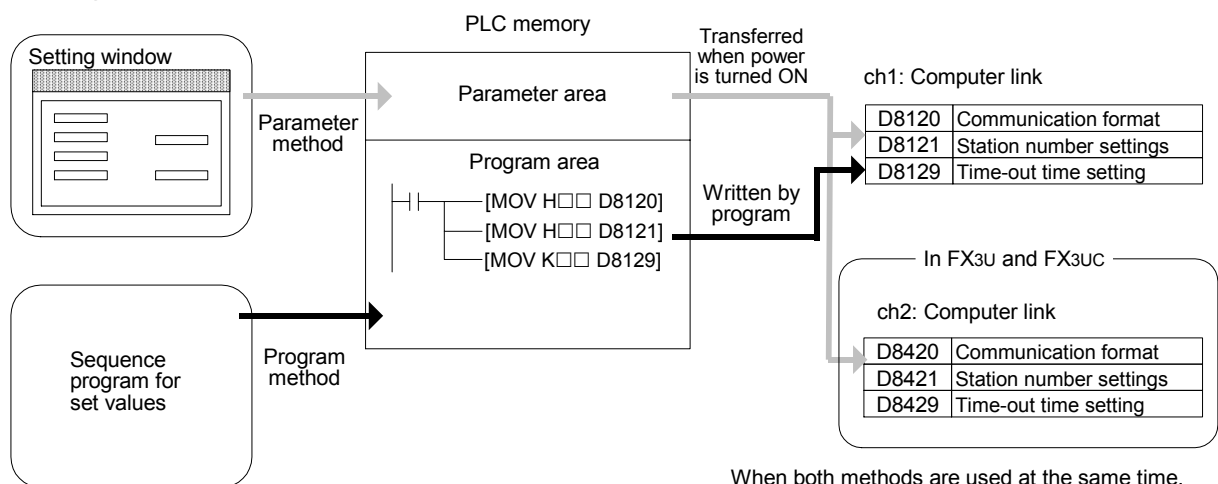
2. Communication setting method applicability for each FX Series

| FX Series | Specification using parameters | Specification using special data registers |
|---|--------------------------------|--|
| FX1S, FX1N, FX2N, FX3U(ch1), FX1NC, FX2NC, FX3UC(ch1) | ✓ (Recommended) | ✓ |
| FX3U(ch2), FX3UC(ch2) | ✓ | — |
| FX0N, FX2(FX), FX2C | — | ✓ |

→ For the detailed contents of special data registers, refer to Section 9.2.

→ Setting data write method to special data registers, refer to Section 9.3.

3. Setting data flow



When both methods are used at the same time, priority is given to the contents set in the parameter method.

4. Time at which the settings become valid

- 1) When specifying the setting using parameters:
When the PLC power is turned ON, the parameters set using the parameter setting window in the sequence programming software are automatically transferred to the PLC.
As soon as the parameters are transferred to the PLC, the setting becomes valid.
After the program (parameters) are transferred to the PLC, it is necessary to reboot the PLC's power.
- 2) When specifying the setting by writing data to special data registers:
Set the PLC mode from STOP to RUN, write the required data, reboot the PLC's power.
As soon as the PLC power is turned ON, the setting becomes valid.

5.2 Communication Setting Using Parameter Method (GX Developer)

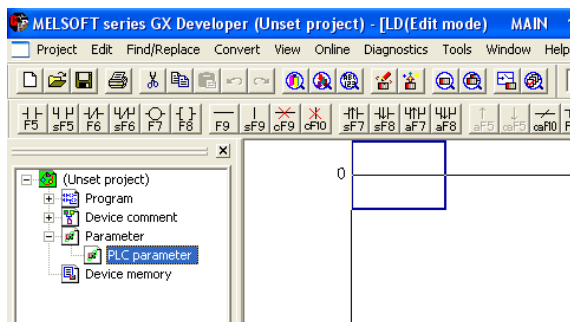
Communication settings may be changed via the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with GX Developer.

5.2.1 Operating procedure

With GX Developer open, follow the steps in this section to use the serial communication setting method.

1 Opening the parameter setting window

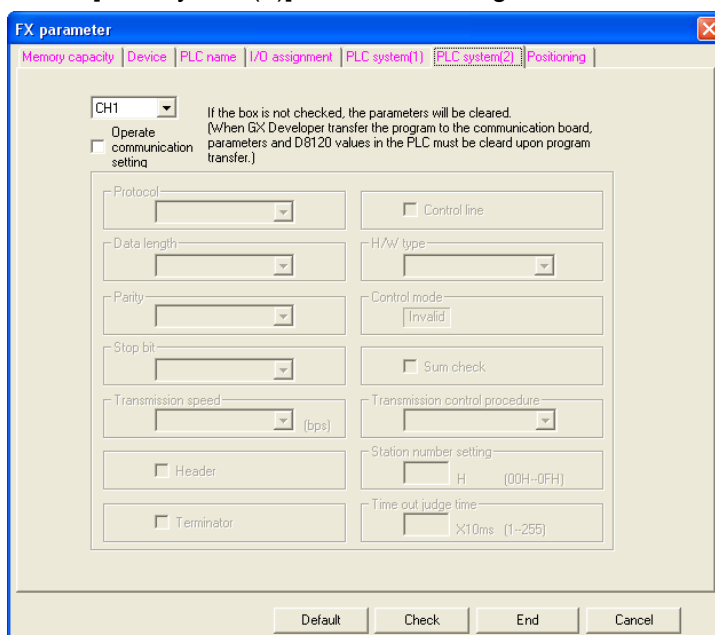
Double-click [Parameter]-[PLC parameter] from the project tree.



If the project tree is not displayed, select [View] - [Project data list] from the toolbar (to display a check mark on the left side).

2 Setting the serial communication (parameters)

Click the [PLC system(2)] tab on the dialog box.



3 Setting the serial communication (parameters)

Select a channel and check the box labeled "Operate communication setting" box, then adjust the parameters for that channel.

FX parameter

Memory capacity | Device | PLC name | I/O assignment | **PLC system(1)** | PLC system(2) | Positioning

CH1

☐ Operate communication setting

If the box is not checked, the parameters will be cleared.
(When GX Developer transfer the program to the communication board, parameters and D8120 values in the PLC must be cleared upon program transfer.)

Protocol: Dedicated protocol

Data length: 7bit

Parity: Odd

Stop bit: 1bit

Transmission speed: 9600 (bps)

☐ Header

☐ Terminator

☐ Control line

H/W type: RS-485

Control mode: Invalid

☐ Sum check

Transmission control procedure: Form4(with CR,LF)

Station number setting: 00 H (00H-0FH)

Time out judge time: 1 X10ms (1-255)

Default Check End Cancel

Adjust the settings on the personal computer to match those set here.

4 Writing parameters to the PLC

Select [Online] - [Write to PLC] from the toolbar.

Put a check mark (✓) next to "Parameter", and click [Execute].

5.3 Communication Settings Using Parameter Method (FXGP/WIN)

Communication settings may be changed by the parameter method with GX Developer and FXGP/WIN for Windows. This section describes how to change parameters with FXGP/WIN.
Ch2 cannot be set using FXGP/WIN.

5.3.1 Operating procedure

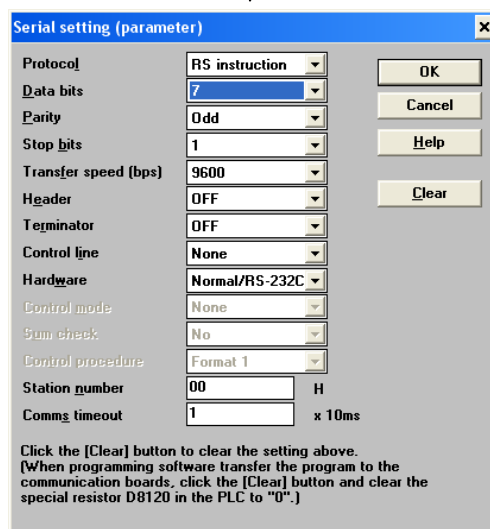
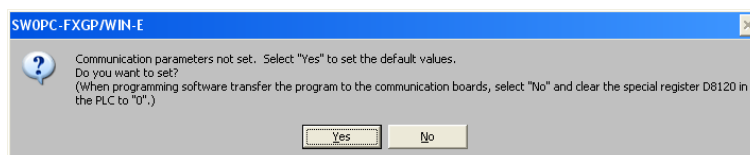
This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

1 Displaying the serial setting (parameter)

Select [Option] - [Serial setting (parameter)] from the toolbar.
The following dialog box appears according to absence/presence of parameter setting.

1. When there are no parameter settings

There are no communication settings. Click the [Yes] button.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

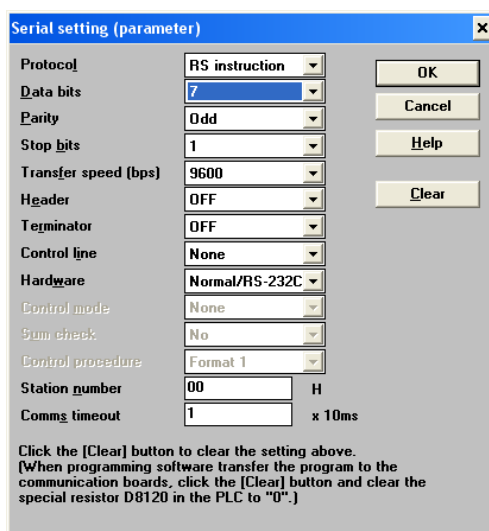
Remote Maintenance

Apx.

Discontinued models

2. When there are already parameter settings

The existing communication setting contents are displayed.



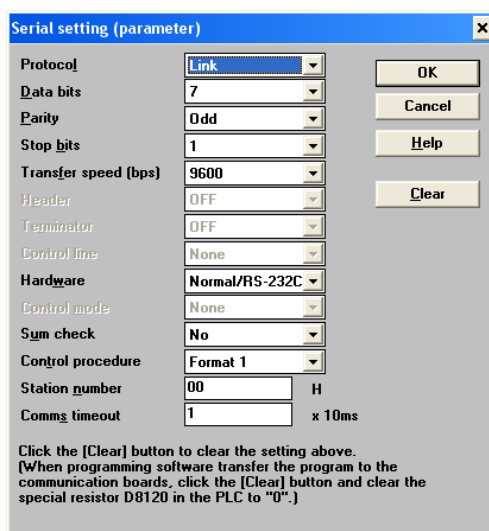
The 'Serial setting (parameter)' dialog box displays the following settings:

| | |
|----------------------|----------------|
| Protocol | RS instruction |
| Data bits | 7 |
| Parity | Odd |
| Stop bits | 1 |
| Transfer speed (bps) | 9600 |
| Header | OFF |
| Terminator | OFF |
| Control line | None |
| Hardware | Normal/RS-232C |
| Control mode | None |
| Sum check | No |
| Control procedure | Format 1 |
| Station number | 00 H |
| Comm. timeout | 1 x 10ms |

Click the [Clear] button to clear the setting above.
[When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".]

2 Adjusting serial setting (parameter)

Execute the communication setting as shown below.



The 'Serial setting (parameter)' dialog box displays the following adjusted settings:

| | |
|----------------------|----------------|
| Protocol | Link |
| Data bits | 7 |
| Parity | Odd |
| Stop bits | 1 |
| Transfer speed (bps) | 9600 |
| Header | OFF |
| Terminator | OFF |
| Control line | None |
| Hardware | Normal/RS-232C |
| Control mode | None |
| Sum check | No |
| Control procedure | Format 1 |
| Station number | 00 H |
| Comm. timeout | 1 x 10ms |

Click the [Clear] button to clear the setting above.
[When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".]

Adjust the settings on the personal computer to match those set here.

3 Writing a sequence program (parameters) to the PLC

Select [PLC] - [Transfers] - [Write] from the toolbar, and click [OK].

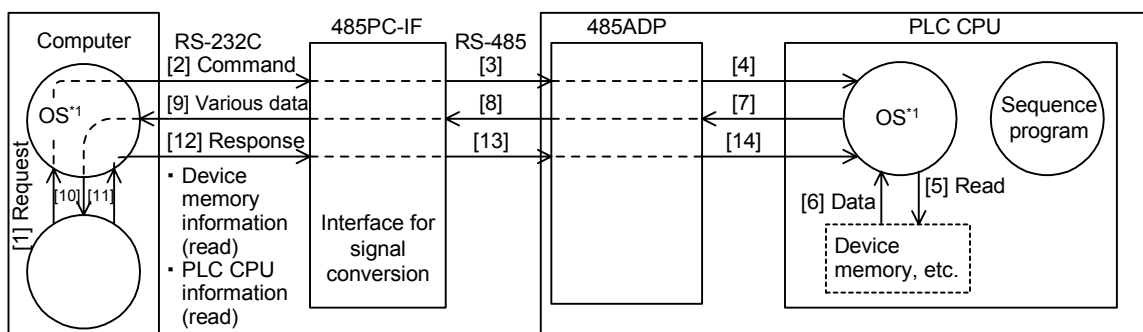
6. Control Procedures and Setting Methods

6.1 Data Flow by Link

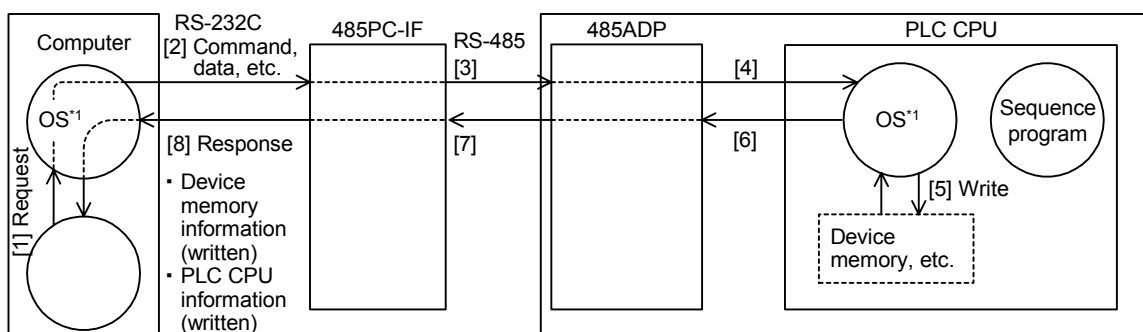
The figures below show images of data flow achieved when data is read from or written to a PLC CPU and the status is controlled.

In the case of communication in accordance with RS-232C, ignore "485PC-IF" and regard "485ADP" as "232ADP".

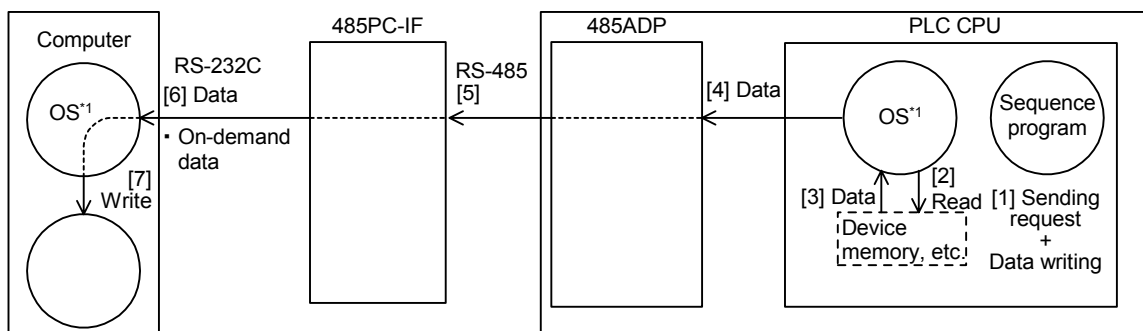
1. When the computer reads data from the PLC



2. When the computer writes data to the PLC



3. When the PLC sends data to the computer (on-demand function)



*1. The OS (standing for "Operating System") indicates the software used to efficiently operate the resources including the CPUs, memories, terminals, files, and networks using user programs, etc.

6.2 Important Points in Computer Link

This section explains important points to be understood before creating programs for computer link.

6.2.1 Operations of PLC caused by data transfer

The PLC operations and scan time using computer link are as described below.

1. While the PLC is in RUN mode

For requests from the computer, the PLC executes access for one request during each END processing. Sending and receiving are executed as interrupts.

Accordingly, when sending and receiving are executed, the scan time is longer by about 10%. The scan time can be checked in D8010 to D8012 in the PLC.

2. Condition in which the transfer sequence in the PLC is initialized

The transfer sequence in the PLC is initialized in the following cases:

- When the power is turned ON
- When regular sending/receiving is completed
- When the control code "EOT" or "CL" is received in each format
- When the control code "NAK" is sent
- When the time-out time setting is detected

→ For details on the time-out time setting, refer to Subsection 6.4.4.

3. Occurrence of framing error in the computer

When a commercial interface in accordance with RS-485 is used in the computer, a framing error may occur while nothing is sent from the PLC to the computer depending on the interface in the computer.

To cope with this nonconformity, let the computer ignore any data until the PLC sends STX, ACK or NAK.

4. Response of "NAK" from the PLC

When an error is detected, the PLC sends NAK to the computer.

5. Command sending from the computer

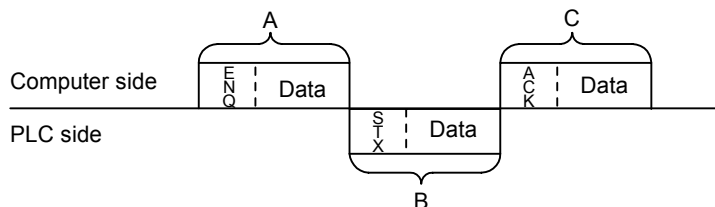
When sending commands from the computer to the PLC, wait for two scan times^{*1} or more after the PLC finishes receiving data in response to the previous command, and then send the next command.

*1. 100 μ s or more in the FX2N, FX3U, FX2NC, and FX3UC Series

6.3 How to Understand Control Procedure

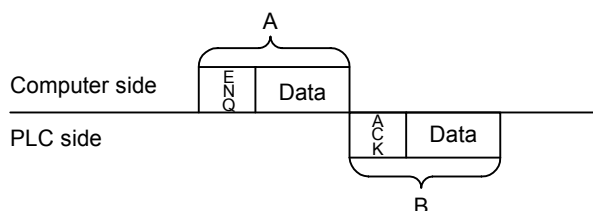
This section explains how to understand the transfer data shown in the later description of each function.

1. When the computer reads data from the PLC (computer ← PLC)



- [1] Parts A and C indicate transfer from the computer to the PLC.
- [2] Part B indicates transfer from the PLC to the computer.
- [3] Create a program in the computer so that each data is transferred in turn from the left to the right, and that the data is transferred in the order "A → B → C" as a whole.
(Example: In the part A, data is transferred in turn from the right starting from "ENQ".)

2. When the computer writes data to the PLC (computer → PLC)



- [1] Part A indicates transfer from the computer to the PLC.
- [2] Part B indicates transfer from the PLC to the computer.
- [3] Create a program in the computer so that each data is transferred in turn from the left to the right, and that the data is transferred in the order "A → B" as a whole.
(Example: In the part A, data is transferred in turn from the right starting from "ENQ".)

6.4 Basic Formats of Dedicated Protocol

There are two types of control procedures in dedicated protocols.

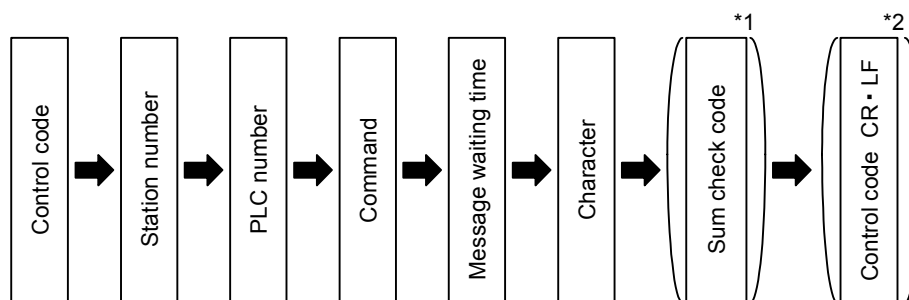
CR and LF are not added to each block in format 1. CR and LF are added to each block in format 4.

(The format names are the same as those used in the computer link units for A Series PLCs.)

This section explains the contents of control procedures and the contents of each item specified in the control procedures in each format.

The basic format of control procedures (protocols) is as shown below:

→ For details, refer to Subsections 6.4.1 and 6.4.2.



- *1. Whether or not the sum check code is added can be specified using a parameter.
- *2. Whether or not the control code is added can be specified by selecting the protocol type.

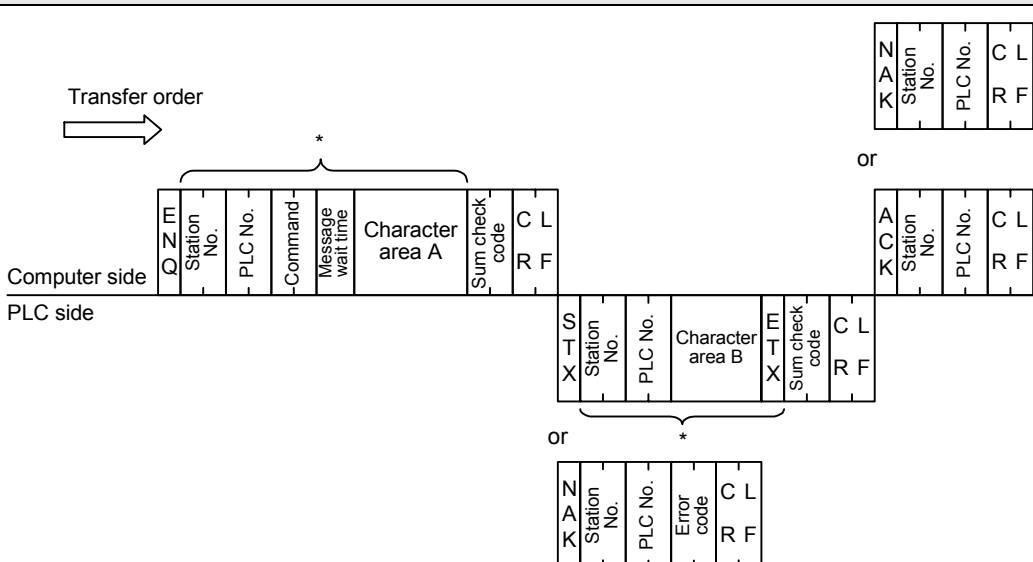
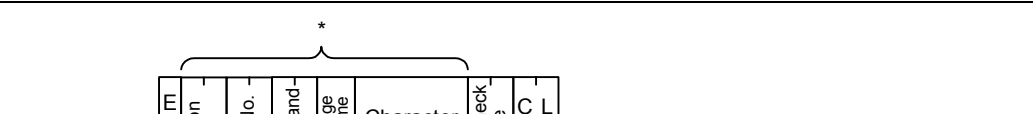
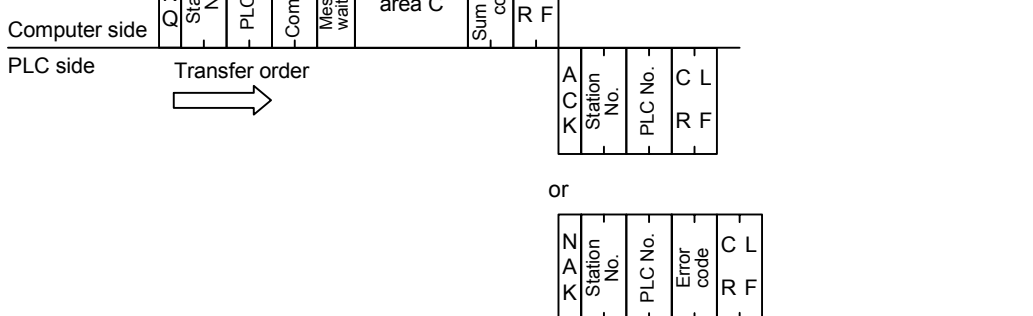
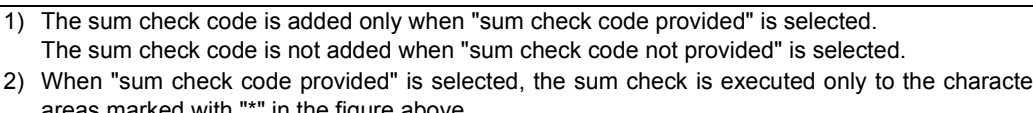
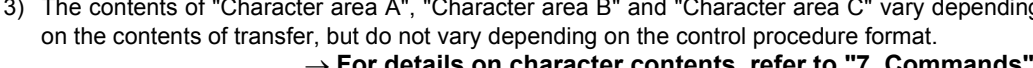
6.4.1 Control procedure format 1

The table below shows the control procedure for format 1.

| Description | Control procedure (protocol) |
|-----------------------------------|---|
| When computer reads data from PLC | <p>The diagram illustrates the data reading procedure. On the computer side, a 'Transfer order' is sent to the PLC. The data frame consists of: QZM, Station No., PLC No., Command, Message wait time, Character area A, and Sum check code. On the PLC side, the response frame includes: STX, Station No., PLC No., Character area B, and ETX. Both sides have an 'or' option for a frame with ACK, Station No., PLC No., and either a Sum check code or an Error code.</p> |
| When computer writes data to PLC | <p>The diagram illustrates the data writing procedure. On the computer side, a 'Transfer order' is sent to the PLC. The data frame consists of: QZM, Station No., PLC No., Command, Message wait time, Character area C, and Sum check code. On the PLC side, the response frame includes: ACK, Station No., and PLC No. Both sides have an 'or' option for a frame with NAK, Station No., PLC No., and an Error code.</p> |
| Remarks | <ol style="list-style-type: none"> 1) The sum check code is added only when "sum check code provided" is selected. The sum check code is not added when "sum check code not provided" is selected. 2) When "sum check code provided" is selected, the sum check is executed only to the character areas marked with "*" in the figure above. 3) The contents of "Character area A", "Character area B" and "Character area C" vary depending on the contents of transfer, but do not vary depending on the control procedure format. → For details on character contents, refer to "7. Commands". |

6.4.2 Control procedure format 4

The table below shows the control procedure for format 4.

| Description | Control procedure (protocol) |
|-----------------------------------|--|
| When computer reads data from PLC | <p>Transfer order →</p> <p>Computer side: </p> <p>or</p> <p>Computer side: </p> |
| When computer writes data to PLC | <p>Computer side: </p> <p>Transfer order →</p> <p>PLC side: </p> <p>or</p> <p>PLC side: </p> |
| Remarks | <p>1) The sum check code is added only when "sum check code provided" is selected. The sum check code is not added when "sum check code not provided" is selected.</p> <p>2) When "sum check code provided" is selected, the sum check is executed only to the character areas marked with "*" in the figure above.</p> <p>3) The contents of "Character area A", "Character area B" and "Character area C" vary depending on the contents of transfer, but do not vary depending on the control procedure format.</p> <p>→ For details on character contents, refer to "7. Commands".</p> |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

6.4.3 Contents of set items in each control procedure (protocol)

This subsection explains the contents of the data used in each control procedure.

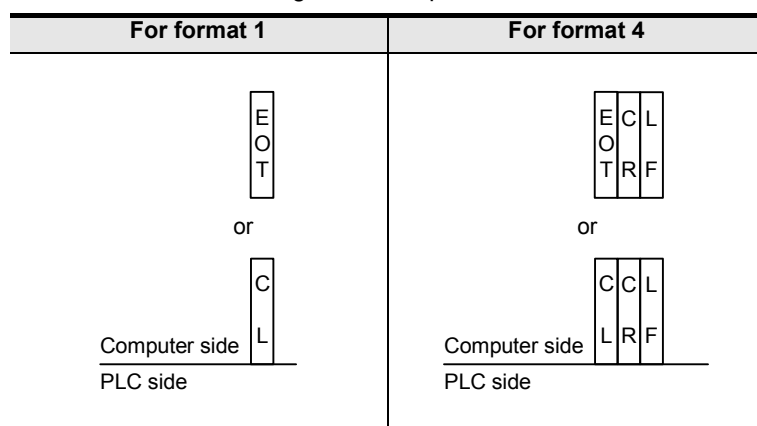
1. Control codes

The table below shows control codes.

| Signal name | Code | Description |
|-------------|------|---------------------|
| STX | 02H | Start of Text |
| ETX | 03H | End of Text |
| EOT | 04H | End of Transmission |
| ENQ | 05H | Enquiry |
| ACK | 06H | Acknowledge |

| Signal name | Code | Description |
|-------------|------|----------------------|
| LF | 0AH | Line Feed |
| CL | 0CH | Clear |
| CR | 0DH | Carriage Return |
| NAK | 15H | Negative Acknowledge |

- 1) When the PLC receives ENQ or ACK, it initializes the transfer sequence and begins receiving.
- 2) When the PLC receives EOT or CL as shown below, it initializes the transfer sequence. At this time, the PLC gives no response.

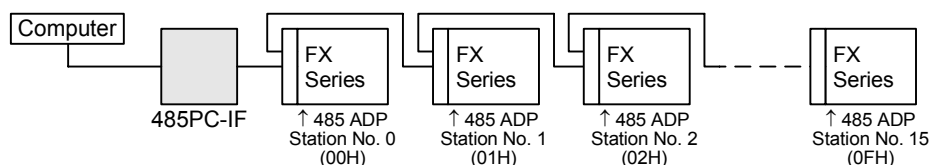


2. Station number

The station number indicates a number provided in each PLC to determine to which PLC the computer accesses.

The station number is specified in hexadecimal.

- In FX Series PLCs, set the station number using parameters. The setting range is from 00H to 0FH.
- For the station number setting method in A Series PLCs, refer to the respective A Series PLC manual.



In FX2(FX), FX2C and FX0N PLCs, set a value to D8121.



→ For details on the program, refer to Section 9.3.

Cautions on setting station numbers

- 1) Do not overlap station numbers. If the same number is set for two or more stations, the transfer data is destroyed and normal communication is not possible.
- 2) It is not necessary to set consecutive station numbers as shown in the setting example above. Any station numbers in the setting range (00H to 0FH) are applicable. (Examples: Station numbers may be set arbitrarily. Some station numbers may be skipped.)

3. PLC number

The PLC number is used to identify a PLC to be accessed when computer link is combined with the MELSECNET (II) or MELSECNET/B in A Series PLCs. The PLC number of each FX Series PLC is fixed to "FFH", and converted into two-digit ASCII code.

When the on-demand function is used, however, the PLC number is automatically changed to "FEH" by the PLC.

For the PLC number of an A Series PLC used together with the MELSECNET (II) or MELSECNET/B, refer to the respective A Series PLC manual.

4. Command

A command specifies the contents of access executed by the computer to a PLC.

A command is converted into a two-digit ASCII code.

→ For an explanation of commands, refer to Chapter 7.

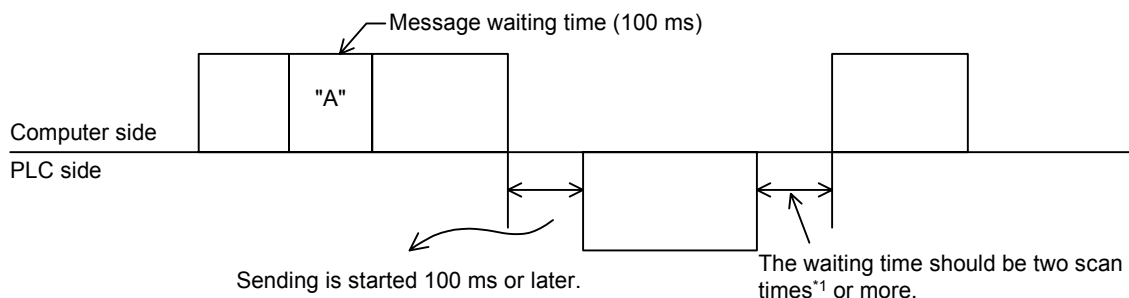
5. Message waiting time

The message waiting time should be specified because some computers require more time before receiving additional data. Set the waiting time according to the specifications of each computer.

Set the waiting time within the range from 0 to 150 ms in 10-ms units. 10 ms is handled as "1H", and a value ranging from "0H (0)" to "FH (15)" is converted into a one-digit ASCII code.

When executing communication using the 485PC-IF in a 1-to-N system adopting the one-pair wiring, make sure to set the message waiting time to 70 ms (7) or more. When the scan time of a PLC in the system exceeds 70 ms, set the message waiting time to the maximum scan time or higher.

Example: When the message waiting time is set to 100 ms



*1. 100 μ s in the FX2N, FX3U, FX2NC, and FX3UC Series

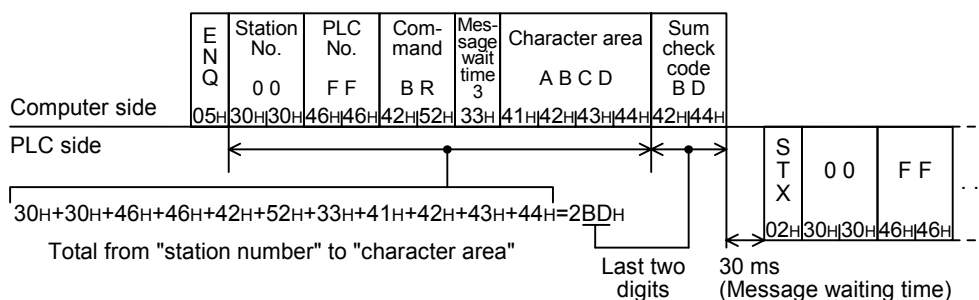
6. Sum check code

The sum check code indicates a two-digit ASCII code converted from the least significant byte (8-bit) of the sum check target data added as hexadecimal data.

Using the FX PLC parameters, set whether or not the sum check code is added in the message.

- When "sum check code provided" is selected, the sum check code is added in the message during sending. During receiving, the sum check code is compared with the value calculated from the received data to check the received data.
- When "sum check code not provided" is selected, the sum check code is not added, so the received data is not checked either. A calculation example of the sum check code is shown below.

Example: When the station number "0", PLC number "FF", command "BR (device memory batch read)," message waiting time "30 ms" and data "ABCD" are transferred in format 1, the sum check code value is as shown below:



6.4.4 Time-out time setting

When the receiving of data from the computer is interrupted and is not restarted within the preset time (time-out time setting), the PLC regards the situation as a timeout error and initializes the transfer sequence.

1. Time-out time setting range

The time-out time setting can be set using parameters or sequence program.

In the FX2(FX), FX2C, and FX0N Series, however, the parameter setting method is not applicable.

When setting the time-out time setting in a sequence program, write a value for ch1 to D8129, and a value for ch2 (in the FX3U and FX3UC Series) to D8429 (unit: 10 ms).

The setting range is different between the parameter method and the sequence program method.

1) Details of setting range

| FX Series | | Setting range in parameter | Setting range in sequence program (D8129 and D8429) |
|-------------------|-----|----------------------------|---|
| FX2(FX), FX2C | | Not applicable | 1 to 3276 (10 to 32760 ms) |
| FX0N | | Not applicable | 1 to 255 (10 to 2550 ms) |
| FX1S, FX1N, FX1NC | | 1 to 255 (10 to 2550 ms) | 1 to 255 (10 to 2550 ms) |
| FX2N, FX2NC | | 1 to 255 (10 to 2550 ms) | 1 to 3276 (10 to 32760 ms) |
| FX3U, FX3UC | ch1 | 1 to 255 (10 to 2550 ms) | 1 to 3276 (10 to 32760 ms) |
| | ch2 | 1 to 3276 (10 to 32760 ms) | 1 to 3276 (10 to 32760 ms) |

When the set value is "0", it is handled as "100 ms".

2) Example of setting program

When setting the time-out time setting to 60 ms

```

M8002
|---|---[ MOV K6 D8129 ]---|

```

→ For details on the program, refer to Section 9.3.

2. Caution on programming

The time-out time setting is not updated until the next character data is received. Set a time to receive a character according to the transmission speed (baud rate).

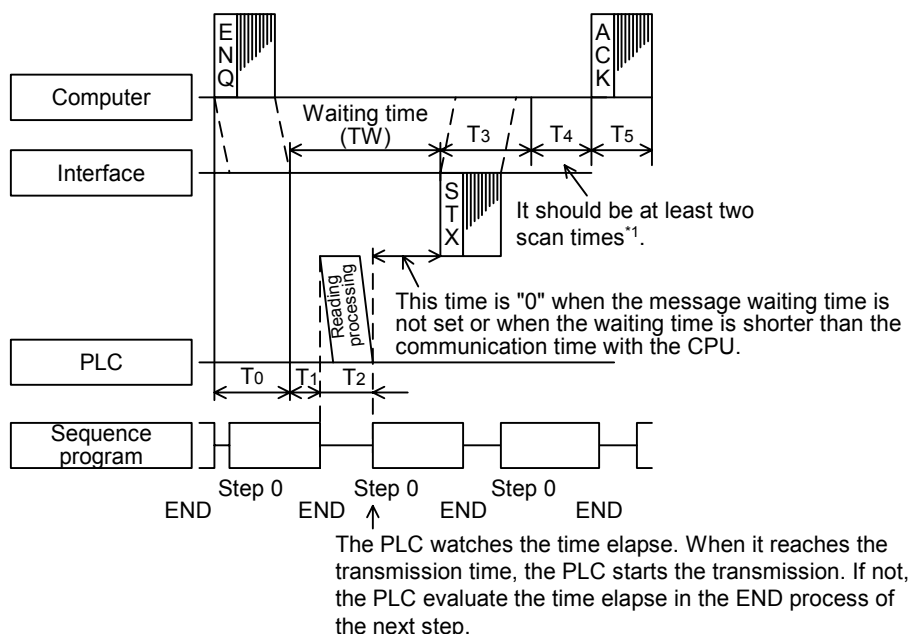
For one character (12-bit), the minimum set value of the time-out time setting is as shown below:

| Baud rate (bps) | Time to receive one character (ms) | Time-out time setting (minimum set value) |
|-----------------|------------------------------------|---|
| 300 | 40 | 50 ms (5) |
| 600 | 20 | 30 ms (3) |
| 1200 | 10 | 20 ms (2) |
| 2400 | 5 | 10 ms (1) |
| 4800 | 2.5 | 10 ms (1) |
| 9600 | 1.25 | 10 ms (1) |
| 19200 | 0.625 | 10 ms (1) |

6.5 Transfer Sequence Time Chart and Communication Time

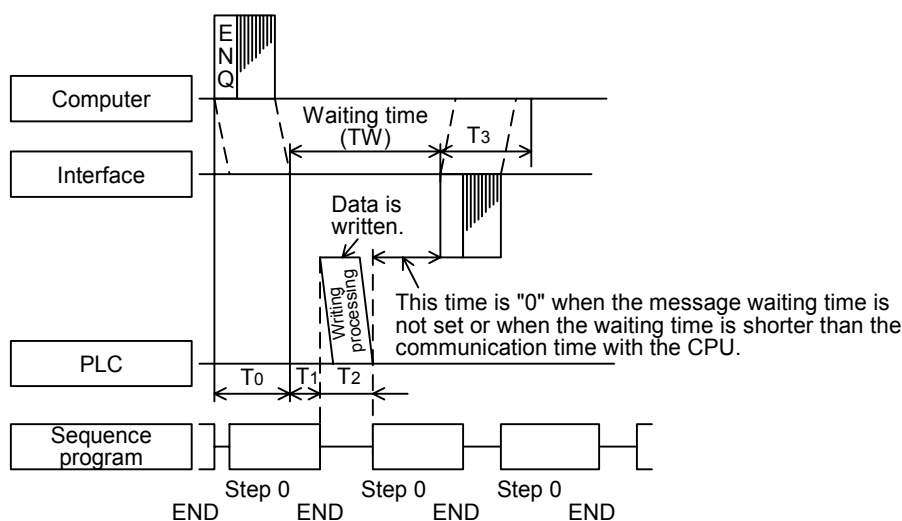
This section explains the communication time chart between the computer and the PLC. As shown in the figures below, communication between the computer and the PLC is always executed after "END". The scan time is extended by the communication time.

6.5.1 When computer reads data from PLC



*1. 100 μ s in the FX2N, FX3U, FX2NC, and FX3UC Series

6.5.2 When computer writes data to PLC



6.5.3 Transfer time in transfer sequence

This subsection explains how to calculate the approximate time after the computer starts data transfer and the PLC gives a response until all communication is completed.
For the contents of T0 to T5, refer to the previous page.

1. When the computer reads data from the PLC

Communication time = T0 + (T1 + Longer time between T2 and TW) + T3 + T4 + T5

$$T0, T3, T5 = \frac{1}{\text{Baud rate}} \times \text{Number of bits in one character} \times \text{Number of characters}$$

$(1 + 7(8) + 0(1) + 1(2))$
 Start bit Data length (7 or 8) Parity bit (0 or 1) Stop bit (1 or 2)

- T1: Maximum one scan time (Because data is read from the PLC during the END processing while the PLC is in RUN mode, reading requires up to one scan time depending on the sending timing. Reading requires about 1 ms while the PLC is in STOP mode.)
 T2: END processing time in the PLC executing data transfer
 T4: Scan time or longer (In the case of wiring in the 1-to-N configuration, T4 should be longer than the time-out time setting (D8129) extended by one scan time.)
 TW: Message waiting time

2. When the computer writes data to the PLC

Communication time = T0 + (T1 + Longer time between T2 and TW) + T3

$$T0, T3 = \frac{1}{\text{Baud rate}} \times \text{Number of bits in one character} \times \text{Number of characters}$$

$(1 + 7(8) + 0(1) + 1(2))$
 Start bit Data length (7 or 8) Parity bit (0 or 1) Stop bit (1 or 2)

- T1: Maximum one scan time (Because data is written to the PLC during the END processing while the PLC is in RUN mode, writing requires up to one scan time depending on the sending timing. Writing requires about 1 ms while the PLC is in STOP mode.)
 T2: END processing time in the PLC executing data transfer
 TW: Message waiting time

6.6 Transfer Data in Character Area

This section explains the transfer data in the character area sent and received between the computer and a PLC using each command.

The transfer data explained below is handled as the character area B in reading and the character area C in writing.

→ For character areas, refer to Subsections 6.4.1 and 6.4.2.

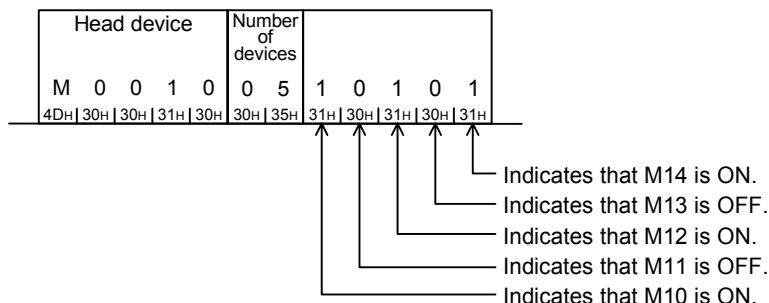
6.6.1 When bit device memory is read or written

The bit device memory is handled in 1-bit (1-point) units or in 1-word (16-point) units.
The transfer data in each case is explained below.

1) In 1-bit (1-point) units

When the bit device memory is handled in 1-bit (1-point) units, a specified number of devices starting from the specified head device are expressed in turn from the left end in "1 (31H)" for the ON status or "0 (30H)" for the OFF status.

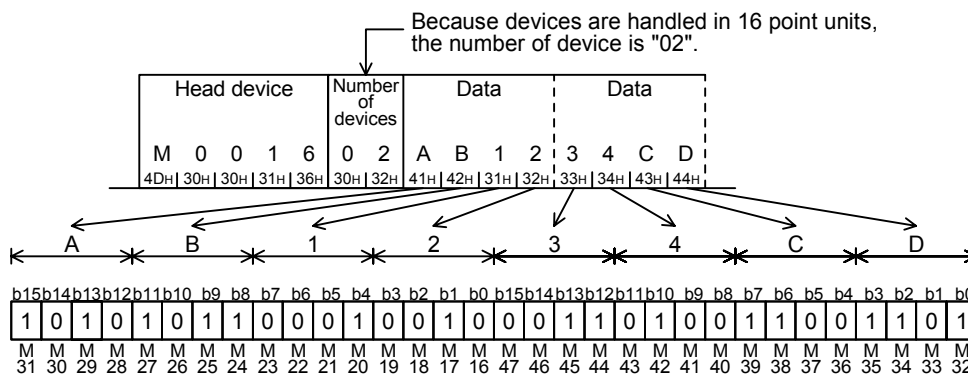
Example: When indicating the ON/OFF status of five devices starting from M10



2) In 1-word (16-point) units

When the bit device memory is handled in 1-word (16-point) units, one word is expressed in 4-bit units in turn from the most significant bit in hexadecimal.

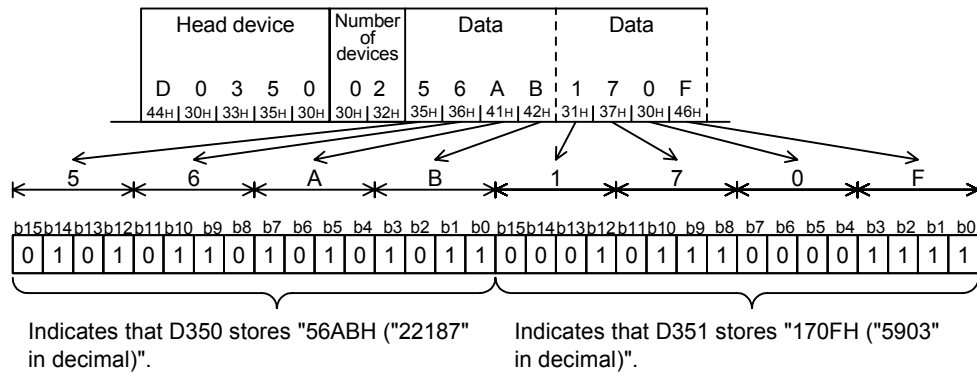
Example: When indicating the ON/OFF status of 32 devices starting from M16



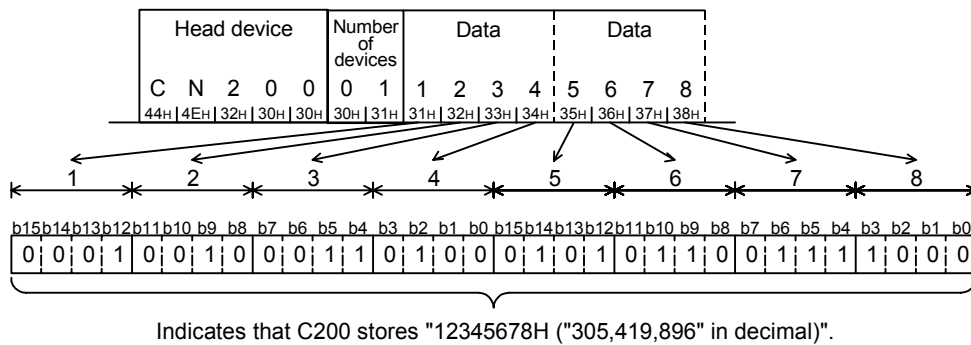
6.6.2 When word device memory is read or written

In the case of word device memory, one word is expressed in 4-bit units in turn from the most significant bit in hexadecimal.

Example 1: When indicating the contents stored in the data registers D350 and D351



Example 2: When indicating the contents stored in the 32-bit counter C200^{*1}



*1. For indicating the current value of C200, use "CN200".

7. Commands

This chapter explains specification methods and specification examples of commands in dedicated protocols used in computer link communication type.

For control procedures in dedicated protocols, refer to "6. Control Procedures and Setting Methods".

The table below shows a reference section for each command.

| Command | Contents of processing | Applicable PLC | | Reference section |
|---------|--|----------------|---|-------------------|
| | | FX3U, FX3UC | FX2(FX), FX2C, FX1S, FX0N, FX2N, FX1N, FX2NC, FX1NC | |
| BR | Reads bit devices in 1-point units. | ✓ | ✓ | 7.1 |
| WR | Reads bit devices in 16-point units, or word devices in 1-point units. | ✓ | ✓ | 7.2 |
| QR | Reads bit devices in 16-point units, or word devices in 1-point units. | ✓ | — | 7.3 |
| BW | Writes bit devices in 1-point units. | ✓ | ✓ | 7.4 |
| WW | Writes bit devices in 16-point units, or word devices in 1-point units. | ✓ | ✓ | 7.5 |
| QW | Writes bit devices in 16-point units, or word devices in 1-point units. | ✓ | — | 7.6 |
| BT | Specifies bit devices arbitrarily in 1-point units, and sets or resets them (forcibly sets them to ON or OFF). | ✓ | ✓ | 7.7 |
| WT | Specifies bit devices arbitrarily in 16-point units, and sets or resets them (forcibly sets them to ON or OFF). Or specifies word devices arbitrarily in 1-point units, and writes data to them. | ✓ | ✓ | 7.8 |
| QT | Specifies bit devices arbitrarily in 16-point units, and sets or resets them (forcibly sets them to ON or OFF). Or specifies word devices arbitrarily in 1-point units, and writes data to them. | ✓ | — | 7.9 |
| RR | Sets a PLC to RUN mode in remote control. | ✓ | ✓ | 7.10 |
| RS | Sets a PLC to STOP mode in remote control. | ✓ | ✓ | |
| PC | Reads the PLC model name code. | ✓ | ✓ | 7.11 |
| GW | Turns the global function ON or OFF in all linked PLCs. | ✓ | ✓ | 7.12 |
| — | Offers the on-demand function (by which a PLC gives a sending request), and does not offer any command. | ✓ | ✓ | 7.13 |
| TT | Returns received characters back to the computer as they are. | ✓ | ✓ | 7.14 |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (FSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

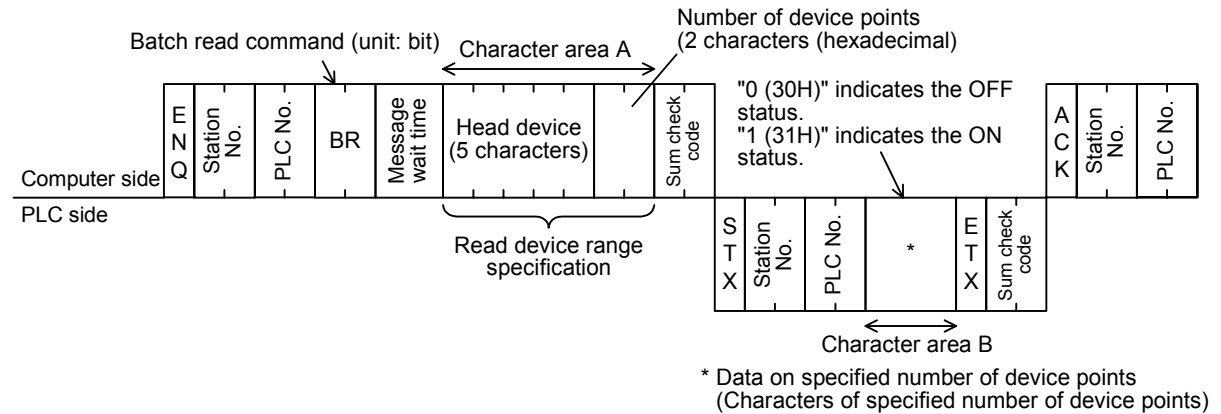
Discontinued models

7.1 BR Command [Reads Device Memory in 1-Bit Units]

This section explains the control procedure specification method and specification example when the bit device memory is read all at once.

1. Specification method

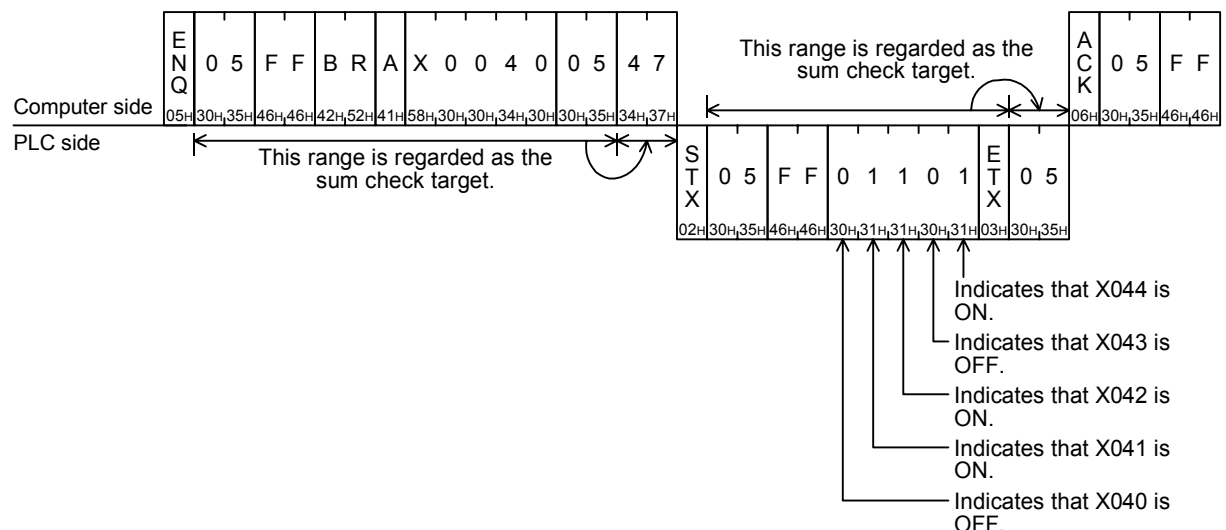
The specification method in the control procedure format 1 is shown below:



- Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 256^{*1}$ (Use "00H" to specify 256 points.)
 - Head device number + Number of device points - 1 \leq Maximum device number
- Express the station number, PLC number, number of device points and sum check code in hexadecimal.
 - *1. 54 in the FX1S and FX0N Series

2. Specification example

When reading the contents of five devices X040 to X044 in the PLC whose station number is 5 (while the message waiting time is set to 100 ms)
(When X040 and X043 are OFF and X041, X042 and X044 are ON)



Important point

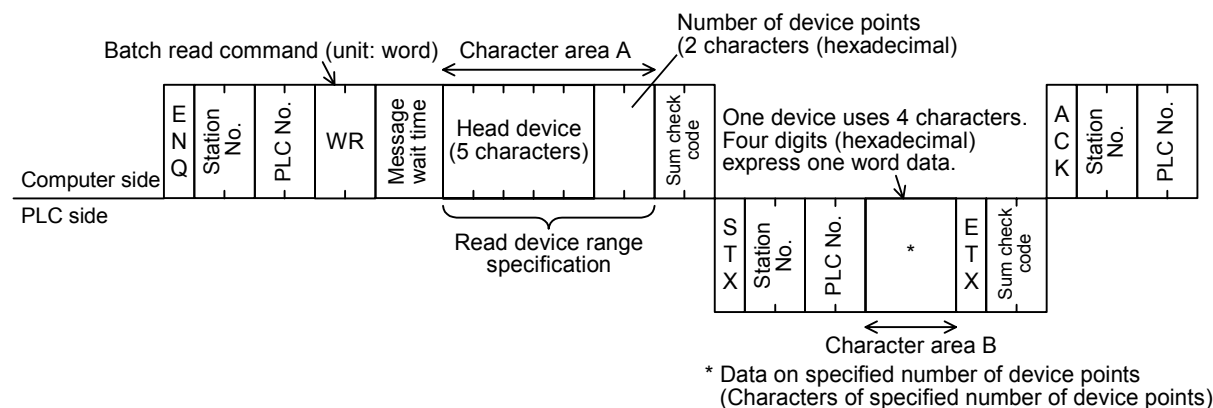
The message wait time is specified in 10-ms units within the range from 0 to 150 ms, and expressed in hexadecimal within the range from 0 to FH. For example, "100 ms" is expressed as "A".

7.2 WR Command [Reads Device Memory in 1-Word Units]

This section explains the control procedure specification method and specification examples when the word device memory is read all at once or when the bit device memory is read (in 16-point units) all at once.

1. Specification method

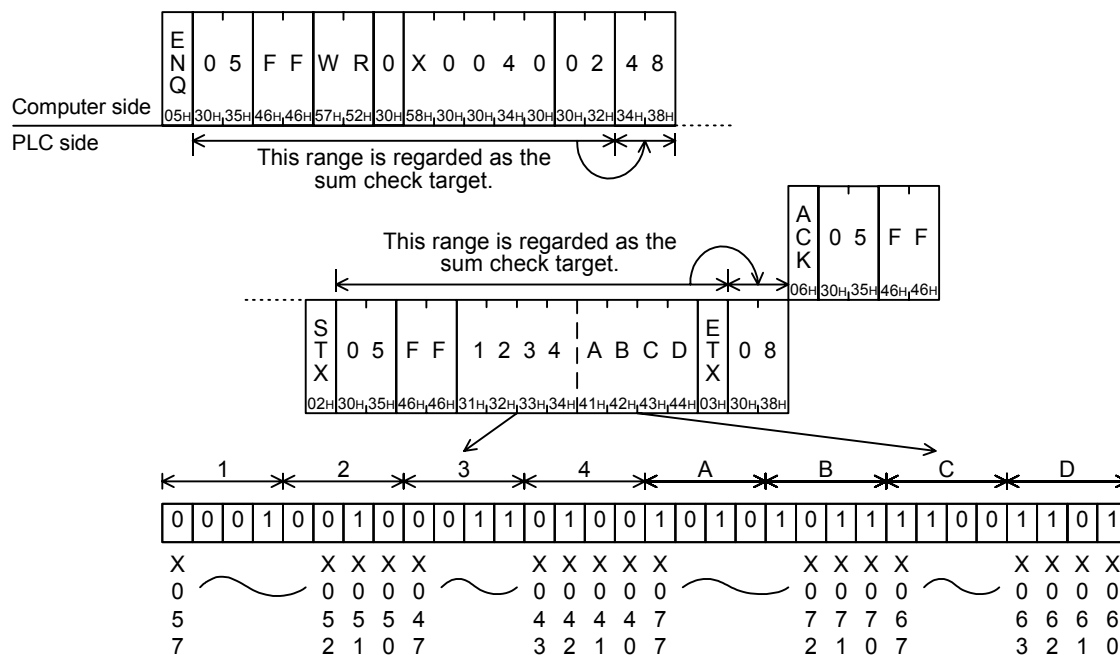
The specification method in the control procedure format 1 is shown below:



- Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 64^{*1}$ (32^{*1} in case of bit devices)
 - Head device number + Number of device points ("Number of devices \times 16" in case of bit devices) - 1 \leq Maximum device number
 - When 32-bit devices (CN200 to CN255) are read, one device point is handled as two word data. Accordingly, up to 32 device points^{*2} can be specified.
- Express the station number, PLC number, number of device points and sum check code in hexadecimal.
 - *1. Up to 13 device points in the FX1s and FX0N Series
 - *2. Up to 6 device points in the FX1s and FX0N Series

2. Specification examples

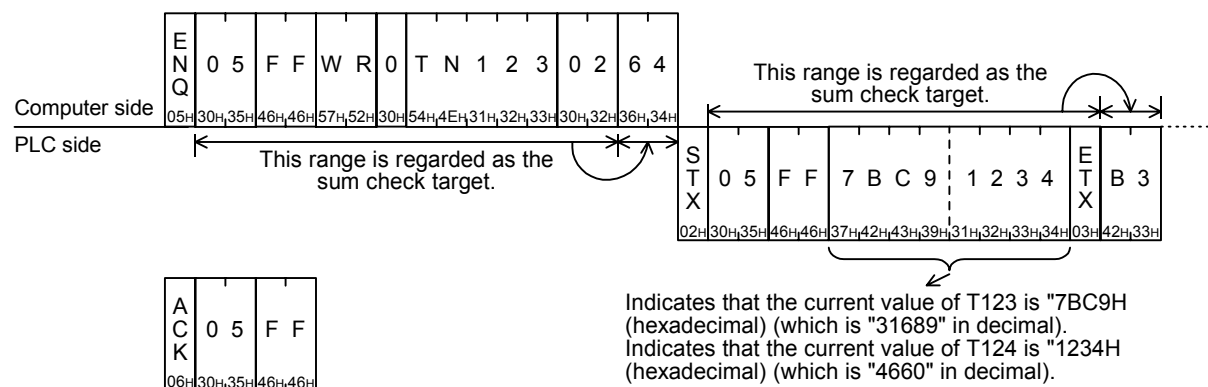
Example 1: When reading the contents of thirty-two devices from X040 to X077 in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)



Important point

The WR command handles data in 1-word units. When reading thirty-two devices from X040 to X077, specify the number of device points as "02" (One point specifies 16 devices.)

Example 2: When reading the present value of two devices from T123 and T124 in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)

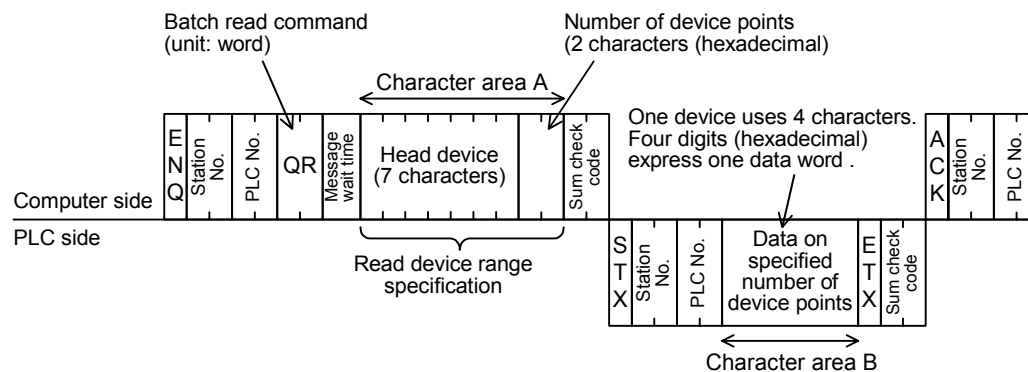


7.3 QR Command [Reads Device Memory in 1-Word Units]

This section explains the control procedure specification method and specification examples when the word device memory is read all at once or when the bit device memory is read (in 16-point units) all at once.

1. Specification method

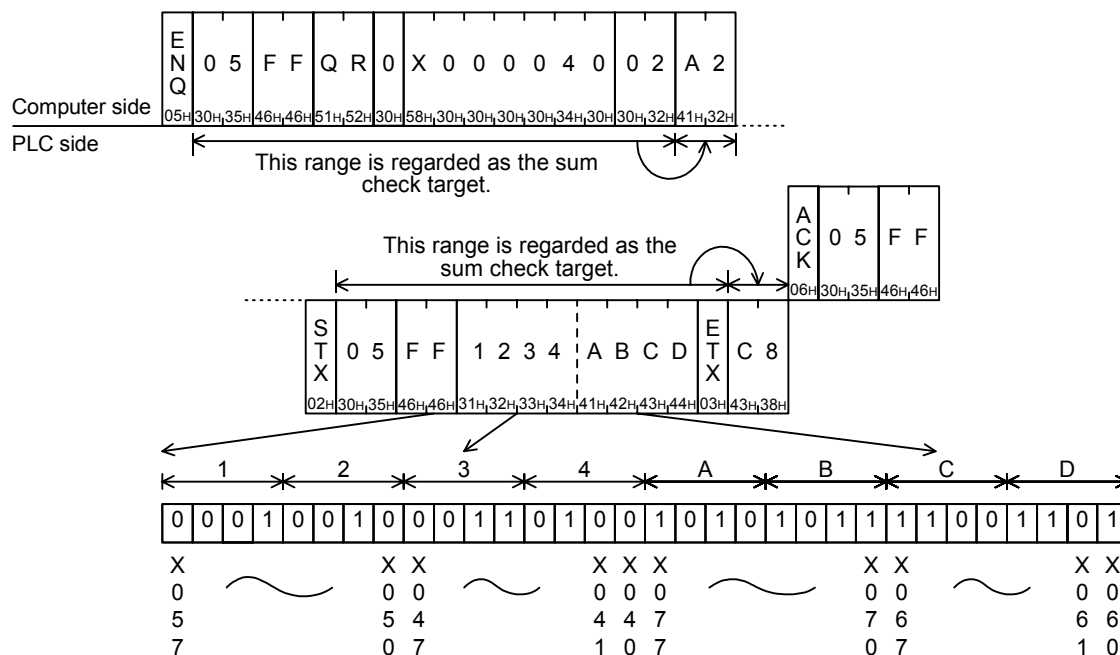
The specification method in the control procedure format 1 is shown below:



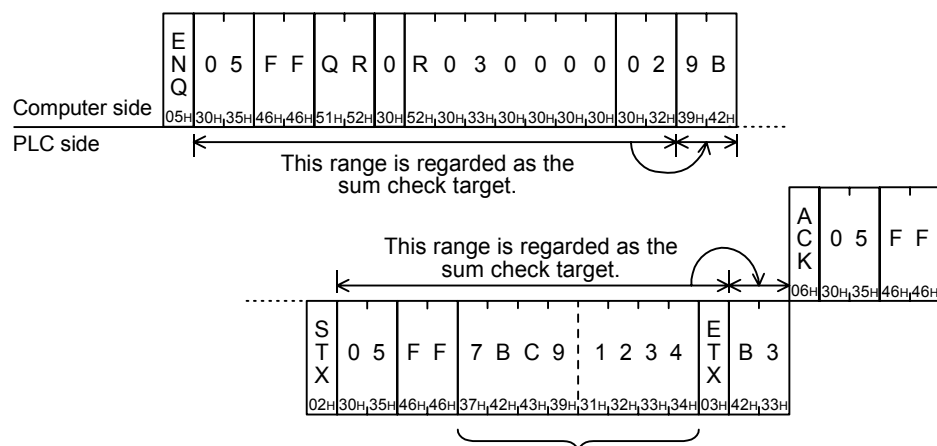
- 1) This command is available only in FX3U and FX3UC PLCs.
- 2) Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 64$ (32 for bit devices)
 - Head device number + Number of device points ("Number of devices \times 16" for bit devices) - 1 \leq Maximum device number
 - When 32-bit devices (CN00200 to CN00255) are read, one device point is handled as two word data. Accordingly, up to 32 device points can be specified.
- 3) Express the station number, PLC number, number of device points and sum check code in hexadecimal.

2. Specification examples

Example 1: When reading the contents of thirty-two devices from X040 to X077 in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)



Example 2: When reading the contents of two devices from R30000 to R30001 in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)



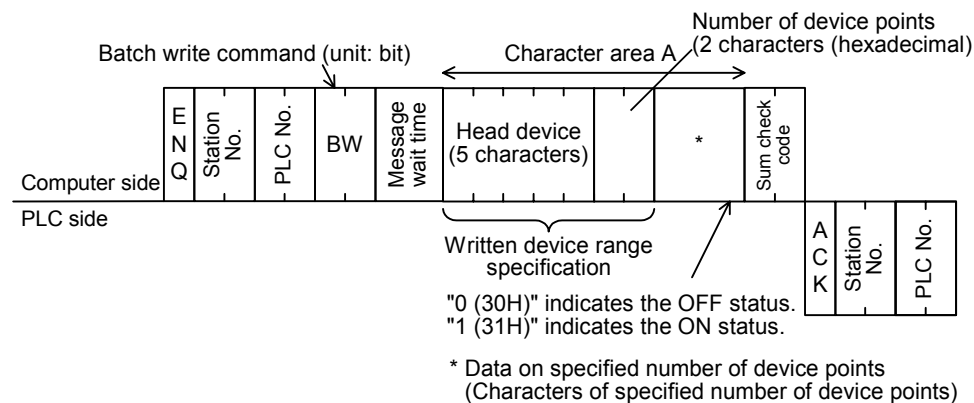
Indicates that the value of R30000 is "7BC9H" (hexadecimal)
(which is "31689" in decimal).
Indicates that the value of R30001 is "1234H" (hexadecimal)
(which is "4660" in decimal).

7.4 BW Command [Writes Device Memory in 1-Bit Units]

This section explains the control procedure specification method and shows a specification example when the bit device memory is written all at once.

1. Specification method

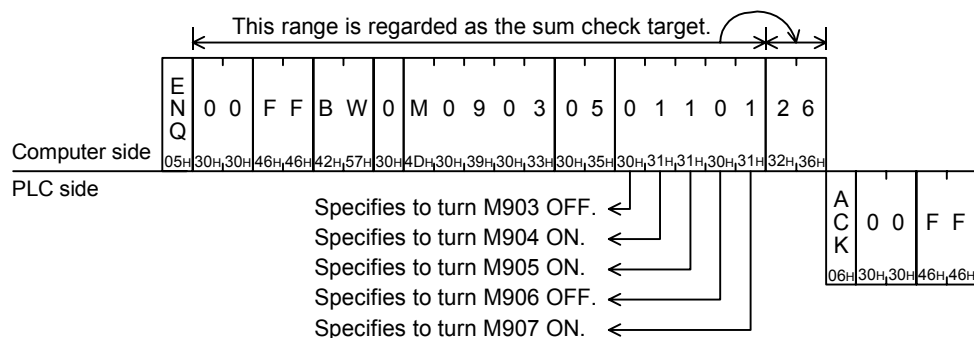
The specification method in the control procedure format 1 is shown below:



- Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 160^{*1}$
 - Head device number + Number of device points - 1 \leq Maximum device number
 - Express the station number, PLC number, number of device points and sum check code in hexadecimal respectively.
- *1. 46 in the FX1S and FX0N Series

2. Specification example

When writing data to five devices from M903 to M907 in the PLC whose station number is 0 (while the message waiting time is set to 0 ms)

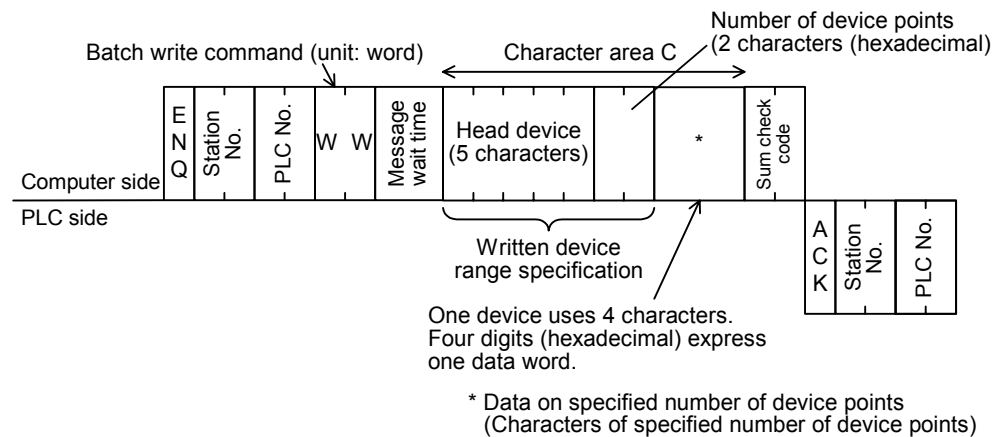


7.5 WW Command [Writes Device Memory in 1-Word Units]

This section explains the control procedure specification method and shows a specification examples when the word device memory is written all at once or when the bit device memory is written (in 16-point units) all at once.

1. Specification method

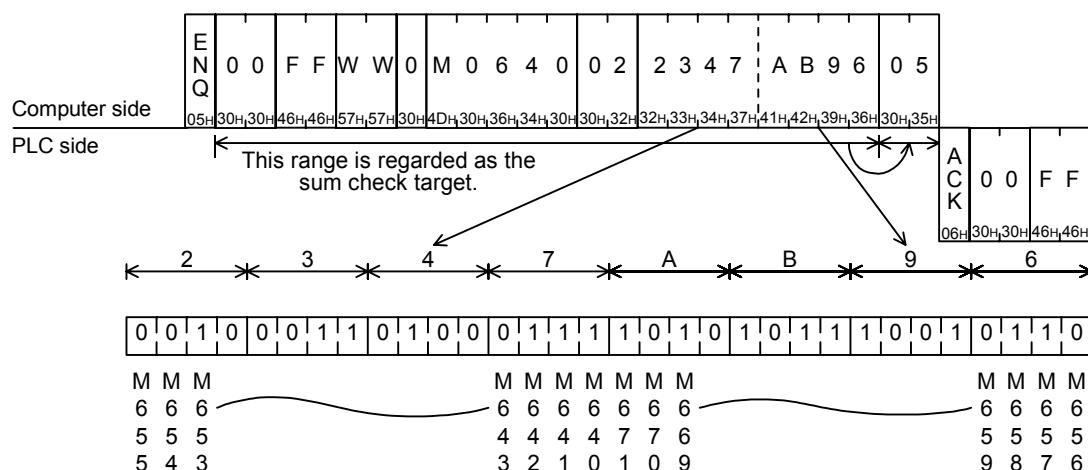
The specification method in the control procedure format 1 is shown below:



- Specify the device point range while satisfying the following conditions:
 - 1 ≤ Number of device points ≤ 64*¹ (10 in case of bit devices)
 - Head device number + Number of device points ("Number of devices x 16" in case of bit devices) - 1 ≤ Maximum device number
 - When 32-bit devices (CN200 to CN255) are written, one device point is handled as two word data. Accordingly, up to 32 device points*² can be specified.
- Express the station number, PLC number, number of device points and sum check code in hexadecimal.
 - *1. Up to 11 device points in the FX1S and FX0N Series
 - *2. Up to 5 device points in the FX1S and FX0N Series

2. Specification examples

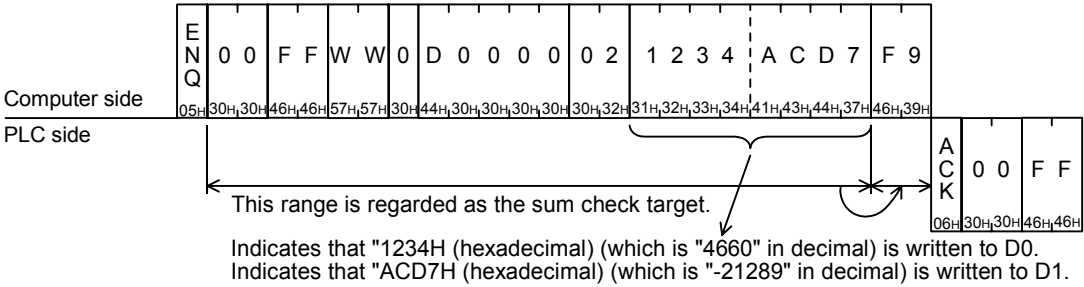
Example 1: When writing data to thirty-two devices from M640 to M671 in the PLC whose station number is 0 (while the message waiting time is set to 0 ms)



Important point

The WW command handles data in 1-word units. When writing data to thirty-two devices from M640 to M671, specify the number of device points as "02" (One point specifies 16 devices.)

Example 2: When writing data to two devices D0 and D1 in the PLC whose station number is 0 (while the message waiting time is set to 0 ms)



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

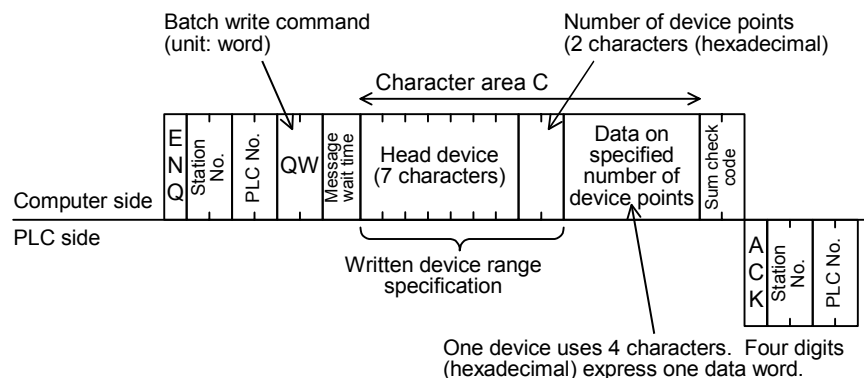
Discontinued models

7.6 QW Command [Writes Device Memory in 1-Word Units]

This section explains the control procedure specification method and shows a specification examples when the word device memory is written all at once or when the bit device memory is written (in 16-point units) all at once.

1. Specification method

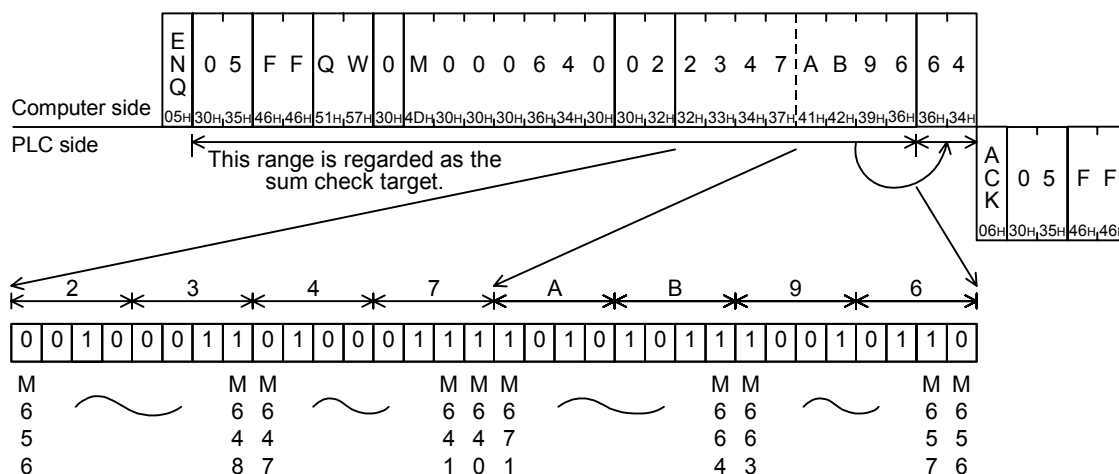
The specification method in the control procedure format 1 is shown below:



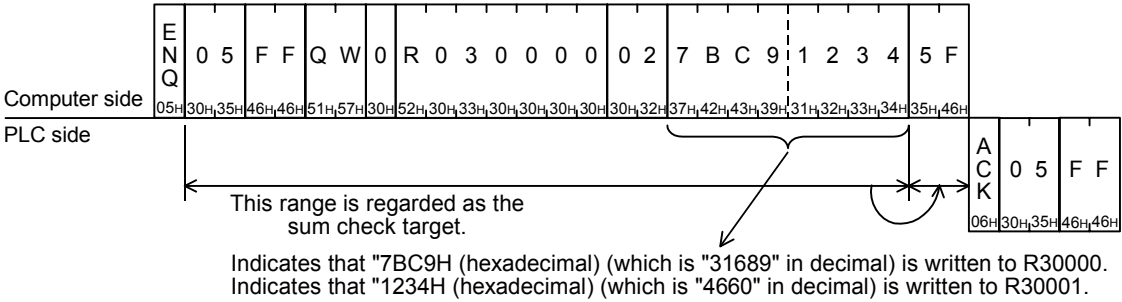
- 1) This command is available only in FX3U and FX3UC PLCs.
- 2) Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 64$ (10 in case of bit devices)
 - Head device number + Number of device points ("Number of devices \times 16" in case of bit devices) - 1 \leq Maximum device number
 - When 32-bit devices (CN00200 to CN00255) are written, one device point is handled as two word data. Accordingly, up to 32 device points can be specified.
- 3) Express the station number, PLC number, number of device points and sum check code in hexadecimal.

2. Specification examples

Example 1: When writing data to thirty-two devices from M640 to M671 in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)



Example 2: When writing data to two devices from R30000 to R30001 in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

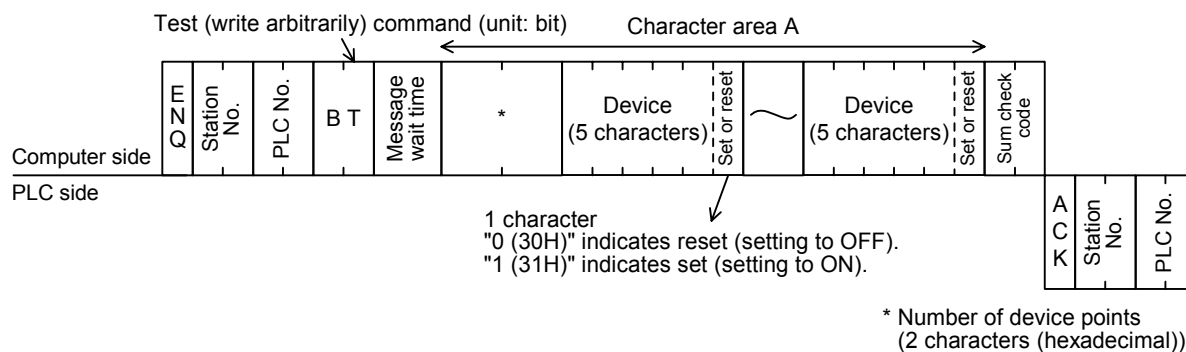
Discontinued models

7.7 BT Command [Tests Device Memory in 1-Bit Units (by Writing Arbitrarily)]

This section explains the control procedure specification method and shows a specification example when the bit device memory is specified arbitrarily and written all at once.

1. Specification method

The specification method in the control procedure format 1 is shown below:

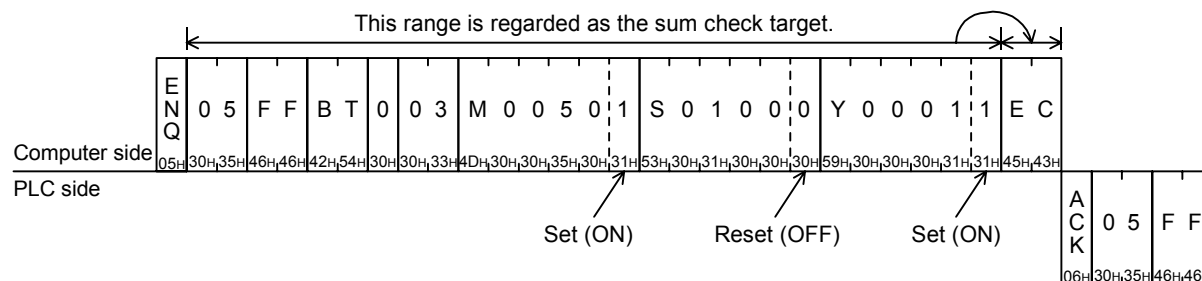


Important points

- Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 20^{*1}$
- Express the station number, PLC number, number of device points and sum check code in hexadecimal.
 - *1. 10 in the FX1S and FX0N Series

2. Specification example

When writing data for setting M50 to ON, S100 to OFF and Y001 to ON in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)

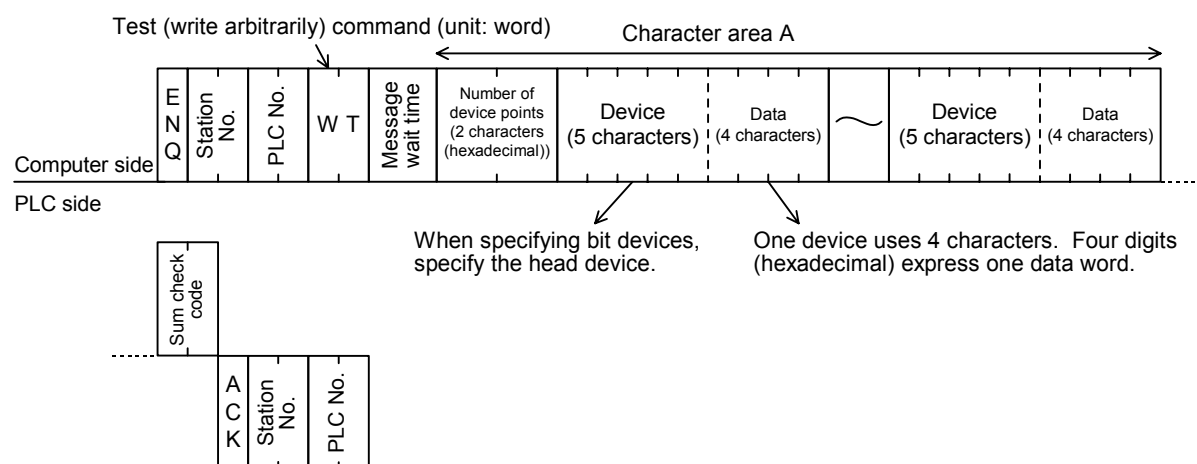


7.8 WT Command [Tests Device Memory in 1-Word Units (by Writing Arbitrarily)]

This section explains the control procedure specification method and shows a specification example when the word device memory and bit device memory (in 16-point units) are specified arbitrarily and written all at once. Word devices and bit devices (in 16-point units) can be specified together. However, the WT command cannot handle 32-bit word devices C200 to C255 (CN200 to CN255).

1. Specification method

The specification method in the control procedure format 1 is shown below:

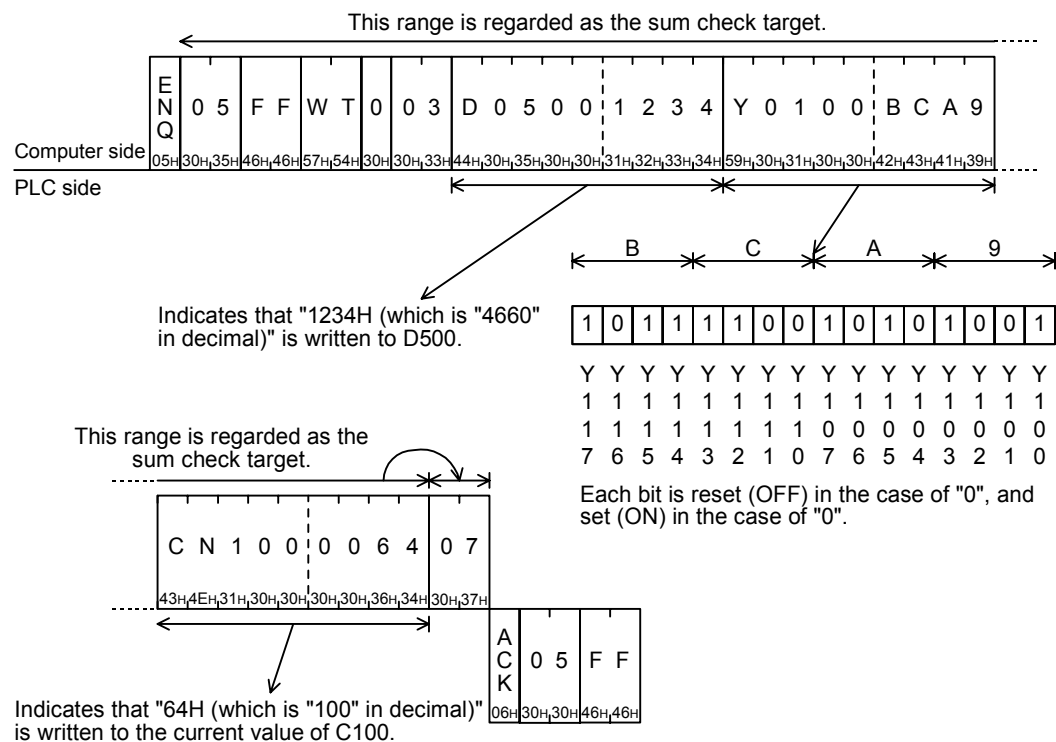


- Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 10^*1$ (in unit of 10^*1 in case of bit devices (One unit indicates 16 points.))
- Express the station number, PLC number, number of device points and sum check code in hexadecimal.
- The WT command cannot handle 32-bit word devices C200 to C255 (CN200 to CN255).

*1. 6 in the FX1S and FX0N Series

2. Specification example

When writing data for setting the current value of D500 to "1234H", Y100 to Y117 to "BCA9H" and the current value of C100 to "64H" in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)

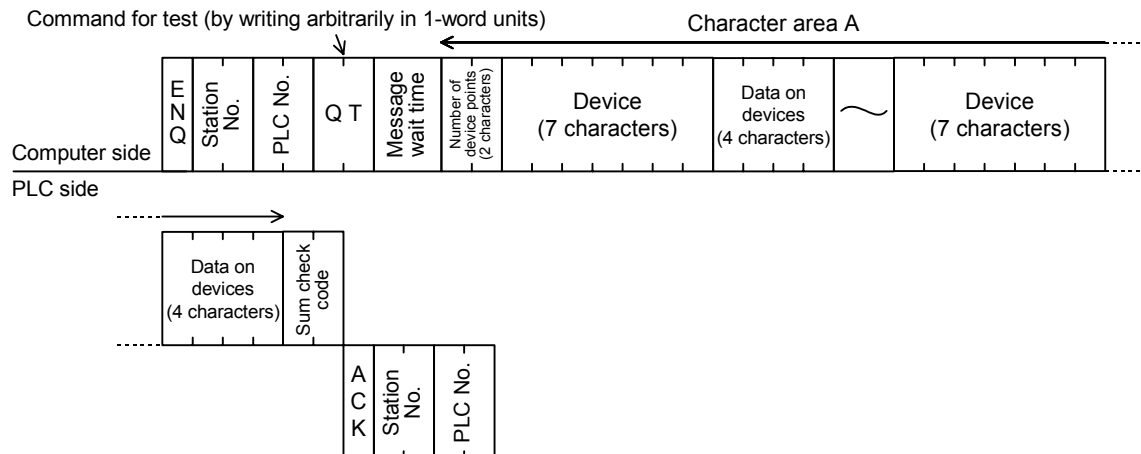


7.9 QT Command [Tests Device Memory in 1-Word Units (by Writing Arbitrarily)]

This section explains the control procedure specification method and shows a specification example when the word device memory and bit device memory (in 16-point units) are specified arbitrarily and written all at once. Word devices and bit devices (in 16-point units) can be specified together. However, the QT command cannot handle 32-bit word devices C200 to C255 (CN00200 to CN00255).

1. Specification method

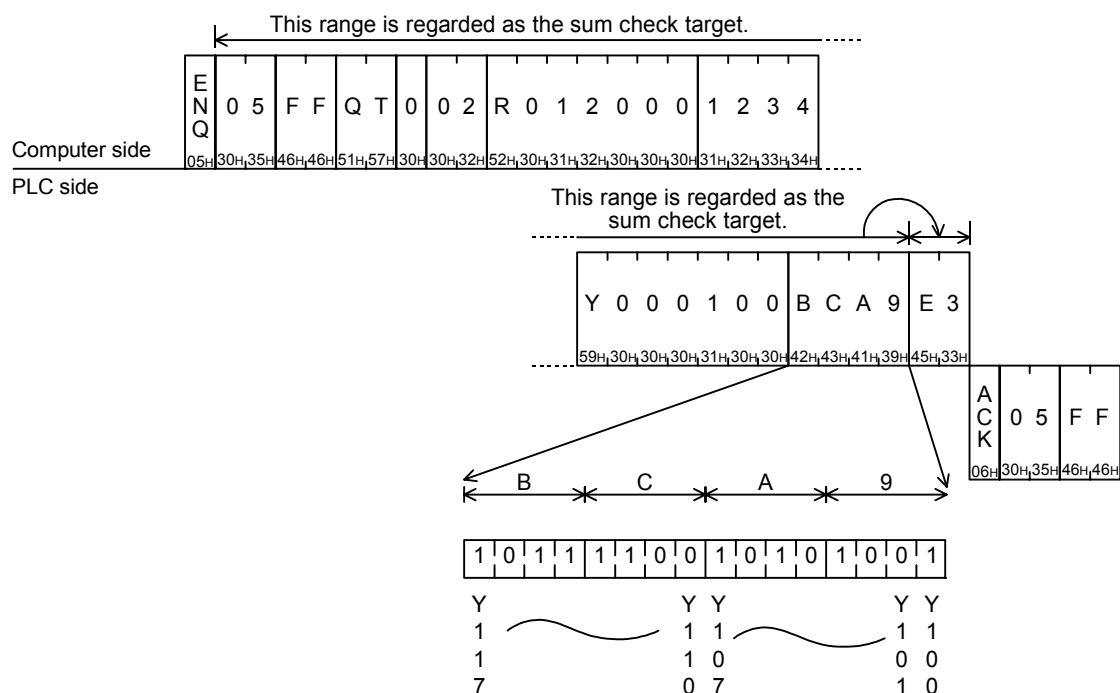
The specification method in the control procedure format 1 is shown below:



- 1) This command is available only in FX3U and FX3UC PLCs.
- 2) Specify the device point range while satisfying the following conditions:
 - $1 \leq \text{Number of device points} \leq 10$ (in unit of 10 in case of bit devices (One unit indicates 16 points.))
- 3) Express the station number, PLC number, number of device points and sum check code in hexadecimal.
- 4) Word devices and bit devices (in 16-point units) can be specified together.
- 5) The QT command cannot handle 32-bit word devices C200 to C255 (CN00200 to CN00255).

2. Specification example

When writing data for setting the current value of R12000 to "1234H" and Y100 to Y117 to "BCA9H" in the PLC whose station number is 5 (while the message waiting time is set to 0 ms)



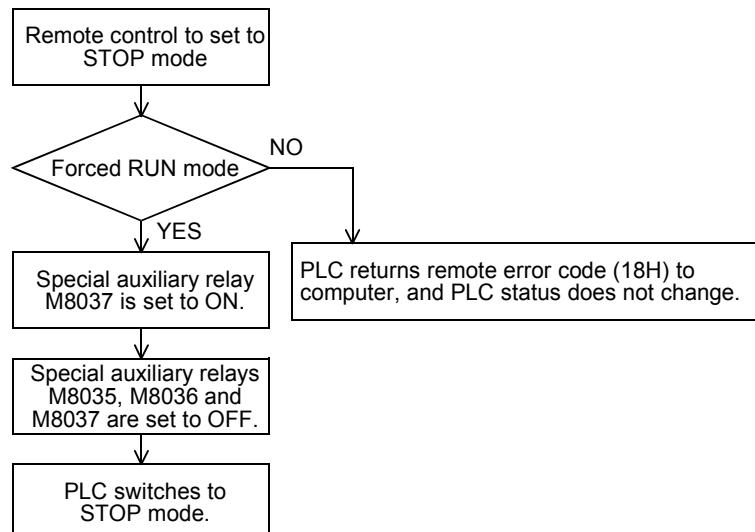
7.10 RR/RS Command [Remotely Sets PLC to RUN/STOP Mode]

This section explains the control procedure specification method and shows a specification example when the computer remotely sets the PLC mode to RUN or STOP.

7.10.1 Contents of remote control to set RUN or STOP mode

When the computer executes remote control of the PLC mode to RUN or STOP, the forced RUN mode is activated in the PLC, and the special auxiliary relays M8035, M8036 and M8037 are controlled as follows:

- Remote RUN mode control
When the RR command (which sets remote RUN mode in control) is executed in the computer, the PLC sets M8035 and M8036 to activate the forced RUN mode.
If the RR command is executed while the PLC is in RUN mode, however, the PLC status does not change, and the PLC returns the remote error code (18H) to the computer.
- Remote STOP mode control
When the RS command (which sets remote STOP mode in control) is executed in the computer, the PLC executes the following processing.
If the RS command is executed while the PLC is in STOP mode, the PLC status does not change, and the PLC returns the remote error code (18H) to the computer.



7.10.2 Condition validating remote control to set RUN or STOP mode

- Remote RUN mode control
The PLC is in STOP mode.
(The built-in RUN/STOP selector switch is set to STOP.)
(In an FX2(FX) or FX2c PLC, the RUN terminal in the PLC is OFF, and the built-in RUN/STOP selector switch is set to STOP.)
- Remote STOP mode control
The PLC is in RUN mode (forced RUN mode) without using the RUN terminal or built-in RUN/STOP selector switch.

Important point

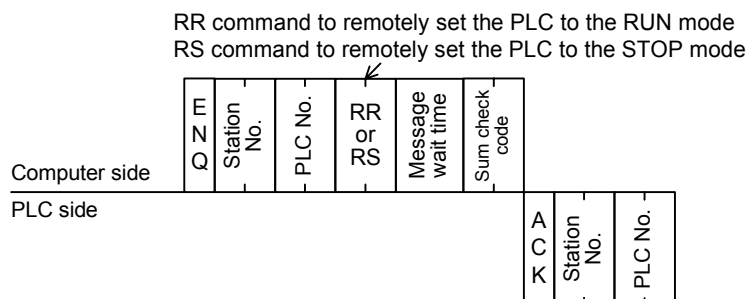
When the PLC power is turned OFF and then ON after the RR command is executed by the computer, all of the special auxiliary relays M8035, M8036 and M8037 are set to OFF. As a result, the PLC switches to STOP mode.

7.10.3 Remote control specification method and specification examples

This subsection explains the control procedure specification method and specification examples when remote RUN or STOP mode control is executed.

1. Specification method

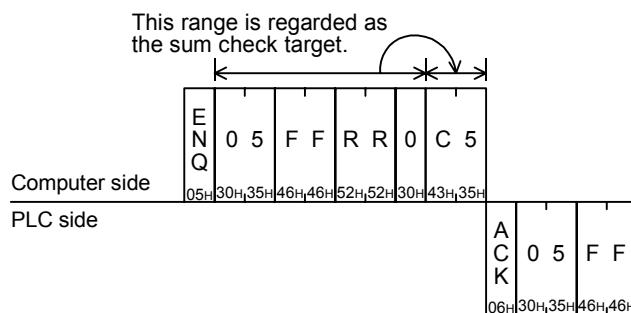
The specification method in the control procedure format 1 is shown below:



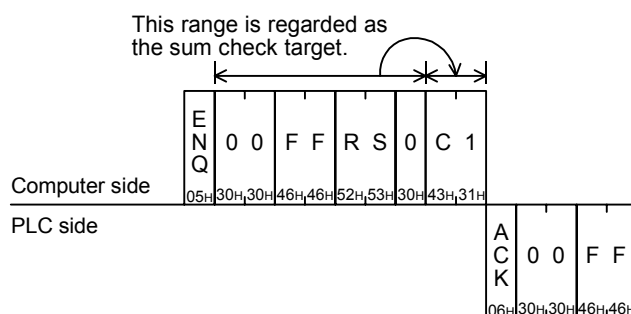
Express the station number, PLC number, number of device points and sum check code in hexadecimal respectively.

2. Specification examples

Example 1: When remotely setting the PLC whose station number is 5 to RUN mode (while the message waiting time is set to 0 ms)



Example 2: When remotely setting the PLC whose station number is 0 to STOP mode (while the message waiting time is set to 0 ms)



7.11 PC Command [Reads PLC Model Name]

This section explains the control procedure specification method and specification example when the model name of a PLC linked to the computer is read.

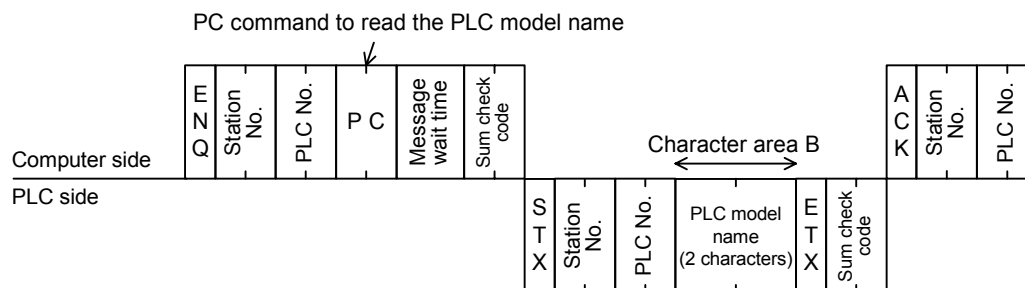
7.11.1 PLC model name (CPU) and read contents

| PLC model name (CPU) | Model name code (hexadecimal) | PLC model name (CPU) | Model name code (hexadecimal) |
|---------------------------------|-------------------------------|----------------------|-------------------------------|
| FX1S | F2H | A2USCPU | 82H |
| FX0N | 8EH | A2CPU-S1, A2USCPU-S1 | 83H |
| FX2(FX), FX2C | 8DH | A3CPU, A3NCPU | A3H |
| FX1N, FX1NC | 9EH | A3ACPU | 94H |
| FX2N, FX2NC | 9DH | A3HCPU, A3MPCU | A4H |
| FX3U, FX3UC | F3H | A3UCPU | 84H |
| A0J2HCPU | 98H | A4UCPU | 85H |
| A1CPU, A1NCPU | A1H | A52GCPU | 9AH |
| A1SCPU, A1SJCPU | 98H | A73CPU | A3H |
| A2CPU(-S1), A2NCPU(-S1), A2SCPU | A2H | A7LMS-F | A3H |
| A2ACPU | 92H | AJ72P25/R25 | ABH |
| A2ACPU-S1 | 93H | AJ72LP25/BR15 | 8BH |
| A2CCPU | 9AH | | |

7.11.2 Control procedure specification method and specification example

1. Specification method

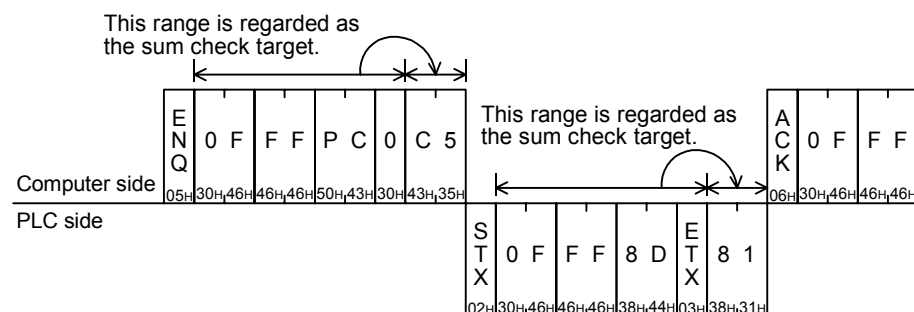
The specification method for control procedure format 1 is shown below:



Express the station number, PLC number, number of device points and sum check code in hexadecimal respectively.

2. Specification example

When reading the model name of the PLC whose station number is 15 (while the message waiting time is set to 0 ms)



The example above indicates that the model name of the target PLC is the FX2(FX) or FX2C Series.

7.12 GW Command [Offers Global Function]

The global function executed in the computer sets a special auxiliary relay to ON or OFF in all PLCs linked to the computer in the multi-drop link method. For A Series PLCs, however, refer to the respective A Series PLC manual.

This section explains the control procedure specification method and specification example when the global function is used.

7.12.1 Contents of control

The global function sets a special auxiliary relay to ON or OFF in all FX Series PLCs linked to the computer. M8126 is set to ON or OFF in PLCs except the FX3U and FX3UC Series.

In FX3U and FX3UC PLCs, M8126 is set to ON or OFF in computer link using ch1, and M8426 is set to ON or OFF in computer link using ch2.

In A Series PLCs, Xn2 is set to ON or OFF for all PLCs linked to the computer.

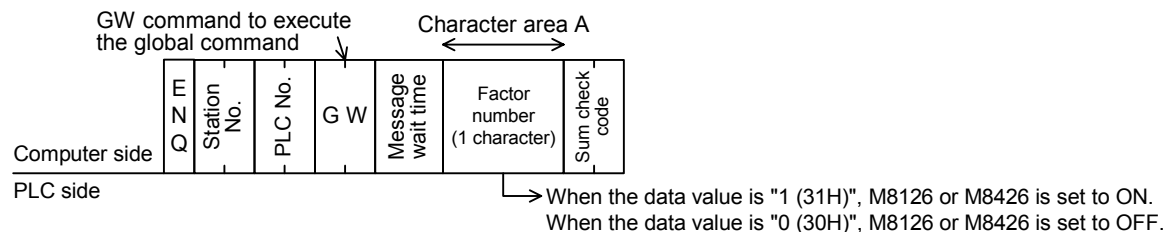
- In the control procedure, specify the station number "FFH" so that all stations are handled as targets. If any value other than "FFH" is specified, a special auxiliary relay is set to ON or OFF only in a station with the specified station number.
- In this function, PLCs do not give any response to the GW command from the computer.
- When the PLC power is turned OFF or when the PLC is set to STOP mode, the special auxiliary relay M8126 or M8426 is set to OFF and the processing request in the global function is cleared.

7.12.2 Global function control procedure specification method and specification example

This subsection explains the control procedure specification method and specification example when the global function is executed from the computer.

1. Specification method

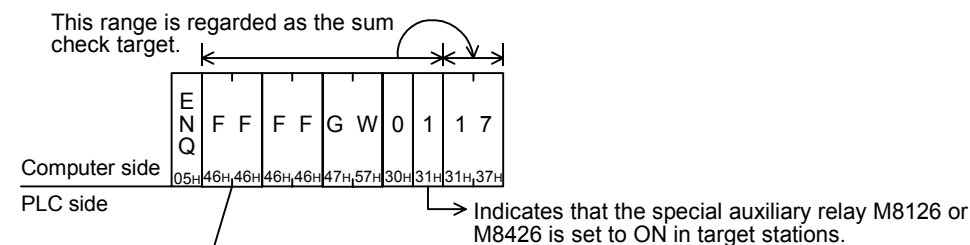
The specification method in the control procedure format 1 is shown below:



Express the station number, PLC number, number of device points and sum check code in hexadecimal respectively.

2. Specification example

When setting to ON the special auxiliary relay M8126 of M8426 in all FX PLCs (In all of A Series PLCs in computer link, however, Xn2 is set to ON.)



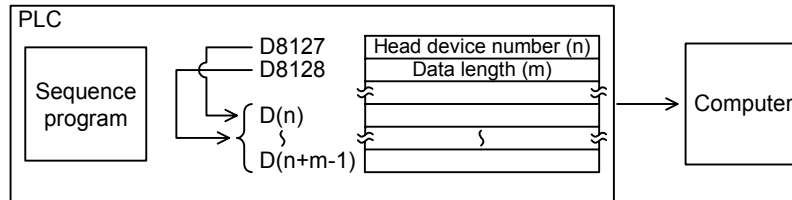
Specify "FFH" for handling all stations as targets.
When handling only one station as a target, specify the station number (ranging from 00 to 0F) of the target station.

7.13 On-demand Function

When there is data to be sent from a PLC to the computer, the on-demand function can specify the data register area storing the data to be sent, and let the PLC start sending.

When data is sent between the computer and a PLC, only the computer can start data transmission.

When there is emergency data to be sent from a PLC to the computer, the on-demand function is applicable to let the PLC begin sending data to the computer.



Important point

This function is applicable when the computer and the PLC CPU have the 1-to-1 configuration.

7.13.1 Special data registers and special auxiliary relays used in on-demand function

The tables below show the special data registers and special auxiliary relays used in the on-demand function.

1. In all PLCs except FX3U and FX3UC PLCs and when ch1 is used in FX3U and FX3uc PLCs

| Device | Name | Description |
|---------------------|--|--|
| M8127 ^{*1} | On-demand send processing | Remains ON while the on-demand function is being executed. ON: On-demand data is being sent. OFF: Sending of on-demand data is completed. |
| M8128 | On-demand error flag | Turns ON when an error is included in a specified value to be sent in the on-demand function. ON: Error is included. OFF: Error is not included. |
| M8129 | On-demand byte/word changeover | Specifies the unit (byte or word) of data handled in the on-demand function. ON: Unit = Byte (8-bit) OFF: Unit = Word (16-bit) |
| D8127 | On-demand head device number specification | Sets the head data register device number containing the data to be sent using the on-demand function in a sequence program. |
| D8128 | On-demand data quantity specification | Sets the amount of data to be sent using the on-demand function in a sequence program. |

*1. FX0N, FX1S, FX1N and FX1NC PLCs do not support this device.

2. When ch2 is used in FX3U and FX3uc PLCs

| Device | Name | Description |
|--------|--|--|
| M8427 | On-demand send processing | Remains ON while the on-demand function is being executed. ON: On-demand data is being sent. OFF: Sending of on-demand data is completed. |
| M8428 | On-demand error flag | Turns ON when an error is included in a specified value to be sent in the on-demand function. ON: Error is included. OFF: Error is not included. |
| M8429 | On-demand byte/word changeover | Specifies the unit (byte or word) of data handled in the on-demand function. ON: Unit = Byte (8-bit) OFF: Unit = Word (16-bit) |
| D8427 | On-demand head device number specification | Sets the head data register device number containing the data to be sent using the on-demand function in a sequence program. |
| D8428 | On-demand data quantity specification | Sets the amount of data to be sent using the on-demand function in a sequence program. |

Important points

- The on-demand send processing signal (M8127 or M8427) turns ON when the PLC gives a request to send data to the computer, and turns OFF when sending of the specified data is completed. Use this signal for interlock to prevent giving two or more on-demand requests at the same time.
- While the on-demand send processing signal is ON, the PLC cannot receive commands sent from the computer.
- Amount of on-demand data and number of data registers used for sending according to the unit specification (word or byte)

When the specified unit is a word:

The amount of on-demand data is equivalent to the number of data registers to be sent.

When the specified unit is a byte:

Two on-demand data units use one data register for sending.

Example: When the amount of on-demand data is "5", the number of data registers for sending is "3".

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

7.13.2 Control procedures in on-demand function

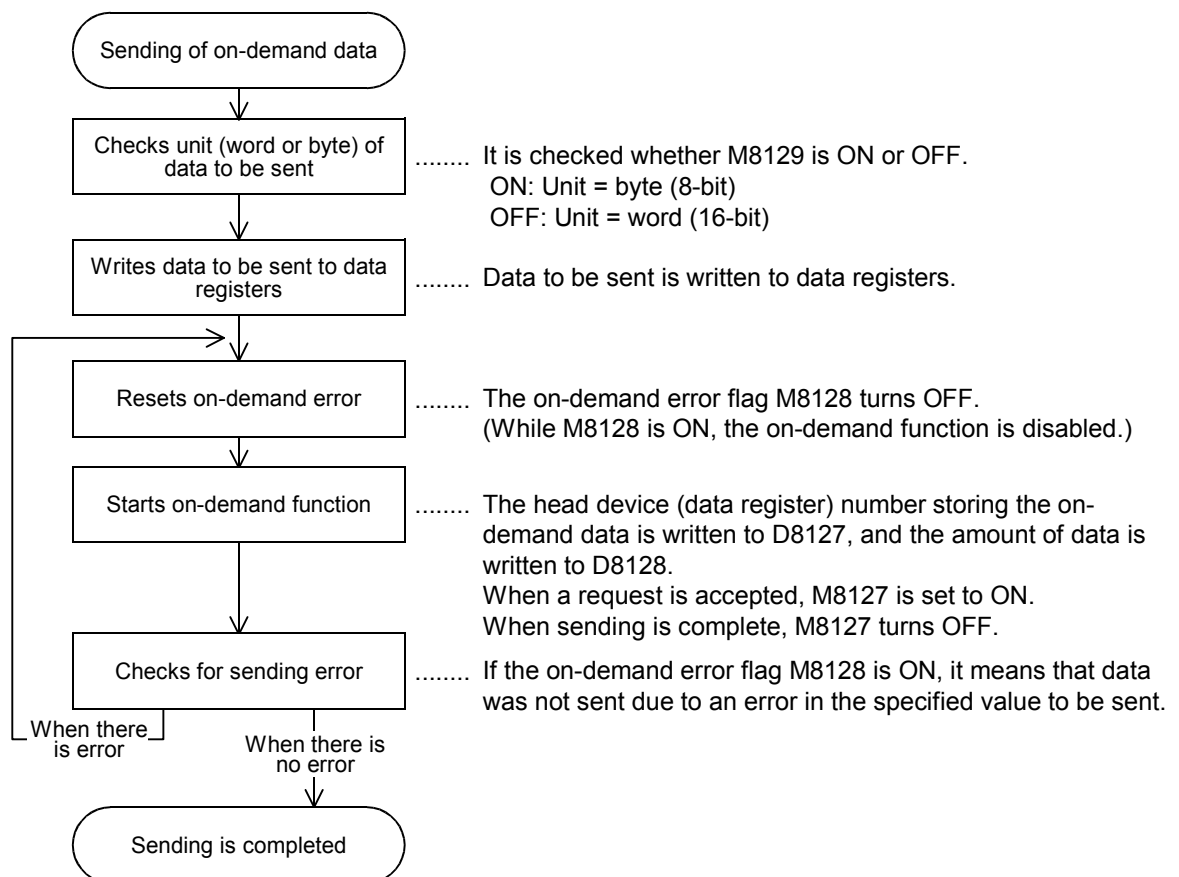
This subsection explains the control procedures for the on-demand function.

When using ch2 in an FX3U or FX3UC Series PLC, exchange special auxiliary relays (M) and special data registers (D) according to the table below.

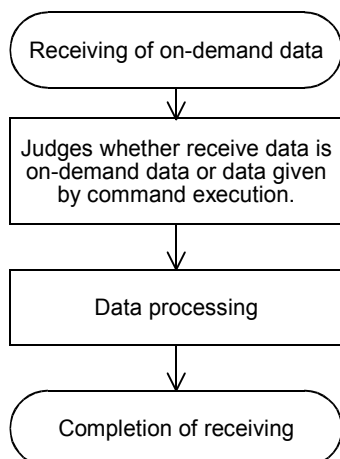
| All PLCs except FX3U and FX3UC PLCs FX3U and FX3UC PLCs (ch1) | | FX3U and FX3UC PLCs (ch2) |
|--|---|---------------------------|
| M8127*1 | ↔ | M8427 |
| M8128 | | M8428 |
| M8129 | | M8429 |
| D8127 | | D8427 |
| D8128 | | D8428 |

*1. FX0N, FX1S, FX1N and FX1NC PLCs do not support this device.

1) Control procedure in the PLC

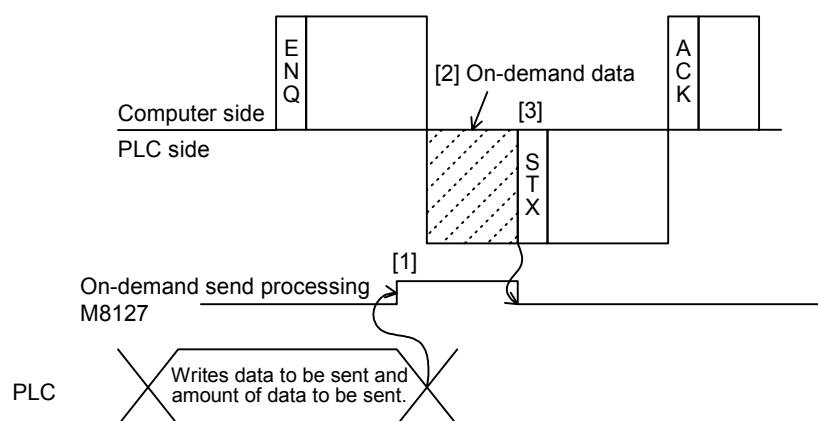


2) Control procedure in the computer



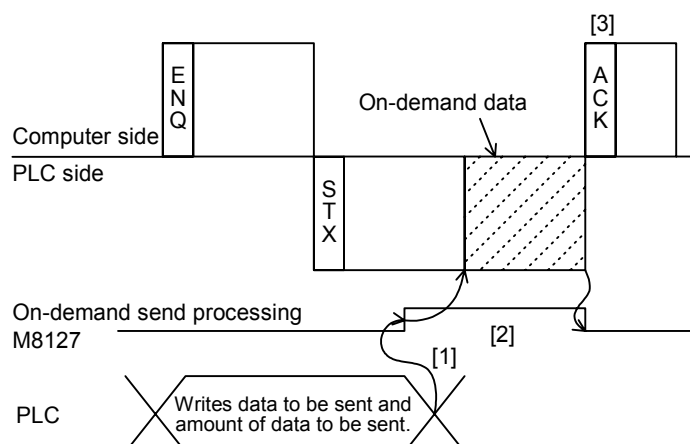
..... To the on-demand data, the PLC adds "FE" as the PLC number. Only when the PLC number of the received data is "FE", the received data should be processed as on-demand data.

3) Time chart when the on-demand function is requested
While the computer is sending data



- [1] As soon as an on-demand request is given, the on-demand send processing signal M8127 turns ON.
- [2] After receiving of command data (ENQ ~) from the computer is completed, the PLC sends on-demand data.
- [3] After the sending of on-demand data is complete, the PLC sends response data (STX ~) to the command data (ENQ ~).

While the computer is receiving data



- [1] As soon as an on-demand request is given, the on-demand send processing signal M8127 turns ON.
- [2] After the sending of response data (STX ~) to the command data (ENQ ~) from the computer is completed, the PLC sends on-demand data.
- [3] After the receiving of on-demand data is complete, the computer sends response data (ACK ~) to the sending of the response data (STX ~) from the PLC.

7.13.3 On-demand function specification method and specification examples

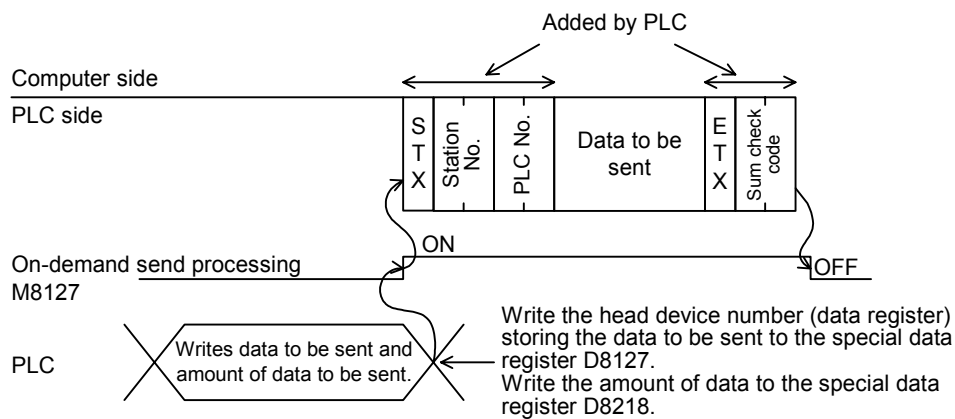
This subsection explains the on-demand function specification method and specification examples. When using ch2 in an FX3U or FX3UC Series PLC, exchange special auxiliary relays (M) and special data registers (D) according to the table below.

| All PLCs except FX3U and FX3UC PLCs FX3U and FX3UC PLCs (ch1) | | FX3U and FX3UC PLCs (ch2) |
|--|---|---------------------------|
| M8127 ^{*1} | ↔ | M8427 |
| M8128 | | M8428 |
| M8129 | | M8429 |
| D8127 | | D8427 |
| D8128 | | D8428 |

*1. FX0N, FX1S, FX1N and FX1NC PLCs do not support this device.

1. Specification method

The specification method in the control procedure format 1 is shown below:



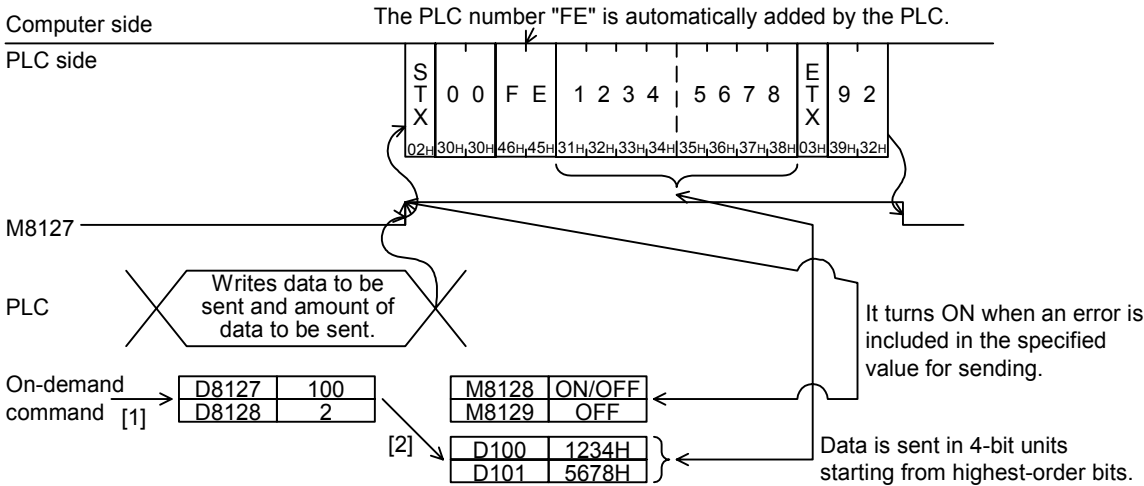
- Specify the data quantity specification range while satisfying the following condition:
 - Amount of data $\leq 40H$ (= 64 in decimal)
- The PLC adds "FE" as the PLC number.
- Express the station number, PLC number, number of device points and sum check code in hexadecimal.

IMPORTANT

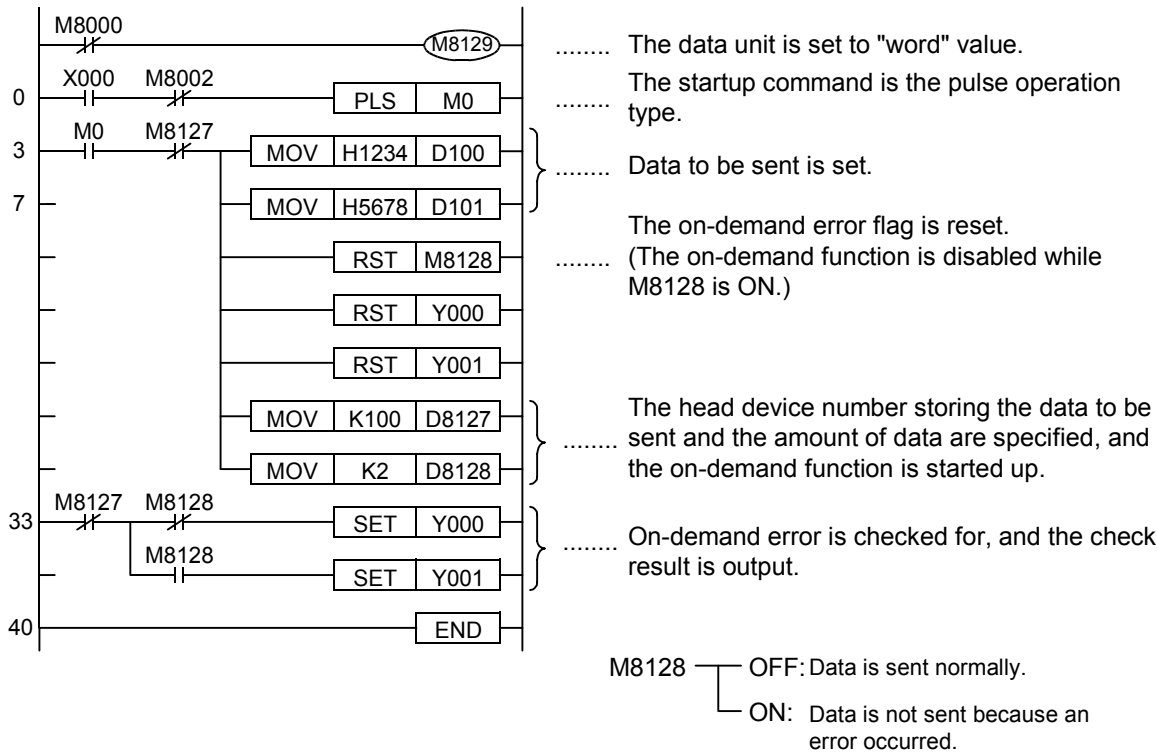
Do not use the on-demand function when the system configuration is not 1-to-1 type.
If the on-demand function is used in the multi-drop link system in which the computer and PLC CPUs have the 1-to-N configuration, the transfer data and on-demand send data in the control procedure format 1 or 4 are destroyed, and normal data sending is not possible.

2. Specification example 1

When sending the data stored in the data registers D100 and D101 by a trigger from a sequence program (when the station number is 0 and the data unit is set to "word")

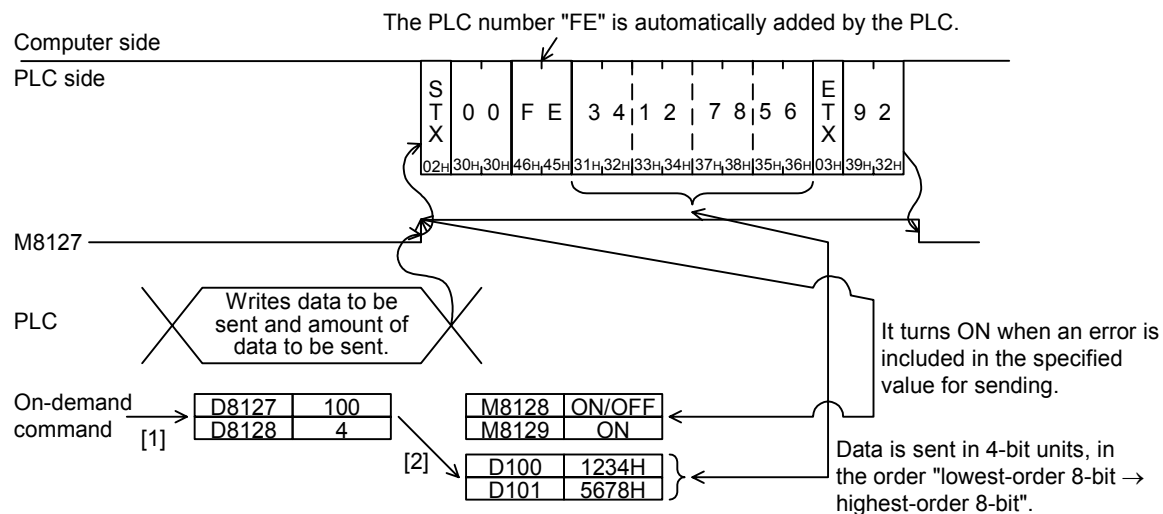


Sequence program example

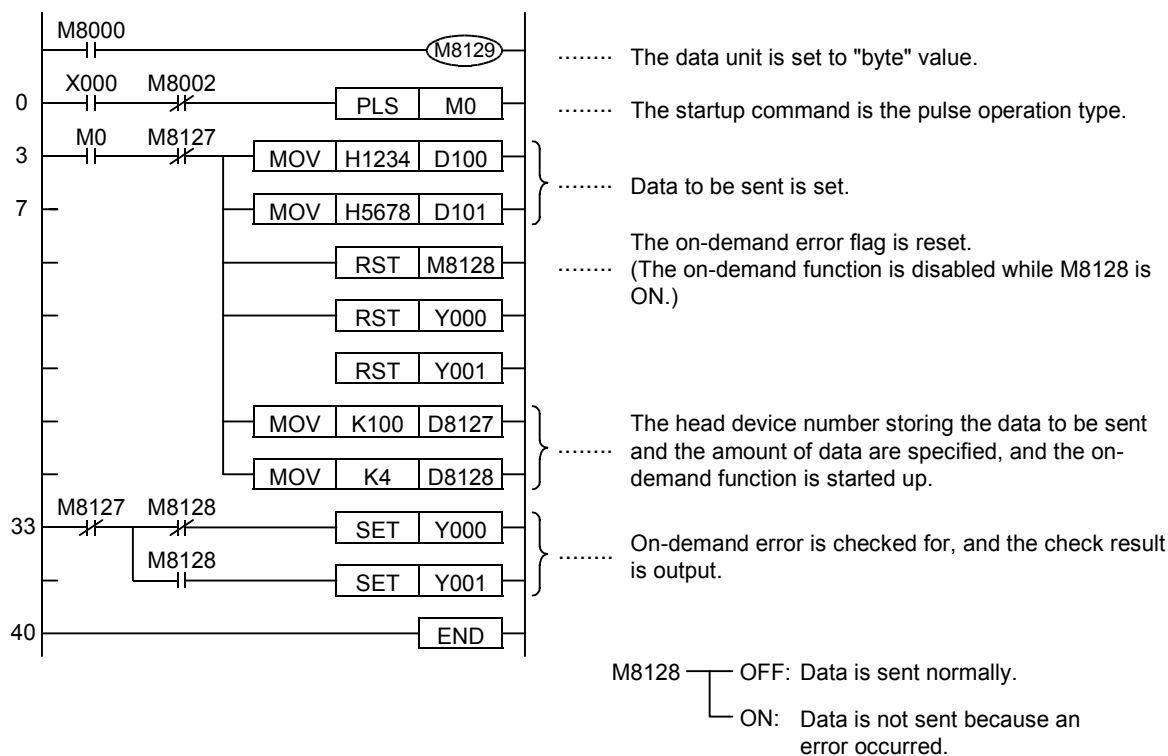


3. Specification example 2

When sending the data stored in the data registers D100 and D101 by a trigger from a sequence program (when the station number is 0 and the data unit to be sent is set to "byte")



Sequence program example

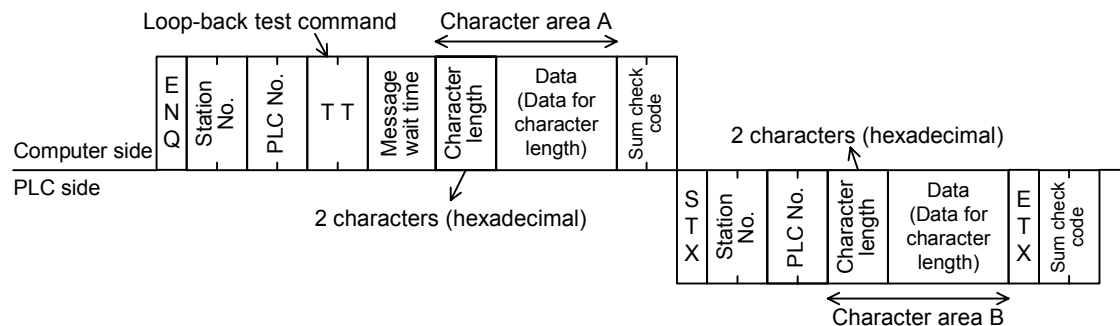


7.14 TT Command [Loop-back Test]

The loop-back test function checks whether or not communication between the computer and a PLC is normal. This section explains the control procedure specification method and specification example when the loop-back test function is used.

1. Specification method

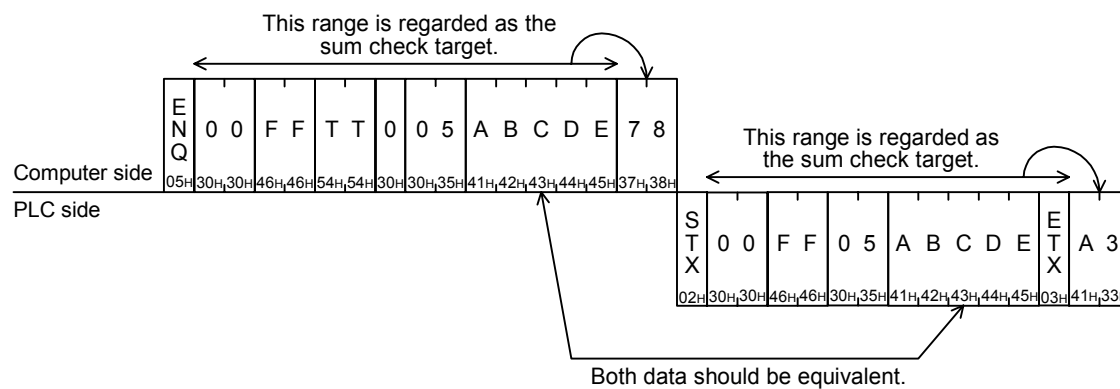
The specification method in the control procedure format 1 is shown below:



- Specify the character length specification range while satisfying the following condition:
 - $1 \leq \text{Character length} \leq 254$
- Express the station number, PLC number, number of device points and sum check code in hexadecimal respectively.

2. Specification example

When executing the loop-back test to the PLC whose station number is 0 using the data "ABCDE" (while the message waiting time is set to 0 ms)



8. Troubleshooting

This chapter explains troubleshooting.

8.1 Checking FX PLC Version Applicability

Verify that the FX PLC main unit is an applicable version.

→ For the version applicability check, refer to Section 1.3.

8.2 Checking Communication Status Based on LED Indication

Check the status of the "RD(RXD)" and "SD(TXD)" indicator LEDs provided in the optional equipment.

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RD(RXD) | SD(TXD) | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received. |
| Off | Off | Data is not sent or received. |

While computer link is executed normally, both LEDs flash brightly.

If they do not flash, check the wiring, station number settings and communication setting.

8.3 Checking Installation and Wiring

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ For mounting method, refer to the respective communication equipment manual.

2. Power supply (for FX0N-485ADP)

The FX0N-485ADP requires a driving power supply. Verify that the power supply is provided correctly.

3. Wiring

Verify that the wiring to all communication equipment is correct. If the communication equipment is wired incorrectly, communication is not possible.

→ For wiring method check, refer to Chapter 4.

8.4 Checking Sequence Program

1. Communication setting in the sequence program

Verify that the parallel link and N:N Network are not set. Verify that the communication format (D8120 and D8420) is set correctly. Communication is not possible if a communication port is set twice or more. After changing any setting, make sure to reboot the PLC's power.

2. Communication setting using parameters

Verify that the communication settings using parameters is suitable to the purpose of use. If the communication settings are not suitable to the purpose of use, communication will not function correctly. After changing any setting, make sure to reboot the PLC's power.

3. Presence of VRRD and VRSC instructions (in FX3U and FX3UC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program. If these instructions are used, delete them, reboot the PLC's power.

4. Presence of RS instruction (except FX3U and FX3UC PLCs)

Verify that the RS instruction is not used in the program. If this instruction is used, delete it, reboot the PLC's power.

5. Presence of RS and RS2 instructions (in FX3U and FX3UC PLCs)

Verify that the RS and RS2 instructions are not being used for the same channel. If these instructions are used for the same channel, delete them, reboot the PLC's power.

6. Presence of EXTR instruction (in FX2N and FX2NC PLCs)

Verify that the EXTR instruction is not used in the program. If this instruction is used, delete it, then reboot the PLC's power.

7. Presence of IVCK, IVDR, IVRD, IVWR, and IVBWR instructions (in FX3U and FX3UC PLCs)

Verify that the IVCK, IVDR, IVRD, IVWR and IVBWR instructions are not being used for the same channel. If these instructions are used for the same channel, delete them, reboot the PLC's power.

| | |
|-------------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

8.5 Checking Error Codes

8.5.1 Error codes when NAK is sent

The table below shows error codes and contents of errors when NAK is sent in communication between the computer and a PLC.

As an error code, a two-digit ASCII code (hexadecimal) within the range from 00H to FFH is sent.

When two or more errors occur at the same time, priority is given to the error code with the smallest number, and the error code with the smallest number is sent.

When any error shown below occurs, the entire transfer sequence is initialized.

Error code list

| Error code (hexadecimal) | Error item | Contents of error | Action |
|--------------------------|----------------------|---|--|
| 02H | Sum check error | Sum check error has occurred. The sum check code included in the received data is different from the sum value calculated from the received data. | Check the data sent from the computer and the contents of the sum check. Modify either one, and then execute communication again. |
| 03H | Protocol error | The communication protocol is abnormal. A control procedure set using parameters was ignored, and a different control procedure was adopted in communication. Or the adopted control procedure was partially different from the preset control procedure. Or a command specified in the preset control procedure does not exist. | 1) Check the contents of parameters and the contents of control procedure. Modify either contents, and then execute communication again. 2) Refer to the command list shown in Chapter 7, modify the specified command etc., and then execute communication again. |
| 06H | Character area error | An error occurred in the character area A, B or C. Or a specified command does not exist. 1) The control procedure set using parameters is different. 2) A specified device number does not exist in the target PLC. 3) A device number is not set with the specified number of characters (5 or 7 characters). | 1) Check the contents of the character areas A, B and C, modify the contents if necessary, and then execute communication again. 2) Refer to "2.2.2 Applicable device ranges", modify the number of characters used to specify the device number, and then execute communication again. |
| 07H | Character error | ASCII code data to be written to a device is not hexadecimal. | Check the data to be written to the device, modify it if necessary, and then execute communication again. |
| 0AH | PLC number error | A station with the corresponding PLC number does not exist. | Check the PLC number included in the message, modify it if necessary, and then execute communication again. The PLC number should be "FFH" in all FX Series PLCs. |
| 10H | PLC number error | A station with the corresponding PLC number does not exist. | Check the PLC number included in the message, modify it if necessary, and then execute communication again. The PLC number should be "FFH" in all FX Series PLCs. |
| 18H | Remote control error | Remote control to set the RUN or STOP mode is disabled. The RUN or STOP mode is determined in the PLC hardware (by using the RUN/STOP selector switch, etc.). | Set the PLC mode to RUN or STOP using the forced RUN mode. |

8.5.2 Error codes in PLC

When an error is included in a message sent from the computer to a PLC, an error occurs in the PLC.

When such an error occurs, the serial communication error flag turns ON.

When PLCs other than FX3U and FX3UC PLCs are used or when ch1 is used in an FX3U or FX3UC PLC, the special auxiliary relay M8063 turns ON as an error flag. When ch2 is used in an FX3U or FX3UC PLC, the special auxiliary relay M8438 turns ON as an error flag.

When a serial communication error occurs, the error code is stored in D8063 if M8063 turns ON, or stored in D8438 if M8438 turns ON.

The error code list is shown below:

| Device | Error code | Error item | Contents of error | Action |
|----------------|------------|----------------------------------|---|--|
| D8063 (ch1) | 6301 | Parity, overrun or framing error | The transfer data is abnormal. | Check the transfer specifications set using parameters, and execute communication again. |
| | 6305 | Command error | When the station number was FF, any command other than "GW" was received. | Check the specified command, modify it if necessary, and then execute communication again. |
| | 6306 | Monitoring timeout | The received message was insufficient. Because normal message was not received within the time-out time setting, the transfer sequence was initialized. | The message is insufficient. Check the transfer program in the computer, modify it if necessary, and then execute communication again. |
| D8438 (ch2) | 3801 | Parity, overrun or framing error | The transfer data is abnormal. | Check the transfer specifications set using parameters, and execute communication again. |
| | 3805 | Command error | When the station number was FF, any command other than "GW" was received. | Check the specified command, modify it if necessary, and then execute communication again. |
| | 3806 | Monitoring timeout | The received message was insufficient. Because normal message was not received within the time-out time setting the transfer sequence was initialized. | The message is insufficient. Check the transfer program in the computer, modify it if necessary, and then execute communication again. |

Error codes are not cleared even if communication errors are reset. They are cleared when the PLC mode is changed from STOP to RUN.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/R2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9. Related Data

9.1 Related Device List

1. Bit devices

| Device | Name | Description | R/W |
|---------|---------------------------------|--|-----|
| M8063 | Serial communication error 1 | Turns ON when an error occurs in serial communication using ch 1. | R |
| M8120 | Communication setting keep | Keeps the communication setting status (for FX0N PLCs). | R/W |
| M8126 | Global function ON | Turns ON or OFF when the global command (GW) is received from the computer (for ch 1). | R |
| M8127*1 | On-demand send processing | Remains ON while the on-demand function is being executed (for ch 1). ON: On-demand data is being sent. OFF: Sending of on-demand data is completed. | R |
| M8128 | On-demand error flag | Turns ON when an error is included in a specified value for data sending used in the on-demand function (for ch 1). | R |
| M8129 | On-demand data byte/word switch | Specifies the unit (byte or word) of data handled in the on-demand function (for ch 1). ON: Unit = Byte (8-bit) OFF: Unit = Word (16-bit) | R/W |
| M8426 | Global function ON | Turns ON or OFF when the global command (GW) is received from the computer (for ch 2). | R |
| M8427 | On-demand send processing | Remains ON while the on-demand function is being executed (for ch 2). ON: On-demand data is being sent. OFF: Sending of on-demand data is completed. | R |
| M8428 | On-demand error flag | Turns ON when an error is included in a specified value for data sending used in the on-demand function (for ch 2). | R |
| M8429 | On-demand data byte/word switch | Specifies the data unit (byte or word) handled in the on-demand function (for ch 2). ON: Unit = Byte (8-bit) OFF: Unit = Word (16-bit) | R/W |
| M8438 | Serial communication error 2 | Turns ON when an error occurs in serial communication using ch 2. | R |

R: Read only

R/W: Read or Write

*1. FX0N, FX1S, FX1N and FX1NC PLCs do not support this device.

2. Word devices

| Device | Name | Description | R/W |
|--------|---|---|-----|
| D8063 | Serial communication error code 1 | Stores the error code when an error occurs in serial communication using ch 1. | R |
| D8120 | Communication format setting | Sets the communication format (for ch 1). | R/W |
| D8121 | Station number settings | Sets the station number in computer link (for ch 1). | R/W |
| D8127 | On-demand data head device number specification | Sets the head data register device number containing the data to be sent using the on-demand function (for ch 1). | R/W |
| D8128 | On-demand data quantity specification | Sets the amount of data to be sent using the on-demand function (for ch 1). | R/W |
| D8129 | Time-out time setting | Sets the evaluation time for error when the receiving of data from the computer is interrupted (for ch 1). | R/W |
| D8420 | Communication format setting | Sets the communication format (for ch 2). | R/W |
| D8421 | Station number settings | Sets the station number in computer link (for ch 2). | R/W |
| D8427 | On-demand data head device number specification | Sets the head data register device number containing the data to be sent using the on-demand function (for ch 2). | R/W |
| D8428 | On-demand data quantity specification | Sets the amount of data to be sent using the on-demand function (for ch 2). | R/W |
| D8429 | Time-out time setting | Sets the evaluation time for error when the receiving of data from the computer is interrupted (for ch 2). | R/W |
| D8438 | Serial communication error code 2 | Stores the error code when an error occurs in serial communication using ch 2. | R |

R: Read only

R/W: Read or Write

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9.2 Details of Related Devices

The devices described below are used for computer link.

9.2.1 Serial communication error [M8063 and M8438]

These devices turn ON when an error occurs during serial communication.

1. Detailed contents

These devices work as the serial communication error flags.

M8063 turns ON when an error occurs in serial communication in any PLC other than FX3U and FX3UC PLCs or in an FX3U or FX3UC PLC using communication port ch1.

M8438 turns ON when an error occurs in serial communication in an FX3U or FX3UC PLC using communication port ch2.

When serial communication error flags turn ON, a corresponding error code is stored in D8063 and D8438.

9.2.2 Cautions on use

The serial communication error flag does not turn OFF even after communication recovers its normal status. Clear it by switching the PLC mode from STOP to RUN.

9.2.3 Communication setting keep [M8120]

Set this device to ON in a sequence program so that the communication setting is kept (for FX0N PLCs).

1. Detailed contents

In an FX0N PLC, set M8120 to ON in a sequence program so that the communication format setting and station number settings are kept.

2. Cautions on use

In an FX0N PLC, the communication setting status is kept only when M8120 is set to ON.

In any PLC other than FX0N PLCs, setting of M8120 is not required.

9.2.4 Global function ON [M8126 and M8426]

These devices turn ON/OFF when the PLC receives the global command (GW) from personal computers.

1. Detailed contents

When the computer sends the global command, the global ON flag turns ON or OFF in all connected stations.

In all PLCs except FX3U and FX3UC PLCs using communication port ch1, M8126 turns ON or OFF.

In FX3U and FX3UC PLCs using communication port ch2, M8426 turns ON or OFF.

2. Cautions on use

The global ON flag turns OFF from ON when the PLC power is turned OFF or when the PLC mode is changed to STOP.

9.2.5 On-demand send processing [M8127 and M8427]

These devices remain ON while the on-demand function is being executed.

1. Detailed contents

When a PLC gives data sending request using the on-demand function, the on-demand send processing flag turns ON.

In FX2(FX), FX2C and FX2N(C) PLCs and in FX3U and FX3UC PLCs using the communication port ch2, M8127 turns ON/OFF.

In FX3U and FX3UC PLCs using the communication port ch.2, M8427 turns ON/OFF.

2. Cautions on use

Use these devices for interlock to prevent generation of two or more on-demand requests at the same time.

9.2.6 On-demand error flag [M8128 and M8428]

These devices turn ON when an error is included in a specified value for data sending used with the on-demand function.

1. Detailed contents

When the amount of on-demand data is incorrect, the on-demand error flag turns ON.
In all PLCs except FX3U and FX3UC PLCs using communication port ch1, M8128 turns ON.
In FX3U and FX3UC PLCs using communication port ch2, M8428 turns ON.

2. Cautions on use

While the on-demand error flag is ON, data sending is disabled for the on-demand function.
When sending data from a PLC using the on-demand function, set to OFF the on-demand error flag.

9.2.7 On-demand data word/byte changeover [M8129 and M8429]

These devices specify the unit (word or byte) of on-demand data.

1. Detailed contents

Use this device to specify the data unit sent using the on-demand function.
Set these devices to ON to specify "byte" (8-bit). Set these devices to OFF to specify "word" (16-bit).
In all PLCs except FX3U and FX3UC PLCs using communication port ch1, use M8129.
In FX3U and FX3UC PLCs using communication port ch2, use M8429.

2. Cautions on use

When the unit is set to "word", the amount of on-demand data units is equivalent to the number of data registers for sending.
When the unit is set to "byte", two on-demand data units use one data register for sending.
Example: When the amount of on-demand data is "5", the amount of data registers for sending is "3".

9.2.8 Serial communication error code [D8063 and D8438]

These devices store the error codes during serial communication.

1. Detailed contents

When the serial communication error flag (M8063 or M8438) turns ON, a corresponding error code is stored in these devices.
In all PLCs except FX3U and FX3UC PLCs using communication port ch1, an error code is stored in D8063.
In FX3U and FX3UC PLCs using communication port ch2, an error code is stored in D8438.
The error code list is shown below:

| Device | Error code | Error item | Contents of error |
|----------------|------------|----------------------------------|---|
| D8063 (ch1) | 6301 | Parity, overrun or framing error | The transfer data is abnormal. |
| | 6305 | Command error | When the station number was FF, any command other than "GW" was received. |
| | 6306 | Monitoring timeout | The received message was insufficient. Because normal message was not received within the time-out time setting, the transfer sequence was initialized. |
| D8438 (ch2) | 3801 | Parity, overrun or framing error | The transfer data is abnormal. |
| | 3805 | Command error | When the station number was FF, any command other than "GW" was received. |
| | 3806 | Monitoring timeout | The received message was insufficient. Because normal message was not received within the time-out time setting, the transfer sequence was initialized. |

2. Cautions on use

Error codes are not cleared even after communication recovers its normal status.
Clear them by switching the PLC mode from STOP to RUN.

9.2.9 Communication format setting [D8120 and D8420]

These devices set the serial communication format.

1. Detailed contents

These devices set the serial communication format. In FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC PLCs, the contents set in parameters are transferred to these devices when the power is turned ON.

In FX0N, FX2(FX) and FX2C PLCs, set the communication format using a sequence program, and then turn ON the power.

In all PLCs except FX3U and FX3UC PLCs using communication port ch1, use D8120.

Set the communication format using parameters when using the communication port ch2 in FX3U and FX3UC PLCs.

Use D8420 for confirmation.

The tables below show the setting details.

- Contents of D8120

| Bit No. | Name | Contents | |
|----------------------|-------------------|--|---|
| | | 0 (bit = OFF) | 1 (bit = ON) |
| b0 | Data length | 7-bit | 8-bit |
| b1 b2 | Parity | b2, b1 (0, 0): Not provided (0, 1): Odd (1, 1): Even | |
| b3 | Stop bit | 1-bit | 2-bit |
| b4 b5 b6 b7 | Baud rate (bps) | b7, b6, b5, b4 (0, 0, 1, 1): 300 (0, 1, 0, 0): 600 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 | b7, b6, b5, b4 (0, 1, 1, 1): 4800 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 |
| b8 | Header | Not provided | Provided (D8124) Initial value: STX (02H) |
| b9 | Terminator | Not provided | Provided (D8125) Initial value: ETX (03H) |
| b10 b11 | Control line | Com-puter link | b11, b10 (0, 0): RS-485/RS-422 interface (1, 0): RS-232C interface |
| b12 | | Not applicable | |
| b13 | Sum check | Not added | Added |
| b14 | Protocol | Not used | Used |
| b15 | Control procedure | Format 1 | Format 4 |

• Contents of D8420

| Bit No. | Name | Contents | |
|----------------------|-------------------|--|---|
| | | 0 (bit = OFF) | 1 (bit = ON) |
| b0 | Data length | 7-bit | 8-bit |
| b1 b2 | Parity | b2, b1 (0, 0): Not provided (0, 1): Odd (1, 1): Even | |
| b3 | Stop bit | 1-bit | 2-bit |
| b4 b5 b6 b7 | Baud rate (bps) | b7, b6, b5, b4 (0, 0, 1, 1): 300 (0, 1, 0, 0): 600 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 | b7, b6, b5, b4 (0, 1, 1, 1): 4800 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 |
| b8 | Header | Not provided | Provided |
| b9 | Terminator | Not provided | Provided |
| b10 b11 b12 | Control line | Com- puter link | b12, b11, b10 (0, 0, 0): RS-485/RS-422 interface (0, 1, 0): RS-232C interface |
| b13 | Sum check | Not added | Added |
| b14 | Protocol | Not used | Used |
| b15 | Control procedure | Format 1 | Format 4 |

2. Cautions on use

Do not use both the parameters and communication format setting devices (D8120 or D8420) at the same time. If the communication format is set using both methods at the same time, priority is given to the setting using parameters.

When setting the communication format device (D8120) in an FX0N PLC, set the communication setting latched (battery backed) device (M8120) to ON.

When using computer link, make sure to set the header (b8) and terminator (b9) to "not provided". And set the protocol (b14) to "used".

If the communication format is set using the special data register, the setting becomes valid when the power is turned ON after the setting is written to the special data register.

9.2.10 Station number settings [D8121 and D8421]

These devices set the station number in computer link.

1. Detailed contents

Set the station number of each PLC used in computer link. The applicable setting range is from 0 to 15 (from H00 to H0F).

In FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC PLCs, the contents set using parameters are stored when the power is turned ON.

In FX0N, FX2(FX), and FX2C PLCs, set the station number using a sequence program, and then turn ON the power.

In all PLCs except FX3U and FX3UC PLCs and in FX3U and FX3UC PLCs using communication port ch1, use D8121.

Set the station number using parameters when using the communication port ch2 in FX3U and FX3UC PLCs. Use D8421 for confirmation.

2. Cautions on use

Do not use both the parameters and station number settings device (D8121 or D8421) at the same time. If the station number is set using both methods at the same time, priority is given to the setting using a parameter.

When setting the station number settings device (D8121) in an FX0N PLC, set the communication setting latched (battery backed) device (M8120) to ON.

9.2.11 On-demand data head device number specification [D8127 and D8427]

These devices set the head data register device number containing the data to be sent using the on-demand function in a sequence program.

1. Detailed contents

These devices set the head data register device number containing the data to be sent using the on-demand function.

In all PLCs except FX3U and FX3UC PLCs and in FX3U and FX3UC PLCs using communication port ch1, use D8127.

In FX3U and FX3UC PLCs using communication port ch2, use D8427.

If there is an error in the set data, the on-demand error flag (M8128 or M8428) turns ON.

2. Cautions on use

When setting the on-demand data head device number specification device (D8127 or D8427), set the flag using the pulse operation type.

While the on-demand send processing flag (M8127 or M8427) is ON, do not write data.

9.2.12 On-demand data quantity specification [D8128 and D8428]

These devices set the amount of data to be sent from a PLC using the on-demand function in a sequence program.

1. Detailed contents

These devices set the amount of data to be sent using the on-demand function. Set the amount of data 64 or less.

In all PLCs except FX3U and FX3UC PLCs using communication port ch1, use D8128.

In FX3U and FX3UC PLCs using communication port ch2, use D8428.

If an error is included in the set data, the on-demand error flag (M8128 or M8428) turns ON.

2. Cautions on use

When setting the on-demand data quantity specification device (D8128 or D8428), set the flag using the pulse operation type.

While the on-demand send processing flag (M8127 or M8427) is ON, do not write data.

9.2.13 Time-out time setting [D8129 and D8429]

These devices set the evaluation time for error when receiving of data from the computer is interrupted.

1. Detailed contents

These devices set the error evaluation time in 10-ms units used when the receiving of data from the computer is interrupted.

In all PLCs except FX3U and FX3UC PLCs using communication port ch1, use D8129.

Set the time-out time setting using parameters when using the communication port ch2 in FX3U and FX3UC PLCs.

Use D8429 for confirmation.

The table below shows the setting range.

| FX Series | Setting range |
|---|--|
| FX0N, FX1S, FX1N, FX1NC | 1 to 255 (10 to 2550 ms) (When "0" is set, it is handled as "100 ms.") |
| FX2(FX), FX2C, FX2N, FX3U, FX2NC, FX3UC | 1 to 3276 (10 to 32760 ms) (When "0" is set, it is handled as "100 ms.") |

2. Cautions on use

When setting the time-out time setting device (D8129) in an FX0N PLC, set the communication setting latched (battery backed) device (M8120) to ON.

Make sure that the time-out time setting is not shorter than the time required to receive one character at the set baud rate.

9.3 Communication Setting Method Using Sequence Program

When adjusting the communication setting using a sequence program, transfer values to D8120 (communication format), D8121 (station number settings) and D8129 (time-out time setting), and then turn the power ON.

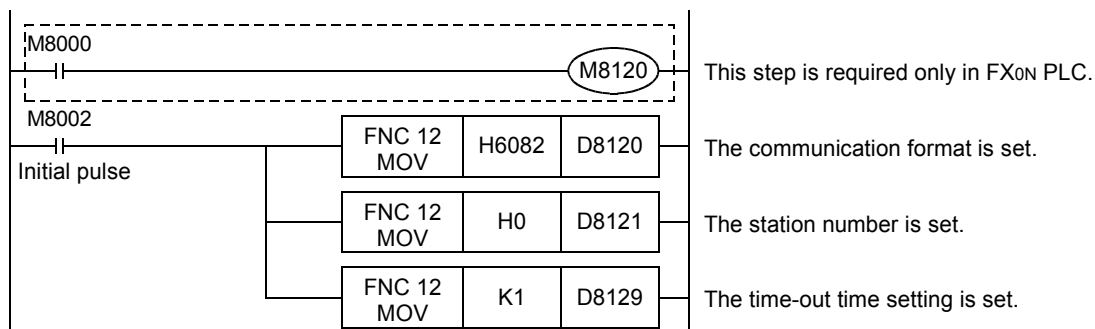
This section explains the communication setting method using a sequence program.

9.3.1 Setting procedure

Perform the following procedure to set the communication using a sequence program.

1 Creating a program using a programming tool

Create the program shown below using a programming tool.



→ For details on these devices, refer to Section 9.2.

2 Writing the sequence program to the PLC

Transfer the created program to the PLC.

3 Setting the PLC mode to RUN

Set the PLC to RUN mode, and execute the program.

4 Turning the PLC power OFF and then ON

Turn OFF the PLC power, and then turn it to ON so that the communication setting becomes valid.

9.3.2 Caution on communication setting using sequence program

Do not set the communication using a sequence program and parameters at the same time.
If the communication is set using both methods at the same time, priority is given to the setting using parameters.

9.4 ASCII Code Table

<ASCII code table (8-bit code expressed in hexadecimal)>
The ASCII codes A1H to DFH indicate Japanese characters.

| Hexa deci- mal | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | A | B | C | D | E | F |
|----------------------|-----|-----|----|---|---|-----|---|-----|---|---|---|---|---|---|---|---|
| 0 | | DLE | SP | 0 | @ | P | ` | p | | | | ー | ﾀ | ﾐ | | |
| 1 | SOH | DC1 | ! | 1 | A | Q | a | q | | | 。 | ｱ | ﾁ | ﾒ | | |
| 2 | STX | DC2 | " | 2 | B | R | b | r | | | 「 | ｲ | ｯ | ｾ | | |
| 3 | ETX | DC3 | # | 3 | C | S | c | s | | | 」 | ｳ | ﾃ | ﾜ | | |
| 4 | EOT | DC4 | \$ | 4 | D | T | d | t | | | , | ｴ | ﾄ | ｵ | | |
| 5 | ENQ | NAK | % | 5 | E | U | e | u | | | . | ｵ | ｴ | ｵ | | |
| 6 | ACK | SYN | & | 6 | F | V | f | v | | | ヲ | ｶ | ﾆ | ﾖ | | |
| 7 | BEL | ETB | ' | 7 | G | W | g | w | | | ｱ | ｷ | ｽ | ﾗ | | |
| 8 | BS | CAN | (| 8 | H | X | h | x | | | ｲ | ｸ | ﾈ | ﾘ | | |
| 9 | HT | EM |) | 9 | I | Y | i | y | | | ｳ | ｹ | / | ﾙ | | |
| A | LF | SUB | * | : | J | Z | j | z | | | ｴ | ｺ | ﾊ | ﾚ | | |
| B | VT | ESC | + | ; | K | [| k | { | | | ｵ | ｻ | ﾋ | ロ | | |
| C | FF | FS | , | < | L | *1 | l | | | | ｴ | ｼ | ﾌ | ｳ | | |
| D | CR | GS | — | = | M |] | m | } | | | ｵ | ｽ | ｴ | ﾝ | | |
| E | SO | RS | . | > | N | ^ | n | ~ | | | ヨ | セ | ホ | ° | | |
| F | SI | US | / | ? | O | _ | o | DEL | | | ッ | ソ | マ | 。 | | |

*1. \ (ASCII CODE:5C) symbol is displayed as "¥" in Japanese.

FX Series Programmable Controllers

User's Manual [Inverter Communication]

Foreword

This manual explains "inverter communication" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit. Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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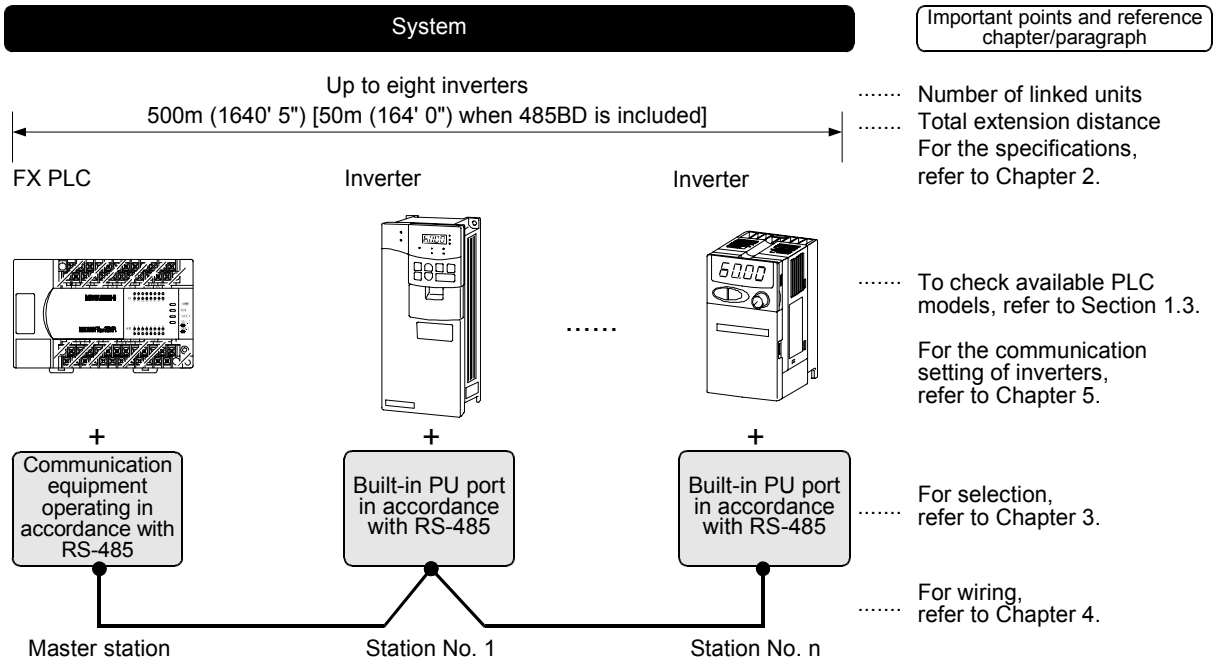
1. Outline

This chapter explains inverter communication.

1.1 Outline of System

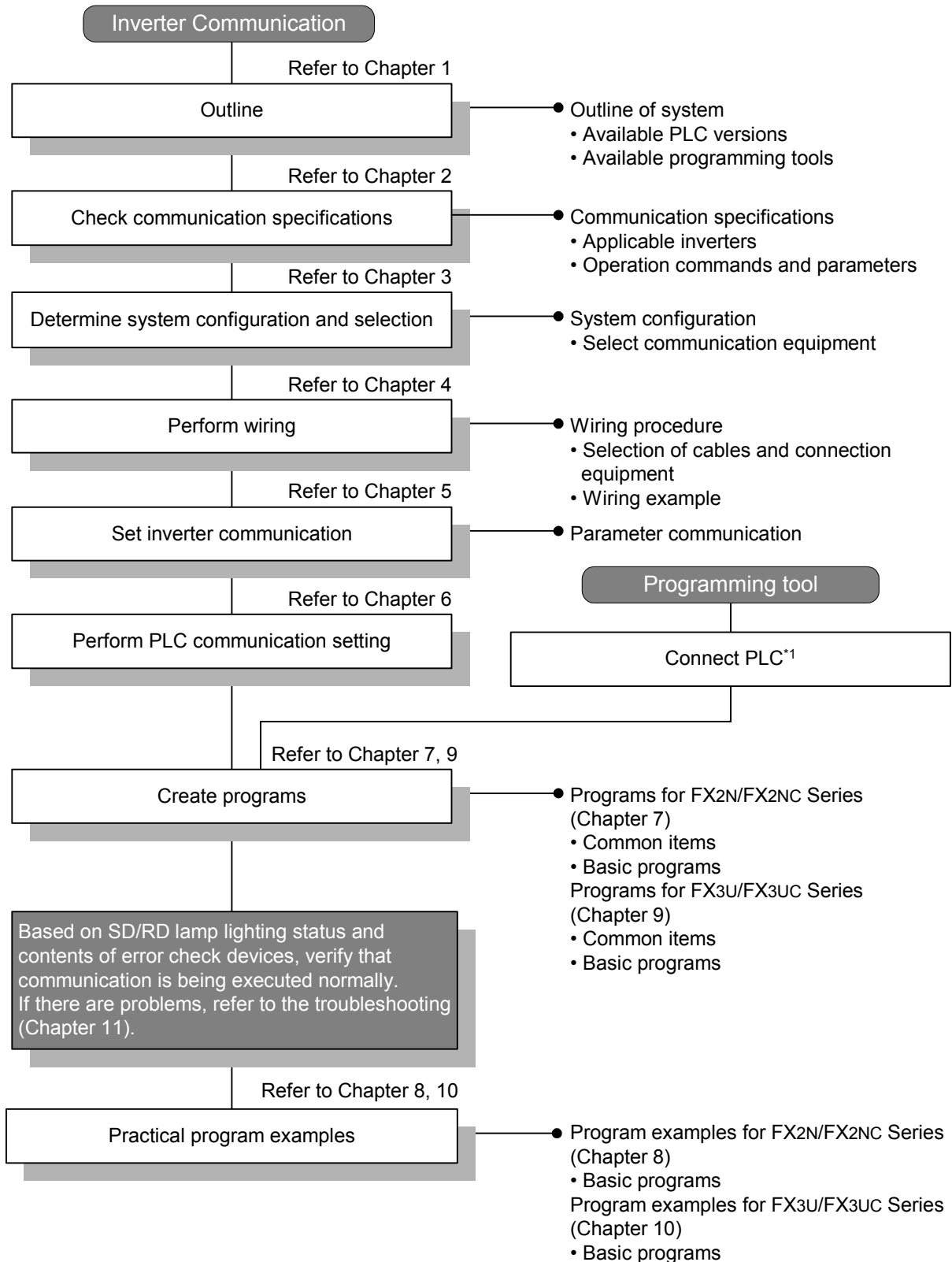
Inverter communication allows connection between an FX PLC and up to eight inverters to monitor operations of inverters, give various commands to inverters and read and write inverter parameters through communication via RS-485 .

- 1) Mitsubishi general-purpose inverters FREQROL F700, A700, E700, V500, F500, A500, E500 and S500 (containing the communication type) Series can be linked.
(F700, A700, E700, V500 and F500 Series inverters can be connected only to FX3U and FX3UC PLCs.)
- 2) Inverter operations can be monitored, various command can be given to inverters, and parameters can be read or written in inverters.
- 3) The total extension distance is 500m (1640' 5") maximum (for the system configured with 485ADP only).



1.2 Procedures Before Operation

The flow chart below shows the Inverter Communication setting and sequence programs creation procedures up until data link:



*1 For the programming tool to PLC connection procedure, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operation method, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 For applicable versions

The communication types are applicable for the following versions.

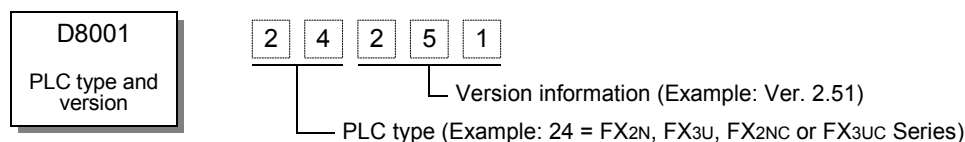
- ✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|------------------------------------|--|
| FX3UC Series | ✓*1*3 | F700, A700, E700, V500, F500, A500, E500 and S500 Series inverters can be connected. |
| FX3U Series | ✓*3 | |
| FX2NC Series | ✓ (Ver. 3.00 or later)*2 | A500, E500 and S500 Series inverters can be connected. |
| FX2N Series | ✓ (Ver. 3.00 or later)*2 | |
| FX1NC Series | — | Inverter communication is not provided. |
| FX1N Series | — | Inverter communication is not provided. |
| FX1s Series | — | Inverter communication is not provided. |
| FX0N Series | — | Inverter communication is not provided. |
| FX0s Series | — | Inverter communication is not provided. |
| FX0 Series | — | Inverter communication is not provided. |
| FX2C Series | — | Inverter communication is not provided. |
| FX2(FX) Series | — | Inverter communication is not provided. |
| FX1 Series | — | Inverter communication is not provided. |

- *1. F700 and A700 Series inverters are supported in Ver. 2.20 and later.
Product manufactured in May, 2005 (manufacturer's serial number: 55****)
- *2. Applicable in products manufactured in May, 2001 (manufacturer's serial No.: 15****) and later.
- *3. E700 Series inverter is supported in Ver.2.32 and later.

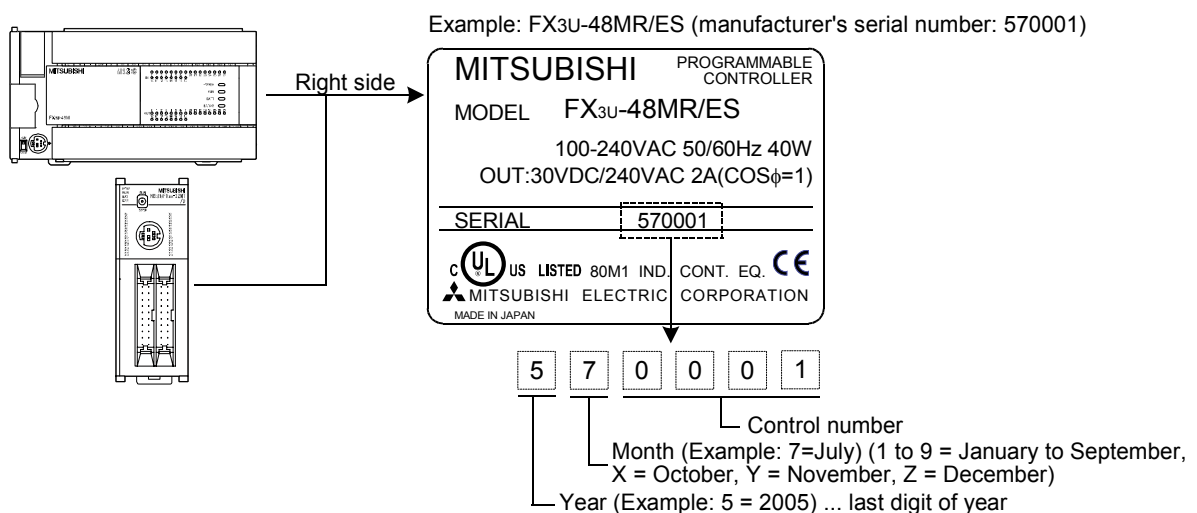
1. Version check

The D8001(decimal) special data register contains information for determining the PLC version.



2. How to look at the manufacturer's serial number

The year and month of production of product can be seen from the Manufacturer's serial number "SERIAL" indicated on the label adhered to the right side of the product.



1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the version shown:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW7 A or later) | Select the model "FX2N/FX2NC" The versions shown on the left supporting EXTR instruction are applicable |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.20 or later) | |
| FX-20P(-SET0) FX-20P-MFXD | ✓ (Ver. 5.10 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 4.10 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.30 or later) F940GOT-LWD, F940GOT-SWD (Ver. 6.30 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 6.30 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 6.30 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW7 A or later) | Select the model "FX2N/FX2NC" The versions shown on the left supporting EXTR instruction are applicable |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.10 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXD-E | ✓ (Ver. 4.10 or later) | |
| FX-10P-E | ✓ (Ver. 4.10 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column) | F940WGOT-TWD-E (Ver. 1.30 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 6.30 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 6.30 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 6.30 or later) |

1.4.2 For non-applicable versions (setting an alternative model)

Programming not possible using software of non-applicable version.

2. Specifications

This chapter explains the communication specifications and performance.

2.1 Communication Specifications (Reference)

| Item | Specifications | Remarks |
|----------------------------------|---|--|
| Number of connectable units | 8 maximum | |
| Transmission standard | RS-485 standard | |
| Maximum total extension distance | 500 m (1640' 5") or less when 485ADP is used 50 m (164' 0") or less when 485BD is used | Distance varies depending on communication equipment type. |
| Protocol type | Inverter computer link | Link startup mode |
| Control procedure | Asynchronous system | |
| Communication method | Half-duplex, bidirectional communication | |
| Baud rate | 4800, 9600 or 19200 bps | Any one can be selected. |
| Character format | ASCII | |
| Start bit | — | |
| Data bit | 7-bit | |
| Parity bit | Even | |
| Stop bit | 1-bit | |

2.2 Connectable Mitsubishi General-purpose Inverters

| Series | Built-in PU connector | FR-A5NR (option) | Remarks |
|--------------|-----------------------|--------------------------|--|
| FREQROL S500 | ✓ | — | Only models containing the RS-485 communication type can be connected. |
| FREQROL E500 | ✓ | — | |
| FREQROL A500 | ✓ | ✓ | |
| FREQROL F500 | ✓ | ✓ | They can only be connected to FX3U and FX3UC PLCs. |
| FREQROL V500 | ✓ | ✓ | |
| Series | Built-in PU connector | Built-in RS-485 terminal | Remarks |
| FREQROL E700 | ✓ | — | They can only be connected to FX3U*1 and FX3UC*1 PLCs. |
| FREQROL A700 | — | ✓ | |
| FREQROL F700 | — | ✓ | |

- *1. F700 and A700 Series inverters are supported in Ver. 2.20 and later.
E700 Series inverter is supported in Ver. 2.32 and later.

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Apx.
Discontinued models

2.3 Link Specifications

The tables below show applicable parameters and operation commands.

2.3.1 When monitoring inverter operations (PLC ← inverter)

| Instruction code (hexadecimal) | Read contents | Applicable inverter | | | | | | | |
|-----------------------------------|--|---------------------|------|------|------|------|------|------|------|
| | | F700 | A700 | E700 | V500 | F500 | A500 | E500 | S500 |
| H7B | Operation mode | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H6F | Output frequency [number of rotations] | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H70 | Output current | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H71 | Output voltage | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — |
| H72 | Special monitor | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — | — |
| H73 | Special monitor selection number | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — | — |
| H74 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H75 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H76 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — |
| H77 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — |
| H79 | Inverter status monitor (extended) | ✓ | ✓ | ✓ | — | — | — | — | — |
| H7A | Inverter status monitor | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H6E | Set frequency (EEPROM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H6D | Set frequency (RAM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |

2.3.2 When controlling inverter operations (PLC → inverter)

| Instruction code (hexadecimal) | Written contents | Applicable inverter | | | | | | | |
|-----------------------------------|----------------------------------|---------------------|------|------|------|------|------|------|------|
| | | F700 | A700 | E700 | V500 | F500 | A500 | E500 | S500 |
| HFB | Operation mode | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HF3 | Special monitor selection number | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — | — |
| HF9 | Run command (extended) | ✓ | ✓ | ✓ | — | — | — | — | — |
| HFA | Run command | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HEE | Set frequency (EEPROM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HED | Set frequency (RAM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HFD | Inverter reset | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HF4 | Alarm definition all clear | ✓ | ✓ | ✓ | — | ✓ | ✓ | ✓ | ✓ |
| HFC | All parameter all clear | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HFC | User clear | ✓ | ✓ | ✓ | — | ✓ | ✓ | — | — |

2.3.3 Parameters (PLC ↔ inverter)

For inverter parameters which can be changed (read and written), refer to "12. Related Detailed Data" later.

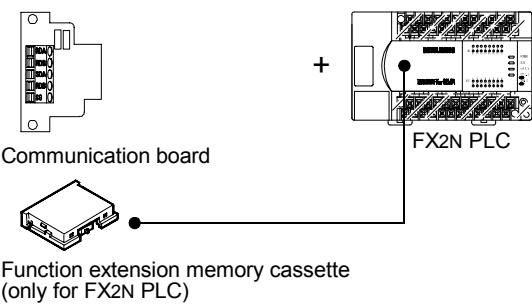
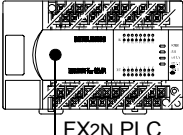
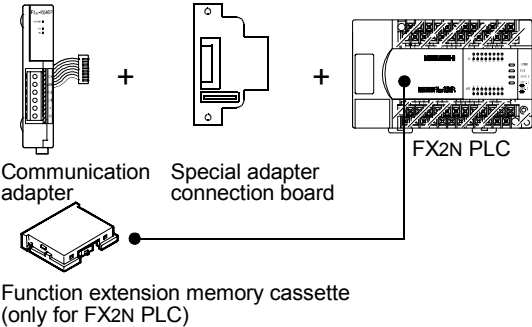
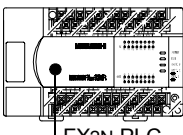
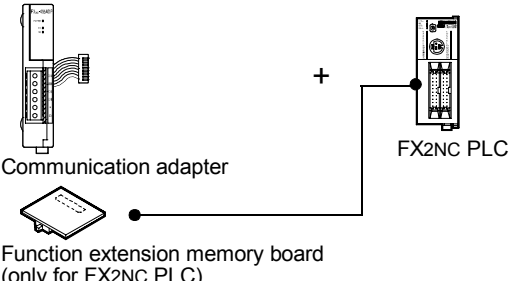
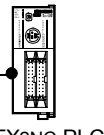
3. System Configuration and Selection

This chapter explains the system configuration and communication equipment selection operating in accordance with RS-485 required by FX PLCs.

3.1 System Configuration

This section outlines the system configuration required to use inverter communication. Connect (optional) equipment operating in accordance with RS-485 to the FX PLC main unit.

1 **2** **3** **4** and **5** indicate the communication equipment combination patterns.

| Communication equipment operating in accordance with RS-485 | FX PLC | Important point in selection | Total extension distance |
|--|---|--|--------------------------|
| 1  Communication board Function extension memory cassette (only for FX2N PLC) | +  FX2N PLC | This is the communication board built into the PLC, reducing the installation area. | 50 m (164' 0") |
| 2  Communication adapter Special adapter connection board Function extension memory cassette (only for FX2N PLC) | +  FX2N PLC | Attach the special adapter connection board to the main unit, and then attach the communication adapter to the left side of the main unit. | 500 m (1640' 5") |
| 3  Communication adapter Function extension memory board (only for FX2NC PLC) | +  FX2NC PLC | Attach the communication adapter to the left side of the main unit. | 500 m (1640' 5") |

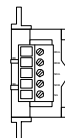
Communication equipment operating
in accordance with RS-485

FX PLC

Important point in selection

Total extension
distance

4



Communication board

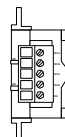
+



FX3U PLC

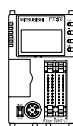
Because the communication board
can be built in to the PLC, the
installation area does not change

50 m
(164' 0")



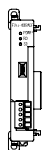
Communication board

+



FX3UC-32MT-LT

5



Communication
adapter

+



Expansion
board

+



FX3U PLC

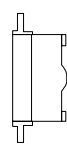
Attach the expansion board to the
main unit, and then attach the
communication adapter to the left
side of the main unit.

500 m
(1640' 5")



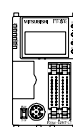
Communication
adapter

+



Expansion
board

+



FX3UC-32MT-LT

6



Communication
adapter

+



FX3UC(D, DSS)

Attach the communication adapter to
the left side of the main unit.

500 m
(1640' 5")

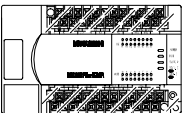
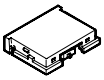
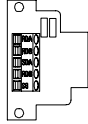
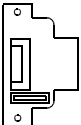
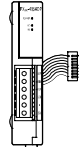
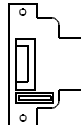
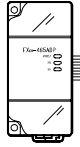
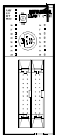

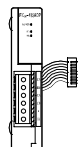
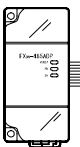


For communication equipment combinations for each FX Series, refer to the next section.

3.2 Applicable FX PLC and Communication Equipment

Select a (optional) communication equipment combination, and put a check mark in the "Check" column.
During selection, pay attention to the following:

- In the table below, only the external dimensions are different between the units shown in "FX2NC-485ADP/FX0N-485ADP".
Select either one.
- Inverter communication is not provided for the FX0, FX0S, FX0N, FX1, FX2(FX), FX2C, FX1S, FX1N, and FX1NC Series.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX2N +  FX2N-ROM-E1 (Function extension memory cassette) |  FX2N-485-BD | 50 m (164' 0") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-485ADP FX2N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX2NC +  FX2NC-ROM-CE1 (Function extension memory board) |  /  FX2NC-485ADP FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |

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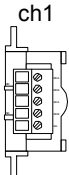
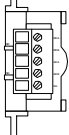


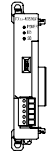


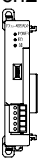
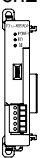



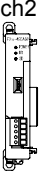
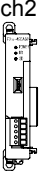
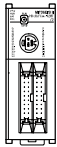
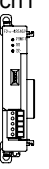
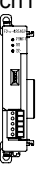


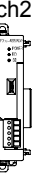
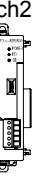
F
Non-Protocol Communication (RS/RSS2 Instruction)

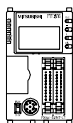
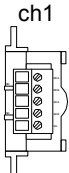




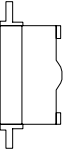


G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1  FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  ch1  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1  FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  ch2  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  ch1  FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  ch2  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX3UC (D, DSS) | When using channel 1 (ch 1) | | |
| |  ch1  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1  FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  ch2  FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3UC-32MT-LT | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |   + FX3U-CNV-BD FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |   + ch1 ch2 FX3U-□-BD FX3U-485ADP(-MB) (Where □ represents 232, 422, 485, and USB). (European terminal block) | 500 m (1640' 5") | |
| |    + + ch1 ch2 FX3U-CNV-BD FX3U-□ADP(-MB) FX3U-485ADP(-MB) (Where □ represents 232 and 485). (European terminal block) | 500 m (1640' 5") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

4. Wiring

This chapter explains the wiring.

WIRING PRECAUTIONS



DANGER

- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to attach the terminal cover, offered as an accessory, before turning on the power or initiating operation after installation or wiring work. Failure to do so may cause electric shock.

WIRING PRECAUTIONS



CAUTION

- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to abnormal data written to the PLC under the influence of noise:
 - 1) Do not bundle the main circuit line together with or lay it close to the main circuit, high-voltage line or load line. Otherwise, noise disturbance and/or surge induction are likely to take place. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or high-voltage line.
 - 2) Ground the shield wire or shield of the shielded cable at one point on the PLC. However, do not use grounding with heavy electrical systems.
- Make sure to properly wire the FX0N/FX2N Series extension equipment in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should follow the specifications in this manual.
- Make sure to properly wire to the European terminal board in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should be follow the specifications in this manual.
 - Twist the end of strand wire and make sure that there are no loose wires.
 - Do not solder-plate the electric wire ends.
 - Do not connect more than the specified number of wires or electric wires of unspecified size.
 - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

4.1 Wiring Procedure

1 Confirming the connection method

Confirm the inverter connection method.

→ For details, refer to Section 4.2.

2 Preparing for wiring

Prepare cables, distributors and terminal resistors required for wiring.

→ For connection cables, refer to Section 4.3.

→ For distributors, refer to Section 4.4.

→ For terminal resistors, refer to Section 4.5.

3 Turning OFF the PLC power

Before starting any wiring work, make sure that the PLC power is OFF.

4 Connecting the power supply (FX0N-485ADP only)

Connect the power supply to the 24V DC power terminal.

5 Wiring communication equipment

Connect communication equipment with communication port of inverters (PU port, built-in terminal for RS-485, FR-A5NR).

→ For details, refer to Section 4.8.

6 Connecting terminal resistors

Connect terminal resistors to the communication equipment of the PLC and the RDA-RDB signal terminal in the last inverter.

→ For details, refer to Section 4.5.

7 Wiring a shielding wire (Class-D grounding)

When using a twisted pair cable, wire a shielding wire.

→ For details, refer to Section 4.6.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

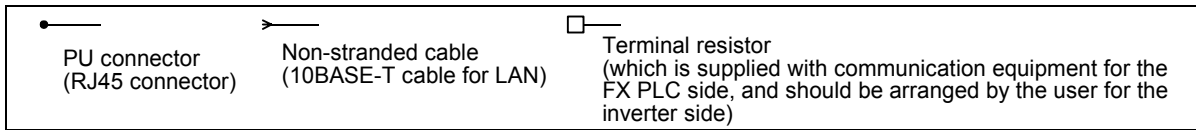
Remote Maintenance

Apx.

Discontinued models

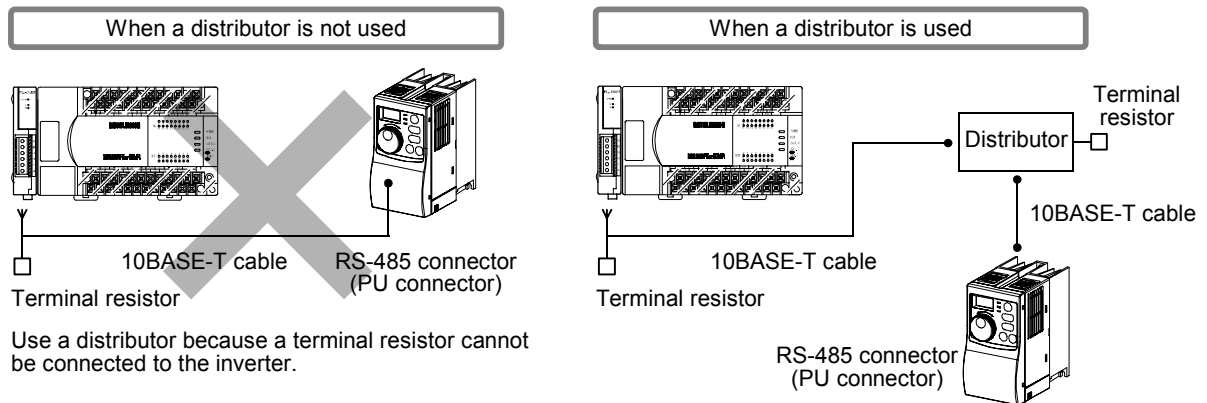
4.2 Selecting Cables and Connection Devices

When connecting equipment operating in accordance with RS-485, use the following connection method with 10BASE-T or shielded twisted pair cables.

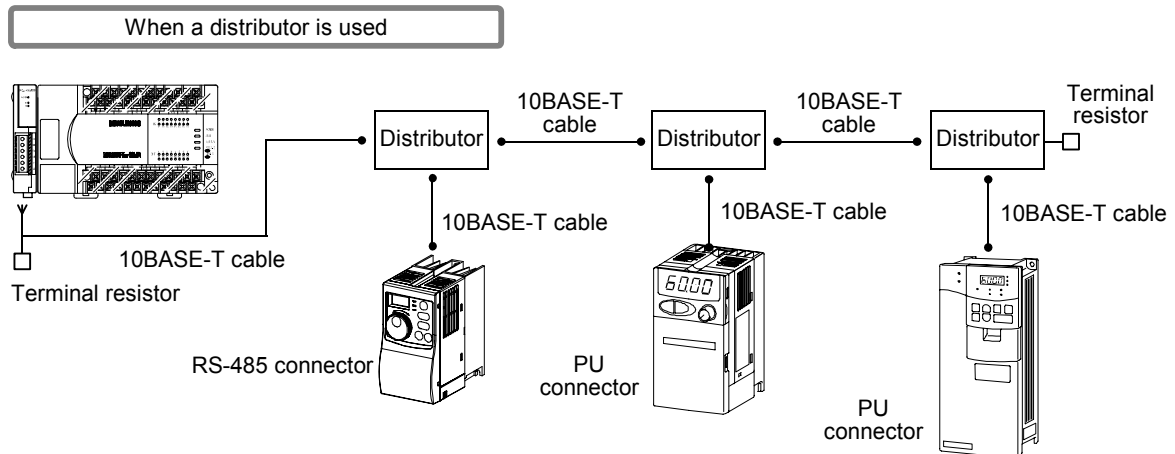


4.2.1 S500, E500, A500, F500, V500 and E700 Series (PU connector)

1. In the case of 1-to-1 connection

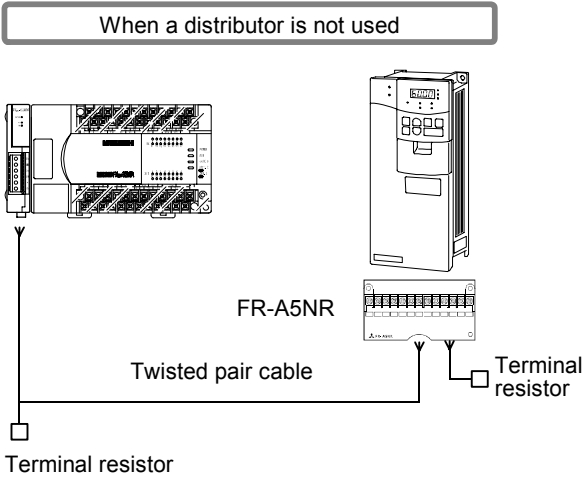


2. In the case of 1-to-N connection

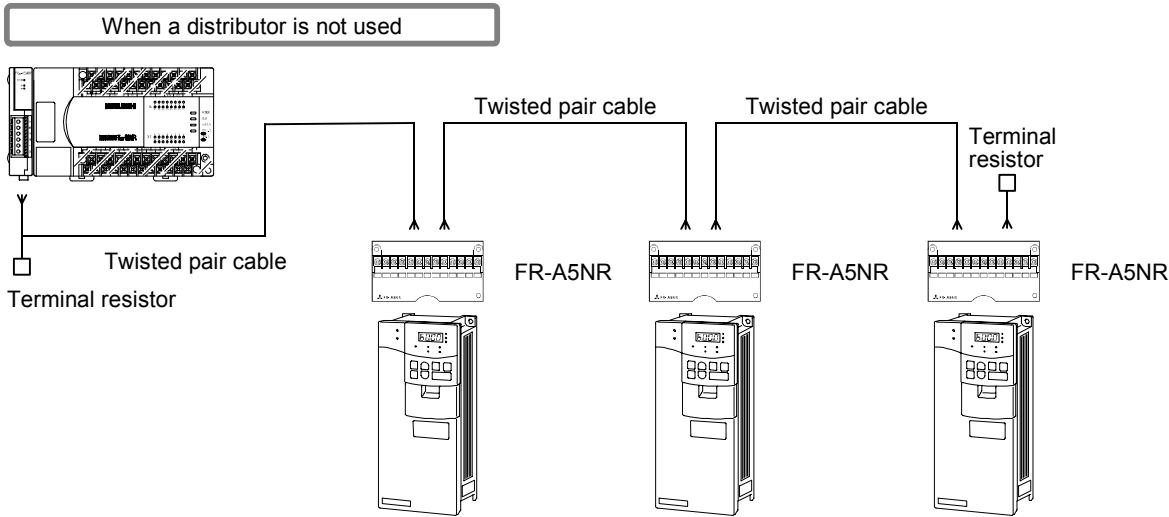


4.2.2 A500, F500 and V500 Series (FR-A5NR)

1. In the case of 1-to-1 connection



2. In the case of 1-to-N connection



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

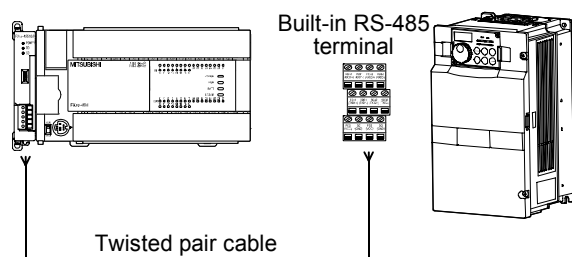
Apx.

Discontinued models

4.2.3 F700 and A700 Series (built-in RS-485 terminal)

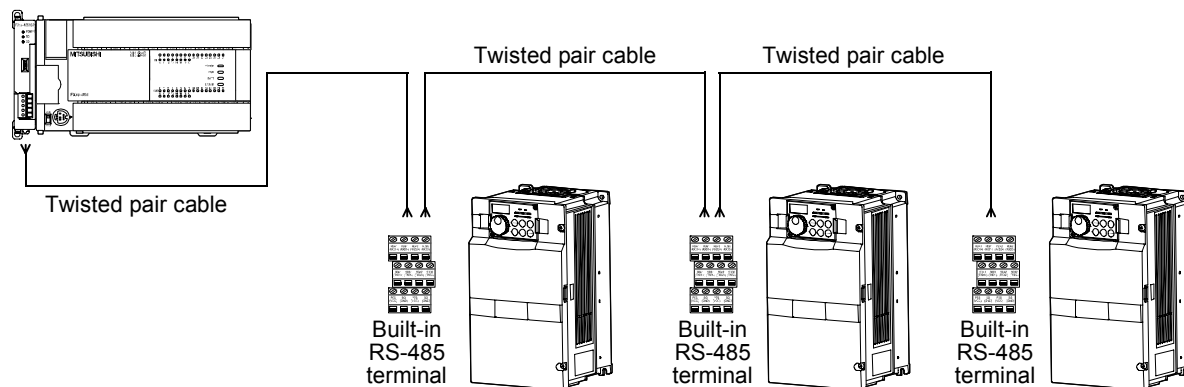
1. In the case of 1-to-1 connection

Set the terminal resistor switch in the F700/A700 Series inverter to "100 Ω ".



2. In the case of 1-to-N connection

Set the terminal resistor switch in the last F700/A700 Series inverter to "100 Ω ".



4.3 Connection Cables

4.3.1 Ethernet (10BASE-T) cable

Ethernet cables used in the LAN wiring for a personal computer can be connected.

1. Selection procedure when purchasing

- 1) Cable type : Ethernet cable in accordance with 10BASE-T (Category 3 or 5)
- 2) Connection specifications : Straight type
- 3) Connector : RJ45 connector

2. Cautions on using commercial cables

Pay attention to the following point when purchasing commercial cables

- 5V DC is output to the PU connector in the inverters for supplying power to the PU.
It is necessary to cut pins No. 2 and 8 of commercial cables to prevent wiring to pins No. 2 and 8.

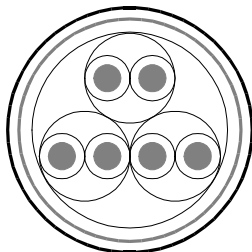
4.3.2 Twisted pair cable (recommended)

The table below shows recommended model names and manufacturers of cables used in wiring.
Use commercial three-pair type twisted pair cables of 0.3 mm² or more.

1. Recommended cable list

| Manufacturer | Model name | Remarks |
|------------------------------------|--------------------|---|
| Sumitomo Electric Industries, Ltd. | DPEV SB 0.3 × 3P | Three-pair cable of 0.3 mm ² |
| | DPEV SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| The Furukawa Electric Co., Ltd. | D-KPEV-SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |

2. Cable structural drawing (reference)



Three-pair cable structural drawing example

3. Point of contact

For details on cables such as specifications and price, contact each cable manufacturer.

4.3.3 Connecting cables

1. European type terminal block

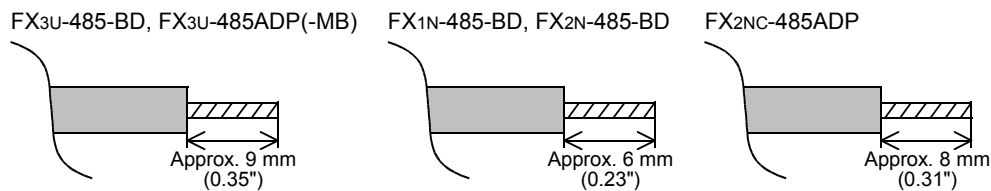
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows applicable cables and tightening torques.

| | Cable size when one cable is connected | Cable size when two cables are connected | Cable size for bar terminal with insulating sleeve | Tightening torque | Tool size | |
|----------------------------------|--|--|--|-------------------|-------------|-------------|
| | | | | | A | B |
| FX3U-485-BD FX3U-485ADP (-MB) | AWG22 to AWG20 | AWG22 | AWG22 to AWG20 | 0.22 to 0.25 N·m | 0.4 (0.01") | 2.5 (0.09") |
| FX2N-485-BD | AWG26 to AWG16 | | — | 0.6 N·m | 0.6 (0.03") | 3.5 (0.14") |
| FX2NC-485ADP | AWG26 to AWG16 | AWG26 to AWG20 | — | 0.4 to 0.5 N·m | 0.6 (0.03") | 3.5 (0.14") |

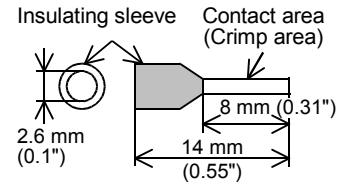
With regard to the cable end treatment, use a stranded cable or solid cable as it is, or use a bar terminal with insulating sleeve.

- When using a stranded cable or solid cable as it is
 - Twist the end of a stranded cable so that wires do not get barbed.
 - Do not plate the end of the cable.



- When using a bar terminal with insulating sleeve
Because it is difficult to insert a cable into an insulating sleeve depending on the thickness of the cable sheath, select the proper cable according to the outline drawing.

| Manufacturer | Model name | Caulking tool |
|-----------------|------------|-------------------------------------|
| Phoenix Contact | AI 0.5-8WH | CRIMPFOX ZA 3 (or CRIMPFOX UD 6) |

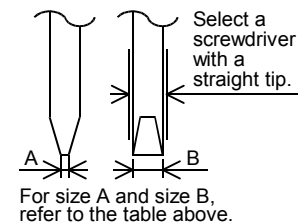


- Tool
 - When tightening a terminal on the European terminal block, use a small commercial straight shape screwdriver whose tip is shown in the figure to the right.

Note:

If the diameter of screwdriver grip is too small, tightening torque will not be able to be achieved. Use the following recommended screwdriver or an appropriate replacement (grip diameter: approximately 25mm).

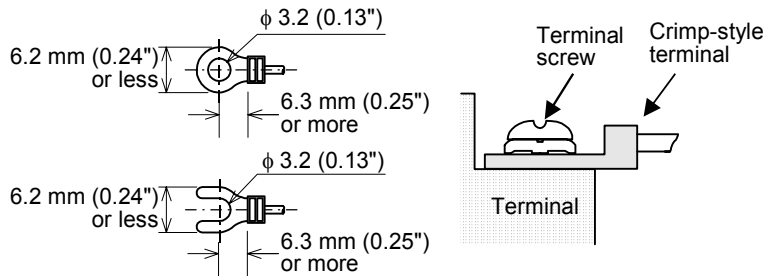
| Manufacturer | Model name |
|-----------------|---------------|
| Phoenix Contact | SZS 0.4 × 2.5 |



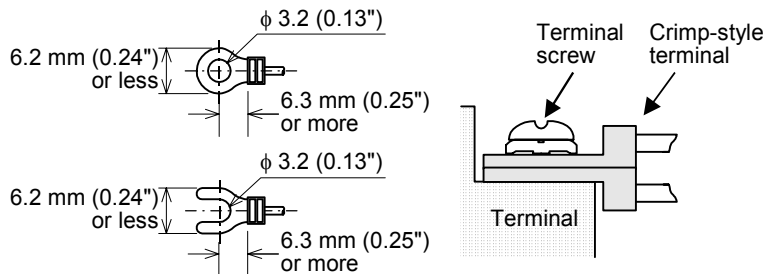
2. Terminal block

In the FX0N-485ADP, the terminal screw size is "M3".
Make sure to use a crimp-style terminal with the following sizes.
Make sure that the tightening torque is 0.5 to 0.8 N·m.

- When wiring one cable to one terminal



- When wiring two cables to one terminal



4.4 Connection Devices (RJ45 Connector and Distributor)

Prepare the following devices if necessary.

| Product name | Model name | Manufacturer | Check |
|----------------|--|---------------------------|-------|
| RJ45 connector | 5-554720-3 | Tyco Electronics AMP K.K. | |
| Distributor | BMJ-8 Modular rosette Do not use a plug with terminal resistor supplied together with the modular rosette above. | HACHIKO ELECTRIC CO., LTD | |

4.5 Connecting Terminal Resistors

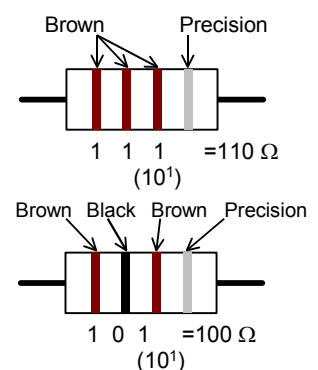
Connect a terminal resistor to both the communication equipment of the FX PLC and the RDA-RDB signal terminal in the last inverter.

→ For details on connection, refer to each wiring diagram.

1. Terminal resistor types

Prepare the following two types of terminal resistors.
Among the terminal resistors supplied with the communication equipment, select ones with the color codes shown to the right.

- On the FX PLC side, use a terminal resistor of 110 Ω , 1/2 W supplied together with the communication equipment operating in accordance with RS-485.
- On the inverter side (PU connector except FR-A5NR), use a terminal resistor of 100 Ω , 1/2 W (not supplied).
- On the inverter side (FR-A5NR), use a terminal resistor chip (supplied together with the FR-A5NR).

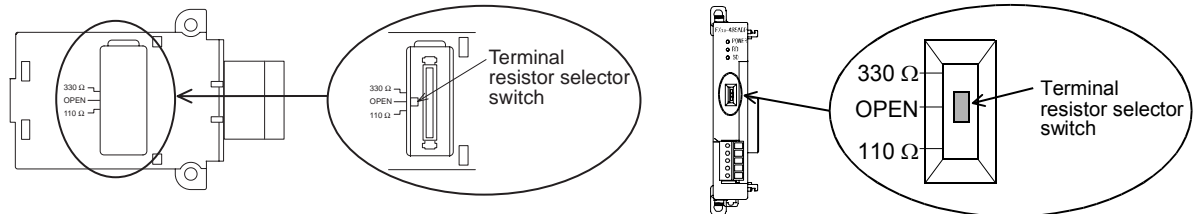


2. Connecting a terminal resistor to the FX PLC

Connect a terminal resistor between the RDA and RDB terminals of the communication equipment.

3. When using the FX3U-485-BD or FX3U-485ADP(-MB)

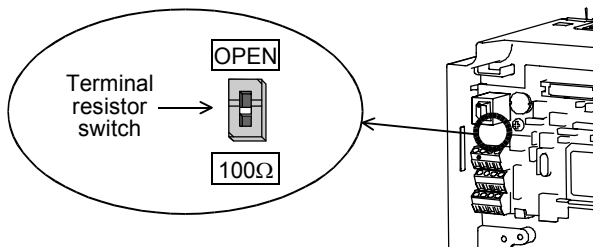
The FX3U-485-BD and FX3U-485ADP(-MB) have built-in terminal resistors. Set the terminal resistor selector switch accordingly.



4. Connecting a terminal resistor to the inverter

Communication may be affected by noise echo depending on the transmission speed and transmission distance. When communication is hindered by noise echo, connect a terminal resistor to the inverter.

- 1) When the PU connector or RS-485 connector (S500 Series) is used
 - Connect a terminal resistor between pin No. 3 (RDA) and pin No. 6 (RDB).
 - Connect a distributor to the PU terminal because terminal resistors cannot be connected.
 - Connect a terminal resistor only to the inverter located furthest away from the FX PLC.
- 2) When the FR-A5NR is used in connection
 - Connect a terminal resistor chip (which is supplied together with the FR-A5NR) between the RDB and RDR terminals in the most distant inverter.
- 3) When the F700 or A700 Series inverter built-in RS-485 terminal is used
A terminal resistor is built into the RS-485 terminal. Set the terminal resistor switch in the F700/A700 Series inverter located at the end to "100Ω".



4.6 Wiring a Shielding Wire (Class-D grounding)

Perform Class-D grounding only to one side of a cable according to the absence/presence of the grounding terminal.

→ For details on connection, refer to each wiring diagram.

1. When the ☐ FG terminal is provided in the communication equipment

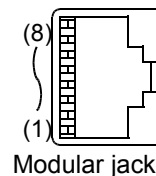
Connect the ☐ FG terminal to the ☐ (grounding) terminal of the PLC requiring Class-D grounding.

2. When the ☐ FG terminal is not provided in the communication equipment

Perform Class-D grounding directly to the shielding wire of the cable.

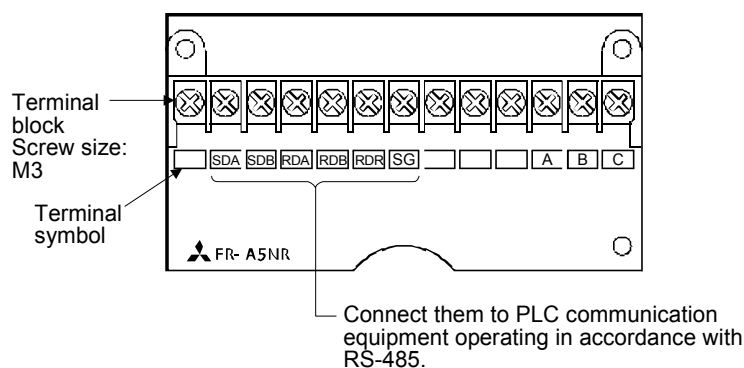
1. In the case of PU port connector

When seen from inverter front
(receptacle side)



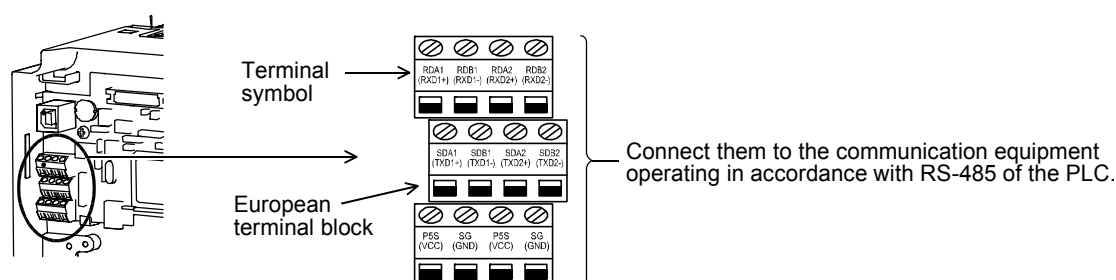
2. In the case of computer link using the FR-A5NR

Attach the FR-5NR to an A500, F500 or V500 Series inverter.



→ For details, refer to the instruction manual of the FR-A5NR.

F700 and A700 Series inverters are equipped with a built-in RS-485 terminal.

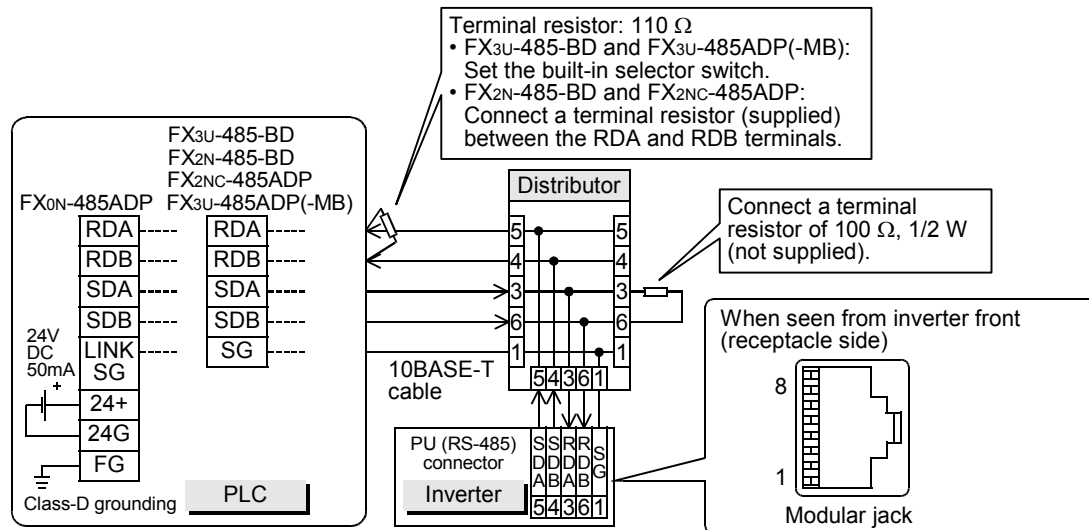


→ For details, refer to the instruction respective inverter manual.

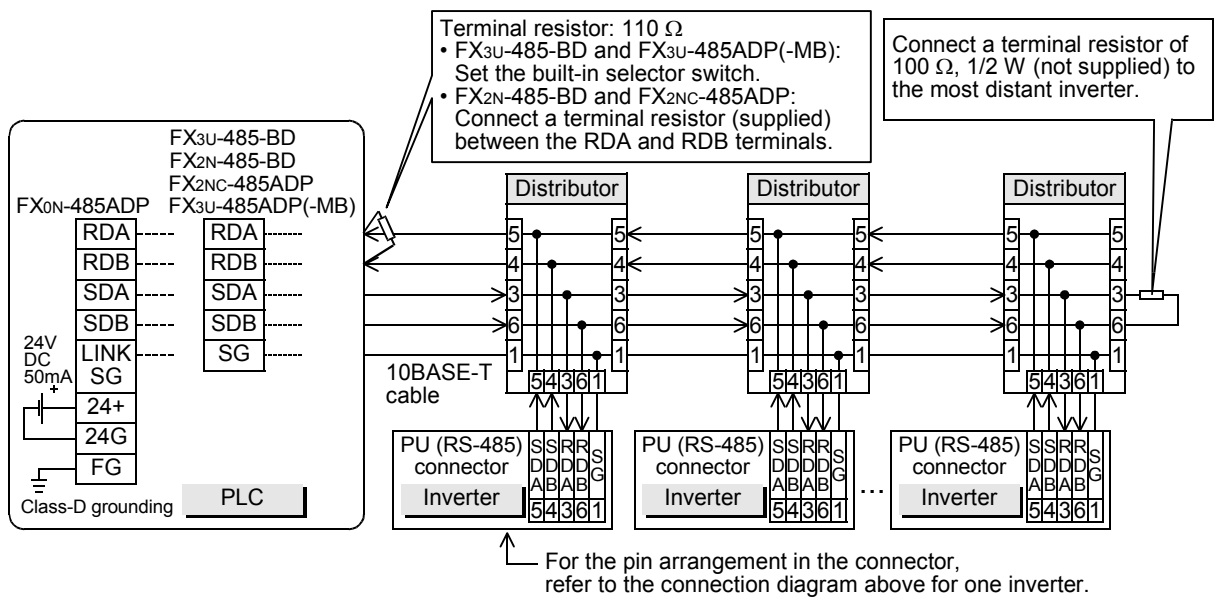
4.8 Connection Diagram

4.8.1 For S500, E500, A500 and E700 Series (PU connector)

1. When one inverter is connected

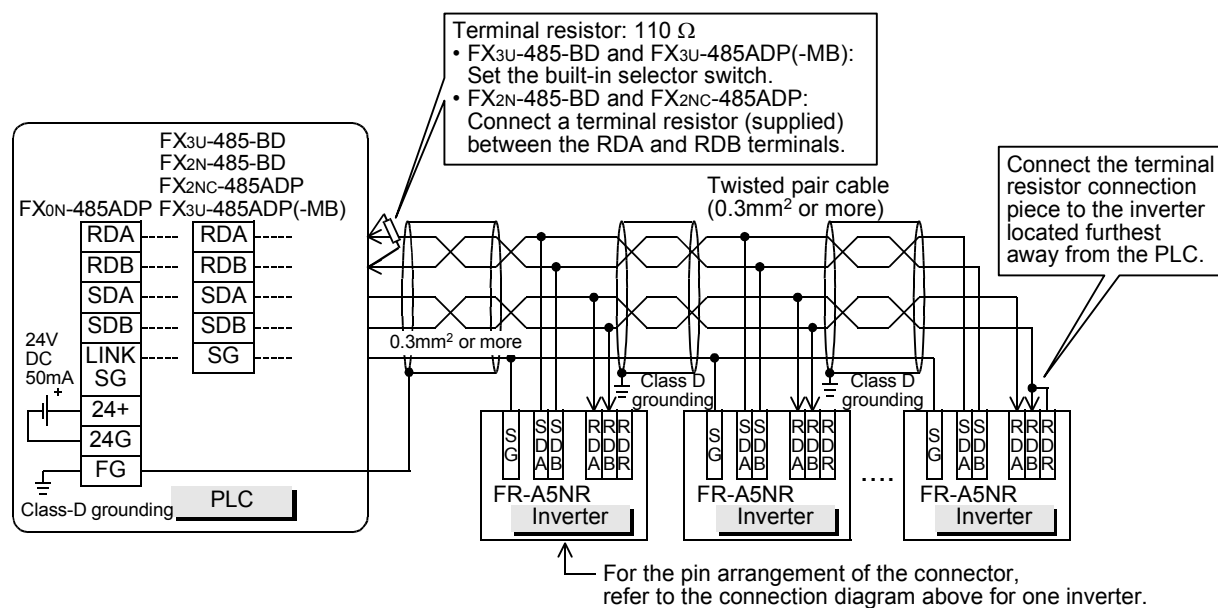
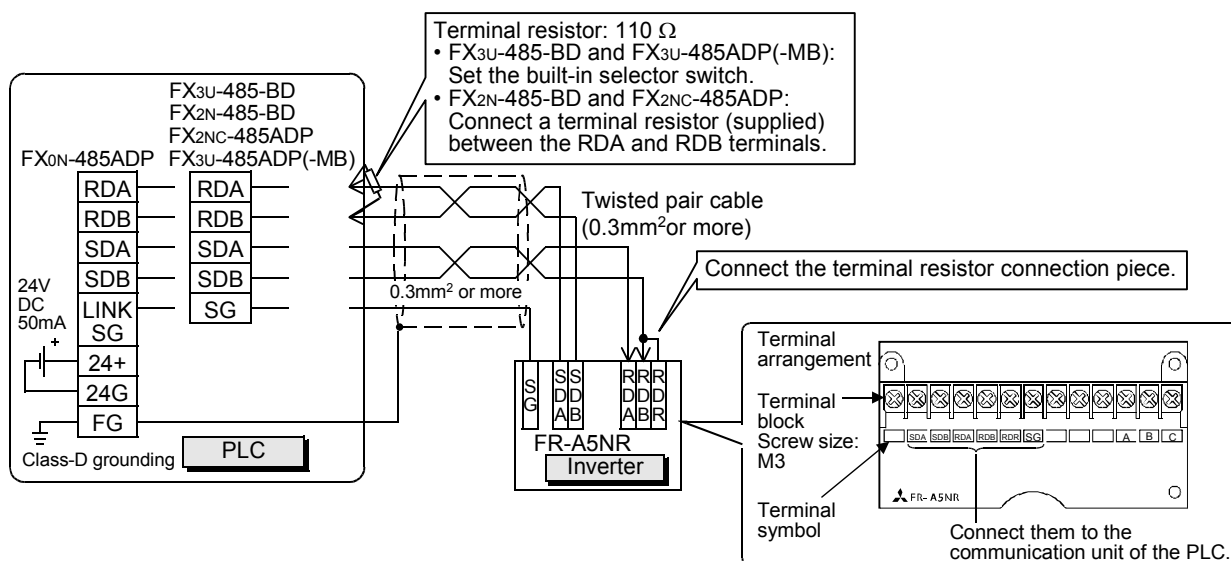


2. When two or more (up to eight) inverters are connected



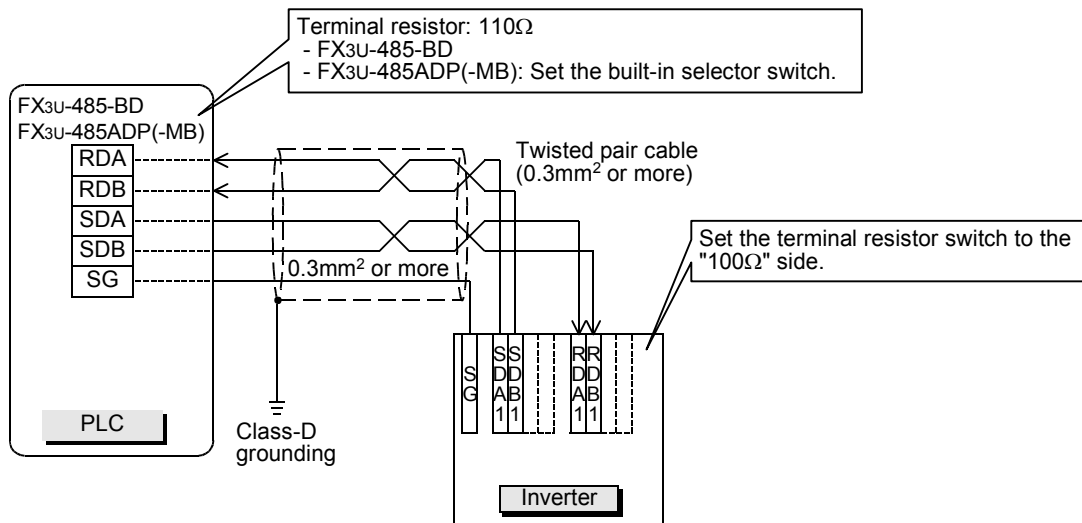
| A | B | C | D | E | F | G | H | I | Apex. |
|--------------|-------------|---------------|---------------|------------------------|----------------------------|----------------------------|---------------------------|--------------------|---------------------|
| Common Items | N:N Network | Parallel Link | Computer Link | Inverter Communication | Non-Protocol Communication | Non-Protocol Communication | Programming Communication | Remote Maintenance | Discontinued models |

2. When two or more (up to eight) inverters are connected

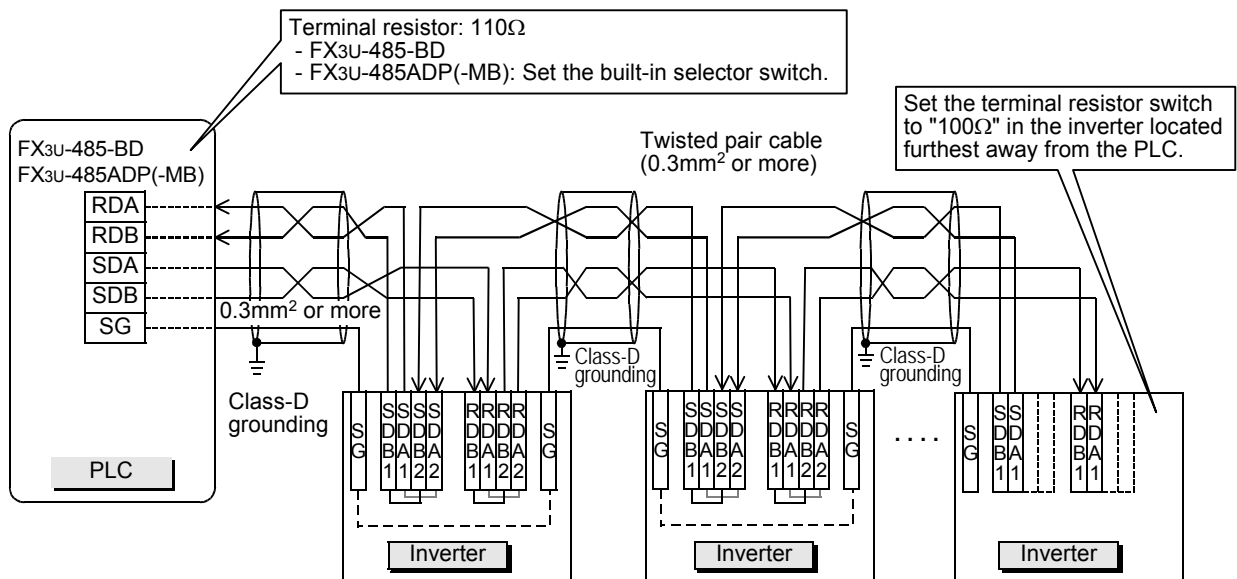


4.8.3 For F700 and A700 Series (built-in RS-485 terminal)

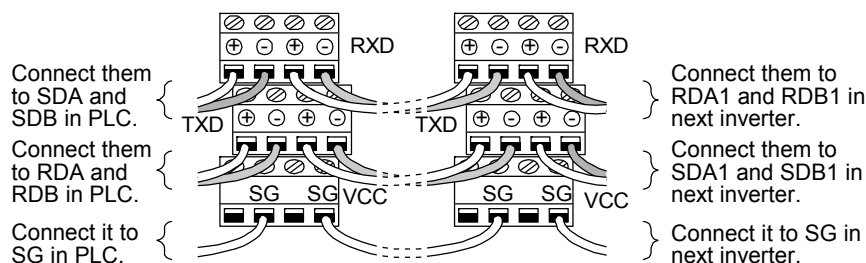
1. When one inverter is connected



2. When two or more (up to eight) inverters are connected



When adopting branches, perform the wiring as shown below:

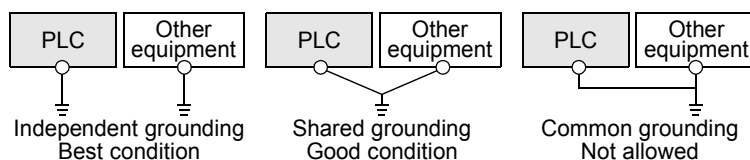


4.9 Grounding

Grounding should be performed as stated below.

- The grounding resistance should be 100Ω or less.
- Independent grounding should be performed for best results.
When independent grounding can not be performed, perform "shared grounding" as shown in the following figure.

→ For details, refer to the Hardware Edition of each series.



- The grounding wire size should be AWG 14 (2 mm²) or larger.
- The grounding point should be close to the PLC, and all grounding wires should be as short as possible.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

5. Communication Setting in Inverter

Before connecting an inverter to a PLC, set parameters related to communication in the inverter parameter unit (PU) in advance using the procedure described in this chapter.

If these parameters are overwritten from the PLC after the inverter is connected, communication will be disabled.

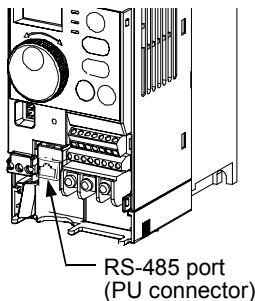
If these parameters are changed by mistake, they should be set again.

5.1 Communication Port and Applicable Parameters

When connecting an inverter to a PLC, it is necessary to set parameters corresponding to the communication port in advance.

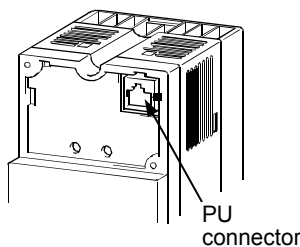
S500 Series

Remove the surface cover.



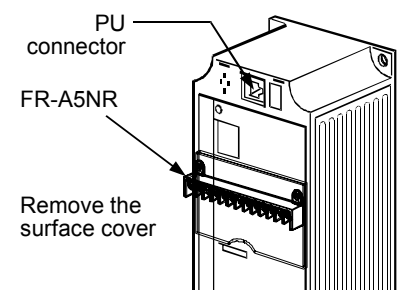
E500 Series

Remove the operation panel.



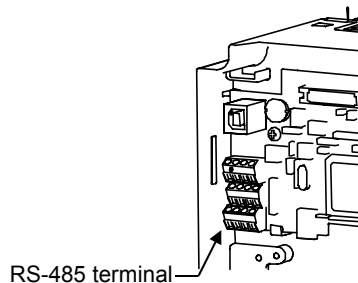
A500, F500 and V500 Series

Remove the operation panel.



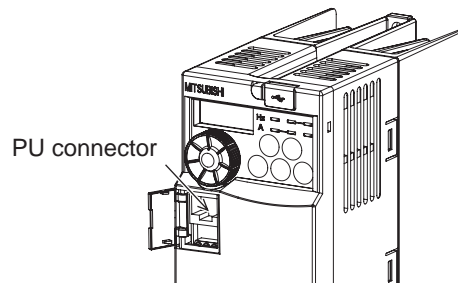
F700 and A700 Series

Remove the surface cover.



E700 Series

Open the PU connector cover



| Model | Model classification | Inverter connection destination | Parameters applicable in inverter | Reference section |
|-------------|---------------------------------------|---------------------------------|---------------------------------------|-------------------|
| S500 Series | Only models with built-in RS-485 port | RS-485 port | Pr79,n1 to n12 | 5.2 |
| E500 Series | Models with built-in PU port | PU port | Pr79,Pr117 to Pr124 | 5.3 |
| A500 Series | Models with built-in PU port | PU port | Pr79,Pr117 to Pr124 | 5.4 |
| | Option | FR-A5NR computer link | Pr79,Pr331 to Pr342 | 5.5 |
| F500 Series | Models with built-in PU port | PU port | Pr79,Pr117 to Pr124 | 5.4 |
| | Option | FR-A5NR computer link | Pr79,Pr331 to Pr342 | 5.5 |
| V500 Series | Models with built-in PU port | PU port | Pr79,Pr117 to Pr124 | 5.4 |
| | Option | FR-A5NR computer link | Pr79,Pr331 to Pr342 | 5.5 |
| E700 Series | Models having built-in PU port | PU port | Pr79,Pr117 to Pr124, Pr.340, Pr549 | 5.6 |
| A700 Series | Models with built-in RS-485 terminal | RS-485 terminal | Pr79,Pr331 to Pr342, Pr549 | 5.7 |
| F700 Series | Models with built-in RS-485 terminal | RS-485 terminal | Pr79,Pr331 to Pr342, Pr549 | 5.7 |

5.2 S500 Series (When Connected to RS-485 Port)

5.2.1 Contents of parameter setting

1. Contents of communication setting (essential items)

The table below shows parameters which should be set in all cases.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|-----------------------------------|-----------|--|
| n1 | Communication station number | 00 to 31 | Up to eight inverters can be connected. |
| n2 | Communication speed | 48 | 4800 bps |
| | | 96 | 9600 bps |
| | | 192 | 19200 bps (standard) |
| n3 | Stop bit length | 10 | Data length: 7-bit/Stop bit: 1-bit |
| n4 | Parity check presence/absence | 2 | Even parity present |
| n7 | Wait time setting | --- | Set with communication data |
| n11 | CR/LF selection | 1 | With CR, without LF |
| Pr79 | Operation mode selection | 0 | External operation mode is selected when power is turned ON. |
| n10 | Link start mode selection | 1 | Computer link operation |
| n6 | Communication check time interval | --- | Communication check suspension |

2. Parameters which should be adjusted between test operation and actual operation

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---------------------------------|-----------|---|
| n5 | Number of communication retries | --- | Set the value shown on the left during adjustment, and set a value from 1 to 10 during operation. |

3. Others (which should be set if necessary)

The table below shows parameters to be considered when using various system configuration and inverters. For the method of use, refer to the respective inverter manual.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|-------------------------|-----------|---|
| n12 | EEPROM write selection | 0 or 1 | 0: Written to RAM and EEPROM 1: Written to RAM only. Not written to EEPROM |
| n8 | Operation command write | 0 or 1 | 0: PLC 1: External |
| n9 | Speed command write | 0 or 1 | 0: PLC 1: External |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/R2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

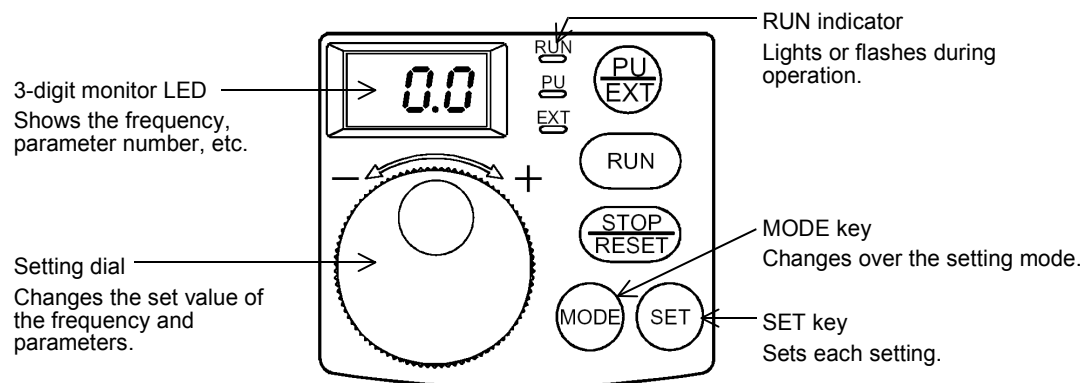
H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

5.2.2 Parameter setting method (reference)

This subsection explains the parameter setting method using the operation panel.
For details on the operation panel, refer to the respective inverter manual.



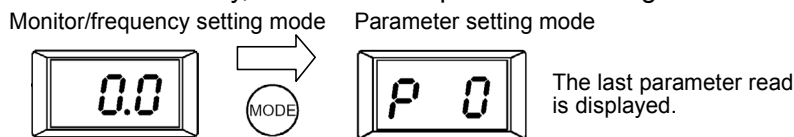
The operating procedure example below shows a case in which the baud rate is set to 19,200 bps.

1 Confirming the RUN indicator and the operation mode

Confirm that the operation is stopped (that the RUN indicator is OFF).

2 Selecting the parameter setting mode

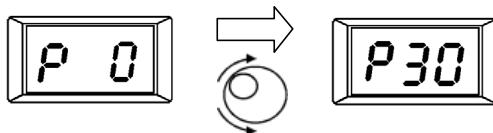
Press the MODE key, and select the parameter setting mode.



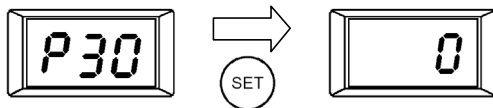
3 Setting the set value of Pr. 30 to "1"

(This step is not necessary if Pr. 30 is already set to "1".)

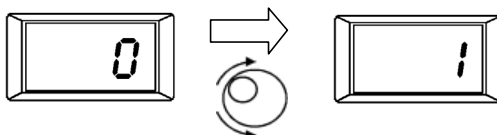
1. Turn the setting dial to display "P30".



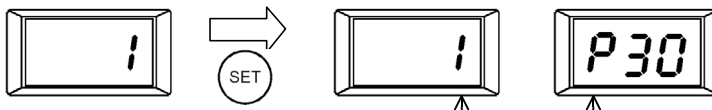
2. Press the SET key to read the currently set value.



3. Turn the setting dial to change the set value to "1".



Press the SET key to set "1".

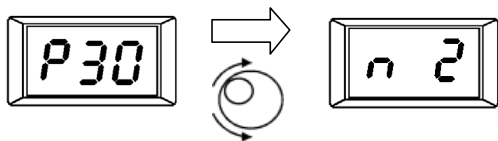


The set value and parameter number are displayed alternately.

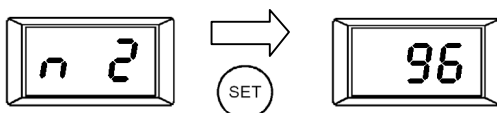
When the set value and parameter number are displayed alternately, the setting is completed.

4 Setting the set value of "n2" to "192" ("192" indicates the baud rate of 19200 bps.)

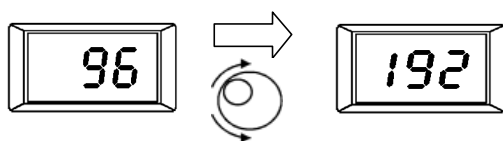
Turn the setting dial to display "n2".



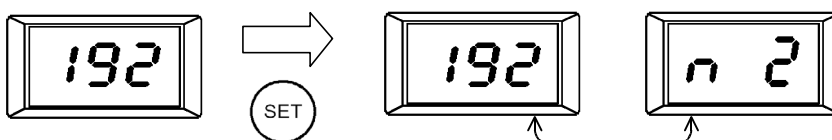
Press the SET key to read the currently set value.



Turn the setting dial to change the set value to "192".



Press the SET key to set "192".



The set value and parameter number are displayed alternately.

When the set value and parameter number are displayed alternately, the setting is completed.

5 Changing other parameters in the same way as step 4

→ For details on the parameters to be set, refer to Subsection 5.2.1.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

5.3 E500 Series (When Connected to PU Port)

5.3.1 Contents of parameter setting

1. Contents of communication setting (essential items)

The table below shows parameters which should be set in all cases.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|-----------------------------------|-----------|--|
| Pr117 | Communication station number | 00 to 31 | Up to eight inverters can be connected. |
| Pr118 | Communication speed | 48 | 4800 bps |
| | | 96 | 9600 bps |
| | | 192 | 19200 bps (standard) |
| Pr119 | Stop bit / Data length | 10 | Data length: 7-bit/Stop bit: 1-bit |
| Pr120 | Parity check presence/absence | 2 | Even parity present |
| Pr123 | Waiting time setting | 9999 | Set with communication data |
| Pr124 | CR·LF presence/absence selection | 1 | With CR, without LF |
| Pr79 | Operation mode selection | 0 | External operation mode is selected when power is turned ON. |
| Pr122 | Communication check time interval | 9999 | Communication check suspension |

2. Parameters which should be adjusted between test operation and actual operation

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---------------------------------|-----------|---|
| Pr121 | Number of communication retries | 9999 | Set the value shown on the left during adjustment, and set a value from 1 to 10 during operation. |

3. Others (which should be set if necessary)

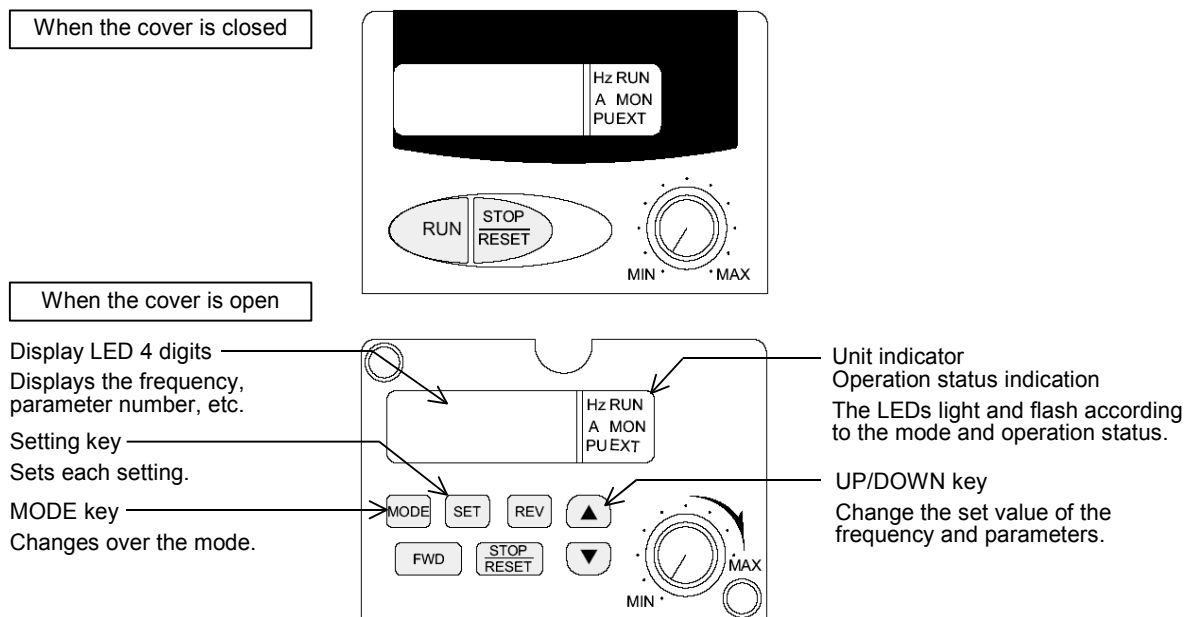
The table below shows parameters to be considered when using various system configuration and inverters. For the method of use, refer to the respective inverter manual.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---|------------|--|
| Pr146 | Frequency setting command selection ^{*1} | 0, 1, 9999 | 0 : The built-in frequency setting knob is valid. 1 : The built-in frequency setting knob is invalid. 9999 : The built-in frequency setting knob is valid when the frequency is set to "0 Hz" by the keys. |
| Pr342 | EEPROM write selection (only in 400 V class) | 0 or 1 | 0: EEPROM is written. 1: RAM is written. |

*1. When changing the frequency from the PLC, set "1" or "9999".

5.3.2 Parameter setting method (reference)

This subsection explains the parameter setting method using the operation panel.
For details on the operation panel, refer to the respective inverter manual.



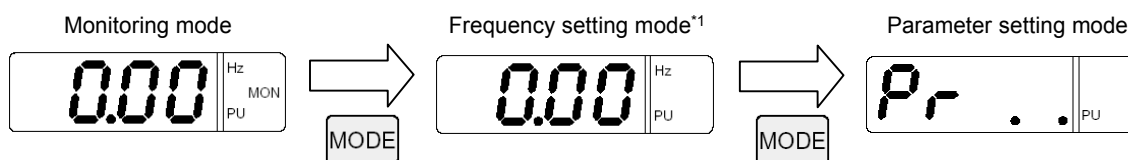
The operating procedure example below shows a case in which the baud rate is set to 19200 bps.

1 Confirming the RUN indicator and the operation mode indicator

Confirm that the operation is stopped (that the RUN indicator is Off).

2 Selecting the parameter setting mode

Press the MODE key, and select the parameter setting mode.

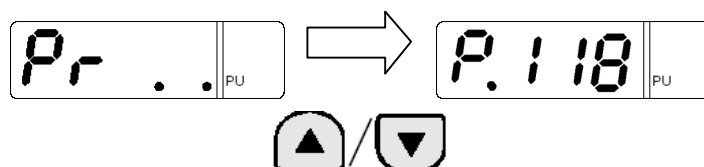


*1. The frequency setting mode is displayed only in the PU operation mode.

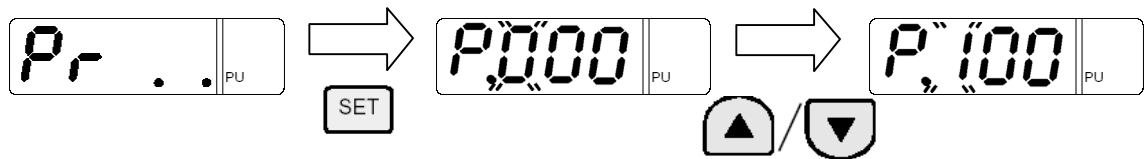
3 Reading the parameter (Pr. 118)

There are two methods to read the parameter number:

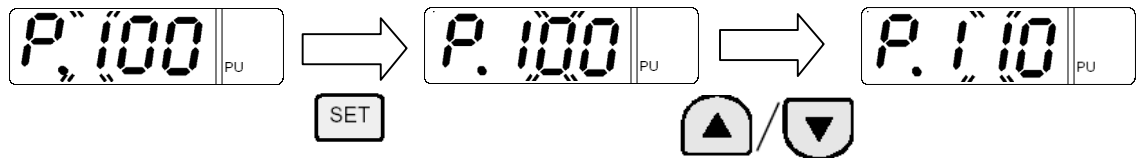
- Method to read the parameter number using the UP and DOWN keys
Press the UP and DOWN keys, and display the parameter number to be read.



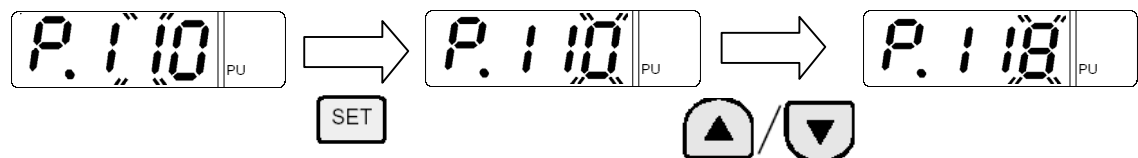
- Method to set each digit of the parameter number
 - Press the SET key to flash the most significant digit. Set a numeric value using the UP and DOWN keys.



- Press the SET key to flash the middle digit. Set a numeric value using the UP and DOWN keys.

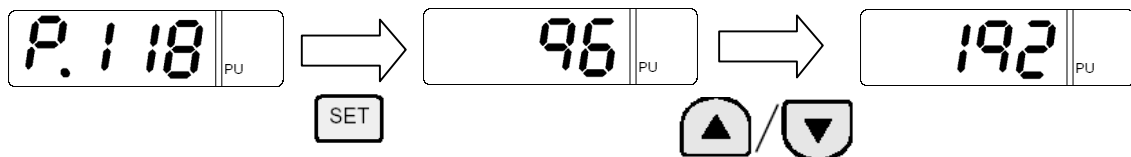


- Press the SET key to flash the least significant digit. Set a numeric value using the UP and DOWN keys.

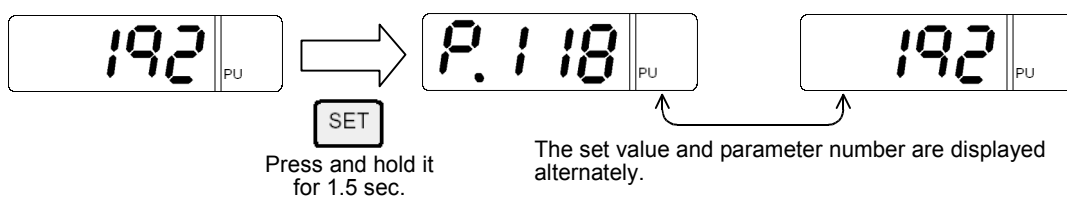


4 Setting the set value of Pr. 118 to "192" ("192" indicates the baud rate of 19200 bps.)

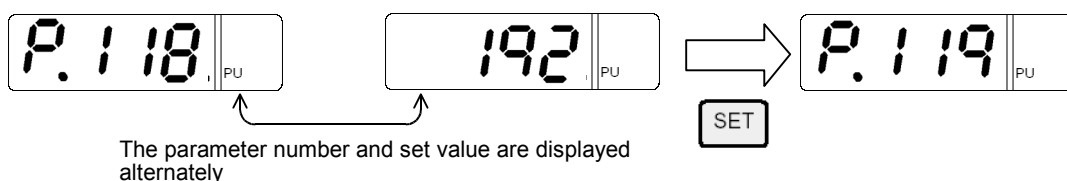
- Press the SET key to read the currently set value. Change the set value using the UP and DOWN keys.



- Press and hold the SET key for 1.5 seconds to set "192".



- Press the SET key to display the next parameter.



5 Change other parameters in the same way as step 3.

→ For details on parameters to be set, refer to Subsection 5.3.1.

5.4 V500, F500 and A500 Series (Connection to PU Port)

5.4.1 Contents of parameter setting

1. Contents of communication setting (essential items)

The table below shows parameters which should be set in any case.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|-----------------------------------|-----------|--|
| Pr117 | Communication station number | 00 to 31 | Up to eight inverters can be connected. |
| Pr118 | Communication speed | 48 | 4800 bps |
| | | 96 | 9600 bps |
| | | 192 | 19200 bps (standard) |
| Pr119 | Stop bit length/data length | 10 | Data length: 7-bit/Stop bit: 1-bit |
| Pr120 | Parity check presence/absence | 2 | 2: Even parity |
| Pr123 | Waiting time setting | 9999 | Set in communication data |
| Pr124 | CR·LF presence/absence selection | 1 | CR: Provided, LF: Not provided |
| Pr79 | Operation mode selection | 0 | External operation mode is selected when power is turned ON. |
| Pr122 | Communication check time interval | 9999 | Communication check is stopped. |

2. Parameters which should be adjusted between test operation and actual operation

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---------------------------------|-----------|---|
| Pr121 | Number of communication retries | 9999 | Set the value shown on the left during adjustment, and set a value from 1 to 10 during operation. |

3. Others (which should be set if necessary)

The table below shows parameters to be considered when using various system configuration and inverters. For the method of use, refer to the respective inverter manual.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|------------------------|-----------|--|
| Pr342 | EEPROM write selection | 0 or 1 | 0: EEPROM are written. 1: RAM is written. |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

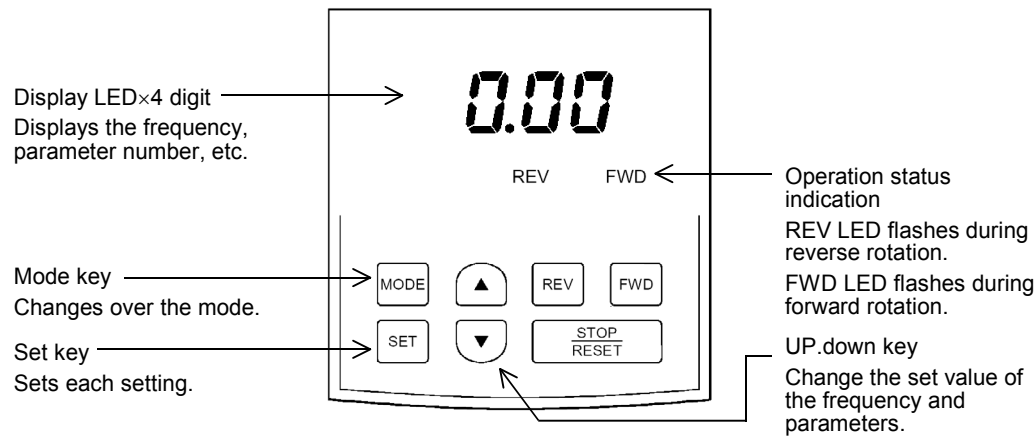
Remote Maintenance

Apx.

Discontinued models

5.4.2 Parameter setting method (reference)

This subsection explains the parameter setting method using the operation panel.
For details on the operation panel, refer to the respective inverter manual.



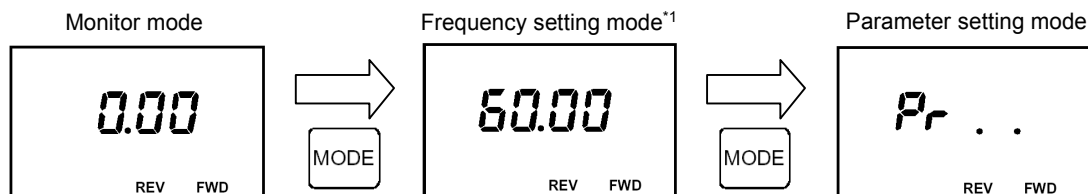
The operating procedure example below shows a case in which the baud rate is set to 19200 bps.

1 Confirming the RUN indicator and the operation mode indicator

Confirm that the operation is stopped (that both the REV and FWD indicators are Off).

2 Selecting the parameter setting mode

Press the MODE key, and select the parameter setting mode.

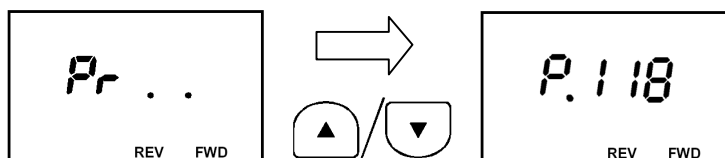


*1. The frequency setting mode is displayed only during the PU operation mode.

3 Reading the parameter (Pr. 118)

There are two methods to read the parameter number:

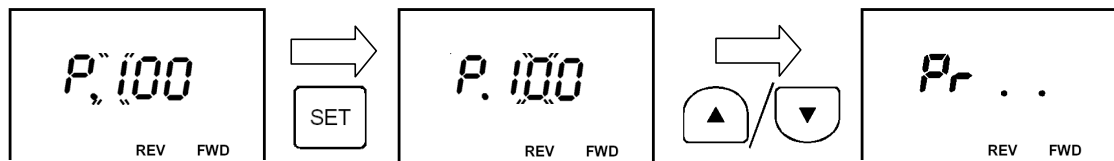
- Method to read the parameter number using the UP and DOWN keys
Press the UP and DOWN keys, and display the parameter number to be read.



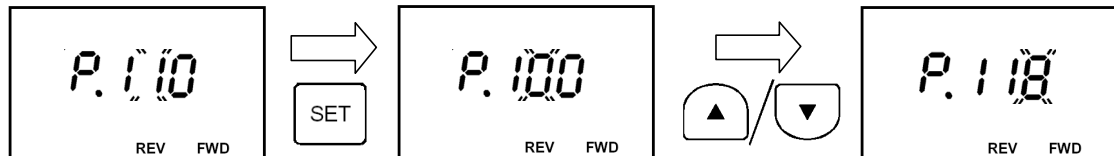
- Method to set each digit of the parameter number
 - Press the SET key to flash the most significant digit. Set a numeric value using the UP and DOWN keys.



- b) Press the SET key to flash the middle digit. Set a numeric value using the UP and DOWN keys.



- c) Press the SET key to flash the least significant digit. Set a numeric value using the UP and DOWN keys.

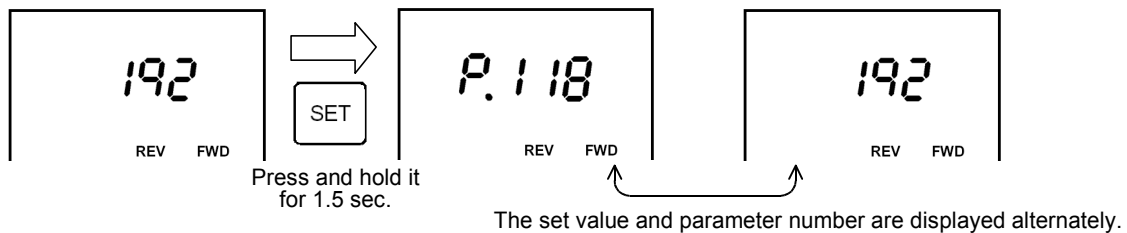


4 Setting the set value of Pr. 118 to "192" ("192" indicates the baud rate of 19200 bps.)

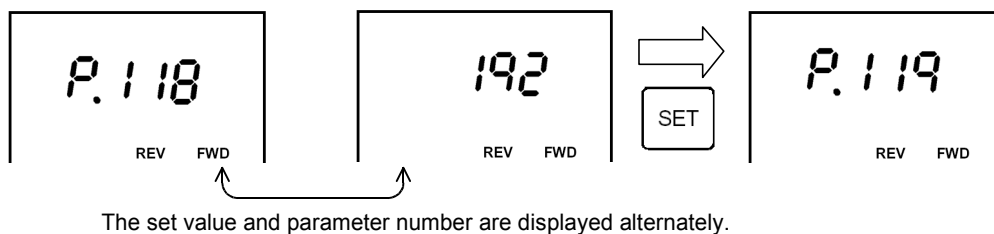
1. Press the SET key to read the currently set value. Change the set value using the UP and DOWN keys.



2. Press and hold the SET key for 1.5 seconds to set "192".



3. Press the SET key to display the next parameter



5 Changing other parameters in the same way as step 3

→ For details on the parameters to be set, refer to Subsection 5.4.1.

5.5 V500, F500 and A500 Series (Connection to FR-A5NR)

5.5.1 Contents of parameter setting

1. Contents of communication setting (essential items)

The table below shows parameters which should be set in all cases.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|-----------------------------------|-----------|--|
| Pr331 | Communication station number | 00 to 31 | Up to eight inverters can be connected. |
| Pr332 | Communication speed | 48 | 4800 bps |
| | | 96 | 9600 bps (standard) |
| | | 192 | 19200 bps |
| Pr333 | Stop bit / Data length | 10 | Data length: 7-bit/Stop bit: 1-bit |
| Pr334 | Parity check presence/absence | 2 | 2: Even parity |
| Pr337 | Waiting time setting | 9999 | Set in communication data |
| Pr341 | CR, LF presence/absence selection | 1 | CR: Provided, LF: Not provided |
| Pr79 | Operation mode selection | 0 | External operation mode is selected when power is turned ON. |
| Pr340 | Link startup mode selection | 1 | Computer link |
| Pr336 | Communication check time interval | 9999 | Communication check is stopped. |

2. Parameters which should be adjusted between test operation and actual operation

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---------------------------------|-----------|---|
| Pr335 | Number of communication retries | 9999 | Set the value shown on the left during adjustment, and set a value from 1 to 10 during operation. |

3. Others (which should be set if necessary)

The table below shows parameters to be considered when using various system configuration and inverters. For the method of use, refer to the respective inverter manual.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|-------------------------|-----------|---|
| Pr342 | EEPROM write selection | 0 or 1 | 0: EEPROM is written. 1: RAM is written. |
| Pr338 | Operation command right | 0 or 1 | 0: PLC 1: Outside |
| Pr339 | Speed command write | 0 or 1 | 0: PLC 1: Outside |

5.5.2 Parameter setting method (reference)

The parameter setting method is the same as that for the V500, F500 and A500 Series (connection to the PU port).
→ For the parameter setting method, refer to Subsection 5.4.2.

5.6 E700 Series (when PU port is connected)

5.6.1 Contents of parameter setting

1. Contents of communication setting (essential items)

The table below shows parameters which should be set in all cases.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---|-----------|---|
| Pr117 | PU communication station number | 00 to 31 | Up to eight inverters can be connected. |
| Pr118 | PU communication speed | 48 | 4800 bps |
| | | 96 | 9600 bps |
| | | 192 | 19200 bps (standard) |
| Pr119 | PU communication stop bit length | 10 | Data length: 7-bit/Stop bit: 1-bit |
| Pr120 | PU communication parity check | 2 | 2: Even parity |
| Pr123 | PU communication waiting time setting | 9999 | Set in communication data |
| Pr124 | PU communication CR/LF presence/absence selection | 1 | CR: Provided, LF: Not provided |
| Pr79 | Operation mode selection | 0 | External operation mode is selected when power is turned ON. |
| Pr549 | Protocol selection | 0 | Mitsubishi inverter (computer link operation) protocol |
| Pr340 | Communication startup mode selection | 1 or 10 | 1: Network operation mode 10: Network operation mode Operation mode can be changed between the PU operation mode and network operation mode from the operation panel. |

2. Parameters which should be adjusted between test operation and actual operation

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|--------------------------------------|-----------|---|
| Pr121 | Number of PU communication retries | 9999 | Set the value shown on the left during adjustment, and set a value from 1 to 10 during operation. |
| Pr122 | PU communication check time interval | 9999 | Set the value shown on the left during adjustment, and set a proper value in accordance with the system specification during operation. |

Caution on setting the PU communication check time interval (Pr122)

| Description | Set value |
|---|-------------------|
| During adjustment or when communication with the PLC is not executed periodically | 9999 |
| When communication with the PLC is not executed | 0 (Initial Value) |
| Set the communication time in the following cases <ul style="list-style-type: none"> When it is necessary to monitor absence of communication for a certain time and stop the inverter in such a case while communication with the PLC is being executed When it is necessary to stop the motor at the point which the PLC mode is changed from RUN to STOP | 0.1 to 999.8 sec |

3. Others (which should be set if necessary)

The table below shows parameters to be considered when using various system configuration and inverters. For the method of use, refer to the respective inverter manual.

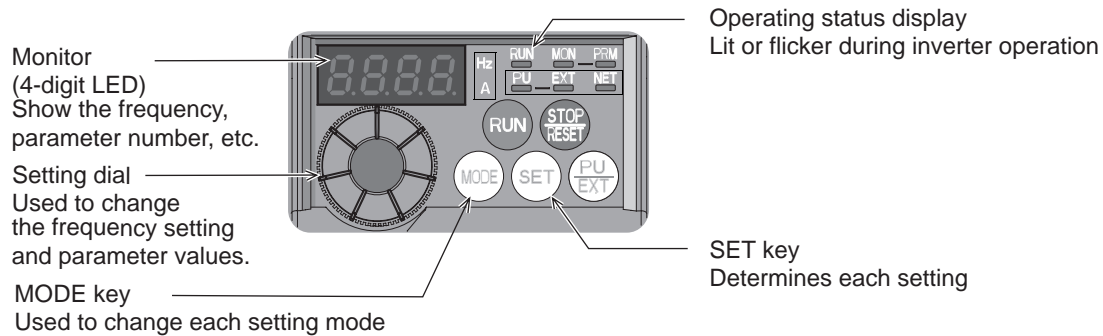
| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|--|-------------------|--|
| Pr37 | Speed display ^{*1} | 0 or 0.01 to 9998 | 0: Frequency display, setting 0.01 to 9998: Machine speed at 60Hz. |
| Pr146 | Built-in potentiometer switching ^{*2} | 0 or 1 | 0: Built-in frequency setting potentiometer valid 1: Built-in frequency setting potentiometer invalid |
| Pr342 | Communication EEPROM write selection | 0 or 1 | 0: EEPROM is written. 1: RAM is written. |

*1. Pr37 cannot be set using this inverter communication function.

*2. Set Pr146 to "1" when changing the frequency from the PLC.

5.6.2 Parameter setting method (reference)

This subsection explains the parameter setting method using the operation panel.
For details on the operation panel, refer to the respective inverter manual.



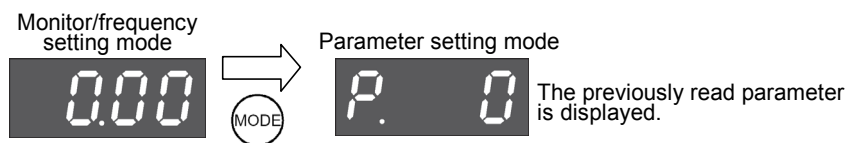
The operating procedure example below shows a case in which the baud rate is set to 19200 bps.

1 Confirming the RUN indicator and the operation mode indicator

Confirm that the operation is stopped (that the RUN indicator is off).

2 Selecting the parameter setting mode

Press the MODE key, and select the parameter setting mode.



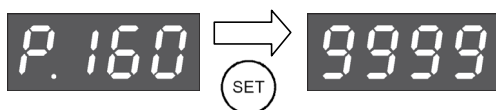
3 Setting the parameter Pr. 160 to "0"

(This step is not required if Pr. 160 is already set to "0".)

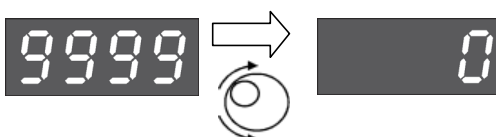
1. Turn the setting dial until "Pr. 160" is displayed.



2. Press the SET key to read the current set value.



3. Turn the setting dial, and change the set value to "0".



Press the SET key to determine the set value.

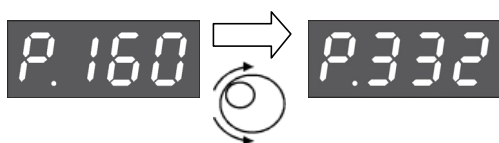


The set value and parameter number are displayed alternately.

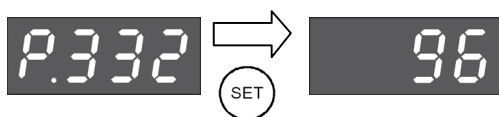
The set value and parameter number are displayed alternately, and the setting is completed.

4 Setting the parameter Pr. 332 to "192" ("192" indicates the baud rate of 19200 bps.)

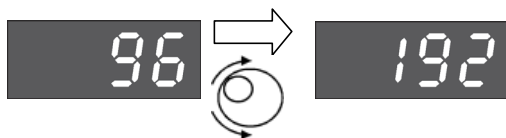
Turn the setting dial until "Pr. 332" is displayed.



Press the SET key to read the current set value.



Turn the setting dial, and change the set value to "192".



Press the SET key to determine the set value.



The set value and parameter number are displayed alternately.

The set value and parameter number are displayed alternately, and the setting is completed.

5 Changing other parameters in the same way as step 4

→ For details on the parameters to be set, refer to Subsection 5.6.1.

5.7 F700 and A700 Series (when built-in RS-485 terminal is connected)

5.7.1 Contents of parameter setting

1. Contents of communication setting (essential items)

The table below shows parameters which should be set in all cases.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|---|-----------|--|
| Pr331 | RS-485 communication station | 00 to 31 | Up to eight inverters can be connected. |
| Pr332 | RS-485 communication speed*1 | 48 | 4800 bps |
| | | 96 | 9600 bps (standard) |
| | | 192 | 19200 bps |
| Pr333 | RS-485 communication stop bit length | 10 | Data length: 7-bit/Stop bit: 1-bit |
| Pr334 | RS-485 communication parity check selection | 2 | 2: Even parity |
| Pr337 | RS-485 communication waiting time setting | 9999 | Set in communication data |
| Pr341 | RS-485 communication CR/LF selection | 1 | CR: Provided, LF: Not provided |
| Pr79 | Operation mode selection | 0 | External operation mode is selected when power is turned ON. |
| Pr340 | Communication startup mode selection | 1 | Computer link |
| Pr336 | RS-485 communication check time interval | 9999 | Communication check is stopped. |
| Pr549 | Protocol selection | 0 | Mitsubishi inverter (computer link) protocol |

*1. The RS-485 communication speed set value "38400 bps" is not supported by FX PLCs.

2. Parameters which should be adjusted between test operation and actual operation

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|--|-----------|---|
| Pr335 | RS-485 communication number of retries | 9999 | Set the value shown on the left during adjustment, and set a value from 1 to 10 during operation. |

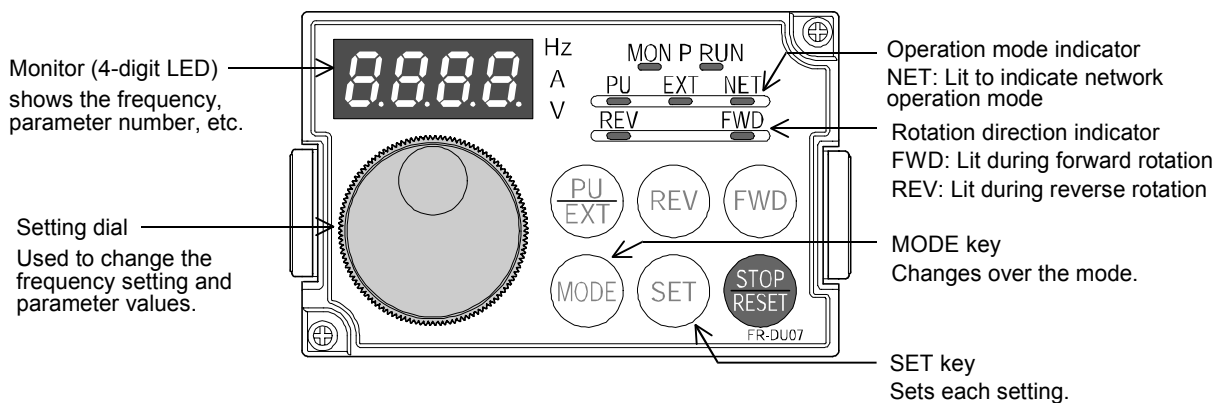
3. Others (which should be set if necessary)

The table below shows parameters to be considered when using various system configuration and inverters. For the method of use, refer to the respective inverter manual.

| Parameter No. | Parameter item | Set value | Setting contents |
|---------------|--|-----------|---|
| Pr342 | Communication EEPROM write selection | 0 or 1 | 0: EEPROM is written. 1: RAM is written. |
| Pr338 | Communication operation command source | 0 or 1 | 0: PLC 1: Outside |
| Pr339 | Communication operation command source | 0 or 1 | 0: PLC 1: Outside |

5.7.2 Parameter setting method (reference)

This subsection explains the parameter setting method using the operation panel.
For details on the operation panel, refer to the respective inverter manual.



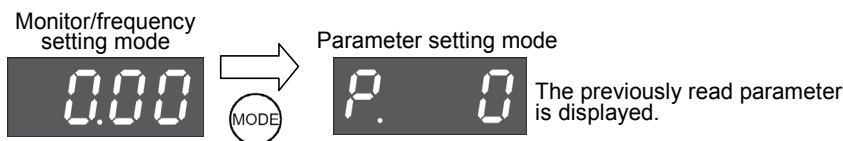
The operating procedure example below shows a case in which the baud rate is set to 19200 bps.

1 Confirming the RUN indicator and the operation mode indicator

Confirm that the operation is stopped (that the RUN indicator is off).

2 Selecting the parameter setting mode

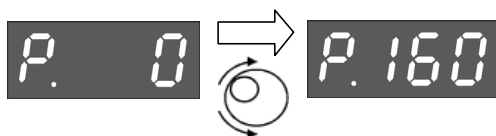
Press the MODE key, and select the parameter setting mode.



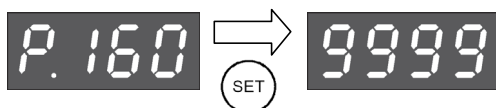
3 Setting the parameter Pr. 160 to "0"

(This step is not required if Pr. 160 is already set to "0".)

1. Turn the setting dial until "Pr. 160" is displayed.



2. Press the SET key to read the current set value.



3. Turn the setting dial, and change the set value to "0".



Press the SET key to determine the set value.

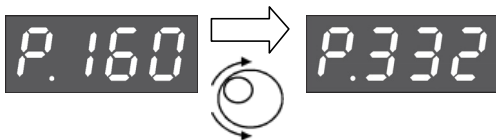


The set value and parameter number are displayed alternately.

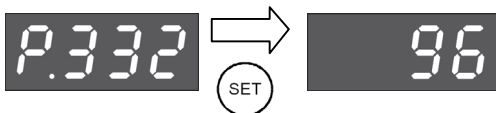
The set value and parameter number are displayed alternately, and the setting is completed.

4 Setting the parameter Pr. 332 to "192" ("192" indicates the baud rate of 19200 bps.)

Turn the setting dial until "Pr. 332" is displayed.



Press the SET key to read the current set value.



Turn the setting dial, and change the set value to "192".



Press the SET key to determine the set value.



The set value and parameter number are displayed alternately.

The set value and parameter number are displayed alternately, and the setting is completed.

5 Change other parameters in the same way as step 4

→ For details on the parameters to be set, refer to Subsection 5.7.1.

5.8 Cautions on Setting

1. Setting of the "communication check time interval"

| Description | Set value |
|---|----------------------|
| During adjustment or when communication with the PLC is not executed periodically | Value shown in table |
| When communication with the PLC is not executed | 0 |
| Set the communication time in the following cases: When it is necessary to monitor the absence of communication for a certain time and stop the inverter in such a case while communication with the PLC is being executed When it is necessary to stop the motor at the point which the PLC mode is changed from RUN to STOP | 0.1 to 999.8 sec |

6. Communication Setting in FX Programmable Controller

This chapter explains the communication setting method for inverter communication.
Set non-protocol communication for inverter communication.

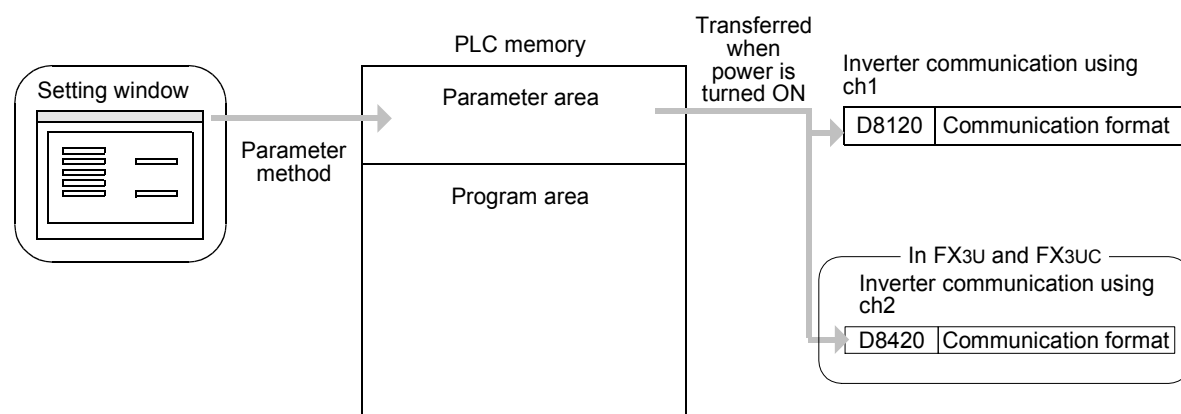
6.1 Parameter Assigning Method

Use parameters for communication setting in the FX PLC.

1. Parameter assigning method

Register the communication setting in the sequence programming software parameters, and transfer the parameters to the PLC.

2. Setting flow



6.2 Communication Setting Using Parameter Method (GX Developer)

Two software packages, GX Developer and FXGP/WIN for Windows, are applicable to the parameter method. This section explains the parameters using GX Developer.

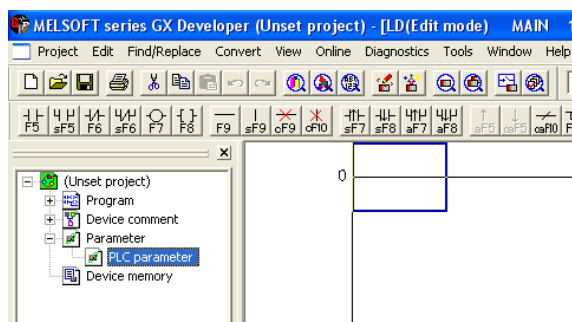
Applicable models: FX2N, FX2NC, FX3U, and FX3UC Series

6.2.1 Operating procedure

This subsection explains the serial communication setting method. Suppose that GX Developer is already started up.

1 Opening the parameter setting window

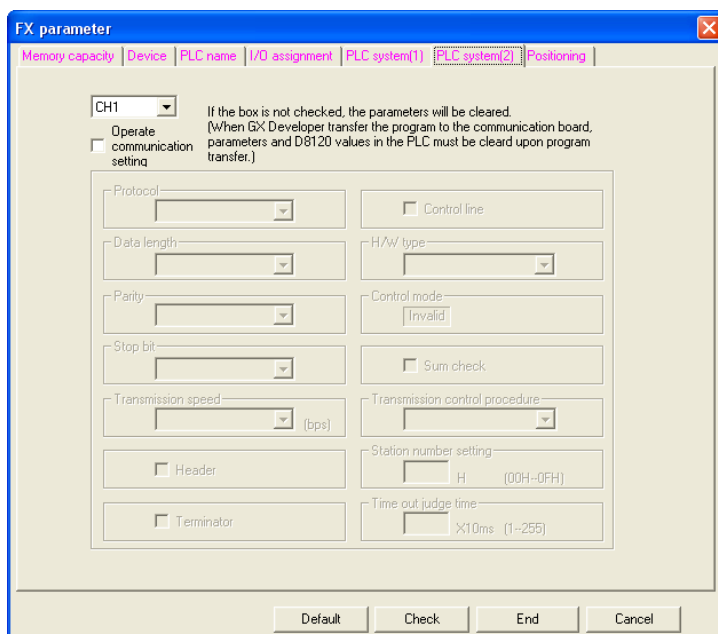
Double-click [Parameter]-[PLC parameter] from the project tree.



If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Setting the serial communication (parameters)

Click the [PLC system(2)] tab in the "FX parameter window".



3 Setting the serial communication (parameters)

Set the parameters as shown below:

[1] Set the channel to be used. (This parameter can be set only in the FX3U and FX3UC PLCs.)

[2] Check the "Operate communication setting" box.

[3] Set "Protocol" to "Non-procedural," "Data length" to "7bit," "Parity" to "Even," and "Stop bit" to "1bit."

[4] Set "Transmission speed" to either "4800," "9600" or "19200," and make sure that the set value here is the same as the set value in the inverters.

[5] Ignore these items.

4 Writing parameters and program to the PLC

Select [Online] - [Write to PLC] from the toolbar, put a check mark (✓) next to "Parameter" and "Program," and then click [Execute].

6.3 Communication Setting Using Parameter Method (FXGP/WIN)

Two software packages, GX Developer and FXGP/WIN for Windows, are applicable to the parameter method. This section explains the parameters using FXGP/WIN.

Applicable models: FX2N and FX2NC Series

6.3.1 Operating procedure

This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

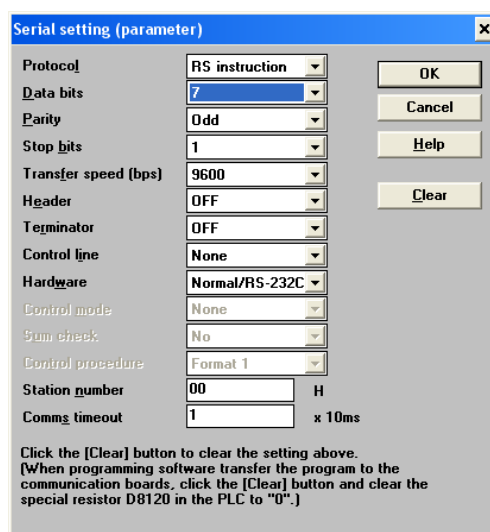
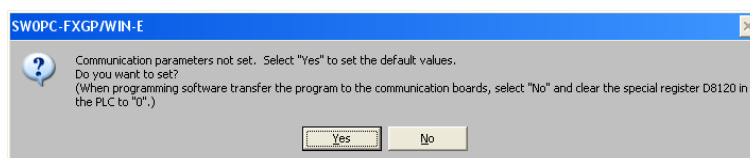
1 Displaying serial setting (parameter)

Select [Option] - [Serial setting (parameter)] from the toolbar.

The following dialog box appears according to absence/presence of parameter setting.

1. When there are no parameter settings

There are no communication settings. Click the [Yes] button.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2. When there are already parameter settings

The existing communication setting contents are displayed.

The 'Serial setting (parameter)' dialog box displays the following settings:

- Protocol: RS instruction
- Data bits: 7
- Parity: Odd
- Stop bits: 1
- Transfer speed (bps): 9600
- Header: OFF
- Terminator: OFF
- Control line: None
- Hardware: Normal/RS-232C
- Control mode: None
- Sum check: No
- Control procedure: Format 1
- Station number: 00 H
- Comm timeout: 1 x 10ms

Buttons: OK, Cancel, Help, Clear.

Click the [Clear] button to clear the setting above.
(When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".)

2 Adjusting serial setting (parameter)

Execute the communication setting as shown below.

The 'Serial setting (parameter)' dialog box shows the following settings with annotations:

- [1] Protocol: RS instruction
- Data bits: 7
- Parity: Even
- Stop bits: 1
- [2] Transfer speed (bps): 9600
- [3] Header: OFF
- Terminator: OFF
- Control line: None
- Hardware: Normal/RS-232C
- Control mode: None
- Sum check: No
- Control procedure: Format 1
- Station number: 00 H
- Comm timeout: 1 x 10ms

Buttons: OK, Cancel, Help, Clear.

Click the [Clear] button to clear the setting above.
(When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".)

[1] Set "Protocol" to "RS instruction," "Data bits" to "7," "Parity" to "Even," and "Stop bits" to "1".

[2] Set "Transfer speed [bps]" to either "4800," "9600" or "19200," and make sure that the set value here is the same as the set value in the inverters.

[3] Ignore these items.

3 Writing a sequence program (parameters) to the PLC

Select [PLC] - [Transfers] - [Write] from the toolbar, and click [OK].

7. Creating Programs (for FX2N and FX2NC PLCs)

This chapter explains how to create programs which change inverter parameters and give operation commands to inverters.

As explanation, a program example is shown for each applied instruction.

7.1 Checking Contents of Related Devices

The tables below show the devices used in inverter communication in FX2N and FX2NC PLCs.

1. Bit devices

| Device No. | Name | Description | R/W |
|------------|---|--|-----|
| M8029 | Instruction execution complete | Turns ON when execution of EXTR instruction is completed, and remains ON for 1 scan. Turns ON also when execution of instruction is completed if M8156 (communication error or parameter error) turns ON. | R |
| M8104 | Extension ROM cassette check | Remains ON while an extension ROM cassette is attached. | R |
| M8154 | Unused | — | R |
| M8155 | Communication port busy | Remains ON while the communication port is used by AN extr instruction. | R |
| M8156 | Communication error or parameter error | Turns ON when a communication error is caused by AN extr instruction. | R |
| M8157 | Communication error latch ^{*1} | Turns ON when a communication error occurs. | R |

R: Read only (used as a contact in program)

^{*1}. Cleared when the PLC mode is changed from STOP to RUN.

2. Word devices

| Device No. | Name | Description | R/W |
|------------|---|--|-----|
| D8104 | Extension ROM cassette type code | Stores the extension ROM cassette type code (value: K1). | R |
| D8105 | Extension ROM cassette version | Stores the extension ROM cassette version. (value: K100 = Ver. 1.00). | R |
| D8154 | Inverter response waiting time | Sets the inverter response waiting time. | R/W |
| D8155 | Step number of instruction using communication port | Stores the step number of the EXTR instruction using the communication port. | R |
| D8156 | Error code ^{*1} | Stores an error code when a communication error is caused by an EXTR instruction. | R |
| D8157 | Error occurrence step number latch ^{*1} | Stores the instruction step number in which a communication error has occurred. (Stores K-1 when no error has occurred.) | R |

R: Read only

R/W: Read or Write

^{*1}. Cleared when the PLC mode is changed from STOP to RUN.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS485 Instruction)

G
Non-Protocol Communication (FX2N-232JF)

H
Programming Communication

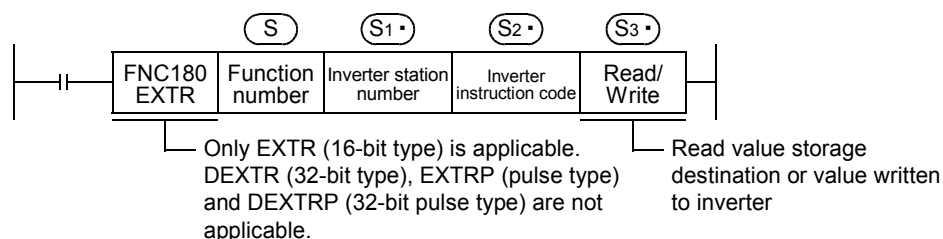
I
Remote Maintenance

Apx.
Discontinued models

7.2 Common Items in Inverter Communication Instructions

7.2.1 Inverter communication types (EXTR K10 to K13)

An FX2N/FX2NC PLC and inverter execute communication using EXTR (FNC180) instruction. EXTR instruction can be described in four types of methods, from "EXTR K10" to "EXTR K13", depending on the data communication direction and parameter writing/reading direction.



| Instruction | Function number (S) | Function | Control direction | Detailed explanation |
|--------------|---------------------|------------------------------|-------------------|----------------------|
| EXTR(FNC180) | K10 | Monitors inverter operations | PLC ← inverter | 7.3 |
| | K11 | Controls inverter operations | PLC → inverter | 7.4 |
| | K12 | Reads inverter parameters | PLC ← inverter | 7.5 |
| | K13 | Writes inverter parameters | PLC → inverter | 7.6 |

7.2.2 Function and operation

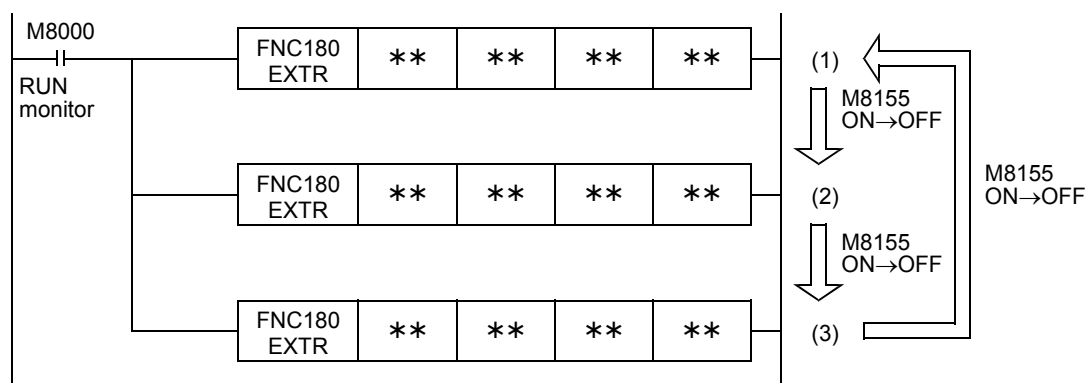
1. Communication start timing

At the rising edge (OFF→ON) of the drive condition, the PLC starts communication with an inverter. Even if the drive condition turns OFF during communication with an inverter, the PLC executes communication until the end. When the drive condition is always ON, the PLC executes communication repeatedly.

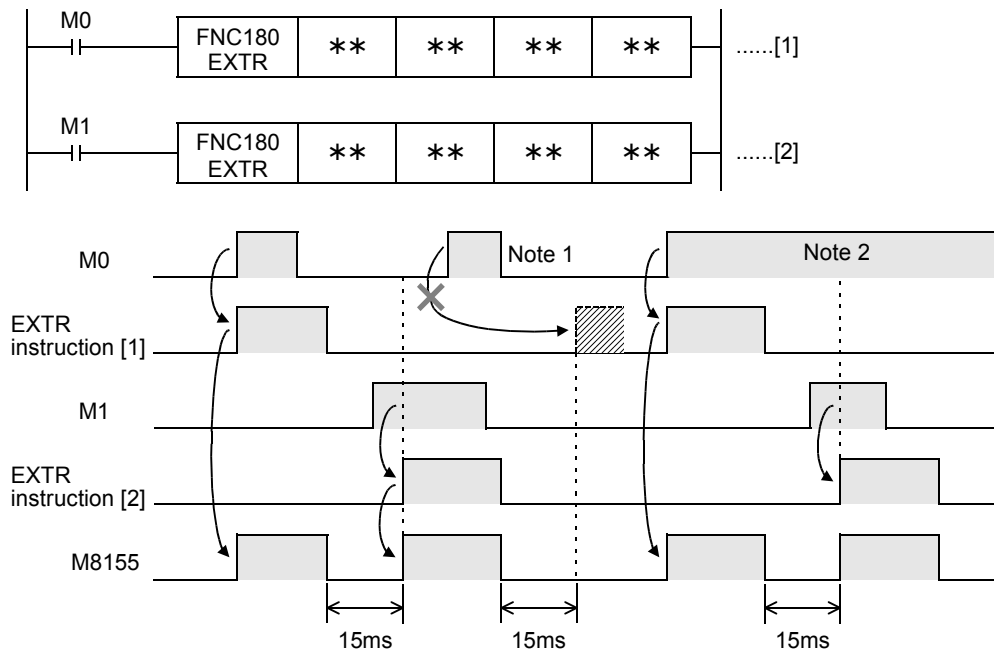
2. Simultaneous driving of EXTR instructions and communication processing

1) Driving instructions at the same time

- Two or more EXTR functions (K10 to K13) can be programmed, and driven at the same time.
- When two or more instructions are driven at the same time during communication, the next EXTR instruction in the program is executed after the current communication with an inverter is finished.



- Even if the drive condition turns ON, the PLC does not start execution of EXTR instruction until the communication port busy flag M8155 turns OFF from ON if M8155 was set to ON by another EXTR instruction.
The PLC waits for 15 ms after freeing the communication port, and then executes EXTR instructions driven in the next step and so on.



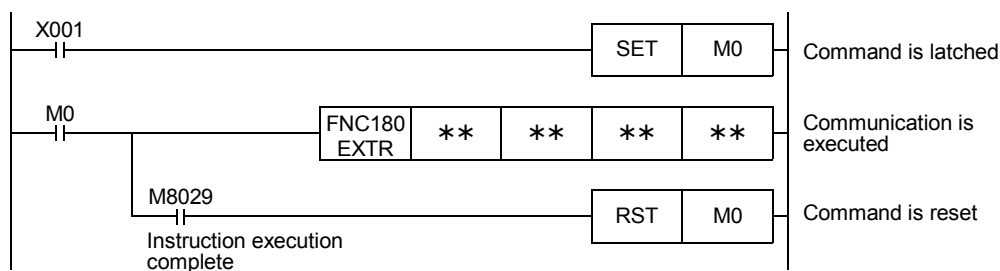
Note 1: If the drive contact is OFF in 15 ms after M8155 turned OFF from ON, the instruction cannot be executed.

Note 2: When two or more instructions are driven at the same time during communication, the EXTR instruction in the next step is executed after the current communication with an inverter is finished.

2) Cautions on programming

When the drive contact for another EXTR instruction is driven by a pulse signal during communication with an inverter, the communication is not executed.

When communicating with inverters for two or more items, let the drive contact for EXTR instruction remain ON until sending is completed. After communication with all inverters is finished, set the drive contact to OFF using the instruction execution complete flag M8029.



3. Communication complete flag (M8029)

When communication with an inverter is finished, the instruction execution complete flag M8029 turns ON, and remains ON for 1 scan.

For details on using M8029 method, refer to program examples shown below.

7.2.3 Instruction completion and error flag operation

When two or more EXTR instructions are programmed, the following flags turn ON or OFF according to the execution result of each EXTR instruction.

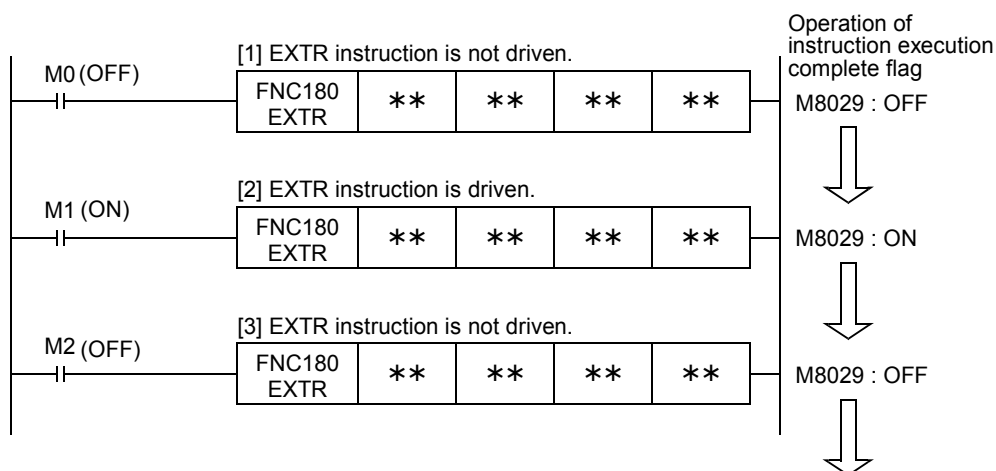
For acquiring the result of each EXTR instruction, make sure to provide these flags just below each EXTR instruction.

| Device number | Description |
|---------------|--|
| M8029 | Instruction execution complete |
| M8156 | Communication error or parameter error |
| D8156 | Error code |

1. Operation of M8029 (instruction execution complete flag)

M8029 (instruction execution complete flag) operates as shown below.

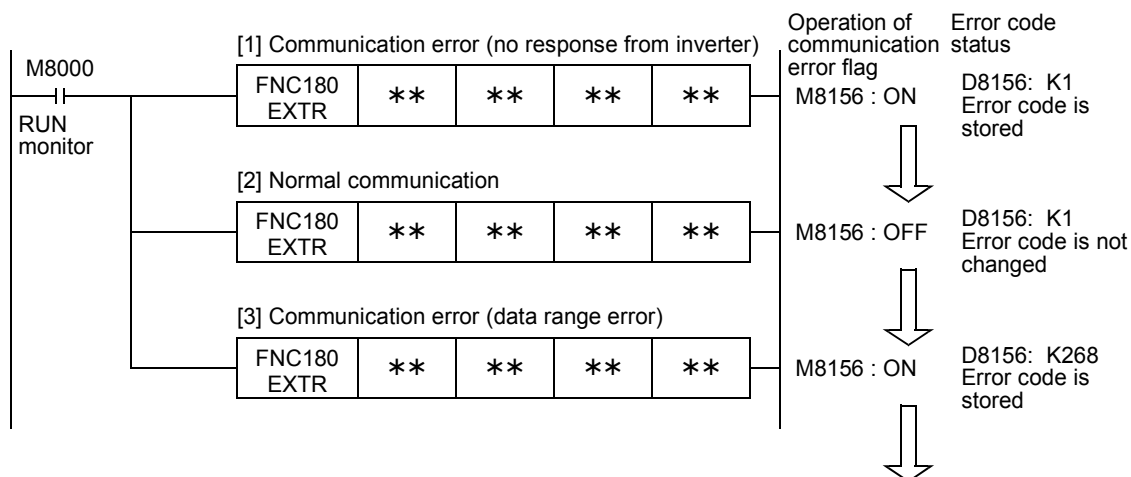
In the program below, M0 and M2 turn OFF and M1 turn ON when communication is completed.



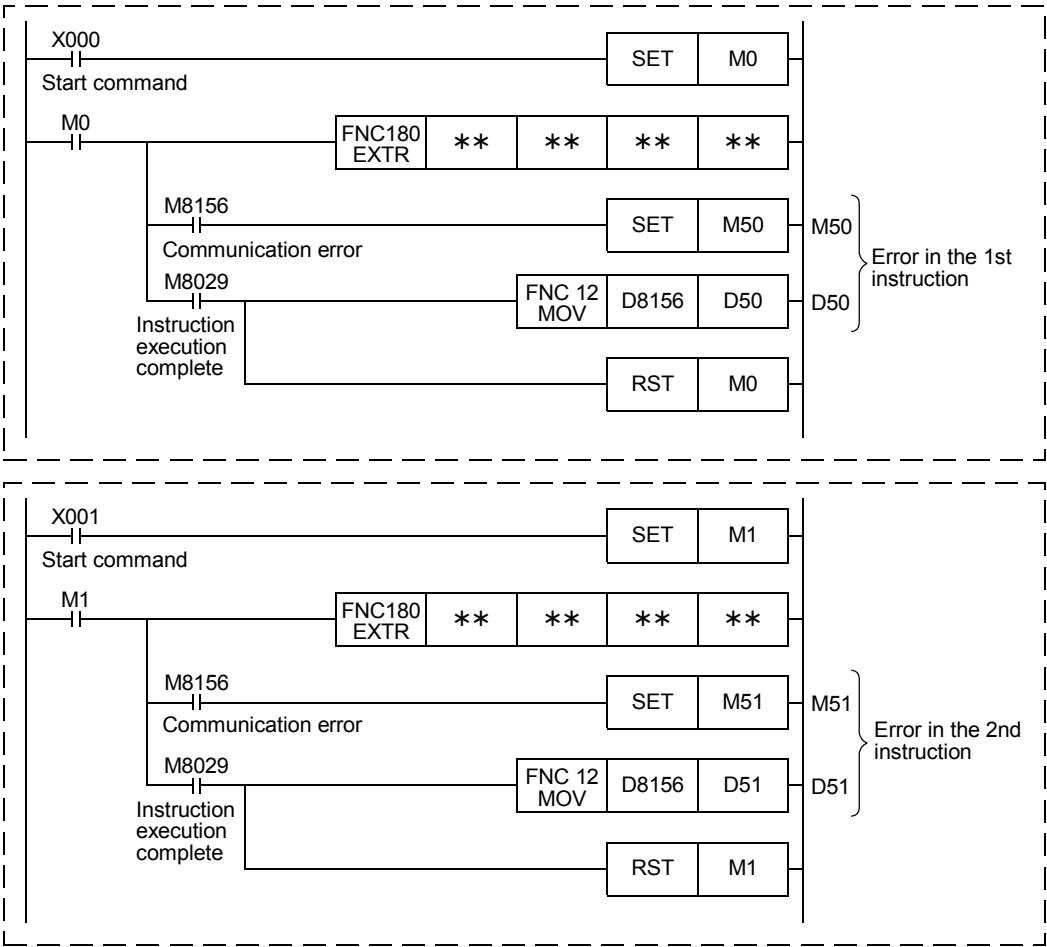
2. Operations of M8156 (error flag) and D8156 (error code)

M8156 (error flag) and D8156 (error code) operate as shown below.

In the program below, a communication error occurs in [1] and [3], and communication is completed normally in [2].



3. Program examples



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

7.2.4 Cautions on programming

1. Using EXTR instruction together with another instruction

- EXTR instruction cannot be used together with RS instruction.
- EXTR instruction cannot be used together with EXTR K0 instruction.

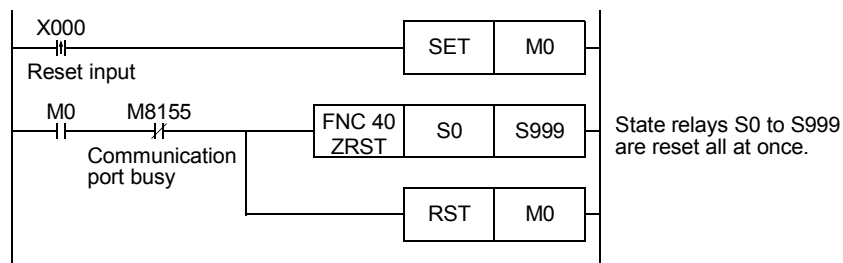
2. When programming EXTR instruction in a state of STL instruction

Make sure to let the state relay remain ON until communication with an inverter is completed. If the state relay is set to OFF during communication, EXTR instruction is stopped in the middle of execution, and another EXTR instruction cannot be started. Program a sequence while observing the following cautions

- Add M8029 (instruction execution complete flag) ON condition to the state relay transfer condition, and provide such an interlock that the state relay ON/OFF status does not change during communication with an inverter.

If the state relay is set to OFF during communication, the remaining communication can be completed by setting the state relay to ON again.

- When resetting many state relays all at once using ZRST (FNC 40) instruction, etc., make sure that the M8155 (communication port busy) OFF condition is established.



3. Using EXTR instruction in a program flow

EXTR instruction cannot be used in the following program flows

| Program flow disabling EXTR instruction | Remarks |
|---|-------------------|
| Between CJ and P instructions | Conditional jump |
| Between FOR and NEXT instructions | Repeat |
| Between P and SRET instructions | Subroutine |
| Between I and IRET instructions | Interrupt routine |

4. Caution on write during RUN

- 1) Condition in which EXTR instruction can be written
While the PLC is in the STOP status, EXTR instruction can be written during RUN.
- 2) Condition in which EXTR instruction cannot be written
EXTR instruction cannot be written in RUN mode by personal computer programming software.
If EXTR instruction is written during RUN while communication or if EXTR instruction is deleted in RUN mode, communication may be disabled after that. (In such a case, set the PLC to STOP, and then to RUN mode again to initialize the status.)

5. When using the E500 Series

Parameters Nos. 922 and 923 in the E500 Series cannot be used in inverter communication.

7.3 Inverter Operation Monitoring Instruction (PLC←Inverter) [EXTR K10]

EXTR K10 instruction reads the operation status of an inverter to the PLC.

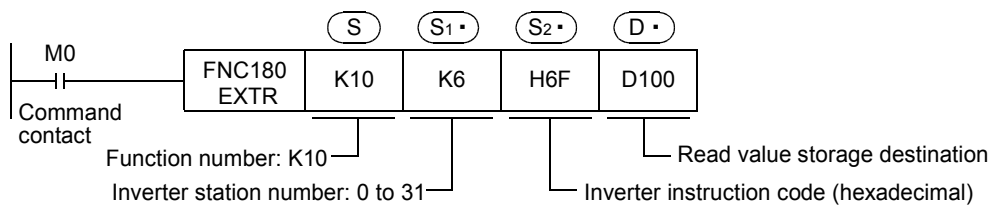
7.3.1 Function and operation

When an "instruction code" specified for computer link operation in inverters is specified in EXTR instruction, a value in the inverter is read to (D•).

1. Applicable devices

| Operand type | Bit device | | | | | | | Word device | | | | | | | | | | Others | | |
|--------------|-------------|---|---|---|---|---|--|---------------------|-----|-----|-----|--------------|---|-------|---|---|--------------|----------|---|---------|
| | System/User | | | | | | | Digit specification | | | | System/ User | | Index | | | | Constant | | Pointer |
| | X | Y | M | T | C | S | | KnX | KnY | KnM | KnS | T | C | D | V | Z | Modification | K | H | P |
| (S) | | | | | | | | | | | | | | | | | | ✓ | ✓ | |
| (S1•) | | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |
| (S2•) | | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |
| (D•) | | | | | | | | ✓ | ✓ | ✓ | | | | ✓ | | | ✓ | | | |

2. Program example



7.3.2 Inverter instruction codes

The table below shows inverter instruction codes which can be specified in (S2•). For the instruction codes, refer to the pages explaining computer link in detail in each inverter manual.

| (S2•) Inverter instruction code (hexadecimal) | Read contents | Applicable inverter | | |
|--|----------------------------------|---|------|------|
| | | A500 | E500 | S500 |
| H7B | Operation mode | ✓ | ✓ | ✓ |
| H6F | Output frequency [speed] | ✓ | ✓ | ✓ |
| H70 | Output current | ✓ | ✓ | ✓ |
| H71 | Output voltage | ✓ | ✓ | — |
| H72 | Special monitor | ✓ | — | — |
| H73 | Special monitor selection No. | ✓ | — | — |
| H74 | Alarm definition | ✓ | ✓ | ✓ |
| H75 | Alarm definition | ✓ | ✓ | ✓ |
| H76 | Alarm definition | ✓ | ✓ | — |
| H77 | Alarm definition | ✓ | ✓ | — |
| H7A | Inverter status monitor | ✓ | ✓ | ✓ |
| H6E | Set frequency read (EEPROM) | ✓ | ✓ | ✓ |
| H6D | Set frequency read (RAM) | ✓ | ✓ | ✓ |
| H7F | Link parameter expansion setting | These codes cannot be specified in (S2•) in EXTR K10 instruction. They are automatically processed when a "second parameter specification code" is specified in EXTR K12 instruction. | | |
| H6C | Second parameter changing | | | |

7.4 Inverter Operation Control Instruction (PLC→Inverter) [EXTR K11]

This instruction writes a control value required to operate an inverter from the PLC to the inverter.

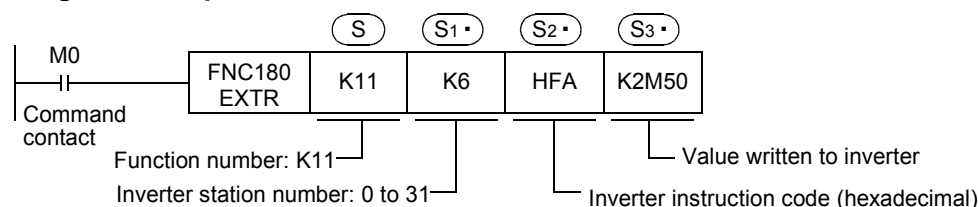
7.4.1 Function and operation

When an "instruction code" specified for computer link operation in inverters is specified in EXTR instruction, a value specified in (S3•) is written to the specified item in the inverter.

1. Applicable devices

| Operand type | Bit device | | | | | | Word device | | | | | | | | | | Others | | |
|--------------|-------------|---|---|---|---|---|---------------------|-----|-----|-----|--------------|---|-------|---|---|--------------|----------|---|---------|
| | System/User | | | | | | Digit specification | | | | System/ User | | Index | | | | Constant | | Pointer |
| | X | Y | M | T | C | S | KnX | KnY | KnM | KnS | T | C | D | V | Z | Modification | K | H | P |
| (S) | | | | | | | | | | | | | | | | | ✓ | ✓ | |
| (S1•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | ✓ | |
| (S2•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | ✓ | |
| (S3•) | | | | | | | ✓ | ✓ | ✓ | ✓ | | | ✓ | | | ✓ | ✓ | ✓ | |

2. Program example



7.4.2 Inverter instruction codes

The table below shows inverter instruction codes which can be specified in (S2•). For the instruction codes, refer to the pages explaining computer link in detail in each inverter manual.

| (S2•) Inverter instruction code (hexadecimal) | Read contents | Applicable inverter | | |
|--|-------------------------------|---------------------|------|------|
| | | A500 | E500 | S500 |
| HFB | Operation mode | ✓ | ✓ | ✓ |
| HF3 | Special monitor selection No. | ✓ | — | — |
| HFA | Run command | ✓ | ✓ | ✓ |
| HEE | Set frequency write (EEPROM) | ✓ | ✓ | ✓ |
| HED | Set frequency write (RAM) | ✓ | ✓ | ✓ |
| HFD*1 | Inverter reset | ✓ | ✓ | ✓ |
| HF4 | Alarm definition batch clear | ✓ | ✓ | ✓ |
| HFC | Parameter all clear | ✓ | ✓ | ✓ |
| HFC | User clear | ✓ | — | — |

- *1. The instruction code "HFD (inverter reset)" does not request response from the inverter. Accordingly, even if inverter reset is executed to a station number in which an inverter is not connected, error does not occur.
It takes about 2.2 seconds to complete execution of inverter reset.

7.5 Inverter Parameter Reading Instruction (PLC←Inverter) [EXTR K12]

This instruction reads a parameter of an inverter to the PLC.

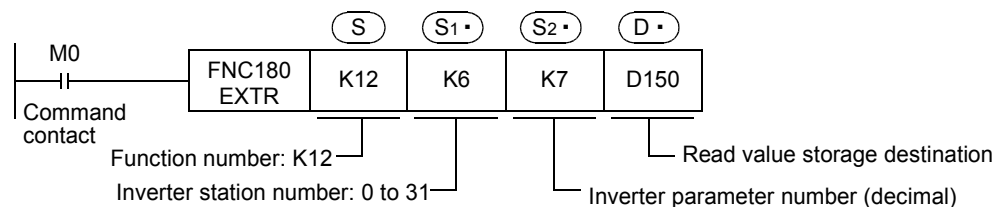
7.5.1 Function and operation

When a parameter number of an inverter is specified in EXTR instruction, the value of the parameter in the inverter is read to (D•).

1. Applicable devices

| Operand type | Bit device | | | | | | Word device | | | | | | | | | | Others | | |
|--------------|-------------|---|---|---|---|---|---------------------|-----|-----|-----|--------------|---|-------|---|---|--------------|----------|---|---------|
| | System/User | | | | | | Digit specification | | | | System/ User | | Index | | | | Constant | | Pointer |
| | X | Y | M | T | C | S | KnX | KnY | KnM | KnS | T | C | D | V | Z | Modification | K | H | P |
| (S) | | | | | | | | | | | | | | | | | ✓ | ✓ | |
| (S1•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |
| (S2•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |
| (D•) | | | | | | | | | | | | | ✓ | | | ✓ | | | |

2. Program example

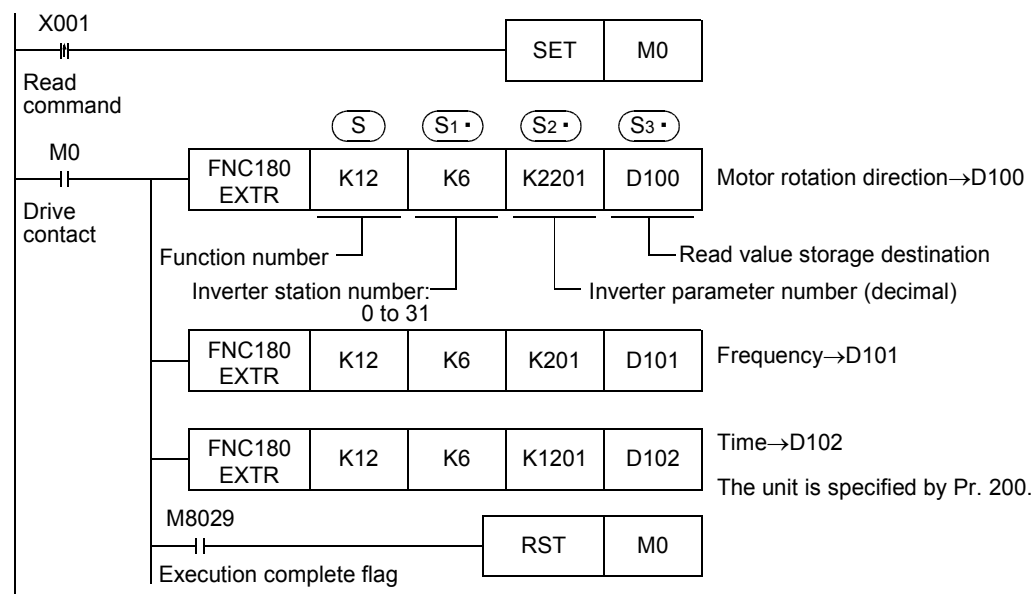


7.5.2 Inverter parameter number

Refer to related data shown later.

7.5.3 Program example of "second parameter specification code"

In the program example shown below, the parameter number 201 (frequency: 201, time: 1201, motor rotation direction: 2201) is read from the A500 inverter whose station number is 6.
Read devices: D100 = Motor rotation direction, D101 = Frequency, D102 = Time



7.6 Inverter Parameter Writing Instruction (PLC→Inverter) [EXTR K13]

This instruction writes a value from the PLC to a parameter in an inverter.

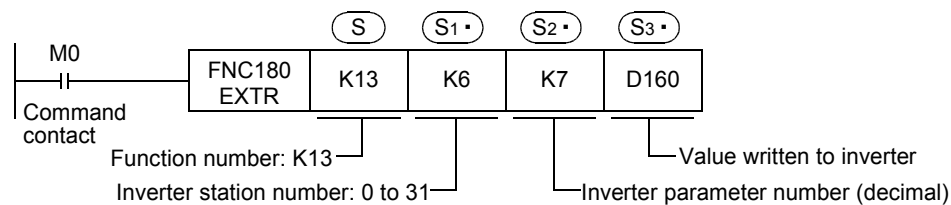
7.6.1 Function and operation

When a parameter number in an inverter is specified in EXTR instruction, the value of (S3•) is written to the specified item in the inverter.

1. Applicable devices

| Operand type | Bit device | | | | | | Word device | | | | | | | | | | Others | | |
|--------------|-------------|---|---|---|---|---|---------------------|-----|-----|-----|--------------|---|-------|---|---|--------------|----------|---|---------|
| | System/User | | | | | | Digit specification | | | | System/ User | | Index | | | | Constant | | Pointer |
| | X | Y | M | T | C | S | KnX | KnY | KnM | KnS | T | C | D | V | Z | Modification | K | H | P |
| (S) | | | | | | | | | | | | | | | | | ✓ | ✓ | |
| (S1•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |
| (S2•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |
| (S3•) | | | | | | | | | | | | | ✓ | | | ✓ | ✓ | | |

2. Program example

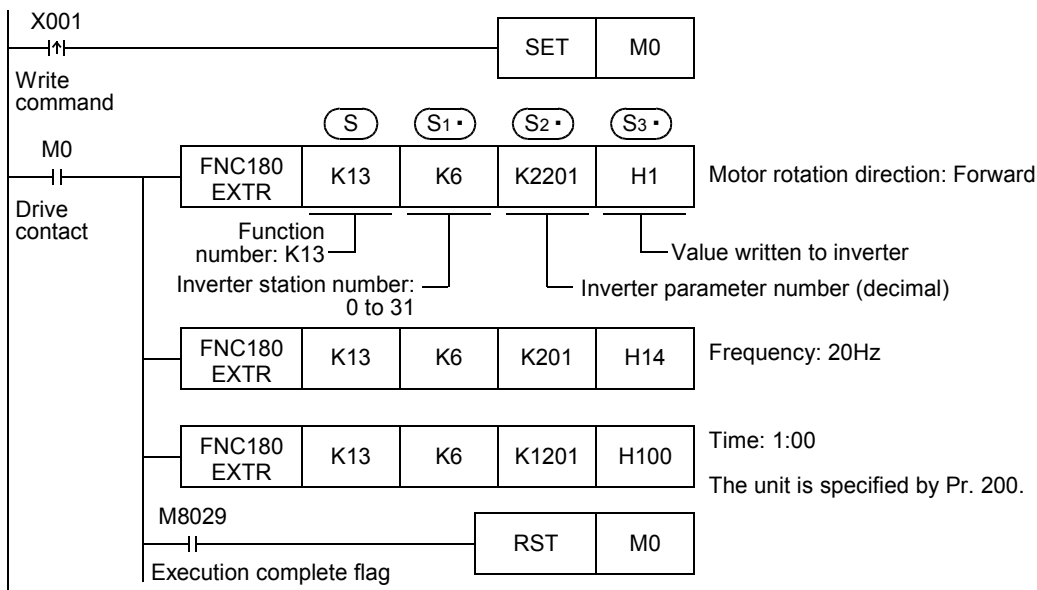


7.6.2 Inverter parameter number

Refer to related data shown later.

7.6.3 Program example of "second parameter specification code"

In the program example shown below, data is written from the PLC to parameter number 201 (frequency: 201, time: 1201, motor rotation direction: 2201) in the A500 inverter.



7.7 Second Parameter Specification Codes

When handling the following parameters in computer link operation, it is necessary to select second parameters.

In EXTR K12 and EXTR K13 instructions, when a value shown in the tables below is set to (S2•), the extension parameter and second parameter are automatically overwritten, and the parameter values are then read or written.

7.7.1 S500 Series

1. Second parameter specification codes for parameter numbers C2 to C7

| Parameter No. | Name | Second parameter specification code [Value to be specified in (S2•) in EXTR instruction for parameter No. (decimal)] |
|---------------|--|---|
| C2 | Frequency setting voltage bias frequency | 902 |
| C3 | Frequency setting voltage bias | 1902 |
| C4 | Frequency setting voltage gain | 903 |
| C5 | Frequency setting current bias frequency | 904 |
| C6 | Frequency setting current bias | 1904 |
| C7 | Frequency setting current gain | 905 |

7.7.2 E500 Series

1. Second parameter specification codes for parameter numbers 902 to 905

| Parameter No. | Name | Second parameter specification code [Value to be specified in (S2•) in EXTR instruction for parameter No. (decimal)] | | |
|---------------|--------------------------------|---|--------------|-----------------------------|
| | | Offset/Gain (H00) | Analog (H01) | Terminal analog value (H02) |
| 902 | Frequency setting voltage bias | 902 | 1902 | 2902 |
| 903 | Frequency setting voltage gain | 903 | 1903 | 2903 |
| 904 | Frequency setting current bias | 904 | 1904 | 2904 |
| 905 | Frequency setting current gain | 905 | 1905 | 2905 |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

7.7.3 A500 Series

1. Second parameter specification codes for parameter numbers 201 to 230

| Parameter No. | Name | Second parameter specification code [Value to be specified in (S2) in EXTR instruction for parameter No. (decimal)] | | |
|---------------|---------------|--|-----------------|-------------------------------|
| | | Operation frequency read/write | Time read/write | Rotation direction write/read |
| 201 | Program set 1 | 201 | 1201 | 2201 |
| 202 | Program set 1 | 202 | 1202 | 2202 |
| 203 | Program set 1 | 203 | 1203 | 2203 |
| 204 | Program set 1 | 204 | 1204 | 2204 |
| 205 | Program set 1 | 205 | 1205 | 2205 |
| 206 | Program set 1 | 206 | 1206 | 2206 |
| 207 | Program set 1 | 207 | 1207 | 2207 |
| 208 | Program set 1 | 208 | 1208 | 2208 |
| 209 | Program set 1 | 209 | 1209 | 2209 |
| 210 | Program set 1 | 210 | 1210 | 2210 |
| 211 | Program set 2 | 211 | 1211 | 2211 |
| 212 | Program set 2 | 212 | 1212 | 2212 |
| 213 | Program set 2 | 213 | 1213 | 2213 |
| 214 | Program set 2 | 214 | 1214 | 2214 |
| 215 | Program set 2 | 215 | 1215 | 2215 |
| 216 | Program set 2 | 216 | 1216 | 2216 |
| 217 | Program set 2 | 217 | 1217 | 2217 |
| 218 | Program set 2 | 218 | 1218 | 2218 |
| 219 | Program set 2 | 219 | 1219 | 2219 |
| 220 | Program set 2 | 220 | 1220 | 2220 |
| 221 | Program set 3 | 221 | 1221 | 2221 |
| 222 | Program set 3 | 222 | 1222 | 2222 |
| 223 | Program set 3 | 223 | 1223 | 2223 |
| 224 | Program set 3 | 224 | 1224 | 2224 |
| 225 | Program set 3 | 225 | 1225 | 2225 |
| 226 | Program set 3 | 226 | 1226 | 2226 |
| 227 | Program set 3 | 227 | 1227 | 2227 |
| 228 | Program set 3 | 228 | 1228 | 2228 |
| 229 | Program set 3 | 229 | 1229 | 2229 |
| 230 | Program set 3 | 230 | 1230 | 2230 |

2. Second parameter specification codes for parameter numbers 902 to 905

| Parameter No. | Name | Second parameter specification code [Value to be specified in (S2) in EXTR instruction for parameter No. (decimal)] | | |
|---------------|--------------------------------|--|--------------|-----------------------------|
| | | Offset/Gain (H00) | Analog (H01) | Terminal analog value (H02) |
| 902 | Frequency setting voltage bias | 902 | 1902 | 2902 |
| 903 | Frequency setting voltage gain | 903 | 1903 | 2903 |
| 904 | Frequency setting current bias | 904 | 1904 | 2904 |
| 905 | Frequency setting current gain | 905 | 1905 | 2905 |

8. Practical Program Examples (for FX2N and FX2NC PLCs)

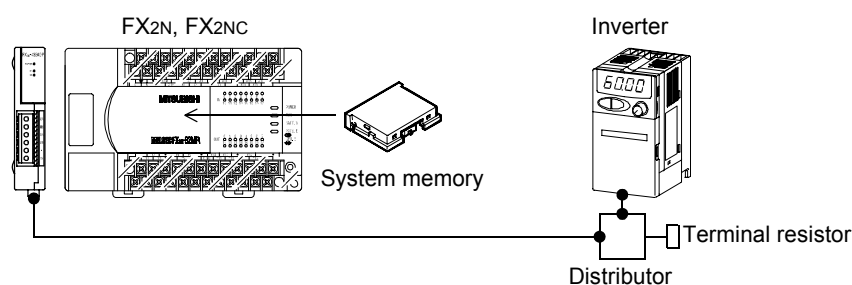
This chapter explains practical programs for inverter communication.

8.1 Practical Example 1

This fundamental program example monitors operations of an inverter, controls operations of an inverter and writes parameters to an inverter.

8.1.1 System configuration example

An FX PLC is connected to an inverter.



8.1.2 Contents of operation

As an example of operation control, an inverter can be stopped (X000), rotated forward (X001) and rotated reverse (X002).

By changing the contents of D10, the speed can be changed.

The contents of D10 can be changed from a sequence program or display unit.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

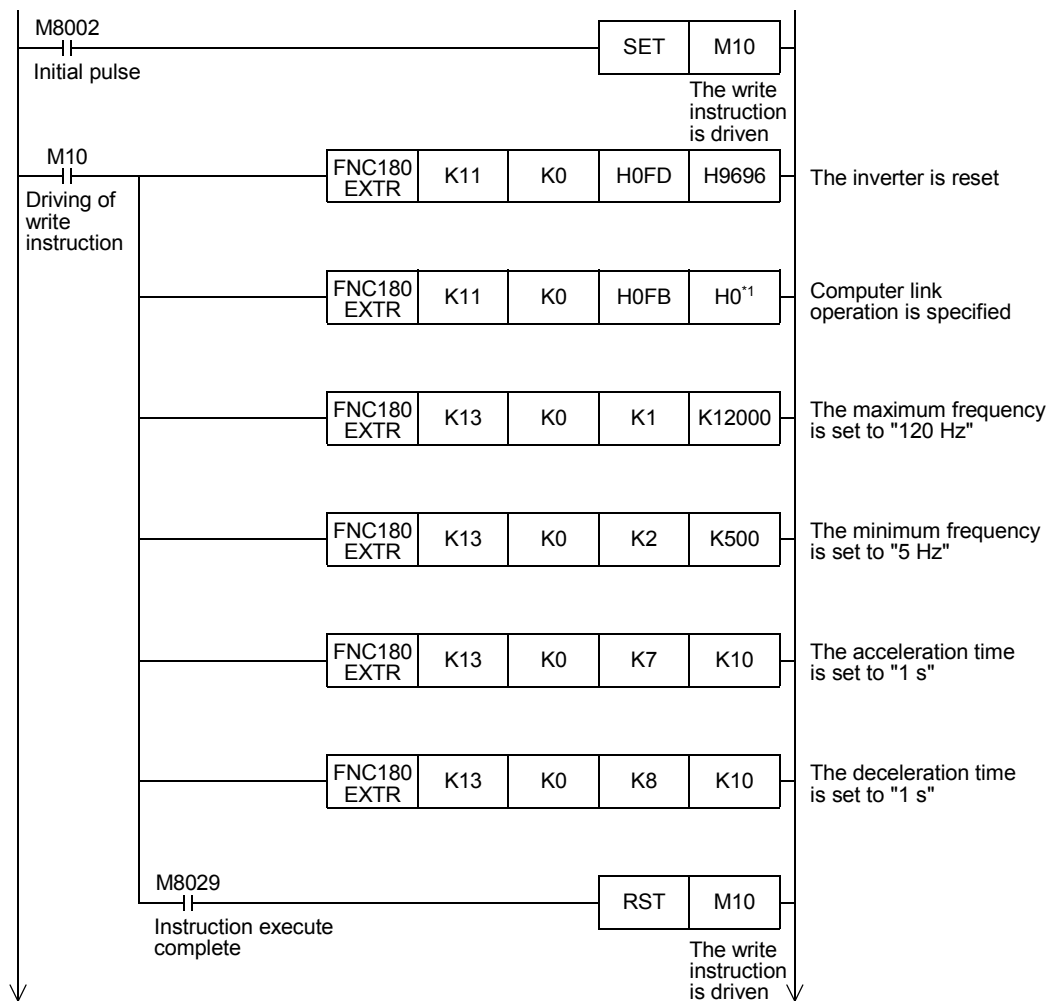
Remote Maintenance

Apx.

Discontinued models

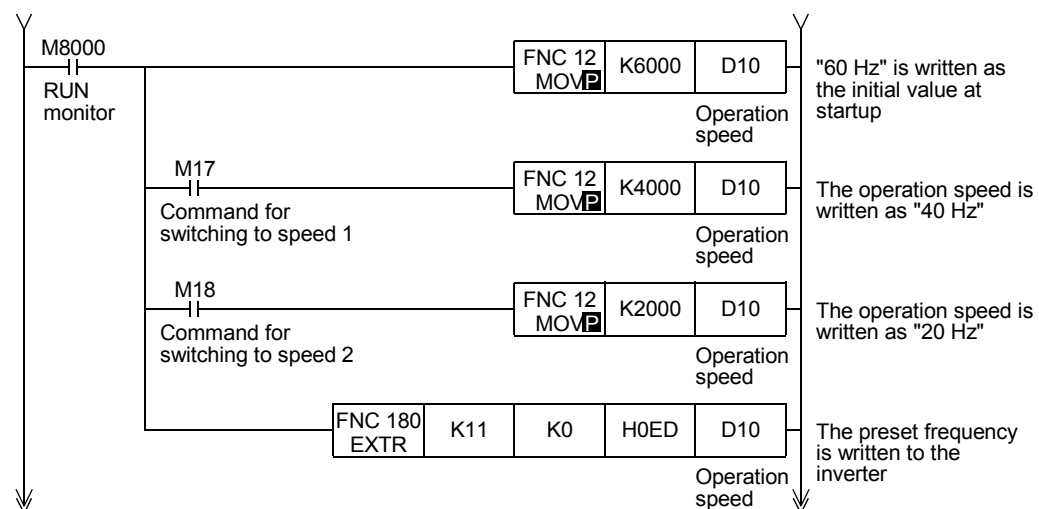
8.1.3 Program example

1. Writing parameters to an inverter while the PLC is in RUN mode

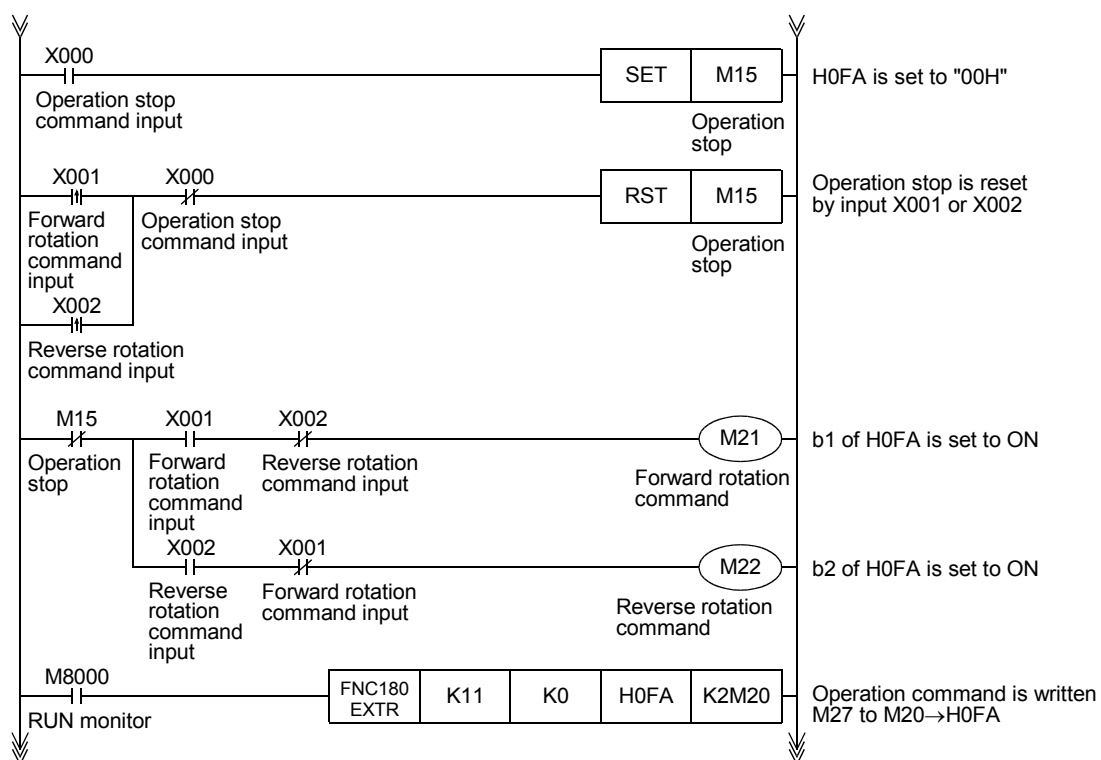


*1. When using an E500 Series inverter, use "H2" to specify computer link operation.

2. Changing the speed using a sequence program



3. Controlling operations of an inverter



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

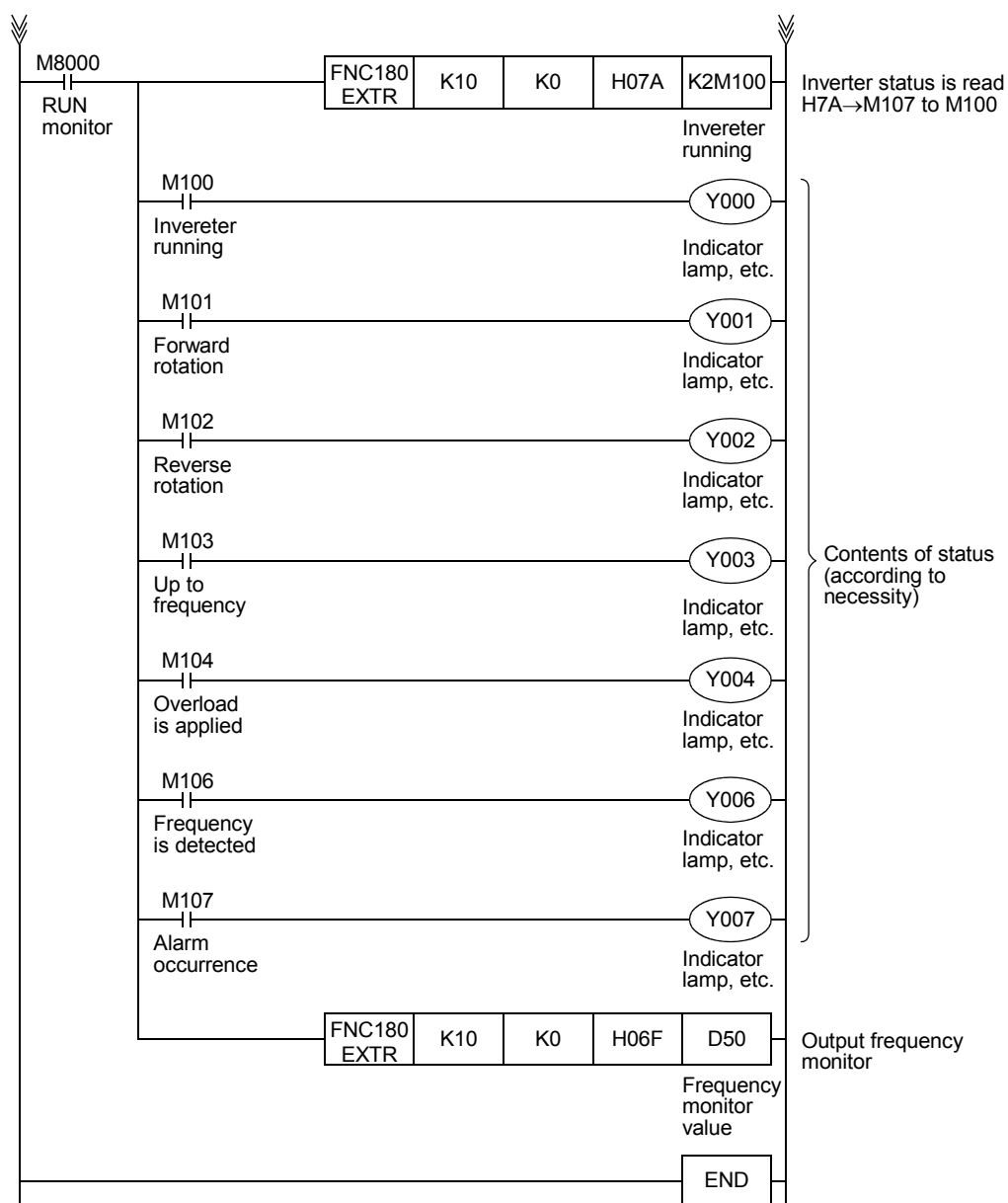
I

Remote Maintenance

Apx.

Discontinued models

4. Monitoring operations of an inverter

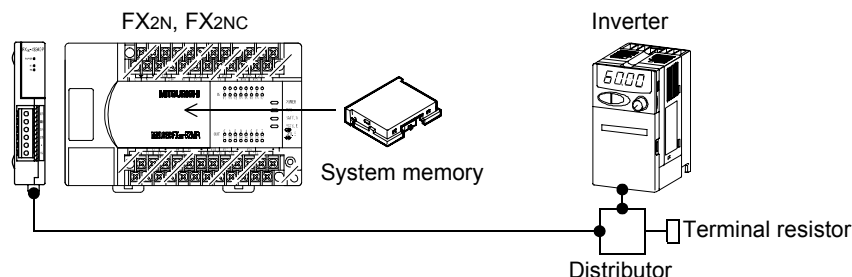


8.2 Practical Example 2

This program executes the same control as practical example 1 shown above.

8.2.1 System configuration example

An FX PLC is connected to an inverter.



8.2.2 Contents of operation

The differences from practical example 1 are that the inverter status is not read while data is written to an inverter, and that the contents to be written are detected and written to an inverter only when the contents to be written are changed.

Because communication between the PLC and the inverter is minimum in this program, the communication time is reduced and the response time is improved.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

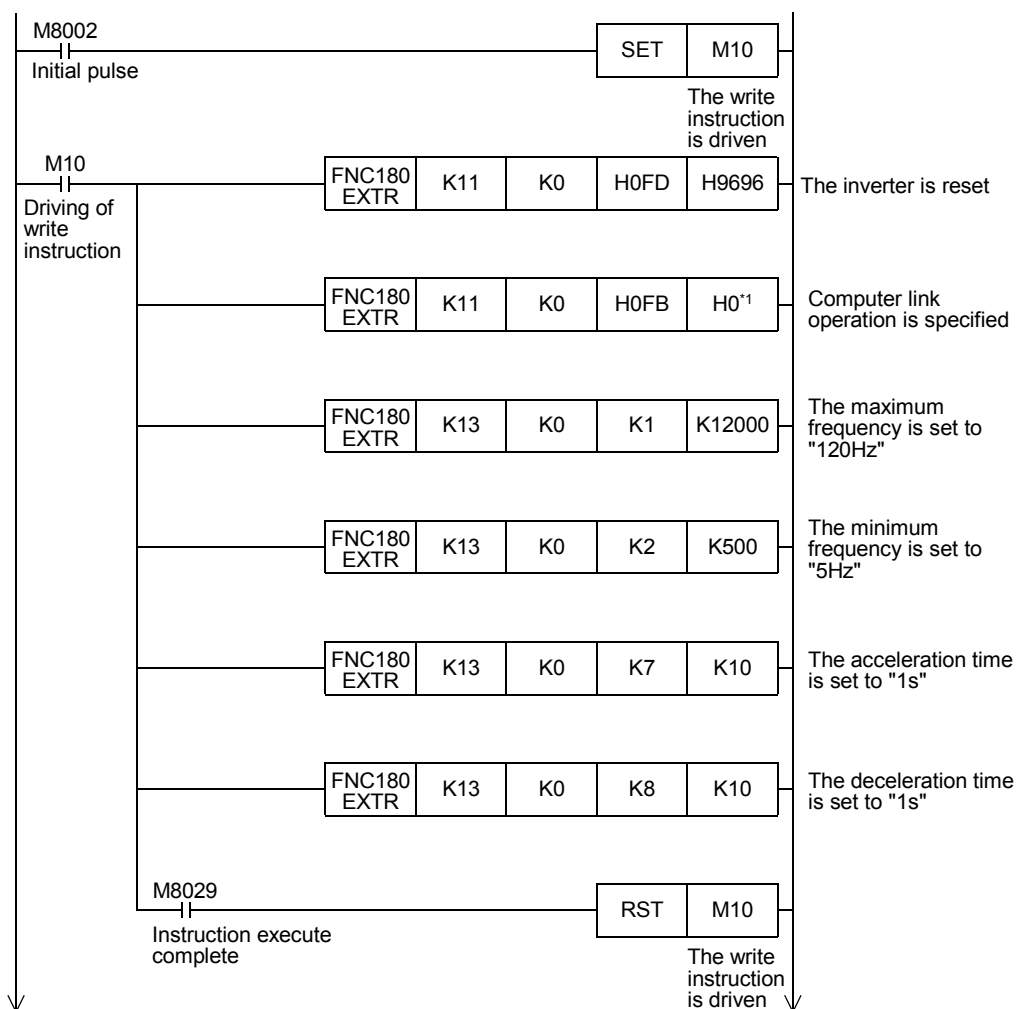
Remote Maintenance

Apx.

Discontinued models

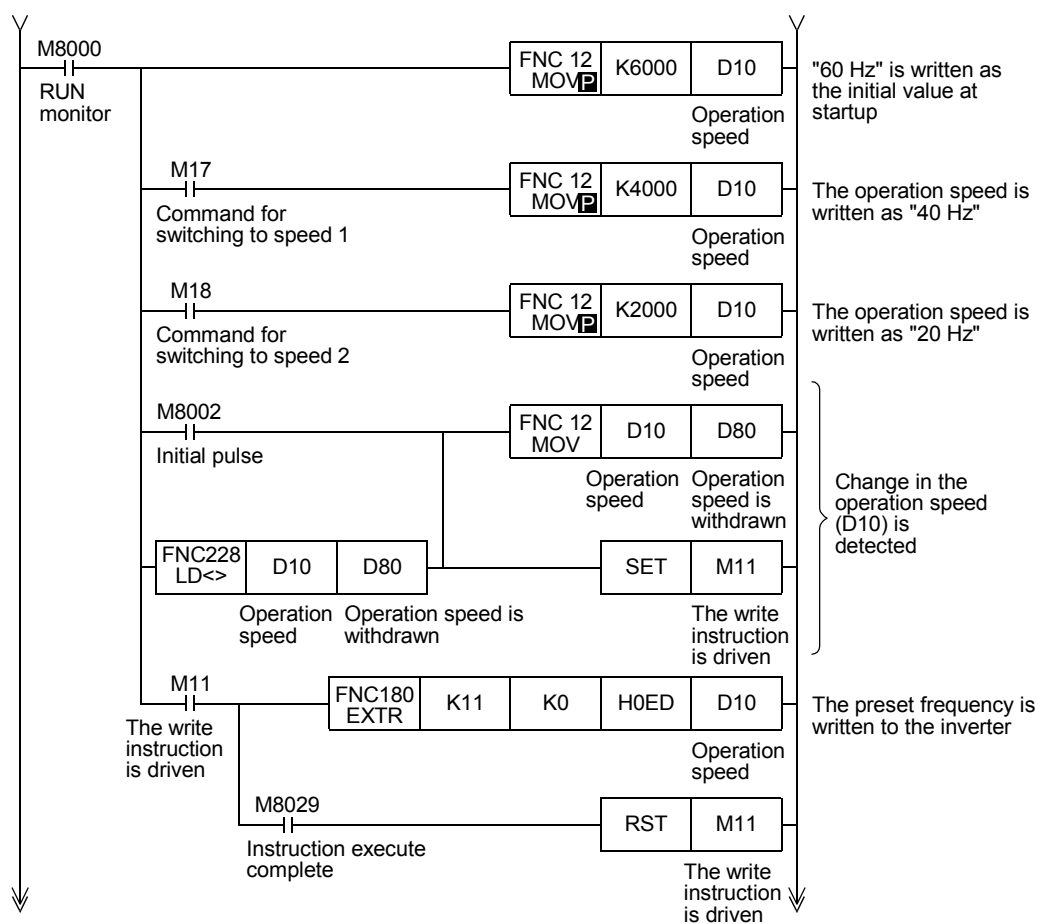
8.2.3 Program example

1. Writing parameters to an inverter while the PLC is in RUN mode



*1. When using an E500 Series inverter, use "H2" to specify computer link operation.

2. Changing the speed using a sequence program



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

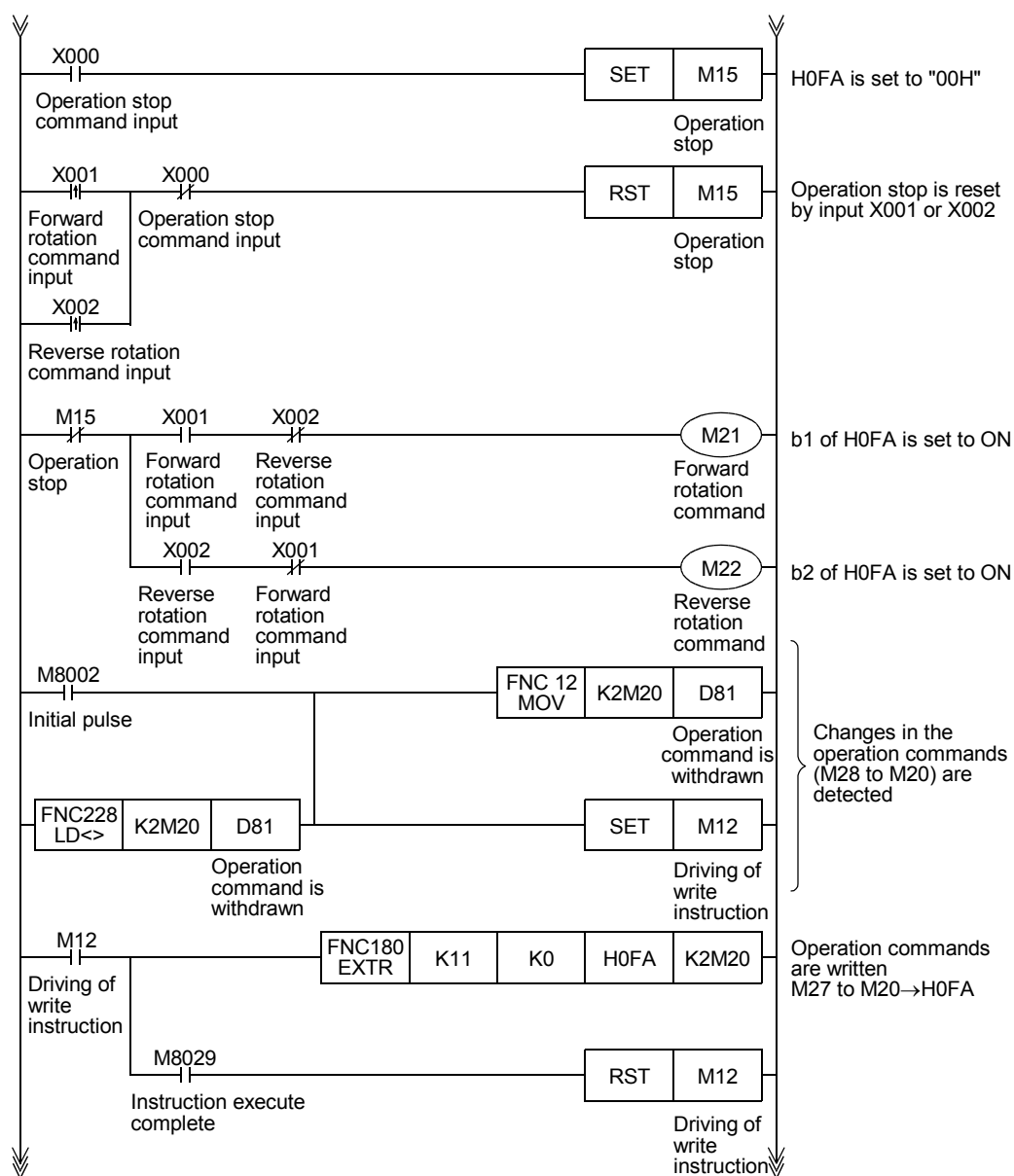
I

Remote Maintenance

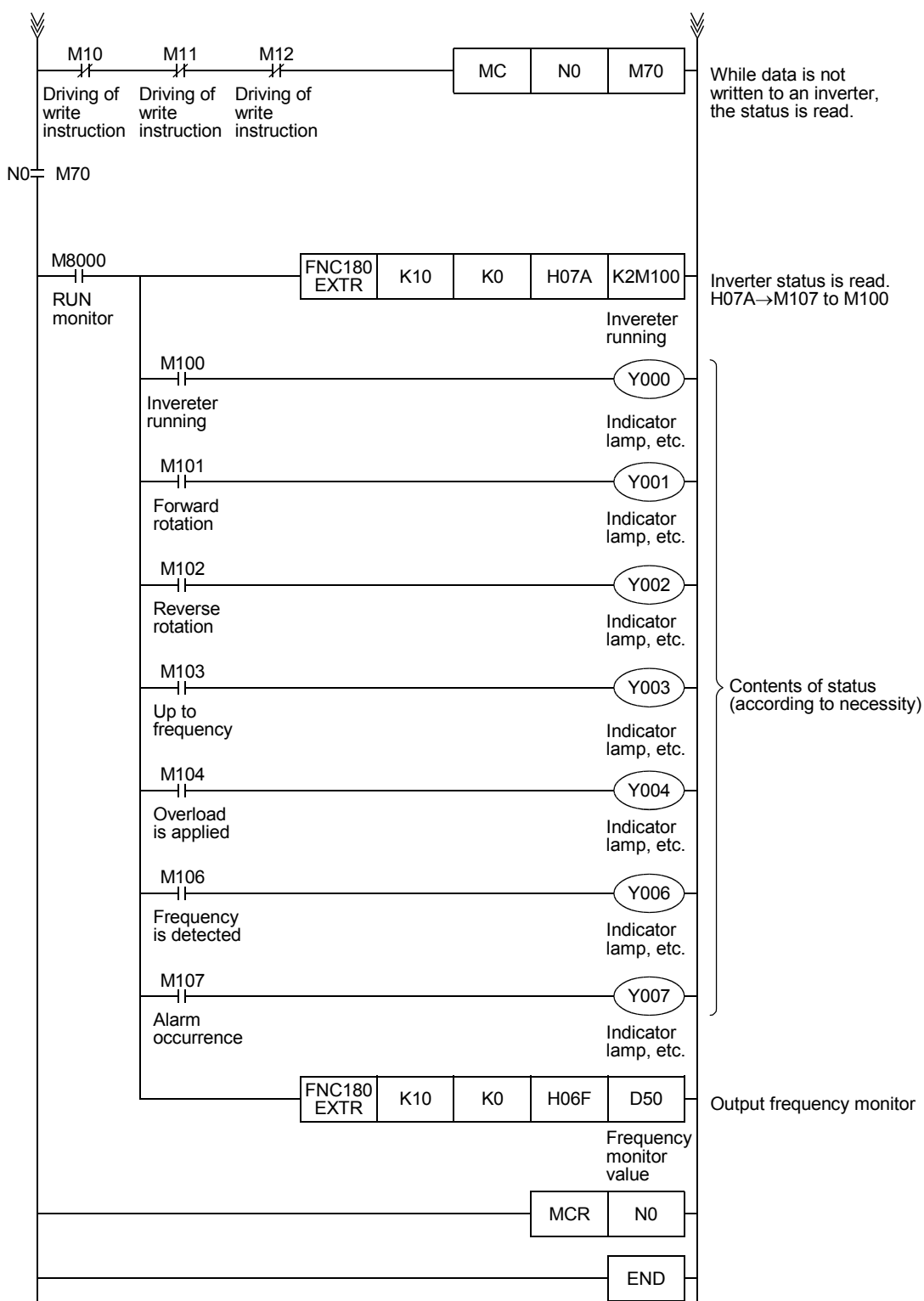
Apx.

Discontinued models

3. Controlling operations of an inverter



4. Monitoring operations of an inverter



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9. Creating Programs (for FX3U and FX3UC PLCs)

This chapter explains how to create programs which change parameters of inverters and give operation commands to inverters.

As explanation, a program example is shown for each applied instruction.

9.1 Differences between FX2N/FX2NC PLCs and FX3U/FX3UC PLCs

Instruction devices used in inverter communication are different between FX3U/FX3UC PLCs and FX2N/FX2NC PLCs.

When using a program for FX2N/FX2NC PLCs in FX3U/FX3UC PLCs, change the devices according to the tables below.

1. Inverter communication instructions

| Function | FX2N,FX2NC | FX3U,FX3UC |
|---|------------|------------|
| Monitoring operation of an inverter | EXTR(K10) | IVCK |
| Controlling operation of an inverter | EXTR(K11) | IVDR |
| Reading parameters from an inverter | EXTR(K12) | IVRD |
| Writing parameters to an inverter | EXTR(K13) | IVWR |
| Writing parameters to an inverter all at once | — | IVBWR |

2. Related devices

1) Bit devices

| Function | FX2N,FX2NC | FX3U,FX3UC | |
|--|------------|------------|-------|
| | | ch1 | ch2 |
| Instruction execution complete | M8029 | M8029 | M8029 |
| Communication error (shared by all communication) | M8063*1 | M8063 | M8438 |
| Inverter communicating | M8155 | M8151 | M8156 |
| Inverter communication error | M8156 | M8152 | M8157 |
| Inverter communication error latch | M8157 | M8153 | M8158 |
| IVBWR instruction error | — | M8154 | M8159 |

*1. In the FX2N and FX2NC PLCs, M8063 does not turn ON when an inverter communication error occurs.

2) Word devices

| Function | FX2N,FX2NC | FX3U,FX3UC | |
|--|------------|------------|-------|
| | | ch1 | ch2 |
| Error code (shared by all communication) | D8063 | D8063 | D8438 |
| Response wait time of inverter communication | D8154 | D8150 | D8155 |
| Step number of instruction during inverter communication | D8155 | D8151 | D8156 |
| Inverter communication error code | D8156 | D8152 | D8157 |
| Inverter communication error occurrence step | D8157 | D8153 | D8158 |
| IVBWR instruction error parameter number | — | D8154 | D8159 |

9.2 Contents of Related Devices

The tables below show devices used for inverter communication in FX3U and FX3UC PLCs.

1. Bit devices

| Device No. | | Name | Description | R/W |
|------------|-------|--------------------------------------|---|-----|
| ch1 | ch2 | | | |
| M8029 | | Instruction execution complete | Turns ON when execution of inverter communication instruction is completed, and remains ON for 1 scan. Turns ON also when execution of instruction is completed if inverter communication error flag (M8152 or M8157) turns ON. | R |
| M8063 | M8438 | Serial communication error | Turns ON when an error occurs in any type of communication. | R |
| M8151 | M8156 | Inverter communicating | Remains ON while inverter communication is being executed. | R |
| M8152 | M8157 | Inverter communication error*1 | Turns ON when an error occurs during communication with an inverter. | R |
| M8153 | M8158 | Inverter communication error latch*1 | Turns ON when an error occurs during communication with an inverter. | R |
| M8154 | M8159 | IVBWR instruction error*1 | Turns ON when an error is caused by IVBWR instruction. | R |

R: Read only (used as a contact in program)

*1. Cleared when the PLC mode is changed from STOP to RUN.

2. Word devices

| Device No. | | Name | Description | R/W |
|------------|-------|---|---|-----|
| ch1 | ch2 | | | |
| D8063 | D8438 | Error code for serial communication*1 | Stores a communication error code. | R |
| D8150 | D8155 | Inverter communication response waiting time | Sets the response wait time of inverter communication. | R/W |
| D8151 | D8156 | Step number of instruction executing inverter communication | Stores the step number of an instruction during inverter communication. | R |
| D8152 | D8157 | Error code for inverter communication*1 | Stores an inverter communication error code. | R |
| D8153 | D8158 | Step where inverter communication error occurred*1 | Latches a step number in which inverter communication error has occurred. | R |
| D8154 | D8159 | Error parameter number of IVBWR instruction*1 | Stores a parameter number in which an IVBWR instruction error has occurred. | R |

R: Read only

R/W: Read or Write

*1. Cleared when the PLC mode is changed from STOP to RUN.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (FS/R52 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

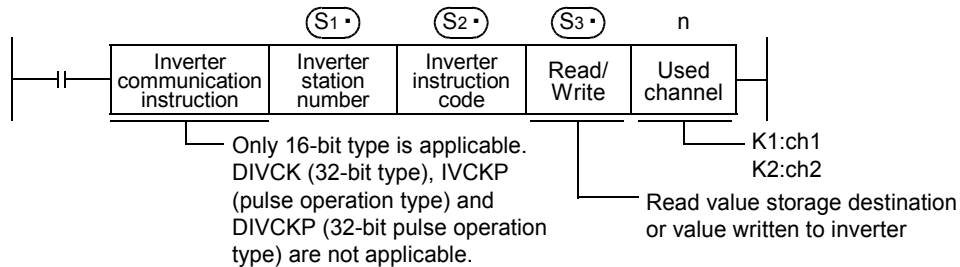
Apx.
Discontinued models

9.3 Common Items in Inverter Communication Instructions

9.3.1 Inverter communication types (IVCK to IVBWR)

Execute inverter communication using the following applied instructions.

There are five types of applied instructions, "IVCK (FNC270) to IVBWR (FNC274)", depending on the data communication direction and parameter reading/writing direction.



| Instruction | Function | Control direction | Detailed explanation |
|---------------|---|-------------------|----------------------|
| IVCK(FNC270) | Monitors operations of an inverter. | PLC ← inverter | 9.4 |
| IVDR(FNC271) | Controls operations of an inverter. | PLC → inverter | 9.5 |
| IVRD(FNC272) | Reads a parameter from an inverter. | PLC ← inverter | 9.6 |
| IVWR(FNC273) | Writes a parameter to an inverter. | PLC → inverter | 9.7 |
| IVBWR(FNC274) | Writes parameters to an inverter all at once. | PLC → inverter | 9.8 |

9.3.2 Function and operation

1. Communication start timing

At the rising edge (OFF→ON) of the drive condition, the PLC starts communication with an inverter.

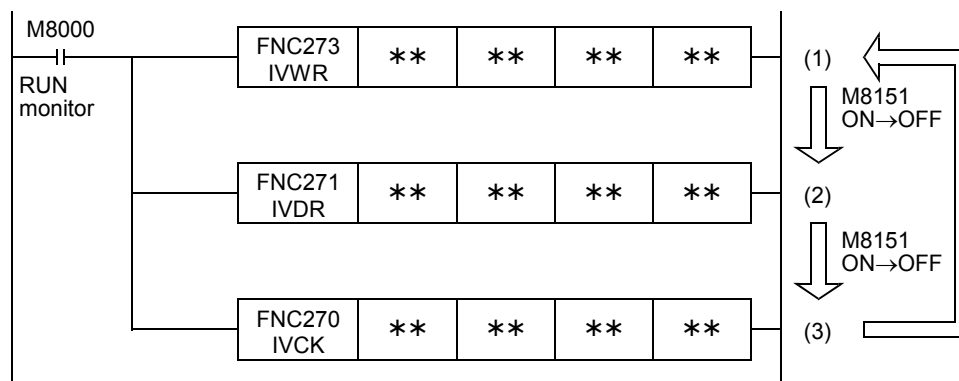
Even if the drive condition turns OFF during communication with an inverter, the PLC executes communication until the last instruction.

When the drive condition is always ON, the PLC executes communication repeatedly.

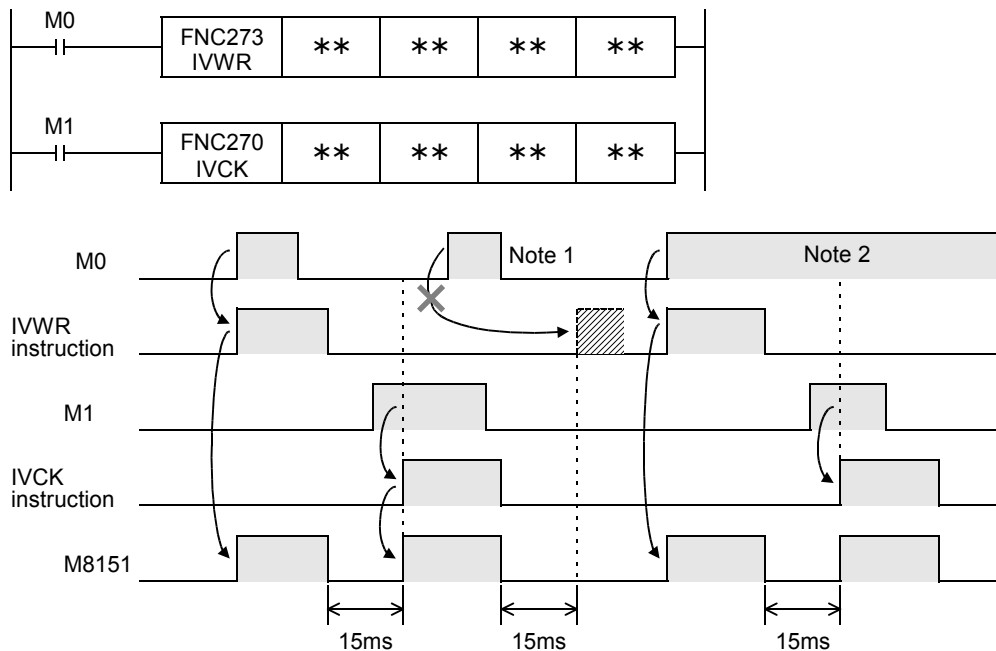
2. Simultaneous driving of instructions and communication processing

1) Driving instructions at the same time

- Two or more IVCK (FNC270) to IVBWR (FNC274) instructions can be programmed, and driven at the same time.
- When two or more instructions are driven at the same time in the channel used for communication, the latter inverter communication instruction in the program is executed after the current communication with the inverter has finished.



- Even if the drive condition turns ON, the PLC does not start execution of an inverter communication instruction until the communication port busy flag M8151 turns OFF from ON, if M8151 is already set to ON by another inverter communication instruction.
The PLC waits for 15 ms after freeing the communication port, and then executes the inverter communication instructions driven in the next step and so on.

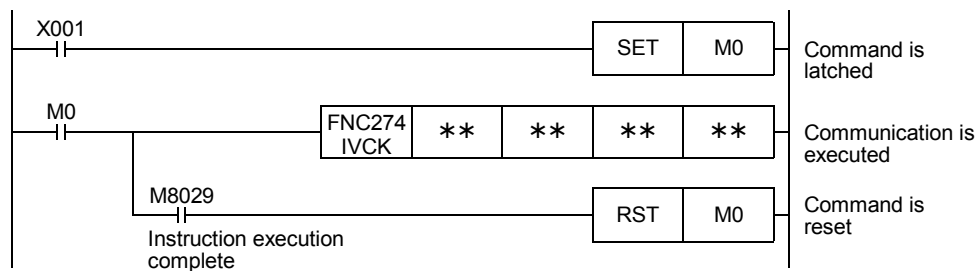


Note 1: If the drive contact is OFF in 15 ms after M8151 is turned OFF from ON, the instruction cannot be executed.

Note 2: When two or more instructions are driven at the same time during communication, the latter inverter communication instruction in the program is executed after the current communication with the inverter is finished.

2) Cautions on programming

When communicating with inverters for two or more items, let the drive contact for inverter communication instruction remain ON until sending is completed. After communication with all inverters is finished, set the drive contact to OFF using the instruction execution complete flag M8029.



3. Communication complete flag (M8029)

When communication with an inverter is finished, the instruction execution complete flag M8029 turns ON, and remains ON for 1 scan.

For the M8029 use method, refer to program examples shown below.

9.3.3 Instruction completion and error flag operation

When two or more inverter communication instructions are programmed, the following flags turn ON or OFF according to the execution result of each inverter communication instruction.

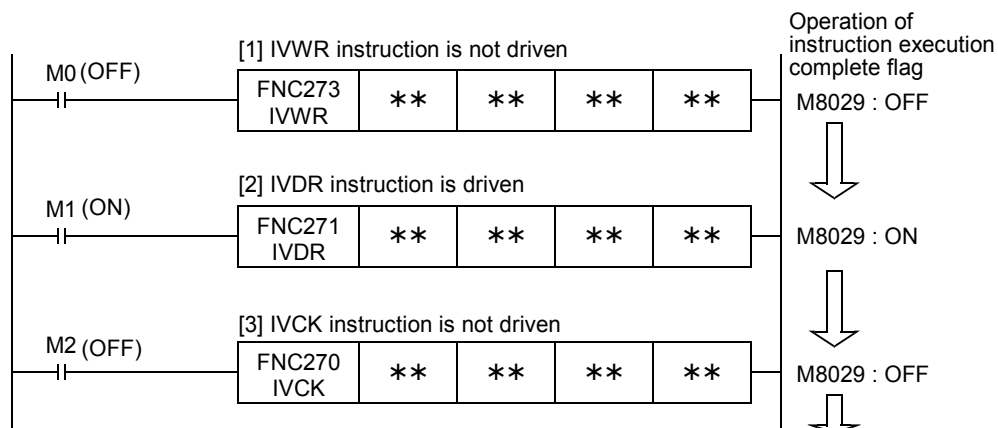
To acquire the result of each inverter communication instruction, make sure to provide these flags just below each inverter communication instruction.

| Device number | | Description |
|---------------|-------|-----------------------------------|
| ch1 | ch2 | |
| M8029 | | Instruction execution complete |
| M8063 | M8438 | Serial communication error |
| M8152 | M8157 | Inverter communication error |
| M8153 | M8158 | Inverter communication error lach |
| M8154 | M8159 | IBWR instruction error |

| Device number | | Description |
|---------------|-------|---|
| ch1 | ch2 | |
| D8063 | D8438 | Serial communication error code |
| D8152 | D8157 | Inverter communication error code |
| D8153 | D8158 | Step in which inverter communication error occurred |
| D8154 | D8159 | IBWR error parameter number |

1. Operation of M8029 (instruction execution complete flag)

The operation of M8029 (instruction execution complete flag) represents the state in which the IVDR instruction is completed while M0, M2 are off and M1 is ON.



2. Processing of communication errors

The following two types of processing are executed for communication errors.

The parity error/overflow error/framing error flags (shown in the upper column) turns ON when an error occurs in any type of communication.

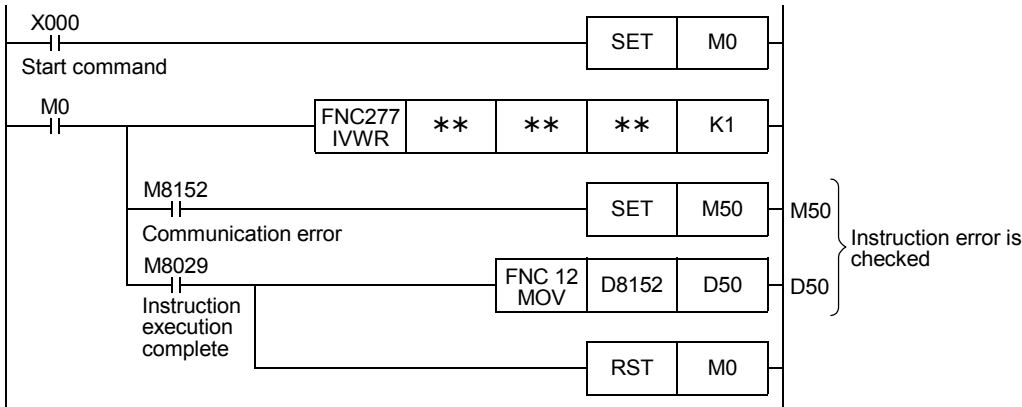
The error flag shown in the lower column turns ON when an error occurs during communication with an inverter.

| Bit device | | | | | | Word device | | Description |
|------------|-------|-------|-------|-------------------------|-------|-------------|-------|---|
| ch1 | ch2 | ch1 | ch2 | ch1 | ch2 | ch1 | ch2 | |
| M8063 | M8438 | M8152 | M8157 | M8153 | M8159 | D8063 | D8438 | |
| ON | | OFF | | OFF | | 6301 | 3801 | Parity error, overrun error or framing error |
| ON | | ON | | ON (only at first time) | | 6320 | 3820 | Any inverter communication error other than those above |

When inverter communication error flag turns ON, the step number is stored in the inverter communication error occurrence step device (D8153 or D8158).

Create the program shown below for each corresponding instruction to check the inverter communication error code (stored in D8152 or D8157).

3. Program example



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9.3.4 Cautions on programming

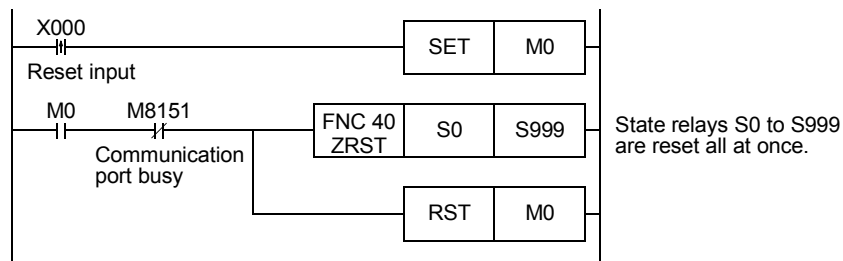
1. Using inverter communication instruction together with another instruction

- Inverter communication instruction using ch1 cannot be used together with RS instruction.
- Inverter communication instruction cannot be used together with RS2 instruction if RS2 instruction uses the same channel.

2. When programming inverter communication instruction in a state of STL instruction

Make sure to let the state relay remain ON until communication with an inverter is completed. If the state relay is set to OFF during communication, inverter communication instruction is stopped in the middle of execution, and another inverter communication instruction cannot be started. Program a sequence while observing the following cautions

- Add M8029 (instruction execution complete flag) ON condition to the state relay transfer condition, and provide such interlock that the state relay ON/OFF status does not change during communication with an inverter.
If the state relay is set to OFF during communication, the remaining communication can be completed by setting the state relay to ON again.
- When resetting many state relays all at once using the ZRST (FNC 40) instruction, etc., make sure that the M8151 or M8156 (communication port busy) condition is OFF.



3. Using inverter communication instruction in a program flow

Inverter communication instruction cannot be used in the following program flows

| Program flow disabling inverter communication instruction | Remarks |
|---|-------------------|
| Between CJ and P instructions | Conditional jump |
| Between FOR and NEXT instructions | Repeat |
| Between P and SRET instructions | Subroutine |
| Between I and IRET instructions | Interrupt routine |

4. Caution on writing during RUN

- 1) Condition in which inverter communication instruction can be written:
While the PLC is in the STOP status, inverter communication instruction can be written during RUN.
- 2) Condition in which inverter communication instruction cannot be written:
Inverter communication instruction cannot be written during RUN by programming software in a personal computer.
If an inverter communication instruction is written during RUN during communication or if an inverter communication instruction is deleted while in RUN, communication may be disabled after that. (In such a case, set the PLC to STOP, and then to RUN mode again to initialize the status.)

5. When using the E500 Series

Parameters Nos. 922 and 923 in the E500 Series cannot be used in inverter communication.

9.4 Inverter Operation Monitoring Instruction (PLC←Inverter) [FNC270 / IVCK]

IVCK instruction reads the operation status of an inverter to the PLC.

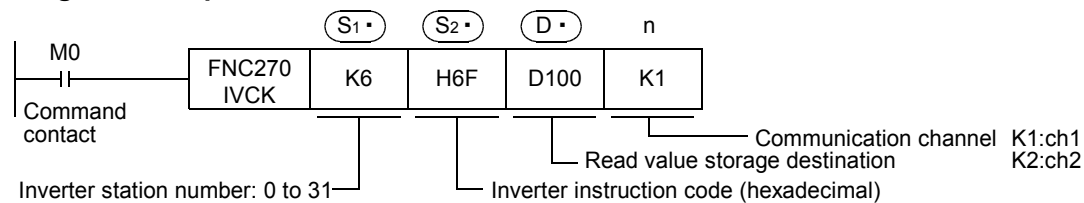
9.4.1 Function and operation

When an "instruction code" specified for computer link operation in the inverters is specified in the IVCK (FNC270) instruction, a value in the inverter is read to (D•).

1. Applicable devices

| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | Others | | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|-------|---|--------|----------|---|-------------|------------------|---------|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | Index | | | Constant | | Real Number | Character String | Pointer |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P |
| (S1•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | |
| (S2•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | |
| (D•) | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | ✓ | | | | | |
| n | | | | | | | | | | | | | | | | | | | | ✓ | ✓ | | | |

2. Program example



9.4.2 Inverter instruction codes

The table below shows inverter instruction codes which can be specified in (S2•).
For the instruction codes, refer to the pages explaining computer link in detail in each inverter manual.

| (S2•) Inverter Instruction code (hexadecimal) | Read contents | Applicable inverter | | | | | | | |
|---|------------------------------------|---|------|------|------|------|------|------|------|
| | | F700 | A700 | E700 | V500 | F500 | A500 | E500 | S500 |
| H7B | Operation mode | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H6F | Output frequency [speed] | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H70 | Output current | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H71 | Output voltage | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — |
| H72 | Special monitor | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — | — |
| H73 | Special monitor selection No. | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — | — |
| H74 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H75 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H76 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — |
| H77 | Alarm definition | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — |
| H79 | Inverter status monitor (extended) | ✓ | ✓ | ✓ | — | — | — | — | — |
| H7A | Inverter status monitor | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H6E | Set frequency read (EEPROM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H6D | Set frequency read (RAM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| H7F | Link parameter expansion setting | These codes cannot be specified in (S2•) of the IVCK instruction. They are automatically processed when a "second parameter specification code" is specified the IVRD instruction. | | | | | | | |
| H6C | Second parameter changing | | | | | | | | |

9.5 Inverter Operation Control Instruction (PLC→Inverter) [FNC271 / IVDR]

This instruction writes a control value required to operate an inverter from the PLC to the inverter.

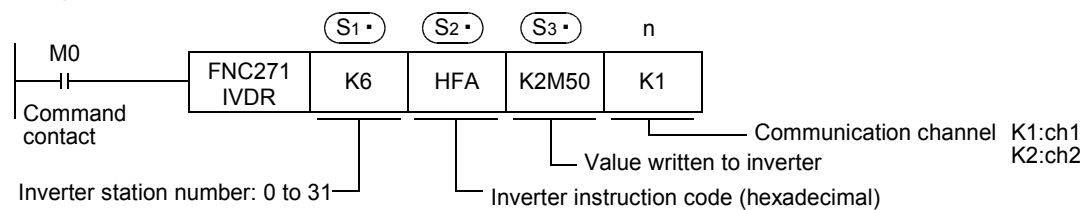
9.5.1 Function and operation

When an "instruction code" specified for computer link operation in the inverters is specified in the IVDR (FNC271) instruction, the value specified in (S3•) is written to the specified item of the inverter.

1. Applicable devices

| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | Others | | | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|---|-------|--------|---|---------------|---|----------------|-----------------------|---------|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | | Index | | | Con- stant | | Real Number | Charac- ter String | Pointer |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P | |
| (S1•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | |
| (S2•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | |
| (S3•) | | | | | | | | ✓ | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | |
| n | | | | | | | | | | | | | | | | | | | | ✓ | ✓ | | | | |

2. Program example



9.5.2 Inverter instruction codes

The table below shows inverter instruction codes which can be specified in (S2•).
For the instruction codes, refer to the pages explaining computer link in detail in each inverter manual.

| (S2•) Inverter Instruction code (hexadecimal) | Write contents | Applicable inverter | | | | | | | |
|---|-------------------------------|---------------------|------|------|------|------|------|------|------|
| | | F700 | A700 | E700 | V500 | F500 | A500 | E500 | S500 |
| HFB | Operation mode | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HF3 | Special monitor selection No. | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | — | — |
| HF9 | Run command (extension) | ✓ | ✓ | ✓ | — | — | — | — | — |
| HFA | Run command | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HEE | Set frequency write (EEPROM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HED | Set frequency write (RAM) | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HFD*1 | Inverter reset*2 | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HF4 | Alarm definition batch clear | ✓ | ✓ | ✓ | — | ✓ | ✓ | ✓ | ✓ |
| HFC | Parameter all clear | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| HFC | User clear | ✓ | ✓ | ✓ | — | ✓ | ✓ | — | — |

*1. The instruction code "HFD (inverter reset)" does not request a response from the inverter. Accordingly, even if inverter reset is executed to a station number at which an inverter is not connected, error does not occur.
It takes about 2.2 seconds to complete execution of inverter reset.

*2. When resetting the inverter, please specify H9696 as the operand (S3•) of the IVDR instruction.
Do not use H9966.

9.6 Inverter Parameter Reading (PLC←Inverter) [FNC272 / IVRD]

This instruction reads a parameter of an inverter to the PLC.

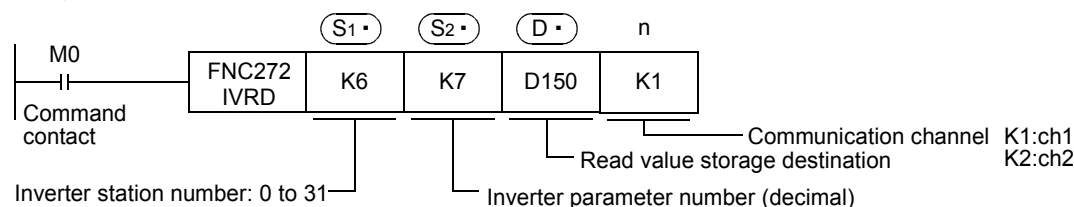
9.6.1 Function and operation

When a parameter number of an inverter is specified in IVRD (FNC272) instruction, the value of the parameter is read to (D•).

1. Applicable devices

| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | Others | | | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|---|-------|--------|---|---------------|---|----------------|-----------------------|---------|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | | Index | | | Con- stant | | Real Number | Charac- ter String | Pointer |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P | |
| (S1•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | |
| (S2•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | |
| (D•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | | | | | | |
| n | | | | | | | | | | | | | | | | | | | | ✓ | ✓ | | | | |

2. Program example



9.6.2 Inverter instruction codes

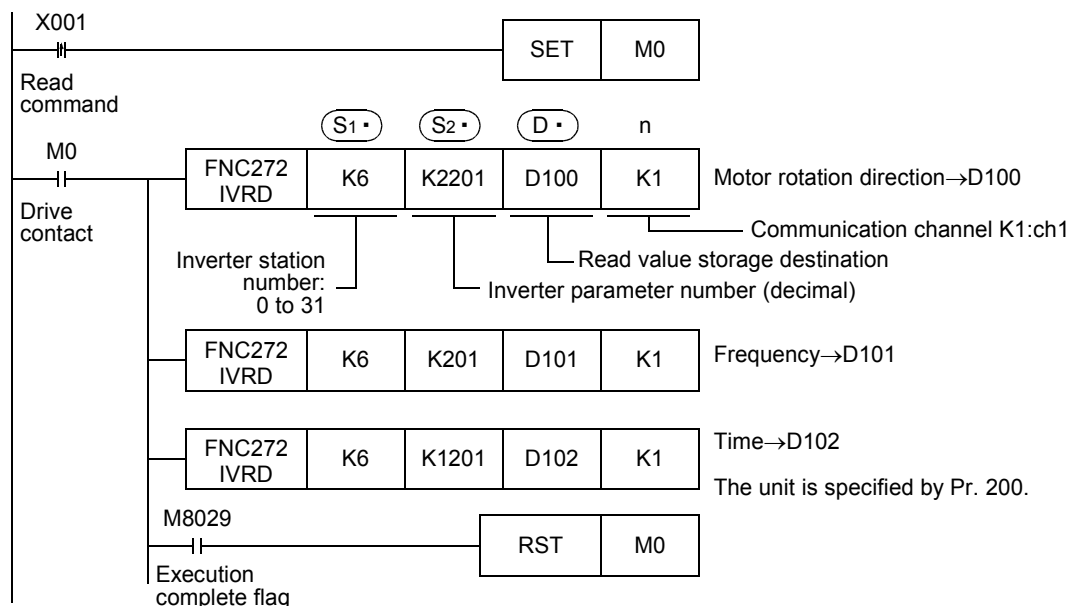
Refer to related data shown later.

9.6.3 Program example of "second parameter specification code"

→ For second parameter specification code, refer to Section 9.9.

In the program example shown below, the parameters (frequency: 201, time: 1201, motor rotation direction: 2201) are read from the A500 inverter whose station number is 6.

Read devices: D100 = Motor rotation direction, D101 = Frequency, D102 = Time



9.7 Inverter Parameter Writing (PLC→Inverter) [FNC273 / IVWR]

This instruction writes a value from the PLC to a parameter in an inverter.

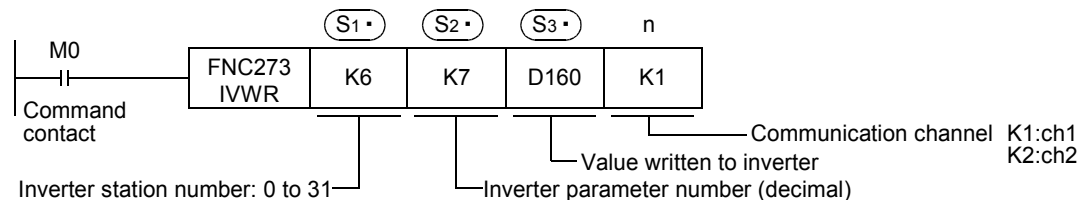
9.7.1 Function and operation

When a parameter number in an inverter is specified in IVWR (FNC273) instruction, the value of (S3•) is written to the specified item in the inverter.

1. Applicable devices

| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | | Others | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|---|-------|--------|---------------|---|----------------|-----------------------|---------|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | | Index | | Con- stant | | Real Number | Charac- ter String | Pointer |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P |
| (S1•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | |
| (S2•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | |
| (S3•) | | | | | | | | | | | | | | ✓ | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | |
| n | | | | | | | | | | | | | | | | | | | | ✓ | ✓ | | | |

2. Program example



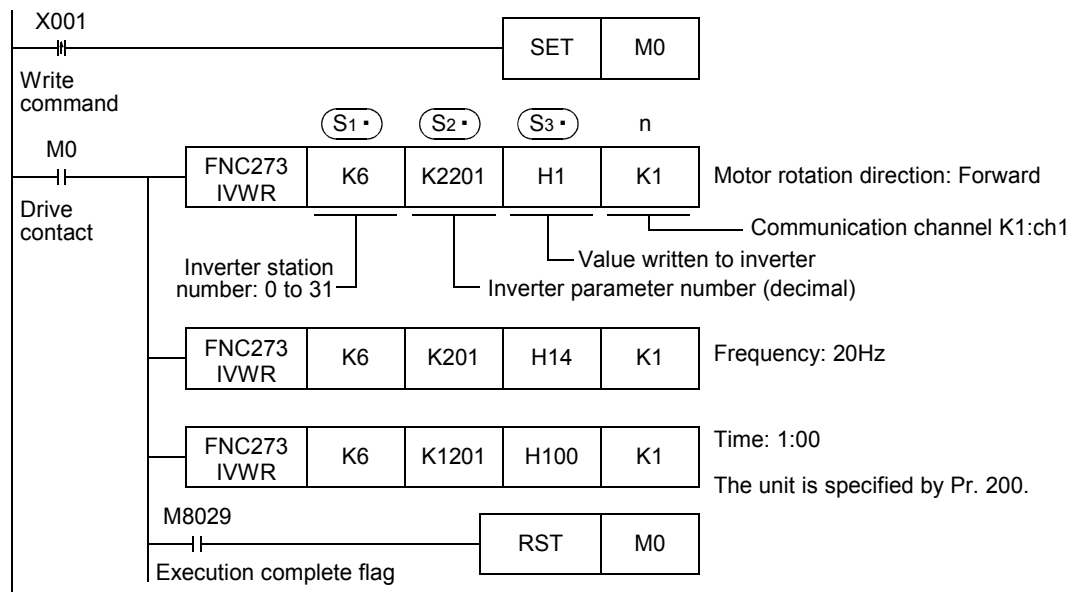
9.7.2 Inverter instruction codes

Refer to related data shown later.

9.7.3 Program example of "second parameter specification code"

→ For second parameter specification code, refer to Section 9.9.

In the program example shown below, data is written from the PLC to the parameters (frequency: 201, time: 1201, motor rotation direction: 2201) in the A500 inverter.



9.8 Inverter Parameter Batch Writing (PLC→Inverter) [FNC274 / IVBWR]

This instruction writes values from the PLC to parameters in an inverter all at once.

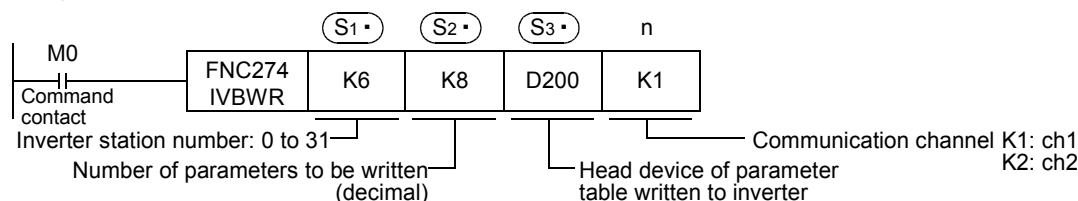
9.8.1 Function and operation

When a parameter number in an inverter is specified in the IVBWR (FNC274) instruction, the values of (S3•) and later are written to the specified items in the inverter all at once.

1. Applicable devices

| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | | Others | | | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|---|-------|--------|---------------|---|----------------|-----|-----------------------|--|---------|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | | Index | | Con- stant | | Real Number | | Charac- ter String | | Pointer |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P | | |
| (S1•) | | | | | | | | | | | | | | | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | | |
| (S2•) | | | | | | | | | | | | | | | ✓ | ✓ | | | ✓ | ✓ | ✓ | | | | | |
| (S3•) | | | | | | | | | | | | | | | ✓ | ✓ | | | ✓ | | | | | | | |
| n | | | | | | | | | | | | | | | | | | | | ✓ | ✓ | | | | | |

2. Program example



The following table shows values (two word devices/point) in a specified table which are written to a number of consecutive parameters specified in (S2•) starting from a word device specified in (S3•).

| | | |
|-----------|------|------------------------------|
| (S3•) | D200 | Parameter No. 1 |
| (S3•) +1 | D201 | Value 1 written to parameter |
| (S3•) +2 | D202 | Parameter No. 2 |
| (S3•) +3 | D203 | Value 2 written to parameter |
| ⋮ | ⋮ | ⋮ |
| (S3•) +14 | D214 | Parameter No. 8 |
| (S3•) +15 | D215 | Value 8 written to parameter |

(S2•) × 2 = Number of occupied word devices

9.9 Second Parameter Specification Codes

When handling the following parameters in computer link operation, it is necessary to select second parameters.

In IVRD, IVWR, and IVBWR instructions, when a value shown in the tables below is set in (S2) (S3) in IVBWR instruction), the extension parameter and second parameter are automatically overwritten, and parameter values are either read or written.

9.9.1 S500 Series

1. Second parameter specification codes for parameter numbers C2 to C7

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2) in IVRD/IVWR instruction for parameter number] |
|---------------|--|--|
| C2 | Frequency setting voltage bias frequency | 902 |
| C3 | Frequency setting voltage bias | 1902 |
| C4 | Frequency setting voltage gain | 903 |
| C5 | Frequency setting current bias frequency | 904 |
| C6 | Frequency setting current bias | 1904 |
| C7 | Frequency setting current gain | 905 |

9.9.2 E500 Series

1. Second parameter specification codes for parameter numbers 902 to 905

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2) in IVRD/IVWR instruction for parameter number] | | |
|---------------|--------------------------------|--|--------------|--------------------------------|
| | | Offset/Gain (H00) | Analog (H01) | Analog value of terminal (H02) |
| 902 | Frequency setting voltage bias | 902 | 1902 | 2902 |
| 903 | Frequency setting voltage gain | 903 | 1903 | 2903 |
| 904 | Frequency setting current bias | 904 | 1904 | 2904 |
| 905 | Frequency setting current gain | 905 | 1905 | 2905 |

9.9.3 A500 Series

1. Second parameter specification codes for parameter numbers 201 to 230 and 902 to 905

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2*) in IVRD/IVWR instruction for parameter number] | | |
|---------------|---------------|---|-----------------|-------------------------------|
| | | Operation frequency read/write | Time read/write | Rotation direction write/read |
| 201 | Program set 1 | 201 | 1201 | 2201 |
| 202 | Program set 1 | 202 | 1202 | 2202 |
| 203 | Program set 1 | 203 | 1203 | 2203 |
| 204 | Program set 1 | 204 | 1204 | 2204 |
| 205 | Program set 1 | 205 | 1205 | 2205 |
| 206 | Program set 1 | 206 | 1206 | 2206 |
| 207 | Program set 1 | 207 | 1207 | 2207 |
| 208 | Program set 1 | 208 | 1208 | 2208 |
| 209 | Program set 1 | 209 | 1209 | 2209 |
| 210 | Program set 1 | 210 | 1210 | 2210 |
| 211 | Program set 2 | 211 | 1211 | 2211 |
| 212 | Program set 2 | 212 | 1212 | 2212 |
| 213 | Program set 2 | 213 | 1213 | 2213 |
| 214 | Program set 2 | 214 | 1214 | 2214 |
| 215 | Program set 2 | 215 | 1215 | 2215 |
| 216 | Program set 2 | 216 | 1216 | 2216 |
| 217 | Program set 2 | 217 | 1217 | 2217 |
| 218 | Program set 2 | 218 | 1218 | 2218 |
| 219 | Program set 2 | 219 | 1219 | 2219 |
| 220 | Program set 2 | 220 | 1220 | 2220 |
| 221 | Program set 3 | 221 | 1221 | 2221 |
| 222 | Program set 3 | 222 | 1222 | 2222 |
| 223 | Program set 3 | 223 | 1223 | 2223 |
| 224 | Program set 3 | 224 | 1224 | 2224 |
| 225 | Program set 3 | 225 | 1225 | 2225 |
| 226 | Program set 3 | 226 | 1226 | 2226 |
| 227 | Program set 3 | 227 | 1227 | 2227 |
| 228 | Program set 3 | 228 | 1228 | 2228 |
| 229 | Program set 3 | 229 | 1229 | 2229 |
| 230 | Program set 3 | 230 | 1230 | 2230 |

2. Second parameter specification codes for parameter numbers 902 to 905

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2*) in IVRD/IVWR instruction for parameter number] | | |
|---------------|--------------------------------|---|--------------|--------------------------------|
| | | Offset/Gain (H00) | Analog (H01) | Analog value of terminal (H02) |
| 902 | Frequency setting voltage bias | 902 | 1902 | 2902 |
| 903 | Frequency setting voltage gain | 903 | 1903 | 2903 |
| 904 | Frequency setting current bias | 904 | 1904 | 2904 |
| 905 | Frequency setting current gain | 905 | 1905 | 2905 |

9.9.4 F500 Series

1. Second parameter specification codes for parameter numbers 902 to 905

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2•) in IVRD/ IVWR instruction for parameter number] | | |
|---------------|--------------------------------|---|-----------------|-----------------------------------|
| | | Offset/Gain (H00) | Analog (H01) | Analog value of terminal (H02) |
| 902 | Frequency setting voltage bias | 902 | 1902 | 2902 |
| 903 | Frequency setting voltage gain | 903 | 1903 | 2903 |
| 904 | Frequency setting current bias | 904 | 1904 | 2904 |
| 905 | Frequency setting current gain | 905 | 1905 | 2905 |

9.9.5 V500 Series

1. Second parameter specification codes for parameter numbers 902 to 905

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2•) in IVRD/ IVWR instruction for parameter number] | | |
|---------------|---|---|-----------------|-----------------------------------|
| | | Offset/Gain (H00) | Analog (H01) | Analog value of terminal (H02) |
| 902 | Speed setting No. 2 bias | 902 | 1902 | 2902 |
| 903 | Speed setting No. 2 gain | 903 | 1903 | 2903 |
| 904 | Torque command No. 3 bias | 904 | 1904 | 2904 |
| 905 | Torque command No. 3 gain | 905 | 1905 | 2905 |
| 917 | No.1 terminal bias (speed) | 917 | 1917 | 2917 |
| 918 | No.1 terminal gain (speed) | 918 | 1918 | 2918 |
| 919 | No.1 terminal bias (torque/magnetic flux) | 919 | 1919 | 2919 |
| 920 | No.1 terminal gain (torque/magnetic flux) | 920 | 1920 | 2920 |

9.9.6 F700 Series

1. Second parameter specification codes for parameter numbers 125, 126, and C2 to C7

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in (S2•) in IVRD/IVWR instruction for parameter number] |
|---------------|---|--|
| C2 | Terminal 2 frequency setting bias frequency | 902 |
| C3 | Terminal 2 frequency setting bias | 1902 |
| 125 | Terminal 2 frequency setting gain frequency | 903 |
| C4 | Terminal 2 frequency setting gain | 1903 |
| C5 | Terminal 4 frequency setting bias frequency | 904 |
| C6 | Terminal 4 frequency setting bias | 1904 |
| 126 | Terminal 4 frequency setting gain frequency | 905 |
| C7 | Terminal 4 frequency setting gain | 1905 |

9.9.7 A700 Series

1. Second parameter specification codes for parameter numbers 125, 126, C2 to C7, C12 to C19, and C38 to C41

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in $\text{S}_{2\bullet}$ in IVRD/IVWR instruction for parameter number] |
|---------------|---|--|
| C2 | Terminal 2 frequency setting bias frequency | 902 |
| C3 | Terminal 2 frequency setting bias | 1902 |
| 125 | Terminal 2 frequency setting gain frequency | 903 |
| C4 | Terminal 2 frequency setting gain | 1903 |
| C5 | Terminal 4 frequency setting bias frequency | 904 |
| C6 | Terminal 4 frequency setting bias | 1904 |
| 126 | Terminal 4 frequency setting gain frequency | 905 |
| C7 | Terminal 4 frequency setting gain | 1905 |
| C12 | Bias frequency (speed) for terminal No. 1 | 917 |
| C13 | Bias (speed) for terminal No. 1 | 1917 |
| C14 | Gain frequency (speed) for terminal No. 1 | 918 |
| C15 | Gain (speed) for terminal No. 1 | 1918 |
| C16 | Bias command (torque) for terminal No. 1 | 919 |
| C17 | Bias (torque) for terminal No. 1 | 1919 |
| C18 | Gain command (torque) for terminal No. 1 | 920 |
| C19 | Gain (torque) for terminal No. 1 | 1920 |
| C38 | Bias command (torque) for terminal No. 4 | 932 |
| C39 | Bias (torque) for terminal No. 4 | 1932 |
| C40 | Gain command (torque) for terminal No. 4 | 933 |
| C41 | Gain (torque) for terminal No. 4 | 1933 |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9.9.8 E700 Series

1. Second parameter specification codes for parameter numbers 125, 126, C2 to C7 and C22 to C25

| Parameter No. | Name | Second parameter specification code [(decimal) value to be specified in $\text{S}_{2\bullet}$ in IVRD/ IVWR instruction for parameter number] |
|---------------|---|---|
| C2 | Terminal 2 frequency setting bias frequency | 902 |
| C3 | Terminal 2 frequency setting bias | 1902 |
| | Terminal 2 analog value | 2902 (Only the IVRD instruction) |
| 125 | Terminal 2 frequency setting gain frequency | 903 |
| C4 | Terminal 2 frequency setting gain | 1903 |
| | Terminal 2 analog value | 2903 (Only the IVRD instruction) |
| C5 | Terminal 4 frequency setting bias frequency | 904 |
| C6 | Terminal 4 frequency setting bias | 1904 |
| | Terminal 4 analog value | 2904 (Only the IVRD instruction) |
| 126 | Terminal 4 frequency setting gain frequency | 905 |
| C7 | Terminal 4 frequency setting gain | 1905 |
| | Terminal 4 analog value | 2905 (Only the IVRD instruction) |
| C22 | Frequency setting voltage bias frequency (built-in potentiometer) | 922 |
| C23 | Frequency setting voltage bias (built-in potentiometer) | 1922 |
| C24 | Frequency setting voltage gain frequency (built-in potentiometer) | 923 |
| C25 | Frequency setting voltage gain (built-in potentiometer) | 1923 |

10. Practical Program Examples (for FX3U and FX3UC PLCs)

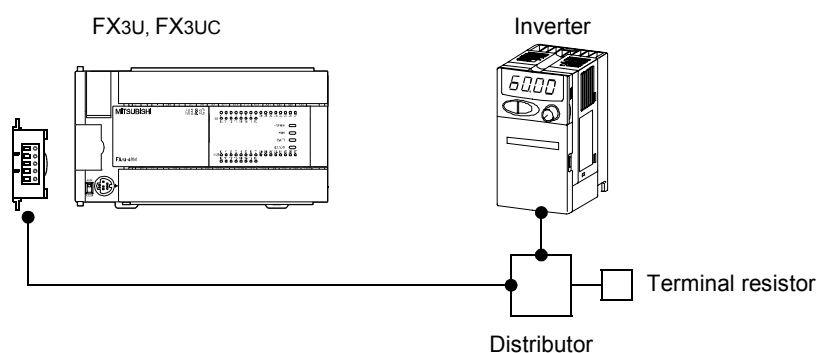
This chapter explains practical programs for inverter communication.

10.1 Practical Example 1

This fundamental program example monitors operations of an inverter, controls operations of an inverter and writes parameters to an inverter.

10.1.1 System configuration example

An FX PLC (ch 1) is connected to an inverter.



10.1.2 Contents of operation

As an example of operation control, an inverter can be stopped (X000), rotated forward (X001) and rotated reverse (X002).

By changing the contents of D10, the speed can be changed.

The contents of D10 can be changed from a sequence program or display unit.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

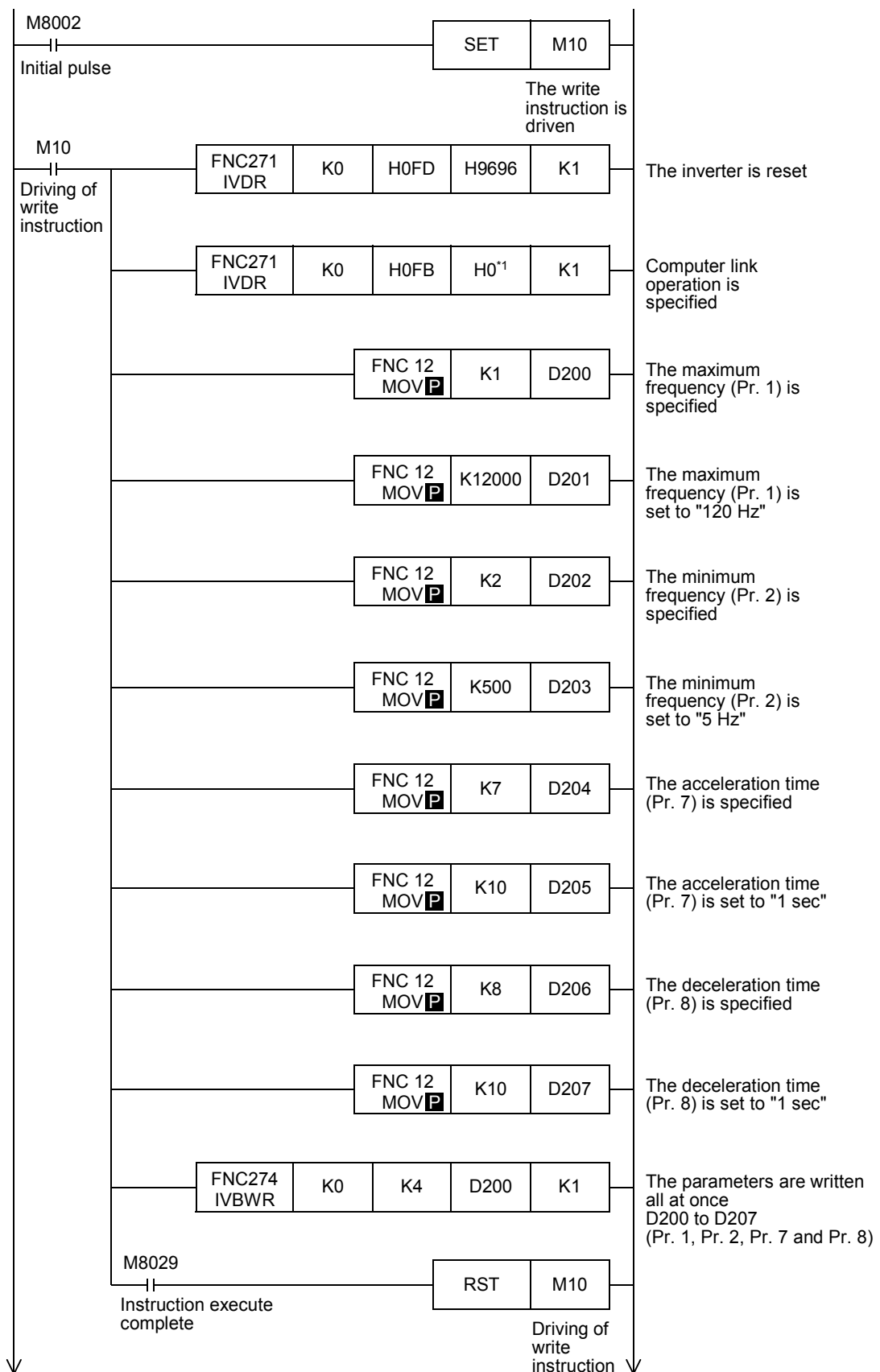
Remote Maintenance

Apx.

Discontinued models

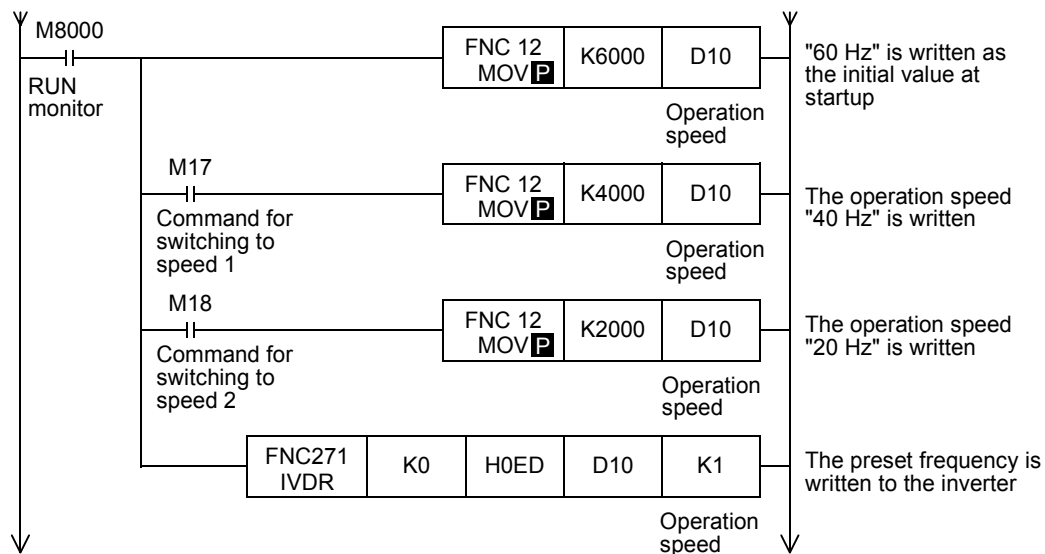
10.1.3 Program example

1. Writing parameters to an inverter while the PLC is in RUN mode

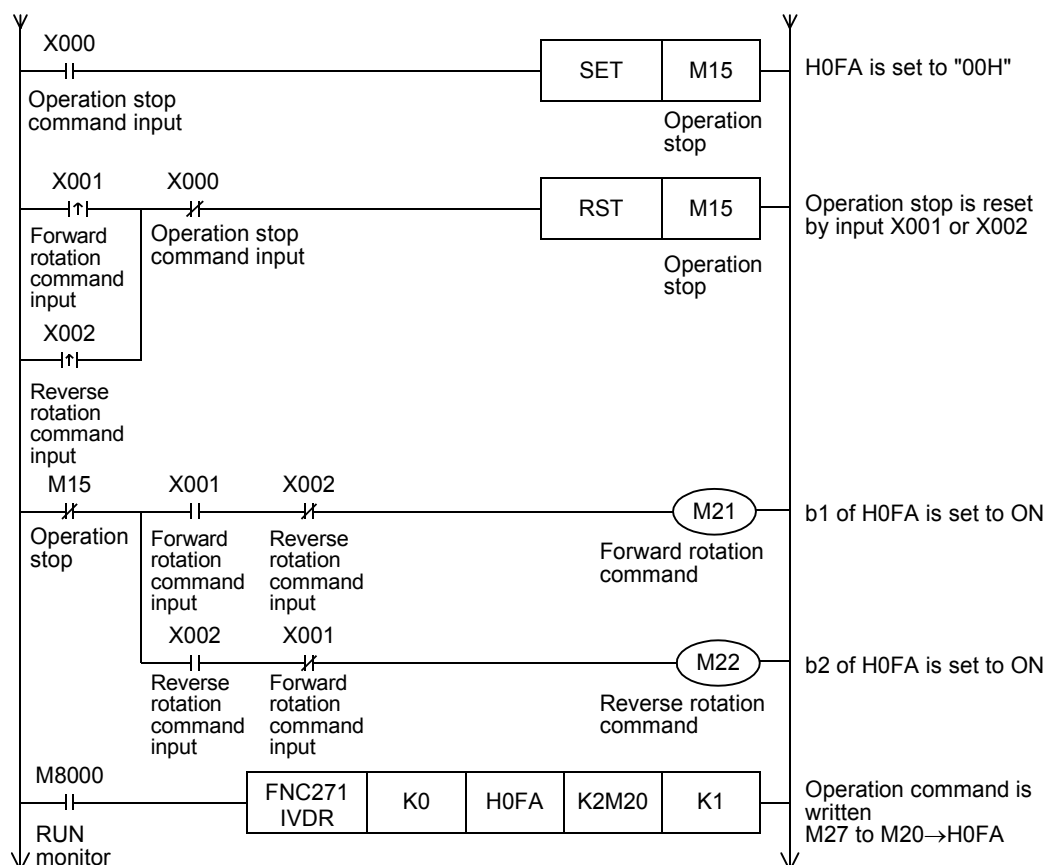


*1. When using an E500 Series inverter, use "H2" to specify computer link operation.

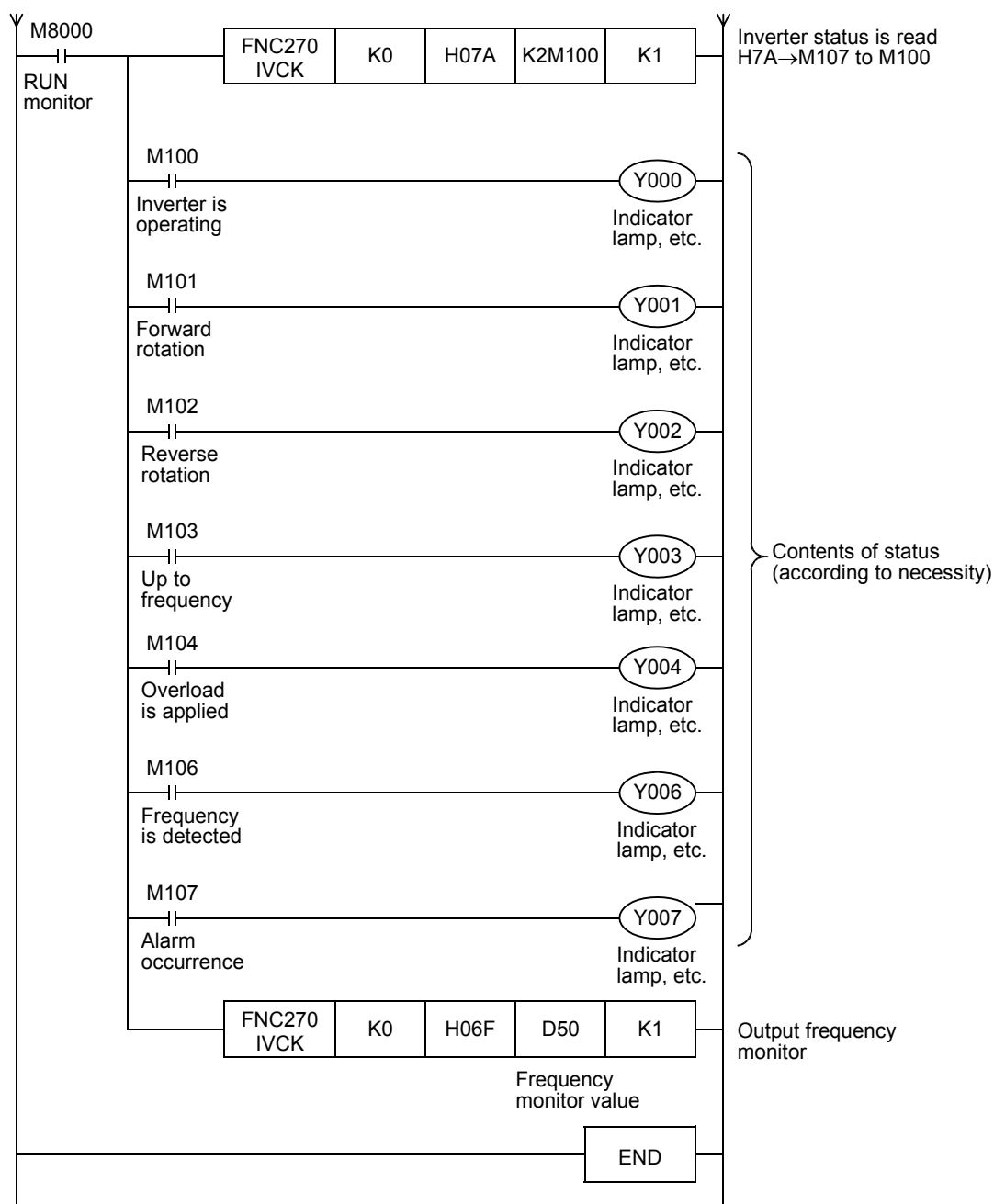
2. Changing the speed using a sequence program



3. Controlling operations of an inverter



4. Monitoring operations of an inverter

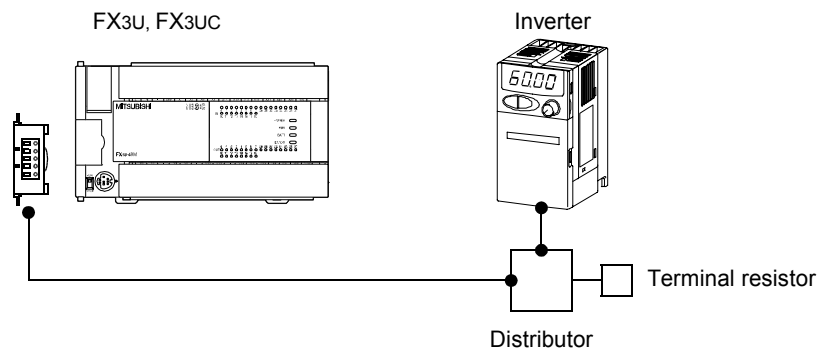


10.2 Practical Example 2

This program executes the same control as the practical example 1 shown above.

10.2.1 System configuration example

An FX PLC (ch 1) is connected to an inverter.



10.2.2 Contents of operation

The differences from practical example 1 are that the inverter status is not read while data is written to an inverter, and the contents to be written are written to an inverter only when change in the contents to be written are detected.

Because communication between the PLC and the inverter is minimum in this program, the communication time is reduced and the response time is improved.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

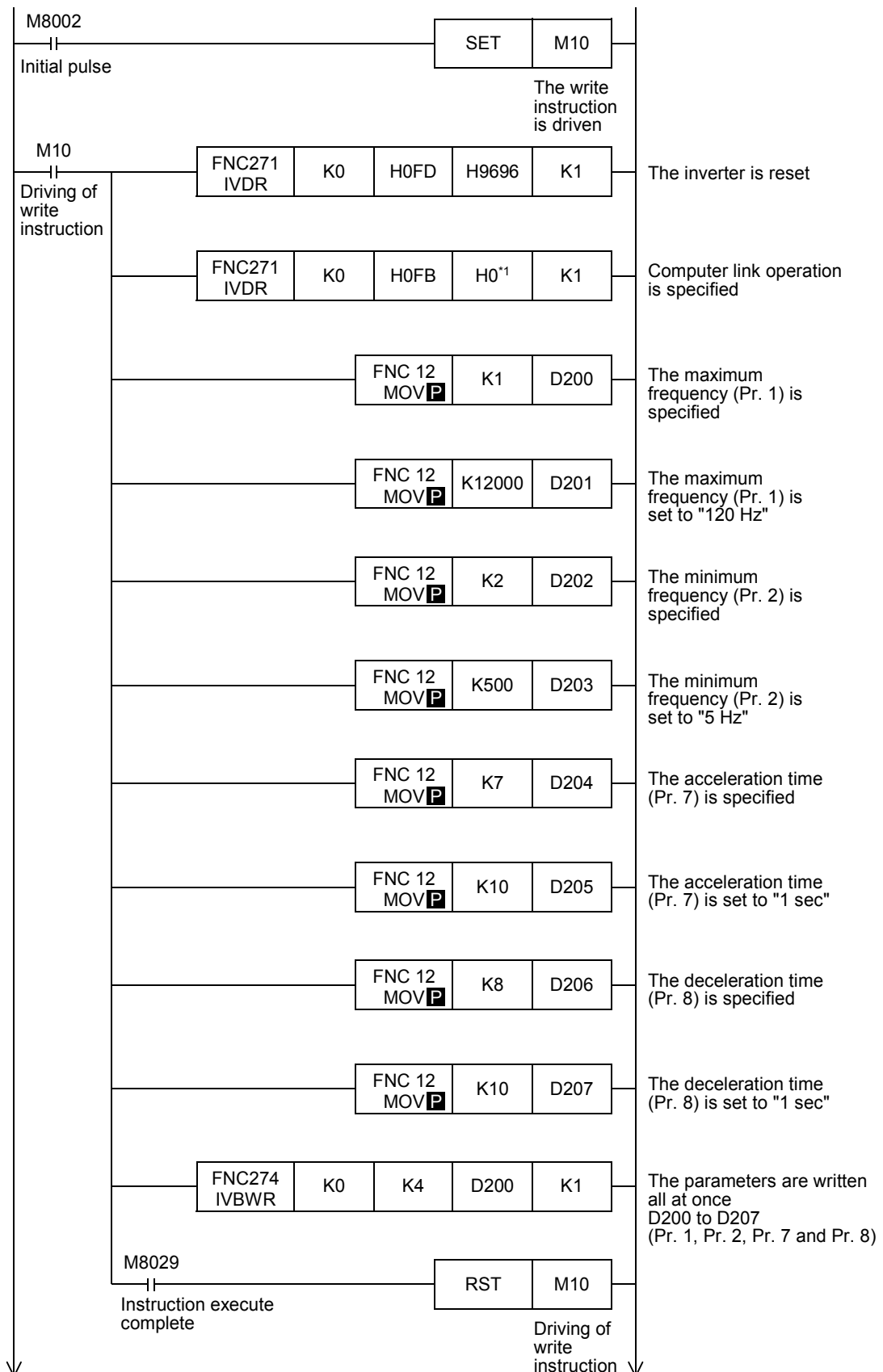
Remote Maintenance

Apx.

Discontinued models

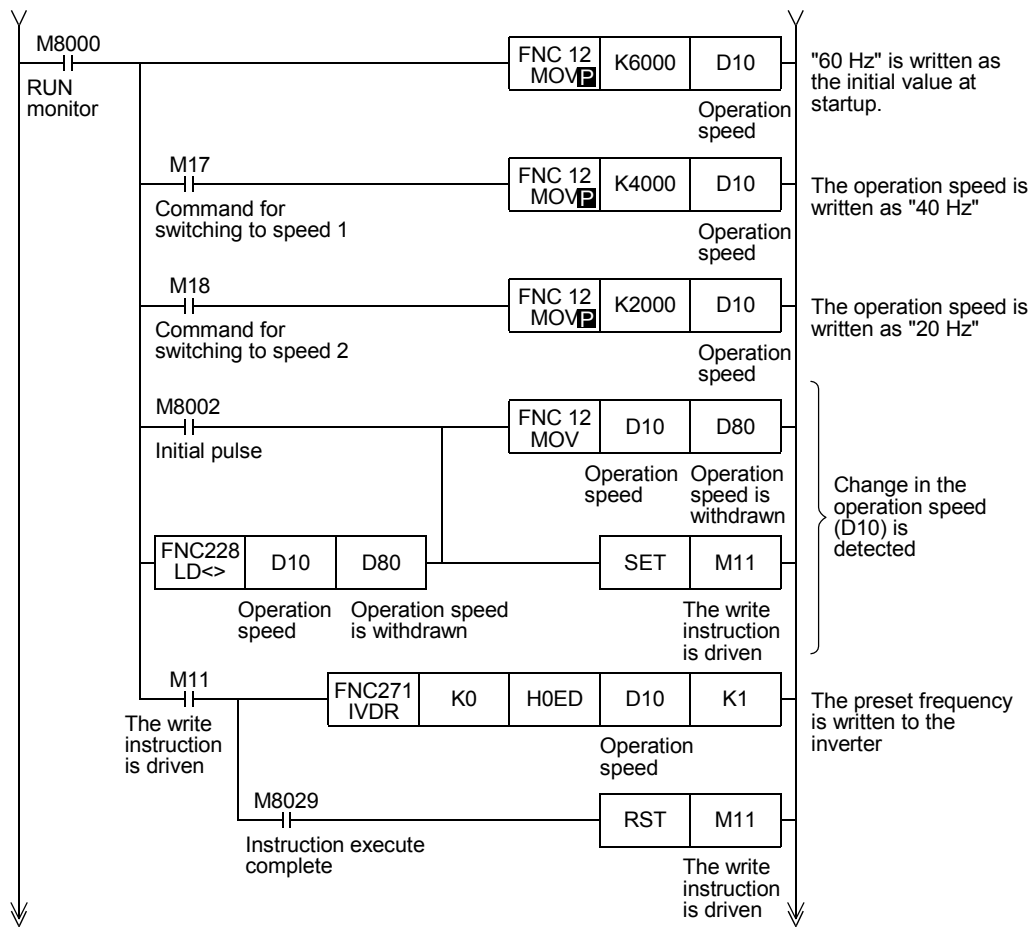
10.2.3 Program example

1. Writing parameters to an inverter while the PLC is in RUN mode



*1. When using an E500 Series inverter, use "H2" to specify computer link operation.

2. Changing the speed using a sequence program



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

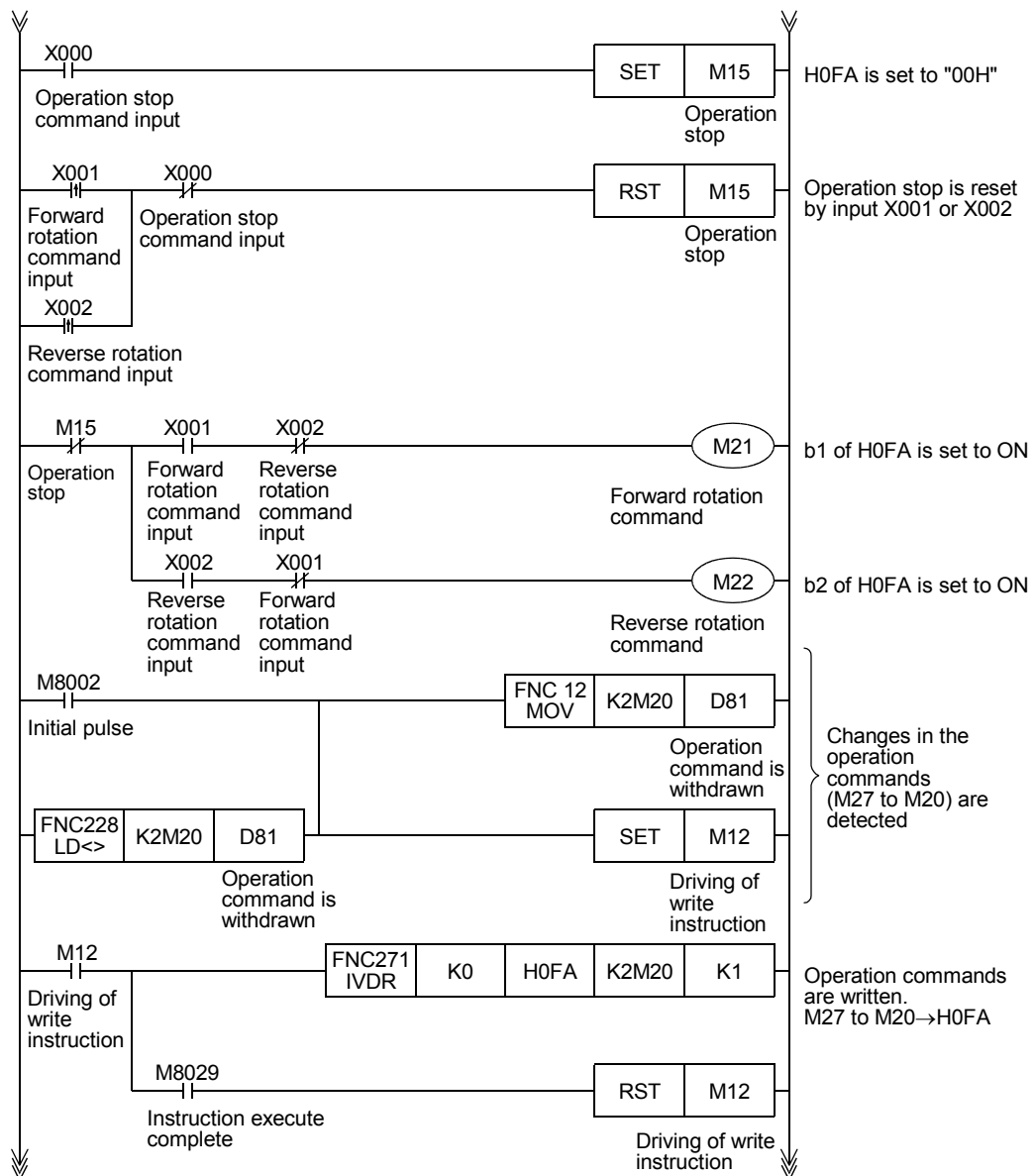
I

Remote Maintenance

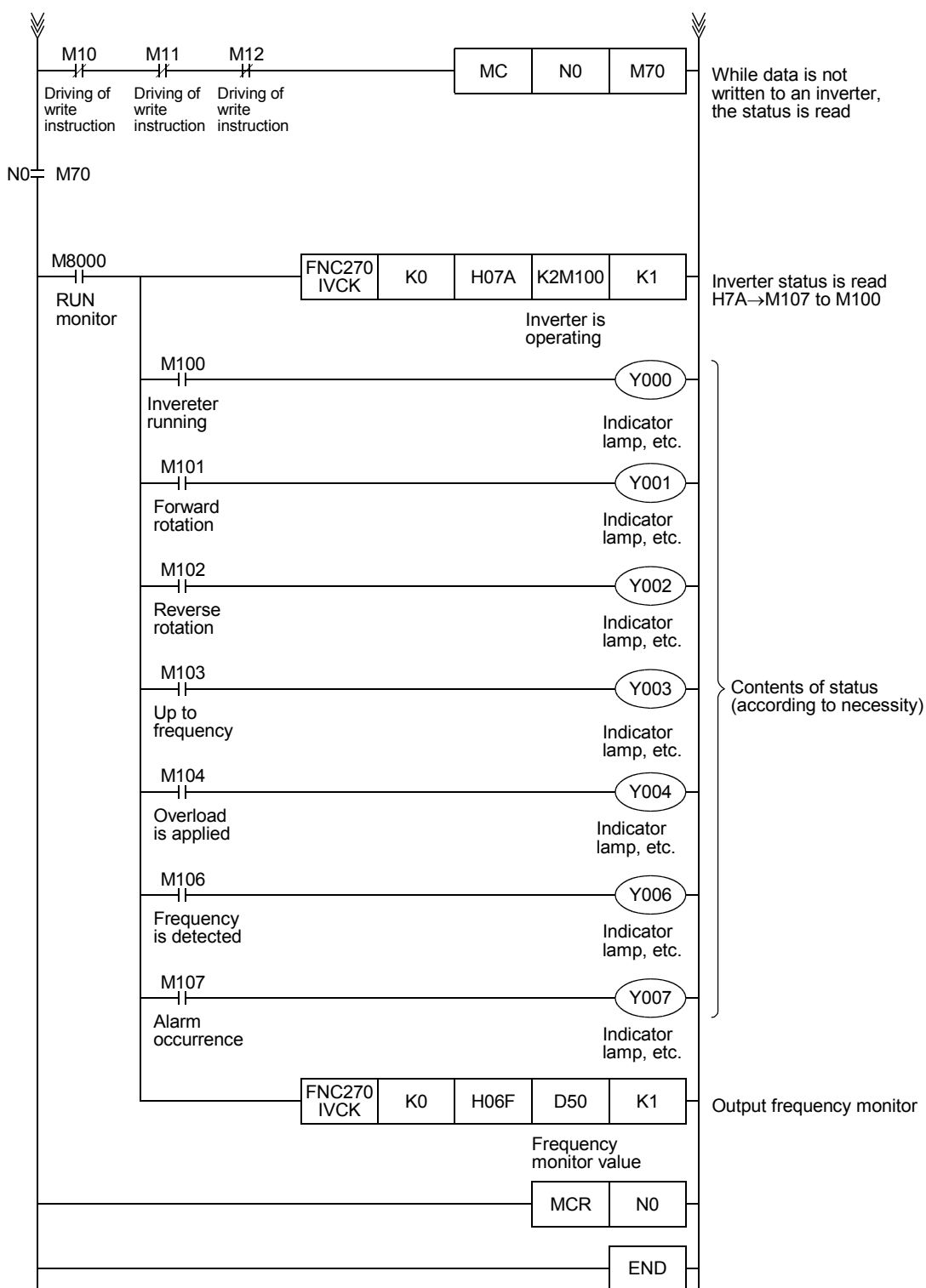
Apx.

Discontinued models

3. Controlling operations of an inverter



4. Monitoring operations of an inverter



11. Troubleshooting

This chapter explains troubleshooting and error codes.

11.1 Checking FX PLC Version Applicability (FX2N and FX2NC Series)

Verify that the FX PLC main unit is an applicable version for inverter communication.

→ **For version applicability, refer to Section 1.3.**

11.2 Checking Communication Status Based on LED Indication

Check the status of the "RD(RXD)" and "SD(TXD)" indicator LEDs provided in the optional equipment.

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RD | SD | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received |
| Off | Off | Data is not sent nor received. |

11.3 Checking Installation

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ **For mounting method, refer to the respective communication equipment manual.**

2. Power supply (for FX0N-485ADP)

The FX0N-485ADP requires a driving power supply. Verify that the power supply is provided correctly.

3. Wiring

Verify that the wiring to all communication equipment is correct. If the communication equipment is wired incorrectly, communication is not possible.

→ **For wiring method check, refer to Chapter 4.**

11.4 Checking Sequence Program

1. Communication setting in the sequence program

Verify that N:N Network (D8173 to D8180) and parallel link (M8070 and M8071) are not set.
After changing any setting, make sure to turn OFF the PLC power, and then turn it ON again.

2. Communication setting using parameters

Verify that the communication settings using parameters are correct. If the contents of the parameters do not agree, communication will not function correctly.
After changing any parameters, make sure to turn OFF the PLC power, and then turn it ON again.

3. Presence of VRRD and VRSC instructions (in FX2N and FX2NC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program.
If these instructions are used, delete them, turn OFF the PLC power, and then turn it ON again.

4. Presence of RS instruction (in FX2N and FX2NC PLCs)

Verify that the RS instruction is not used in the program.
If this instruction is used, delete it, turn OFF the PLC power, and then turn it ON again.

5. Presence of RS and RS2 instructions (in FX3U and FX3UC PLCs)

Verify that the RS and RS2 instructions are not being used for the same channel.
If these instructions are used for the same channel, delete them, turn OFF the PLC power, and then turn it ON again.

11.4.1 Checking inverter operation status

1. When the operation mode of an inverter is not changed over to computer link mode

- 1) Verify that the inverter is set to the external operation mode.
- 2) Verify that no signal is being input to the external terminals STF and STR.
- 3) Verify that the correct operation mode changeover program is being executed.

2. When an inverter cannot be started even in computer link mode

- 1) Verify that the program for starting the inverter is executed correctly.
- 2) Verify that the operation command and speed command are set correctly.
- 3) Verify that the allowable communication time interval is set correctly.

3. When an inverter is stopped by an alarm during operation due to defective communication

- 1) Verify that a communication cable is connected correctly between the PLC and the inverter.
(Check for poor contact or wire breakage.)
- 2) Verify that a sequence program is created so that communication is executed with each inverter within a constant cycle. Set the communication check time interval to a large value, and check the communication status.
- 3) Verify that the allowable communication time interval is set correctly.
- 4) Verify that terminal resistors are wired correctly.

11.5 Checking Absence/Presence of Errors

Verify that the error flag is not ON.

If the error flag is ON, check the error code and take proper countermeasures.

→ For error codes, refer to the next page.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

11.6 Error Codes

When a communication error occurs, the error flag turns ON, and the error code is stored in the data register. For error codes, refer to the table below.

1. Error storing devices

| FX Series | Error flag | Data register for storing error code | |
|------------|------------|--------------------------------------|-------|
| FX2N,FX2NC | M8156 | D8156 | |
| FX3U,FX3UC | ch1 | ch1 | ch2 |
| | M8152 | D8152 | D8157 |

2. Error code list

| Error code | Contents of error | | Inverter operation |
|------------|---|--|---|
| 0 | Normal end | (No Errors) | |
| 1 | — | Inverter did not give response. | |
| 2 | Timeout error | Sending from inverter was aborted midway. | |
| 3 | Station number error | Unspecified station gave response. | |
| 4 | Sum check error | The sum of data sent back by the inverter did not match. | |
| 5 | Parameter number specification error | In writing or reading a parameter, an improper parameter number was specified. At this time, error code (K6706) is set to D8067. K6706: Out-of-range data value for operand in applied instruction. | |
| 6 | Communication port occupied by another communication type | Because the port is being used for another communication type, it cannot be used for communication with the inverter. At this time, error code (K6762) is set to D8067. K6762: The port specified in inverter communication instruction is being used by another communication type. | When errors have occurred consecutively beyond the allowable number of retries, inverter is brought to an alarm stop. |
| 256 | Computer NAK error | Inverter sent the error code H0. The number of retries exceeded the allowable number because of an error in the transfer request data. | |
| 257 | Parity error | Inverter sent the error code H1. The contents are different from the specified parity. | |
| 258 | Sum check error | Inverter sent the error code H2. The sum check code in the computer is different from the sum value calculated from the data received by the inverter. | |
| 259 | Protocol error | Inverter sent the error code H3. Syntax error is included in the data received by the inverter, receiving of data was not completed within the specified time, or CR/LF does not agree with the parameters. | |
| 260 | Framing error | Inverter sent the error code H4. The stop bit length is different from the initial set value. | |
| 261 | Overrun error | Inverter sent the error code H5. Before receiving the completed data in the inverter, the computer sent the next set of data. | |
| 262 | Undefined | Inverter sent the error code H6. Not defined currently in inverter. | Inverter does not accept received data, but is not brought to an alarm stop. |
| 263 | Character error | Inverter sent the error code H7. An unused character (other than 0 to 9, A to F and control codes) was received. | |
| 264 | Undefined | Inverter sent the error code H8. Not defined currently in inverter. | |
| 265 | Undefined | Inverter sent the error code H9. Not defined currently in inverter. | |

| Error code | Contents of error | | Inverter operation |
|------------|------------------------|---|--|
| 266 | Mode error | Inverter sent the error code HA. A parameter was written in a mode other than computer link mode, or while the inverter was operating. | Inverter does not accept received data, but is not brought to an alarm stop. |
| 267 | Instruction code error | Inverter sent the error code HB. Non-existing instruction code was specified. | |
| 268 | Data range error | Inverter sent the error code HC. In writing a parameter or operation frequency, data outside the allowable range was specified. | |
| 269 | Undefined | Inverter sent the error code HD. Not defined currently in inverter. | |
| 270 | Undefined | Inverter sent the error code HE. Not defined currently in inverter. | |
| 271 | Undefined | Inverter sent the error code HF. Not defined currently in inverter. | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

12. Related Data

This chapter shows various technical information.

12.1 Related Device List for FX2N and FX2NC PLCs

The tables below show special auxiliary relays and special data registers used in inverter communication (EXTR K10 to EXTR K13).

1. Bit devices

| Device No. | Name | Description | R/W |
|------------|---|--|-----|
| M8029 | Instruction execution complete | Turns ON when execution of EXTR instruction is completed, and remains ON for 1 scan. Turns ON also when execution of instruction is completed if M8156 (communication error or parameter error) turns ON. | R |
| M8104 | Extension ROM cassette check | Remains ON while an extension ROM cassette is attached. | R |
| M8154 | Unused | — | R |
| M8155 | Communication port busy | Remains ON while the communication port is used by an EXTR instruction. | R |
| M8156 | Communication error or parameter error | Turns ON when a communication error is caused by an EXTR instruction. | R |
| M8157 | Communication error latch ^{*1} | Turns ON when a communication error is caused by an EXTR instruction. | R |

R: Read only (used as a contact in program)

*1. Cleared when the PLC mode is changed from STOP to RUN.

2. Word devices

| Device No. | Name | Description | R/W |
|------------|---|--|-----|
| D8104 | Extension ROM cassette type code | Stores the type code of an extension ROM cassette (value: K1). | R |
| D8105 | Extension ROM cassette version | Stores the version of an extension ROM cassette (value: K100 = Ver. 1.00). | R |
| D8154 | Inverter response waiting time | Sets the inverter response waiting time. | R/W |
| D8155 | Step number of instruction using the communication port | Stores the step number of EXTR instruction using the communication port. | R |
| D8156 | Error code ^{*1} | Stores an error code when a communication error is caused by an EXTR instruction. | R |
| D8157 | Error occurrence step number latch ^{*1} | Stores the instruction step number in which a communication error has occurred. (Stores K-1 when no error has occurred.) | R |

R: Read only

R/W: Read or Write

*1. Cleared when the PLC mode is changed from STOP to RUN.

12.2 Details of Related Devices for FX2N and FX2NC PLCs

The following devices are special devices used in inverter communication.

12.2.1 Instruction execution complete [M8029]

When execution of an inverter communication instruction is completed, this device turns ON.

1. Detailed contents

When execution of an inverter communication instruction is completed, M8029 turns ON, and remains ON for 1 scan.

When an error occurs in an inverter communication instruction, M8029 turns ON.

2. Cautions on use

M8029 is used as the execution complete flag for other instructions (such as positioning instructions).

When using M8029, provide the contact just under the instruction whose execution completion is to be checked.

12.2.2 Extension ROM cassette check [M8104]

This device remains ON while an extension ROM cassette is attached.

1. Detailed contents

M8104 remains ON while an extension ROM cassette is attached.

- FX2N FX2N-ROM-E1
- FX2NC FX2NC-ROM-CE1

2. Cautions on use

While M8104 is OFF, EXTR instructions cannot be used.

12.2.3 Communication port busy [M8155]

This device remains ON while the communication port is being used by an EXTR instruction.

1. Detailed contents

M8155 remains ON while communication with an inverter is executed by an EXTR instruction.

When M8155 turns ON, D8155 stores the step number of an instruction using the communication port.

While M8155 is ON, another EXTR instruction cannot be executed.

12.2.4 Communication error or parameter error [M8156]

This device turns ON when an error is caused in communication with an inverter by an EXTR instruction.

1. Detailed contents

M8156 turns ON when an error is caused in communication with an inverter by an EXTR instruction.

When M8156 turns ON, D8156 stores the error code.

2. Cautions on use

M8156 is set to OFF by an EXTR instruction located in the next step in the program.

When using M8156, provide it just under the EXTR instruction whose error is to be checked.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (FSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

12.2.5 Communication error latch [M8157]

This device turns ON when the communication error flag M8156 turns ON.

1. Detailed contents

M8157 turns ON when a communication error occurs and M8156 turns ON.
When M8157 turns ON, D8157 stores the step number in which the error has occurred.

2. Cautions on use

M8157 remains ON until the PLC mode is changed from STOP to RUN.

12.2.6 Extension ROM cassette type code [D8104]

This device stores the type code of an extension ROM cassette.

1. Detailed contents

While the following ROM is attached to an FX PLC, D8104 stores its model code.

- FX2N FX2N-ROM-E1 (model code: K1)
- FX2NC FX2NC-ROM-CE1 (model code: K1)

12.2.7 Extension ROM cassette version [D8105]

This device stores the version of an extension ROM cassette.

1. Detailed contents

While an extension ROM is attached, D8105 stores its version information (K100 = Ver. 1.00).

12.2.8 Inverter response waiting time [D8154]

This device sets the response waiting time of an inverter.

1. Detailed contents

D8154 sets the response waiting time of an inverter.
Set a value within the range from "1 to 32767" (unit: 100 ms) to D8154.
When "0" or a negative value is set, it is handled as "100 ms".

12.2.9 Step number of instruction using communication port [D8155]

This device stores the step number of an instruction occupying the communication port.

1. Detailed contents

D8155 stores the step number of EXTR instruction using the communication port.

12.2.10 Error code [D8156]

This device stores the error code when an error is caused in communication with an inverter by an EXTR instruction.

1. Detailed contents

D8156 stores one of the following error codes when an error is caused in communication with an inverter by the EXTR instruction.

| Error code | Contents of error | Inverter operation |
|------------|---|---|
| 0 | Normal end (no error) | |
| 1 | Inverter did not give response. | |
| 2 | Timeout error. This code interlocks with M8156. Sending from inverter was aborted midway through. | |
| 3 | An unspecified station gave response. | |
| 4 | The sum of data sent back by the inverter did not match. | |
| 5 | In writing or reading a parameter, an improper parameter number was specified. At this time, the error code K6702 is set to D8067. | |
| 6 | Because the port is being used for another communication, it cannot be used for communication with the inverter. At this time, the error code K6762 is set to D8067. | |
| 256 | Inverter sent the error code H0. Computer NAK error. An error was included in the transfer request data from the computer beyond the allowable number of retries. | When errors have occurred consecutively beyond the allowable number of retries, inverter is brought to an alarm stop. |
| 257 | Inverter sent the error code H1. Parity error. The contents are different from the specified parity. | |
| 258 | Inverter sent the error code H2. Sum check error. The sum check code in the computer is different from the sum value calculated from the data received by inverter. | |
| 259 | Inverter sent the error code H3. Protocol error. Syntax error is included in the data received by the inverter, and the receiving of data has not been completed within the specified time, or CR/LF does not agree with the parameters. | |
| 260 | Inverter sent the error code H4. Framing error. The stop bit length is different from the initial set value. | |
| 261 | Inverter sent the error code H5. Overrun error. Before receiving the completed data in the inverter, the computer sent the next set of data. | |
| 262 | Inverter sent the error code H6. Not defined currently in inverter. | |
| 263 | Inverter sent the error code H7. Character error. An unused character (other than 0 to 9, A to F and control codes) was received. | Inverter does not accept the received data, but is not brought to an alarm stop. |
| 264 | Inverter sent the error code H8. Not defined currently in inverter. | |
| 265 | Inverter sent the error code H9. Not defined currently in inverter. | |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RSRS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

| Error code | Contents of error | Inverter operation |
|------------|---|--|
| 266 | Inverter sent the error code HA. Mode error. A parameter was written in a mode other than computer link mode, or while inverter was operating. Inverter does not accept the received data, but is not stopped by alarm. | Inverter does not accept the received data, but is not brought to an alarm stop. |
| 267 | Inverter sent the error code HB. Instruction code error. Non-existing instruction code was specified. | |
| 268 | Inverter sent the error code HC. Data range error. In writing a parameter or operation frequency, data outside the allowable range was specified. Inverter does not accept the received data, but is not stopped by alarm. | |
| 269 | Inverter sent the error code HD. Not defined currently in inverter. | |
| 270 | Inverter sent the error code HE. Not defined currently in inverter. | |
| 271 | Inverter sent the error code HF. Not defined currently in inverter. | |

12.2.11 Error occurrence step number latch [D8157]

This device stores the step number in which the communication error has occurred.

1. Detailed contents

When M8157 turns ON, D8157 stores the step number in which communication error has occurred.

When errors have occurred in two or more instructions, D8157 holds the step number of the instruction in which an error occurred first.

When no error has occurred, D8157 stores "-1".

12.3 Related Device List for FX3U and FX3UC PLCs

The tables below show special auxiliary relays and special data registers used in inverter communication (FNC270 (IVCK) to FNC274 (IVBWR)).

1. Bit devices

| Device No. | | Name | Description | R/W |
|------------|-------|--|--|-----|
| ch1 | ch2 | | | |
| M8029 | | Instruction execution complete | Turns ON when the execution of inverter communication instruction is completed, and remains ON for 1 scan. Turns ON also when the execution of instruction is completed if inverter communication error flag (M8152 or M8157) turns ON. | R |
| M8063 | M8438 | Serial communication error ^{*1} | Turns ON when an error occurs in any type of communication. | R |
| M8151 | M8156 | Inverter communicating | Remains ON while inverter communication is being executed. | R |
| M8152 | M8157 | Inverter communication error ^{*1} | Turns ON when an error occurs during communication with an inverter. | R |
| M8153 | M8158 | Inverter communication error latch ^{*1} | Turns ON when an error occurs during communication with an inverter. | R |
| M8154 | M8159 | IVBWR instruction error ^{*1} | Turns ON when an error is caused by IVBWR instruction. | R |

R: Read only (used as a contact in program)

^{*1}. Cleared when the PLC mode is changed from STOP to RUN.

2. Word devices

| Device No. | | Name | Description | R/W |
|------------|-------|---|--|-----|
| ch1 | ch2 | | | |
| D8063 | D8438 | Error code for serial communication ^{*1} | Stores a communication error code. | R |
| D8150 | D8155 | Inverter communication response waiting time | Sets the response waiting time for inverter communication. | R/W |
| D8151 | D8156 | Step number of instruction executing inverter communication | Stores the step number of an instruction executing inverter communication. | R |
| D8152 | D8157 | Error code for inverter communication ^{*1} | Stores an inverter communication error code. ^{*2} | R |
| D8153 | D8158 | Inverter communication error occurring step latch ^{*1} | Latches a step number in which an inverter communication error has occurred. ^{*2} | R |
| D8154 | D8159 | Error parameter number of IVBWR instruction ^{*1} | Stores a parameter number in which an IVBWR instruction error has occurred. | R |

R: Read only

R/W: Read or Write

^{*1}. Cleared when the PLC mode is changed from STOP to RUN.

^{*2}. Updated only for the first error occurrence, and not for the second error occurrence or later.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/R52 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

12.4 Details of Related Devices for FX3U and FX3UC PLCs

The following devices are special devices used in inverter communications.

12.4.1 Instruction execution complete [M8029]

When execution of an inverter communication instruction is completed, this device turns ON.

1. Detailed contents

When execution of an inverter communication instruction is completed, M8029 turns ON, and remains ON for 1 scan.

When an error occurs in an inverter communication instruction, M8029 turns ON, and remains ON for 1 scan in the same way.

2. Cautions on use

M8029 is used as the execution complete flag for other instructions (such as positioning instructions).

When using M8029, provide the contact just under the instruction whose execution completion is to be checked.

12.4.2 Serial communication error [M8063 and M8438]

These devices turn ON when an error occurs during communication with an inverter.

1. Detailed contents

M8063 or M8438 turns ON when a parity error, overrun error or framing error occurs during communication with inverters or when an inverter communication error occurs.

M8063 turns ON when an error occurs during communication using ch1. When M8063 turns ON, D8063 stores the error code.

M8438 turns ON when an error occurs during communication using ch2. When M8438 turns ON, D8438 stores the error code.

2. Cautions on use

M8063 and M8438 do not turn OFF even if the communication recovers its normal status. Clear them by switching the PLC mode from STOP to RUN.

12.4.3 Inverter communication ON [M8151 and M8156]

These devices remain ON while the communication port is used by an inverter communication instruction.

1. Detailed contents

M8151 or M8156 remains ON while communication with an inverter is executed by an inverter communication instruction.

M8151 remains ON while communication port ch1 is used. While M8151 remains ON, D8151 stores the step number of an instruction using the communication port.

M8156 remains ON while communication port ch2 is used. While M8156 remains ON, D8156 stores the step number of an instruction using the communication port.

2. Cautions on use

While M8151 or M8156 remains ON, another inverter communication instruction cannot be executed.

12.4.4 Inverter communication error [M8152, M8153, M8157 and M8158]

These devices turn ON when an error occurs in an inverter communication instruction.

1. Detailed contents

M8152 or M8157 turn ON when an error occurs in an inverter communication instruction.

M8152 turn ON when an error occurs during communication using communication port ch1. When M8152 turn ON, D8152 stores the error code and D8153 stores the error step number.(M8153 is an error latch.)

M8157 turn ON when an error occurs during communication using communication port ch2. When M8157 turn ON, D8157 stores the error code and D8158 stores the error step number.(M8158 is an error latch.)

To D8152, D8153, D8157 and D8158 are updated only for the first error occurrence, and not for the second error occurrence or later.

2. Cautions on use

M8152 and M8157 do not turn OFF even if the communication recovers its normal status. Clear them by switching the PLC mode from STOP to RUN.

12.4.5 IVBWR instruction error [M8154 and M8159]

These devices turn ON when an error occurs in IVBWR instruction.

1. Detailed contents

M8154 or M8159 turns ON when a parameter number of set value specified in IVBWR instruction is outside the allowable range.

M8154 turns ON when an error occurs in IVBWR instruction using communication port ch1. When M8154 turns ON, D8154 stores the rejected parameter number.

M8159 turns ON when an error occurs in IVBWR instruction using the communication port ch2. When M8159 turns ON, D8159 stores the rejected parameter number.

2. Cautions on use

M8154 and M8159 do not turn OFF even if the communication recovers its normal status. Clear them by switching the PLC mode from STOP to RUN.

12.4.6 Serial communication error code [D8063 and D8438]

These devices store the error code when the serial communication error flag turns ON.

1. Detailed contents

When an error occurs in an inverter communication instruction, D8063 or D8438 stores one of the following error codes.

| Error code | | Contents |
|------------|-------|--|
| ch1 | ch2 | |
| D8063 | D8438 | |
| 6301 | 3801 | Parity error, framing error or overrun error |
| 6320 | 3820 | Inverter communication error |

2. Cautions on use

D8063 and D8438 do not turn OFF even if the communication recovers its normal status. Clear them by switching the PLC mode from STOP to RUN.

12.4.7 Inverter response waiting time [D8150 and D8155]

These devices set the response waiting time of the inverter.

1. Detailed contents

Set the response waiting time of an inverter.

When using communication port ch1, set a value to D8150.

When using communication port ch2, set a value to D8155.

Set a value within the range from "1 to 32767" (unit: 100 ms).

If "0" or negative value is set, it is handled as "100 ms".

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

12.4.8 Step number of instruction using communication port [D8151 and D8156]

These devices store the step number of the instruction occupying the communication port.

1. Detailed contents.

D8151 or D8156 stores the step number of the inverter communication instruction using the communication port.

D8151 stores the step number using communication port ch1.

D8156 stores the step number using communication port ch2.

2. Cautions on use

A decimal value without sign is stored as the step number in D8151 and D8156.

12.4.9 Inverter communication error code [D8152 and D8157]

These devices store an error code when a communication error is caused by an inverter communication instruction.

1. Detailed contents

Special data registers shown below respectively store inverter communication errors, depending on each communication port.

- D8152 stores the error code of an error in communication using communication port ch1.
- D8157 stores the error code of an error in communication using communication port ch2.

2. Error codes

The following error codes are stored.

| Error code | Contents of error | Inverter operation |
|------------|---|---|
| 0 | Normal end (no error) | |
| 1 | Inverter did not give response. | |
| 2 | Timeout error. This code interlocks with M8156. Sending from inverter was aborted midway through. | |
| 3 | An unspecified station gave response. | |
| 4 | The sum of data sent back by the inverter did not match. | |
| 5 | In writing or reading a parameter, an improper parameter number was specified. At this time, the error code K6702 is set to D8067. | |
| 6 | Because the port is being used for another communication type, it cannot be used for communication with the inverter. At this time, the error code K6762 is set to D8067. | When errors have occurred consecutively beyond the allowable number of retries, inverter is brought to an alarm stop. |
| 256 | Inverter sent the error code H0. Computer NAK error. An error was included in the transfer request data from the computer beyond the allowable number of retries. | |
| 257 | Inverter sent the error code H1. Parity error. The contents are different from the specified parity. | |
| 258 | Inverter sent the error code H2. Sum check error. The sum check code in the computer is different from the sum value calculated from the data received by the inverter. | |
| 259 | Inverter sent the error code H3. Protocol error. Syntax error is included in the data received by the inverter, and the receiving of data was not completed within the specified time, or CR/LF does not agree with the parameters. | |
| 260 | Inverter sent the error code H4. Framing error. The stop bit length is different from the initial set value. | |
| 261 | Inverter sent the error code H5. Overrun error. Before receiving the completed data in the inverter, the computer sent the next set of data. | |
| 262 | Inverter sent the error code H6. Not defined currently in inverter. | |

| Error code | Contents of error | Inverter operation |
|------------|---|--|
| 263 | Inverter sent the error code H7. Character error. An unused character (other than 0 to 9, A to F and control codes) is received. | Inverter does not accept the received data, but is not brought to an alarm stop. |
| 264 | Inverter sent the error code H8. Not defined currently in inverter. | |
| 265 | Inverter sent the error code H9. Not defined currently in inverter. | |
| 266 | Inverter sent the error code HA. Mode error. A parameter was written in a mode other than computer link mode or while inverter was operating. Inverter does not accept the received data, but is not stopped by alarm. | Inverter does not accept the received data, but is not brought to an alarm stop. |
| 267 | Inverter sent the error code HB. Instruction code error. Non-existing instruction code was specified. | |
| 268 | Inverter sent the error code HC. Data range error. In writing a parameter or operation frequency, data outside the allowable range was specified. Inverter does not accept the received data, but is not stopped by alarm. | |
| 269 | Inverter sent the error code HD. Not defined currently in inverter. | |
| 270 | Inverter sent the error code HE. Not defined currently in inverter. | |
| 271 | Inverter sent the error code HF. Not defined currently in inverter. | |

12.4.10 Inverter communication error occurrence step [D8153 and D8158]

These devices store the step number in which an inverter communication error has occurred.

1. Detailed contents

D8153 or D8158 stores the step number of the instruction causing an inverter communication error.

D8153 stores the step number in which an error has occurred in communication using communication port ch1.

D8158 stores the step number in which an error has occurred in communication using communication port ch2.

When errors that occurred in two or more instructions, D8153 or D8158 holds the step number in which the error occurred first.

When no error has occurred, D8153 or D8158 stores "-1".

2. Cautions on use

A decimal value without the sign is stored as the step number in D8153 and D8158.

12.4.11 IVBWR instruction error parameter number [D8154 and D8159]

These devices store the parameter number in which an error has occurred when IVBWR instruction error flag "M8154 or M8159" turns ON.

1. Detailed contents

D8154 or D8159 stores the parameter number which was not written by IVBWR instruction.

D8154 stores the parameter number which was not written in communication using communication port ch1.

D8159 stores the parameter number which was not written in communication using communication port ch2.

When errors that occurred in two or more IVBWR instructions, D8154 or D8159 holds the parameter number in which the error occurred first.

12.5 FREQROL Inverter Parameter List

This section shows the list of parameters provided in FREQROL F700, A700, E700, V500, F500, A500, E500 and S500 Series inverters.

For details on each function, refer to the respective inverter manual.

12.5.1 Parameters in V500, F500, A500, E500, and S500 Series

The following parameters are provided in FREQROL inverters. (For details, make sure to refer to the respective inverter manual.)

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|---|---------------------|--|---------------------|--|---------------------|--|---------------------|--|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Basic functions | 0 | Torque boost (manual) | 0 | Torque boost | 0 | Torque boost ^{*3} | 0 | Torque boost ^{*3} | 0 | Torque boost ^{*3} |
| | 1 | Maximum speed (simple mode) | 1 | Maximum frequency | 1 | Maximum frequency | 1 | Maximum frequency | 1 | Maximum frequency |
| | 2 | Minimum speed (simple mode) | 2 | Minimum frequency | 2 | Minimum frequency | 2 | Minimum frequency | 2 | Minimum frequency |
| | 3 | Base frequency | 3 | Base frequency | 3 | Base frequency | 3 | Base frequency ^{*3} | 3 | Base frequency ^{*3} |
| | 4 | Multi-speed setting (high speed) (simple mode) | 4 | Multi-speed setting (high speed) | 4 | Multi-speed setting (high speed) | 4 | Multi-speed setting (high speed) | 4 | Multi-speed setting (high speed) |
| | 5 | Multi-speed setting (middle speed) (simple mode) | 5 | Multi-speed setting (middle speed) | 5 | Multi-speed setting (middle speed) | 5 | Multi-speed setting (middle speed) | 5 | Multi-speed setting (middle speed) |
| | 6 | Multi-speed setting (low speed) (simple mode) | 6 | Multi-speed setting (low speed) | 6 | Multi-speed setting (low speed) | 6 | Multi-speed setting (low speed) | 6 | Multi-speed setting (low speed) |
| | 7 | Acceleration time (simple mode) | 7 | Acceleration time | 7 | Acceleration time | 7 | Acceleration time | 7 | Acceleration time |
| | 8 | Deceleration time (simple mode) | 8 | Deceleration time | 8 | Deceleration time | 8 | Deceleration time | 8 | Deceleration time |
| | 9 | Electronic thermal O/L relay | 9 | Electronic thermal O/L relay | 9 | Electronic thermal O/L relay | 9 | Electronic thermal O/L relay | 9 | Electronic thermal O/L relay |
| Standard operation functions | 10 | DC injection brake operation speed | 10 | DC injection brake operation frequency | 10 | DC injection brake operation frequency | 10 | DC injection brake operation frequency | 10 | DC injection brake operation frequency |
| | 11 | DC injection brake operation time | 11 | DC injection brake operation time | 11 | DC injection brake operation time | 11 | DC injection brake operation time | 11 | DC injection brake operation time |
| | 12 | DC injection brake voltage | 12 | DC injection brake voltage | 12 | DC injection brake voltage | 12 | DC injection brake voltage | 12 | DC injection brake voltage |
| | 13 | Starting speed | 13 | Starting frequency | 13 | Starting frequency | 13 | Starting frequency | 13 | Starting frequency |
| | — | — | 14 | Load pattern selection | 14 | Load pattern selection ^{*3} | 14 | Load pattern selection ^{*3} | 14 | Load pattern selection ^{*3} |
| | 15 | Jog speed setting | 15 | Jog frequency | 15 | Jog frequency | 15 | Jog frequency | 15 | Jog frequency |
| | 16 | Jog acceleration/ deceleration time | 16 | Jog acceleration/ deceleration time | 16 | Jog acceleration/ deceleration time | 16 | Jog acceleration/ deceleration time | 16 | Jog acceleration/ deceleration time |
| Standard operation function (V500 Series operation selection functions) | 17 | MRS input selection | 17 | MRS input selection | 17 | MRS input selection | — | — | 17 | RUN key rotation direction selection |
| | — | — | — | — | 18 | High speed maximum frequency | 18 | High speed maximum frequency | — | — |
| | 19 | Base frequency voltage | 19 | Base frequency voltage | 19 | Base frequency voltage ^{*3} | 19 | Base frequency voltage ^{*3} | 19 | Base frequency voltage ^{*3} |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|---|---------------------|---|---------------------|--|---------------------|--|---------------------|--|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Standard operation function (V500 Series operation selection functions) | 20 | Acceleration/deceleration reference speed | 20 | Acceleration/deceleration reference frequency | 20 | Acceleration/deceleration reference frequency | 20 | Acceleration/deceleration reference frequency | 20 | Acceleration/deceleration reference frequency |
| | 21 | Acceleration/deceleration time increment | 21 | Acceleration/deceleration time increment | 21 | Acceleration/deceleration time increment | 21 | Acceleration/deceleration time increment | 21 | Stall preventing function selection |
| | 22 | Torque restriction level | 22 | Stall prevention operation level | 22 | Stall prevention operation level | 22 | Stall prevention operation level | 22 | Stall prevention operation level |
| | — | — | 23 | Stall prevention operation level compensation factor at double speed | 23 | Stall prevention operation level compensation factor at double speed | 23 | Stall prevention operation level compensation factor at double speed | 23 | Stall prevention operation level compensation factor at double speed |
| | 24 | Multi-speed setting (speed 4) | 24 | Multi-speed setting (speed 4) | 24 | Multi-speed setting (speed 4) | 24 | Multi-speed setting (speed 4) | 24 | Multi-speed setting (speed 4) |
| | 25 | Multi-speed setting (speed 5) | 25 | Multi-speed setting (speed 5) | 25 | Multi-speed setting (speed 5) | 25 | Multi-speed setting (speed 5) | 25 | Multi-speed setting (speed 5) |
| | 26 | Multi-speed setting (speed 6) | 26 | Multi-speed setting (speed 6) | 26 | Multi-speed setting (speed 6) | 26 | Multi-speed setting (speed 6) | 26 | Multi-speed setting (speed 6) |
| | 27 | Multi-speed setting (speed 7) | 27 | Multi-speed setting (speed 7) | 27 | Multi-speed setting (speed 7) | 27 | Multi-speed setting (speed 7) | 27 | Multi-speed setting (speed 7) |
| | 28 | Multi-speed input compensation | 28 | Multi-speed input compensation | 28 | Multi-speed input compensation | — | — | 28 | Stall preventing operation reduction starting frequency |
| | 29 | Acceleration/deceleration pattern | 29 | Acceleration/deceleration pattern | 29 | Acceleration/deceleration pattern | 29 | Acceleration/deceleration pattern | 29 | Acceleration/deceleration pattern |
| | 30 | Regenerative function selection | 30 | Regenerative function selection | 30 | Regenerative function selection | 30 | Regenerative function selection | — | — |
| | 31 | Speed jump 1A | 31 | Frequency jump 1A | 31 | Frequency jump 1A | 31 | Frequency jump 1A | 31 | Frequency jump 1A |
| | 32 | Speed jump 1B | 32 | Frequency jump 1B | 32 | Frequency jump 1B | 32 | Frequency jump 1B | 32 | Frequency jump 1B |
| | 33 | Speed jump 2A | 33 | Frequency jump 2A | 33 | Frequency jump 2A | 33 | Frequency jump 2A | 33 | Frequency jump 2A |
| | 34 | Speed jump 2B | 34 | Frequency jump 2B | 34 | Frequency jump 2B | 34 | Frequency jump 2B | 34 | Frequency jump 2B |
| | 35 | Speed jump 3A | 35 | Frequency jump 3A | 35 | Frequency jump 3A | 35 | Frequency jump 3A | 35 | Frequency jump 3A |
| | 36 | Speed jump 3B | 36 | Frequency jump 3B | 36 | Frequency jump 3B | 36 | Frequency jump 3B | 36 | Frequency jump 3B |
| | 37 | Speed display | 37 | Speed display | 37 | Speed display | 37 | Speed display | 37 | Speed display |
| | — | — | 38 | Automatic torque boost | — | — | 38 | Frequency at 5V (10V) input | 38 | Frequency setting voltage gain frequency |
| | | | 39 | Automatic torque boost operation starting current | | | 39 | Frequency at 20mA input | 39 | Frequency setting current gain frequency |
| | | | — | — | | | — | — | 40 | Start-time ground fault detection selection |
| Output terminal functions | 41 | Up-to-speed sensitivity | 41 | Up-to-frequency sensitivity | 41 | Up-to-frequency sensitivity | 41 | Up-to-frequency sensitivity | 41 | Up-to-frequency sensitivity |
| | 42 | Speed detection | 42 | Output frequency detection | 42 | Output frequency detection | 42 | Output frequency detection | 42 | Output frequency detection |
| | 43 | Speed detection for reverse rotation | 43 | Output frequency detection for reverse rotation | 43 | Output frequency detection for reverse rotation | 43 | Output frequency detection for reverse rotation | 43 | Output frequency detection for reverse rotation |

| | |
|-------------|--|
| A | Common Items |
| B | N/N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RSS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|-------------------------------|---------------------|--|---------------------|---|---------------------|---|---------------------|---|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Second functions | 44 | Second acceleration/ deceleration time | 44 | Second acceleration/ deceleration time | 44 | Second acceleration/ deceleration time | 44 | Second acceleration/ deceleration time | 44 | Second acceleration/ deceleration time |
| | 45 | Second deceleration time | 45 | Second deceleration time | 45 | Second deceleration time | 45 | Second deceleration time | 45 | Second deceleration time |
| | — | — | 46 | Second torque boost | 46 | Second torque boost* ³ | 46 | Second torque boost* ³ | 46 | Second torque boost* ³ |
| | | | 47 | Second V/F (base frequency) | 47 | Second V/F (base frequency)* ³ | 47 | Second V/F (base frequency)* ³ | 47 | Second V/F (base frequency)* ³ |
| | | | 48 | Second stall prevention operation current | 48 | Second stall prevention operation current | 48 | Second electronic thermal O/L relay | — | — |
| | 50 | Second speed detection | 49 | Second stall prevention operation frequency | 49 | Second stall prevention operation frequency | — | — | | |
| | | | 50 | Second output frequency detection | 50 | Second output frequency detection | — | — | — | — |
| Display functions | 52 | DU/PU main display data selection | 52 | DU/PU main display data selection | 52 | DU/PU main display data selection | 52 | Operation panel/ PU main display data selection | 52 | Control panel display data selection |
| | 53 | PU level display data selection | 53 | PU level display data selection | 53 | PU level display data selection | — | — | 53 | Frequency setting operation function selection |
| | 54 | DA1 terminal function selection | 54 | FM terminal function selection | 54 | FM terminal function selection | 54 | FM terminal function selection | 54 | FM (AM) terminal function selection |
| | 55 | Speed monitoring reference | 55 | Frequency monitoring reference | 55 | Frequency monitoring reference | 55 | Frequency monitoring reference | 55 | Frequency monitoring reference |
| | 56 | Current monitoring reference | 56 | Current monitoring reference | 56 | Current monitoring reference | 56 | Current monitoring reference | 56 | Current monitoring reference |
| Restart | 57 | Restart coasting time | 57 | Restart coasting time | 57 | Restart coasting time | 57 | Restart coasting time | 57 | Restart coasting time |
| | 58 | Restart cushion time | 58 | Restart cushion time | 58 | Restart cushion time | 58 | Restart cushion time | 58 | Restart cushion time |
| Additional function | 59 | Remote setting function selection | 59 | Remote setting function selection | 59 | Remote setting function selection | 59 | Remote setting function selection | 59 | Remote setting function selection |
| Operation selecting functions | 60 | Intelligent mode selection | 60 | Intelligent mode selection | 60 | Intelligent mode selection | 60 | Shortest acceleration/ deceleration mode | — | — |
| | — | — | 61 | Reference I for intelligent mode | 61 | Reference I for intelligent mode | 61 | Reference current | | |
| | | | 62 | Reference I for intelligent mode acceleration | 62 | Reference I for intelligent mode acceleration | 62 | Reference current for acceleration | | |
| | | | 63 | Reference I for intelligent mode deceleration | 63 | Reference I for intelligent mode deceleration | 63 | Reference current for deceleration | | |
| | 65 | Retry selection | — | — | 64 | Starting frequency for elevator mode | — | — | | |
| | | | 65 | Retry selection | 65 | Retry selection | 65 | Retry selection | 66 | Retry selection |
| | 67 | Number of retries at alarm occurrence | 67 | Number of retries at alarm occurrence | 67 | Number of retries at alarm occurrence | 67 | Number of retries at alarm occurrence | 67 | Number of retries at alarm occurrence |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|-------------------------------|---------------------|---|---------------------|---|---------------------|---|---------------------|---|---------------------|---------------------------------------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Operation selecting functions | 68 | Retry waiting time | 68 | Retry waiting time | 68 | Retry waiting time | 68 | Retry waiting time | 68 | Retry waiting time |
| | 69 | Retry count display erasure | 69 | Retry count display erasure | 69 | Retry count display erase | 69 | Retry count display erasure | 69 | Retry count display erase |
| | 70 | Special regenerative brake duty | — | — | 70 | Special regenerative brake duty | 70 | Special regenerative brake duty | — | — |
| | 71 | Applied motor | 71 | Applied motor | 71 | Applied motor | 71 | Applied motor | 71 | Applied motor |
| | 72 | PWM frequency selection (simple mode) | 72 | PWM frequency selection | 72 | PWM frequency selection | 72 | PWM frequency selection | 72 | PWM frequency selection |
| | 73 | Speed setting signal | 73 | 0 to 5V/0 to 10V selection | 73 | 0 to 5V/0 to 10V selection | 73 | 0 to 5V/0 to 10V selection | 73 | 0 to 5V/0 to 10V selection |
| | — | — | 74 | Filter time constant | 74 | Filter time constant | 74 | Filter time constant | 74 | Input filter time constant |
| | 75 | Reset selection/disconnected PU detection/PU stop selection | 75 | Reset selection/disconnected PU detection/PU stop selection | 75 | Reset selection/disconnected PU detection/PU stop selection | 75 | Reset selection/disconnected PU detection/PU stop selection | 75 | Reset selection/PU stop selection |
| | — | — | 76 | Alarm code output selection | 76 | Alarm code output selection | — | — | — | — |
| | 77 | Parameter write disable selection (simple mode) | 77 | Parameter write disable selection | 77 | Parameter write disable selection | 77 | Parameter write disable selection | 77 | Parameter write disable selection |
| | 78 | Reverse rotation prevention selection | 78 | Reverse rotation prevention selection | 78 | Reverse rotation prevention selection | 78 | Reverse rotation prevention selection | 78 | Reverse rotation prevention selection |
| | 79 | Operation mode selection (simple mode) | 79 | Operation mode selection | 79 | Operation mode selection | 79 | Operation mode selection | 79 | Operation mode selection |
| Motor constant | 80 | Motor capacity | — | — | 80 | Motor capacity | 80 | Motor capacity | — | — |
| | 81 | Number of motor poles | | | 81 | Number of motor poles | — | — | | |
| | 82 | Motor excitation current (no load current)* ¹ | | | 82 | Motor excitation current* ⁵ | 82 | Motor excitation current | | |
| | 83 | Rated motor voltage | | | 83 | Rated motor voltage | 83 | Rated motor voltage | | |
| | 84 | Rated motor frequency | | | 84 | Rated motor frequency | 84 | Rated motor frequency | | |
| | — | — | | | 89 | Speed control gain | — | — | | |
| | 90 | Motor constant R1* ¹ | | | 90 | Motor constant (R1)* ⁵ | 90 | Motor constant (R1) | | |
| | 91 | Motor constant R2* ¹ | | | 91 | Motor constant (R2)* ⁵ | — | — | | |
| | 92 | Motor constant L1* ¹ | | | 92 | Motor constant (L1)* ⁵ | | | | |
| | 93 | Motor constant L2* ¹ | | | 93 | Motor constant (L2)* ⁵ | | | | |
| | 94 | Motor constant X* ¹ | | | 94 | Motor constant (X)* ⁵ | | | | |
| | 95 | Online auto tuning selection (simple mode) | — | — | 95 | Online auto tuning selection | — | — | — | — |
| | 96 | Auto tuning setting/status | | | 96 | Auto tuning setting/status | 96 | Auto tuning setting/status | | |

| | |
|-------------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/R52 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|--------------------------------------|---------------------|---------------------------------------|---------------------|-----------------------------------|---------------------|--|---------------------|-----------------------------------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| 5-point flexible V/F characteristics | — | — | 100 | V/F 1 (first frequency) | 100 | V/F 1 (first frequency) ^{*3} | — | — | — | — |
| | | | 101 | V/F 1 (first frequency voltage) | 101 | V/F 1 (first frequency voltage) ^{*3} | | | | |
| | | | 102 | V/F 2 (second frequency) | 102 | V/F 2 (second frequency) ^{*3} | | | | |
| | | | 103 | V/F 2 (second frequency voltage) | 103 | V/F 2 (second frequency voltage) ^{*3} | | | | |
| | | | 104 | V/F 3 (third frequency) | 104 | V/F 3 (third frequency) ^{*3} | | | | |
| | | | 105 | V/F 3 (third frequency voltage) | 105 | V/F 3 (third frequency voltage) ^{*3} | | | | |
| | | | 106 | V/F 4 (fourth frequency) | 106 | V/F 4 (fourth frequency) ^{*3} | | | | |
| | | | 107 | V/F 4 (fourth frequency voltage) | 107 | V/F 4 (fourth frequency voltage) ^{*3} | | | | |
| | | | 108 | V/F 5 (fifth frequency) | 108 | V/F 5 (fifth frequency) ^{*3} | | | | |
| | | | 109 | V/F 5 (fifth frequency voltage) | 109 | V/F 5 (fifth frequency voltage) ^{*3} | | | | |
| Third functions | 110 | Third acceleration /deceleration time | — | — | 110 | Third acceleration /deceleration time | — | — | — | — |
| | 111 | Third deceleration time | | | 111 | Third deceleration time | | | | |
| | — | — | | | 112 | Third torque boost ^{*3} | | | | |
| | | | | | 113 | Third V/F (base frequency) ^{*3} | | | | |
| | | | | | 114 | Third stall prevention operation current | | | | |
| | | | | | 115 | Third stall prevention operation frequency | | | | |
| | 116 | Third speed detection | | | 116 | Third output frequency detection | | | | |
| Communication functions | 117 | Communication station number | 117 | Communication station number | 117 | Communication station number | 117 | Communication station number | — | — |
| | 118 | Communication speed | 118 | Communication speed | 118 | Communication speed | 118 | Communication speed | | |
| | 119 | Stop bit length/ data length | 119 | Stop bit length/ data length | 119 | Stop bit length/ data length | 119 | Stop bit length/ data length | | |
| | 120 | Parity check presence/ absence | 120 | Parity check presence/ absence | 120 | Parity check presence/ absence | 120 | Parity check presence/ absence | | |
| | 121 | Number of communication retries | 121 | Number of communication retries | 121 | Number of communication retries | 121 | Number of communication retries | | |
| | 122 | Communication check time interval | 122 | Communication check time interval | 122 | Communication check time interval | 122 | Communication check time interval | | |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|--|---------------------|---------------------------------------|---------------------|---|---------------------|---|---------------------|---------------------------------------|---------------------|---------------------------------------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Communication functions | 123 | Waiting time setting | 123 | Waiting time setting | 123 | Waiting time setting | 123 | Waiting time setting | — | — |
| | 124 | CR and LF presence/absence selection | 124 | CR and LF presence/absence selection | 124 | CR and LF presence/absence selection | 124 | CR and LF presence/absence selection | | |
| PID control | 128 | PID action selection | 128 | PID action selection | 128 | PID action selection | 128 | PID action selection | 88 | PID action selection |
| | 129 | PID proportional band | 129 | PID proportional band | 129 | PID proportional band | 129 | PID proportional band | 89 | PID proportional band |
| | 130 | PID integral time | 130 | PID integral time | 130 | PID integral time | 130 | PID integral time | 90 | PID integral time |
| | 131 | Maximum | 131 | Maximum | 131 | Maximum | 131 | Maximum | 91 | PID maximum |
| | 132 | Minimum | 132 | Minimum | 132 | Minimum | 132 | Minimum | 92 | PID minimum |
| | 133 | PID action set point for PU operation | 133 | PID action set point for PU operation | 133 | PID action set point for PU operation | 133 | PID action set point for PU operation | 93 | PID action set point for PU operation |
| | 134 | PID differential time | 134 | PID differential time | 134 | PID differential time | 134 | PID differential time | 94 | PID differential time |
| Commercial power supply-inverter switch-over | — | — | 135 | Commercial power supply-inverter switch-over sequence output terminal selection | 135 | Commercial power supply-inverter switch-over sequence output terminal selection | — | — | — | — |
| | | | 136 | MC switch-over interlock time | 136 | MC switch-over interlock time | | | | |
| | | | 137 | Start waiting time | 137 | Start waiting time | | | | |
| | | | 138 | Commercial power supply-inverter switch-over selection at alarm occurrence | 138 | Commercial power supply-inverter switch-over selection at alarm occurrence | | | | |
| | | | 139 | Automatic inverter-commercial power supply switch-over frequency | 139 | Automatic inverter-commercial power supply switch-over frequency | | | | |
| Backlash | 140 | Backlash acceleration stopping speed | 140 | Backlash acceleration stopping frequency*2 | 140 | Backlash acceleration stopping frequency*2 | — | — | — | — |
| | 141 | Backlash acceleration stopping time | 141 | Backlash acceleration stopping time*2 | 141 | Backlash acceleration stopping time*2 | | | | |
| | 142 | Backlash deceleration stopping speed | 142 | Backlash deceleration stopping frequency*2 | 142 | Backlash deceleration stopping frequency*2 | | | | |
| | 143 | Backlash deceleration stopping time | 143 | Backlash deceleration stopping time*2 | 143 | Backlash deceleration stopping time*2 | | | | |
| Display functions | 144 | Speed setting switchover | 144 | Speed setting switchover | 144 | Speed setting switchover | — | — | — | — |
| | 145 | PU display language selection | 145 | PU display language selection | 145 | PU display language selection | 145 | PU display language selection | n13 (145) | PU display language |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | | | |
|---|---------------------|---|---------------------|---|---------------------|---|---------------------|--------------------------------------|---------------------|--|----|------------------------------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | | |
| Additional functions | — | — | — | — | — | — | 146 | Frequency setting command selection | — | — | | |
| | | | 148 | Stall prevention operation level at 0 V input | 148 | Stall prevention operation level at 0 V input | — | — | | | | |
| | | | 149 | Stall prevention operation level at 10 V input | 149 | Stall prevention operation level at 10 V input | | | | | | |
| Current detection | 150 | Output current detection level | — | — | 150 | Output current detection level | 150 | Output current detection level | 48 | Output current detection level | | |
| | 151 | Output current detection period | | | 151 | Output current detection period | 151 | Output current detection period | 49 | Output current detection signal delay time | | |
| | 152 | Zero current detection level | | | 152 | Zero current detection level | 152 | Zero current detection level | 152 | Zero current detection level | 50 | Zero current detection level |
| | 153 | Zero current detection period | | | 153 | Zero current detection period | 153 | Zero current detection period | 153 | Zero current detection period | 51 | Zero current detection time |
| Sub functions | — | — | 154 | Voltage reduction selection during stall prevention operation | 154 | Voltage reduction selection during stall prevention operation | — | — | — | — | | |
| | | | 155 | RT activated condition | 155 | RT signal activated condition | | | | | | |
| | 156 | Stall prevention operation selection | 156 | Stall prevention operation selection | 156 | Stall prevention operation selection | 156 | Stall prevention operation selection | | | | |
| | 157 | OL signal output timer | 157 | OL signal output waiting time | 157 | OL signal waiting time | — | — | | | | |
| | 158 | DA2 terminal function selection | 158 | AM terminal function selection | 158 | AM terminal function selection | | | | | | |
| Additional function | 160 | Extended function selection (simple mode) | 160 | User group read selection | 160 | User group read selection | 160 | User group read selection | — | — | | |
| Restart after instantaneous power failure | 162 | Automatic restart after instantaneous power failure selection | 162 | Automatic restart after instantaneous power failure selection | 162 | Automatic restart after instantaneous power failure selection | — | — | — | — | | |
| | 163 | First cushion time for restart | 163 | First cushion time for restart | 163 | First cushion time for restart | | | | | | |
| | 164 | First cushion voltage for restart | 164 | First cushion voltage for restart | 164 | First cushion voltage for restart | | | | | | |
| | 165 | Restart current restruction level | 165 | Restart stall prevention operation level | 165 | Restart stall prevention operation level | | | | | | |
| Initial monitor value | — | — | 170 | Watt-hour meter clear | 170 | Watt-hour meter clear | — | — | — | — | | |
| | 171 | Actual operation hour meter clear | 171 | Actual operation hour meter clear | 171 | Actual operation hour meter clear | 171 | Actual operation hour meter clear | | | | |
| User functions | — | — | 173 | User group 1 registration | 173 | User group 1 registration | 173 | User group 1 registration | — | — | | |
| | | | 174 | User group 1 deletion | 174 | User group 1 deletion | 174 | User group 1 deletion | | | | |
| | | | 175 | User group 2 registration | 175 | User group 2 registration | 175 | User group 2 registration | | | | |
| | | | 176 | User group 2 deletion | 176 | User group 2 deletion | 176 | User group 2 deletion | | | | |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|-------------------------------|---------------------|-----------------------------------|---------------------|-----------------------------------|---------------------|--|---------------------|-----------------------------------|---------------------|-----------------------------------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Terminal assignment functions | 180 | DI1 terminal function selection | 180 | RL terminal function selection | 180 | RL terminal function selection | 180 | RL terminal function selection | 60 | RL terminal function selection |
| | 181 | DI2 terminal function selection | 181 | RM terminal function selection | 181 | RM terminal function selection | 181 | RM terminal function selection | 61 | RM terminal function selection |
| | 182 | DI3 terminal function selection | 182 | RH terminal function selection | 182 | RH terminal function selection | 182 | RH terminal function selection | 62 | RH terminal function selection |
| | 183 | DI4 terminal function selection | 183 | RT terminal function selection | 183 | RT terminal function selection | 183 | MRS terminal function selection | | |
| | — | — | 184 | AU terminal function selection | 184 | AU terminal function selection | — | — | — | — |
| | | | 185 | JOG terminal function selection | 185 | JOG terminal function selection | | | | |
| | | | 186 | CS terminal function selection | 186 | CS terminal function selection | | | | |
| | 187 | STR terminal function selection | — | — | — | — | — | — | 63 | STR terminal function selection |
| | 190 | DO1 terminal function selection | 190 | RUN terminal function selection | 190 | RUN terminal function selection | 190 | RUN terminal function selection | 64 | RUN terminal function selection |
| | 191 | DO2 terminal function selection | 191 | SU terminal function selection | 191 | SU terminal function selection | 191 | FU terminal function selection | — | — |
| | 192 | DO3 terminal function selection | 192 | IPF terminal function selection | 192 | IPF terminal function selection | 192 | A/B/C terminal function selection | 65 | A/B/C terminal function selection |
| | — | — | 193 | OL terminal function selection | 193 | OL terminal function selection | — | — | — | — |
| | | | 194 | FU terminal function selection | 194 | FU terminal function selection | | | | |
| | 195 | A/B/C terminal function selection | 195 | A/B/C terminal function selection | 195 | A/B/C terminal function selection | — | — | — | — |
| Additional function | — | — | 199 | User's initial value setting | 199 | User's initial value setting | — | — | — | — |
| Programmed operation | — | — | — | — | 200 | Programmed operation minute/second selection | — | — | — | — |
| | | | | | 201 | Program set 1 | | | | |
| | | | | | 202 | Program set 1 | | | | |
| | | | | | 203 | Program set 1 | | | | |
| | | | | | 204 | Program set 1 | | | | |
| | | | | | 205 | Program set 1 | | | | |
| | | | | | 206 | Program set 1 | | | | |
| | | | | | 207 | Program set 1 | | | | |
| | | | | | 208 | Program set 1 | | | | |
| | | | | | 209 | Program set 1 | | | | |
| | | | | | 210 | Program set 1 | | | | |
| | | | | | 211 | Program set 2 | | | | |
| | | | | | 212 | Program set 2 | | | | |
| | | | | | 213 | Program set 2 | | | | |
| | | | | | 214 | Program set 2 | | | | |
| | | | | | 215 | Program set 2 | | | | |
| | | | | | 216 | Program set 2 | | | | |
| | | | | | 217 | Program set 2 | | | | |
| | | | | | 218 | Program set 2 | | | | |
| | | | | | 219 | Program set 2 | | | | |
| | | | | | 220 | Program set 2 | | | | |
| | | | | | 221 | Program set 3 | | | | |
| | | | | | 222 | Program set 3 | | | | |
| | | | | | 223 | Program set 3 | | | | |

| | |
|-------------|--|
| A | Common Items |
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|------------------------------|---------------------|---|---------------------|---|---------------------|---|---------------------|--|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Programmed operation | — | — | — | — | 224 | Program set 3 | — | — | — | — |
| | | | | | 225 | Program set 3 | | | | |
| | | | | | 226 | Program set 3 | | | | |
| | | | | | 227 | Program set 3 | | | | |
| | | | | | 228 | Program set 3 | | | | |
| | | | | | 229 | Program set 3 | | | | |
| | | | | | 230 | Program set 3 | | | | |
| | | | | | 231 | Timer setting | | | | |
| Multi-speed operation | 232 | Multi-speed setting (speed 8) | — | — | 232 | Multi-speed setting (speed 8) | 232 | Multi-speed setting (speed 8) | 80 | Multi-speed setting (speed 8) |
| | 233 | Multi-speed setting (speed 9) | | | 233 | Multi-speed setting (speed 9) | 233 | Multi-speed setting (speed 9) | 81 | Multi-speed setting (speed 9) |
| | 234 | Multi-speed setting (speed 10) | | | 234 | Multi-speed setting (speed 10) | 234 | Multi-speed setting (speed 10) | 82 | Multi-speed setting (speed 10) |
| | 235 | Multi-speed setting (speed 11) | | | 235 | Multi-speed setting (speed 11) | 235 | Multi-speed setting (speed 11) | 83 | Multi-speed setting (speed 11) |
| | 236 | Multi-speed setting (speed 12) | | | 236 | Multi-speed setting (speed 12) | 236 | Multi-speed setting (speed 12) | 84 | Multi-speed setting (speed 12) |
| | 237 | Multi-speed setting (speed 13) | | | 237 | Multi-speed setting (speed 13) | 237 | Multi-speed setting (speed 13) | 85 | Multi-speed setting (speed 13) |
| | 238 | Multi-speed setting (speed 14) | | | 238 | Multi-speed setting (speed 14) | 238 | Multi-speed setting (speed 14) | 86 | Multi-speed setting (speed 14) |
| | 239 | Multi-speed setting (speed 15) | | | 239 | Multi-speed setting (speed 15) | 239 | Multi-speed setting (speed 15) | 87 | Multi-speed setting (speed 15) |
| Sub functions | 240 | Soft-PWM setting | 240 | Soft-PWM setting | 240 | Soft-PWM setting | 240 | Soft-PWM setting | 70 | Soft-PWM setting |
| | 244 | Cooling fan operation selection | 244 | Cooling fan operation selection | 244 | Cooling fan operation selection | 244 | Cooling fan operation selection | 76 | Cooling fan operation selection |
| | — | — | — | — | — | — | 245 | Rated motor slip | 95 | Rated motor slip |
| | | | | | | | 246 | Slip compensation response time | 96 | Slip compensation time constant |
| | | | | | | | 247 | Constant-output region slip compensation selection | 97 | Constant-output region slip compensation selection |
| | | | | | | | — | — | 98 | Automatic torque boost selection (motor capacity) |
| | | | | | | | 249 | Earth (ground) fault detection at start*6 | 99 | Motor primary resistance |
| Stop selecting function | 250 | Stop selection | — | — | 250 | Stop selection | 250 | Stop selection | — | — |
| Additional functions | 251 | Output phase failure protection selection | 251 | Output phase failure protection selection | 251 | Output phase failure protection selection | 251 | Output phase failure protection selection | — | — |
| | 252 | Override bias | 252 | Override bias | 252 | Override bias | — | — | — | — |
| | 253 | Override gain | 253 | Override gain | 253 | Override gain | | | | |
| Power failure stop functions | 261 | Power failure stop selection | — | — | 261 | Power failure stop selection | — | — | — | — |
| | 262 | Subtraction speed at deceleration start | | | 262 | Subtraction frequency at deceleration start | | | | |
| | 263 | Subtraction starting speed | | | 263 | Subtraction starting frequency | | | | |
| | 264 | Power-failure deceleration time 1 | | | 264 | Power-failure deceleration time 1 | | | | |

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|------------------------------|---------------------|--|---------------------|---------------------|---------------------|---|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Power failure stop functions | 265 | Power-failure deceleration time 2 | — | — | 265 | Power-failure deceleration time 2 | — | — | — | — |
| | 266 | Power-failure deceleration time switchover speed | | | 266 | Power-failure deceleration time switchover frequency | | | | |
| Function selection | — | — | — | — | 270 | Stop-on-contact/ load torque high speed frequency control selection | — | — | — | — |
| High speed frequency control | — | — | — | — | 271 | High speed setting maximum current | — | — | — | — |
| | | | | | 272 | Middle speed setting minimum current | | | | |
| | | | | | 273 | Current averaging range | | | | |
| | | | | | 274 | Current averaging filter constant | | | | |
| Stop-on-contact | — | — | — | — | 275 | Stop-on-contact exciting current low speed multiplying factor | — | — | — | — |
| | | | | | 276 | Stop-on-contact PWM carrier frequency | | | | |
| Brake sequence function | 278 | Brake opening speed | — | — | 278 | Brake opening frequency ^{*4} | — | — | — | — |
| | 279 | Brake opening current | | | 279 | Brake opening current ^{*4} | | | | |
| | 280 | Brake opening current detection time | | | 280 | Brake opening current detection time ^{*4} | | | | |
| | 281 | Brake operation time at start | | | 281 | Brake operation time at start ^{*4} | | | | |
| | 282 | Brake operation speed | | | 282 | Brake operation frequency ^{*4} | | | | |
| | 283 | Brake operation time at stop | | | 283 | Brake operation time at stop ^{*4} | | | | |
| | 284 | Deceleration detection function selection | | | 284 | Deceleration detection function selection ^{*4} | | | | |
| | 285 | Overspeed detection speed | | | 285 | Overspeed detection frequency | | | | |
| Droop control functions | 286 | Droop gain | — | — | 286 | Droop gain | — | — | — | — |
| | 287 | Droop filter constant | | | 287 | Droop filter constant | | | | |
| | 288 | Droop function activation selection | | | — | — | | | | |
| 12-bit digital input | 300 | BCD input bias | 300 | BCD code input bias | 300 | BCD code input bias | — | — | — | — |
| | 301 | BCD input gain | 301 | BCD code input gain | 301 | BCD code input gain | | | | |
| | 302 | Binary input bias | 302 | Binary input bias | 302 | Binary input bias | | | | |
| | 303 | Binary input gain | 303 | Binary input gain | 303 | Binary input gain | | | | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
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|--|---------------------|--|---------------------|--|---------------------|--|---------------------|------|---------------------|---------------------------------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| 12-bit digital input | 304 | Digital input and analog compensation input enable/disable selection | 304 | Selection of whether digital input and analog compensation input are enabled or disabled | 304 | Selection of whether digital input and analog compensation input are enabled or disabled | — | — | — | — |
| | 305 | Read timing operation selection | 305 | Data read timing signal on/off selection | 305 | Data read timing signal on/off selection | | | | |
| Analog output/digital output | 306 | Analog output signal selection | 306 | Analog output signal selection | 306 | Analog output signal selection | — | — | — | — |
| | 307 | Setting for zero analog output | 307 | Setting for zero analog output | 307 | Setting for zero analog output | | | | |
| | 308 | Setting for maximum analog output | 308 | Setting for maximum analog output | 308 | Setting for maximum analog output | | | | |
| | 309 | Analog output signal voltage/current switchover | 309 | Analog output signal voltage/current switchover | 309 | Analog output signal voltage/current switchover | | | | |
| | 310 | Analog meter voltage output selection | 310 | Analog meter voltage output selection | 310 | Analog meter voltage output selection | | | | |
| | 311 | Setting for zero analog meter voltage output | 311 | Setting for zero analog meter voltage output | 311 | Setting for zero analog meter voltage output | | | | |
| | 312 | Setting for maximum analog meter voltage output | 312 | Setting for maximum analog meter voltage output | 312 | Setting for maximum analog meter voltage output | | | | |
| | 313 | Y0 output selection | 313 | Y0 output selection | 313 | Y0 output selection | | | | |
| | 314 | Y1 output selection | 314 | Y1 output selection | 314 | Y1 output selection | | | | |
| | 315 | Y2 output selection | 315 | Y2 output selection | 315 | Y2 output selection | | | | |
| | 316 | Y3 output selection | 316 | Y3 output selection | 316 | Y3 output selection | | | | |
| | 317 | Y4 output selection | 317 | Y4 output selection | 317 | Y4 output selection | | | | |
| | 318 | Y5 output selection | 318 | Y5 output selection | 318 | Y5 output selection | | | | |
| | 319 | Y6 output selection | 319 | Y6 output selection | 319 | Y6 output selection | | | | |
| Relay output | 320 | RA1 output selection | 320 | RA1 output selection | 320 | RA1 output selection | — | — | — | — |
| | 321 | RA2 output selection | 321 | RA2 output selection | 321 | RA2 output selection | | | | |
| | 322 | RA3 output selection | 322 | RA3 output selection | 322 | RA3 output selection | | | | |
| Digital input | 329 | Digital input unit selection | — | — | — | — | — | — | — | — |
| Relay output | 330 | RA output selection | 330 | RA output selection | 330 | RA output selection | — | — | — | — |
| Computer link function (S500 Series communication parameter) | 331 | Communication station number | 331 | Inverter station number | 331 | Communication station number | — | — | n1 (331) | Communication station number |
| | 332 | Communication speed | 332 | Communication speed | 332 | Communication speed | | | n2 (332) | Communication speed |
| | 333 | Stop bit length/data length | 333 | Stop bit length/data length | 333 | Stop bit length/data length | | | n3 (333) | Stop bit length/data length |
| | 334 | Parity check presence/absence | 334 | Parity check yes/no | 334 | Parity check yes/no | | | n4 (334) | Parity check presence/absence |
| | 335 | Number of communication retries | 335 | Communication retry count | 335 | Communication retry count | | | n5 (335) | Number of communication retries |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|--|---------------------|--|---------------------|---|---------------------|--|---------------------|--|---------------------|-----------------------------------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Computer link function (S500 Series communication parameter) | 336 | Communication check time interval | 336 | Communication check time interval | 336 | Communication check time interval | — | — | n6 (336) | Communication check time interval |
| | 337 | Waiting time setting | 337 | Waiting time setting | 337 | Waiting time setting | — | — | n7 (337) | Wait time setting |
| | 338 | Operation command source | 338 | Operation command write | 338 | Operation command right | 338 | Operation command source | n8 (338) | Operation command write |
| | 339 | Speed command source | 339 | Speed command write | 339 | Speed command write | 339 | Speed command source | n9 (339) | Speed command write |
| | 340 | Link startup mode selection | 340 | Link startup mode selection | 340 | Link startup mode selection | 340 | Link startup mode selection | n10 (340) | Link start mode selection |
| | 341 | CR and LF presence/absence selection | 341 | CR and LF yes/no selection | 341 | CR and LF yes/no selection | — | — | n11 (341) | CR and LF selection |
| | 342 | EEPROM write selection | 342 | EEPROM write selection | 342 | EEPROM write selection | 342 | EEPROM write selection | n12 (342) | EEPROM write selection |
| DeviceNet communication | 345 | DeviceNet address (lower) | 345 | DeviceNet address startup data (lower byte) | 345 | DeviceNet address startup data (lower byte) | 345 | DeviceNet address startup data (lower byte) | — | — |
| | 346 | DeviceNet baud rate (lower) | 346 | DeviceNet baud rate startup data (lower byte) | 346 | DeviceNet baud rate startup data (lower byte) | 346 | DeviceNet baud rate startup data (lower byte) | — | — |
| | 347 | DeviceNet address (higher) | — | — | 347 | DeviceNet address startup data (higher byte) | 347 | DeviceNet address startup data (higher byte) | — | — |
| | 348 | DeviceNet baud rate (higher) | — | — | 348 | DeviceNet baud rate startup data (higher byte) | 348 | DeviceNet baud rate startup data (higher byte) | — | — |
| Orientation control/ encoder feedback control/ pulse train input | 350 | Stop position command selection | — | — | 350 | Stop position command selection | — | — | — | — |
| | 351 | Orientation switchover speed | — | — | 351 | Orientation switchover speed | — | — | — | — |
| | — | — | — | — | 352 | Creep speed | — | — | — | — |
| | — | — | — | — | 353 | Creep switch position | — | — | — | — |
| | — | — | — | — | 354 | Position loop switchover position | — | — | — | — |
| | — | — | — | — | 355 | DC injection start position | — | — | — | — |
| | 356 | Internal stop position command | — | — | 356 | Internal stop position command | — | — | — | — |
| | 357 | In-position zone | — | — | 357 | In-position zone | — | — | — | — |
| | — | — | — | — | 358 | Servo torque selection | — | — | — | — |
| | 359 | Orientation encoder rotation direction | — | — | 359 | Encoder rotation direction | — | — | — | — |
| | 360 | External position command selection | — | — | 360 | 12-bit data selection | — | — | — | — |
| | 361 | Position shift | — | — | 361 | Position shift | — | — | — | — |
| | 362 | Orientation position loop gain | — | — | 362 | Position loop gain | — | — | — | — |
| | — | — | — | — | 363 | Completion signal output delay time | — | — | — | — |

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|--|---------------------|-------------------------------------|---------------------|------|---------------------|-------------------------------------|------------------------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Orientation control/ encoder feedback control/ pulse train input | — | — | — | — | 364 | Encoder stop check time | — | — | — | — |
| | | | | | 365 | Orientation censored limit | | | | |
| | | | | | 366 | Reconfirmation time | | | | |
| | | | | | 367 | Speed feedback range | | | | |
| | | | | | 368 | Feedback gain | | | | |
| | 369 | Number of orientation encoder pulse | | | 369 | Number of orientation encoder pulse | | | | |
| | — | — | | | 370 | Control mode selection | | | | |
| | | | | | 371 | Torque characteristic selection | | | | |
| | | | | | 372 | Speed control P gain | | | | |
| | | | | | 373 | Speed control I gain | | | | |
| | 374 | Over-speed detection level | | | 374 | Over-speed detection level | | | | |
| | — | — | | | 375 | Servo lock gain | | | | |
| | | | | | 376 | Disconnection detection selection | | | | |
| | 380 | Acceleration S pattern 1 | | | 380 | Acceleration S pattern 1 | | | | |
| | 381 | Deceleration S pattern 1 | | | 381 | Deceleration S pattern 1 | | | | |
| | 382 | Acceleration S pattern 2 | | | 382 | Acceleration S pattern 2 | | | | |
| | 383 | Deceleration S pattern 2 | | | 383 | Deceleration S pattern 2 | | | | |
| | 384 | Input pulse division scaling factor | | | 384 | Input pulse division scaling factor | | | | |
| | 385 | Speed for zero input pulse | | | 385 | Frequency for zero input pulse | | | | |
| | 386 | Speed for maximum input pulse | | | 386 | Frequency for maximum input pulse | | | | |
| LONWORKS® function | — | — | — | — | — | 387 | Initial communication delay time | — | — | |
| | | | | | | 388 | Send time interval at hart beat | | | |
| | | | | | | 389 | Minimum sending time at hart beat | | | |
| | | | | | | 390 | % setting reference frequency | | | |
| | | | | | | 391 | Receive time interval at hart beat | | | |
| | | | | | | 392 | Event-driven detection width | | | |

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|-----------------------|---------------------|---|---------------------|------|---------------------|------|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Orientation selection | 393 | Orientation selection | — | — | — | — | — | — | — | — |
| | 394 | Number of machine side gear teeth | | | | | | | | |
| | 395 | Number of motor side gear teeth | | | | | | | | |
| | 396 | Orientation speed gain (P term) | | | | | | | | |
| | 397 | Orientation speed integral time | | | | | | | | |
| | 398 | Orientation speed gain (D term) | | | | | | | | |
| | 399 | Orientation deceleration ratio | | | | | | | | |
| Extension input | 400 | DI11 terminal function selection | — | — | — | — | — | — | — | — |
| | 401 | DI12 terminal function selection | | | | | | | | |
| | 402 | DI13 terminal function selection | | | | | | | | |
| | 403 | DI14 terminal function selection | | | | | | | | |
| | 404 | DI15 terminal function selection | | | | | | | | |
| | 405 | DI16 terminal function selection | | | | | | | | |
| | 406 | High resolution analog input selection | | | | | | | | |
| | 407 | Motor temperature detection filter | | | | | | | | |
| Extension output | 410 | DO11 terminal function selection | — | — | — | — | — | — | — | — |
| | 411 | DO12 terminal function selection | | | | | | | | |
| | 412 | DO13 terminal function selection | | | | | | | | |
| | 413 | Encoder pulse output division ratio | | | | | | | | |
| Positioning control | 419 | Position command source selection | — | — | — | — | — | — | — | — |
| | 420 | Command pulse scaling factor numerator | | | | | | | | |
| | 421 | Command pulse scaling factor denominator | | | | | | | | |
| | 422 | Position loop gain | | | | | | | | |
| | 423 | Position feed forward gain | | | | | | | | |
| | 424 | Position command acceleration/ deceleration time constant | | | | | | | | |

| | |
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|---------------------|---------------------|--|---------------------|------|---------------------|------|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Positioning control | 425 | Position feed forward command filter | — | — | — | — | — | — | — | — |
| | 426 | In-position width | | | | | | | | |
| | 427 | Excessive level error | | | | | | | | |
| | 428 | Command pulse selection | | | | | | | | |
| | 429 | Clear signal selection | | | | | | | | |
| | 430 | Pulse monitor selection | | | | | | | | |
| Torque command | 432 | Pulse train torque command bias | — | — | — | — | — | — | — | — |
| | 433 | Pulse train torque command gain | | | | | | | | |
| Position control | 434 | IP address 1 | — | — | — | — | — | — | — | — |
| | 435 | IP address 2 | | | | | | | | |
| | 436 | IP address 3 | | | | | | | | |
| | 437 | IP address 4 | | | | | | | | |
| | 438 | Sub-net mask 1 | | | | | | | | |
| | 439 | Sub-net mask 2 | | | | | | | | |
| | 440 | Sub-net mask 3 | | | | | | | | |
| | 441 | Sub-net mask 4 | | | | | | | | |
| | 442 | Gateway address 1 | | | | | | | | |
| | 443 | Gateway address 2 | | | | | | | | |
| | 444 | Gateway address 3 | | | | | | | | |
| | 445 | Gateway address 4 | | | | | | | | |
| | 446 | Password | | | | | | | | |
| Torque command | 447 | Digital torque command bias | — | — | — | — | — | — | — | — |
| | 448 | Digital torque command gain | | | | | | | | |
| Motor constant | 450 | Second applied motor | — | — | — | — | — | — | — | — |
| | 451 | Second motor control method selection | | | | | | | | |
| | 452 | Second electronic thermal O/L relay | | | | | | | | |
| | 453 | Second motor capacity | | | | | | | | |
| | 454 | Number of second motor poles | | | | | | | | |
| Position control | 464 | Digital position control sudden stop deceleration time | — | — | — | — | — | — | — | — |
| | 465 | First position feed amount lower 4 digits | | | | | | | | |
| | 466 | First position feed amount upper 4 digits | | | | | | | | |
| | 467 | Second position feed amount lower 4 digits | | | | | | | | |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|------------------|---------------------|--|---------------------|------|---------------------|------|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Position control | 468 | Second position feed amount upper 4 digits | — | — | — | — | — | — | — | — |
| | 469 | Third position feed amount lower 4 digits | | | | | | | | |
| | 470 | Third position feed amount upper 4 digits | | | | | | | | |
| | 471 | Fourth position feed amount lower 4 digits | | | | | | | | |
| | 472 | Fourth position feed amount upper 4 digits | | | | | | | | |
| | 473 | Fifth position feed amount lower 4 digits | | | | | | | | |
| | 474 | Fifth position feed amount upper 4 digits | | | | | | | | |
| | 475 | Sixth position feed amount lower 4 digits | | | | | | | | |
| | 476 | Sixth position feed amount upper 4 digits | | | | | | | | |
| | 477 | Seventh position feed amount lower 4 digits | | | | | | | | |
| | 478 | Seventh position feed amount upper 4 digits | | | | | | | | |
| | 479 | Eighth position feed amount lower 4 digits | | | | | | | | |
| | 480 | Eighth position feed amount upper 4 digits | | | | | | | | |
| | 481 | Ninth position feed amount lower 4 digits | | | | | | | | |
| | 482 | Ninth position feed amount upper 4 digits | | | | | | | | |
| | 483 | Tenth position feed amount lower 4 digits | | | | | | | | |
| | 484 | Tenth position feed amount upper 4 digits | | | | | | | | |
| | 485 | Eleventh position feed amount lower 4 digits | | | | | | | | |
| | 486 | Eleventh position feed amount upper 4 digits | | | | | | | | |
| | 487 | Twelfth position feed amount lower 4 digits | | | | | | | | |

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|-------------|--|
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|---|---------------------|---|---------------------|--|---------------------|--|---------------------|--|---------------------|------|---|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | |
| Position control | 488 | Twelfth position feed amount upper 4 digits | — | — | — | — | — | — | — | — | |
| | 489 | Thirteenth position feed amount lower 4 digits | | | | | | | | | |
| | 490 | Thirteenth position feed amount upper 4 digits | | | | | | | | | |
| | 491 | Fourteenth position feed amount lower 4 digits | | | | | | | | | |
| | 492 | Fourteenth position feed amount upper 4 digits | | | | | | | | | |
| | 493 | Fifteenth position feed amount lower 4 digits | | | | | | | | | |
| | 494 | Fifteenth position feed amount upper 4 digits | | | | | | | | | |
| Remote output | 495 | Remote output selection | — | — | — | — | — | — | — | — | |
| | 496 | Remote output data 1 | | | | | | | | | |
| | 497 | Remote output data 2 | | | | | | | | | |
| Communication (F500 Series Advanced PID control functions) | 499 | Action selection at SSCNET communication interruption | — | — | — | — | — | — | — | — | |
| | 500 | Communication error recognition waiting time | 500 | Auxiliary motor operation | 500 | Communication error recognition waiting time | 500 | Communication error recognition waiting time | | | |
| | 501 | Communication error occurrence count display | 501 | Motor switch-over selection | 501 | Communication error occurrence count display | 501 | Communication error occurrence count display | | | |
| | 502 | Stop mode selection at communication error | 502 | MC switching interlock time | 502 | Communication error-time stop mode selection | 502 | Stop mode selection at communication error | | | |
| Capacitor life (F500 Series Advanced PID control functions) | — | — | 503 | Start waiting time | 503 | Capacitor life timer | — | — | — | — | — |
| | | | 504 | Auxiliary motor connection-time deceleration time | 504 | Capacitor life alarm output setting time | | | | | |
| | | | 505 | Auxiliary motor disconnection-time acceleration time | — | — | | | | | |
| | | | 506 | Output stop detection time | | | | | | | |
| | | | 507 | Output stop detection level | | | | | | | |
| | | | 508 | Output stop cancel process value level | | | | | | | |
| | | | 509 | Auxiliary motor 1 starting frequency | | | | | | | |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|---|---------------------|--|---------------------|--------------------------------------|---------------------|---------------------------|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Capacitor life (F500 Series Advanced PID control functions) | — | — | 510 | Auxiliary motor 2 starting frequency | — | — | — | — | — | — |
| | | | 511 | Auxiliary motor 3 starting frequency | | | | | | |
| | | | 512 | Auxiliary motor 1 stopping frequency | | | | | | |
| | | | 513 | Auxiliary motor 2 stopping frequency | | | | | | |
| | | | 514 | Auxiliary motor 3 stopping frequency | | | | | | |
| | | | 515 | Auxiliary motor start delay time | | | | | | |
| | | | 516 | Auxiliary motor start delay time | | | | | | |
| Restart after instantaneous power failure | — | — | — | — | 611 | Restart acceleration time | — | — | — | — |
| Operation selecting function | 800 | Control system selection (simple mode) | — | — | — | — | — | — | — | — |
| | 801 | Torque characteristic selection | | | | | | | | |
| | 802 | Pre-excitation selection | — | — | — | — | — | — | — | — |
| | 803 | Constant output region torque characteristic selection | | | | | | | | |
| | 804 | Torque command source selection | | | | | | | | |
| | 805 | Torque command source (RAM) | | | | | | | | |
| | 806 | Torque command source (RAM, EEPROM) | | | | | | | | |
| | 807 | Speed restriction selection | | | | | | | | |
| | 808 | Forward rotation speed restriction | | | | | | | | |
| | 809 | Reverse rotation speed restriction | | | | | | | | |
| Control system function (A500 Series vector control) | 810 | Torque restriction input method selection | — | — | — | — | — | — | — | — |
| | 812 | Torque restriction level (regeneration) | | | | | | | | |
| | 813 | Torque restriction level (3rd quadrant) | | | | | | | | |
| | 814 | Torque restriction level (4th quadrant) | | | | | | | | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS485 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|--|---------------------------|---|---------------------|------|---------------------|---------------------------------------|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Control system function (A500 Series vector control) | 815 | Torque restriction level 2 | — | — | — | — | — | — | — | — |
| | 816 | Acceleration torque restriction level | | | 816 | Acceleration torque restriction level | | | | |
| | 817 | Deceleration torque restriction level | | | 817 | Deceleration torque restriction level | | | | |
| | 818 | Easy gain tuning response level setting (simple mode) | | | — | — | | | | |
| | 819 | Easy gain tuning selection (simple mode) | | | | | | | | |
| | 820 | Speed control P gain 1 | | | | | | | | |
| | 821 | Speed control integral time 1 | | | | | | | | |
| | 822 | Speed setting filter 1 | | | | | | | | |
| | 823 | Speed detection filter 1 | | | | | | | | |
| | 824 | Torque control P gain 1 | | | | | | | | |
| | 825 | Torque control integral time 1 | | | | | | | | |
| | 826 | Torque setting filter 1 | | | | | | | | |
| | 827 | Torque detection filter 1 | | | | | | | | |
| | 828 | Model speed control gain | | | | | | | | |
| | 830 | Speed control P gain 2 | | | | | | | | |
| | 831 | Speed control integral time 2 | | | | | | | | |
| | 832 | Speed setting filter 2 | | | | | | | | |
| | 833 | Speed detection filter 2 | | | | | | | | |
| | 834 | Torque control P gain 2 | | | | | | | | |
| | 835 | Torque control integral time 2 | | | | | | | | |
| 836 | Torque setting filter 2 | | | | | | | | | |
| 837 | Torque detection filter 2 | | | | | | | | | |
| Torque biases | 840 | Torque bias selection | — | — | — | — | — | — | — | — |
| | 841 | Torque bias 1 | | | | | | | | |
| | 842 | Torque bias 2 | | | | | | | | |
| | 843 | Torque bias 3 | | | | | | | | |
| | 844 | Torque bias filter | | | | | | | | |
| | 845 | Torque bias operation time | | | | | | | | |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|-------------------------------|---------------------|---|---------------------|------|---------------------|------|---------------------|------|---------------------|------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Torque biases | 846 | Torque bias balance compensation | — | — | — | — | — | — | — | — |
| | 847 | Fall-time torque bias No. 3 bias | | | | | | | | |
| | 848 | Fall-time torque bias No. 3 gain | | | | | | | | |
| | 849 | Analog input offset adjustment | | | | | | | | |
| Additional functions | 851 | Number of encoder pulses | — | — | — | — | — | — | — | — |
| | 852 | Encoder rotation direction | | | | | | | | |
| | 854 | Excitation ratio | | | | | | | | |
| | 859 | Torque current | | | | | | | | |
| | 862 | Notch filter frequency | | | | | | | | |
| | 863 | Notch filter depth | | | | | | | | |
| | 864 | Torque detection | | | | | | | | |
| Display functions | 865 | Low speed detection | — | — | — | — | — | — | — | — |
| | 866 | Torque monitoring reference | | | | | | | | |
| Terminal assignment function | 867 | DA1 output filter | — | — | — | — | — | — | — | — |
| | 868 | No. 1 terminal function assignment | | | | | | | | |
| Protection functions | 870 | Speed deviation level | — | — | — | — | — | — | — | — |
| | 871 | Speed deviation time | | | | | | | | |
| | 873 | Speed restriction | | | | | | | | |
| | 874 | OLT level setting | | | | | | | | |
| Operation selecting functions | 875 | Fault definition | — | — | — | — | — | — | — | — |
| | 876 | Thermal relay protector input | | | | | | | | |
| Control system functions | 877 | Speed feed forward/model adaptive speed control selection | — | — | — | — | — | — | — | — |
| | 878 | Speed feed forward filter | | | | | | | | |
| | 879 | Speed feed forward torque restriction | | | | | | | | |
| | 880 | Load inertia ratio | | | | | | | | |
| | 881 | Speed feed forward gain | | | | | | | | |
| Maintenance functions | 890 | Maintenance output setting time | — | — | — | — | — | — | — | — |
| | 891 | Maintenance output timer | | | | | | | | |
| | 892 | Maintenance output signal clear | | | | | | | | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RSRS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|-----------------------|---------------------|---|---------------------|--------------------------------|---------------------|--------------------------------|---------------------|--------------------------------|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Calibration functions | 900 | DA1 terminal calibration | 900 | FM terminal calibration | 900 | FM terminal calibration | 900 | FM terminal calibration | C1 (900 (901)) | FM (AM) terminal calibration |
| | 901 | DA2 terminal calibration | 901 | AM terminal calibration | 901 | AM terminal calibration | — | — | — | — |
| | 902 | Speed setting No. 2 bias | 902 | Frequency setting voltage bias | 902 | Frequency setting voltage bias | 902 | Frequency setting voltage bias | C2 (902) | Frequency setting voltage bias frequency |
| | | | | | | | | | C3 (902) | Frequency setting voltage bias |
| | 903 | Speed setting No. 2 gain | 903 | Frequency setting voltage gain | 903 | Frequency setting voltage gain | 903 | Frequency setting voltage gain | C4 (903) | Frequency setting voltage gain |
| | 904 | Torque command No. 3 bias | 904 | Frequency setting current bias | 904 | Frequency setting current bias | 904 | Frequency setting current bias | C5 (904) | Frequency setting current bias frequency |
| | | | | | | | | | C6 (904) | Frequency setting current bias |
| | 905 | Torque command No. 3 gain | 905 | Frequency setting current gain | 905 | Frequency setting current gain | 905 | Frequency setting current gain | C7 (905) | Frequency setting current gain |
| | — | — | — | — | — | — | — | — | C8 (269) | Parameter set by manufacturer. Do not set. |
| | 917 | No. 1 terminal bias (speed) | | | | | | | | |
| | 918 | No. 1 terminal gain (speed) | | | | | | | | |
| | 919 | No. 1 terminal bias (torque/magnetic flux) | | | | | | | | |
| | 920 | No. 1 terminal gain (torque/magnetic flux) | | | | | | | | |
| | — | — | | | | | | | | |
| | — | — | | | | | | | | |
| | 922 | Built-in frequency setting potentiometer bias*7 | | | | | | | | |
| | 923 | Built-in frequency setting potentiometer gain*7 | | | | | | | | |
| | 925 | Motor temperature detection calibration | | | | | | | | |
| | 926 | No. 6 terminal bias (speed) | | | | | | | | |
| | 927 | No. 6 terminal gain (speed) | | | | | | | | |
| | 928 | No. 6 terminal bias (torque) | | | | | | | | |
| | 929 | No. 6 terminal gain (torque) | | | | | | | | |
| Additional functions | 990 | PU buzzer control | 990 | PU buzzer control | 990 | PU Buzzer control | 990 | PU buzzer control | n14 (990) | PU buzzer sound control |
| | 991 | PU contrast adjustment | 991 | PU contrast adjustment | 991 | PU contrast adjustment | 991 | PU contrast adjustment | n15 (991) | PU contrast adjustment |
| | — | — | — | — | — | — | — | — | n16 (992) | PU main display screen data selection |

| | FREQROL V500 Series | | FREQROL F500 Series | | FREQROL A500 Series | | FREQROL E500 Series | | FREQROL S500 Series | |
|----------------------|---------------------|------|---------------------|------|---------------------|------|---------------------|------|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Additional functions | — | — | — | — | — | — | — | — | n17 (993) | PU disconnection detection/PU setting lock |

The parameters No. 77 and No. 79 cannot be written in computer link operation using the FR-A5NR.

- *1. Can be read or written when the parameter No. 77 is set to "801".
- *2. Can be read or written when the parameter No. 29 is set to "3".
- *3. Indicates a parameter whose setting is ignored when the advanced magnetic flux vector control mode is selected.
- *4. Can be set when the parameters Nos. 80 and 81 are not set to "9999" and the parameter No. 60 is set to "7" or "8".
- *5. Can be read or written when the parameters Nos. 80 and 81 are not set to "9999" and the parameter No. 77 is set to "801".
- *6. Can be set only in the 200 V/100 V class.
- *7. Cannot be used in inverter communication.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

12.5.2 Parameters in F700, A700, and E700 Series

The following parameters are provided in the F700, A700, and E700 Series inverters. (For details, make sure to refer to the respective inverter manual.)

| Function | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|---------------------------------|---------------------|--|---------------------|--|---------------------|--|
| | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Basic functions | 0 | Torque boost | 0 | Torque boost | 0 | Torque boost |
| | 1 | Maximum frequency | 1 | Maximum frequency | 1 | Maximum frequency |
| | 2 | Minimum frequency | 2 | Minimum frequency | 2 | Minimum frequency |
| | 3 | Base frequency | 3 | Base frequency | 3 | Base frequency |
| | 4 | Multi-speed setting (high speed) | 4 | Multi-speed setting (high speed) | 4 | Multi-speed setting (high speed) |
| | 5 | Multi-speed setting (middle speed) | 5 | Multi-speed setting (middle speed) | 5 | Multi-speed setting (middle speed) |
| | 6 | Multi-speed setting (low speed) | 6 | Multi-speed setting (low speed) | 6 | Multi-speed setting (low speed) |
| | 7 | Acceleration time | 7 | Acceleration time | 7 | Acceleration time |
| | 8 | Deceleration time | 8 | Deceleration time | 8 | Deceleration time |
| | 9 | Electronic thermal O/L relay | 9 | Electronic thermal O/L relay | 9 | Electronic thermal O/L relay |
| DC injection brake | 10 | DC injection brake operation frequency | 10 | DC injection brake operation frequency | 10 | DC injection brake operation frequency |
| | 11 | DC injection brake operation time | 11 | DC injection brake operation time | 11 | DC injection brake operation time |
| | 12 | DC injection brake operation voltage | 12 | DC injection brake operation voltage | 12 | DC injection brake operation voltage |
| – | 13 | Starting frequency | 13 | Starting frequency | 13 | Starting frequency |
| – | 14 | Load pattern selection | 14 | Load pattern selection | 14 | Load pattern selection |
| Jog operation | 15 | Jog frequency | 15 | Jog frequency | 15 | Jog frequency |
| | 16 | Jog acceleration/deceleration time | 16 | Jog acceleration/deceleration time | 16 | Jog acceleration/deceleration time |
| – | 17 | MRS input selection | 17 | MRS input selection | 17 | MRS input selection |
| – | 18 | High speed maximum frequency | 18 | High speed maximum frequency | 18 | High speed maximum frequency |
| – | 19 | Base frequency voltage | 19 | Base frequency voltage | 19 | Base frequency voltage |
| Acceleration/deceleration times | 20 | Acceleration/deceleration reference frequency | 20 | Acceleration/deceleration reference frequency | 20 | Acceleration/deceleration reference frequency |
| | 21 | Acceleration/deceleration time increments | 21 | Acceleration/deceleration time increments | 21 | Acceleration/deceleration time increments |
| Stall prevention | 22 | Stall prevention operation level | 22 | Stall prevention operation level (torque limit level) | 22 | Stall prevention operation level |
| | 23 | Stall prevention operation level compensation factor at double speed | 23 | Stall prevention operation level compensation factor at double speed | 23 | Stall prevention operation level compensation factor at double speed |
| Multi-speed setting | 24 | Multi-speed setting (speed 4) | 24 | Multi-speed setting (speed 4) | 24 | Multi-speed setting (speed 4) |
| | 25 | Multi-speed setting (speed 5) | 25 | Multi-speed setting (speed 5) | 25 | Multi-speed setting (speed 5) |
| | 26 | Multi-speed setting (speed 6) | 26 | Multi-speed setting (speed 6) | 26 | Multi-speed setting (speed 6) |
| | 27 | Multi-speed setting (speed 7) | 27 | Multi-speed setting (speed 7) | 27 | Multi-speed setting (speed 7) |
| – | 28 | Multi-speed input compensation selection | 28 | Multi-speed input compensation selection | – | – |
| – | 29 | Acceleration/deceleration pattern selection | 29 | Acceleration/deceleration pattern selection | 29 | Acceleration/deceleration pattern selection |
| – | 30 | Regenerative function selection | 30 | Regenerative function selection | 30 | Regenerative function selection |
| Frequency jump | 31 | Frequency jump 1A | 31 | Frequency jump 1A | 31 | Frequency jump 1A |
| | 32 | Frequency jump 1B | 32 | Frequency jump 1B | 32 | Frequency jump 1B |
| | 33 | Frequency jump 2A | 33 | Frequency jump 2A | 33 | Frequency jump 2A |
| | 34 | Frequency jump 2B | 34 | Frequency jump 2B | 34 | Frequency jump 2B |
| | 35 | Frequency jump 3A | 35 | Frequency jump 3A | 35 | Frequency jump 3A |

| Function | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|--------------------------------------|---------------------|---|---------------------|---|---------------------|---|
| | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Frequency jump | 36 | Frequency jump 3B | 36 | Frequency jump 3B | 36 | Frequency jump 3B |
| – | 37 | Speed display | 37 | Speed display | 37 | Speed display |
| – | – | – | – | – | 40 | RUN key rotation direction selection |
| Frequency detection | 41 | Up-to-frequency sensitivity | 41 | Up-to-frequency sensitivity | 41 | Up-to-frequency sensitivity |
| | 42 | Output frequency detection | 42 | Output frequency detection | 42 | Output frequency detection |
| | 43 | Output frequency detection for reverse rotation | 43 | Output frequency detection for reverse rotation | 43 | Output frequency detection for reverse rotation |
| Second functions | 44 | Second acceleration/ deceleration time | 44 | Second acceleration/ deceleration time | 44 | Second acceleration/ deceleration time |
| | 45 | Second deceleration time | 45 | Second deceleration time | 45 | Second deceleration time |
| | 46 | Second torque boost | 46 | Second torque boost | 46 | Second torque boost |
| | 47 | Second V/F (base frequency) | 47 | Second V/F (base frequency) | 47 | Second V/F (base frequency) |
| | 48 | Second stall prevention operation current | 48 | Second stall prevention operation current | 48 | Second stall prevention operation current |
| | 49 | Second stall prevention operation frequency | 49 | Second stall prevention operation frequency | – | – |
| | 50 | Second output frequency detection | 50 | Second output frequency detection | | |
| Monitor functions | 51 | Second electronic thermal O/L relay | 51 | Second electronic thermal O/L relay | 51 | Second electronic thermal O/L relay |
| | 52 | DU/PU main display data selection | 52 | DU/PU main display data selection | 52 | DU/PU main display data selection |
| | 54 | FM terminal function selection | 54 | FM terminal function selection | 54 | FM terminal function selection |
| | 55 | Frequency monitoring reference | 55 | Frequency monitoring reference | 55 | Frequency monitoring reference |
| Automatic restart functions | 56 | Current monitoring reference | 56 | Current monitoring reference | 56 | Current monitoring reference |
| | 57 | Restart coasting time | 57 | Restart coasting time | 57 | Restart coasting time |
| – | 58 | Restart cushion time | 58 | Restart cushion time | 58 | Restart cushion time |
| – | 59 | Remote function selection | 59 | Remote function selection | 59 | Remote function selection |
| – | 60 | Energy saving control selection | 60 | Energy saving control selection | 60 | Energy saving control selection |
| Automatic acceleration /deceleration | – | – | 61 | Reference current | 61 | Reference current |
| | | | 62 | Reference value at acceleration | 62 | Reference value at acceleration |
| | | | 63 | Reference value at deceleration | 63 | Reference value at deceleration |
| | | | 64 | Starting frequency for elevator mode | – | – |
| – | 65 | Retry selection | 65 | Retry selection | 65 | Retry selection |
| – | 66 | Stall prevention operation reduction starting frequency | 66 | Stall prevention operation reduction starting frequency | 66 | Stall prevention operation reduction starting frequency |
| Retry | 67 | Number of retries at alarm occurrence | 67 | Number of retries at alarm occurrence | 67 | Number of retries at fault occurrence |
| | 68 | Retry waiting time | 68 | Retry waiting time | 68 | Retry waiting time |
| | 69 | Retry count display erase | 69 | Retry count display erase | 69 | Retry count display erase |
| – | 70 | Special regenerative brake duty | 70 | Special regenerative brake duty | 70 | Special regenerative brake duty |
| – | 71 | Applied motor | 71 | Applied motor | 71 | Applied motor |
| – | 72 | PWM frequency selection | 72 | PWM frequency selection | 72 | PWM frequency selection |
| – | 73 | Analog input selection | 73 | Analog input selection | 73 | Analog input selection |
| – | 74 | Input filter time constant | 74 | Input filter time constant | 74 | Input filter time constant |
| – | 75 | Reset selection/disconnected PU detection/PU stop selection | 75 | Reset selection/disconnected PU detection/PU stop selection | 75 | Reset selection/disconnected PU detection/PU stop selection |
| – | 76 | Alarm code output selection | 76 | Alarm code output selection | – | – |
| – | 77 | Parameter write selection | 77 | Parameter write selection | 77 | Parameter write selection |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RSRS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| Function | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|-------------------------------------|---------------------|--|---------------------|---|---------------------|--|
| | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| – | 78 | Reverse rotation prevention selection | 78 | Reverse rotation prevention selection | 78 | Reverse rotation prevention selection |
| – | 79 | Operation mode selection | 79 | Operation mode selection | 79 | Operation mode selection |
| Simple magnetic flux vector control | 80 | Motor capacity (simple magnetic flux vector control) | 80 | Motor capacity | 80 | Motor capacity |
| | – | – | 81 | Number of motor poles | 81 | Number of motor poles |
| | | | 82 | Motor excitation current | 82 | Motor excitation current |
| | | | 83 | Motor rated voltage | 83 | Motor rated voltage |
| | | | 84 | Rated motor frequency | 84 | Rated motor frequency |
| | | | 89 | Speed control gain (magnetic flux vector) | 89 | Speed control gain (advanced magnetic flux vector) |
| – | 90 | Motor constant (R1) | 90 | Motor constant (R1) | 90 | Motor constant (R1) |
| | – | – | 91 | Motor constant (R2) | 91 | Motor constant (R2) |
| | | | 92 | Motor constant (L1) | 92 | Motor constant (L1) |
| | | | 93 | Motor constant (L2) | 93 | Motor constant (L2) |
| | | | 94 | Motor constant (X) | 94 | Motor constant (X) |
| | | | 95 | Online auto tuning selection | – | – |
| Adjustable 5 points V/F | – | – | 96 | Auto tuning setting/status | 96 | Auto tuning setting/status |
| | | | 100 | V/F1 (first frequency) | – | – |
| | | | 101 | V/F1 (first frequency voltage) | | |
| | | | 102 | V/F2 (second frequency) | | |
| | | | 103 | V/F1 (first frequency) | | |
| | | | 104 | V/F3 (third frequency) | | |
| | | | 105 | V/F3 (third frequency voltage) | | |
| | | | 106 | V/F4 (fourth frequency) | | |
| | | | 107 | V/F4 (fourth frequency voltage) | | |
| | | | 108 | V/F5 (fifth frequency) | | |
| | | | 109 | V/F5 (fifth frequency voltage) | | |
| Third functions | – | – | 110 | Third acceleration/deceleration time | – | – |
| | | | 111 | Third deceleration time | | |
| | | | 112 | Third torque boost | | |
| | | | 113 | Third V/F (base frequency) | | |
| | | | 114 | Third stall prevention operation current | | |
| | | | 115 | Third stall prevention operation frequency | | |
| | | | 116 | Third output frequency detection | | |
| PU connector communication | 117 | PU communication station | 117 | PU communication station number | 117 | PU communication station number |
| | 118 | PU communication speed | 118 | PU communication speed | 118 | PU communication speed |
| | 119 | PU communication stop bit length. | 119 | PU communication stop bit length | 119 | PU communication stop bit length |
| | 120 | PU communication parity check | 120 | PU communication parity check | 120 | PU communication parity check |
| | 121 | Number of PU communication retries | 121 | Number of PU communication retries | 121 | Number of PU communication retries |
| | 122 | PU communication check time interval | 122 | PU communication check time interval | 122 | PU communication check time interval |
| | 123 | PU communication waiting time setting | 123 | PU communication waiting time setting | 123 | PU communication waiting time setting |
| PU connector communication | 124 | PU communication CR/LF presence/absence selection | 124 | PU communication CR/LF presence/absence selection | 124 | PU communication CR/LF selection |

| FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|--|--------|---|--------|--|--------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. |
| – | 125 | Terminal 2 frequency setting gain frequency | 125 | Terminal 2 frequency setting gain frequency | 125 |
| – | 126 | Terminal 4 frequency setting gain frequency | 126 | Terminal 4 frequency setting gain frequency | 126 |
| PID operation | 127 | PID control automatic switchover frequency | 127 | PID control automatic switchover frequency | 127 |
| | 128 | PID action selection | 128 | PID action selection | 128 |
| | 129 | PID proportional band | 129 | PID proportional band | 129 |
| | 130 | PID integral time | 130 | PID integral time | 130 |
| | 131 | PID maximum | 131 | PID upper limit | 131 |
| | 132 | PID minimum | 132 | PID lower limit | 132 |
| | 133 | PID action set point | 133 | PID action set point | 133 |
| | 134 | PID differential time | 134 | PID differential time | 134 |
| Commercial power supply-inverter switch-over | 135 | Commercial power-supply switchover sequence output terminal selection | 135 | Electronic bypass sequence selection | – |
| | 136 | MC switchover interlock time | 136 | MC switchover interlock time | |
| | 137 | Waiting time at a start | 137 | Start waiting time | |
| | 138 | Commercial power-supply operation switchover selection at an alarm | 138 | Bypass selection at an alarm | |
| | 139 | Automatic switchover frequency between inverter and commercial power-supply operation | 139 | Automatic switchover frequency from inverter to bypass operation | |
| Backlash measures | 140 | Backlash acceleration stopping frequency | 140 | Backlash acceleration stopping frequency | |
| | 141 | Backlash acceleration stopping time | 141 | Backlash acceleration stopping time | |
| | 142 | Backlash deceleration stopping frequency | 142 | Backlash deceleration stopping frequency | |
| | 143 | Backlash deceleration stopping time | 143 | Backlash deceleration stopping time | |
| – | 144 | Speed setting switchover | 144 | Speed setting switchover | |
| PU | 145 | PU display language selection | 145 | PU display language selection | 145 |
| – | – | – | – | – | 146 |
| Current detection | 148 | Stall prevention level at 0V input. | 148 | Stall prevention level at 0V input | – |
| | 149 | Stall prevention level at 10V input. | 149 | Stall prevention level at 10V input | |
| | 150 | Output current detection level | 150 | Output current detection level | 150 |
| | 151 | Output current detection signal delay time | 151 | Output current detection signal delay time | 151 |
| | 152 | Zero current detection level | 152 | Zero current detection level | 152 |
| | 153 | Zero current detection time | 153 | Zero current detection time | 153 |
| – | 154 | Voltage reduction selection during stall prevention operation | 154 | Voltage reduction selection during stall prevention operation | – |
| – | 155 | RT signal reflection time selection | 155 | RT signal function validity condition selection | |
| – | 156 | Stall prevention operation selection | 156 | Stall prevention operation selection | 156 |
| – | 157 | OL signal output timer | 157 | OL signal output timer | 157 |
| – | 158 | AM terminal function selection | 158 | AM terminal function selection | – |
| – | 159 | Automatic switchover ON range between commercial power-supply and inverter operation | 159 | Automatic switchover frequency range from bypass to inverter operation | |
| – | 160 | User group read selection | 160 | User group read selection | 160 |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS485 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|-------------------------------------|--------|---|--------|---|--------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. |
| – | 161 | Frequency setting/key lock operation selection | 161 | Frequency setting/key lock operation selection | 161 |
| Automatic restart functions | 162 | Automatic restart after instantaneous power failure selection | 162 | Automatic restart after instantaneous power failure selection | 162 |
| | 163 | First cushion time for restart | 163 | First cushion time for restart | – |
| | 164 | First cushion voltage for restart | 164 | First cushion voltage for restart | – |
| | 165 | Stall prevention operation level for restart | 165 | Stall prevention operation level for restart | 165 |
| Current detection | 166 | Output current detection signal retention time | 166 | Output current detection signal retention time | – |
| | 167 | Output current detection operation selection | 167 | Output current detection operation selection | – |
| Cumulative monitor clear | 170 | Cumulative power meter clear | 170 | Watt-hour meter clear | 170 |
| | 171 | Operation hour meter clear | 171 | Operation hour meter clear | 171 |
| User group | 172 | User group registered display/batch clear | 172 | User group registered display/batch clear | 172 |
| | 173 | User group registration | 173 | User group registration | 173 |
| | 174 | User group clear | 174 | User group clear | 174 |
| Input terminal function assignment | 178 | STF terminal function selection | 178 | STF terminal function selection | 178 |
| | 179 | STR terminal function selection | 179 | STR terminal function selection | 179 |
| | 180 | RL terminal function selection | 180 | RL terminal function selection | 180 |
| | 181 | RM terminal function selection | 181 | RM terminal function selection | 181 |
| | 182 | RH terminal function selection | 182 | RH terminal function selection | 182 |
| | 183 | RT terminal function selection | 183 | RT terminal function selection | 183 |
| | 184 | AU terminal function selection | 184 | AU terminal function selection | 184 |
| | 185 | JOG terminal function selection | 185 | JOG terminal function selection | – |
| | 186 | CS terminal function selection | 186 | CS terminal function selection | |
| | 187 | MRS terminal function selection | 187 | MRS terminal function selection | |
| | 188 | STOP terminal function selection | 188 | STOP terminal function selection | |
| | 189 | RES terminal function selection | 189 | RES terminal function selection | |
| Output terminal function assignment | 190 | RUN terminal function selection | 190 | RUN terminal function selection | 190 |
| | 191 | SU terminal function selection | 191 | SU terminal function selection | 191 |
| | 192 | IPF terminal function selection | 192 | IPF terminal function selection | 192 |
| | 193 | OL terminal function selection | 193 | OL terminal function selection | – |
| | 194 | FU terminal function selection | 194 | FU terminal function selection | |
| | 195 | ABC1 terminal function selection | 195 | ABC1 terminal function selection | |
| | 196 | ABC2 terminal function selection | 196 | ABC2 terminal function selection | |
| Multi-speed setting | 232 | Multi-speed setting (speeds 8) | 232 | Multi-speed setting (speed 8) | 232 |
| | 233 | Multi-speed setting (speeds 9) | 233 | Multi-speed setting (speed 9) | 233 |
| | 234 | Multi-speed setting (speeds 10) | 234 | Multi-speed setting (speed 10) | 234 |
| | 235 | Multi-speed setting (speeds 11) | 235 | Multi-speed setting (speed 11) | 235 |
| | 236 | Multi-speed setting (speeds 12) | 236 | Multi-speed setting (speed 12) | 236 |
| | 237 | Multi-speed setting (speeds 13) | 237 | Multi-speed setting (speed 13) | 237 |
| Multi-speed setting | 238 | Multi-speed setting (speeds 14) | 238 | Multi-speed setting (speed 14) | 238 |
| | 239 | Multi-speed setting (speeds 15) | 239 | Multi-speed setting (speed 15) | 239 |
| – | 240 | Soft-PWM operation selection | 240 | Soft-PWM operation selection | 240 |
| – | 241 | Analog input display unit switchover | 241 | Analog input display unit switchover | 241 |
| – | 242 | Terminal 1 added compensation amount (terminal 2) | 242 | Terminal 1 added compensation amount (terminal 2) | – |
| – | 243 | Terminal 1 added compensation amount (terminal 4) | 243 | Terminal 1 added compensation amount (terminal 4) | |

| | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|--|---------------------|--|---------------------|--|---------------------|---|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| – | 244 | Cooling fan operation selection | 244 | Cooling fan operation selection | 244 | Cooling fan operation selection |
| Slip compensation | 245 | Rated slip | 245 | Rated slip | 245 | Rated slip |
| | 246 | Slip compensation time constant | 246 | Slip compensation time constant | 246 | Slip compensation time constant |
| | 247 | Constant-power region slip compensation selection | 247 | Constant-power region slip compensation selection | 247 | Constant-power region slip compensation selection |
| – | – | – | – | – | 249 | Earth (ground) fault detection at start |
| – | 250 | Stop selection | 250 | Stop selection | 250 | Stop selection |
| – | 251 | Output phase failure protection selection | 251 | Output phase failure protection selection | 251 | Output phase loss protection selection |
| Frequency compensation function | 252 | Override bias | 252 | Override bias | – | – |
| | 253 | Override gain | 253 | Override gain | | |
| Life check | 255 | Life alarm status display | 255 | Life alarm status display | 255 | Life alarm status display |
| | 256 | Inrush current limit circuit life display | 256 | Inrush current limit circuit life display | 256 | Inrush current limit circuit life display |
| | 257 | Control circuit capacitor life display | 257 | Control circuit capacitor life display | 257 | Control circuit capacitor life display |
| | 258 | Main circuit capacitor life display | 258 | Main circuit capacitor life display | 258 | Main circuit capacitor life display |
| | 259 | Main circuit capacitor life measuring | 259 | Main circuit capacitor life measuring | 259 | Main circuit capacitor life measuring |
| – | 260 | PWM frequency automatic switchover | – | – | – | – |
| Power failure stop | 261 | Power failure stop selection | 261 | Power failure stop selection | 261 | Power failure stop selection |
| | 262 | Subtracted frequency at deceleration start | 262 | Subtracted frequency at deceleration start | – | – |
| | 263 | Subtraction starting frequency | 263 | Subtraction starting frequency | | |
| | 264 | Power–failure deceleration time 1 | 264 | Power-failure deceleration time 1 | | |
| | 265 | Power–failure deceleration time 2 | 265 | Power-failure deceleration time 2 | | |
| | 266 | Power failure deceleration time switchover frequency | 266 | Power failure deceleration time switchover frequency | | |
| – | 267 | Terminal 4 input selection | 267 | Terminal 4 input selection | 267 | Terminal 4 input selection |
| – | 268 | Monitor decimal digits selection | 268 | Monitor decimal digits selection | 268 | Monitor decimal digits selection |
| – | – | – | 270 | Stop-on contact/load torque high speed frequency control selection | 270 | Stop-on contact control selection |
| Load torque high speed frequency control | | | 271 | High-speed setting maximum current | – | – |
| | | | 272 | Middle-speed setting minimum current | | |
| | | | 273 | Current averaging range | | |
| | | | 274 | Current averaging filter time constant | | |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RSRS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| FREQROL F700 Series | | | FREQROL A700 Series | | FREQROL E700 Series | |
|-------------------------|--------|--|---------------------|--|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Stop-on contact control | | | 275 | Stop-on contact excitation current lowspeed multiplying factor | 275 | Stop-on contact excitation current low-speed multiplying factor |
| | | | 276 | PWM carrier frequency at stop-on contact | 276 | PWM carrier frequency at stop-on contact |
| | | | – | – | 277 | Stall prevention operation current switchover |
| Brake sequence function | | | 278 | Brake opening frequency | 278 | Brake opening frequency |
| | | | 279 | Brake opening current | 279 | Brake opening current |
| | | | 280 | Brake opening current detection time | 280 | Brake opening current detection time |
| | | | 281 | Brake operation time at start | 281 | Brake operation time at start |
| | | | 282 | Brake operation frequency | 282 | Brake operation frequency |
| | | | 283 | Brake operation time at stop | 283 | Brake operation time at stop |
| | | | 284 | Deceleration detection function selection | – | – |
| | | | 285 | Overspeed detection frequency (Speed deviation excess detection frequency) | | |
| | | | 286 | Droop gain | 286 | Droop gain |
| | | | 287 | Droop filter time constant | 287 | Droop filter time constant |
| Droop control | | | 288 | Droop function activation selection | – | – |
| | | | 291 | Pulse train I/O selection | | |
| – | | | 292 | Automatic acceleration/ deceleration | 292 | Automatic acceleration/ deceleration |
| – | | | 293 | Acceleration/deceleration separate selection | 293 | Acceleration/deceleration separate selection |
| – | | | 294 | UV avoidance voltage gain | – | – |
| – | | | – | – | 295 | Magnitude of frequency change setting |
| – | | | – | – | 298 | Frequency search gain |
| – | 299 | Rotation direction detection selection at restarting | 299 | Rotation direction detection selection at restarting | 299 | Rotation direction detection selection at restarting |
| Digital input | 300 | BCD input bias | | | 300 | BCD input bias |
| | 301 | BCD input gain | | | 301 | BCD input gain |
| | 302 | BIN input bias | | | 302 | BIN input bias |
| | 303 | BIN input gain | | | 303 | BIN input gain |
| | 304 | Digital input and analog input compensation enable/disable selection | | | 304 | Digital input and analog input compensation enable/disable selection |
| | 305 | Read timing operation selection | | | 305 | Read timing operation selection |
| Analog output | 306 | Analog output signal selection | – | – | 306 | Analog output signal selection |
| | 307 | Setting for zero analog output | | | 307 | Setting for zero analog output |
| | 308 | Setting for maximum analog output | | | 308 | Setting for maximum analog output |
| | 309 | Analog output signal voltage/ current switchover | | | 309 | Analog output signal voltage/ current switchover |
| | 310 | Analog meter voltage output selection | | | 310 | Analog meter voltage output selection |
| | 311 | Setting for zero analog meter voltage output | | | 311 | Setting for zero analog meter voltage output |
| Analog output | 312 | Setting for maximum analog meter voltage output | | | 312 | Setting for maximum analog meter voltage output- |

| | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|--|---------------------|---|---------------------|---|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Digital output | 313 | DO0 output selection | - | - | 313 | DO0 output selection |
| | 314 | DO1 output selection | | | 314 | DO1 output selection |
| | 315 | DO2 output selection | | | 315 | DO2 output selection |
| | 316 | DO3 output selection | | | 316 | DO3 output selection |
| | 317 | DO4 output selection | | | 317 | DO4 output selection |
| | 318 | DO5 output selection | | | 318 | DO5 output selection |
| | 319 | DO6 output selection | | | 319 | DO6 output selection |
| Relay output | 320 | RA1 output selection | | | 320 | RA1 output selection |
| | 321 | RA2 output selection | | | 321 | RA2 output selection |
| | 322 | RA3 output selection | | | 322 | RA3 output selection |
| Analog output | 323 | AM0 0V adjustment | | | 323 | AM0 0V adjustment |
| | 324 | AM1 0mA adjustment | | | 324 | AM1 0mA adjustment |
| - | 329 | Digital input unit selection | | | 329 | Digital input unit selection |
| RS-485 communication | 331 | RS-485 communication station | 331 | RS-485 communication station number | - | - |
| | 332 | RS-485 communication speed | 332 | RS-485 communication speed | | |
| | 333 | RS-485 communication stop bit length | 333 | RS-485 communication stop bit length | | |
| | 334 | RS-485 communication parity check selection | 334 | RS-485 communication parity check selection | | |
| | 335 | RS-485 communication number of retries | 335 | RS-485 communication retry count | | |
| | 336 | RS-485 communication check time interval | 336 | RS-485 communication check time interval | | |
| | 337 | RS-485 communication waiting time setting | 337 | RS-485 communication waiting time setting | | |
| | 338 | Communication operation command source | 338 | Communication operation command source | 338 | Communication operation command source |
| | 339 | Communication speed command source | 339 | Communication speed command source | 339 | Communication speed command source |
| | 340 | Communication startup mode selection | 340 | Communication startup mode selection | 340 | Communication startup mode selection |
| | 341 | RS-485 communication CR/LF selection | 341 | RS-485 communication CR/LF selection | - | - |
| | 342 | Communication EEPROM write selection | 342 | Communication EEPROM write selection | 342 | Communication EEPROM write selection |
| | 343 | Communication error count | 343 | Communication error count | 343 | Communication error count |
| DeviceNet | 345 | DeviceNet address | - | - | - | - |
| | 346 | DeviceNet baud rate | | | | |
| CC-Link | 349 | Communication reset selection | | | | |
| S-pattern acceleration/ deceleration C | - | - | 380 | Acceleration S-pattern 1 | - | - |
| | | | 381 | Deceleration S-pattern 1 | | |
| | | | 382 | Acceleration S-pattern 2 | | |
| | | | 383 | Deceleration S-pattern 2 | | |
| Pulse train input | | | 384 | Input pulse division scaling factor | | |
| | | | 385 | Frequency for 0 input pulse | | |
| | | | 386 | Frequency for maximum input pulse | | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/R2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

| FREQROL F700 Series | | | FREQROL A700 Series | | FREQROL E700 Series | |
|--|--------|--|---------------------|--|---------------------|--|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| LONWORKS | 387 | Initial communication delay time | - | - | - | - |
| | 388 | Send time interval at heart beat | | | | |
| | 389 | Minimum sending time at heart beat | | | | |
| | 390 | % setting reference frequency | | | | |
| | 391 | Receive time interval at heart beat | | | | |
| | 392 | Event driven detection width | | | | |
| Second motor constants | - | - | 450 | Second applied motor | 450 | Second applied motor |
| | | | 451 | Second motor control method selection | - | - |
| | | | 453 | Second motor capacity | | |
| | | | 454 | Number of second motor poles | | |
| | | | 455 | Second motor excitation current | | |
| | | | 456 | Rated second motor voltage | | |
| | | | 457 | Rated second motor frequency | | |
| | | | 458 | Second motor constant (R1) | | |
| | | | 459 | Second motor constant (R2) | | |
| | | | 460 | Second motor constant (L1) | | |
| | | | 461 | Second motor constant (L2) | | |
| | | | 462 | Second motor constant (X) | | |
| | | | 463 | Second motor auto tuning setting/status | | |
| Remote output | 495 | Remote output selection | 495 | Remote output selection | 495 | Remote output selection |
| | 496 | Remote output data 1 | 496 | Remote output data 1 | 496 | Remote output data 1 |
| | 497 | Remote output data 2 | 497 | Remote output data 2 | 497 | Remote output data 2 |
| Communication error | 500 | Communication error execution waiting time | - | - | 500 | Communication error execution waiting time |
| | 501 | Communication error occurrence count display | | | 501 | Communication error occurrence count display |
| | 502 | Stop mode selection at communication error | | | 502 | Stop mode selection at communication error |
| Maintenance | 503 | Maintenance timer | 503 | Maintenance timer | 503 | Maintenance timer |
| | 504 | Maintenance timer alarm output set time | 504 | Maintenance timer alarm output set time | 504 | Maintenance timer alarm output set time |
| S-pattern acceleration/ deceleration D | - | - | 516 | S-pattern time at a start of acceleration | - | - |
| | | | 517 | S-pattern time at a completion of acceleration | | |
| | | | 518 | S-pattern time at a start of deceleration | | |
| | | | 519 | S-pattern time at a completion of deceleration | | |
| CC-Link | - | - | - | - | 541 | Frequency command sign selection (CC-Link) |
| | | | | | 542 | Communication station number (CC-Link) |
| | | | | | 543 | Baud rate selection (CC-Link) |
| | | | | | 544 | CC-Link extended setting |
| USB | - | - | 547 | USB communication station number | 547 | USB communication station number |
| | | | 548 | USB communication check time interval | 548 | USB communication check time interval |

| FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|-------------------------|--------|---|--------|---|--------|
| Function | Pr No. | Name | Pr No. | Name | Pr No. |
| Communica- tion | 549 | Protocol selection | 549 | Protocol selection | 549 |
| | 550 | NET mode operation command source selection | 550 | NET mode operation command source selection | 550 |
| | 551 | PU mode operation command source selection | 551 | PU mode operation command source selection | 551 |
| Current average monitor | 555 | Current average time | 555 | Current average time | 555 |
| | 556 | Data output mask time | 556 | Data output mask time | 556 |
| | 557 | Current average value monitor signal output reference current | 557 | Current average value monitor signal output reference current | 557 |
| – | 563 | Energization time carrying-over times | 563 | Energization time carrying-over times | 563 |
| – | 564 | Operating time carrying-over times | 564 | Operating time carrying-over times | 564 |
| – | – | – | 569 | Second motor speed control gain | – |
| – | 571 | Holding time at a start | 571 | Holding time at a start | 571 |
| – | – | – | 574 | Second motor online auto tuning | – |
| PID control | 575 | Output interruption detection time | 575 | Output interruption detection time | – |
| | 576 | Output interruption detection level | 576 | Output interruption detection level | – |
| | 577 | Output interruption release level | 577 | Output interruption cancel level | – |
| – | 611 | Acceleration time at a restart | 611 | Acceleration time at a restart | 611 |
| – | – | – | – | – | 653 |
| – | – | – | – | – | 665 |
| – | – | – | – | – | – |
| – | – | – | – | – | – |
| Torque command | – | – | 684 | Tuning data unit switchover | – |
| | – | – | 800 | Control method selection | 800 |
| | – | – | 803 | Constant power range torque characteristic selection | – |
| Speed limit | – | – | 804 | Torque command source selection | – |
| | – | – | 805 | Torque command value (RAM) | – |
| | – | – | 806 | Torque command value (RAM,EEPROM) | – |
| Torque limit | – | – | 807 | Speed limit selection | – |
| | – | – | 808 | Forward rotation speed limit | – |
| | – | – | 809 | Reverse rotation speed limit | – |
| Easy gain tuning | – | – | 810 | Torque limit input method selection | – |
| | – | – | 811 | Set resolution switchover | – |
| | – | – | 812 | Torque limit level (regeneration) | – |
| | – | – | 813 | Torque limit level (3rd quadrant) | – |
| | – | – | 814 | Torque limit level (4th quadrant) | – |
| | – | – | 815 | Torque limit level 2 | – |
| | – | – | 816 | Torque limit level during acceleration | – |
| | – | – | 817 | Torque limit level during deceleration | – |
| | – | – | 818 | Easy gain tuning response level setting | – |
| | – | – | 819 | Easy gain tuning selection | – |
| | – | – | – | – | – |

| | |
|-------------|--|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RSRS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

| | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|---------------------------------|---------------------|--|--|--|---------------------|---|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Adjustment function | - | - | 820 | Speed control P gain 1 | - | - |
| | | | 821 | Speed control integral time 1 | | |
| | | | 822 | Speed setting filter 1 | | |
| | | | 824 | Torque control P gain 1 | | |
| | | | 825 | Torque control integral time 1 | | |
| | | | 826 | Torque setting filter 1 | | |
| | | | 827 | Torque detection filter 1 | | |
| | | | 828 | Model speed control gain | | |
| | | | 830 | Speed control P gain 2 | | |
| | | | 831 | Speed control integral time 2 | | |
| | | | 832 | Speed setting filter2 | | |
| | | | 834 | Torque control P gain 2 | | |
| | | | 835 | Torque control integral time 2 | | |
| | | | 836 | Torque setting filter2 | | |
| | | | 837 | Torque detection filter 2 | | |
| | | | Torque bias | 849 | | |
| 850 | | | | Control operation selection | | |
| 858 | | | | Terminal 4 function assignment | | |
| 859 | | | | Torque current | 859 | Torque current |
| | | | 860 | Second motor torque current | - | - |
| | 862 | Notch filter time constant | | | | |
| | 863 | Notch filter depth | | | | |
| | 864 | Torque detection | | | | |
| Indication function | 865 | Low speed detection | - | - | | |
| | 866 | Torque monitoring reference | | | | |
| - | 867 | AM output filter | 867 | AM output filter | - | - |
| - | - | - | 868 | Terminal 1 function assignment | | |
| Protective Functions | 872 | Input phase failure protection selection | 872 | Input phase failure protection selection | 872 | Input phase loss protection selection |
| | - | - | 874 | OLT level setting | - | - |
| 875 | | | Fault definition | | | |
| 877 | | | Speed feed forward control/ model adaptive speed control selection | | | |
| 878 | | | Speed feed forward filter | | | |
| 879 | | | Speed feed forward torque limit | | | |
| 880 | | | Load inertia ratio | | | |
| Control system functions | 881 | Speed feed forward gain | - | - | | |
| | | | | | | |
| Regeneration avoidance function | 882 | Regeneration avoidance operation selection | 882 | Regeneration avoidance operation selection | 882 | Regeneration avoidance operation selection |
| | 883 | Regeneration avoidance operation level | 883 | Regeneration avoidance operation level | 883 | Regeneration avoidance operation level |
| | 884 | Regeneration avoidance at deceleration detection sensitivity | 884 | Regeneration avoidance at deceleration detection sensitivity | - | - |
| | 885 | Regeneration avoidance compensation frequency limit value | 885 | Regeneration avoidance compensation frequency limit value | 885 | Regeneration avoidance compensation frequency limit value |
| | 886 | Regeneration avoidance voltage gain | 886 | Regeneration avoidance voltage gain | 886 | Regeneration avoidance voltage gain |
| Free parameter | 888 | Free parameter 1 | 888 | Free parameter 1 | 888 | Free parameter 1 |
| | 889 | Free parameter 2 | 889 | Free parameter 2 | 889 | Free parameter 2 |

| | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|------------------------|---------------------|--|---------------------|--|---------------------|---|
| Function | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Energy saving monitor | 891 | Cumulative power monitor digit shifted times | 891 | Cumulative power monitor digit shifted times | - | - |
| | 892 | Load factor | 892 | Load factor | | |
| | 893 | Energy saving monitor reference (motor capacity) | 893 | Energy saving monitor reference (motor capacity) | | |
| | 894 | Control selection during commercial power-supply operation | 894 | Control selection during commercial power-supply operation | | |
| | 895 | Power saving rate reference value | 895 | Power saving rate reference value | | |
| | 896 | Power unit cost | 896 | Power unit cost | | |
| | 897 | Power saving monitor average time | 897 | Power saving monitor average time | | |
| | 898 | Power saving cumulative monitor clear | 898 | Power saving cumulative monitor clear | | |
| | 899 | Operation time rate (estimated value) | 899 | Operation time rate (estimated value) | | |
| Calibration parameters | C0 (900) | FM terminal calibration | C0 (900) | FM terminal calibration | C0 (900) | FM terminal calibration |
| | C1 (901) | AM terminal calibration | C1 (901) | AM terminal calibration | - | - |
| | C2 (902) | Terminal 2 frequency setting bias frequency | C2 (902) | Terminal 2 frequency setting bias frequency | C2 (902) | Terminal 2 frequency setting bias frequency |
| | C3 (902) | Terminal 2 frequency setting bias | C3 (902) | Terminal 2 frequency setting bias | C3 (902) | Terminal 2 frequency setting bias |
| | 125 (903) | Terminal 2 frequency setting gain frequency | 125 (903) | Terminal 2 frequency setting gain frequency | 125 (903) | Terminal 2 frequency setting gain frequency |
| | C4 (904) | Terminal 2 frequency setting gain | C4 (904) | Terminal 2 frequency setting gain | C4 (904) | Terminal 2 frequency setting gain |
| | C5 (904) | Terminal 4 frequency setting bias frequency | C5 (904) | Terminal 4 frequency setting bias frequency | C5 (904) | Terminal 4 frequency setting bias frequency |
| | C6 (904) | Terminal 4 frequency setting bias | C6 (904) | Terminal 4 frequency setting bias | C6 (904) | Terminal 4 frequency setting bias |
| | 126 (905) | Terminal 4 frequency setting gain frequency | 126 (905) | Terminal 4 frequency setting gain frequency | 126 (905) | Terminal 4 frequency setting gain frequency |
| | C7 (905) | Terminal 4 frequency setting gain | C7 (905) | Terminal 4 frequency setting gain | C7 (905) | Terminal 4 frequency setting gain |
| | - | - | C12 (917) | Terminal 1 bias frequency (speed) | - | - |
| | | | C13 (917) | Terminal 1 bias (speed) | | |
| | | | C14 (918) | Terminal 1 gain frequency (speed) | | |
| | | | C15 (918) | Terminal 1 gain (speed) | | |
| | | | C16 (919) | Terminal 1 bias command (torque/magnetic flux) | | |
| | | | C17 (919) | Terminal 1 bias (torque/magnetic flux) | | |
| | | | C18 (920) | Terminal 1 gain command (torque/magnetic flux) | | |
| | | | C19 (920) | Terminal 1 gain (torque/magnetic flux) | | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

| Function | FREQROL F700 Series | | FREQROL A700 Series | | FREQROL E700 Series | |
|------------------------|---------------------|------------------------------|---------------------|--|---------------------|---|
| | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Calibration parameters | - | - | - | - | C22 (922) | Frequency setting voltage bias frequency (built-in potentiometer) |
| | | | | | C23 (922) | Frequency setting voltage bias (built-in potentiometer) |
| | | | | | C24 (923) | Frequency setting voltage gain frequency (built-in potentiometer) |
| | | | | | C25 (923) | Frequency setting voltage gain (built-in potentiometer) |
| | | | C38 (932) | Terminal 4 bias command (torque/magnetic flux) | - | - |
| | | | C39 (932) | Terminal 4 bias (torque/magnetic flux) | | |
| | | | C40 (933) | Terminal 4 gain command (torque/magnetic flux) | | |
| | | | C41 (933) | Terminal 4 gain (torque/magnetic flux) | | |
| - | 989 | Parameter copy alarm release | - | - | | |
| PU | 990 | PU buzzer control | 990 | PU buzzer control | 990 | PU buzzer control |
| | 991 | PU contrast adjustment | 991 | PU contrast adjustment | 991 | PU contrast adjustment |

12.5.3 Communication parameters

The table below shows the parameters corresponding to each communication port.

- The PU port is common in the V500, F500, A500, and E500 Series.
- In the F700, and A700 Series, communication parameters for the built-in RS-485 terminal are provided.
- In the V500, F500, and A500 Series, communication parameters for the FR-A5NR computer link are provided.
- In the E500, and E700 Series, only the PU port is provided.
- In the S500 Series containing RS-485 communication, the following parameters are applicable.

| Function | FREQROL V500, F500, A500 and E500 Series (PU port) | | FREQROL E700 Series (PU port) | | FREQROL F700 and A700 Series (Built-in RS-485 terminal) | | FREQROL V500, F500 and A500 Series (FR-A5NR computer link) | | FREQROL S500 Series (Built-in port in accordance with RS-485) | |
|--------------------|--|-----------------------------------|-------------------------------|---|---|---|--|-------------------------------------|---|--|
| | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name | Pr No. | Name |
| Communication type | 117 | Communication station number | 117 | PU communication station number | 331 | RS-485 communication station | 331 | Communication station number | n1 331 | Communication station number |
| | 118 | Communication speed | 118 | PU communication speed | 332 | RS-485 communication speed | 332 | Communication speed | n2 332 | Communication speed |
| | 119 | Stop bit length/Data length | 119 | PU communication stop bit length | 333 | RS-485 communication stop bit length | 333 | Stop bit length/Data length | n3 333 | Stop bit length/Data length |
| | 120 | Parity check presence/absence | 120 | PU communication parity check | 334 | RS-485 communication parity check selection | 334 | Parity check presence/absence | n4 334 | Parity check presence/absence |
| | 121 | Number of communication retries | 121 | Number of PU communication retries | 335 | RS-485 communication number of retries | 335 | Number of communication retries | n5 335 | Number of times of communication retries |
| | 122 | Communication check time interval | 122 | PU communication check time interval | 336 | RS-485 communication check time interval | 336 | Communication check time interval | n6 336 | Communication check time interval |
| | 123 | Waiting time setting | 123 | PU communication waiting time setting | 337 | RS-485 communication waiting time setting | 337 | Waiting time setting | n7 337 | Waiting time setting |
| | - | - | 338 | Communication operation command source | 338 | Communication operation command source | 338 | Operation command right | n8 338 | Operation command right |
| | - | - | 339 | Communication frequency command source | 339 | Communication speed command source | 339 | Speed command write | n9 339 | Speed command right |
| | - | - | 340 | Communication startup mode selection | 340 | Communication startup mode selection | 340 | Link startup mode selection | n10 340 | Link startup mode selection |
| | 124 | CR, LF presence/absence selection | 124 | PU communication CR/LF presence/absence selection | 341 | RS-485 communication CR/LF selection | 341 | CR, LF presence/absence selection | n11 341 | Absence/presence of CR and LF |
| | - | - | 342 | Communication EEPROM write selection | 342 | Communication EEPROM write selection | 342 | E ² PROM write selection | n12 342 | E ² PROM write selection |
| | - | - | 549 | Protocol selection | 549 | Protocol selection | - | - | - | - |

MEMO

FX Series Programmable Controllers

User's Manual

[Non-Protocol Communication (RS/RS2 Instruction)]

Foreword

This manual explains "non-protocol communication" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit. Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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1. Outline

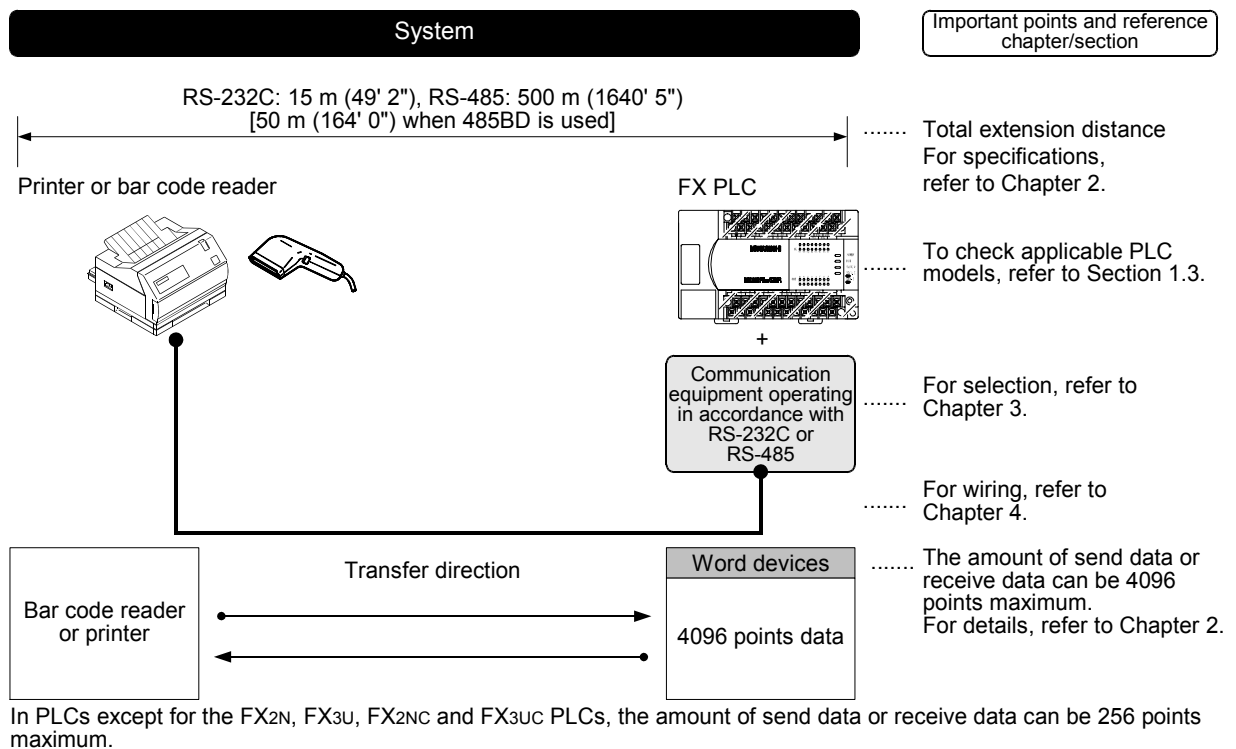
This chapter explains Non-protocol communication.

1.1 Outline of System

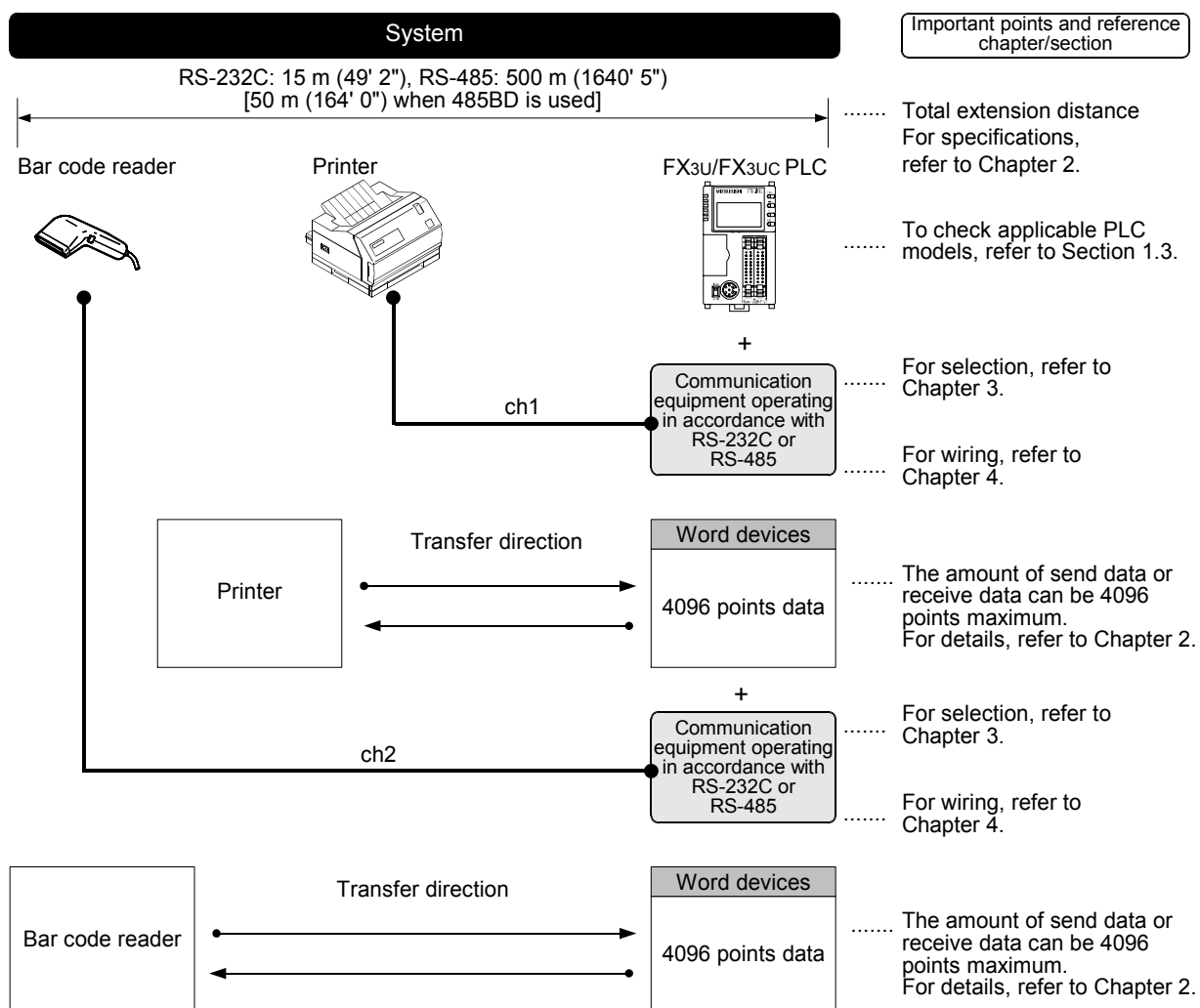
Non-protocol communication exchanges non-protocol data using a printer, bar code reader, etc. In FX Series PLCs, non-protocol communication is available using the RS and RS2 instructions. The RS2 instruction is dedicated to the FX3U and FX3UC PLCs, and allows communication using two channels at the same time when the channels are specified.

- 1) Up to 4096 points of data can be sent, and up to 4096 points of data can be received. However, make sure that the total number of sent and received data is 8000 points or less.
- 2) Data transfer is enabled when the connected equipment supports non-protocol serial communication.
- 3) The applicable total extension distance is 15m (49' 2") maximum in accordance with RS-232C communication, and 500m (1640' 5") maximum in accordance with RS-485 communication [50m (164' 0") when 485BD connection is used].

- RS instruction (FX2(FX), FX2C, FX0N, FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC)

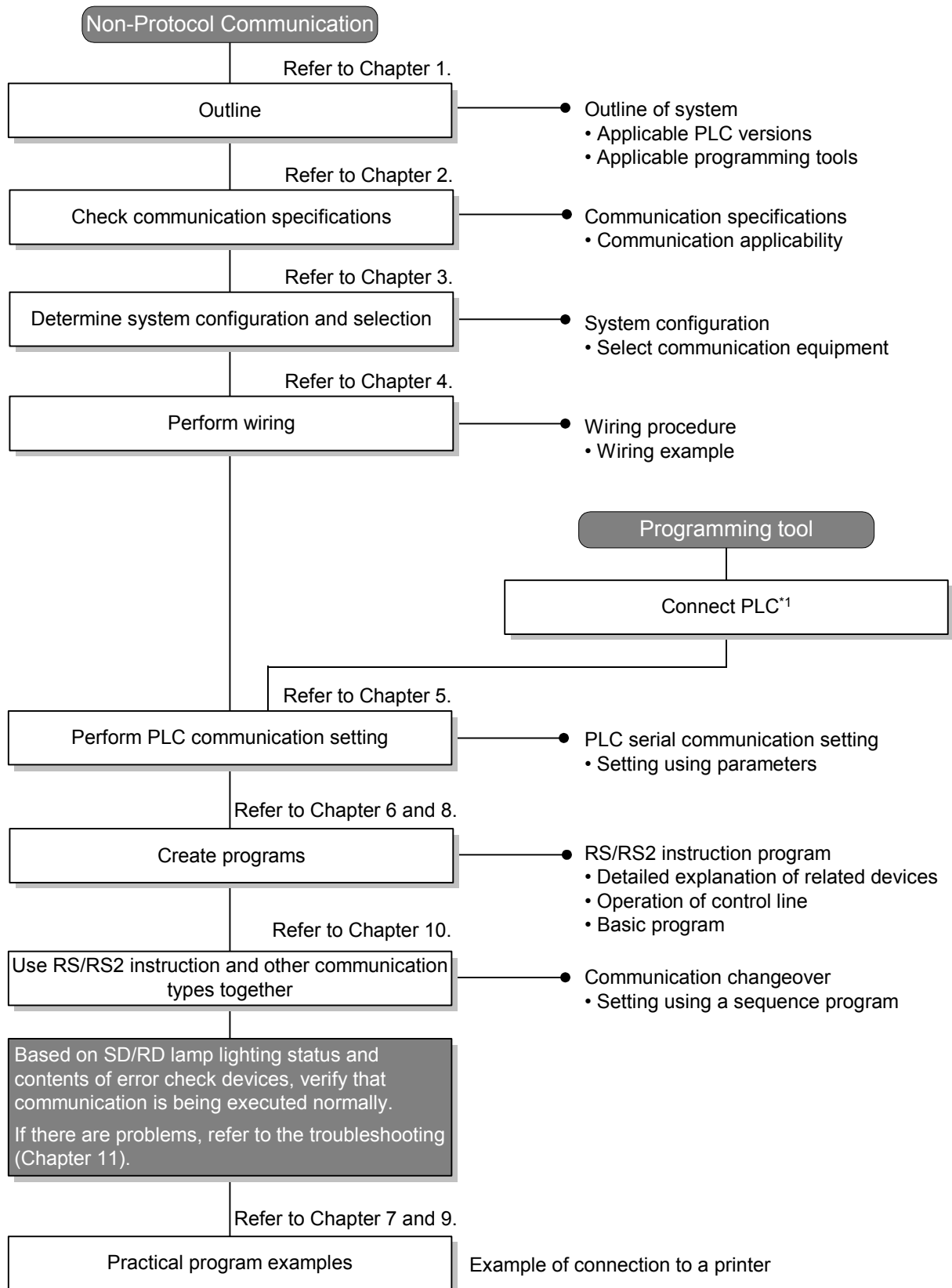


• RS2 instruction (FX3U and FX3UC)



1.2 Procedures Before Operation

The flow chart below shows the Non-Protocol Communication setting procedures up until data link:



*1 For the programming tool to PLC connection procedure, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operating procedures, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

The communication types are applicable in the following versions.

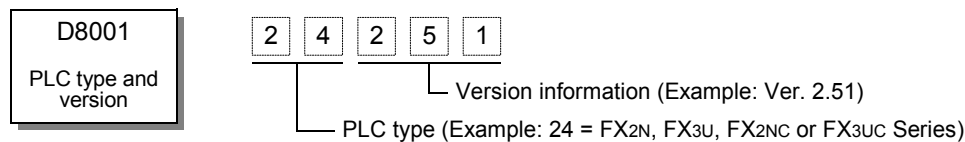
- ✓: Applicable (If applicable versions are limited, they are described inside ().)
- : Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|------------------------------------|--|
| FX3UC Series | ✓ | Full-duplex communication/half-duplex communication |
| FX3U Series | ✓ | Full-duplex communication/half-duplex communication |
| FX2NC Series | ✓ | Full-duplex communication/half-duplex communication |
| FX2N Series | ✓ (Ver. 1.06 or later) | Full-duplex communication (Ver. 2.00 or later)/half-duplex communication |
| FX1NC Series | ✓ | Half-duplex communication |
| FX1N Series | ✓ | Half-duplex communication |
| FX1S Series | ✓ | Half-duplex communication |
| FX0N Series | ✓ (Ver. 1.20 or later) | Half-duplex communication |
| FX0S Series | — | Non-protocol communication is not provided |
| FX0 Series | — | Non-protocol communication is not provided |
| FX2C Series | ✓ | Half-duplex communication |
| FX2(FX) Series | ✓ (Ver. 3.07 or later)*1 | Half-duplex communication |
| FX1 Series | — | Non-protocol communication is not provided |

*1. Applicable in products manufactured in January, 1994 (manufacturer's serial No.: 41****) and later.

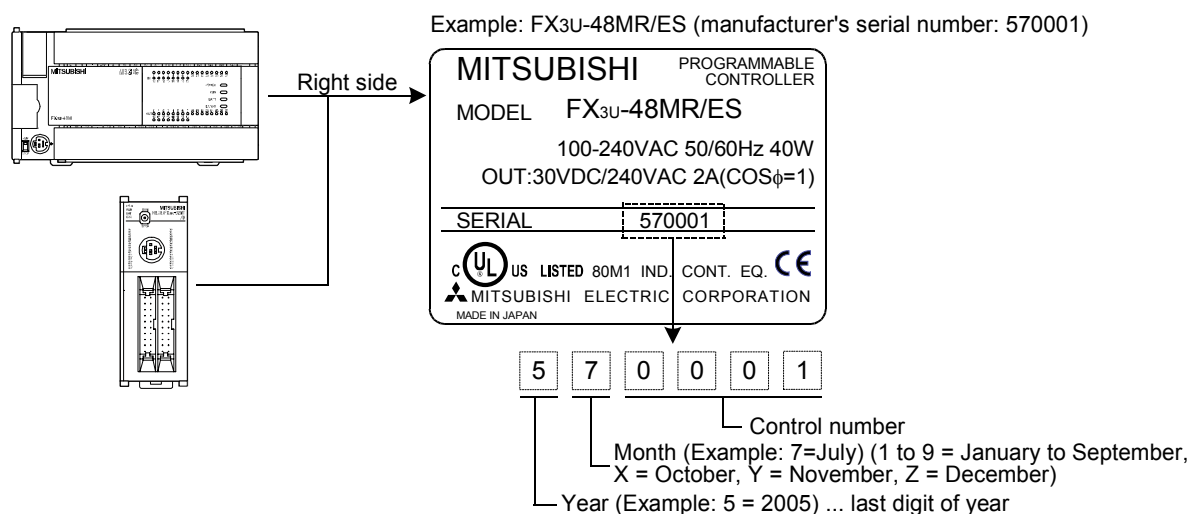
1. Version check

The D8001(decimal) special data register contains information for determining the PLC version.



2. How to look at the manufacturer's serial number

The year and month of production of product can be seen from the Manufacturer's serial number "SERIAL" indicated on the label adhered to the right side of the product.



1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description on system configuration, etc. in this manual for maintenance.

| PLC | Date when production was stopped | Remarks |
|----------------|----------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2c Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the version shown.

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.00 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXC | ✓ (Ver. 4.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column) | F940WGOT-TWD (Ver.1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver.1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver.1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver.1.00 or later) |

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 5.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXD | ✓ (Ver. 5.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column.) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver.8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXC-E | ✓ (Ver. 3.00 or later) | |
| FX-10P-E | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXD-E | ✓ (Ver. 4.00 or later) | |
| FX-10P-E | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |

1.4.2 For non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set. In this case, however, programming is enabled only in the ranges provided for the alternative PLC model such as instructions and program size.

| Model to be programmed | Model to be set | Priority: High → Low | | | |
|------------------------|-----------------|----------------------|---------|---|---------|
| FX3UC Series | FX3UC | → | FX2N | → | FX2(FX) |
| FX3U Series | FX3U, FX3UC | → | FX2N | → | FX2(FX) |
| FX2NC Series | FX2NC, FX2N | → | FX2(FX) | | |
| FX2N Series | FX2N | → | FX2(FX) | | |
| FX1NC Series | FX1NC, FX1N | → | FX2N | → | FX2(FX) |
| FX1N Series | FX1N | → | FX2N | → | FX2(FX) |
| FX1S Series | FX1S | → | FX2(FX) | | |
| FX0N Series | FX0N | → | FX2(FX) | | |
| FX0S Series | FX0S | → | FX2(FX) | | |
| FX0 Series | FX0 | → | FX2(FX) | | |
| FX2C Series | FX2C, FX2(FX) | → | FX2(FX) | | |
| FX2(FX) Series | FX2(FX) | → | FX2(FX) | | |
| FX1 Series | FX1 | | | | |

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Computer Link

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Non-Protocol Communication (RS/RS2 Instruction)

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Non-Protocol Communication (FX2N-232IF)

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Programming Communication

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Discontinued models

2. Specifications

This chapter explains the communication specifications and performance of non-protocol communication.

2.1 Communication Specifications (Reference)

Non-protocol communication is executed in the communication specifications shown in the table below.

| Item | Specifications | | Remarks |
|----------------------------------|--|--------------------------|--|
| Transmission standard | RS-485 or RS-422 standard | RS-232C standard | |
| Maximum total extension distance | 500 m (1640' 5") or less when using 485ADP 50 m (164' 0") or less when using 485BD — | 15 m (49' 2") or less | |
| FX3UC Series | | | |
| FX3U Series | | | |
| FX2NC Series | | | |
| FX2N Series | | | |
| FX1NC Series | | | |
| FX1N Series | | | |
| FX1S Series | | | |
| FX0N Series | | | |
| FX2C Series | | | |
| FX2(FX) Series | | | |
| Protocol type | — | | |
| Control procedure | Non-protocol communication | | |
| Communication method | Half-duplex, bidirectional communication/ full-duplex, bidirectional communication | | Method varies depending on FX Series. |
| Baud rate | 300, 600, 1200, 2400, 4800, 9600 or 19200 bps | | |
| Character format | | | These items are set using parameters or using D8120, D8400 or D8420. |
| Start bit | — | | |
| Data bit | 7 or 8-bit | | |
| Parity bit | None, odd or even | | |
| Stop bit | 1 or 2-bit | | |
| Header | Provided or not provided | | |
| Terminator | Provided or not provided | | |
| Control line | — | Provided or not provided | |
| Sum check | Provided or not provided | | Sum check is provided only with RS2 instruction. |

2.2 Data Communication Specifications

2.2.1 Communication type applicability in PLC

1. Full-duplex communication

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC Series | Applicability of communication in accordance with RS-485 (applicable version) | Applicability of communication in accordance with RS-232C (applicable version) |
|----------------|---|--|
| FX3UC Series | — | ✓ |
| FX3U Series | — | ✓ |
| FX2NC Series | — | ✓ |
| FX2N Series | ✓ (Ver. 2.00 or later)*1 | ✓ (Ver. 2.00 or later) |
| FX1NC Series | — | — |
| FX1N Series | — | — |
| FX1S Series | — | — |
| FX0N Series | — | — |
| FX0S Series | — | — |
| FX0 Series | — | — |
| FX2C Series | — | — |
| FX2(FX) Series | — | — |

*1. Only the 485BD is applicable.

2. Half-duplex communication

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC Series | Applicability of communication in accordance with RS-485 (applicable version) | Applicability of communication in accordance with RS-232C (applicable version) |
|----------------|---|--|
| FX3UC Series | ✓ | ✓ |
| FX3U Series | ✓ | ✓ |
| FX2NC Series | ✓ | ✓ |
| FX2N Series | ✓ (Ver. 1.06 or later) | ✓ (Ver. 1.06 or later) |
| FX1NC Series | ✓ | ✓ |
| FX1N Series | ✓ | ✓ |
| FX1S Series | ✓ | ✓ |
| FX0N Series | ✓ (Ver. 1.20 or later) | ✓ (Ver. 1.20 or later) |
| FX0S Series | — | — |
| FX0 Series | — | — |
| FX2C Series | — | ✓ |
| FX2(FX) Series | — | ✓ (Ver. 3.00 or later)*2 |

*2. Communication is applicable in products manufactured in November, 1994 (manufacturer's serial No.: 4Y****) and later.

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Common Items

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N:N Network

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Parallel Link

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Computer Link

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Inverter Communication

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Non-Protocol Communication (RS/RS2 Instruction)

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Non-Protocol Communication (FX2N-232IF)

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Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

2.3 Number of Transfer Data

| FX Series | Number of send/receive data | Remarks |
|----------------|-----------------------------|---|
| FX3UC Series | 0 to 4096 points | The total number of sent and received data should be 8000 points or less. |
| FX3U Series | 0 to 4096 points | |
| FX2NC Series | 0 to 4096 points | |
| FX2N Series | 0 to 4096 points | |
| FX1NC Series | 0 to 256 points | |
| FX1N Series | 0 to 256 points | |
| FX1S Series | 0 to 256 points | |
| FX0N Series | 0 to 256 points | |
| FX0S Series | — | |
| FX0 Series | — | |
| FX2C Series | 0 to 256 points | |
| FX2(FX) Series | 0 to 256 points | |

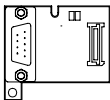
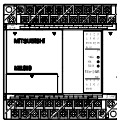
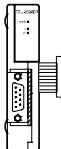
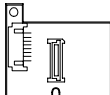
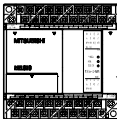
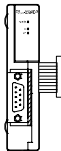
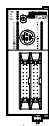
3. System Configuration and Selection

This chapter explains the system configuration and communication equipment selection operating in accordance with RS-485 or RS-232C required by FX PLCs.

3.1 System Configuration

This section outlines the system configuration required to use non-protocol communication. Connect (optional) equipment operating in accordance with RS-485 or RS-232C to the FX PLC main unit.

1, **2** and **3** indicate the communication equipment combination patterns.

| Communication equipment operating in accordance with RS-485 or RS-232C | FX PLC | Important point in selection | Total extension distance |
|--|---|---|--|
| <div>1</div> <div></div> <div>Communication board</div> | <div>+</div> <div></div> | <p>This is the communication board built into the PLC, reducing the installation area.</p> | <p>RS-485: 50 m (164' 0") RS-232C: 15 m (49' 2")</p> |
| <div>2</div> <div></div> <div>Communication adapter</div> | <div>+</div> <div></div> <div>Special adapter connection board</div> <div>+</div> <div></div> | <p>Attach the special adapter connection board to the main unit, and then attach the communication adapter to the left side of the main unit.</p> | <p>RS-485: 500 m (1640' 5") RS-232C: 15 m (49' 2")</p> |
| <div>3</div> <div></div> <div>Communication adapter</div> | <div>+</div> <div></div> | <p>Attach the communication adapter to the left side of the main unit.</p> | <p>RS-485: 500 m (1640' 5") RS-232C: 15 m (49' 2")</p> |



For communication equipment combinations for each FX Series, refer to the next page.

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Common Items

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N:N Network

C
Parallel Link

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Computer Link

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Inverter Communication

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Non-Protocol Communication (RS/RS2 Instruction)

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Non-Protocol Communication (FX2N-232IF)

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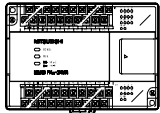
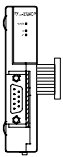
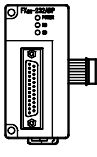

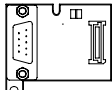
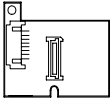
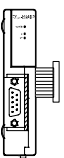
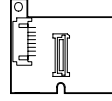
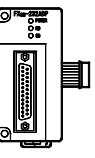

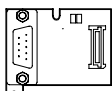
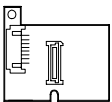
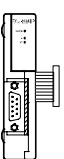
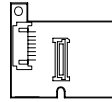
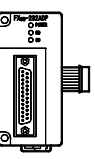
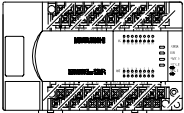
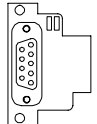
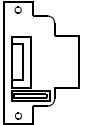
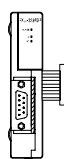
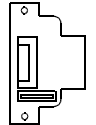
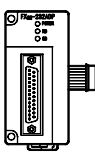
Apx.
Discontinued models

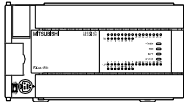
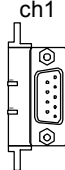

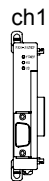




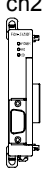
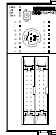
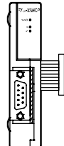
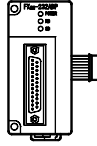
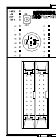
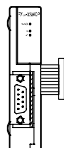
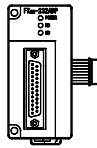
3.2 Applicable FX PLC and Communication Equipment

Select a communication equipment combination, and put a check mark in the "Check" column.
During selection, pay attention to the following:

- Non-protocol communication is not provided for the FX0, FX0S, FX1 Series.
- In the table below, only the external dimensions are different between the units shown in "FX2NC-485ADP/FX0N-485ADP". Select either one.

3.2.1 For communication in accordance with RS-232C

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|--|--------------------------|-------|
|  FX0N |  /  FX2NC-232ADP (9-pin D-Sub, male) / FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX1S |  FX1N-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-232ADP (9-pin D-Sub, male) / FX1N-CNV-BD FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX1N |  FX1N-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-232ADP (9-pin D-Sub, male) / FX1N-CNV-BD FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX2N |  FX2N-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-232ADP (9-pin D-Sub, male) / FX2N-CNV-BD FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|---|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  ch1 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485 and USB) +  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485) +  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX1NC |  FX2NC-232ADP (9-pin D-Sub, male) /  FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX2NC |  FX2NC-232ADP (9-pin D-Sub, male) /  FX0N-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

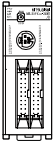


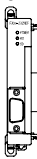

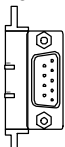



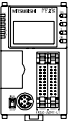









Programming Communication

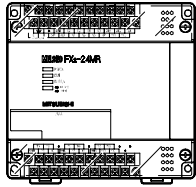
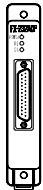
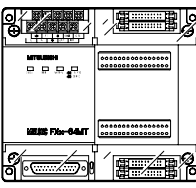
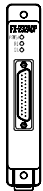
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Remote Maintenance

Apx.

Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1)  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2)   FX3U-□ADP(-MB) (Where □ represents 232 and 485)  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 1 (ch 1)  FX3U-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |   FX3U-CNV-BD  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX3UC-32MT-LT | When using channel 2 (ch 2)   FX3U-□-BD (Where □ represents 232, 422, 485 and USB)  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| |     FX3U-CNV-BD  FX3U-232ADP(-MB) (9-pin D-Sub, male)  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX2(FX) |  FX-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |
|  FX2C |  FX-232ADP (25-pin D-Sub, female) | 15 m (49' 2") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

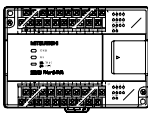
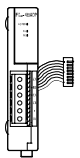
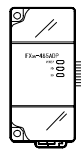

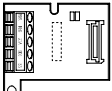
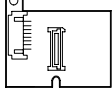
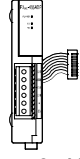
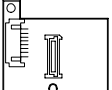
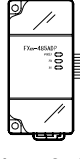
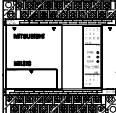
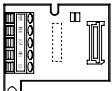
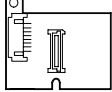
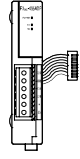
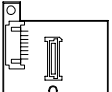
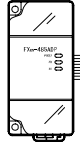
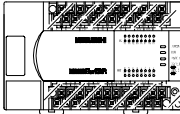
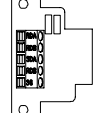
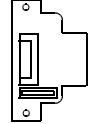
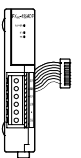
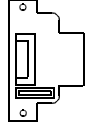

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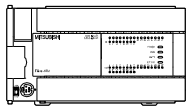
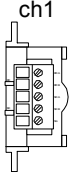

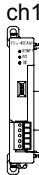





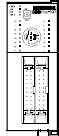
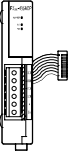

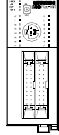
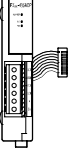

Remote Maintenance

Apx.

Discontinued models

3.2.2 For communication in accordance with RS-485.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX0N |  /  FX2NC-485ADP (European terminal block) FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX1S |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP FX1N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX1N |  FX1N-485-BD (European terminal block) | 50 m (164' 0") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-485ADP FX1N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |
|  FX2N |  FX2N-485-BD | 50 m (164' 0") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-485ADP FX2N-CNV-BD FX0N-485ADP (European terminal block) (Terminal block) | 500 m (1640' 5") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD +  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485, and USB). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485). +  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX1NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |
|  FX2NC |  FX2NC-485ADP (European terminal block) /  FX0N-485ADP (Terminal block) | 500 m (1640' 5") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

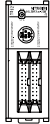



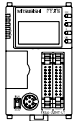
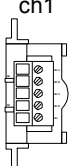

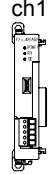


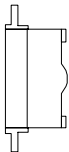


Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485).  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
|  FX3UC-32MT-LT | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-485-BD (European terminal block) | 50 m (164' 0") | |
| |  FX3U-CNV-BD  ch1 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| | When using channel 2 (ch 2) | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485, and USB).  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |
| |  FX3U-CNV-BD  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485).  ch2 FX3U-485ADP(-MB) (European terminal block) | 500 m (1640' 5") | |

4. Wiring

This chapter explains the wiring.

WIRING PRECAUTIONS



- Make sure to cut off all phases of the power supply externally before attempting installation or wiring work. Failure to do so may cause electric shock or damage to the product.
- Make sure to attach the terminal cover, offered as an accessory, before turning on the power or initiating operation after installation or wiring work. Failure to do so may cause electric shock.

WIRING PRECAUTIONS



- Make sure to observe the following precautions in order to prevent any damage to the machinery or accidents due to abnormal data written to the PLC under the influence of noise:
 - 1) Do not bundle the main circuit line together with or lay it close to the main circuit, high-voltage line or load line. Otherwise, noise disturbance and/or surge induction are likely to take place. As a guideline, lay the control line at least 100mm (3.94") or more away from the main circuit or high-voltage line.
 - 2) Ground the shield wire or shield of the shielded cable at one point on the PLC. However, do not use grounding with heavy electrical systems.
- Make sure to properly wire the FX0N/FX2N Series extension equipment in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should follow the specifications in this manual.
- Make sure to properly wire to the European terminal board in accordance with the following precautions. Failure to do so may cause electric shock, a short-circuit, wire breakage, or damage to the product.
 - The disposal size of the cable end should follow the dimensions described in this manual.
 - Tightening torque should be follow the specifications in this manual.
 - Twist the end of strand wire and make sure that there are no loose wires.
 - Do not solder-plate the electric wire ends.
 - Do not connect more than the specified number of wires or electric wires of unspecified size.
 - Affix the electric wires so that neither the terminal block nor the connected parts are directly stressed.

4.1 Wiring Procedure

1 Preparing for wiring

Prepare cables and terminal resistors required for wiring.

→ For details, refer to Section 4.2.

2 Turning OFF the PLC power

Before starting any wiring work, make sure that the PLC power is OFF.

3 Connecting the power supply (FX0N-485ADP only)

Connect the power supply to the 24V DC power terminal.

4 Wiring communication equipment

Connect communication equipment operating in accordance with RS-485 or RS-232C.

→ For details, refer to Section 4.3.

4.2 Selecting Cables and Terminal Resistors

Select cables using the procedure described below.

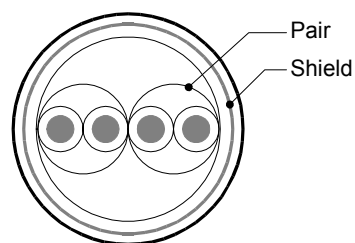
4.2.1 Twisted pair cable

Use twisted pair cables for connecting communication equipment operating in accordance with RS-485. The table below shows recommended model names and manufacturers of cables used for wiring.

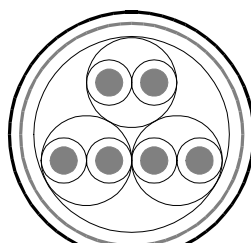
1. Recommended cables

| Manufacturer | Model name | Remarks |
|---------------------------------------|----------------------------------|---|
| Mitsubishi Cable Industries, Ltd. | SPEV(SB)-0.2-2P | Two-pair cable of 0.2 mm ² |
| | SPEV(SB)-MPC-0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | SPEV(SB)-0.5-2P | Two-pair cable of 0.5 mm ² |
| Showa Electric Wire & Cable Co., Ltd. | KMPEV-SB CWS-178 0.2SQ × 2P | Two-pair cable of 0.2 mm ² |
| | KMPEV-SB CWS-178 0.5SQ × 2P | Two-pair cable of 0.5 mm ² |
| Sumitomo Electric Industries, Ltd. | DPEV SB 0.3 × 3P | Three-pair cable of 0.3 mm ² |
| | DPEV SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| The Furukawa Electric Co., Ltd. | D-KPEV-SB 0.2 × 3P | Three-pair cable of 0.2 mm ² |
| | D-KPEV-SB 0.5 × 3P | Three-pair cable of 0.5 mm ² |
| Fujikura Ltd. | IPEV-SB 2P × 0.3 mm ² | Two-pair cable of 0.3 mm ² |
| | IPEV-SB 2P × 0.5 mm ² | Two-pair cable of 0.5 mm ² |

2. Cable structural drawing (reference)



Two-pair cable structural drawing example



Three-pair cable structural drawing example

4.2.2 Connecting cables

1. European type terminal block

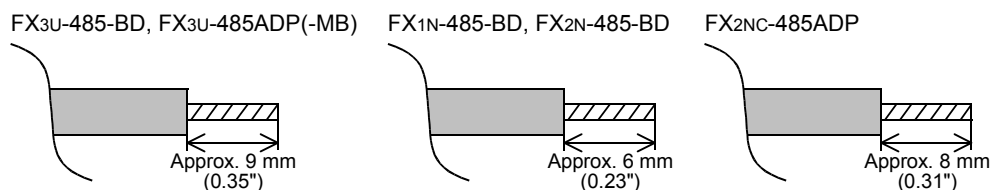
Use shielded twisted pair cables for connecting communication equipment operating in accordance with RS-485.

The table below shows applicable cables and tightening torques.

| | Cable size when one cable is connected | Cable size when two cables are connected | Cable size for bar terminal with insulating sleeve | Tightening torque | Tool size | |
|----------------------------------|--|--|--|-------------------|-------------|-------------|
| | | | | | A | B |
| FX3U-485-BD FX3U-485ADP (-MB) | AWG22 to AWG20 | AWG22 | AWG22 to AWG20 | 0.22 to 0.25 N·m | 0.4 (0.01") | 2.5 (0.09") |
| FX2N-485-BD FX1N-485-BD | AWG26 to AWG16 | | — | 0.6 N·m | 0.6 (0.03") | 3.5 (0.14") |
| FX2NC-485ADP | AWG26 to AWG16 | AWG26 to AWG20 | — | 0.4 to 0.5 N·m | 0.6 (0.03") | 3.5 (0.14") |

With regard to the cable end treatment, use a stranded cable or solid cable as it is, or use a bar terminal with an insulating sleeve.

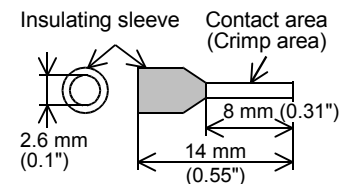
- When using a stranded cable or solid cable as it is
 - Twist the end of a stranded cable so that wires do not get barbed.
 - Do not plate the end of the cable.



- When using a bar terminal with an insulating sleeve

Because it is difficult to insert a cable into an insulating sleeve depending on the thickness of the cable sheath, select the proper cable according to the outline drawing.

| Manufacturer | Model name | Caulking tool |
|-----------------|------------|----------------------------------|
| Phoenix Contact | AI 0.5-8WH | CRIMPFOX ZA 3 (or CRIMPFOX UD 6) |

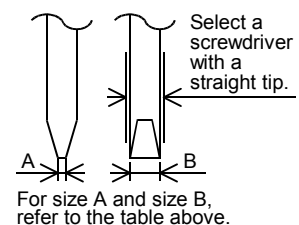


- Tool
 - When tightening a terminal on the European terminal block, use a small commercial straight shape screwdriver whose tip is shown in the figure to the right.

Note:

If the diameter of screwdriver grip is too small, tightening torque will not be able to be achieved. Use the following recommended screwdriver or an appropriate replacement (grip diameter: approximately 25mm).

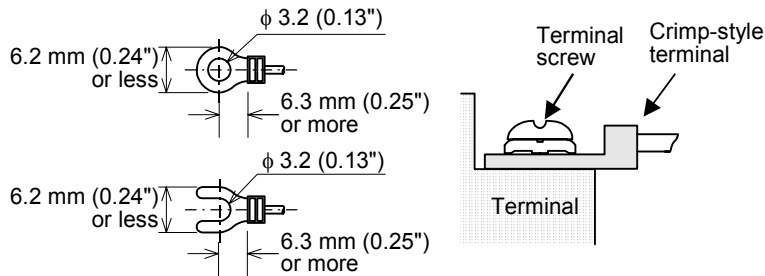
| Manufacturer | Model name |
|-----------------|---------------|
| Phoenix Contact | SZS 0.4 × 2.5 |



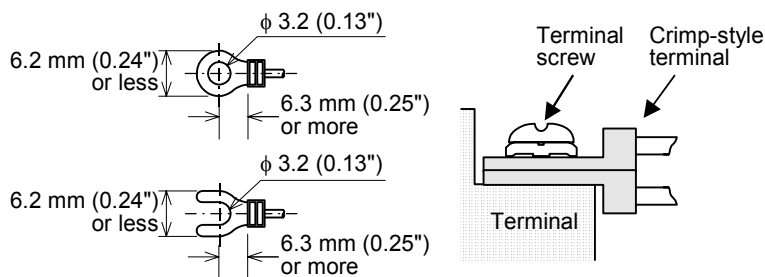
2. Terminal block

In the FX0N-485ADP and FX-485ADP, the terminal screw size is "M3".
Make sure to use a crimp-style terminal with the following sizes.
Make sure that the tightening torque is 0.5 to 0.8 N·m.

- When wiring one cable to one terminal



- When wiring two cables to one terminal

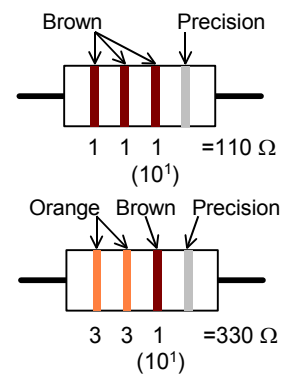


4.2.3 Connecting terminal resistors

Make sure to provide a terminal resistor at the end of each line.
In the case of one-pair wiring, connect a terminal resistor between the RDA-RDB signal terminals of the communication equipment.
In the case of two-pair wiring, connect a terminal resistor between the RDA-RDB signal terminals and SDA-SDB terminal of in the communication equipment.

1. Terminal resistor type

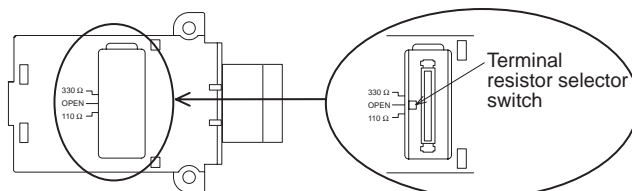
In the case of one-pair wiring, use two terminal resistors of 110 Ω , 1/2 W.
In the case of two-pair wiring, use four terminal resistors of 330 Ω , 1/4 W.
Among the terminal resistors supplied together with the communication equipment, select ones with the color codes shown to the right.



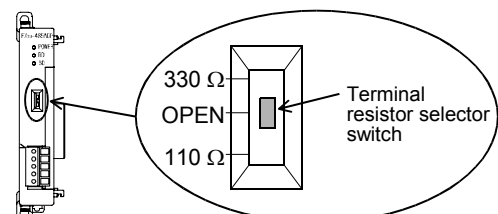
2. When using the FX3U-485-BD or FX3U-485ADP(-MB)

The FX3U-485-BD and FX3U-485ADP(-MB) have built-in terminal resistors.
Set the terminal resistor selector switch accordingly.

- FX3U-485-BD

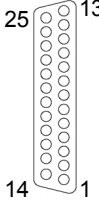
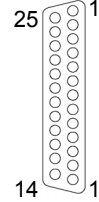



- FX3U-485ADP(-MB)



4.3 Connection Diagram

4.3.1 Connector pin arrangement in communication equipment operating in accordance with RS-232C

| FX-232ADP | | FX0N-232ADP | | FX1N-232-BD, FX2N-232-BD FX2NC-232ADP, FX3U-232-BD FX3U-232ADP(-MB) | | Signal name | Function |
|---|----|---|----|---|-----|----------------|---------------------------|
| 25-pin D-Sub (female) connector | | 25-pin D-Sub (female) connector | | 9-pin D-Sub (male) connector | | | |
|  | 8 |  | — |  | 1*1 | CD (DCD) | Receive carrier detection |
| | 3 | | 3 | | 2 | RD (RXD) | Receive data input |
| | 2 | | 2 | | 3 | SD (TXD) | Send data output |
| | 20 | | 20 | | 4 | ER (DTR) | Data terminal ready |
| | 7 | | 7 | | 5 | SG (GND) | Signal ground |
| | 6 | | 6 | | 6 | DR (DSR) | Data set ready |
| | 1 | | — | | — | FG | Frame ground |

*1. The FX2NC-232ADP does not use the CD (DCD) signal.

4.3.2 Wiring for communication in accordance with RS-232C

Representative wiring examples are shown in this subsection. When pin numbers in the external equipment are different, wire the pins as shown below.

1. When connected equipment has the terminal specifications

| PLC | | | | | | External equipment operating in accordance with RS-232C | | | | | |
|---------------|---|--------------|-------------------------------|-----------|---------|---|-------------|--------------|------|-------------|--------------|
| Name | 9-pin D-Sub (female) connector | | 25-pin D-Sub (male) connector | | | Name | CS, RS | | Name | DR, ER | |
| | FX3U-232-BD FX2N-232-BD FX1N-232-BD FX3U-232ADP(-MB) | FX2NC-232ADP | FX0N-232ADP | FX-232ADP | | | 9-pin D-Sub | 25-pin D-Sub | | 9-pin D-Sub | 25-pin D-Sub |
| | | | | | | | | | | | |
| | | | | | | | | | | | |
| FG | — | | | 1 | FG | — | 1 | FG | — | 1 | |
| RD(RXD) | 2 | | 3 | | RD(RXD) | 2 | 3 | RD(RXD) | 2 | 3 | |
| SD(TXD) | 3 | | 2 | | SD(TXD) | 3 | 2 | SD(TXD) | 3 | 2 | |
| ER(DTR) *1 | 4 | | 20 | | RS(RTS) | 7 | 4 | ER(DTR) | 4 | 20 | |
| SG(GND) | 5 | | 7 | | SG(GND) | 5 | 7 | SG(GND) | 5 | 7 | |
| DR(DSR) *1 | 6 | | 6 | | CS(CTS) | 8 | 5 | DR(DSR) | 6 | 6 | |

*1. When the control line is not used, wiring is not required for this signal.
Because the interlink mode (provided only in FX2N, FX3U, FX2NC, and FX3UC PLCs) uses the control line, wiring is required for this signal.

2. When connected equipment has the modem specifications

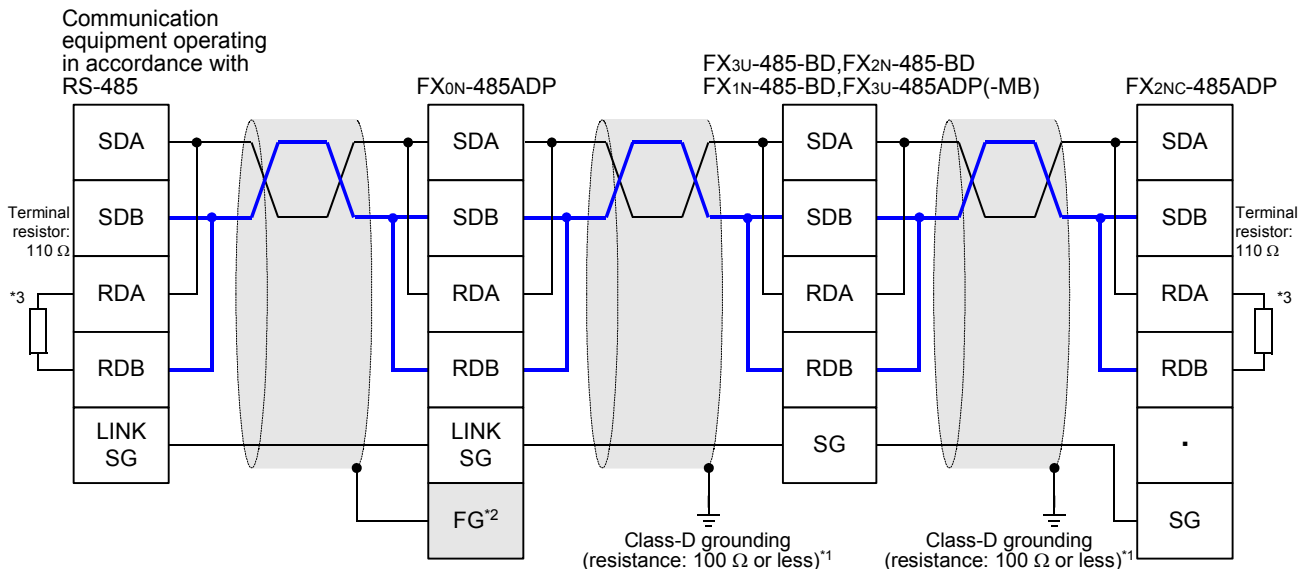
| PLC | | | | | External equipment operating in accordance with RS-232C | | | | | |
|---------|---|--------------|-------------------------------|-----------|---|---------|-------------|--------------|---------|-------------|
| Name | 9-pin D-Sub (female) connector | | 25-pin D-Sub (male) connector | | | CS, RS | | DR, ER | | |
| | FX3U-232-BD FX2N-232-BD FX1N-232-BD FX3U-232ADP(-MB) | FX2NC-232ADP | FX0N-232ADP | FX-232ADP | | Name | 9-pin D-Sub | 25-pin D-Sub | Name | 9-pin D-Sub |
| FG | — | | | 1 | | FG | — | 1 | FG | — |
| CD(DCD) | 1 | — | | | 8 | CD(DCD) | 1 | 8 | CD(DCD) | 1 |
| RD(RXD) | 2 | | 3 | | | RD(RXD) | 2 | 3 | RD(RXD) | 2 |
| SD(TXD) | 3 | | 2 | | | SD(TXD) | 3 | 2 | SD(TXD) | 3 |
| ER(DTR) | 4 | | 20 | | | RS(RTS) | 7 | 4 | ER(DTR) | 4 |
| SG(GND) | 5 | | 7 | | | SG(GND) | 5 | 7 | SG(GND) | 5 |
| DR(DSR) | 6 | | 6 | | | CS(CTS) | 8 | 5 | DR(DSR) | 6 |

• The FX0N-232ADP and FX2NC-232ADP do not use the CD (DCD) signal.

4.3.3 Wiring for communication in accordance with RS-485

One-pair wiring and two-pair wiring (for FS-422) are applicable for communication in accordance with RS-485. Perform proper wiring according to the external equipment.

4.3.4 One-pair wiring



*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD, FX3U-485-BD, FX2NC-485ADP or FX3U-485ADP(-MB).

*2 Make sure to connect the **FG** terminal to the **⏏** (grounding) terminal in the PLC requiring Class-D grounding.

If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.

*3 Make sure to provide a terminal resistor at the end of each line.

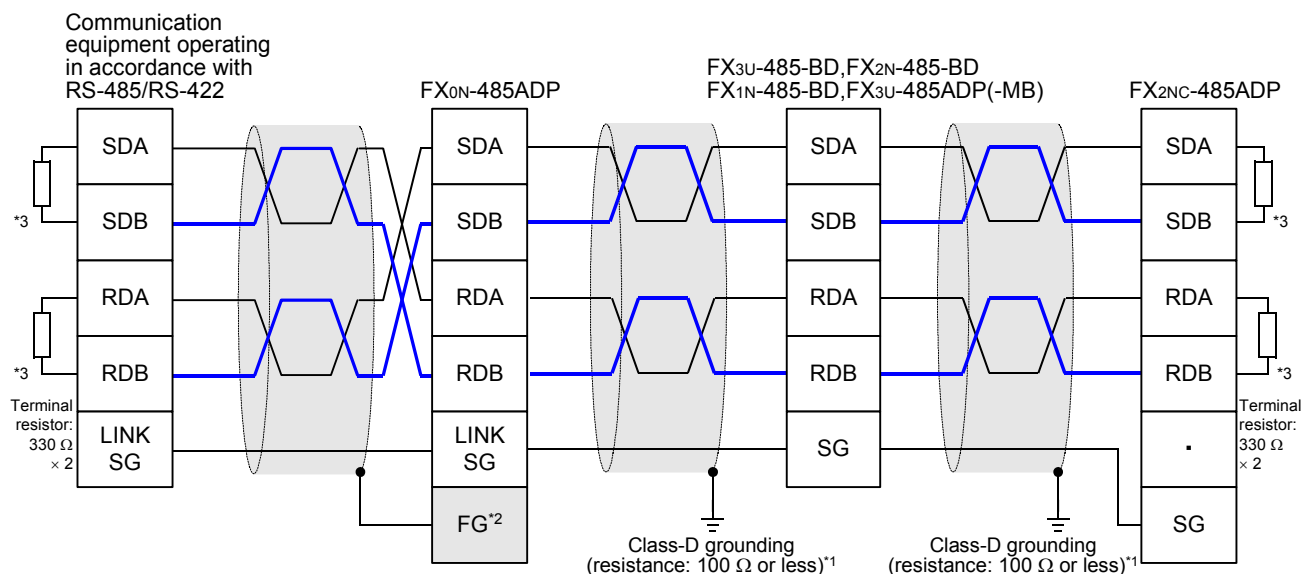
- The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor.

- Set the terminal resistor selector switch accordingly.

- The FX0N-485ADP, FX2NC-485ADP, FX2N-485-BD and FX1N-485-BD are supplied together with terminal resistors.

- When using the FX2N-485-BD, signal loop between the PLC and the external device occurs since the FX2N-485-BD has a full-duplex interface.

4.3.5 Two-pair wiring



*1 Make sure to perform Class-D grounding to the shield of a twisted pair cable connected to the FX2N-485-BD, FX1N-485-BD, FX3U-485-BD, FX2NC-485ADP or FX3U-485ADP(-MB).

*2 Make sure to connect the **FG** terminal to the **⏏** (grounding) terminal in the PLC requiring Class-D grounding.

If the grounding terminal is not provided in the PLC, perform Class-D grounding directly.

*3 Make sure to provide a terminal resistor at the end of each line.

- The FX3U-485-BD and FX3U-485ADP(-MB) have a built-in terminal resistor.

- Set the terminal resistor selector switch accordingly.

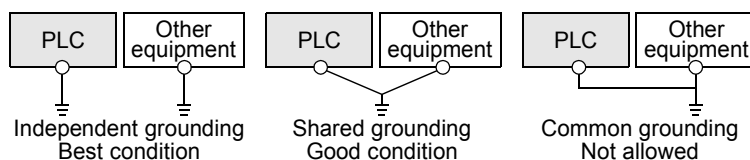
- The FX0N-485ADP, FX2NC-485ADP, FX2N-485-BD and FX1N-485-BD are supplied together with terminal resistors.

4.4 Grounding

Grounding should be performed as stated below.

- The grounding resistance should be 100Ω or less.
- Independent grounding should be performed for best results.
When independent grounding can not be performed, perform "shared grounding" as shown in the following figure.

→ For details, refer to the Hardware Edition of each series.



- The grounding wire size should be AWG 14 (2 mm²) or larger.
- The grounding point should be close to the PLC, and all grounding wires should be as short as possible.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-2321F)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

5. Communication Setting in FX Programmable Controller

This chapter explains the communication setting types and setting methods for non-protocol communication using RS instruction.

5.1 Communication Setting Method Mechanism

This section explains the communication setting method types and setting procedures in FX PLCs.

1. Setting method types

- 1) Specifying the setting using parameters:
Set the parameters by adjusting communication settings on the personal computer screen using the sequence programming software, and transfer them to a PLC.
(This method using parameters is not available in FX2(FX), FX2C, and FX0N PLCs.)
- 2) Specifying the settings by writing data to special data registers:
Prepare a sequence program which sets the communication format and time-out time setting, and then transfer the program to the PLC.

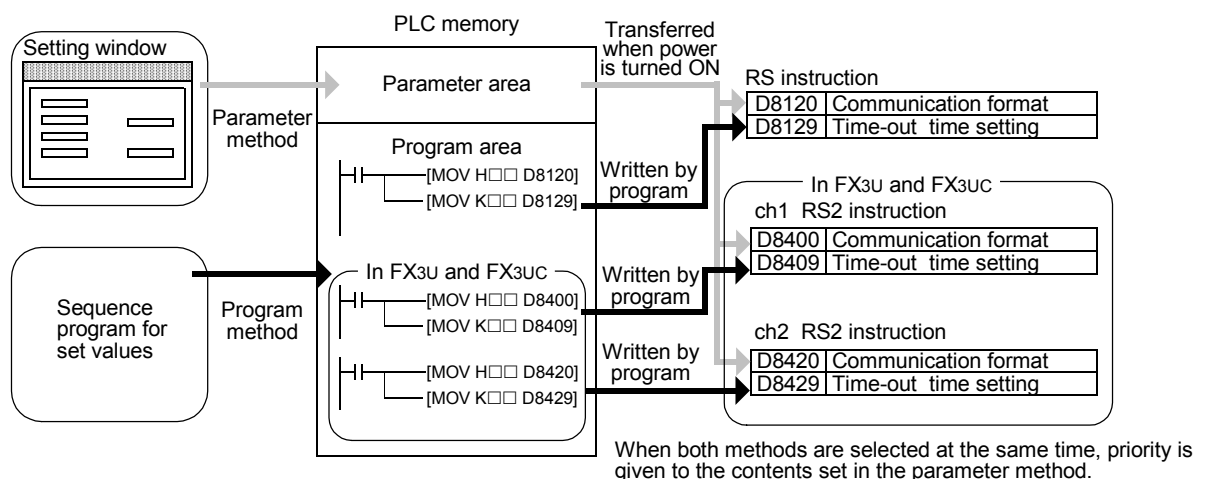
Caution

A PLC operates in the same way without regard to a selected method shown above. If both methods are selected, priority is given to the method using parameters.

2. Communication setting method applicability in each FX Series

| FX Series | Specification using parameters | Specification by writing settings data to special data registers |
|---|--------------------------------|--|
| FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC, FX3UC | ✓ (Recommended) | ✓ |
| FX0N, FX2(FX), FX2C | — | ✓ |

3. Setting data flow



4. Time at which the settings become valid

- 1) When specifying the settings by parameters
When the PLC power is turned ON, the contents of parameters set on the parameter setting window using sequence programming software are automatically transferred to D8120, D8129, D8400, D8409, D8420 and D8429 in the PLC.
As soon as the parameters are transferred to the PLC, the settings become valid.
After the program parameters are transferred to the PLC, it is necessary to turn OFF the PLC power once, and then turn it ON again.

- 2) When specifying the settings by writing data to special data registers
After writing a sequence program, set the PLC mode from STOP to RUN to write the preset data to D8120, D8400 or D8420. After that, set the PLC mode to STOP once, and then set it to RUN again. Or turn OFF the PLC power once, and then turn it ON again.
As soon as the PLC mode is set to RUN from STOP or the PLC power is turned ON from OFF, the settings become valid.

5.2 Communication Setting Using Parameter Method (GX Developer)

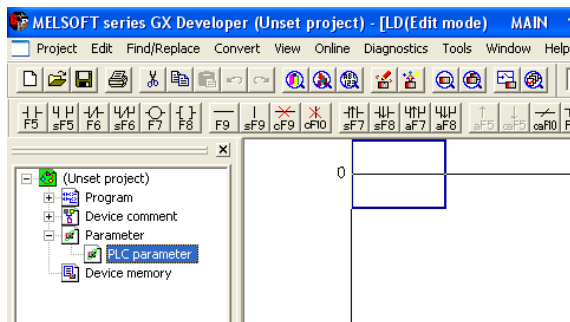
Two software packages, GX Developer and FXGP/WIN for Windows, are available using the parameter method. This section explains the parameter method using GX Developer.

5.2.1 Operating procedure

This subsection explains the serial communication setting method. Suppose that GX Developer is already started up.

1 Opening the parameter setting window

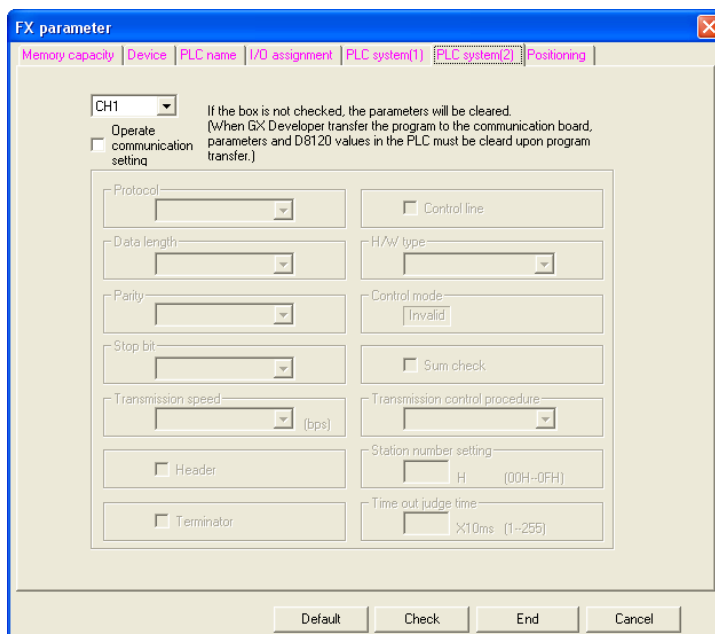
Double-click [Parameter]-[PLC parameter] from the project tree.



If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Setting the serial communication (parameters)

Click the [PLC system(2)] tab in the dialog box



3 Setting the serial communication (parameters)

Select a channel and check the "Operate communication setting" box, then adjust the parameters for that channel.

Execute the setting according to the connected communication equipment.

The screenshot shows the 'FX parameter' dialog box with the 'PLC system(2)' tab active. The 'Operate communication setting' checkbox is checked. The parameters for CH1 are as follows:

- Protocol: Non-procedural
- Data length: 7bit
- Parity: Even
- Stop bit: 1bit
- Transmission speed: 9600 (bps)
- H/W type: Regular/RS-232C
- Control line: ☐ Control line
- Control mode: Invalid
- Sum check: ☐ Sum check
- Transmission control procedure: Form1 (without CR,LF)
- Station number setting: 00 H (00H-0FH)
- Time out judge time: 1 x10ms (1-255)
- Header: ☐ Header
- Terminator: ☐ Terminator

Buttons at the bottom: Default, Check, End, Cancel.

Caution

When setting "H/W type" to "RS485", check the "Control line" box.

4 Writing parameters to the PLC

Select [Online] - [Write to PLC] from the toolbar. Put a check mark (✓) next to the "Parameter" and "Program" options, and click [Execute].

5.3 Communication Setting Using Parameter Method (FXGP/WIN)

Two software packages, GX Developer and FXGP/WIN for Windows, are available using the parameter method. This section explains the parameter method using FXGP/WIN.
Ch2 cannot be set using FXGP/WIN.

5.3.1 Operating procedure

This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

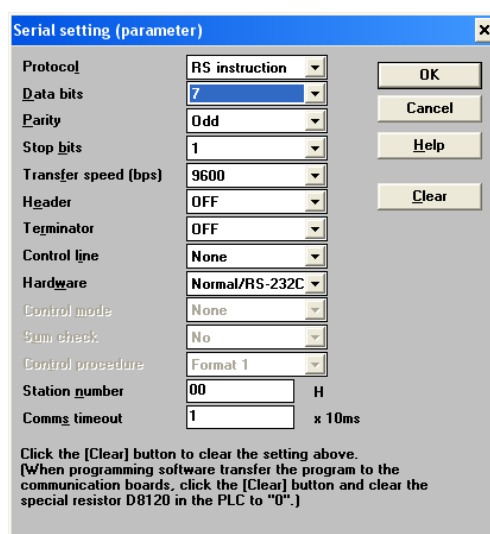
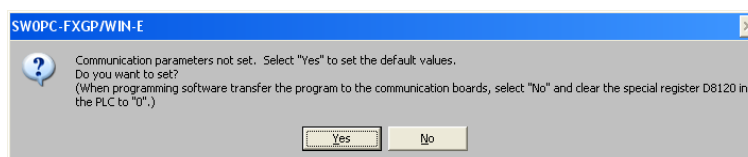
1 Displaying serial setting (parameter)

Select [Option] - [Serial setting (parameter)] from the toolbar.

The following dialog box appears according to absence/presence of the parameter settings.

1. When there is no parameter setting

There is no communication setting. Click the [Yes] button.



2. When there are already parameter settings.

The existing communication setting contents are displayed.

The 'Serial setting (parameter)' dialog box displays the following settings:

| | |
|----------------------|----------------|
| Protocol | RS instruction |
| Data bits | 7 |
| Parity | Odd |
| Stop bits | 1 |
| Transfer speed (bps) | 9600 |
| Header | OFF |
| Terminator | OFF |
| Control line | None |
| Hardware | Normal/RS-232C |
| Control mode | None |
| Sum check | No |
| Control procedure | Format 1 |
| Station number | 00 H |
| Comm. timeout | 1 x 10ms |

Buttons: OK, Cancel, Help, Clear.

Click the [Clear] button to clear the setting above.
(When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".)

2 Adjusting serial setting (parameter)

Execute the settings according to the connected communication equipment.

The 'Serial setting (parameter)' dialog box displays the following adjusted settings:

| | |
|----------------------|----------------|
| Protocol | RS instruction |
| Data bits | 7 |
| Parity | Even |
| Stop bits | 1 |
| Transfer speed (bps) | 9600 |
| Header | OFF |
| Terminator | OFF |
| Control line | H/W mode |
| Hardware | RS-485 |
| Control mode | None |
| Sum check | No |
| Control procedure | Format 1 |
| Station number | 00 H |
| Comm. timeout | 1 x 10ms |

Buttons: OK, Cancel, Help, Clear.

Click the [Clear] button to clear the setting above.
(When programming software transfer the program to the communication boards, click the [Clear] button and clear the special resistor D8120 in the PLC to "0".)

Caution

When setting "Hardware" to "RS-485", set "Control line" to "H/W mode".

3 Writing a sequence program (parameters) to the PLC

Select [PLC] - [Transfers] - [Write] from the toolbar, and click [OK].

6. Creating Programs (RS Instruction)

This chapter explains how to create programs for non-protocol communication using RS instruction and how such programs operate.

6.1 Checking Contents of Related Devices

The tables below show devices used in non-protocol communication using the RS instruction.

1. Bit devices

| Device | Name | Description | R/W |
|---------|----------------------------------|--|-----|
| M8063 | Serial communication error (ch1) | This device turns ON when a communication error occurs. When this device (serial communication error) turns ON, D8063 stores the corresponding error code. | R |
| M8120 | Communication setting keep | This device keeps the communication setting status (for FX0N PLC). | W |
| M8121 | Sending wait flag | This device remains ON while the PLC is waiting to send. | R |
| M8122 | Sending request | When this device is set to ON, the PLC starts to send. | R/W |
| M8123 | Receiving complete flag | This device turns ON when receiving is completed. While this device (receiving complete flag) is ON, the PLC cannot receive any data. | R/W |
| M8124 | Carrier detection flag | This device turns ON in synchronization with the CD signal. | R |
| M8129*1 | Time-out check flag | This device turns ON when data receiving is suspended and the next set of data is not given within the time set by the timeout settings device (D8129). | R/W |
| M8161 | 8-bit processing mode | This device sets the send/receive data bit length to 16-bit or 8-bit. ON: 8-bit mode OFF: 16-bit mode | W |

R: Read only

W: Write only

R/W: Read or Write

*1. Not provided in FX0N, FX2(FX), FX2C, and FX2N (before Ver. 2.00) PLCs.

2. Word devices

| Device | Name | Description | R/W |
|---------|-------------------------------------|---|-----|
| D8063 | Error code display | When the serial communication error flag (M8063) turns ON, this device stores the corresponding error code. | R/W |
| D8120 | Communication format setting | This device sets the communication format. | R/W |
| D8122 | Amount of data remaining to be sent | This device stores the amount of remaining data to be sent. | R |
| D8123 | Amount of data received | This device stores the amount of received data. | R |
| D8124 | Header | This device sets the header (initial value: STX (H02)). | R/W |
| D8125 | Terminator | This device sets the terminator (initial value: ETX (H03)). | R/W |
| D8129*1 | Time-out time setting | This device sets the timeout time. | R/W |
| D8405*2 | Communication parameter display | This device stores communication parameters set in the PLC. | R |
| D8419*2 | Operation mode display | This device stores the communication type being used. | R |

R: Read only

R/W: Read or Write

*1. Not provided in FX0N, FX2(FX), FX2C, and FX2N (before Ver. 2.00) PLCs.

*2. Provided only in FX3U and FX3UC PLCs.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

6.2 How to Use RS Instruction

This section explains the function, operation and programming method of RS instruction.

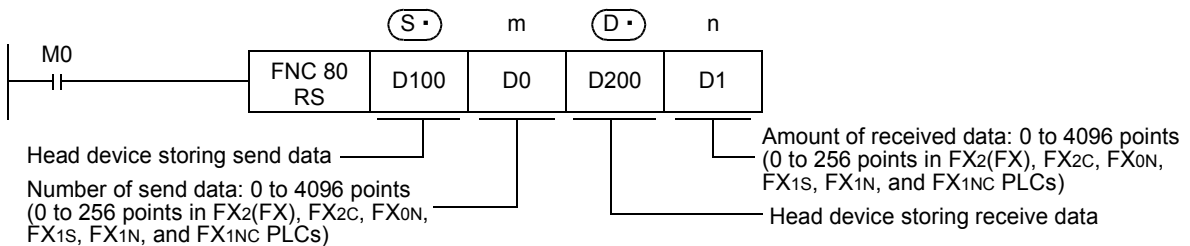
1. Applicable devices

| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | | Others | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|-------|---|--------|---------------|----------------|-----------------------|---------|---|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | Index | | | Con- stant | Real Number | Charac- ter String | Pointer | |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P |
| <div>S•</div> | | | | | | | | | | | | | | ✓ | ▲ | | | | ✓ | | | | | |
| m | | | | | | | | | | | | | | ✓ | ▲ | | | | | ✓ | ✓ | | | |
| <div>D•</div> | | | | | | | | | | | | | | ✓ | ▲ | | | | ✓ | | | | | |
| n | | | | | | | | | | | | | | ✓ | ▲ | | | | | ✓ | ✓ | | | |

▲: Applicable only in FX3U, FX3UC PLCs.

m, n: 0 to 4096 points in FX2N, FX3U, FX2NC, and FX3UC PLCs
(However, "m + n" should not be more than 8000 points.)
0 to 256 points in FX2(FX), FX2C, FX0N, FX1S, FX1N, and FX1NC PLCs

2. Program example



6.2.1 Applicable frames

Message frames used in communication can be selected by setting the communication format. The table below shows the message frames applicable to the RS instruction.

| | | | | |
|---|-----------------|------|------------|--|
| 1 | Data | | | Header: Not provided Terminator: Not provided |
| 2 | Data Terminator | | | Header: Not provided Terminator: Provided |
| 3 | Header | Data | | Header: Provided Terminator: Not provided |
| 4 | Header | Data | Terminator | Header: Provided Terminator: Provided |

1. Header

When "header provided" is selected in the communication format settings, the lowest-order byte of D8124 is used.

When data is sent, the lowest-order byte of D8124 is added at the head of the specified send data to be sent.

When data is received, receiving begins when the data on lowest-order byte of D8124 is received.

2. Terminator

When "terminator provided" is selected in the communication format settings, the lowest-order byte of D8125 is used.

When data is sent, the lowest-order byte of D8125 is added at the end of the specified send data.

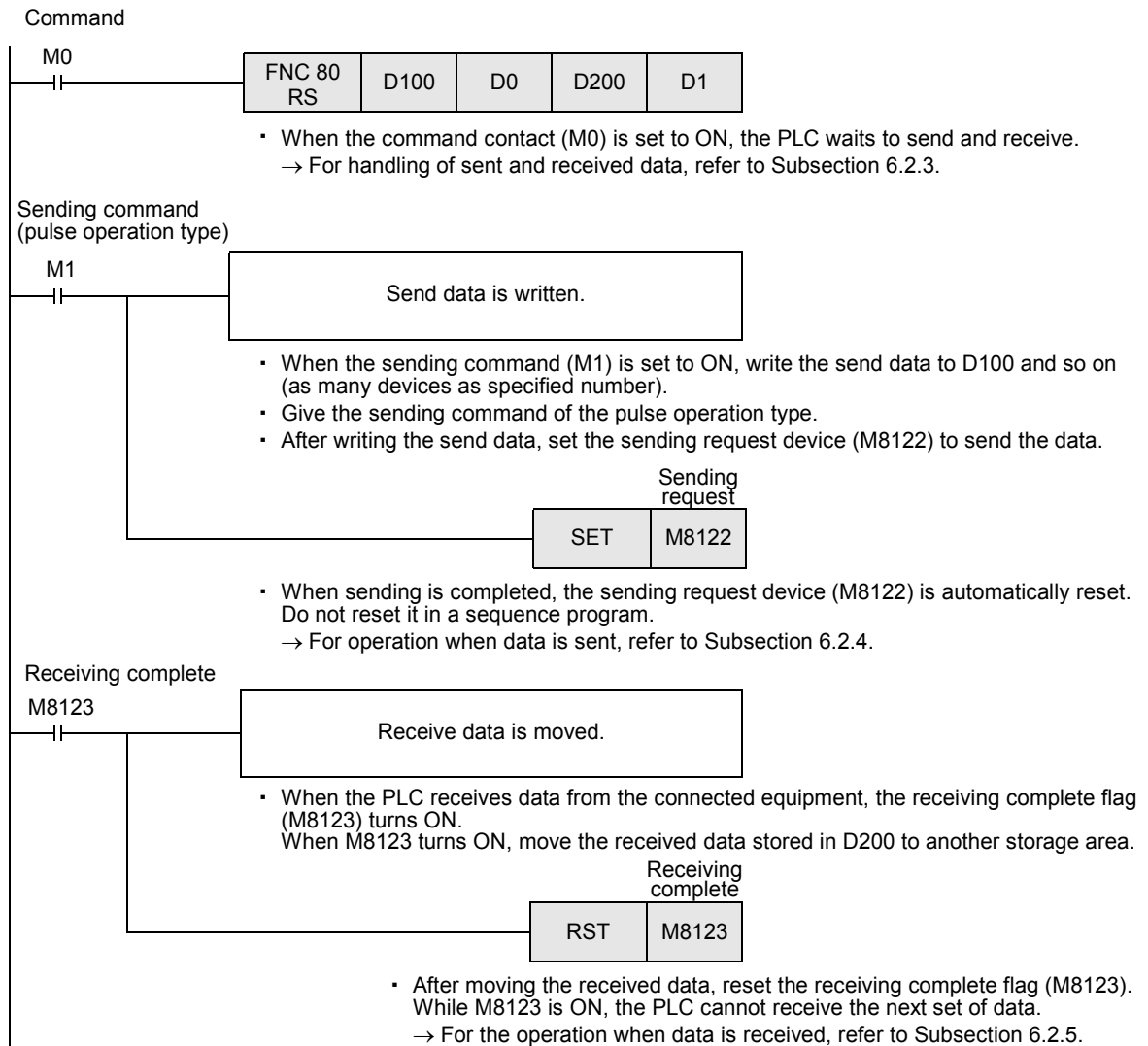
When data is received, receiving is completed*1 when the data on lowest-order byte of D8125 is received.

*1. Receiving is completed also when the amount of received data specified by the RS instruction is received or when the receiving of data is suspended and the next set of data is not executed within the timeout time set by D8129.

6.2.2 Function and operation

RS instruction specifies the head device storing the sent data sent from the PLC, amount of data, head device storing the received data and the maximum allowable amount of received data.

Create a program as shown below.



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Common Items

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Parallel Link

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Inverter Communication

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Non-Protocol Communication (RS/RS2 Instruction)

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Non-Protocol Communication (FX2N-232IF)

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Programming Communication

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Remote Maintenance

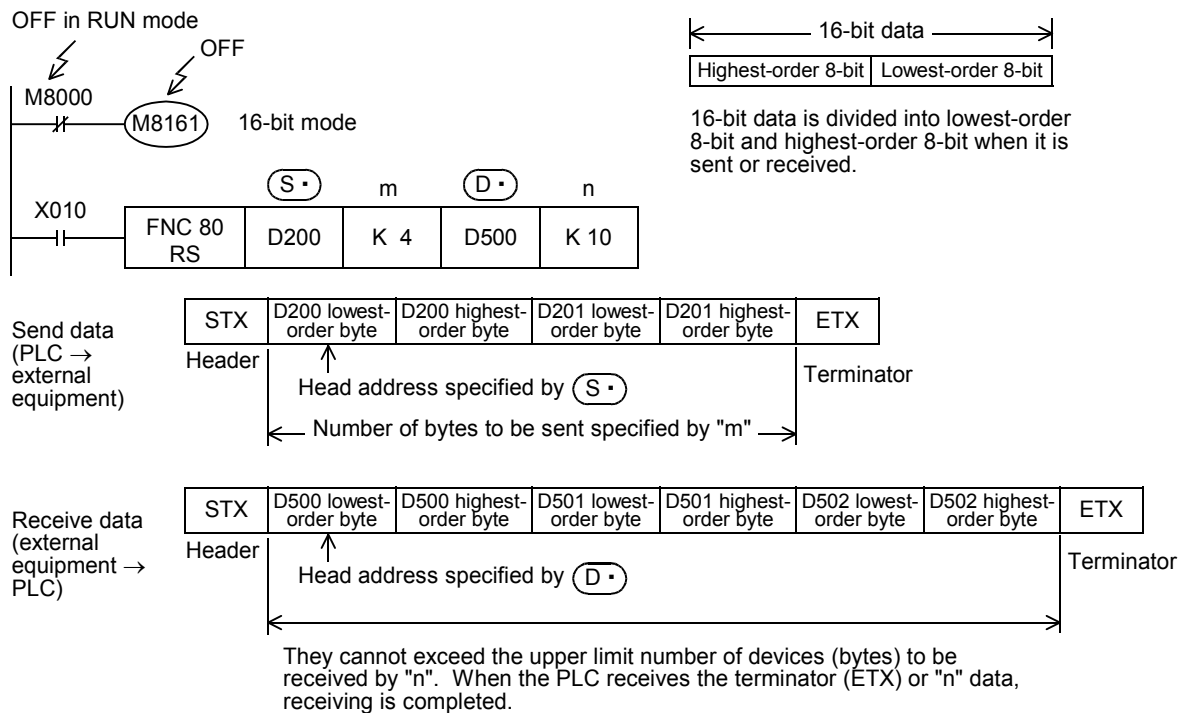
Apx.

Discontinued models

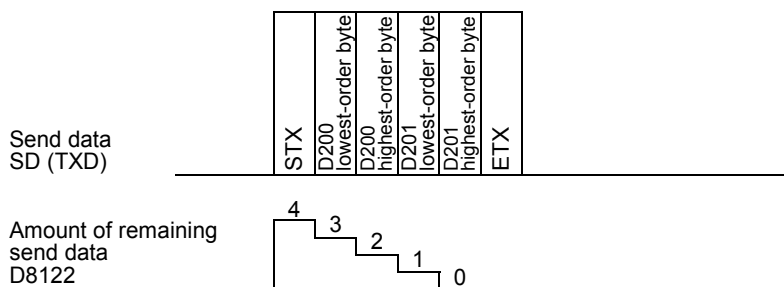
6.2.3 Send/receive data and amount of data

RS instruction can handle sent and received data in two modes, 16-bit mode and 8-bit mode.
Data is handled as shown below in each mode. (In the examples shown below, "header provided" and "terminator provided" are selected in the communication setting.)

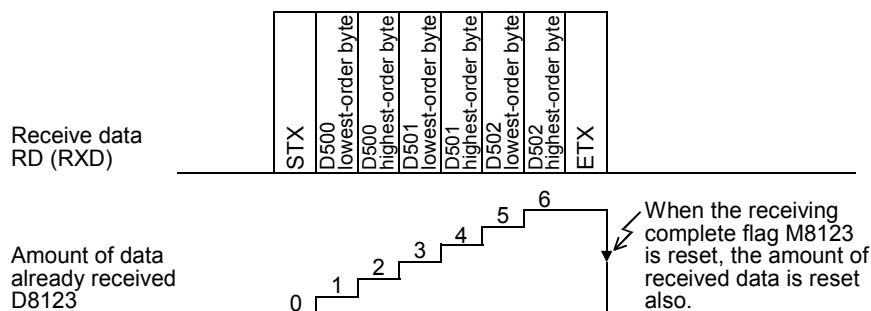
1. Handling of 16-bit data (when M8161 is set to OFF)



1) Send data and amount of remaining send data



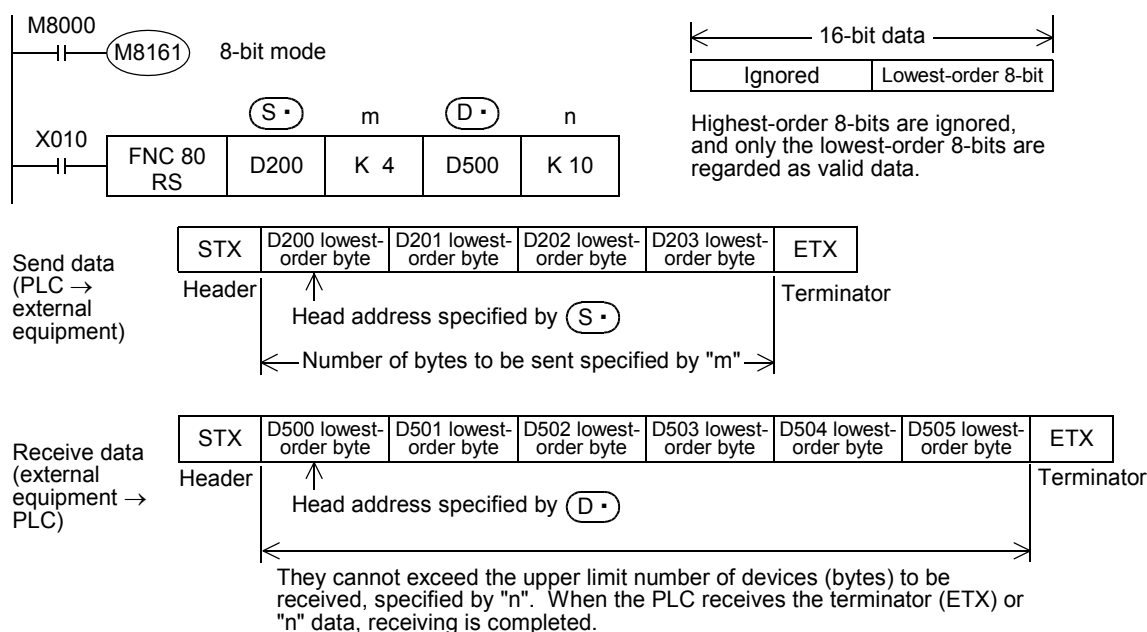
2) Receive data and amount of data already received



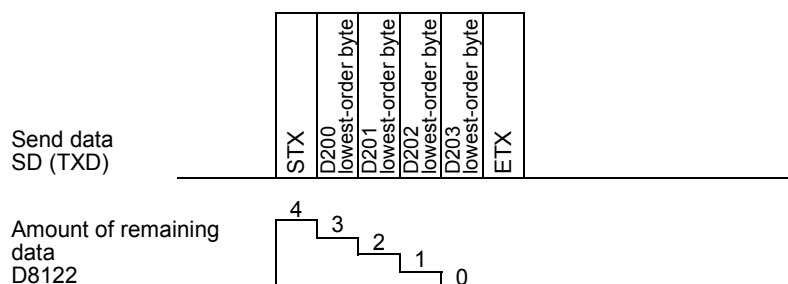
Caution on other instructions using M8161

M8161 is shared by RS, ASCII, HEX, CCD, and CRC (provided only in FX3U and FX3UC PLCs) instructions.

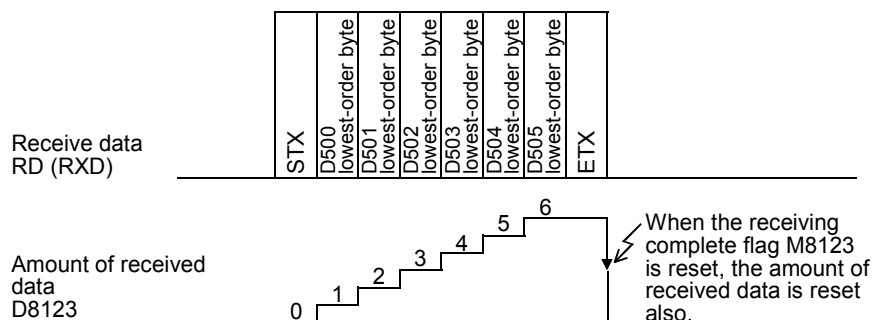
2. Handling of 8-bit data (when M8161 is set to ON)



1) Send data and amount of remaining data



2) Receive data and amount of received data



Caution on other instructions using M8161

M8161 is shared by RS, ASCI, HEX, CCD, and CRC (provided only in FX3U and FX3UC PLCs) instructions.

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Common Items

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Parallel Link

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Non-Protocol Communication (RS/RS2 Instruction)

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Non-Protocol Communication (FX2N-2321F)

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Programming Communication

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Apx.

Discontinued models

6.2.4 Operation when data is sent

When the sending request flag (M8122) is set to ON while RS instruction is driven, the PLC sends the data stored in the data registers (S•) to (S•)+m-1 specified by the RS instruction.

When sending of the data is complete, the sending request flag (M8122) is automatically set to OFF.

1. Time at which sending is started

When RS instruction is executed after the sending request flag (M8122) is set to ON, the PLC starts to send. When sending begins, the PLC sends the data stored in the data registers specified by the RS instruction in interrupt processing regardless of the operation cycle.

2. Time at which sending is completed

When all send data is sent, sending is completed.

(If the terminator is set, the terminator is included in the send data.)

3. Cautions on sending

When sending data, observe the following cautions

- 1) While the sending request flag (M8122) is ON, do not change the amount of send data or contents of send data.
- 2) Do not set the sending request flag (M8122) to OFF in a sequence program.
If the send data is changed while the sending request flag (M8122) is ON or if the sending request flag (M8122) is set to OFF in a sequence program, correct data will not be sent.

6.2.5 Operation when data is received

When RS instruction is executed, the PLC waits to receive. When the PLC receives data from the connected equipment and receiving is completed, the receiving complete flag (M8123) is set to ON.

When the PLC receives data, it stores the received data to the data registers (D•) to (D•)+n-1 specified by the RS instruction.

While the receiving complete flag (M8123) is ON, the PLC cannot receive new data.

1. Time at which receiving is started

When the PLC receives data while it is waiting to receive, it starts receiving data.

When receiving begins, the PLC stores the received data in interrupt processing regardless of the operation cycle.

When the header (D8124) is specified in the communication format, however, the PLC starts receiving when it receives the code set in the header. And the PLC stores the received data except the header.

2. Time at which receiving is completed

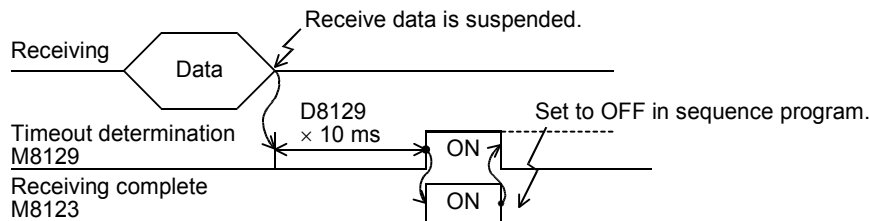
Receiving is completed in the following three conditions. When either condition is established, receiving is completed.

- 1) When the PLC receives as much data as specified by the RS instruction
- 2) When "terminator provided" is selected in the communication format, and the PLC receives the code set in the terminator (D8125)
- 3) When data receiving is suspended and the PLC does not receive the next set of data within the time set in the time-out time setting device (D8129)
At this time, the time-out check flag (M8129) turns ON.
(The time-out check flag is not provided in FX0N, FX2(FX), FX2C, and FX2N (before Ver. 2.00) PLCs.)

3. Operation of the time-out check flag (which is not provided in FX0N, FX2(FX), FX2c, and FX2N (before Ver. 2.00) PLCs)

When data receiving is suspended, counting of the timeout time is started immediately. If the PLC does not receive the next set of data within the time-out time setting set by D8129, the time-out check flag (M8129) is set to ON. At this time, the receiving complete flag (M8123) is set to ON also.

The time-out time setting (D8129) can be set to a value from 1 to 255 (10 ms to 2550 ms).



The time-out check flag (M8129) does not turn OFF automatically.

Set it to OFF in the sequence program. (When M8123 is set to OFF, M8129 is also set to OFF.)

Using this function, the PLC can receive data from equipment where the amount of send data varies without the terminator.

4. When the control line is set to interlink mode

When interlink mode is selected as the communication format, the following sequence is adopted from the start of receiving to completion:

- 1) When the amount of data already received becomes "number of bytes to be received -30", the control line ER (DTR) turns OFF.
When the control line ER (DTR) turns OFF, the external equipment should suspend data sending.
After the control line ER (DTR) turns OFF, the PLC can receive up to 30 characters (bytes).
- 2) When the external equipment suspends data sending, the PLC sets the time-out check flag (M8129) and receiving complete flag (M8123) to ON after the time-out time setting (D8129).
Move the received data in a sequence program, and then set the receiving complete flag (M8123) and time-out check flag (M8129) to OFF.
- 3) When the receiving complete flag (M8123) is set to OFF, the control line ER (DTR) turns ON.
When the control line ER (DTR) turns ON, resume sending data from the external equipment.
- 4) Repeat steps 1) to 3) until data receiving is completed.

5. Cautions on receiving

When receiving data, observe the following cautions:

- 1) While the receiving complete flag (M8123) is ON, the PLC cannot receive the next set of data.
When the receiving complete flag is set to OFF, the PLC waits to receive.
- 2) When RS instruction is driven, the receiving complete flag (M8123) remains OFF in an FX1S, FX1N, or FX1NC PLC if the amount of received data (n) is "0", but the PLC does not wait to receive.
To make the PLC wait to receive, it is necessary to set the amount of received data "n" to "1" or more and set the receiving complete flag to OFF from ON.

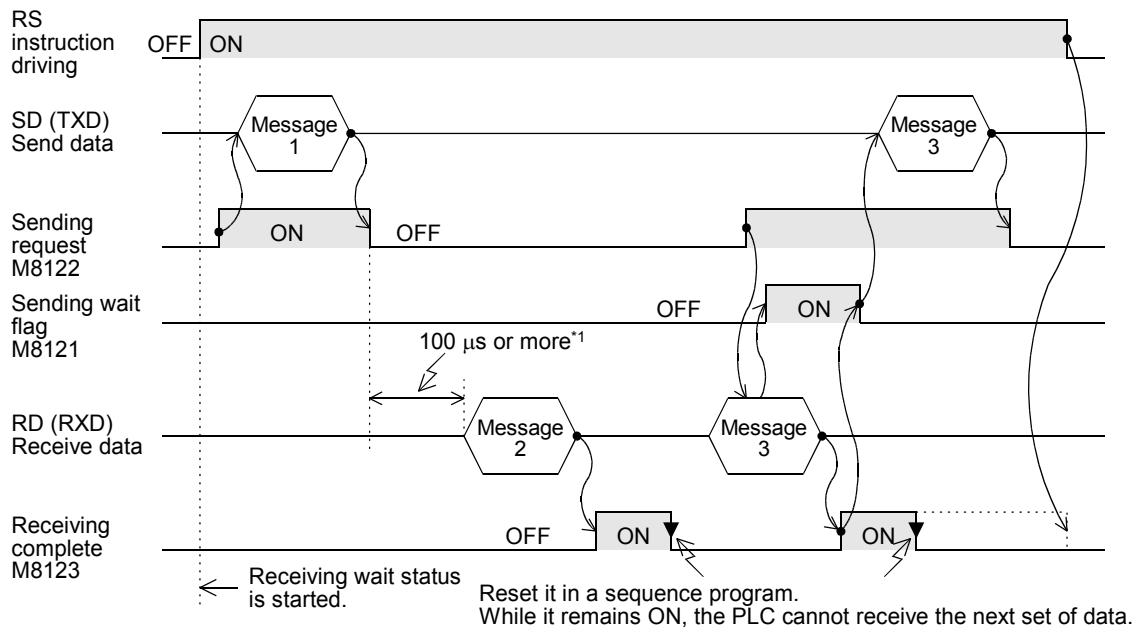
6.3 Operation of Control Line

6.3.1 FX2(FX), FX2C, FX1S, FX0N, FX1N, FX1NC, and FX2N (before Ver. 2.00) PLCs

FX2, FX2C, FX1S, FX0N, FX1N, FX1NC, and FX2N (before Ver. 2.00) PLCs execute half-duplex, bidirectional communication.

When the sending flag is set to ON during receiving, the sending wait flag M8121 turns ON. When the receiving complete flag turns ON from OFF, the PLC starts to send.

1. When the control line is not provided

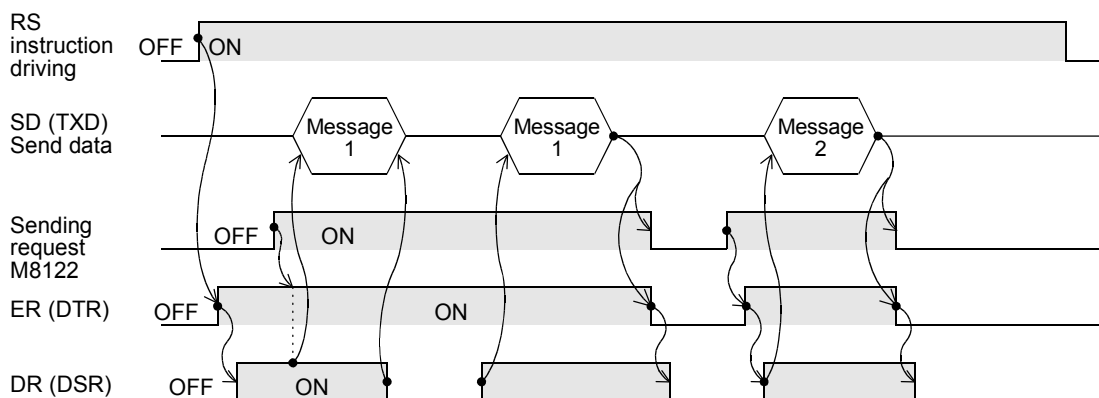


*1. Set it to 2 scan times or more in FX1S, FX0N, FX2(FX), FX2C, FX1N, and FX1NC PLCs.

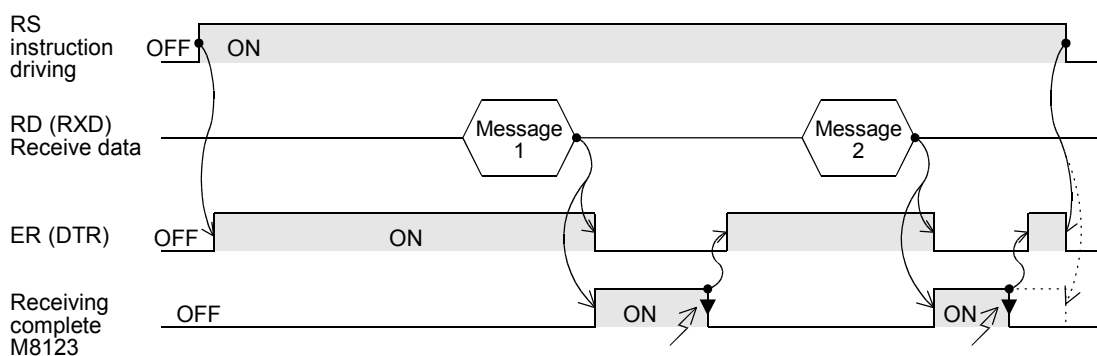
2. When the control line is in the standard mode

Use this mode when only sending or receiving.

1) When only sending is executed

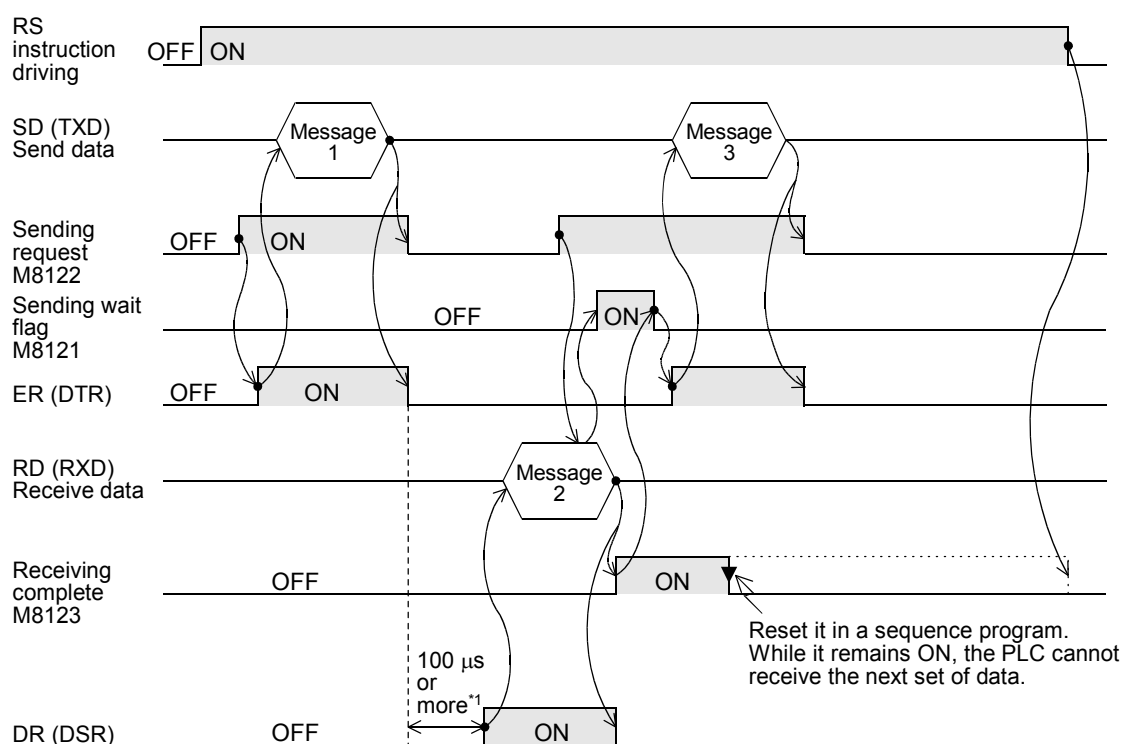


2) When only receiving is executed [The DR (DSR) signal is not used.]



Reset it in a sequence program. While it remains ON, the PLC cannot receive the next set of data.

3. When the control line is in the modem mode



*1. Set it to 2 scan times or more in FX1S, FX0N, FX2(FX), FX2C, FX1N, and FX1NC PLCs.

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Common Items

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N:N Network

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Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

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Programming Communication

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Remote Maintenance

Apx.

Discontinued models

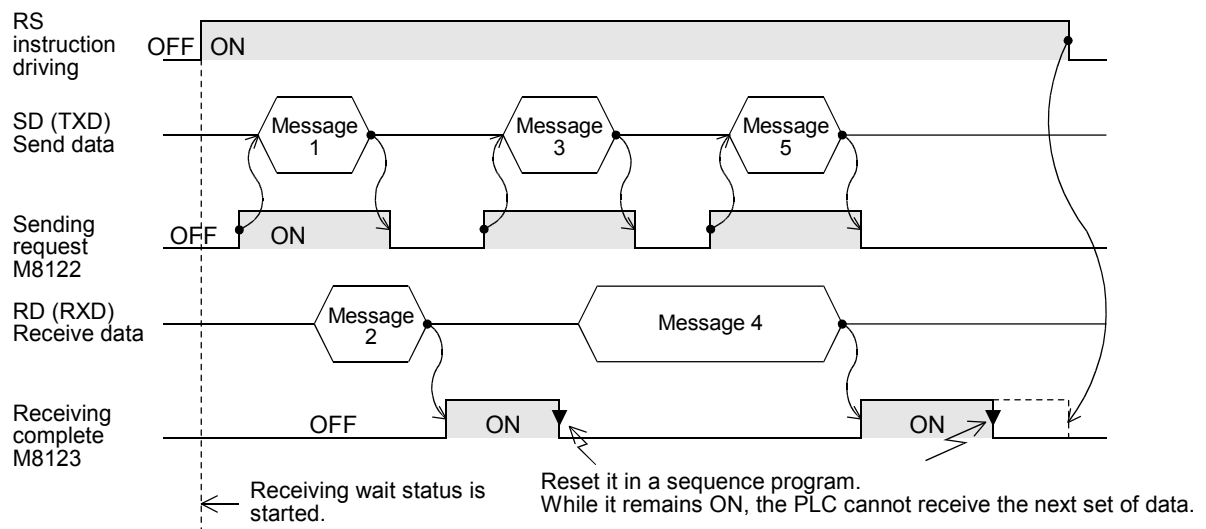
6.3.2 FX2N (Ver. 2.00 or later), FX3U, FX2NC, and FX3UC PLCs

FX2N (Ver. 2.00 or later), FX3U, FX2NC, and FX3UC PLCs execute full-duplex, bidirectional communication. When executing half-duplex, bidirectional communication, pay attention not to set the sending request to ON while receiving. If the sending request is set to ON, the PLC starts to send. As a result, the external equipment may not be able to receive data, and the sent and received data may be destroyed.

In full-duplex, bidirectional communication, the sending wait flag M8121 does not turn ON.

In FX3U and FX3UC PLCs, however, the sending wait flag M8121 remains ON while the DR (DSR) is OFF, the PLC waits to send, and the control line is in the standard mode or interlink mode.

1. Without control line

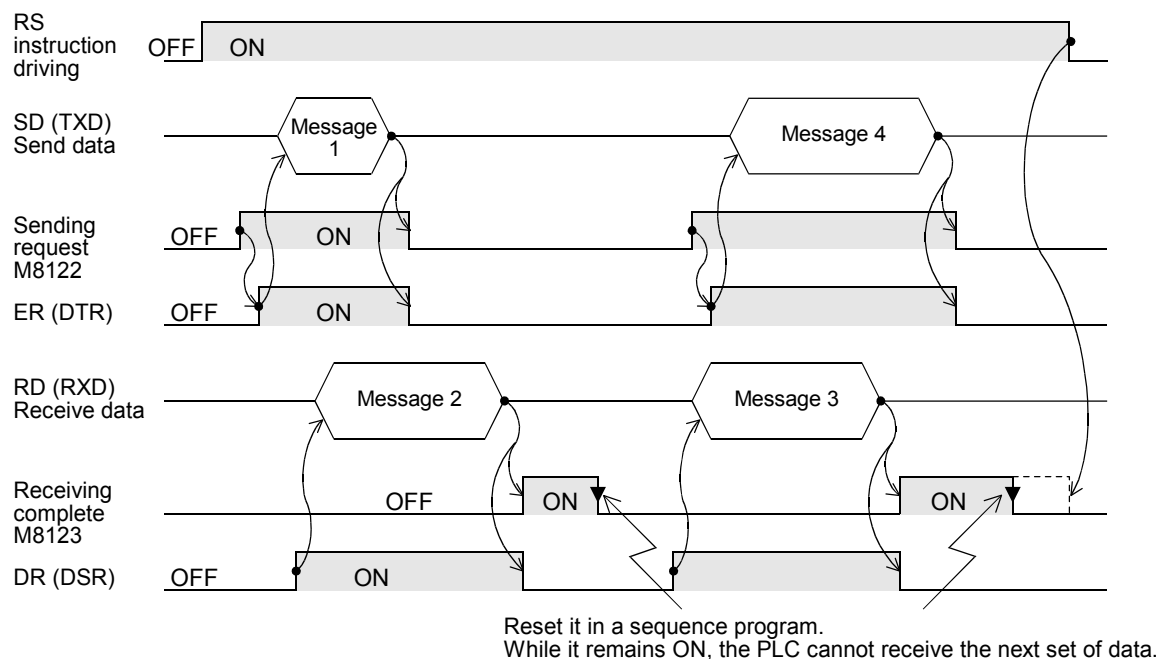


2. When the control line is in the standard mode

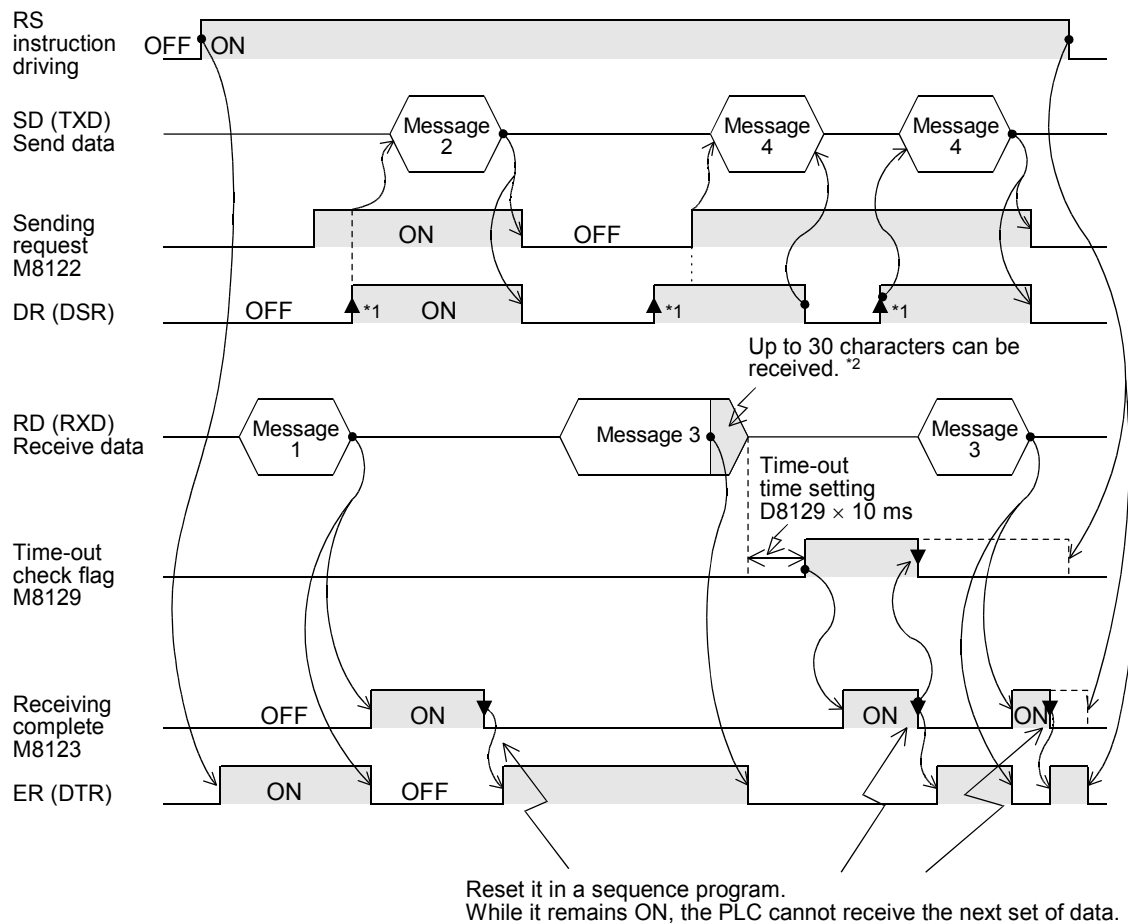
Use this mode when only sending or receiving.

The control line and transfer sequence are equivalent to those in FX2N PLCs (before Ver. 2.00). Refer to Subsection 6.3.1.

3. When the control line is in the modem mode



4. When the control line is in the interlink mode



- *1. On the external equipment side, set the DR (DSR) signal to ON when the external equipment is ready to receive.
The FX2N, FX3U, FX2NC or FX3UC PLC sends the send data when both the DR (DSR) signal and the sending request turn ON.
- *2. In the interlink mode, the PLC sets ER (DTR) signal to OFF 30 characters before reaching the specified amount of received data, and asks the external equipment to stop sending. After that, the PLC can only receive up to 30 characters. In this case, temporarily stop sending, and then send the remaining data after the ER (DTR) signal turns ON again.
When sending is stopped, the PLC finishes receiving after the time-out time setting is reached.
When sending is not stopped, the PLC finishes receiving after it has received the final send data or 30 characters. Accordingly, make sure that the amount of received data is "30 + α".

6.4 Important Points in Creating Programs

- 1) RS instruction can be used as many times as necessary in a program, but make sure that only one RS instruction is driven at a time.
For multiple RS instructions to be driven, make sure the OFF time is longer than one scan time.
- 2) In FX2(FX), FX2C, FX0N, FX1S, FX1N and FX1NC PLCs, make sure to provide an interval of two scan times or more between completion of sending and the start of receiving or between completion of receiving and the start of sending.
In FX2N PLCs (whose version is before Ver. 2.00), provide an interval of 100 μ s or more.
In FX2N (whose version is Ver. 2.00 or later), FX3U, FX2NC and FX3UC PLCs, this interval is not necessary.
- 3) While RS instruction is being driven, change of D8120 is prohibited.
To change D8120, set RS instruction to OFF, set D8120 to "0", and then set a new value to D8120.
- 4) In the interlink mode, set the amount of received data n to "31" or more.
If it is set to "30" or less, the control line ER (DTR) is set to OFF as soon as the PLC receives data. As a result, the received data may be partially skipped.
- 5) Do not use another instruction which uses the same communication port. If such an instruction is used, communication may not function normally.
FX3U and FX3UC PLCs: RS2 instruction, IVDR instruction, etc.
FX2N and FX2NC PLCs: EXTR instruction

6.5 Communication Error

When a communication error occurs, the error flag M8063 turns ON and D8063 stores the error code.

| Error code | Description |
|------------|--|
| 6301 | Parity error, overrun error or framing error |

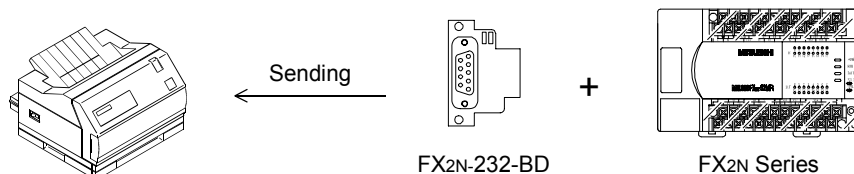
→ Confirm the contents in "Chapter 11. Troubleshooting".

7. Practical Program Example (RS Instruction)

7.1 Example of Printing Using RS Instruction (Using RS-232C Connection)

In this example, a printer with an RS-232C interface is connected to a PLC, and data sent from the PLC is printed.

1. System configuration



Use a communication cable suitable to the pin arrangement of the printer connector.
(For representative wiring, refer to Chapter 4.)

2. Communication format

Align the communication format in the PLC with that in the printer used.
(The table below shows the communication format in the main unit.)

| | |
|--|---------------------|
| Data length | 8-bit |
| Parity | Even |
| Stop bit | 2-bit |
| Baud rate | 2400 bps |
| Header | Not provided |
| Terminator | Not provided |
| Control line (hardware) | Not provided |
| Communication method (protocol) | Non-protocol method |

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Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

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Programming Communication

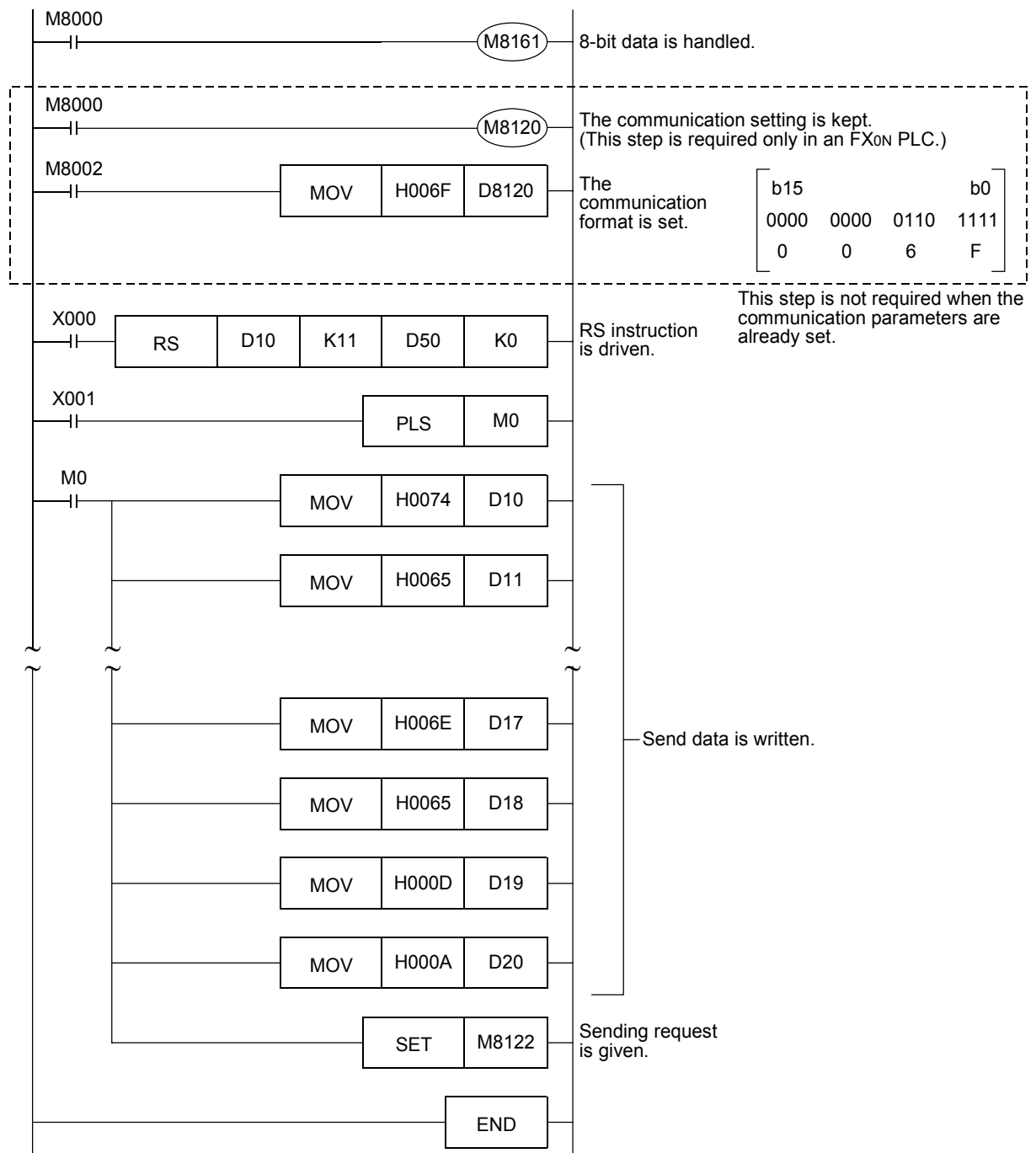
I

Remote Maintenance

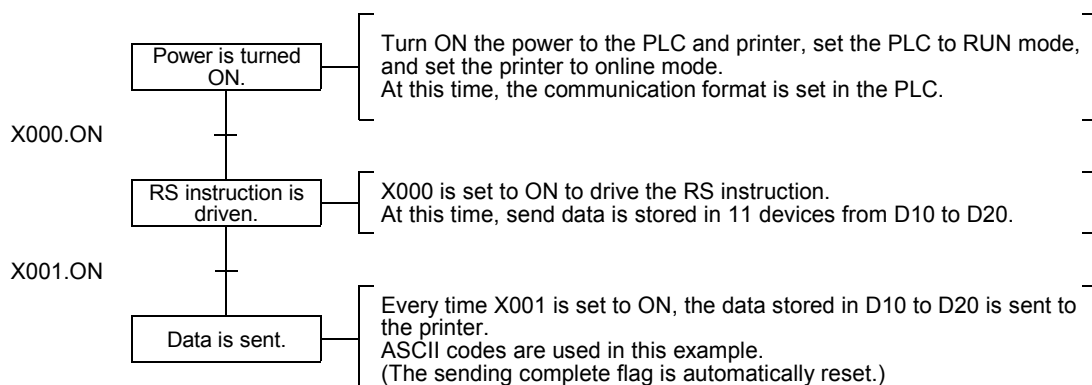
Apx.

Discontinued models

3. Sequence program



4. Operation



8. Creating Programs (RS2 Instruction)

This chapter explains how to create programs for non-protocol communication using RS2 instruction and how such programs operate.

RS2 instruction is supported only in FX3U and FX3UC PLCs.

RS2 instruction has the following additional functions which are not provided in the RS instruction:

- 1) Up to 4 characters (bytes) can be specified as the header and terminator.
- 2) The sum check can be added automatically.
- 3) The communication port (channel) can be specified.

8.1 Checking Contents of Related Devices

The tables below show devices used in non-protocol communication using RS2 instruction.

1. Bit devices

| Device | | Name | Description | R/W |
|----------|-------|----------------------------|---|-----|
| ch1 | ch2 | | | |
| M8063 | M8438 | Serial communication error | This device turns ON when a communication error occurs. When this device (serial communication error) turns ON, D8063 or D8438 stores the corresponding error code. | R |
| M8401 | M8421 | Sending wait flag | This device remains ON while the PLC is waiting to send. | R |
| M8402 | M8422 | Sending request | When this device is set to ON, the PLC starts to send. | R/W |
| M8403 | M8423 | Receiving complete flag | This device turns ON when receiving is completed. While this device (receiving complete flag) is ON, the PLC cannot receive any receive data. | R/W |
| M8404 | M8424 | Carrier detection flag | This device turns ON in synchronization with the CD (DCD) signal. | R |
| *1 M8405 | M8425 | Data set ready (DSR) flag | This device turns ON in synchronization with the DR (DSR) signal. | R |
| M8409 | M8429 | Time-out check flag | This device turns ON when data receiving is suspended and the next set of receive data is not given within the time set by the time-out time setting device. | R/W |

R: Read only

R/W: Read or Write

*1. Available in Ver.2.30 or later of FX3U or FX3UC PLC

2. Word devices

| Device | | Name | Description | R/W | | | | | | | | | | | | | | | | | | | | | | | | | |
|------------|----------------------------|------------------------------------|--|------|---|---|---|------|------------|-----|-----|---------------|---|---------------------------|---------------------------|-----------|---|----------------------------|----------------------------|-----|---|---------------------------|---------------------------|-----|---|----------------------------|----------------------------|-----|-----|
| ch1 | ch2 | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8063 | D8438 | Serial communication error code | When the serial communication error flag turns ON, this device stores the corresponding error code. | R/W | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8400 | D8420 | Communication format setting | This device sets the communication format. | R/W | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8402 | D8422 | Amount of remaining send data | This device stores the amount of remaining send data. | R | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8403 | D8423 | Amount of data already received | This device stores the amount of data already received. | R | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8405 | D8425 | Communication parameter display | This devices stores communication parameters set in the PLC. | R | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8409 | D8429 | Time-out time setting | This device sets the timeout time. | R/W | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8410 | D8430 | Header 1 and header 2 | <div>These devices set the headers 1 to 4.</div> <div><div>Header</div><table><tr><td>1</td><td>2</td><td>3</td><td>4</td><td>Data</td></tr></table></div> <table><tr><th>Header</th><th>ch1</th><th>ch2</th><th>Initial value</th></tr><tr><td>1</td><td>D8410 (lowest-order byte)</td><td>D8430 (lowest-order byte)</td><td>H02 (STX)</td></tr><tr><td>2</td><td>D8410 (highest-order byte)</td><td>D8430 (highest-order byte)</td><td>H00</td></tr><tr><td>3</td><td>D8411 (lowest-order byte)</td><td>D8431 (lowest-order byte)</td><td>H00</td></tr><tr><td>4</td><td>D8411 (highest-order byte)</td><td>D8431 (highest-order byte)</td><td>H00</td></tr></table> | 1 | 2 | 3 | 4 | Data | Header | ch1 | ch2 | Initial value | 1 | D8410 (lowest-order byte) | D8430 (lowest-order byte) | H02 (STX) | 2 | D8410 (highest-order byte) | D8430 (highest-order byte) | H00 | 3 | D8411 (lowest-order byte) | D8431 (lowest-order byte) | H00 | 4 | D8411 (highest-order byte) | D8431 (highest-order byte) | H00 | R/W |
| 1 | 2 | 3 | 4 | Data | | | | | | | | | | | | | | | | | | | | | | | | | |
| Header | ch1 | ch2 | Initial value | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | D8410 (lowest-order byte) | D8430 (lowest-order byte) | H02 (STX) | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | D8410 (highest-order byte) | D8430 (highest-order byte) | H00 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | D8411 (lowest-order byte) | D8431 (lowest-order byte) | H00 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | D8411 (highest-order byte) | D8431 (highest-order byte) | H00 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8411 | D8431 | Header 3 and header 4 | <div>When "H00" is set to the header 1, headers are not provided. The area before H00 (in 1-byte units) is used to set the headers.</div> | R/W | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8412 | D8432 | Terminator 1 and terminator 2 | <div>These devices set the terminators 1 to 4.</div> <div><div>Terminator</div><table><tr><td>Data</td><td>1</td><td>2</td><td>3</td><td>4</td></tr></table></div> <table><tr><th>Terminator</th><th>ch1</th><th>ch2</th><th>Initial value</th></tr><tr><td>1</td><td>D8412 (lowest-order byte)</td><td>D8432 (lowest-order byte)</td><td>H03 (ETX)</td></tr><tr><td>2</td><td>D8412 (highest-order byte)</td><td>D8432 (highest-order byte)</td><td>H00</td></tr><tr><td>3</td><td>D8413 (lowest-order byte)</td><td>D8433 (lowest-order byte)</td><td>H00</td></tr><tr><td>4</td><td>D8413 (highest-order byte)</td><td>D8433 (highest-order byte)</td><td>H00</td></tr></table> | Data | 1 | 2 | 3 | 4 | Terminator | ch1 | ch2 | Initial value | 1 | D8412 (lowest-order byte) | D8432 (lowest-order byte) | H03 (ETX) | 2 | D8412 (highest-order byte) | D8432 (highest-order byte) | H00 | 3 | D8413 (lowest-order byte) | D8433 (lowest-order byte) | H00 | 4 | D8413 (highest-order byte) | D8433 (highest-order byte) | H00 | R/W |
| Data | 1 | 2 | 3 | 4 | | | | | | | | | | | | | | | | | | | | | | | | | |
| Terminator | ch1 | ch2 | Initial value | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | D8412 (lowest-order byte) | D8432 (lowest-order byte) | H03 (ETX) | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 2 | D8412 (highest-order byte) | D8432 (highest-order byte) | H00 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 3 | D8413 (lowest-order byte) | D8433 (lowest-order byte) | H00 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 4 | D8413 (highest-order byte) | D8433 (highest-order byte) | H00 | | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8413 | D8433 | Terminator 3 and terminator 4 | <div>When "H00" is set to the terminator 1, terminators are not provided. The area before H00 (in 1-byte units) is used to set the terminators.</div> | R/W | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8414 | D8434 | Receiving sum (receive data) | This device stores the received sum check value. | R | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8415 | D8435 | Receiving sum (calculation result) | This device stores the sum check value calculated from the received data. | R | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8416 | D8436 | Sending sum | This device stores the sum check value added to the send data. | R | | | | | | | | | | | | | | | | | | | | | | | | | |
| D8419 | D8439 | Operation mode display | This device stores the current communication being executed. | R | | | | | | | | | | | | | | | | | | | | | | | | | |

R: Read only
R/W: Read or Write

8.2 How to Use RS2 Instruction

This section explains the function, operation and programming method of the RS2 instruction.

1. Applicable devices

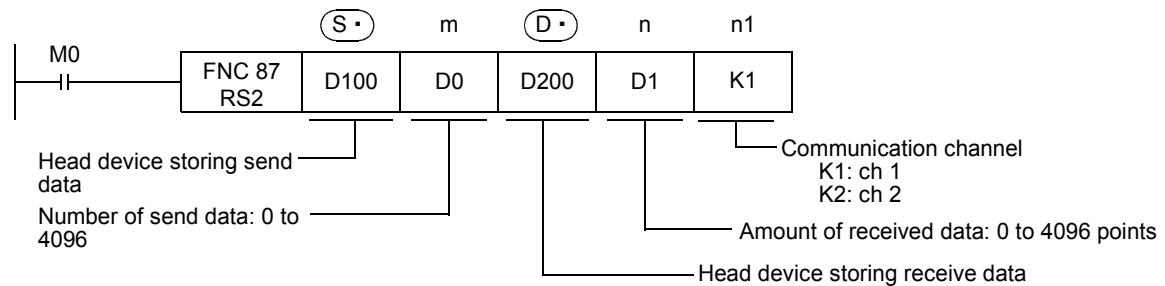
| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | Others | | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|-------|---|---------------|---|-------------|-----------------------|---------|---|
| | System/User | | | | | | | Digit Specification | | | | System/User | | | | Special Unit | Index | | Con- stant | | Real Number | Charac- ter String | Pointer | |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P |
| (S•) | | | | | | | | | | | | | | ✓ | ✓ | | | | ✓ | | | | | |
| m | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |
| (D•) | | | | | | | | | | | | | | ✓ | ✓ | | | | ✓ | | | | | |
| n | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |
| n1 | | | | | | | | | | | | | | | | | | | | ✓ | ✓ | | | |

m, n: 0 to 4096 points

(However, "m + n" should not be more than 8000 points.)

n1: K1 or K2

2. Program example



8.2.1 Applicable frames

Message frames used in communication can be selected by setting the communication format. The table below shows message frames applicable to the RS2 instruction.

| | |
|----|--|
| 1 | Data |
| 2 | Data CR+LF |
| 3 | Data Terminator |
| 4 | Data Terminator CR+LF |
| 5 | Data Terminator Sum check |
| 6 | Data Terminator Sum check CR+LF |
| 7 | Header Data |
| 8 | Header Data CR+LF |
| 9 | Header Data Terminator |
| 10 | Header Data Terminator CR+LF |
| 11 | Header Data Terminator Sum check |
| 12 | Header Data Terminator Sum check CR+LF |

1. Header

When "header provided" is selected in the communication format settings, the values of D8410 and D8411 are used for ch.1, and the values of D8430 and D8431 are used for ch.2.

Up to four headers can be set.

| Header | Header 1 | Header 2 | Header 3 | Header 4 |
|--------|---------------------------|----------------------------|---------------------------|----------------------------|
| ch1 | D8410 (lowest-order byte) | D8410 (highest-order byte) | D8411 (lowest-order byte) | D8411 (highest-order byte) |
| ch2 | D8430 (lowest-order byte) | D8430 (highest-order byte) | D8431 (lowest-order byte) | D8431 (highest-order byte) |

When data is sent, the data set in the devices above is added at the head of the specified send data.

When data is received, receiving begins when the data set in the devices above is received continuously.

Even if "header provided" is selected, headers are not provided if header 1 is set to "00H".

The area before 00H (in 1-byte units) is used to set the headers.

Cautions

Set the header before driving the RS2 instruction. Do not change the setting while the RS2 instruction is being driven.

2. Terminator

When "terminator provided" is selected in the communication format setting, the values of D8412 and D8413 are used for ch.1, and the values of D8432 and D8433 are used for ch.2.

Up to four terminators can be set.

| Terminator | Terminator 1 | Terminator 2 | Terminator 3 | Terminator 4 |
|------------|---------------------------|----------------------------|---------------------------|----------------------------|
| ch1 | D8412 (lowest-order byte) | D8412 (highest-order byte) | D8413 (lowest-order byte) | D8413 (highest-order byte) |
| ch2 | D8432 (lowest-order byte) | D8432 (highest-order byte) | D8433 (lowest-order byte) | D8433 (highest-order byte) |

When data is sent, the data set in the devices above is added at the end of the specified send data.

When data is received, receiving is completed*1 when the data set in the devices above is received.

Even if "terminator provided" is selected, terminators are not provided if terminator 1 is set to "00H".

The area before 00H (in 1-byte units) is used to set the terminators.

Cautions

Set the terminator before driving the RS2 instruction. Do not change the setting while the RS2 instruction is being driven.

- *1. Receiving is also completed when the amount of received data specified by the RS2 instruction is finished receiving or when data receiving is suspended and the next set of data is not received within the time-out time setting device (D8409 or D8429).

3. Sum check

When "sum check provided" is selected in the communication format setting, the sum check is executed for the sent and received data.

When selecting "sum check provided", make sure to select "terminator provided".

When data is sent, the sum of "data" + "terminator" is calculated, and added to the send data.

When data is received, it is checked whether or not the received sum is equivalent to the sum calculated by the PLC.

→ For details on sum check, refer to Subsection 8.2.6.

4. CR + LF

When "CR + LF provided" is selected in the communication format setting, the character code of "CR + LF" is added at the end of the send data.

When data is received, receiving is completed when "CR + LF" is received continuously.

However, receiving is also completed when the specified amount of received data is received or when data receiving is suspended and the next set of data is not received within the time-out time setting.

Make sure that "CR" is not included in the message.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

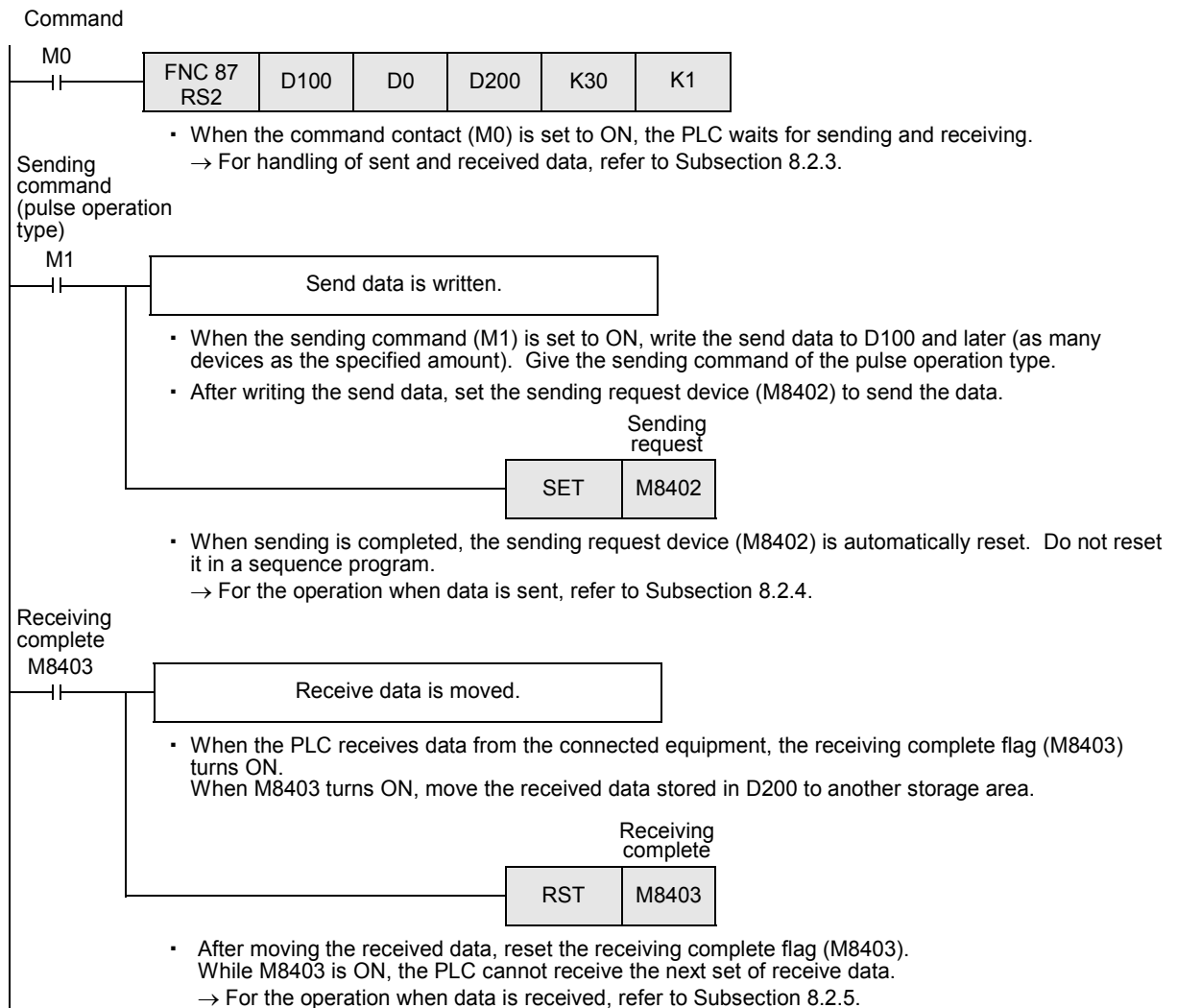
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Discontinued models

8.2.2 Function and operation

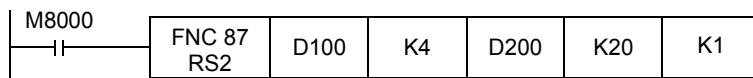
RS2 instruction specifies the head device storing the send data from the PLC, amount of data, head device storing the received data and maximum allowable amount of received data.

Create a program as shown below.



8.2.3 Send/receive data and amount of data

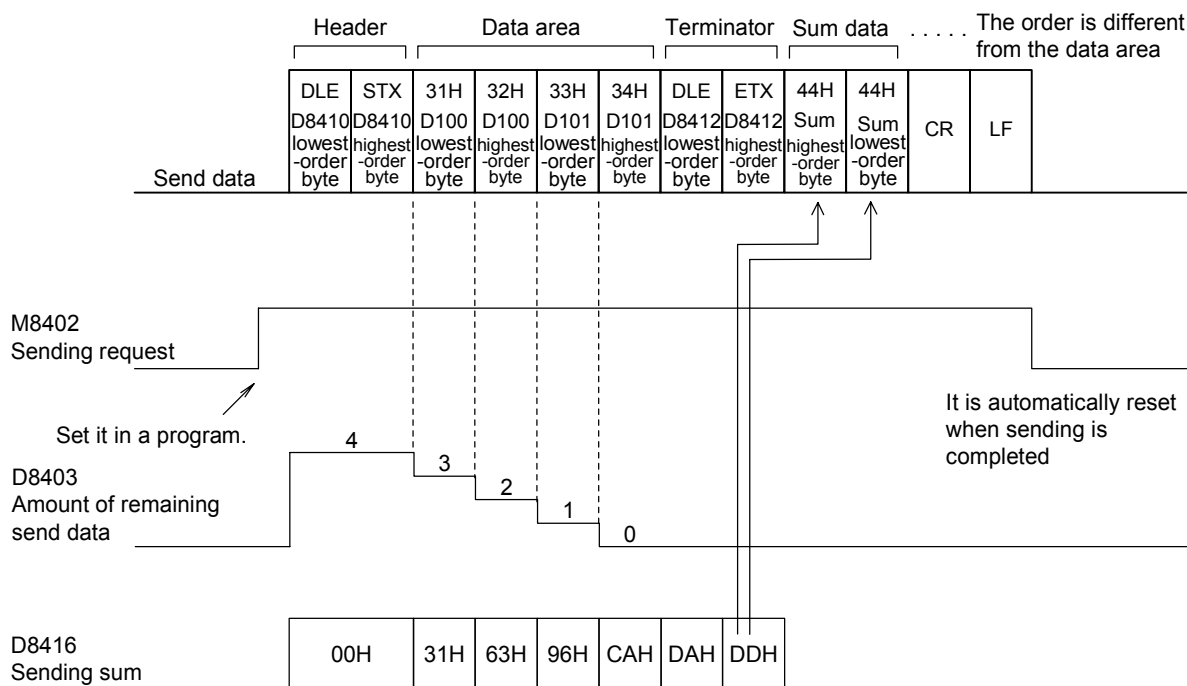
RS2 instruction can handle send data and receive data while storing two characters in one data register.



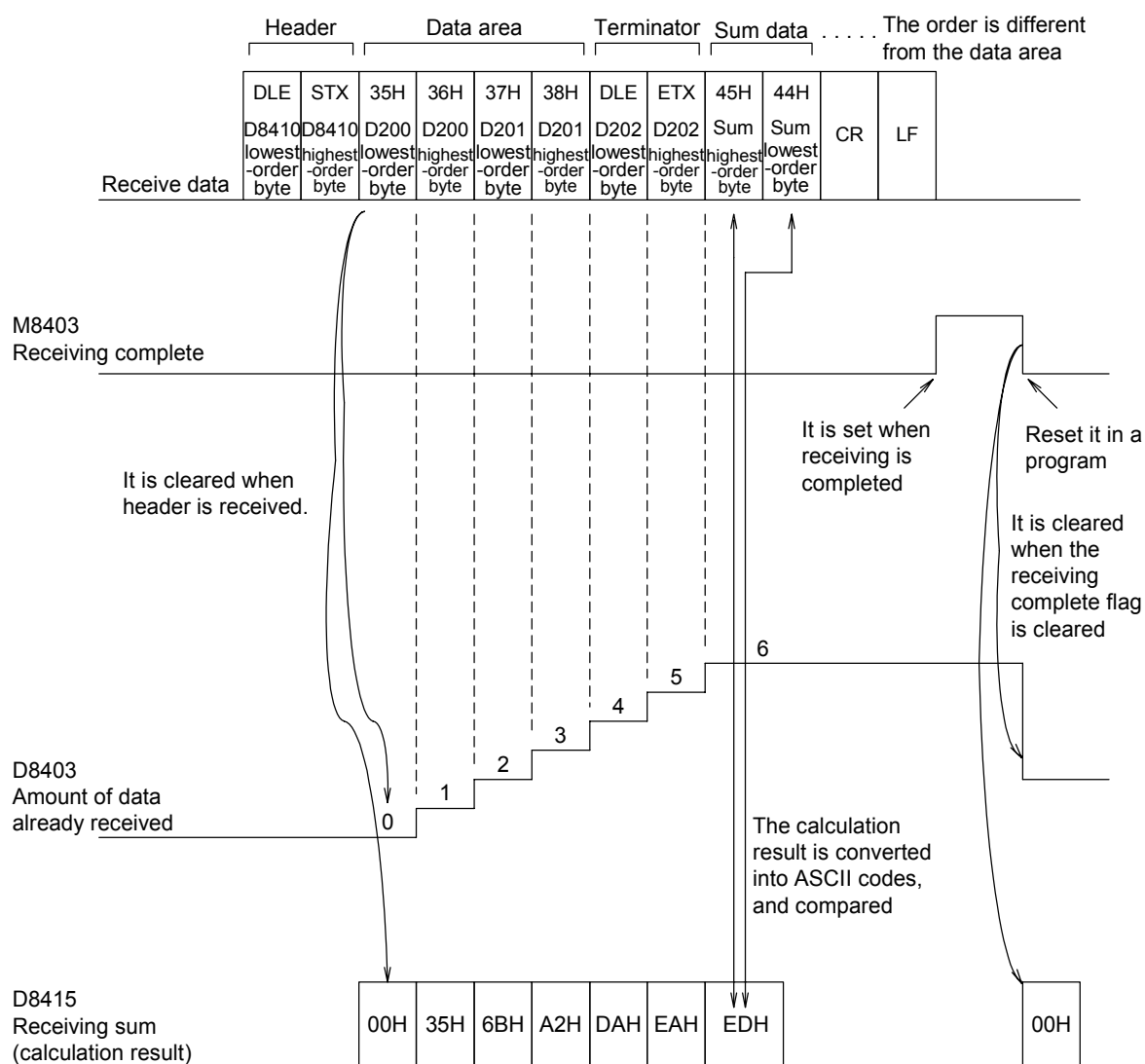
Communication format setting

- Control line not provided
- Headers provided [DLE + STX (D8410: 0210H D8411: 0000H)]
- Terminators provided [DLE + ETX (D8412: 0310H D8413: 0000H)]
- Sum check provided
- CR + LF added

1. Send data and amount of remaining send data



2. Receive data and amount of data already received



Caution

The 8-bit mode is not applicable in RS2 instruction.

8.2.4 Operation when data is sent

When the sending request flag is set to ON while RS2 instruction is driven, the PLC sends the data stored in the specified data registers (S•) to (S•+m-1).

When using communication port ch1, set M8402.

When using communication port ch2, set M8422.

When sending of the data is completed, the sending request flag is automatically set to OFF.

1. Time at which sending is started

When RS2 instruction is executed after the sending request flag is set to ON, the PLC starts to send.

When sending is started, the PLC sends the data stored in the data registers specified by RS2 instruction in interrupt processing regardless of the operation cycle.

2. Time at which sending is completed

When all send data*1 is sent, sending is completed.

- *1. The "terminators", "sum check" and "CR + LF" set in the communication format are included also in the send data.

3. Cautions on sending

When sending data, observe the following cautions

- 1) While the sending request flag is ON, do not change the amount of send data or the contents of the send data.
- 2) Do not set the sending request flag to OFF in a sequence program.
If the send data is changed while the sending request flag is ON or if the sending request flag is set to OFF in a sequence program, correct data is not sent.

8.2.5 Operation when data is received

When RS2 instruction is executed, the PLC waits to receive. When the PLC receives data from the connected equipment and receiving is completed, the receiving complete flag is set to ON.

When communication port ch1 is used, M8403 turns ON.

When communication port ch2 is used, M8423 turns ON.

When the PLC receives data, it stores the received data to the data registers (D•) to (D•+n-1) specified by the RS2 instruction.

While the receiving complete flag is ON, the PLC cannot receive new data.

1. Time at which receiving is started

When the PLC receives data while it is waiting to receive, it starts receiving data.

When receiving begins, the PLC stores the received data in interrupt processing regardless of the operation cycle.

When the headers are specified in the communication format, however, the PLC starts receiving when it continuously receives the codes set in the headers. The PLC stores the received data except the headers.

2. Time at which receiving is completed

Receiving is completed in the following three conditions. When either condition is established, receiving is completed.

- 1) When the PLC receives the amount of receive data specified by the RS2 instruction
- 2) When the "terminators", "sum check" and "CR + LF" set in the communication format are received normally.

| | | | |
|------------|------------|-----------|-------|
| Data | CR+LF | | |
| Data | Terminator | | |
| Data | Terminator | CR+LF | |
| Data | Terminator | Sum check | |
| Data | Terminator | Sum check | CR+LF |

- 3) When data receiving is suspended and the PLC does not receive the next set of data within the time set within the time-out time setting device (D8409 or D8429), the time-out check flag (M8409 or M8429) turns ON.

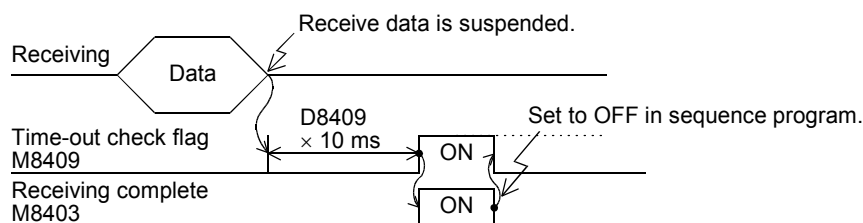
3. Operation of time-out check flag

When data receiving is suspended, if the PLC does not receive the next set of data within the preset time-out time setting, the time-out check flag is set to ON.

At this time, the receiving complete flag is also set to ON.

The time-out time setting can be set to a value from 1 to 255 (10 ms to 2550 ms).

| Name | ch1 | ch2 |
|-----------------------|-------|-------|
| Time-out check flag | M8409 | M8429 |
| Time-out time setting | D8409 | D8429 |



The time-out check flag does not turn OFF automatically. Set it to OFF in the sequence program. (When the receiving complete flag is set to OFF, the time-out check flag is also set to OFF.)

By using this function, the PLC can receive data from equipment where the amount of send data varies without the terminator.

4. When the control line is set to the interlink mode

When the interlink mode is selected in the communication format, the following sequence is adopted from start of receiving to completion of receiving:

- 1) When the amount of data already received becomes "preset amount of received data -30", the control line ER (DTR) turns OFF.
When the control line ER (DTR) turns OFF, the external equipment should suspend data sending.
After the control line ER (DTR) turns OFF, the PLC can receive up to 30 characters (bytes).
- 2) When the external equipment suspends data sending, the PLC sets the time-out check flag and receiving complete flag to ON after the preset time-out time setting.
Move the received data in a sequence program, and then set the receiving complete flag and time-out check flag to OFF.
- 3) When the receiving complete flag is set to OFF, the control line ER (DTR) turns ON.
When the control line ER (DTR) turns ON, restart data sending from the external equipment.
- 4) Repeat steps 1) to 3) until data receiving is completed.

5. Cautions on receiving

When receiving data, observe the following cautions

- 1) While the receiving complete flag is ON, the PLC cannot receive the next set of receive data.
When the receiving complete flag is set to OFF, the PLC waits to receive.
- 2) Set the amount of received data to a value including "terminators", "sum check" and "CR+LF".
If the specified amount of received data is small, the serial communication error flag (M8063 or M8438) turns ON.

8.2.6 Sum check code

The sum check code indicates a two-digit ASCII code converted from the lowest-order byte (8-bit) of the result (sum) acquired by adding the sum check target data as hexadecimal data.

By setting a parameter, set whether or not the sum check code is added in the message.

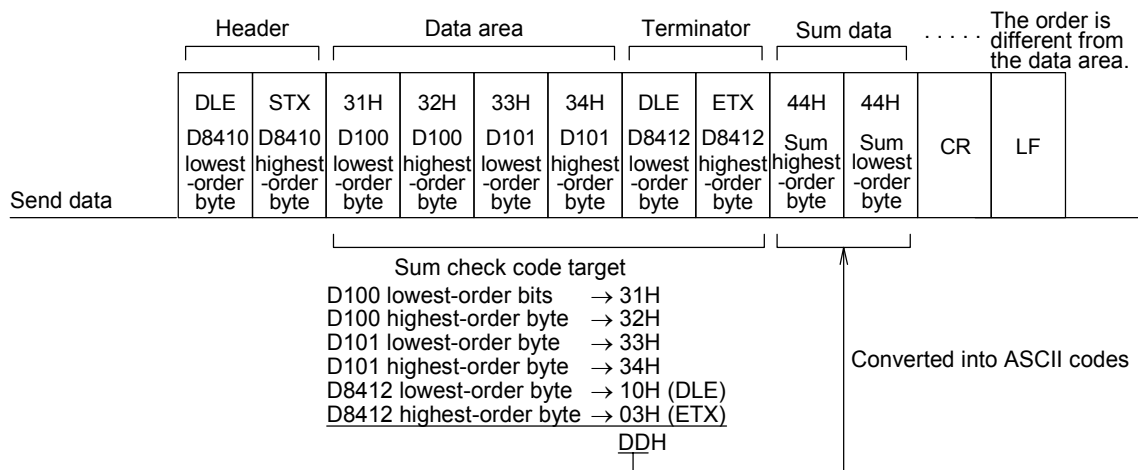
- When "sum check provided" is selected, the sum check code is added in the message during sending. During receiving, the sum check code is compared with the value calculated from the received data to check the received data.
- When "sum check not provided" is selected, the sum check code is not added, so the received data is not checked either.

A calculation example of the sum check code is shown below.

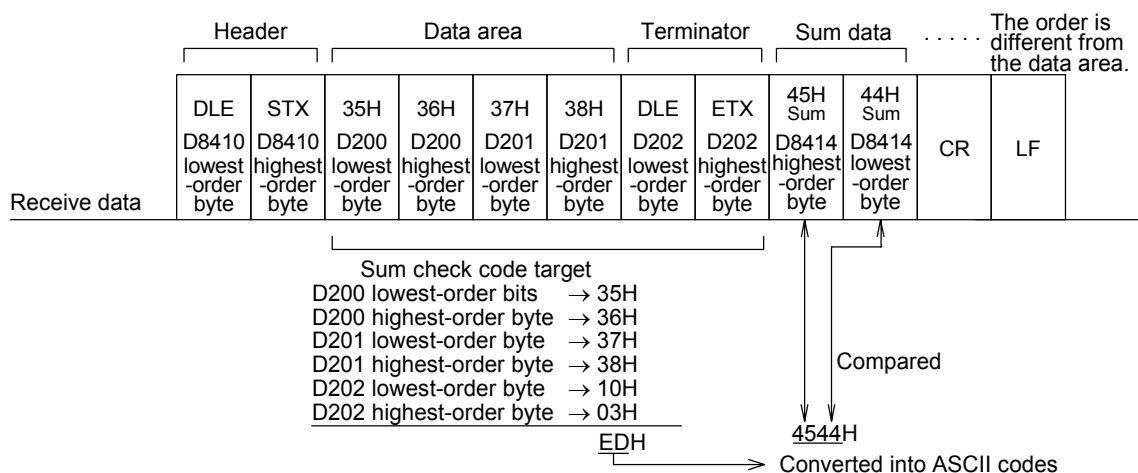
Example: When the communication format (parameters) is set as follows

- Control line not provided
- Headers provided [DLE+STX (D8410: 0210H, D8411: 0000H)]
- Terminators provided [DLE+ETX (D8412: 0310H, D8413: 0000H)]

In the case of send data

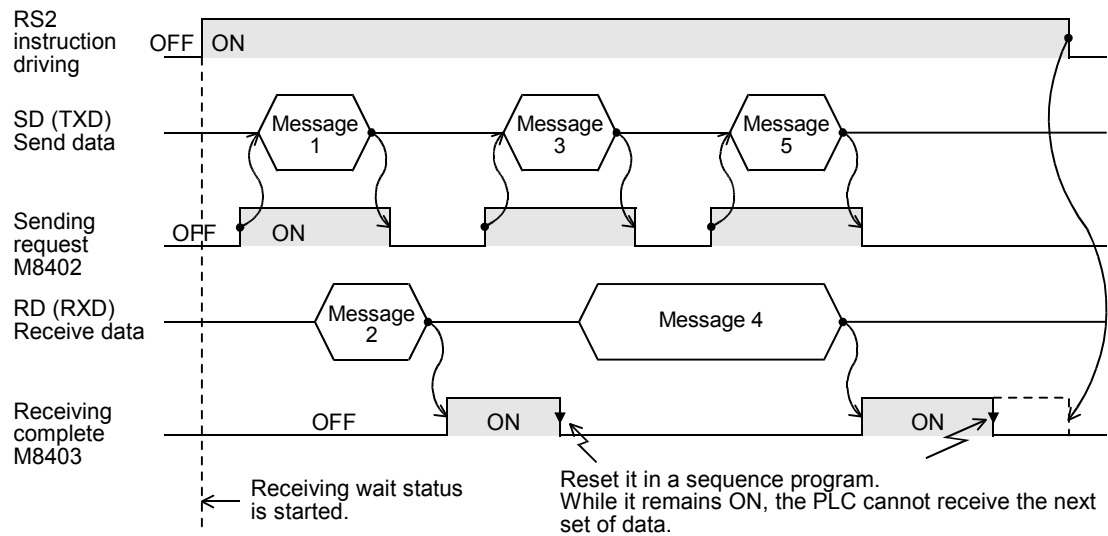


In the case of receive data



8.3 Operation of Control Line

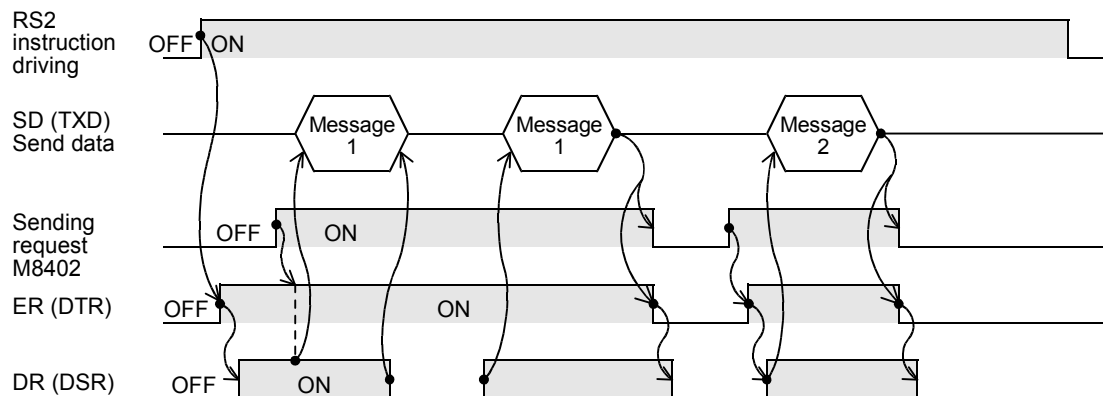
1. When the control line is not provided



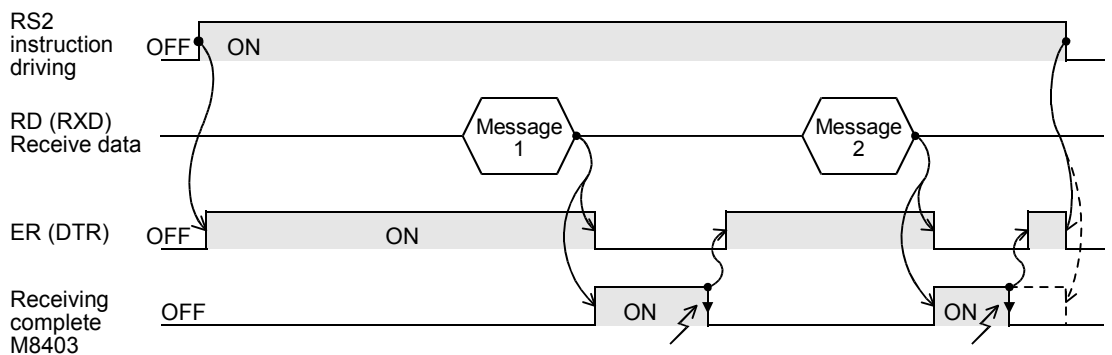
2. When the control line is in the standard mode

Use this mode when only sending or receiving.

1) When only sending is executed

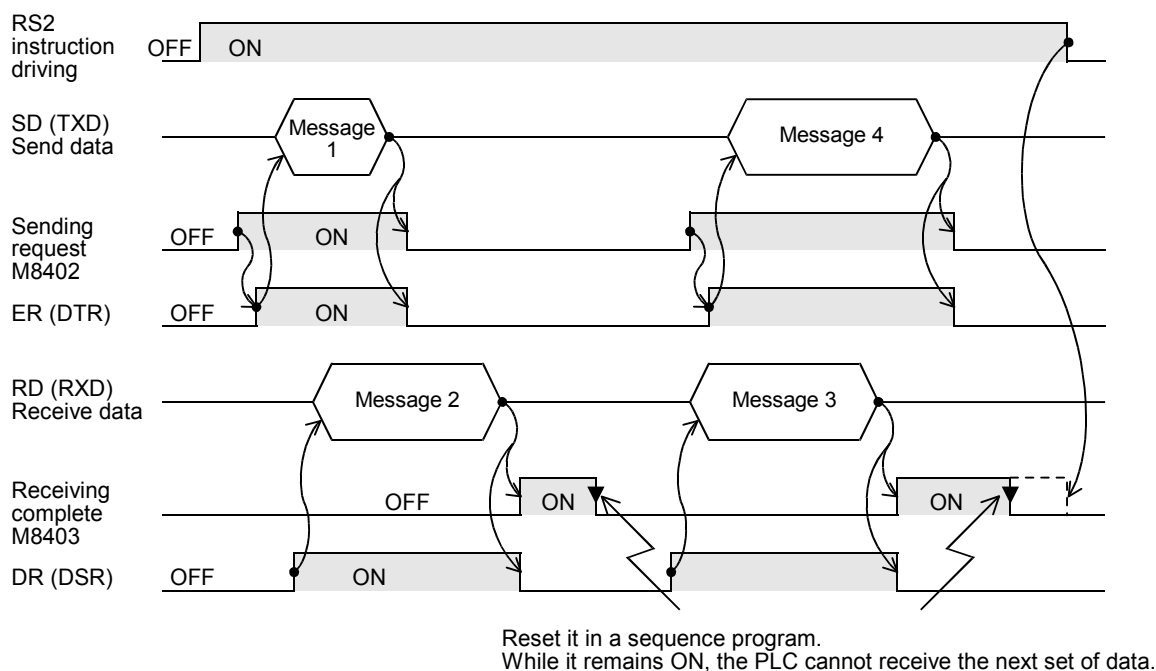


2) When only receiving is executed [The DR (DSR) signal is not used.]



Reset it in a sequence program.
While it remains ON, the PLC cannot receive the next set of data.

3. When the control line is in the modem mode



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

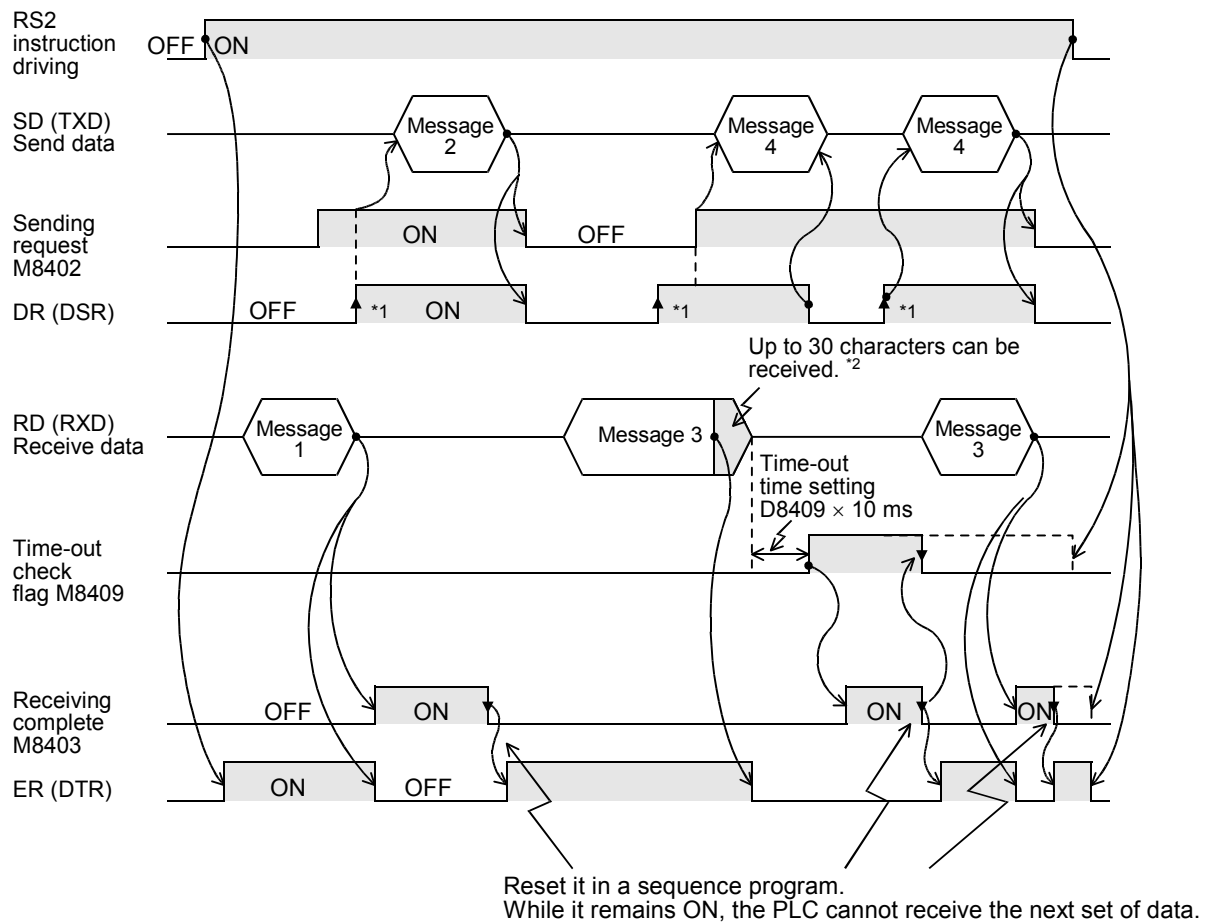
I

Remote Maintenance

Apx.

Discontinued models

4. When the control line is in the interlink mode



- *1. On the external equipment side, set the DR (DSR) signal to ON when the external equipment is ready to receive.
The FX3U/FX3UC PLC sends the send data when both the DR (DSR) signal and the sending request turn ON.
- *2. In the interlink mode, the PLC sets the ER (DTR) signal to OFF 30 characters before reaching the specified amount of received data, and asks the external equipment to stop sending. After that, the PLC can only receive up to 30 characters. In this case, temporarily stop sending, and then send the remaining data after the ER (DTR) signal turns ON again.
When sending is stopped, the PLC finishes receiving after the time-out time setting is reached.
When sending is not stopped, the PLC finishes receiving after it has received the final send data or 30 characters. Accordingly, make sure that the number of receive characters are "30 + α".

8.4 Important Points in Creating Programs

- 1) RS2 instruction can be used as many times as necessary in a program, but make sure that only one RS2 instruction is driven in each communication port at a time.
For multiple RS instructions to be driven, make sure the OFF time is longer than one scan time.
- 2) Do not use another instruction (such as RS instruction or IVDR instruction) which uses the same communication port. If such an instruction is used, communication may not function normally.
- 3) While RS2 instruction is being driven, change of D8400 or D8420 is prohibited.
To change D8400 or D8420, set the RS2 instruction to OFF, set D8400 or D8420 to "0", and then set a new value to D8400 or D8420.
- 4) In the interlink mode, set the amount of received data "n" to "31" or more.
If it is set to "30" or less, the control line ER (DTR) is set to OFF as soon as the PLC receives data.
- 5) FX3U and FX3UC PLCs execute full-duplex, bidirectional communication. When using half-duplex, bidirectional communication, pay attention not to turn ON the sending request flag while receiving.
- 6) When using the header and terminator, set them before driving the RS2 instruction. Do not change the setting while the RS2 instruction is being driven.

8.5 Communication Error

When a communication error occurs, the error flag M8063 turns ON during communication using ch1, or the error flag M8438 turns ON during communication using ch2.
D8063 or D8438 stores the error code respectively.

| Error code | | Description |
|-------------|-------------|--|
| D8063 (ch1) | D8438 (ch2) | |
| 6301 | 3801 | Parity error, overrun error or framing error |
| 6303 | 3803 | Receive data sum mismatch |
| 6304 | 3804 | Defective data format |

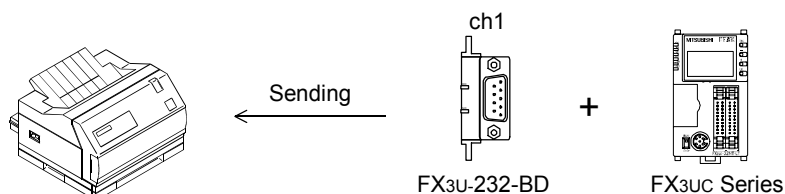
→ Confirm the contents in "Chapter 11. Troubleshooting".

9. Practical Program Example (RS2 Instruction)

9.1 Example of Printing Using RS2 Instruction (Using RS-232C Connection)

In this example, a printer with the RS-232C interface is connected to a PLC, and the data sent from the PLC is printed.

1. System configuration



Use a communication cable suitable to the pin arrangement of the connector of the printer used.

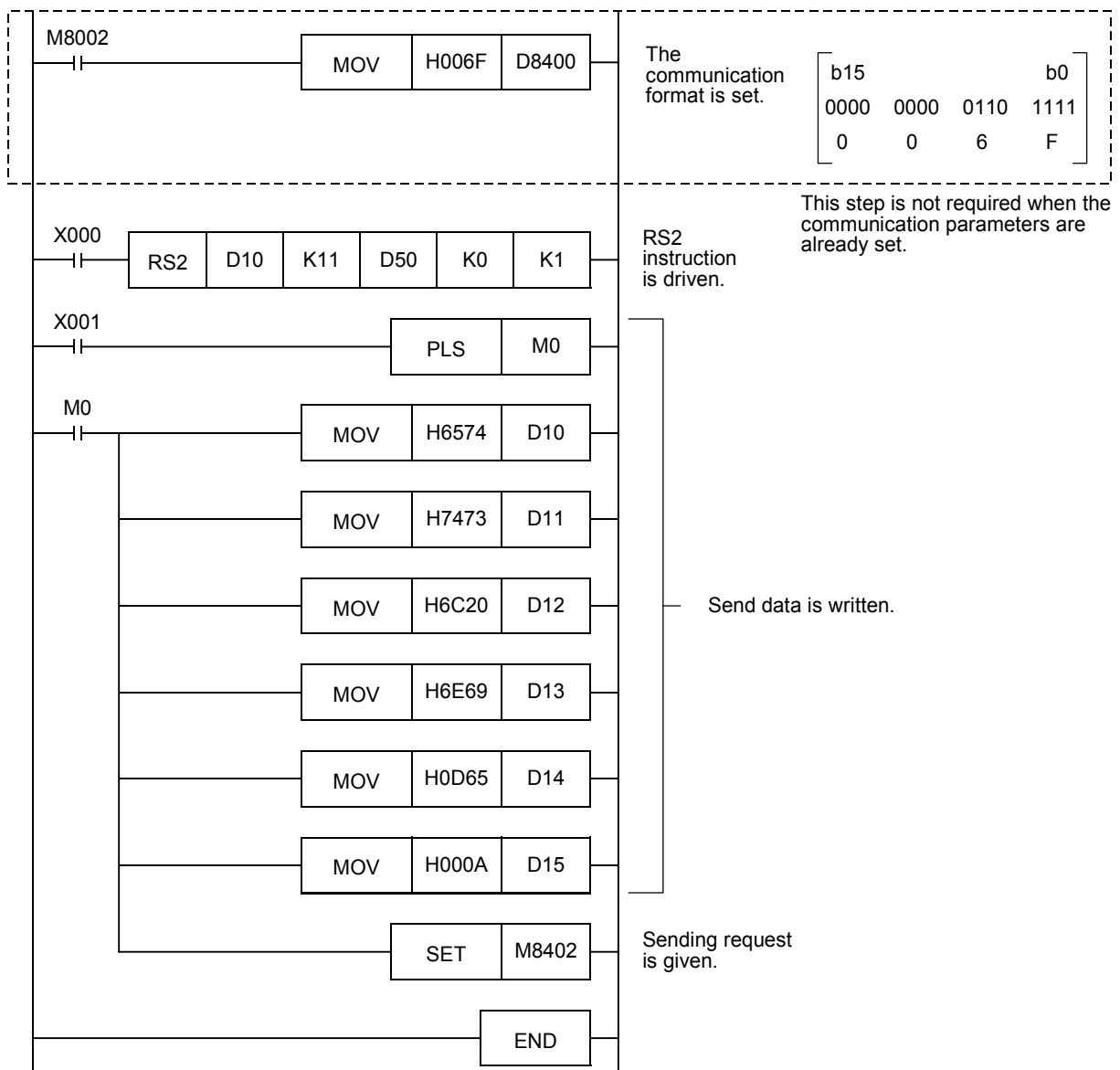
Communication format

Align the communication format in the PLC with that in the printer used.

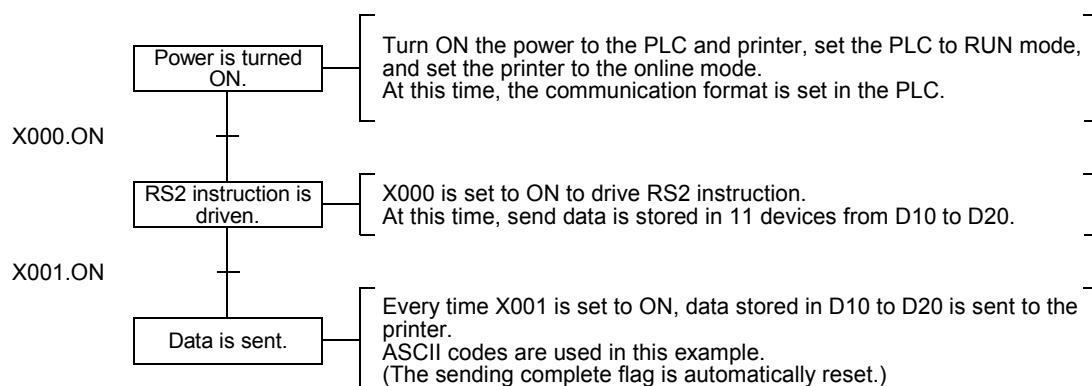
(The table below shows the communication format in the main unit.)

| | |
|--|----------------------------|
| Data length | 8-bit |
| Parity | Even |
| Stop bit | 2-bit |
| Baud rate | 2400 bps |
| Header | Not provided |
| Terminator | Not provided |
| Control line (H/W) | Standard/RS-232C, provided |
| Communication method (protocol) | Non-protocol method |
| CR, LF | Not provided |

2. Sequence program



3. Operation

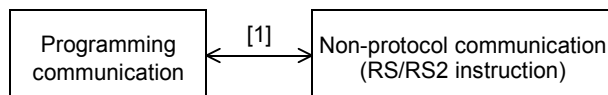


10. When Combined with Another Communication

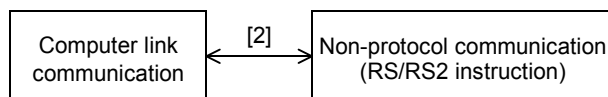
This chapter explains how to use non-protocol communication (RS or RS2 instruction) together with another communication type.

10.1 Other Communication Type Used Together

In FX PLCs, the following communication types can be changed over.



[1] Applicable only in FX2N (Ver. 2.01 or later), FX3U, FX2NC, and FX3UC PLCs.



[2] Applicable only in FX3U and FX3UC PLCs.

When changing over the communication types above, it is necessary to set the communication using a sequence program.

The tables below show devices used in sequence programs.

1) RS instruction

| Device | Name | Description |
|--------|---|---|
| D8120 | Communication format setting | Sets the communication format. |
| D8419 | Operation mode display (in FX3U and FX3UC) | Allows the communication type being executed to be checked. |

2) RS2 instruction

| Device | | Name | Description |
|--------|-------|------------------------------|---|
| ch1 | ch2 | | |
| D8400 | D8420 | Communication format setting | Sets the communication format. |
| D8419 | D8439 | Operation mode display | Allows the communication type being executed to be checked. |

→ For the communication setting method, refer to Section 10.6.
→ For details on the operation mode display, refer to Subsection 11.4.1.

10.2 When Combined with Programming Communication

In FX2N (Ver. 2.01 or later), FX3U, FX2NC, and FX3UC PLCs, non-protocol communication in accordance with RS-232C using RS instruction can be changed over to the programming communication for peripheral equipment.

10.2.1 For FX2N and FX2NC PLCs

In FX2N (Ver. 2.01 or later) and FX2NC PLCs, non-protocol communication using RS instruction by way of RS-232C port in the FX2N-232-BD (for FX2N PLCs), FX0N-232ADP, or FX2NC-232ADP can be changed over to the communication with a programming tool (programming communication) by the following methods. If the external equipment executes another type of communication while the programming communication is selected, the PLC sends back "NAK".

1. When changing over using RUN mode and STOP mode

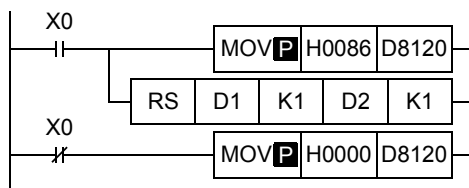
Set the communication format to one of the settings shown below to use non-protocol communication (in accordance with RS-232C) using the RS instruction while in RUN mode and then use the programming communication while in STOP mode.

| Item | Contents | | | |
|-----------------|--------------|----------|--------------|----------|
| | H0086 | H0186 | H0286 | H0386 |
| Data length | 7-bit | | | |
| Parity bit | Even | | | |
| Stop bit | 1-bit | | | |
| Baud rate (bps) | 9600 bps | | | |
| Header | Not provided | Provided | Not provided | Provided |
| Terminator | Not provided | | Provided | |
| Control line | Not provided | | | |

2. When changing over using the RS instruction while in RUN mode

When changing over non-protocol communication using RS instruction to the programming communication while in RUN mode, set RS instruction to OFF, and then overwrite the communication format (D8120) to "H0000".

Before starting up RS instruction again, make sure to properly overwrite the communication format (D8120) used in the RS instruction.



In this setting also, the communication mode can be changed over using RUN mode and STOP mode if the condition shown in 1 above is satisfied.

3. Caution on using the RS instruction and programming communication together

Do not use the communication setting by parameters. Use the communication format device (D8120).

10.2.2 For FX3U and FX3UC PLCs

In FX3U and FX3UC PLCs, non-protocol communication using RS instruction can be changed over to communication with a programming tool (programming communication) by the following methods.

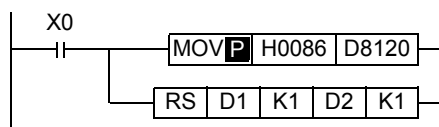
If the external equipment executes another type of communication while the programming communication is selected, the PLC sends back "NAK".

In FX3U and FX3UC PLCs, the communication type operating in the communication port can be checked in the operation mode display device (D8419).

1. When changing over using RUN mode and STOP mode

Set the communication format as shown below to use non-protocol communication (in accordance with RS-232C) using RS instruction while in RUN mode and then use the programming communication while in STOP mode.

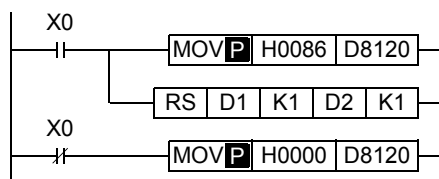
Make sure to set the communication format used in the RS instruction to D8120, and write it before executing the RS instruction.



2. When changing over using the RS instruction while in RUN mode

When changing over non-protocol communication using RS instruction to the programming communication while in RUN mode, set RS instruction to OFF, and then overwrite the communication format (D8120) to "H0000".

Before starting up RS instruction again, make sure to properly overwrite the communication format (D8120) used in the RS instruction.



3. Caution on using the RS instruction and programming communication together

Do not use the communication setting by parameters. Use the communication format device (D8120).

10.3 When Combined with Computer Link Communication (Only in FX3U and FX3UC)

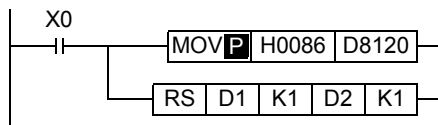
In FX3U and FX3UC PLCs, non-protocol communication (in accordance with RS-232C or RS-485) using the RS instruction can be changed over to a protocol dedicated to computer link by the following methods. The protocol supported by the communication port can be checked in the operation mode display device (D8149).

1. When changing over using RUN mode and STOP mode

Set the communication format as shown below to use non-protocol communication (in accordance with RS-232C or RS-485) using the RS instruction while in RUN mode and then use computer link while in STOP mode.

Set computer link using parameters.

Make sure to set the communication format used in the RS instruction to D8120, and write it before executing the RS instruction.

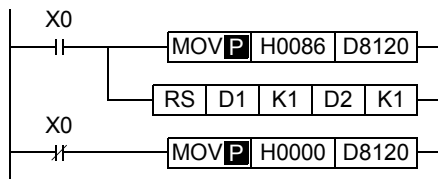


2. When changing over using the RS instruction while in RUN mode

When changing over non-protocol communication using the RS instruction to computer link while in RUN mode, set the RS instruction to OFF, and then overwrite the communication format (D8120) to "H0000".

Set computer link using parameters.

Before starting up the RS instruction again, make sure to properly overwrite the communication format (D8120) used in the RS instruction.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

10.4 When Combined with Programming Communication (FX3U and FX3UC only)

In FX3U and FX3UC PLCs, non-protocol communication using RS2 instruction can be changed over to communication with a programming tool (programming communication) by the following methods.

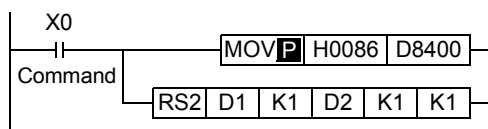
If the external equipment executes another type of communication while the programming communication is selected, the PLC sends back "NAK".

In FX3U and FX3UC PLCs, the communication type operating in the communication port can be checked in the operation mode display devices (D8419 and D8439).

1. When changing over using RUN mode and STOP mode

Set the communication format as shown below to use non-protocol communication (in accordance with RS-232C) using the RS2 instruction while in RUN mode and then use the programming communication while in STOP mode.

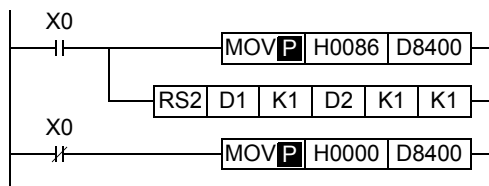
Make sure to set the communication format used in the RS2 instruction to D8400 or D8420, and write it before executing the RS2 instruction.



2. When changing over using the RS2 instruction while in RUN mode

When changing over non-protocol communication using the RS2 instruction to the programming communication while in RUN mode, set the RS2 instruction to OFF, and then overwrite the communication format (D8400 or D8420) to "H0000".

Before starting up the RS2 instruction again, make sure to properly overwrite the communication format (D8400 or D8420) used in the RS2 instruction.



3. Caution on using the RS2 instruction and programming communication together

Do not use the communication setting by parameters. Use the communication format device (D8400 or D8420).

10.5 Using RS2 Instruction and Computer Link Communication Together (FX3U and FX3UC only)

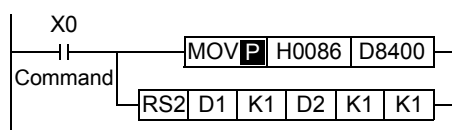
In FX3U and FX3UC PLCs, non-protocol communication (in accordance with RS-232C or RS-485) using RS2 instruction can be changed over to computer link by the following methods.

In FX3U and FX3UC PLCs, the communication type operating in the communication port can be checked in the operation mode display devices (D8419 and D8439).

1. When changing over using RUN mode and STOP mode

Set the communication format as shown below to use non-protocol communication (in accordance with RS-232C) using RS2 instruction while in RUN mode and then use a protocol for computer link while in STOP mode. Set computer link using parameters.

Make sure to set the communication format used in the RS2 instruction to D8400 or D8420, and write it before executing the RS2 instruction.



Non-protocol communication (in accordance with RS-485) cannot be changed over to computer link using RUN mode and STOP mode.

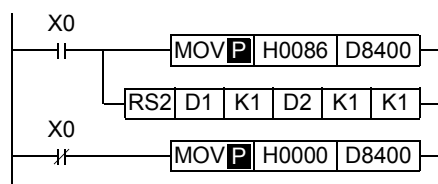
When changing over non-protocol communication (in accordance with RS-485) to computer link, refer to "2. When changing over using the RS2 instruction while in RUN mode" below.

2. When changing over using the RS2 instruction while in RUN mode

When changing over non-protocol communication using the RS2 instruction to computer link while in RUN mode, set the RS2 instruction to OFF, and then overwrite the communication format (D8400 or D8420) to "H0000".

Set computer link using parameters.

Before starting up the RS2 instruction again, make sure to properly overwrite the communication format (D8400 or D8420) used in the RS2 instruction.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

10.6 Communication Setting Method Using Sequence Program

In the setting method using a sequence program, transfer values to the communication format device (D8120, D8400 or D8420).

This section explains related devices and the setting method using a sequence program.

10.6.1 Communication setting for RS instruction

The following device is used in the communication setting.

1. D8120 (communication format)

By setting values to D8120, the data length, parity, baud rate, etc. can be set.

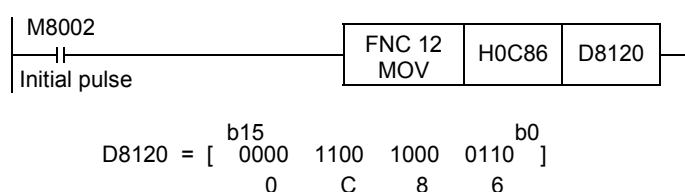
The table below shows the contents of D8120.

| Bit No. | Name | Contents | |
|----------------------|--------------------|--|--|
| | | 0 (bit = OFF) | 1 (bit = ON) |
| b0 | Data length | 7-bit | 8-bit |
| b1 b2 | Parity | b2, b1 (0, 0): Not provided (0, 1): Odd (1, 1): Even | |
| b3 | Stop bit | 1-bit | 2-bit |
| b4 b5 b6 b7 | Baud rate (bps) | b7, b6, b5, b4 (0, 0, 1, 1): 300 (0, 1, 0, 0): 600 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 | b7, b6, b5, b4 (0, 1, 1, 1): 4800 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 |
| b8 | Header | Not provided | Provided (D8124) initial value: STX (02H) |
| b9 | Terminator | Not provided | Provided (D8125) initial value: ETX (03H) |
| b10 b11 | Control line | Non-protocol communication | b11, b10 (0, 0): Not provided <RS-232C interface> (0, 1): Standard mode <RS-232C interface> (1, 0): Interlink mode <RS-232C interface> (FX2N whose version is Ver. 2.00 or later, FX3U, FX2NC, and FX3UC) (1, 1): Modem mode <RS-232C interface, RS-485/RS-422 interface ^{*2} > |
| | | Computer link | b11, b10 (0, 0): RS-485/RS-422 interface (1, 0): RS-232C interface |
| b12 | Not applicable | | |
| b13 ^{*1} | Sum check | Not added | Added |
| b14 ^{*1} | Protocol | Not used | Used |
| b15 ^{*1} | Control procedure | Format 1 | Format 4 |

*1. Make sure to set as "0" when using non-protocol communication.

*2. When using the RS-485/RS-422 interface, only FX1S, FX0N, FX1N, FX2N, FX3U, FX1NC, FX2NC, and FX3UC PLCs are applicable.

To set the communication type, use the following program.



| Data length | 7-bit |
|--------------|--------------|
| Parity | Even |
| Stop bit | 1-bit |
| Baud rate | 9600 bps |
| Protocol | Non-protocol |
| Header | Not provided |
| Terminator | Not provided |
| Control line | Modem mode |

10.6.2 Communication setting for RS2 instruction

The following devices are used in the communication setting.
When using communication port ch1, set D8400.
When using communication port ch2, set D8420.

1. D8400 and D8420 (communication format)

By setting values to D8400 or D8420, the data length, parity, baud rate, etc. can be set.
The table below shows the contents of D8400 and D8420.

| Bit No. | Name | Contents | |
|----------------------|----------------------------|--|--|
| | | 0 (bit = OFF) | 1 (bit = ON) |
| b0 | Data length | 7-bit | 8-bit |
| b1 b2 | Parity | b2, b1 (0, 0): Not provided (0, 1): Odd (1, 1): Even | |
| b3 | Stop bit | 1-bit | 2-bit |
| b4 b5 b6 b7 | Baud rate (bps) | b7, b6, b5, b4 (0, 0, 1, 1): 300 (0, 1, 0, 0): 600 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 | b7, b6, b5, b4 (0, 1, 1, 1): 4800 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 |
| b8 | Header | Not provided | Provided*2 |
| b9 | Terminator | Not provided | Provided*2 |
| b10 b11 b12 | Control line | Non-protocol communication | b12, b11, b10 (0, 0, 0): Not provided <RS-232C interface> (0, 0, 1): Standard mode <RS-232C interface> (0, 1, 0): Interlink mode <RS-232C interface> (0, 1, 1): Modem mode <RS-232C interface> (1, 1, 1): Communication in accordance with RS-485 <RS-485/RS-422 interface> |
| b13 | Sum check | Not added | Added*3 |
| b14*1 | Protocol | Not used | Used |
| b15 | Control procedure (CR, LF) | CR, LF: Not used (Format 1) | CR, LF: Used (Format 4) |

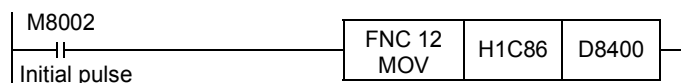
*1. Make sure to set as "0" when using non-protocol communication.

*2. In RS2 instruction, up to four headers and up to four terminators can be set.

*3. When executing non-protocol communication using RS2 instruction, add the sum check code after the terminators.

Make sure to set the terminators when adding the sum check code.

To set the communication type, use the following program.



D8120 = [^{b15} 0001 1100 1000 0110 ^{b0}]
 1 C 8 6

| Data length | 7-bit |
|--------------|---|
| Parity | Even |
| Stop bit | 1-bit |
| Baud rate | 9600 bps |
| Protocol | Non-protocol |
| Header | Not provided |
| Terminator | Not provided |
| Control line | Communication in accordance with RS-485 |

11. Troubleshooting

This chapter explains troubleshooting and error codes.

11.1 Checking FX PLC Version Applicability

Verify that the FX PLC main unit is an applicable version in non-protocol communication.

→ **For version applicability, refer to Section 1.3.**

11.2 Checking Communication Status Based on LED Indication

Check the status of the "RD" and "SD" indicator LEDs provided in the optional equipment.

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RD | SD | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received |
| Off | Off | Data is not sent nor received. |

11.3 Checking Installation

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ **For mounting method, refer to the respective communication equipment manual.**

2. Power supply (for FX0N-485ADP)

The FX0N-485ADP requires a driving power supply. Verify that the power supply is provided correctly.

3. Wiring

Verify that the wiring to an communication equipment is correct. If the communication equipment is wired incorrectly, communication is not possible.

→ **For wiring method check, refer to Chapter 4.**

11.4 Checking Sequence Program

1. Communication settings in a sequence program

Verify that N:N Network (D8176 to D8180) and parallel link (M8070 and M8071) are not set.
Verify that the communication format (D8120, D8400 or D8420) is set correctly. If a communication port is set more than once, communication is not possible.
After changing any settings, make sure to turn OFF the PLC power, and then turn it ON again.

2. Communication settings using parameters

Verify that the communication settings using parameters are correct. If the contents of the settings do not agree, communication will not function correctly.
After changing any settings, make sure to turn OFF the PLC power, and then turn it ON again.

3. Presence of VRRD and VRSC instructions (except FX3U and FX3UC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program.
If these instructions are used, delete them, turn OFF the PLC power, and then turn it ON again.

4. Presence of IVCK, IVDR, IVRD, IVWR, and IVBWR instructions (in FX3U and FX3UC PLCs)

Verify that the IVCK, IVDR, IVRD, IVWR and IVBWR instructions are not being used for the same channel.
If these instructions are used for the same channel, revise them, turn OFF the PLC power, and then turn it ON again.

5. Presence of EXTR instruction (in FX2N and FX2NC PLCs)

Verify that the EXTR instruction is not used in the program.
If this instruction is used, delete it, turn OFF the PLC power, and then turn it ON again.

6. Presence of RS and RS2 instruction

Verify that two or more RS/RS2 instructions are not being driven for the same channel.
If two or more RS/RS2 instructions are driven, modify the program so that only one RS/RS2 instruction is driven.

11.4.1 Checking communication port settings (in FX3U and FX3UC PLCs)

1. Checking the operation mode

In FX3U and FX3UC PLCs, the communication port operation status can be checked.
D8419 stores the communication type code currently adopted in communication port ch1.
D8439 stores the communication type code currently adopted in communication port ch2.
The table below shows the contents of the communication type codes.

| Code | Description |
|------|-------------------------------------|
| 0 | Programming communication |
| 2 | Protocol dedicated to computer link |
| 3 | N:N Network |
| 4 | RS instruction |
| 5 | RS2 instruction |
| 6 | Parallel link |
| 7 | Inverter instruction |

If the operation mode is different, check the parameters and sequence programs.

11.5 Checking the Absence/Presence of Errors

1. Checking for communication errors

When a communication error occurs, the serial communication error flag turns ON.

In all PLCs except FX3U and FX3UC PLCs and when communication port ch1 is used in FX3U and FX3UC PLCs, M8063 turns ON.

When communication port ch2 is used in FX3U and FX3UC PLCs, M8438 turns ON.

When the serial communication error flag turns ON, D8063 or D8438 stores the corresponding error code.

2. Checking the error code

When the serial communication error flag turns ON, a corresponding error code shown below is stored in D8063 or D8438.

| Error code | | Contents of error |
|-------------|-------------|--|
| ch1 (D8063) | ch2 (D8438) | |
| 6301 | 3801 | Parity error, overrun error or framing error |
| 6302 | 3802 | Defective communication character |
| 6303 | 3803 | Communication data sum mismatch |
| 6304 | 3804 | Defective data format |
| 6305 | 3805 | Defective command |
| 6306 | 3806 | Monitoring timeout |
| 6307 | 3807 | Modem initialization error |
| 6308 | 3808 | N:N Network parameter error |
| 6312 | 3812 | Parallel link parameter error |
| 6313 | 3813 | Parallel link sum error |
| 6314 | 3814 | Parallel link format error |
| 6320 | 3820 | Error in communication with inverter |

When an error code above is stored, check the following items:

- Wiring
- Parameter settings

12. Related Data

12.1 Related Device List (RS Instruction)

1. Bit devices

| Device | Name | Description | R/W |
|---------|---------------------------------|--|-----|
| M8063 | Serial communication error flag | This device turns ON when a communication error occurs. | R |
| M8120 | Communication setting keep | This device keeps the communication setting status (for FX0N PLC). | W |
| M8121 | Sending wait flag | This device remains ON while the PLC is waiting to send. | R |
| M8122 | Sending request | When this device is set to ON by SET instruction, the PLC starts to send. | R/W |
| M8123 | Receiving complete flag | This device turns ON when receiving is completed. | R/W |
| M8124 | Carrier detection flag | This device turns ON and OFF in synchronization with the CD signal. | R |
| M8129*1 | Time-out check flag | This device turns ON when data receiving is suspended and the next set of receive data is not given within the time set by the time-out time setting device (D8129). | R/W |
| M8161 | 8-bit processing mode | This device sets the send/receive data to 16-bit data or 8-bit data. | W |

R: Read only

W: Write only

R/W: Read or Write

*1. Not provided in FX0N, FX2(FX), FX2C, and FX2N (before Ver. 2.00) PLCs.

2. Word devicesite

| Device | Name | Description | R/W |
|---------|---------------------------------|---|-----|
| D8063 | Serial communication error code | When the serial communication error flag (M8063) turns ON, this device stores the corresponding error code. | R/W |
| D8120 | Communication format setting | This device sets the communication format. | R/W |
| D8122 | Amount of remaining send data | This device stores the amount of remaining send data. | R |
| D8123 | Amount of data already received | This device stores the amount of data already received. | R |
| D8124 | Header | This device sets the header (initial value: STX (H02)). | R/W |
| D8125 | Terminator | This device sets the terminator (initial value: ETX (H03)). | R/W |
| D8129*1 | Time-out time setting | This device sets the time-out time. | R/W |
| D8405*2 | Communication parameter display | This device stores communication parameters set in the PLC. | R |
| D8419*2 | Operation mode display | This device stores the communication type being used. | R |

R: Read only

R/W: Read or Write

*1. Not provided in FX0N, FX2(FX), FX2C, and FX2N (before Ver. 2.00) PLCs.

*2. Provided only in FX3U and FX3UC PLCs.

12.2 Details of related devices (RS instruction)

This section explains devices used during non-protocol communication.

12.2.1 Serial communication error [M8063]

This device turns ON when an error occurs during serial communication.

1. Detailed contents

This device works as the serial communication error flag.
When this device turns ON, a corresponding error code is stored in D8063.

2. Cautions on use

The serial communication error flag does not turn OFF even after communication recovers its normal status.
Clear it by switching the PLC mode from STOP to RUN.

12.2.2 Communication setting keep [M8120]

Set this device to ON in a sequence program so that the communication setting is kept (for FX0N PLCs).

1. Detailed contents

In FX0N PLCs, set M8120 to ON in a sequence program so that the communication format setting is kept.

2. Cautions on use

In FX0N PLCs, the communication setting status is kept only when M8120 is set to ON.
In any PLC other than the FX0N PLCs, setting of M8120 is not required.

12.2.3 Sending wait flag [M8121]

This device remains ON while the PLC is waiting to send.

1. Detailed contents

- In full-duplex communication in FX3U and FX3UC PLCs
While the control line is set to the standard or interlink mode in a communication parameter, when the control line DR (DSR) turns OFF while sending data, the PLC waits to send and M8121 turns ON.
- In full-duplex communication in all PLCs except FX3U and FX3UC PLCs
M8121 does not turn ON.
- In half-duplex communication
When the sending request device is set to ON while data is being received, the PLC waits to send and M8121 turns ON.

12.2.4 Sending request [M8122]

When this device is set to ON by the SET instruction, the PLC starts to send.

1. Detailed contents

When this device is set to ON by the SET instruction, the PLC starts to send. When sending is completed, this device is automatically set to OFF.

2. Cautions on use

When setting this device to ON, set the drive condition in the pulse type.
In FX2(FX), FX2C, FX1S, FX0N, FX1N, FX1NC, and FX2N (before Ver. 2.00) PLCs, note the following contents:

- While the PLC is receiving data, next data is sent after the receiving is finished. During this period, the sending wait flag remains ON.
- From when the head data is received until the receiving complete flag turns ON, it is regarded as data is being received. If a sending request is given while the head data is being received, data is confused.

12.2.5 Receiving complete flag [M8123]

This device turns ON when receiving is completed.

1. Detailed contents

This device turns ON when receiving is completed.

Receiving is completed in one of the following three conditions.

- When the PLC receives the amount of receive data specified by RS instruction
- When "terminator provided" is selected in the communication format, and the PLC receives the code set in the terminator
- When data receiving is suspended and the PLC does not receive the next set of data within the time set in the time-out time setting device

When the receiving complete flag turns ON, transfer the received data to another storage destination, and then set this flag to OFF.

When this flag is set to OFF, the PLC waits to receive.

2. Cautions on use

When RS instruction is driven while the amount of received data is set to "0", the PLC does not wait to receive. In such a case, set the amount of received data to "1" or more, set the receiving complete flag to ON, and then set it to OFF.

12.2.6 Carrier detection flag [M8124]

This device turns ON and OFF in synchronization with the CD (DCD) signal.

1. Detailed contents

The CD (DCD) signal (channel receiving carrier detection) turns ON when the modem line is established.

While the carrier detection flag is OFF, the dial number can be sent.

While the carrier detection flag is ON, data can be sent and received.

12.2.7 Time-out check flag [M8129]

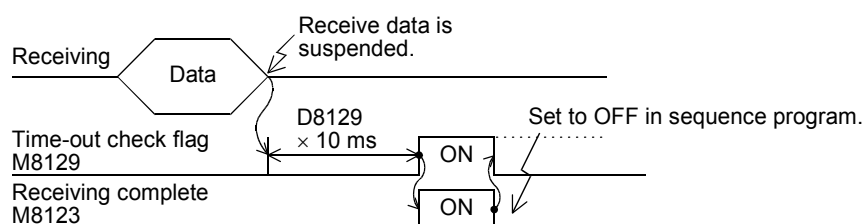
This device turns ON when data receiving is suspended, and the next set of receive data is not given within the time set by the time-out time setting device.

1. Detailed contents

This device turns ON when data receiving is suspended and the next set of receive data is not given within the time set by the time-out time setting device. The receiving complete flag also turns ON.

The time-out check flag turns OFF when the PLC waits to receive.

Using this function, the PLC can receive data from equipment where the amount of send data varies without the terminator.



12.2.8 Serial communication error code [D8063]

When a serial communication error occurs, this device stores the corresponding error code.

1. Detailed contents

When a serial communication error occurs, this device stores the corresponding error code shown below.

| Error code | Contents of error |
|------------|--|
| 6301 | Parity error, overrun error or framing error |
| 6302 | Defective communication character |
| 6303 | Communication data sum mismatch |
| 6304 | Defective data format |
| 6305 | Defective command |
| 6306 | Monitoring timeout |
| 6307 | Modem initialization error |
| 6308 | N:N Network parameter error |
| 6312 | Parallel link character error |
| 6313 | Parallel link sum error |
| 6314 | Parallel link format error |
| 6320 | Error in communication with inverter |

2. Cautions on use

The serial communication error code is not cleared even after communication recovers its normal status. Clear it by switching the PLC mode from STOP to RUN.

12.2.9 Communication format setting [D8120]

This device sets the communication format.

1. Detailed contents

This device can set the data length, parity, baud rate, etc.

The table below shows the contents of the communication format setting.

| Bit No. | Name | Contents | |
|----------------------|-------------------|--|--|
| | | 0 (bit = OFF) | 1 (bit = ON) |
| b0 | Data length | 7-bit | 8-bit |
| b1 b2 | Parity | b2, b1 (0, 0): Not provided (0, 1): Odd (1, 1): Even | |
| b3 | Stop bit | 1-bit | 2-bit |
| b4 b5 b6 b7 | Baud rate (bps) | b7, b6, b5, b4 (0, 0, 1, 1): 300 (0, 1, 0, 0): 600 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 | b7, b6, b5, b4 (0, 1, 1, 1): 4800 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 |
| b8 | Header | Not provided | Provided (D8124) Initial value: STX (02H) |
| b9 | Terminator | Not provided | Provided (D8125) Initial value: ETX (03H) |
| b10 b11 | Control line | Non-protocol communication | b11, b10 (0, 0): Not provided <RS-232C interface> (0, 1): Standard mode <RS-232C interface> (1, 0): Interlink mode <RS-232C interface> (FX2N whose version is Ver. 2.00 or later, FX3U, FX2NC, and FX3UC) (1, 1): Modem mode <RS-232C interface, RS-485/RS-422 interface ^{*2} > |
| | | Computer link | b11, b10 (0, 0): RS-485/RS-422 interface (1, 0): RS-232C interface |
| b12 | | Not applicable | |
| b13 ^{*1} | Sum check | Not added | Added |
| b14 ^{*1} | Protocol | Not used | Used |
| b15 ^{*1} | Control procedure | Format 1 | Format 4 |

*1. Make sure to set as "0" when using non-protocol communication.

*2. When using the RS-485/RS-422 interface, only FX1S, FX0N, FX1N, FX2N, FX3U, FX1NC, FX2NC, and FX3UC PLCs are applicable.

2. Cautions on use

In all PLCs except FX2(FX), FX2C, and FX0N PLCs, the communication format can be set using parameters. When setting the communication format in FX0N PLCs, set the communication setting latched (battery backed) device (M8120) to ON.

12.2.10 Amount of remaining send data [D8122]

This device stores the amount of remaining send data.

1. Detailed contents

This device stores the amount of remaining send data in 8-bit (1 byte) units. Only data in communication frames are regarded as targets of counting.

12.2.11 Amount of data already received [D8123]

This device stores the amount of data already received.

1. Detailed contents.

This device stores the amount of data already received in 8-bit (1 byte) units.

12.2.12 Header [D8124]

This device sets the header.

1. Detailed contents

When "header provided" is selected in the communication format setting, the lowest-order byte of D8124 is used.

When data is sent, the data in the lowest-order byte of D8124 is added at the head of the specified send data.

When data is received, receiving begins when the data in the lowest-order byte of D8124 is received.

12.2.13 Terminator [D8125]

This device sets the terminator.

1. Detailed contents

When "terminator provided" is selected in the communication format setting, the lowest-order byte of D8125 is used.

When data is sent, the lowest-order byte of D8125 is added at the end of the specified send data.

When data is received, receiving is completed when the data in the lowest-order byte of D8125 is received.

12.2.14 Time-out time setting time [D8129]

This device sets the time-out time setting.

1. Detailed contents

This device sets the error evaluation time (in 10-ms units) used when receiving of data is interrupted.

The setting range is from 1 to 255 (10 ms to 2550 ms).

2. Cautions on use

In all PLCs except FX2(FX), FX2C, and FX0N PLCs, the time-out time setting can be set using a parameter.

When setting the time-out time setting in FX0N PLCs, set the communication setting latched (battery backed) device (M8120) to ON.

12.2.15 Communication parameter display [D8405]

This device stores the communication parameters set in the PLC (in FX3U and FX3UC PLCs).

1. Detailed contents

When the PLC power is turned ON, D8405 stores the contents of the communication parameters.

The contents of the parameters are the same as those of the communication format setting device (D8120).

12.2.16 Operation mode display [D8419]

This device stores the communication type being used.

1. Detailed contents

This device stores the code of the communication type currently being used by the communication port. The table below shows the contents of the codes.

| Code | Description |
|------|-------------------------------------|
| 0 | Programming communication |
| 2 | Protocol dedicated to computer link |
| 3 | N:N Network |
| 4 | RS instruction |
| 5 | RS2 instruction |
| 6 | Parallel link |
| 7 | Inverter instruction |

2. Cautions on use

This device stores "4" while RS instruction is driven or when the RS instruction is not changed over to another mode.

12.3 Related Devices (RS2 Instruction)

1. Bit devices

| Device | | Name | Description | R/W |
|----------|-------|----------------------------|---|-----|
| ch1 | ch2 | | | |
| M8063 | M8438 | Serial communication error | This device turns ON when a communication error occurs. When this device (serial communication error) turns ON, D8063 or D8438 stores the corresponding error code. | R |
| M8401 | M8421 | Sending wait flag | This device remains ON while the PLC is waiting to send. | R |
| M8402 | M8422 | Sending request | When this device is set to ON, the PLC starts to send. | R/W |
| M8403 | M8423 | Receiving complete flag | This device turns ON when receiving is completed. While this device (receiving complete flag) is ON, the PLC cannot receive any receive data. | R/W |
| M8404 | M8424 | Carrier detection flag | This device turns ON in synchronization with the CD (DCD) signal. | R |
| *1 M8405 | M8425 | Data set ready (DSR) flag | This device turns ON in synchronization with the DR (DSR) signal. | R |
| M8409 | M8429 | Time-out check flag | This device turns ON when data receiving is suspended and the next set of receive data is not given within the time set by the time-out time setting device. | R/W |

R: Read only

R/W: Read or Write

*1. Available in Ver.2.30 or later of FX3U or FX3UC PLC

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2. Word devices

| Device | | Name | Description | R/W |
|--------|-------|------------------------------------|---|-----|
| ch1 | ch2 | | | |
| D8063 | D8438 | Serial communication error code | When the serial communication error flag turns ON, this device stores the corresponding error code. | R/W |
| D8400 | D8420 | Communication format setting | This device sets the communication format. | R/W |
| D8402 | D8422 | Amount of remaining send data | This device stores the amount of remaining send data. | R |
| D8403 | D8423 | Amount of data already received | This device stores the amount of data already received. | R |
| D8405 | D8425 | Communication parameter display | This device stores communication parameters set in the PLC. | R |
| D8409 | D8429 | Time-out time setting | This device sets the timeout time. | R/W |
| D8410 | D8430 | Header 1 and header 2 | These devices set the headers 1 to 4. | R/W |
| D8411 | D8431 | Header 3 and header 4 | | R/W |
| D8412 | D8432 | Terminator 1 and terminator 2 | These devices set the terminators 1 to 4. | R/W |
| D8413 | D8433 | Terminator 3 and terminator 4 | | R/W |
| D8414 | D8434 | Receiving sum (receive data) | This device stores the received sum check value. | R |
| D8415 | D8435 | Receiving sum (calculation result) | This device stores the sum check value calculated from the received data. | R |
| D8416 | D8436 | Sending sum | This device stores the sum check value added to the send data. | R |
| D8419 | D8439 | Operation mode display | This device stores the communication type being used. | R |

R: Read only

R/W: Read or Write

12.4 Details of Related Devices (RS2 Instruction)

12.4.1 Serial communication error [M8063 and M8438]

These devices turn ON when an error occurs during serial communication.

1. Detailed contents

These devices work as serial communication error flags.

M8063 turns ON when an error occurs in serial communication using communication port ch1.

M8438 turns ON when an error occurs in serial communication using communication port ch2.

When M8063 turns ON, a corresponding error code is stored in D8063.

When M8438 turns ON, a corresponding error code is stored in D8438.

2. Cautions on use

The serial communication error flag does not turn OFF even after communication recovers its normal status.

Clear it by switching the PLC mode from STOP to RUN.

12.4.2 Sending wait flag [M8401 and M8421]

These devices remain ON while the PLC is waiting to send.

1. Detailed contents

M8401 remains ON while the PLC is waiting to send in communication using communication port ch1.

M8421 remains ON while the PLC is waiting to send in communication using communication port ch2.

- In full-duplex communication

While the control line is set to the standard or interlink mode in the communication parameter, when the control line DR (DSR) turns OFF while sending data, the PLC waits to send and M8401 or M8421 turns ON.

- In half-duplex communication

When the sending request device is set to ON while data is being received, the PLC waits to send and M8401 or M8421 turns ON.

12.4.3 Sending request [M8402 and M8422]

When these devices are set to ON by SET instruction, the PLC starts to send.

1. Detailed contents

When these devices are set to ON by SET instruction, the PLC starts to send. When sending is completed, these devices are automatically set to OFF.

When communication port ch1 is used, M8402 is set.

When communication port ch2 is used, M8422 is set.

2. Cautions on use

When setting these devices to ON, set the drive condition in the pulse type.

12.4.4 Receiving complete flag [M8403 and M8423]

These devices turn ON when receiving is completed.

1. Detailed contents

These devices turn ON when receiving is completed.

When communication port ch1 is used, M8403 is set.

When communication port ch2 is used, M8423 is set.

Receiving is completed in one of the following three conditions.

- When the PLC receives the amount of receive data specified by the RS2 instruction
- When the terminators are set, and the PLC receives the code set by the terminator
- When data receiving is suspended and the PLC does not receive the next set of data within the time set by the time-out time setting device

When the receiving complete flag turns ON, transfer the received data to another storage destination, and then set this flag to OFF.

When this flag is set to OFF, the PLC waits to receive.

2. Cautions on use

When the RS2 instruction is driven while the amount of received data is set to "0", the PLC does not wait to receive. To make the PLC wait to receive it is necessary to set the amount of received data "n" to "1" or more and set the receiving complete flag to OFF from ON.

12.4.5 Carrier detection flag [M8404 and M8424]

These devices turn ON/OFF in synchronization with the CD (DCD) signal.

1. Detailed contents

The CD (DCD) signal (channel receiving carrier detection) turns ON when the modem line is established.

When communication port ch1 is used, M8404 turns ON/OFF.

When communication port ch2 is used, M8424 turns ON/OFF.

While the carrier detection flag is OFF, the dial number can be sent.

While the carrier detection flag is ON, data can be sent and received.

12.4.6 Data set ready (DSR) flag [M8405 and M8425]

These devices turn ON/OFF in synchronization with the DR (DSR) signal.

1. Detailed contents

The state of DR (DSR) signal can be checked when executing RS2 instruction.

When communicating port ch1 is used, M8405*¹ turns ON/OFF.

When communication port ch2 is used, M8425*¹ turns ON/OFF.

The images of M8405 and M8425 are updated during END processing.

*1. Supported in FX3U and FX3UC PLCs Ver.2.30 and later.

| | |
|-------------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RS2 Instruction) |
| G | Non-Protocol Communication (FX2N-232JF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

12.4.7 Time-out check flag [M8409 and M8429]

These devices turn ON when data receiving is suspended, and the next set of receive data is not given within the time set by the time-out time setting device.

1. Detailed contents

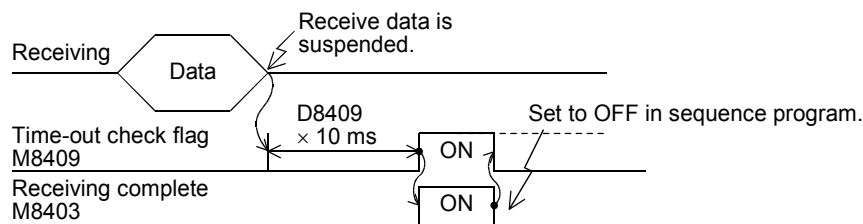
These devices turn ON when data receiving is suspended and the next set of receive data is not given within the time set by the time-out time setting device. The receiving complete flag also turns ON.

When communication port ch1 is used, M8409 turns ON.

When communication port ch2 is used, M8429 turns ON.

The time-out check flag turns OFF when the PLC waits to receive.

Using this function, the PLC can receive data from equipment where the amount of send data varies without the terminators.



12.4.8 Serial communication error code [D8063 and D8438]

When a serial communication error occurs, these devices store the corresponding error codes.

1. Detailed contents

When a serial communication error occurs, these devices store the corresponding error codes shown below.

When communication port ch1 is used, M8063 turns ON.

When communication port ch2 is used, M8438 turns ON.

| Error code | | Contents of error |
|-------------|-------------|--|
| ch1 (D8063) | ch2 (D8438) | |
| 6301 | 3801 | Parity error, overrun error or framing error |
| 6302 | 3802 | Incorrect communication character |
| 6303 | 3803 | Communication data sum mismatch |
| 6304 | 3804 | Incorrect data format |
| 6305 | 3805 | Incorrect command |
| 6306 | 3806 | Monitoring timeout |
| 6307 | 3807 | Modem initialization error |
| 6308 | 3808 | N:N Network parameter error |
| 6312 | 3812 | Parallel link parameter error |
| 6313 | 3813 | Parallel link sum error |
| 6314 | 3814 | Parallel link format error |
| 6320 | 3820 | Error in communication with inverter |

2. Cautions on use

The serial communication error code is not cleared even after communication recovers its normal status. Clear it by switching the PLC mode from STOP to RUN.

12.4.9 Communication format setting [D8400 and D8420]

These devices set the communication format.

1. Detailed contents

These devices can set the data length, parity, baud rate, etc.

When communication port ch1 is used, D8400 sets the communication format.

When communication port ch2 is used, D8420 sets the communication format.

The table below shows the contents of the communication format settings. Computer link setting is not applicable for D8400.

| Bit No. | Name | Contents | | | |
|----------------------|---------------------------------|--|---|---|----------------------------|
| | | 0 (bit = OFF) | | 1 (bit = ON) | |
| b0 | Data length | 7-bit | | 8-bit | |
| b1 b2 | Parity | b2, b1 (0, 0): Not provided (0, 1): Odd (1, 1): Even | | | |
| b3 | Stop bit | 1-bit | | 2-bit | |
| b4 b5 b6 b7 | Baud rate (bps) | b7, b6, b5, b4 (0, 0, 1, 1): 300 (0, 1, 0, 0): 600 (0, 1, 0, 1): 1200 (0, 1, 1, 0): 2400 | | b7, b6, b5, b4 (0, 1, 1, 1): 4800 (1, 0, 0, 0): 9600 (1, 0, 0, 1): 19200 | |
| b8*1 | Header | Not provided | | Provided*3 | |
| b9*1 | Terminator | Not provided | | Provided*3 | |
| b10 b11 b12 | Control line | Non-protocol communica- tion | b12, b11, b10 (0, 0, 0): Not provided <RS-232C interface> (0, 0, 1): Standard mode <RS-232C interface> (0, 1, 0): Interlink mode <RS-232C interface> (0, 1, 1): Modem mode <RS-232C interface> (1, 1, 1): Communication in accordance with RS-485 <RS-485/RS-422 interface> | | |
| | | Computer link | b12, b11, b10 (0, 0, 0): RS-485/RS-422 interface (0, 1, 0): RS-232C interface | | |
| b13 | Sum check | Not added | | Added*4 | |
| b14*2 | Protocol | Not used | | Used | |
| b15 | Control proce- dure (CR, LF) | Non-protocol communica- tion | CR, LF: Not used (Format 1) | Non-protocol communica- tion | CR, LF: Used (Format 2) |
| | | Computer link | CR, LF: Not used (Format 1) | Computer link | CR, LF: Used (Format 4) |

*1. Make sure to set as "0" when using computer link.

*2. Make sure to set as "0" when using non-protocol communication.

*3. In RS2 instruction, up to four headers and up to four terminators can be set.

*4. When executing non-protocol communication using RS2 instruction, add the sum check after the terminators.

Make sure to set the terminators when adding the sum check.

2. Cautions on use

In FX3U and FX3UC PLCs, the communication format can be set using parameters.

12.4.10 Amount of remaining send data [D8402 and D8422]

These devices store the amount of remaining send data.

1. Detailed contents

These devices store the amount of remaining send data in 8-bit (1 byte) units.
When communication port ch1 is used, D8402 stores the value.
When communication port ch2 is used, D8422 stores the value.
Only data in communication frames are regarded as the targets of counting.

12.4.11 Amount of data already received [D8403 and D8423]

These devices store the amount of data already received.

1. Detailed contents.

These devices stores the amount of data already received in 8-bit (1 byte) units.
When communication port ch1 is used, D8403 stores the value.
When communication port ch2 is used, D8423 stores the value.

12.4.12 Communication parameter display [D8405 and D8425]

These devices store the communication parameters set in the PLC.

1. Detailed contents

When the PLC power is turned ON, these devices store the contents of the communication parameters.
The setting contents are the same as those of the communication format setting device.
When communication port ch1 is used, D8405 stores the contents.
When communication port ch2 is used, D8425 stores the contents.

12.4.13 Time-out time setting [D8409 and D8429]

These devices set the time-out time setting.

1. Detailed contents

These devices set the error evaluation time (in 10 ms units) used when receiving of data is interrupted.
When communication port ch1 is used, D8409 sets the time.
When communication port ch2 is used, D8429 stores the time.
The setting range is from 1 to 255 (10 ms to 2550 ms).

12.4.14 Header [D8410, D8411, D8430 and D8431]

These devices set the headers 1, 2, 3 and 4.

1. Detailed contents

When "header provided" is selected in the communication format setting, the headers are set in the sent and received data.

Up to four headers can be set in each channel.

When communication port ch1 is used, D8410 and D8411 set the headers.

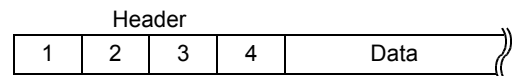
When communication port ch2 is used, D8430 and D8431 set the headers.

The headers are set in the following order.

| Header | Header 1 | Header 2 | Header 3 | Header 4 |
|--------|---------------------------|----------------------------|---------------------------|----------------------------|
| ch1 | D8410 (lowest-order byte) | D8410 (highest-order byte) | D8411 (lowest-order byte) | D8411 (highest-order byte) |
| ch2 | D8430 (lowest-order byte) | D8430 (highest-order byte) | D8431 (lowest-order byte) | D8431 (highest-order byte) |

When data is sent, the data set in the headers is added at the head of the specified send data.

When data is received, receiving begins when the data set in the headers is received.



2. Cautions on use

Even if "header provided" is selected, headers are not provided if header 1 is set to "H00".

The area before "H00" (in 1-byte units) is used to set the headers.

12.4.15 Terminator [D8412, D8413, D8432 and D8433]

These devices set the terminators 1, 2, 3 and 4.

1. Detailed contents

When "terminator provided" is selected in the communication format setting, the terminators are set in the sent and received data.

Up to four terminators can be set in each channel.

When communication port ch1 is used, D8412 and D8413 set the terminators.

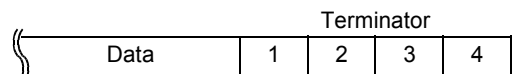
When communication port ch2 is used, D8432 and D8433 set the terminators.

The terminators are set in the following order.

| Terminator | Terminator 1 | Terminator 2 | Terminator 3 | Terminator 4 |
|------------|---------------------------|----------------------------|---------------------------|----------------------------|
| ch1 | D8412 (lowest-order byte) | D8412(highest-order byte) | D8413 (lowest-order byte) | D8413 (highest-order byte) |
| ch2 | D8432 (lowest-order byte) | D8432 (highest-order byte) | D8433 (lowest-order byte) | D8433 (highest-order byte) |

When data is sent, the data set in the terminators is added at the end of the specified send data.

When data is received, receiving is completed when the data set in the terminators is received.



2. Cautions on use

Even if "terminator provided" is selected, terminators are not provided if terminator 1 is set to "H00".

The area before "H00" (in 1-byte units) is used to set the terminators.

12.4.16 Receiving sum (receive data) [D8414 and D8434]

These devices store the received sum check value.

1. Detailed contents

When "sum check provided" is selected in the communication format setting, the sum check is executed for the sent and received data.

These devices store the sum added to the received data sent from the external equipment.

When communication port ch1 is used, D8414 stores the receiving sum.

When communication port ch2 is used, D8434 stores the receiving sum.

2. Cautions on use

When selecting "sum check provided", make sure to also select "terminator provided".

12.4.17 Receiving sum (calculation result) [D8415 and D8435]

These devices store the sum check value calculated using the received data.

1. Detailed contents

When "sum check provided" is selected in the communication format settings, the sum check is executed for the sent and received data.

These devices store the sum calculated by the FX PLC from the data received sent from the external equipment.

When communication port ch1 is used, D8415 stores the receiving sum.

When communication port ch2 is used, D8435 stores the receiving sum.

2. Cautions on use

When selecting "sum check provided", make sure to also select "terminator provided".

12.4.18 Sending sum [D8416 and D8436]

These devices store the sum check value added to the send data.

1. Detailed contents

When "sum check provided" is selected in the communication format settings, the sum check is executed for the sent and received data.

These devices store the sum calculated from the send data.

When communication port ch1 is used, D8416 stores the sending sum.

When communication port ch2 is used, D8436 stores the sending sum.

2. Cautions on use

When selecting "sum check provided", make sure to select "terminator provided".

12.4.19 Operation mode display [D8419 and D8439]

These devices store the communication type being used.

1. Detailed contents

These devices store the code of the communication type currently being used in the communication port.

When communication port ch1 is used, D8419 stores the communication type.

When communication port ch2 is used, D8439 stores the communication type.

The table below shows the contents of the communication type codes.

| Code | Description |
|------|-------------------------------------|
| 0 | Programming communication |
| 2 | Protocol dedicated to computer link |
| 3 | N:N Network |
| 4 | RS instruction |
| 5 | RS2 instruction |
| 6 | Parallel link |
| 7 | Inverter instruction |

2. Cautions on use

These devices store "5" while RS2 instruction is being driven or when RS2 instruction is not changed over to another mode.

12.5 ASCII Code Table

<ASCII code table (8-bit code expressed in hexadecimal)>
The ASCII codes A1H to DFH indicate Japanese characters.

| Hexa deci- mal | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | A | B | C | D | E | F |
|----------------------|-----|-----|----|---|---|-----|---|-----|---|---|---|---|---|---|---|---|
| 0 | | DLE | SP | 0 | @ | P | ` | p | | | | — | 々 | ミ | | |
| 1 | SOH | DC1 | ! | 1 | A | Q | a | q | | | 。 | ア | チ | ム | | |
| 2 | STX | DC2 | " | 2 | B | R | b | r | | | 「 | イ | ツ | メ | | |
| 3 | ETX | DC3 | # | 3 | C | S | c | s | | | 」 | ウ | テ | モ | | |
| 4 | EOT | DC4 | \$ | 4 | D | T | d | t | | | , | エ | ト | ヤ | | |
| 5 | ENQ | NAK | % | 5 | E | U | e | u | | | . | オ | ナ | ユ | | |
| 6 | ACK | SYN | & | 6 | F | V | f | v | | | ヲ | カ | ニ | ヨ | | |
| 7 | BEL | ETB | ' | 7 | G | W | g | w | | | ア | キ | ヌ | ラ | | |
| 8 | BS | CAN | (| 8 | H | X | h | x | | | イ | ク | ネ | リ | | |
| 9 | HT | EM |) | 9 | I | Y | i | y | | | ウ | ケ | ノ | ル | | |
| A | LF | SUB | * | : | J | Z | j | z | | | エ | コ | ハ | レ | | |
| B | VT | ESC | + | ; | K | [| k | { | | | オ | サ | ヒ | ロ | | |
| C | FF | FS | , | < | L | *1 | l | | | | ヤ | シ | フ | ワ | | |
| D | CR | GS | — | = | M |] | m | } | | | ユ | ス | ヘ | ン | | |
| E | SO | RS | . | > | N | ^ | n | ~ | | | ヨ | セ | ホ | ド | | |
| F | SI | US | / | ? | O | _ | o | DEL | | | ツ | ソ | マ | 。 | | |

*1. \ (ASCII CODE:5C) symbol is displayed as "¥" in Japanese.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

MEMO

FX Series Programmable Controllers

User's Manual

[Non-Protocol Communication (FX2N-232IF)]

Foreword

This manual explains "non protocol communication" provided for the MELSEC-F FX Series Programmable Controllers using the FX2N-232IF and should be read and understood before attempting to install or use the unit.

Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apex.
Discontinued models

1. Outline

The communication special function block operating in accordance with RS-232C, FX2N-232IF (hereafter referred to as "232IF"), is connected to an FX2N, FX3U, FX2NC, or FX3UC PLC to exchange serial data in the full-duplex method between equipment with RS-232C interfaces such as a personal computer, bar code reader or printer.

For the contents of the hardware, refer to the "FX2N-232IF Hardware Manual".

1.1 Features

1. Two or more 232IF (operating in accordance with RS-232C) blocks can be connected.

Two or more RS-232C interface blocks can be connected to an FX PLC.

1) For FX2N, FX3U and FX3UC*1 PLCs

Up to eight blocks can be connected to one PLC.

*1. Up to seven blocks can be connected to the FX3UC-32MT-LT PLC.

2) For FX2NC PLCs

Up to four blocks can be connected to one PLC.

2. Non-protocol communication

Communication is executed in the full-duplex, asynchronous system, non-protocol method. The communication format can be specified using the buffer memory (BFM).

The FROM and TO instructions are applicable for the buffer memory.

(In FX3U and FX3UC PLCs, other instructions are also applicable.)

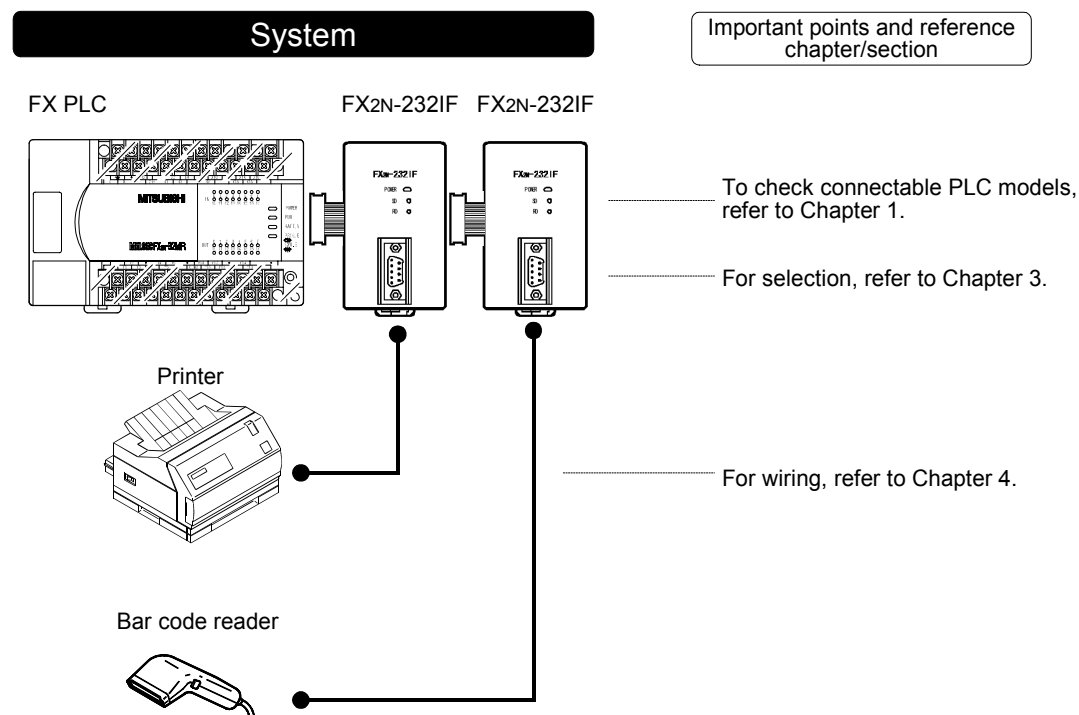
3. Send/receive data buffer of 512 bytes/256 words

The send data buffer and receive data buffer can store 512 bytes/256 words independently.

In the RS-232C interlink connection mode, the 232IF can receive data beyond 512 bytes/256 words.

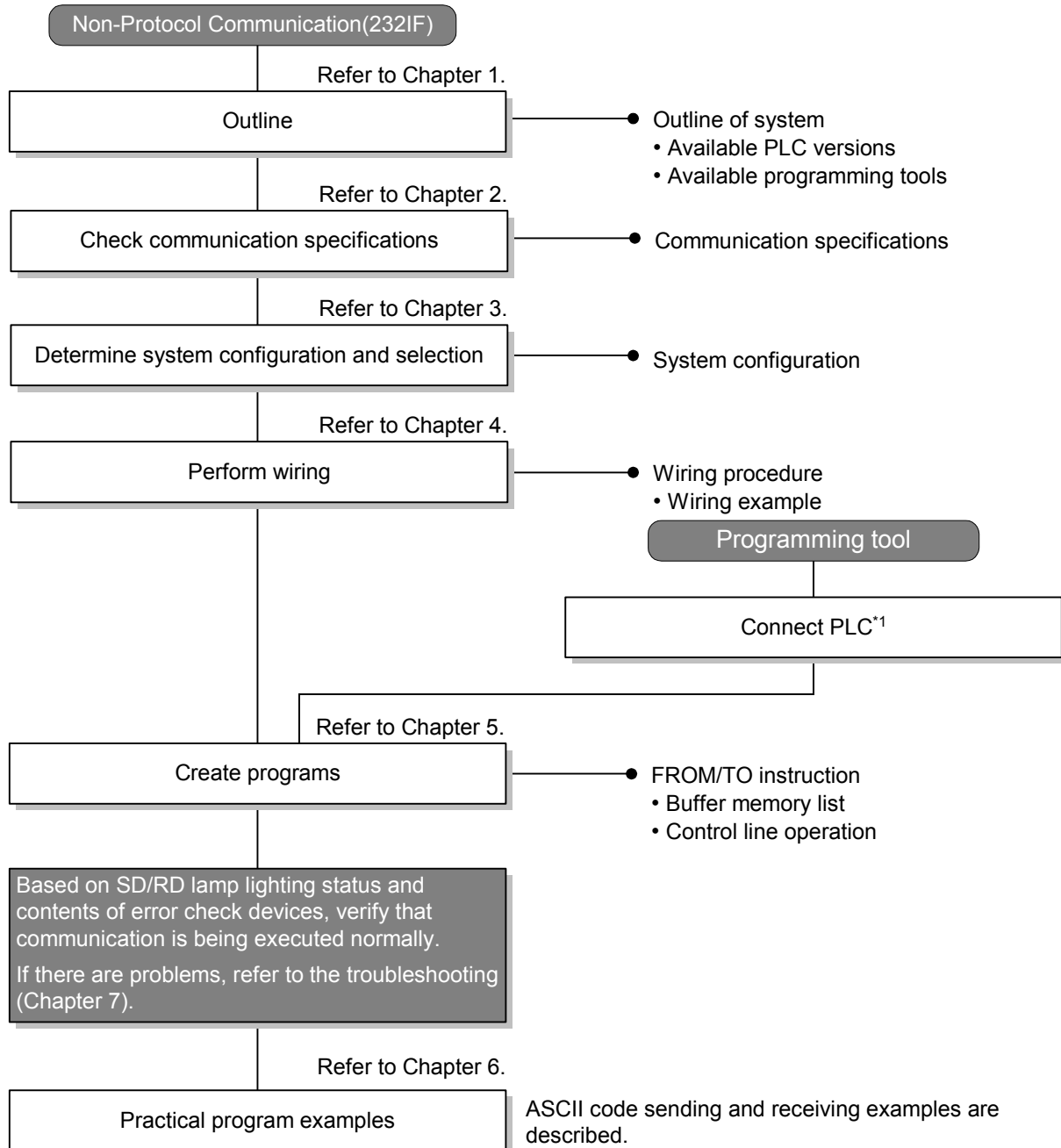
4. Built-in ASCII-Hexadecimal conversion function

By using this built-in conversion function, hexadecimal numeric values (0 to F) inside the send data buffer can be converted into ASCII code when being sent, and received ASCII code can be converted into hexadecimal values (0 to F) when being stored in the receive data buffer.



1.2 Procedures Before Operation

The flow chart below shows the Non-Protocol Communication (operating in accordance with 232IF) setting procedures up until data link:



*1 For the programming tool to PLC connection procedure, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operating procedures, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

The communication types are applicable in the following versions.

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|------------------------------------|---------------------------|
| FX3UC Series | ✓ | |
| FX3U Series | ✓ | |
| FX2NC Series | ✓ | |
| FX2N Series | ✓ | |
| FX1NC Series | — | 232IF is not connectable. |
| FX1N Series | — | 232IF is not connectable. |
| FX1S Series | — | 232IF is not connectable. |
| FX0N Series | — | 232IF is not connectable. |
| FX0S Series | — | 232IF is not connectable. |
| FX0 Series | — | 232IF is not connectable. |
| FX2C Series | — | 232IF is not connectable. |
| FX2(FX) Series | — | 232IF is not connectable. |
| FX1 Series | — | 232IF is not connectable. |

1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description on system configuration, etc. in this manual for maintenance.

| PLC | Date when production was stopped | Remarks |
|----------------|----------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2C Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the version shown:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)

—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.00 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXC | ✓ (Ver. 4.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXC-E | ✓ (Ver. 3.00 or later) | |
| FX-10P-E | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |

1.4.2 For non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set.
In this case, however, programming is enabled only in the ranges provided for the alternative PLC model such as instructions and program size.

| Model to be programmed | Model to be set | Priority: High → Low | | | |
|---------------------------|-----------------|----------------------|---------|---|---------|
| FX3UC Series | FX3UC | → | FX2N | → | FX2(FX) |
| FX3U Series | FX3U, FX3UC | → | FX2N | → | FX2(FX) |
| FX2NC Series | FX2NC, FX2N | → | FX2(FX) | | |
| FX2N Series | FX2N | → | FX2(FX) | | |

2. Specification

This chapter explains the communication specifications.

2.1 Communication Specifications

Non-protocol communication type is used in the communication specifications shown in the table below.

| Item | Specifications | Remarks |
|----------------------------------|---------------------------------------|------------------------------------|
| Transmission standard | RS-232C standard | |
| Maximum total extension distance | 15 m (49' 2") | |
| Protocol type | Non-protocol communication | |
| Communication method | Full-duplex, asynchronous system | |
| Baud rate | 300/600/1200/2400/4800/9600/19200 bps | |
| Character format | — | |
| Start bit | — | |
| Data bit | 7-bit/8-bit | |
| Parity bit | None, odd or even | |
| Stop bit | 1-bit/2-bit | |
| Header | Provided or not provided | Up to four bytes can be specified. |
| Terminator | Provided or not provided | |
| Control line | Provided or not provided | |
| Sum check | Provided or not provided | |

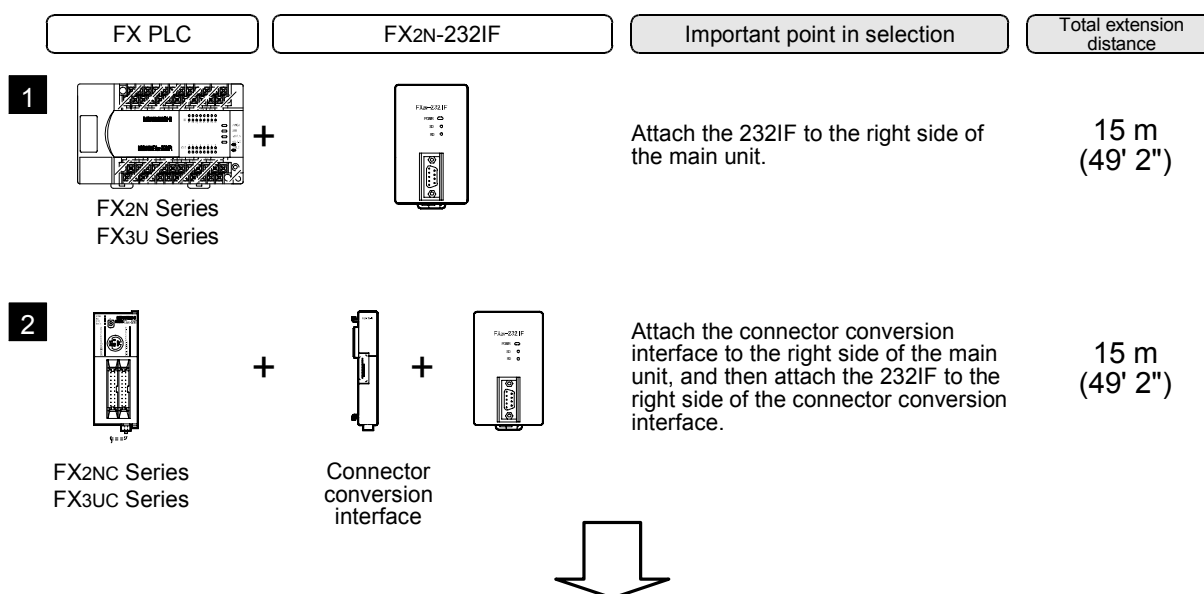
3. System Configuration and Selection

This chapter explains the system configuration and selection of the FX PLC and 232IF.

3.1 System Configuration

This section outlines the system configuration required to use the 232IF.

1 and **2** indicate the communication equipment combination patterns.



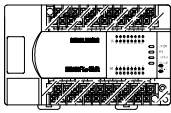
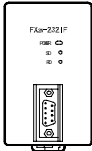
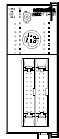

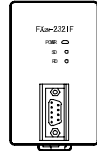
For communication equipment combinations for each FX Series, refer to the next section.

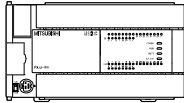
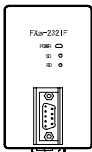
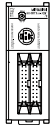



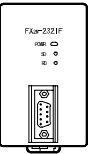
3.2 Applicable FX PLC and Communication Equipment

Select a 232IF combination, and put a check mark in the "Check" column.

During selection, pay attention to the following:

- The capacity of the 5V DC power supplied from the PLC is limited. The current consumption at 5V DC of the 232IF is 40 mA. Make sure that total current consumption at 5V DC including other blocks does not exceed the specified value.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX2N |  FX2N-232IF (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX2NC |   FX2NC-CNV-IF FX2N-232IF (9-pin D-Sub, male) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|--|--------------------------|-------|
|  FX3U |  FX2N-232IF (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX3UC |  +  FX2NC-CNV-IF FX2N-232IF (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  +  FX3UC-1PS-5V FX2N-232IF (9-pin D-Sub, male) | 15 m (49' 2") | |

3.3 Connection to PLC

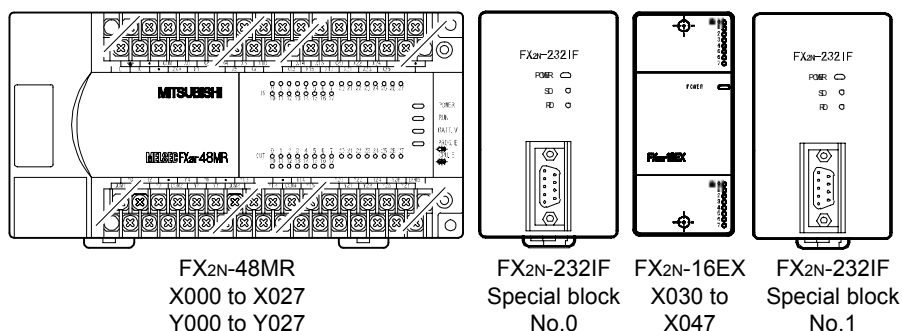
The 232IF can be directly connected to an FX PLC main unit or to the right side of another function block or powered extension unit.

The unit number is assigned to each special unit/block in the order "No. 0, No. 1, No. 2 ..." from the unit/block nearest to the main unit. (for FX3UC-32MT-LT PLC, the unit number is assigned in the order "No. 1, No. 2, No. 3 ...".)

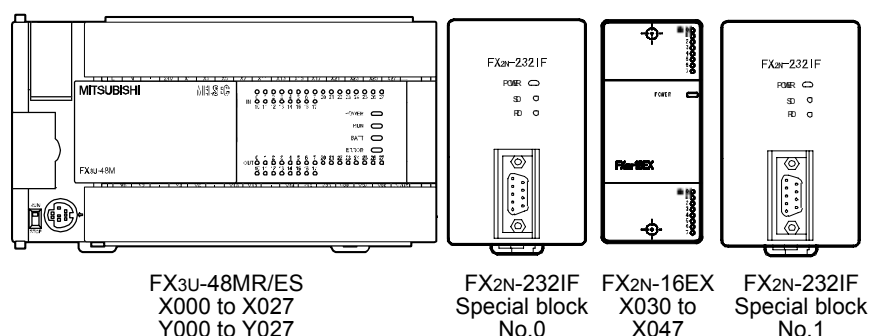
Up to eight 232IF units can be connected to an FX2N/FX3U/FX3UC*1 PLC, up to four 232IF units can be connected to an FX2NC PLC.

*1. Up to seven 232IF units can be connected to an FX3UC-32MT-LT PLC.

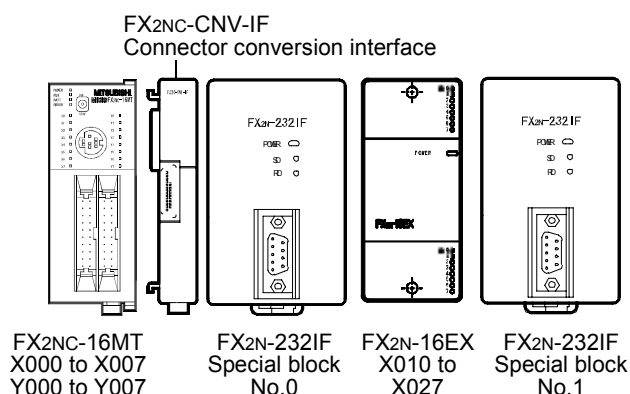
1. For FX2N PLC



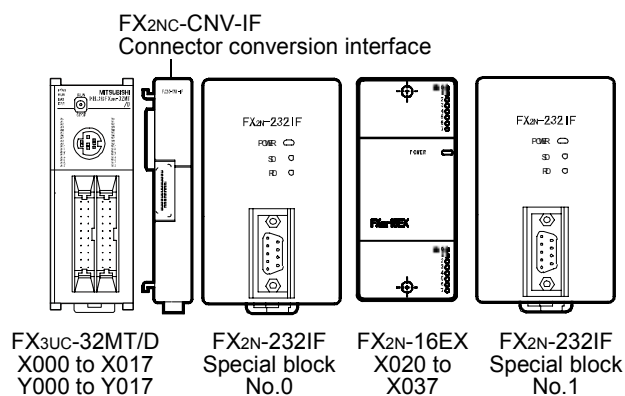
2. For FX3u PLC



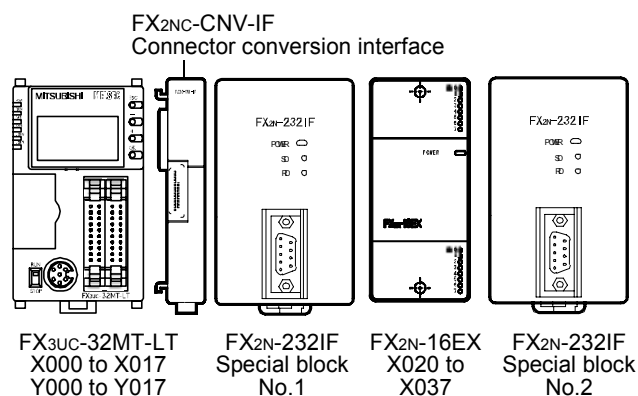
3. For FX2Nc PLC



4. For FX3uc(D, DSS) PLC



5. For FX3uc-32MT-LT PLC



| | |
|-------------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol (RS485 Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

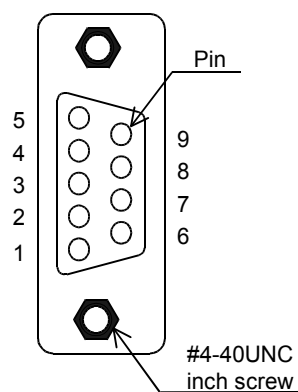
4. Wiring

This chapter explains the wiring.

4.1 Pin Arrangement

The table below shows the pin arrangement of the 232IF.

Example of applicable connector: 17JE-13090-02 (D8C2) by DDK Ltd.



| Pin No. | Signal name | Function | Signal direction 232IF: External equipment |
|---------|-------------|---|---|
| 1 | CD(DCD) | Carrier detection | ← |
| 2 | RD(RXD) | Receive data (with LED indicator) | ← |
| 3 | SD(TXD) | Send data (with LED indicator) | → |
| 4 | ER(DTR) | Data terminal ready | → |
| 5 | SG(GND) | Signal ground | — |
| 6 | DR(DSR) | Data set ready | ← |
| 7 | RS(RTS) | Sending request (receiving enable)*1 | → |
| 8 | CS(CTS) | Sending enable | ← |
| 9 | CI(RI) | Calling indicator | ← |

*1. The signal inside () is adopted in the interlink connection mode.

4.2 Connection to External Equipment with Terminal Specifications (without Control Line)

BFM # 0 (communication format): b9 = 0, b8 = 0 (control line not provided)

| PLC side | | RS-232C external equipment side | | |
|----------|------------|---------------------------------|-------------|--------------|
| Name | FX2N-232IF | Name | 9-pin D-Sub | 25-pin D-Sub |
| SD(TXD) | 3 | SD(TXD) | 3 | 2 |
| RD(RXD) | 2 | RD(RXD) | 2 | 3 |
| SG(GND) | 5 | SG(GND) | 5 | 7 |

4.3 Connection to External Equipment with Terminal Specifications (with Control Line)

4.3.1 Standard RS-232C mode

Cross cable, BFM #0 (communication format): b9 = 0, b8 = 1 (standard RS-232C mode)

| PLC side | | RS-232C external equipment side | | |
|----------|------------|---------------------------------|-------------|--------------|
| Name | FX2N-232IF | Name | 9-pin D-Sub | 25-pin D-Sub |
| SD(TXD) | 3 | SD(TXD) | 3 | 2 |
| RD(RXD) | 2 | RD(RXD) | 2 | 3 |
| RS(RTS) | 7 | RS(RTS) | 7 | 4 |
| CS(CTS) | 8 | CS(CTS) | 8 | 5 |
| CD(DCD) | 1 | CD(DCD) | 1 | 8 |
| ER(DTR) | 4 | ER(DTR) | 4 | 20 |
| DR(DSR) | 6 | DR(DSR) | 6 | 6 |
| SG(GND) | 5 | SG(GND) | 5 | 7 |

When the FX2N-232IF receives the RS (request to send) signal at its carrier to send (CS) pin, the FX2N-232IF transfers signals as if the external equipment exists.

- *1. It is not necessary to connect the CD signal if monitoring the CD signal is not required. For the CD signal, the 232IF indicates only the status.
- *2. The 232IF indicates only the status.

4.3.2 Interlink connection mode

Interlink serial cross cable, BFM #0 (communication format): b9 = 1, b8 = 1 (RS-232C interlink connection mode)

| PLC side | | RS-232C external equipment side | | |
|----------|------------|---------------------------------|-------------|--------------|
| Name | FX2N-232IF | Name | 9-pin D-Sub | 25-pin D-Sub |
| SD(TXD) | 3 | SD(TXD) | 3 | 2 |
| RD(RXD) | 2 | RD(RXD) | 2 | 3 |
| RS(RTS) | 7 | RS(RTS) | 7 | 4 |
| CS(CTS) | 8 | CS(CTS) | 8 | 5 |
| ER(DTR) | 4 | ER(DTR) | 4 | 20 |
| DR(DSR) | 6 | DR(DSR) | 6 | 6 |
| SG(GND) | 5 | SG(GND) | 5 | 7 |

In the interlink connection mode, the 232IF can receive data larger than 512 bytes which is the upper limit of the received data buffer in the 232IF.

- *1. In this mode, the request to send (RS) signal works as the receiving enable signal for the 232IF. When the 232IF receives data beyond the maximum number of receivable bytes, it turns OFF which works as the receive ready signal (RS signal) to ask the external equipment to stop sending. At this time, by withdrawing the data located in the received data buffer using a sequence program, the 232IF can receive remaining data.

4.4 Connection to External Equipment with Modem Specifications

Straight cable, BFM #0 (communication format): b9 = 0, b8 = 1 (standard RS-232C mode)

| PLC side | | RS-232C external equipment side | | |
|----------|------------|---------------------------------|-------------|--------------|
| Name | FX2N-232IF | Name | 9-pin D-Sub | 25-pin D-Sub |
| SD(TXD) | 3 | SD(TXD) | 3 | 2 |
| RD(RXD) | 2 | RD(RXD) | 2 | 3 |
| RS(RTS) | 7 | RS(RTS) | 7 | 4 |
| CS(CTS) | 8 | CS(CTS) | 8 | 5 |
| CD(DCD) | 1 | CD(DCD) | 1 | 8 |
| ER(DTR) | 4 | ER(DTR) | 4 | 20 |
| DR(DSR) | 6 | DR(DSR) | 6 | 6 |
| SG(GND) | 5 | SG(GND) | 5 | 7 |
| CI(RI) | 9 | CI(RI) | 9 | 22 |

- *1. It is not necessary to connect the CD signal if monitoring the CD signal is not required. For the CD signal, the 232IF indicates only the status.
- *2. The 232IF indicates only the status.
- *3. It is not necessary to connect the CI signal if monitoring of the CI signal is not required. For the CI signal, the 232IF indicates only the status.

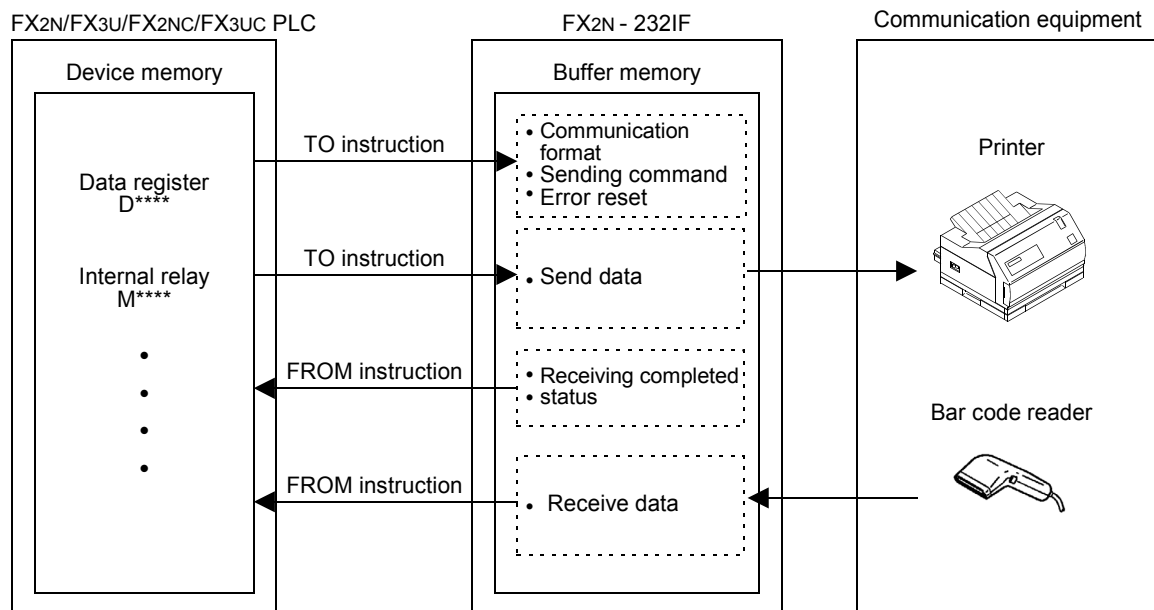
5. Creating Programs

This chapter explains how to create programs for non-protocol communication type using the 232IF.

5.1 Outline of Communication between FX PLC and 232IF

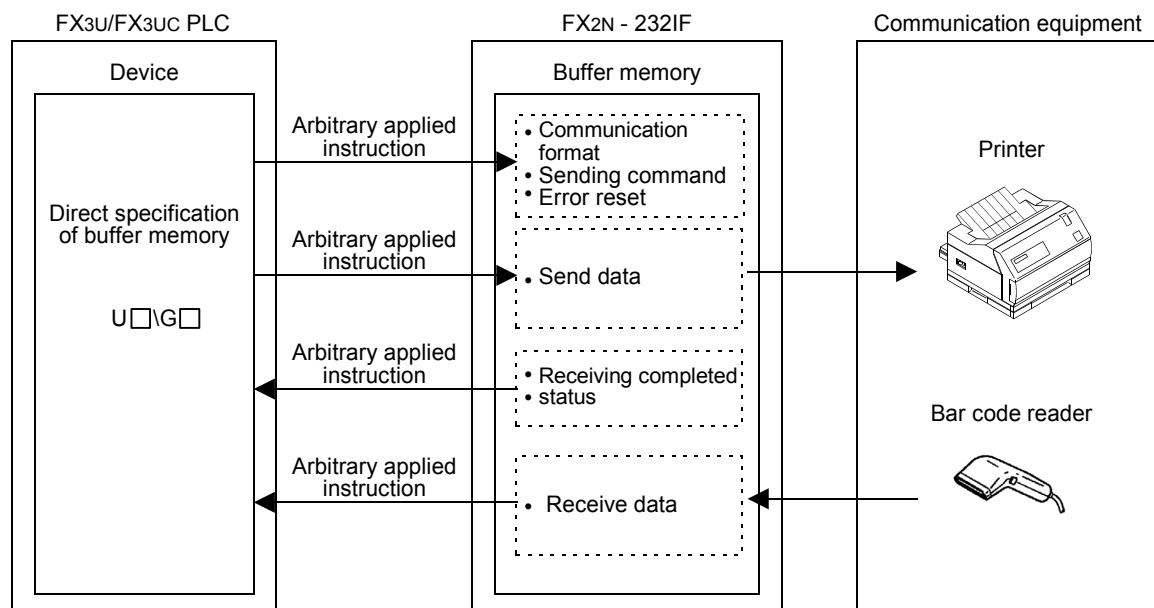
An FX PLC and 232IF transfer data between each other through the buffer memory (BFM).

5.1.1 For FROM and TO instructions



5.1.2 For direct specification of buffer memory (U□\G□)

FX3U and FX3UC PLCs allow not only FROM and TO instructions but also direct specification of the buffer memory (U□\G□) using the MOV instruction, etc.



5.2 FROM and TO Instructions

This section explains how to use FROM and TO instructions.

5.2.1 FROM instruction

FROM instruction reads data of the buffer memory in a special block.

1. Applicable devices

- For FX2N/FX2NC PLCs

| Operand Type | Bit Devices | | | | | | Word Devices | | | | | | | | | | | Others | | |
|---------------|-------------|---|---|---|---|---|---------------------|-----|-----|-----|-------------|---|---|-------|---|--------|---|----------|---|---------|
| | System User | | | | | | Digit Specification | | | | System User | | | Index | | | | Constant | | Pointer |
| | X | Y | M | T | C | S | KnX | KnY | KnM | KnS | T | C | D | V | Z | Modify | K | H | P | |
| m1 | | | | | | | | | | | | | ✓ | | | | ✓ | ✓ | | |
| m2 | | | | | | | | | | | | | ✓ | | | | ✓ | ✓ | | |
| <div>D•</div> | | | | | | | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | | | | |
| n | | | | | | | | | | | | | ✓ | | | | ✓ | ✓ | | |

- For FX3U/FX3UC PLCs

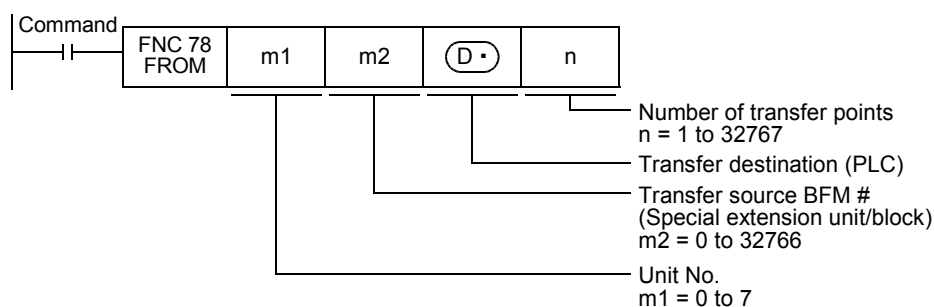
| Oper- and Type | Bit Devices | | | | | | | Word Devices | | | | | | | | | | | Others | | | | | |
|----------------------|-------------|---|---|---|---|---|------|---------------------|-----|-----|-----|-------------|---|---|---|--------------|-------|---|--------|---------------|----------------|-----------------------|---------|---|
| | System User | | | | | | | Digit Specification | | | | System User | | | | Special Unit | Index | | | Con- stant | Real Number | Charac- ter String | Pointer | |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□\G□ | V | Z | Modify | K | H | E | "□" | P |
| m1 | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |
| m2 | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |
| <div>D•</div> | | | | | | | | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | | ✓ | ✓ | ✓ | | | | | |
| n | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |

2. Function and operation

- 16-bit operation (FROM and FROMP)

Special function block (BFM) → PLC (word device)

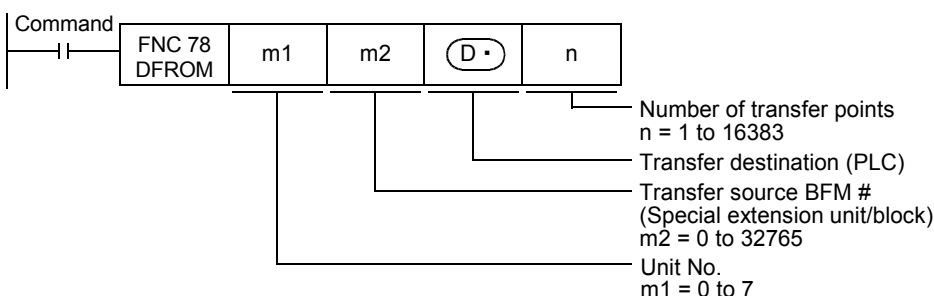
"n" 16-bit data starting from buffer memory (BFM) No. m2 inside the special function block No. m1 are transferred (read) to "n" devices starting from (D•) inside the PLC.



- 32-bit operation (DFROM and DFROMP)

Special function block (BFM) → PLC (word device)

"n" 32-bit data starting from buffer memory (BFM) No. m2 inside the special function block No. m1 are transferred (read) to "n" devices starting from [(D•)+1, (D•)] inside the PLC.



5.2.2 TO instruction

TO instruction writes data to the buffer memory in a special function block.

1. Applicable devices

- For FX2N/FX2NC PLCs

| Operand Type | Bit Devices | | | | | | Word Devices | | | | | | | | | | Others | | |
|---------------|-------------|---|---|---|---|---|---------------------|-----|-----|-----|-------------|---|---|-------|---|--------|----------|---|---------|
| | System User | | | | | | Digit Specification | | | | System User | | | Index | | | Constant | | Pointer |
| | X | Y | M | T | C | S | KnX | KnY | KnM | KnS | T | C | D | V | Z | Modify | K | H | P |
| m1 | | | | | | | | | | | | | ✓ | | | | ✓ | ✓ | |
| m2 | | | | | | | | | | | | | ✓ | | | | ✓ | ✓ | |
| <div>S•</div> | | | | | | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | |
| n | | | | | | | | | | | | | ✓ | | | | ✓ | ✓ | |

- For FX3U/FX3UC PLCs

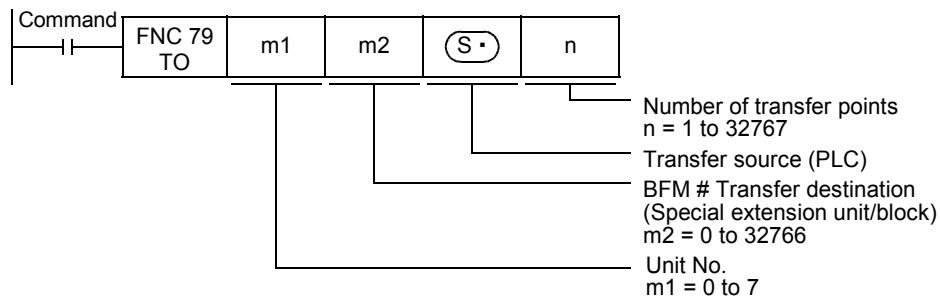
| Oper- and Type | Bit Devices | | | | | | | | Word Devices | | | | | | | | | | | | Others | | | |
|----------------------|-------------|---|---|---|---|---|------|-----|---------------------|-----|-----|---|-------------|---|---|-------|--------------|-------|--------|---|---------------|----------------|-----------------------|---------|
| | System User | | | | | | | | Digit Specification | | | | System User | | | | Special Unit | Index | | | Con- stant | Real Number | Charac- ter String | Pointer |
| | X | Y | M | T | C | S | D□.b | KnX | KnY | KnM | KnS | T | C | D | R | U□/G□ | V | Z | Modify | K | H | E | "□" | P |
| m1 | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |
| m2 | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |
| (S•) | | | | | | | | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | | ✓ | ✓ | ✓ | ✓ | ✓ | | | |
| n | | | | | | | | | | | | | | ✓ | ✓ | | | | | ✓ | ✓ | | | |

2. Function and operation

- 16-bit operation (TO and TOP)

PLC (word device) → Special function block (BFM)

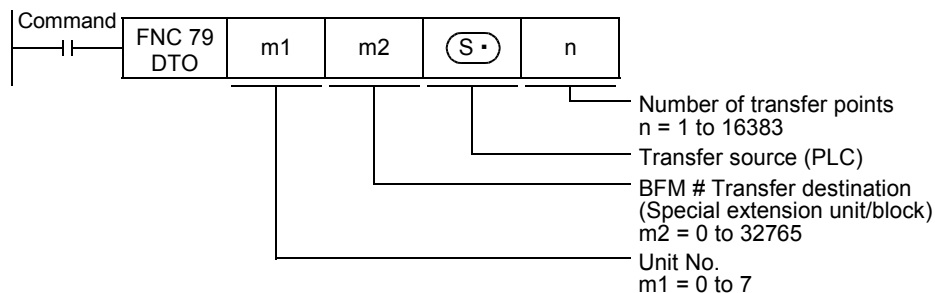
"n" 16-bit data starting from (S•) inside the PLC are transferred (written) to "n" buffer memories starting from buffer memory No. m2 inside the special function block No. m1.



- 32-bit operation (DTO and DTOPT)

PLC (word device) → Special function block (BFM)

"n" 32-bit data starting from [(S•) + 1, (S•)] inside the PLC are transferred (written) to "n" buffer memories starting from the buffer memory No. m2 inside the special function block No. m1.



5.3 Direct Specification of Buffer Memory (U□\G□)

In FX3U and FX3UC PLCs, one is able to directly specify buffer memories and read/write data from/to the specified buffer memories even with instructions other than the FROM and TO.

1. How to specify a buffer memory directly

When directly specifying a buffer memory, put the following setting directly into the source or destination of the command.

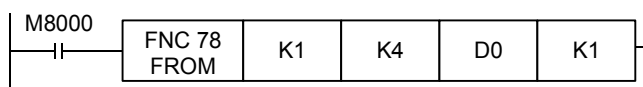
U□\G□

Specifies the block number

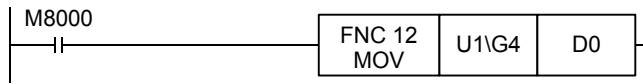
Specifies the buffer memory number

Example 1: When reading data from buffer memory No. 4 in special function block No. 1, and transferring it to D0

In the case of FROM instruction

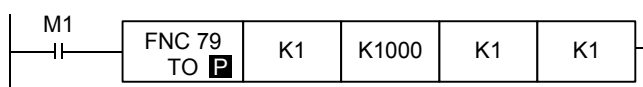


In the case of direct specification

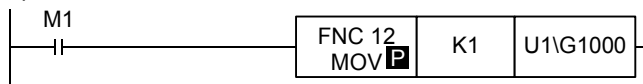


Example 2: When writing the numeric value K1 to buffer memory No. 1000 in special function block No. 1 (pulse operation type)

In the case of TO instruction

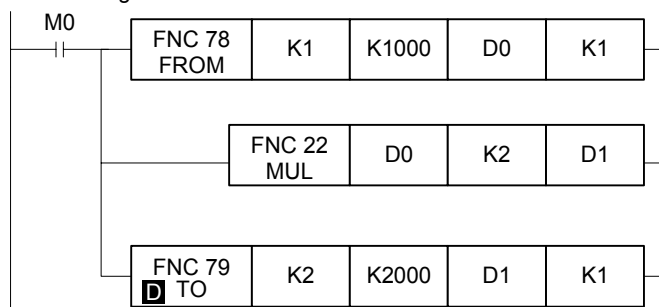


In the case of direct specification

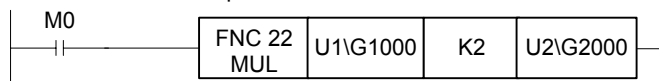


Example 3: When multiplying the value stored in buffer memory No. 1000 in special function block No. 1 by the numeric value "K2", and writing the multiplication result to buffer memories Nos. 2000 and 2001 in special function block No. 2

When using the FROM and TO instructions



In the case of direct specification



Caution

The FX3UC-32MT-LT PLC main unit has a built-in CC-Link/LT master. When using special function blocks, set the block numbers, starting from "1".

5.4 Buffer Memory (BFM)

This section explains the contents of the buffer memory (BFM).

5.4.1 Buffer memory list

| BFM No. | Name | Setting range | Initial value | R/W |
|----------------------|---|---|-------------------|-----|
| #0 | Communication format | | 0087H | W |
| #1 | Command | | 0 | W |
| #2 | Maximum number of receivable bytes | 1 to 512 (when data length is 16-bit) 1 to 256 (when data length is 8-bit) "0" is handled as "512" or "256" | 0 | W |
| #3 | Receiving timeout time | 1 to 32767 (× 10 ms) "0" is handled as "no timeout time". | 0 | W |
| #4 | Sending header (lowest-order 2 bytes) | 4 bytes maximum, 0 suppression | 0 (no header) | W |
| #5 | Sending header (highest-order 2 bytes) | 0 suppression | 0 | W |
| #6 | Sending terminator (lowest-order 2 bytes) | 4 bytes maximum, 0 suppression | 0 (no terminator) | W |
| #7 | Sending terminator (highest-order 2 bytes) | 0 suppression | 0 | W |
| #8 | Receiving header (lowest-order 2 bytes) | 4 bytes maximum, 0 suppression | 0 (no header) | W |
| #9 | Receiving header (highest-order 2 bytes) | 0 suppression | 0 | W |
| #10 | Receiving terminator (lowest-order 2 bytes) | 4 bytes maximum, 0 suppression | 0 (no terminator) | W |
| #11 | Receiving terminator (highest-order 2 bytes) | 0 suppression | 0 | W |
| #12 | Receiving suspension waiting time (in interlink connection mode) | 0 to 32767(× 10 ms) | 0 | W |
| #13 | Amount of remaining send data | 0 to 512 (when data length is 16-bit) 0 to 256 (when data length is 8-bit) | 0 | R |
| #14 | Amount of received data buffers | 0 to 256+15*1 | 0 | R |
| #15 | Sending sum result | | 0 | R |
| #16 | Receiving sum result | | 0 | R |
| #20 | Time from CS ON to sending start | 0 to 32,767(× 10 ms) | 0 | W |
| #21 | Time from actual sending completion to RS OFF (complete flag ON) | 0 to 32,767(× 10 ms) | 0 | W |
| #28 | Status | | 0 | R |
| #29 | Error code | | 0 | R |
| #30 | Model code | | K7030 | R |
| #1000 | Number of bytes to be sent | 0 to 512 (when data length is 16-bit) 0 to 256 (when data length is 8-bit) | 0 | W |
| #1001 to #1256 | Send data buffer | | 0 | W |
| #2000 | Number of received bytes | 0 to 512+30*1 (when data length is 16-bit) 0 to 256+15*1 (when data length is 8-bit) | 0 | R |
| #2001 to #2256 | Receive data buffer | | 0 | R |

| BFM No. | Name | Setting range | Initial value | R/W |
|----------------|---|---------------|---------------|-----|
| #2257 to #2271 | Preliminary receive data buffer for interlink connection mode | | 0 | R |

R: Read only

W: Read or Write

Caution

Buffer memories specified as "W: For write" can be read also.

Do not use undefined buffer memory numbers in programs.

- *1. Provided for preliminary buffers for the interlink connection mode.

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5.4.2 Communication format <BFM #0>

| Bit | Contents | 0 | 1 | Initial value |
|----------------------|--|---|-------|---------------------|
| b0 | Data length | 7-bit | 8-bit | 1 : 8-bit |
| b1 b2 | Parity | (00) : Not provided (01) : Odd (11) : Even | | (11) : Even |
| b3 | Stop bit | 1-bit | 2-bit | 0 : 1-bit |
| b4 b5 b6 b7 | Baud rate (bps) | (0011) : 300 (0100) : 600 (0101) : 1200 (0110) : 2400 (0111) : 4800 (1000) : 9600 (1001) : 19200 | | (1000) : 9600 bps |
| b8 b9 | Control line | (00) : Not provided (01) : Standard RS-232C (11) : RS-232C interlink mode | | (00) : Not provided |
| b10 b11 | CR and LF addition | (00) : Both CR and LF are not added. (01) : Only CR is added. (11) : Both CR and LF are added. | | (00) : Not provided |
| b12 b13 | Absence/presence of check sum and ASCII-Hexadecimal conversion | (00) : Both check sum and ASCII-hexadecimal conversion are not provided. (01) : Only ASCII-hexadecimal conversion is provided. (10) : Only check sum is provided. (11) : Both check sum and ASCII-hexadecimal conversion are provided. | | (00) : Not provided |
| b14 | Send/receive data buffer data length | 16-bit | 8-bit | 0 : 16-bit |
| b15 | Undefined (cannot be used) | — | | 0 : Undefined |

The communication format setting contents are determined when the sending/receiving enable command (BFM #1, b0) turns ON.

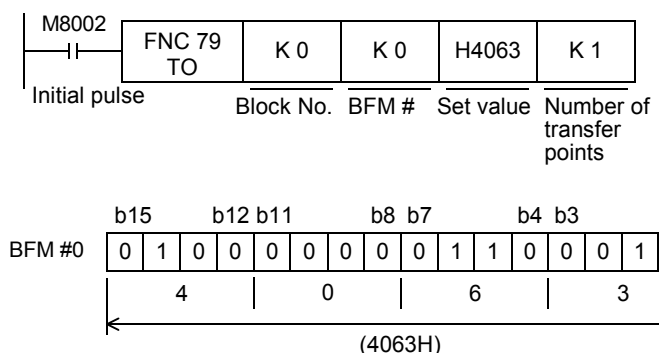
Accordingly, it is necessary to transfer the communication format setting in advance using TO instruction before setting the sending/receiving enable command to ON.

However, the sending header and sending terminator are determined when the sending command (BFM #1, b1) turns ON. And the receiving header and receiving terminator are determined when the sending/receiving enable command (BFM #1, b0) turns ON and the receiving complete flag reset command (BFM #1, b2) turns ON. Accordingly, if only the header and terminator are changed in the middle of communication, such change will become valid at the next sending/receiving operation, (so it is not necessary to turn OFF the sending/receiving enable command).

Example of communication format setting (specified in hexadecimal constant)

When specifying the communication format as shown in the table below, use the following program.

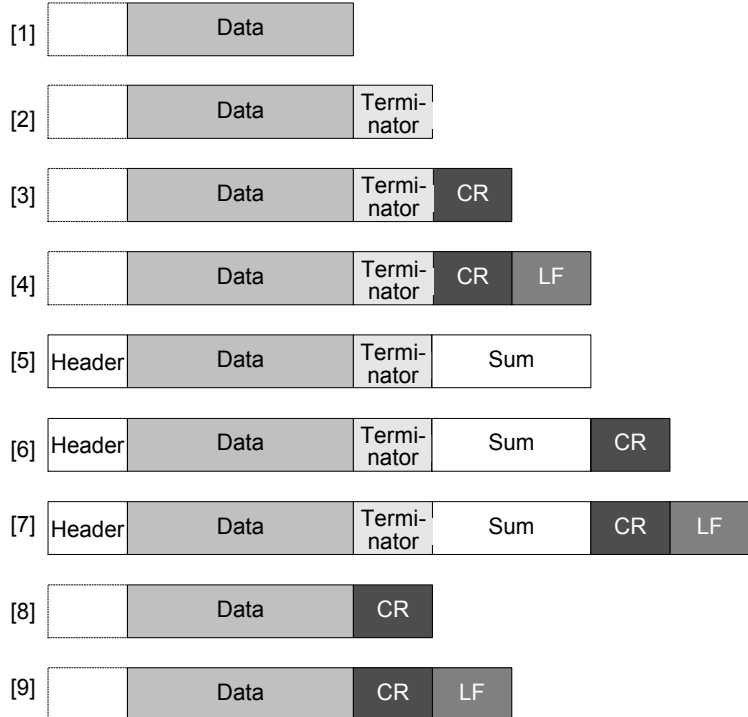
| | |
|------------------------------|--------------|
| Data length | 8-bit |
| Parity | Odd |
| Stop bit | 1-bit |
| Baud rate | 2400 bps |
| Control line | Not provided |
| CR and LF | Not added |
| Check sum | Not provided |
| ASCII-hexadecimal conversion | Not provided |
| Buffer data length | 8-bit |



1. Communication format

Select the communication format to be used to send and receive data in the 232IF from the formats shown to the right.

- 1) The header can be specified before the data in the communication format.
- 2) In the communication format [1], hexadecimal (binary) values and ASCII codes can be sent and received.
When using the communication formats [2] to [9], make sure to use ASCII codes as the sent and received data.
The received data should not include the header, terminator or CR. (In communication formats [4], [7] and [9], the data area after "CR" is not received.)
By specifying b13 and b12 of BFM #0, the ASCII-Hexadecimal conversion function can be used for communication.
- 3) ASCII codes "01H" to "1FH" can be used as the head terminator.
- 4) In the RS-232C interlink connection mode, the communication formats [2] to [7] are valid.



2. b0 to b7 (data length, parity, stop bit and baud rate)

Align the setting of b0 to b7 with the communication specifications in the connected external equipment.

3. b9 and b8 (control line)

- 1) When "control line not provided (b9 = 0, b8 = 0)" is specified, data is transferred using only the SD and RD signals without using the control line.
- 2) When the "standard RS-232C mode (b9 = 0, b8 = 1)" is specified, use a cross cable to connect equipment with the terminal specifications, and use a straight cable to connect equipment with the modem specifications.
- 3) When the "RS-232C interlink connection mode (b9 = 1, b8 = 1)" is specified, the sending request (RS) signal works as the receiving enable signal for the 232IF. When the 232IF receives data beyond the maximum number of receivable bytes (BFM #2), it turns OFF the receiving enable (RS) signal to ask the external equipment to suspend sending.

At this time, by withdrawing the contents of the received data buffer to data registers in the PLC using a sequence program, the 232IF can continuously receive the remaining data.

When this mode is specified, make sure to perform the interlink connection for RS-232C.

→ For the wiring of equipment according to each setting, refer to Chapter 4.

→ For the operation of the control line, refer to Section 5.5.

4. b11 and b10 (CR and LF addition)

The following specification methods are applicable:

- 1) Both CR and LF are not added (b11 = 0, b10 = 0).
 - 2) Only CR is added (b11 = 0, b10 = 1).
 - 3) Both CR and LF are added (b11 = 1, b10 = 1).
- For the CR/LF addition format, refer to the communication format list above.

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5. b13 and b12 (absence/presence of check sum and ASCII-Hexadecimal conversion)

The following specification methods are applicable:

- 1) Neither the check sum nor ASCII-Hexadecimal conversion are provided (b13 = 0, b12 = 0).
 - 2) Only the ASCII-Hexadecimal conversion is provided (b13 = 0, b12 = 1).
 - 3) Only the check sum is provided (b13 = 1, b12 = 0).
 - 4) Both the check sum and ASCII-Hexadecimal conversion are provided (b13 = 1, b12 = 1).
- For the check sum addition format, refer to the communication format list above.

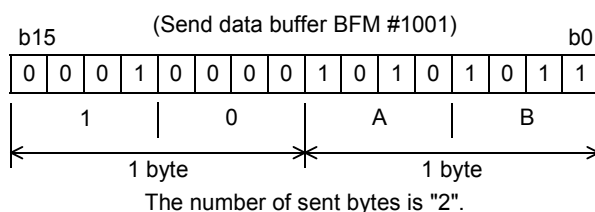
<ASCII-Hexadecimal conversion>

When "ASCII-Hexadecimal conversion provided" is specified, the hexadecimal numeric value data (0 to F) inside the send data buffer (BFM #1001 to 1256) is converted into ASCII data before being sent. And the received ASCII data is converted into the hexadecimal numeric value data (0 to F) before being stored in the received data buffer (BFM #2001 to 2256).

The number of sent/received bytes at this time indicates the amount of hexadecimal data.

<Sending format during conversion from hexadecimal data into ASCII data>

Example: When the send data is "10ABH", the header is "STX" and the terminator is "ETX"



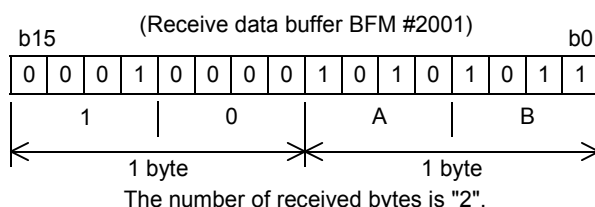
Data is converted into ASCII data when being sent.

| | | | | | |
|-----|-----|-----|-----|-----|-----|
| S | A | B | 1 | 0 | E |
| T | | | | | T |
| X | | | | | X |
| 02H | 41H | 42H | 31H | 30H | 03H |

<Receiving format in conversion from ASCII data into hexadecimal data>

Example: When the received data is "10ABH", the header is "STX" and the terminator is "ETX"

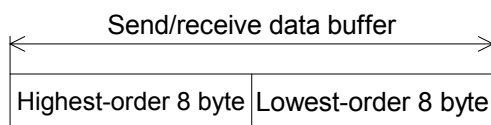
| | | | | | |
|-----|-----|-----|-----|-----|-----|
| S | A | B | 1 | 0 | E |
| T | | | | | T |
| X | | | | | X |
| 02H | 41H | 42H | 31H | 30H | 03H |



6. b14 (send/receive data buffer data length)

The data is handled as shown below according to the buffer data length.

1) 16-bit (b14 = 0)

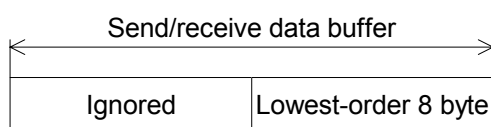


16-bit data is divided into lowest-order 8-bit and highest-order 8-bit when being sent or received.

Example of send data buffer

| | | | | | |
|---|-------------------|--------------------|-------------------|--------------------|---|
| S | BFM | BFM | BFM | BFM | E |
| T | #1001 | #1001 | #1002 | #1002 | T |
| X | lowest-order byte | highest-order byte | lowest-order byte | highest-order byte | X |

2) 8-bit (b14 = 1)



Highest-order 8-bit are ignored. Only lowest-order 8-bit are sent and received as valid data.

Example of send data buffer

| | | | | | |
|---|-------------------|-------------------|-------------------|-------------------|---|
| S | BFM | BFM | BFM | BFM | E |
| T | #1001 | #1002 | #1003 | #1004 | T |
| X | lowest-order byte | lowest-order byte | lowest-order byte | lowest-order byte | X |

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5.4.3 Command <BFM #1>

BFM #1 gives the command for sending or receiving data or resetting the status information to the 232IF.

| Bit | Contents |
|-----|---------------------------------------|
| b0 | Sending/receiving enable (ER ON) |
| b1 | Sending command |
| b2 | Receiving complete flag reset command |
| b3 | Error reset |

1. b0 (sending/receiving enable)

While b0 is ON, the 232IF can send and receive data.

Because the contents of the following set items are determined at the rising edge of b0, transfer these values in advance using the TO instruction before setting b0 to ON:

- BFM #0 (communication format)
- BFM #9 and 8 (receiving header)
- BFM #11 and 10 (receiving terminator)

At the rising edge of b0, the error occurrence status (BFM #28, b3) and error code (BFM #29) are cleared.

2. b1 (sending command)

At the rising edge of b1, the contents of the send data buffer (BFM #1001 to 1256) in the amount of bytes specified (BFM #1000) are sent to the external equipment.

When sending is completed, the sending complete status (BFM #28, b0) is set to ON. When the next sending command (b1) is given, the sending complete status (BFM #28, b0) is automatically set to OFF.

When the sending command is given, the contents of the following set items are determined:

- BFM #5 and 4 (sending header)
- BFM #7 and 6 (sending terminator)

3. b2 (receiving complete flag reset command)

When b2 is set to ON, the following items are cleared:

- BFM #28, b1 (receiving complete)
- BFM #2000 (number of received bytes)
- BFM #2001 to 2256 (receive data buffer)

After receiving is completed, it is necessary to clear the receiving complete status (BFM #28, b1) because the 232IF cannot receive next data while b1 of the BFM #28 remains ON.

When the receiving complete flag reset command is given, the contents of the following set items are determined:

- BFM #9 and 8 (receiving header)
- BFM #11 and 10 (receiving terminator)

In the RS-232C interlink connection mode (BFM #0, b9 = 1, b8 = 1), the receiving complete flag reset command works as the receiving continue command for receiving data beyond the maximum number of receivable bytes (BFM #2), and clears the following items:

- BFM #28, b4 (receiving suspended)
- BFM #2000 (number of received bytes)
- BFM #2001 to 2256 (receive data buffer)
- BFM #2257 to 2271 (preliminary receive data buffer)

The receiving enable (RS) signal is automatically set to ON.

4. b3 (error reset)

When b3 is set to ON, the contents of the error occurrence status (BFM #28, b3) and error code (BFM #29) are cleared.

5.4.4 Maximum number of receivable bytes <BFM #2>

Setting range: 1 to 512 bytes (when the buffer data length is 16-bit)
1 to 256 bytes (when the buffer data length is 8-bit)

"0" is handled as "512" or "256 bytes". The initial value is "0".

This bit specifies the maximum number of bytes which can be received by the 232IF.

When the 232IF receives the maximum number of receivable bytes, it sets the receiving complete flag (BFM #28, b1) to ON.

If the receiving terminator (BFM #11 and 10) or receiving timeout time (BFM #3) are set, the 232IF recognizes that receiving is completed even if the already received data does not reach the maximum number of receivable bytes when either condition is satisfied.

5.4.5 Receiving timeout time <BFM #3>

Setting range: 1 to 32767 (× 10 ms)

"0" is regarded as no timeout time. The initial value is "0".

This bit specifies the waiting time limit for receive data.

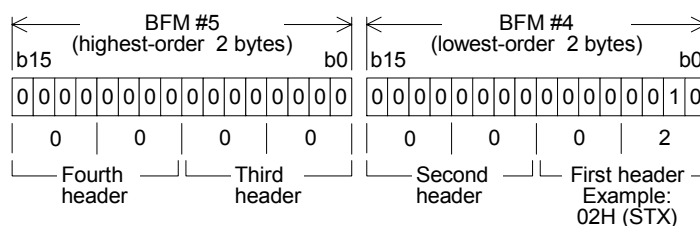
When the 232IF does not receive the next set of data within the receiving timeout time after the receiving edge of each data, the receiving timeout flag (BFM #28, b2) turns ON. At this time, the 232IF recognizes that receiving is completed, and sets the receiving complete flag (BFM #28, b1) to ON.

5.4.6 Sending header <BFM #5 (highest-order 2 bytes) and BFM #4 (lowest-order 2 bytes)>

Setting range: 4 bytes maximum, 0 suppression

The initial value is "0" (no sending header).

Up to four headers can be specified for the 232IF send data. When the number of headers is less than 4, "0"s in upper positions are ignored (0 suppression) and are not transferred.



The transfer order is "fourth header → third header → second header → first header" when four headers are set.

5.4.7 Sending terminator <BFM #7 (highest-order 2 bytes) and BFM #6 (lowest-order 2 bytes)>

Setting range: 4 bytes maximum, 0 suppression

The initial value is "0" (no sending terminator).

Up to four terminators can be specified for the 232IF send data. When the number of terminators is less than 4, "0"s in upper positions are ignored (0 suppression) and are not transferred.

For the terminator transferred first, specify ASCII code from "01H" to "1FH". (For other terminators after that, any ASCII code other than "01H" to "1FH" can be specified.)

The register structure and transfer order are the same as those of the sending header described above.

5.4.8 Receiving header <BFM #9 (highest-order 2 bytes) and BFM #8 (lowest-order 2 bytes)>

Setting range: 4 bytes maximum, 0 suppression

The initial value is "0" (no sending header).

Up to four headers can be specified for the 232IF received data. When the number of headers is less than 4, "0"s in upper positions are ignored (0 suppression) and are not transferred.

The register structure and transfer order are the same as those of the sending header described above.

5.4.9 Receiving terminator <BFM #11 (highest-order 2 bytes) and BFM #10 (lowest-order 2 bytes)>

Setting range: 4 bytes maximum, 0 suppression

The initial value is "0" (no sending terminator).

Up to four terminators can be specified for the 232IF received data. When the number of terminators is less than 4, "0"s in upper positions are ignored (0 suppression) and are not transferred.

For the terminator received first, specify an ASCII code from "01H" to "1FH". (For other terminators after that, any ASCII code other than "01H" to "1FH" can be specified.)

The register structure and transfer order are the same as those of the sending header described above.

5.4.10 Receiving suspension waiting time <BFM #12>

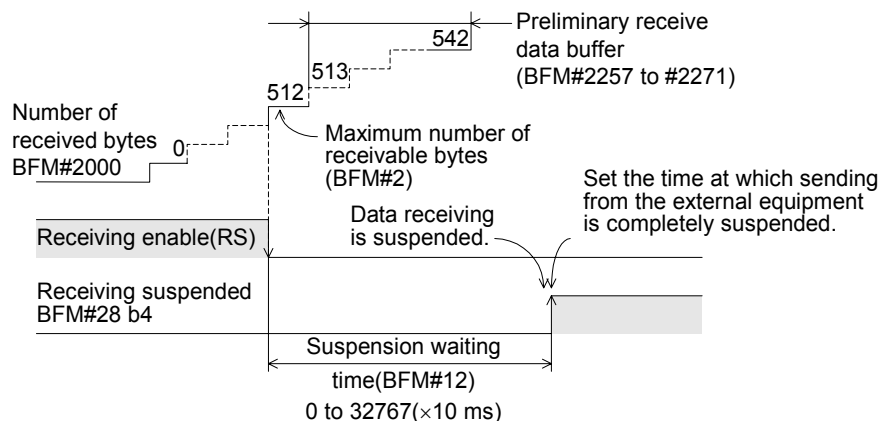
Setting range: 0 to 32767 ($\times 10$ ms)

The initial value is "0 ms".

When the 232IF receives data beyond the maximum number of receivable bytes (BFM #2) in the RS-232C interlink connection mode (BFM #0, b9 = 1, b8 = 1), it sets the receiving enable (RS) signal to OFF to ask the external equipment to suspend sending.

BFM #12 sets the time after the receiving enable (RS) signal is set to OFF until the receiving suspended status bit (BFM #28, b4) is set to ON. Make sure that the time set by BFM #12 is longer than the time between when the 232IF sets the receiving enable (RS) signal to OFF until the external equipment completely suspends sending.

If the receiving suspended status bit (BFM #28, b4) is set to ON before the external equipment stops sending, the 232IF cannot receive the remaining data any more.



5.4.11 Amount of remaining send data <BFM #13>

Stored value: 0 to 512 (when the buffer data length is 16-bit)

0 to 256 (when the buffer data length is 8-bit)

This buffer stores the value set in the number of bytes to be sent (BFM #1000) subtracted by the number of already sent data.

5.4.12 Amount of received data buffers <BFM #14>

Stored value: 0 to 256+15 ("15" is provided for the preliminary receive data buffer.)

This buffer stores the amount of received data buffers which have already received data among the received data buffers BFM #2001 to 2256 and preliminary receive data buffers for interlink connection mode BFM #2257 to 2271.

5.4.13 Sending sum result <BFM #15>

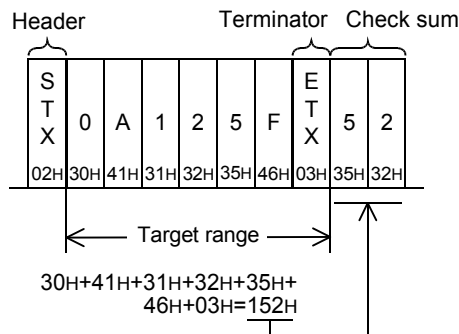
Initial value: 0

This buffer stores the value of the check sum added to the send data.

The sum check target range and check sum calculation method are as shown below.

Sum check target range and check sum calculation method

(Example)



The sum of the data including the terminators but not the first header (first one byte only) is calculated, the least significant byte of the calculation result is converted into ASCII code, and the data is sent and received. The ASCII data is arranged in the order of "upper digit, lower digit".

5.4.14 Receiving sum result <BFM #16>

Initial value: 0

This buffer stores the sum check value of the received data.

If the check sum value added to the received data is different from the receiving sum result, "receiving sum check error" occurs.

The sum check target range and check sum calculation method are the same as those shown in "5.4.13 Sending sum result" above.

5.4.15 Time from CS ON to sending start <BFM #20>

Set value: 0 to 32767 (× 10 ms)

Initial value: 0 ms

This buffer sets the time between when the sending enable (CS) signal is set to ON until the 232IF actually starts to send.

When "control line not provided" is specified, this buffer sets the time after the sending command is given until sending starts.

Set proper time according to the modem, etc.

5.4.16 Time from actual sending completion to RS OFF <BFM #21>

Set value: 0 to 32767 (× 10 ms)

Initial value: 0 ms

This buffer sets the time between when the 232IF completes sending until RS signal turns OFF and the sending complete flag (BFM #28, b0) turns ON.

Set proper time according to the modem, etc.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/R2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

5.4.17 Status <BFM #28>

| Bit | Contents | Bit | Contents |
|-----|---------------------|-----|-----------|
| b0 | Sending complete | b8 | RS(RTS) |
| b1 | Receiving complete | b9 | ER(DTR) |
| b2 | Receiving timeout | b10 | Undefined |
| b3 | Error occurrence | b11 | Undefined |
| b4 | Receiving suspended | b12 | DR(DSR) |
| b5 | Undefined | b13 | CD(DCD) |
| b6 | Sending | b14 | DS(CTS) |
| b7 | Receiving | b15 | CI(RI) |

This buffer stores the 232IF status and sending/receiving result as the status information. The PLC can read this buffer using the FROM instruction.

1. b0 (sending complete)

When sending the specified amount of bytes (BFM #1000) is completed, the sending complete flag (b0) is set to ON.

The sending complete flag (b0) is automatically set to OFF when the next sending command (BFM #1, b1) is set to ON.

2. b1 (receiving complete)

When the maximum number of receivable bytes (BFM #2) are received, the receiving complete flag (b1) is set to ON.

If the receiving terminator (BFM #11 and 10) or receiving timeout time (BFM #3) is set, the 232IF recognizes that receiving is completed even if the already received data does not reach the maximum number of received bytes when either condition is satisfied.

It is necessary to set this receiving complete flag to OFF in a sequence program. The 232IF is not ready to receive the next set of data while this bit is ON. Use the receiving complete flag reset command (BFM #1, b2) to set this bit to OFF.

3. b2 (receiving timeout)

When the receiving timeout time (BFM #3) is reached during receiving, the receiving timeout bit (b2) is set to ON. And the receiving complete flag (b1) is also set to ON.

The receiving timeout status (b2) is set to OFF when the receiving complete flag reset command (BFM #1, b2) is executed.

4. b3 (error occurrence)

When an error occurs during sending or receiving, the error occurrence status bit (b3) is set to ON and the contents of the error are stored in the error code (BFM #29).

5. b4 (receiving suspended)

When the 232IF receives data beyond the maximum number of receivable bytes (BFM #2) in the RS-232C interlink connection mode (BFM #0, b9 = 1, b8 = 1), it sets the receiving enable (RS) signal to OFF and asks the external equipment to suspend sending. After the receiving suspension waiting time (BFM #12), the 232IF sets the receiving suspended status bit (b4) to ON.

To receive data beyond the maximum number of receivable bytes (BFM #2) in the interlink connection mode, it is necessary to monitor the rising edge of this receiving suspended status bit (b4) in the sequence program, and withdraw the number of received bytes (BFM #2000) or amount of received data buffers (BFM #14) from the received data buffer (BFM #2001 to 2271) to data registers inside the PLC.

6. b6 (sending)

This bit remains ON from when the sending command (BFM #1, b1) is given until the sending complete flag (BFM #28, b0) is set to ON.

7. b7 (receiving)

This bit remains ON from when the head data is received until the receiving complete flag (BFM #28, b1) is set to ON.

8. b8 (RS), b9 (ER), b12 (DR), b13 (CD), b14 (CS) and b15 (CI)

These bits indicate the operation status by their ON/OFF status.

5.4.18 Error code <BFM #29>

For the error codes, refer to Section 7.2.

5.4.19 Model code <BFM #30>

The model code of the 232IF is "K7030".

The model code is a specific code assigned to each special extension module. By reading the model code in the PLC, the equipment type can be checked.

5.4.20 Number of bytes to be sent <BFM #1000>

Setting range: 0 to 512 bytes (when the buffer data length is 16-bit)

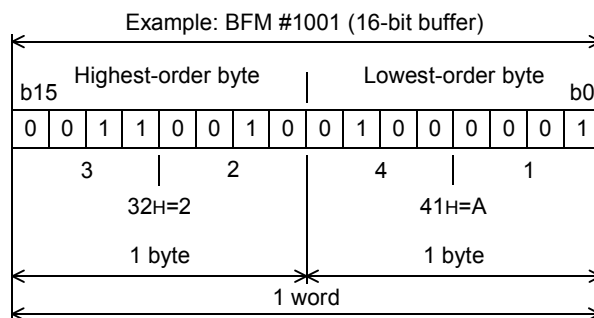
0 to 256 bytes (when the buffer data length is 8-bit)

This buffer specifies how many bytes should be sent among the 512 bytes/256 words in the 16-bit send data buffer (BFM #1001 to 1256).

5.4.21 Send data buffer <BFM #1001 to 1256>

The send data buffer is a section of 16-bit buffers for storing the send data. The send data buffers can store up to 512 bytes/256 words.

Structure of send/receive data buffer



Values in the send data buffers and receive data buffers are handled as hexadecimal values.

5.4.22 Number of received bytes <BFM #2000>

Stored value: 0 to 512+30*1 bytes (when the buffer data length is 16-bit)

0 to 256+15*1 bytes (when the buffer data length is 8-bit)

This buffer stores the number of bytes received from the external equipment. The value stored in this buffer is cleared when the receiving complete flag reset command (BFM #1, b2) is given.

*1. "30" or "15" bytes are provided for the preliminary buffer in the interlink connection mode.

5.4.23 Receive data buffer <BFM #2001 to 2256>

The received data buffer is a section of 16-bit buffers for storing the data received from the external equipment. The received data buffer can store up to 512 bytes/256 words.

The received data buffer structure is same as the send data buffer structure.

The contents of the received data buffer are cleared when the receiving complete flag reset command (BFM #1, b2) is given.

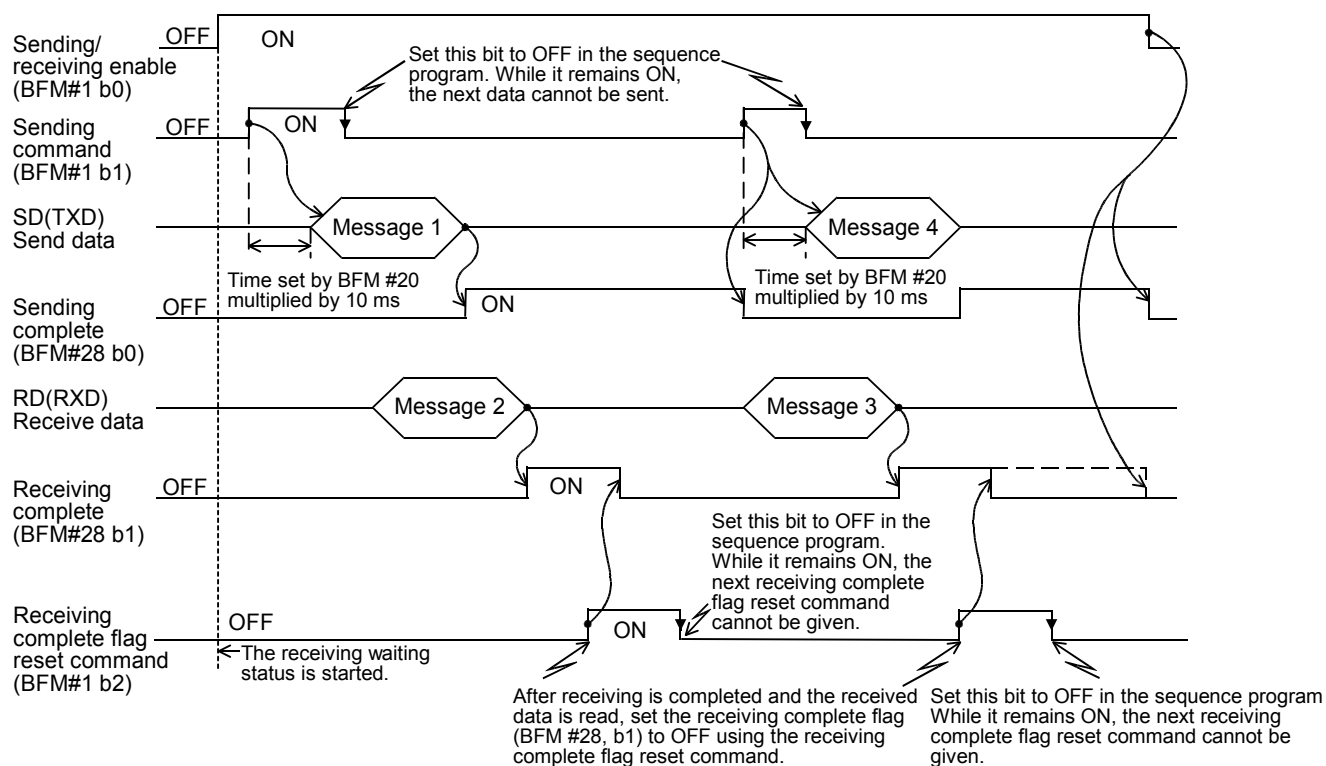
5.4.24 Preliminary receive data buffer for interlink connection mode <BFM #2257 to 2271>

The preliminary receive data buffer is provided for storing the data beyond 512 bytes in the interlink connection mode. The preliminary receive data buffers are used to receive the data sent after the receiving enable (RS) signal is set to OFF until the external equipment suspends sending.

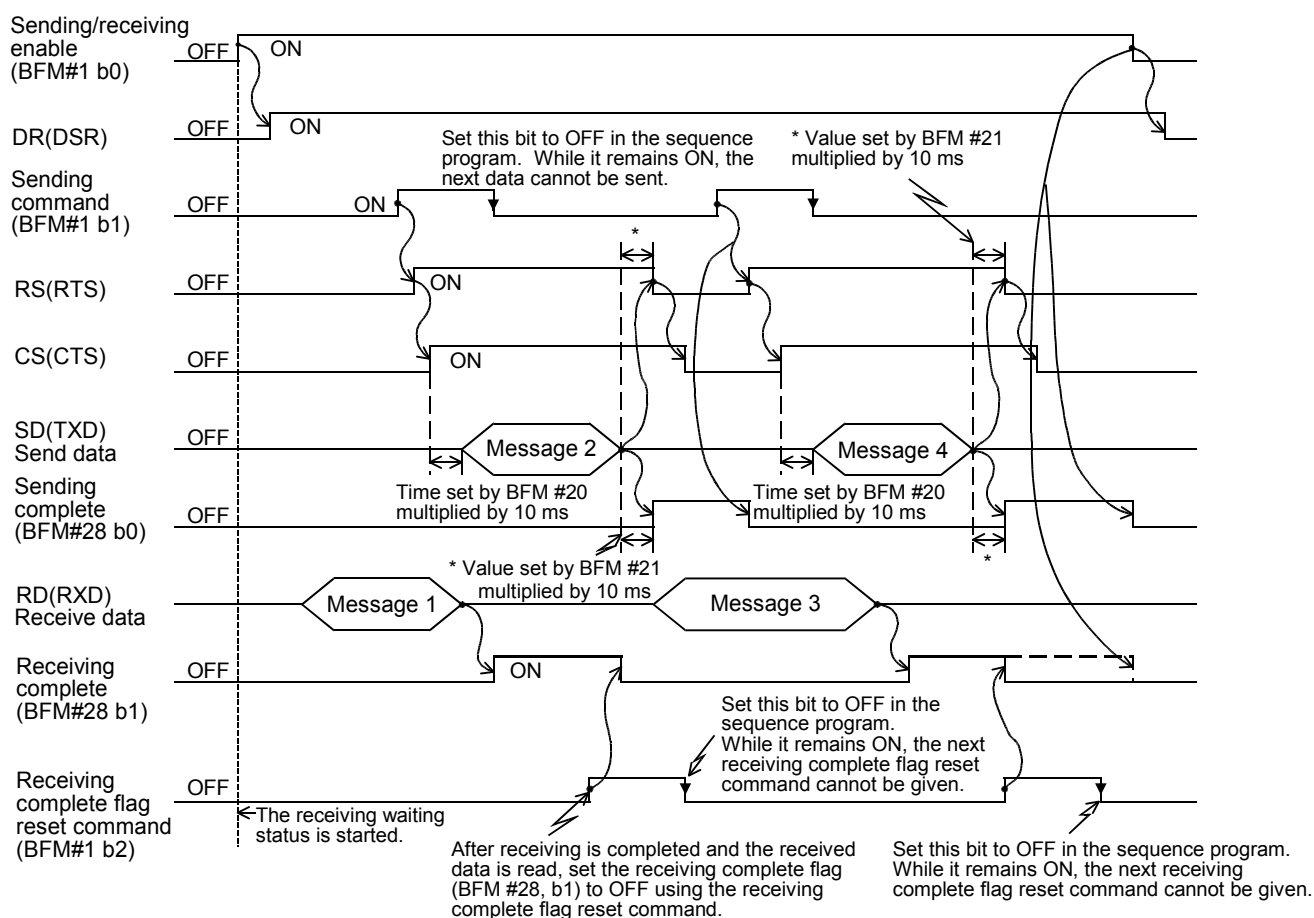
The contents of the preliminary receive data buffer are cleared when the receiving complete flag reset command (BFM #1, b2) is given.

5.5 Operation of Control Line

5.5.1 When control line is not provided [BFM #0, (b9, b8) = (0, 0)]



5.5.2 When control line is in standard RS-232C mode [BFM #0, (b9, b8) = (0, 1)]



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

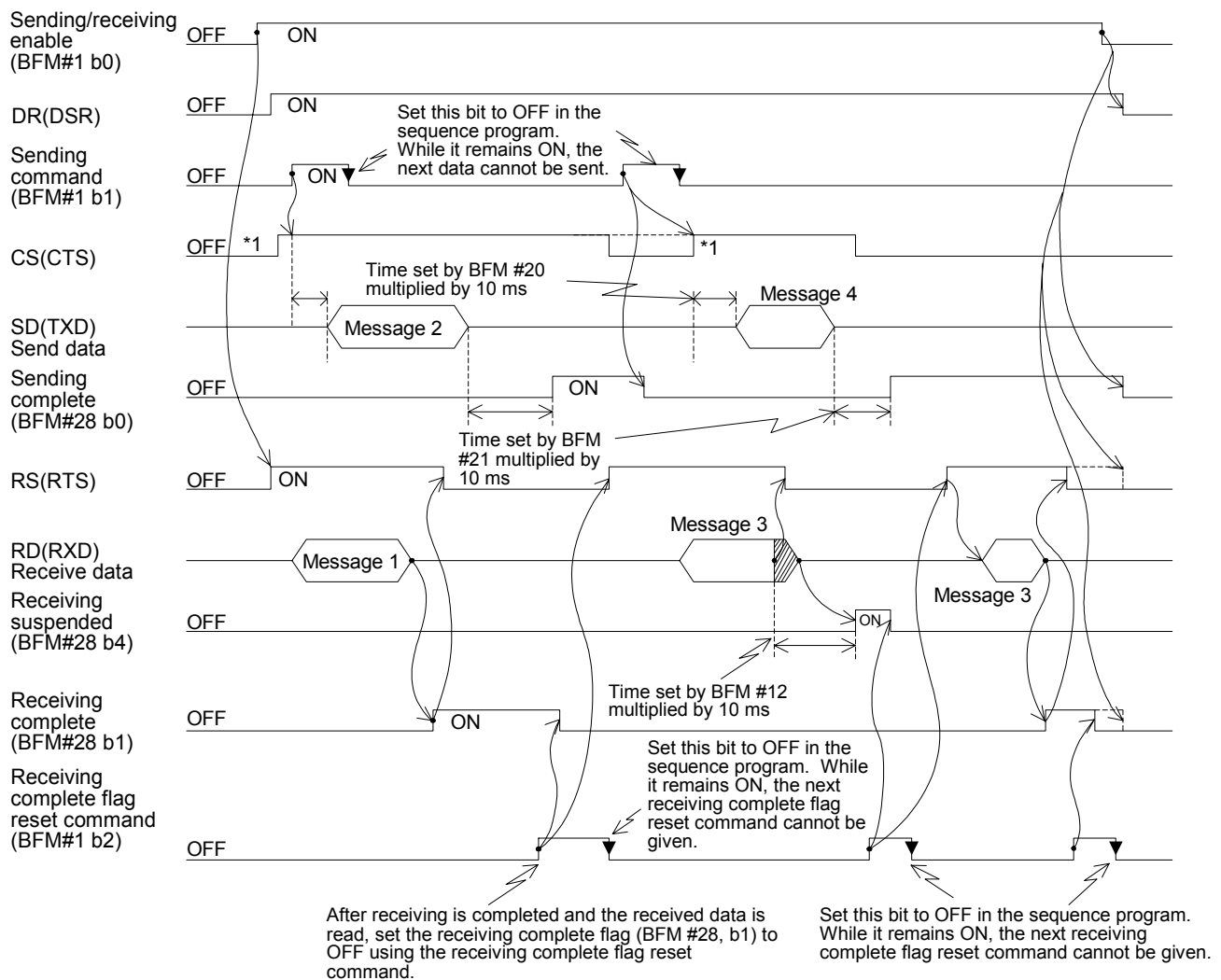
I

Remote Maintenance

Apx.

Discontinued models

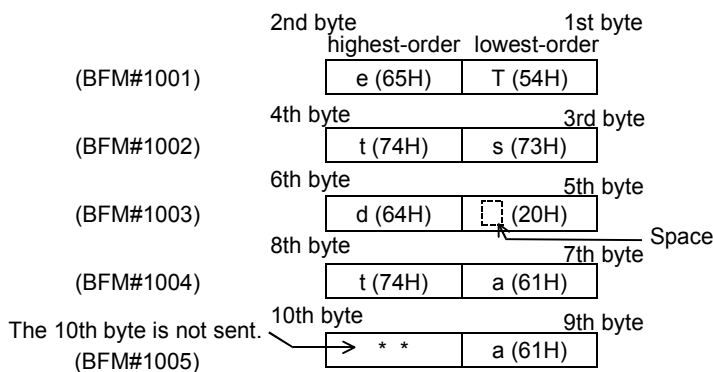
5.5.3 When control line is in RS-232C interlink mode [BFM #0, (b9, b8) = (1, 1)]



- *1. Make sure that the CS (CTS) signal turns ON in the 232IF while the external equipment is ready to receive.
- *2. When the amount of data already received exceeds the maximum number of receivable bytes specified by BFM #2, the RS (RTS) signal turns OFF. Accordingly, sending is suspended from the external equipment within 30 bytes when the send/receive data buffer data length is 16-bit (BFM #0, b14= 0), or within 15 bytes when the send/receive data buffer data length is 8-bit (BFM #0, b14= 1). If sending is not suspended, the 232IF cannot receive all sent data.
- *3. Read the amount of received bytes (BFM #14) from the received data buffer (BFM #2001 to 2271) to data registers in the PLC, and then set it to ON.

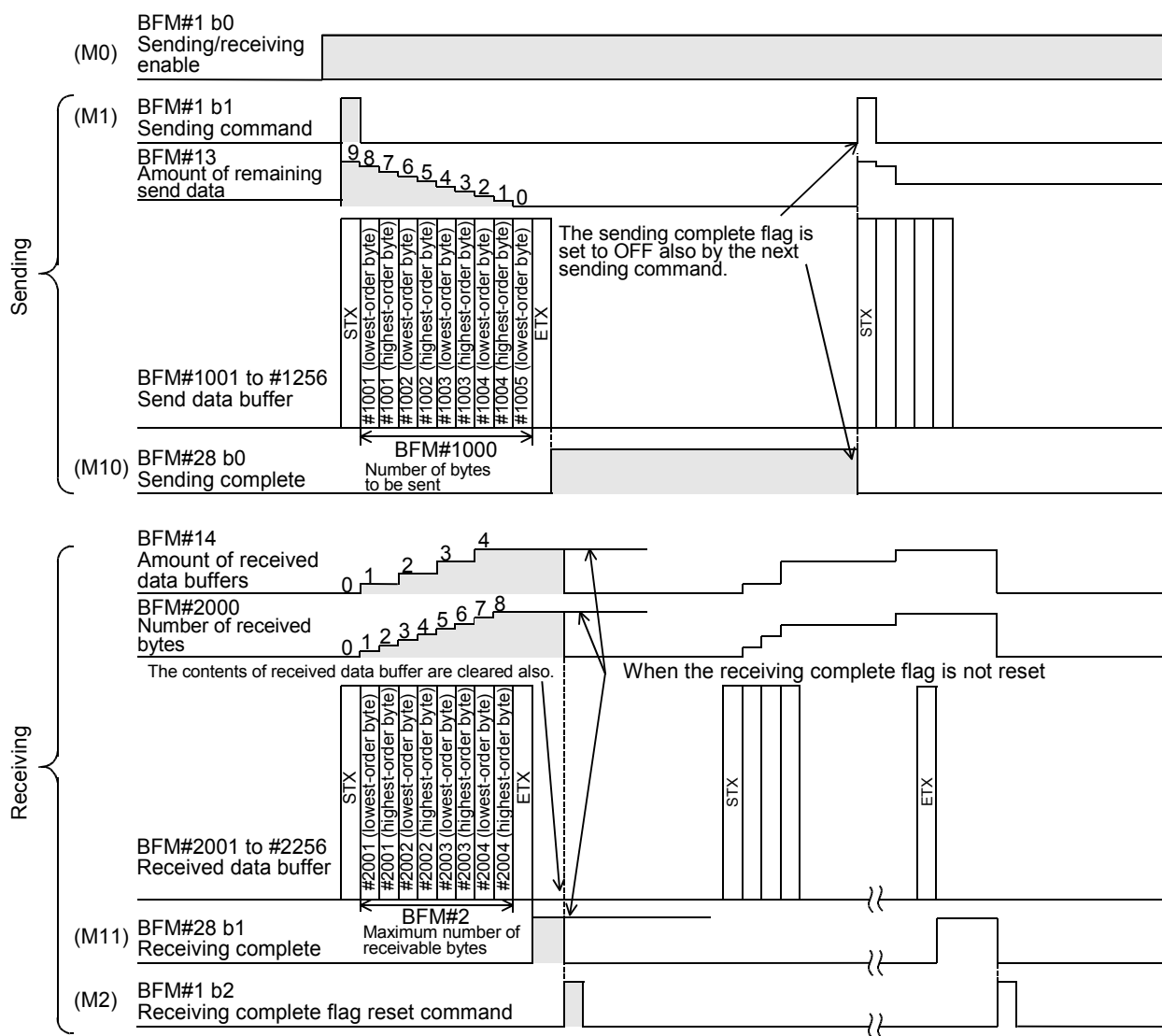
- 4) Header and terminator <BFM #4 to 11>
BFM #4 and 8 (sending header and receiving header): 02H (STX)
BFM #6 and 10 (sending terminator and receiving terminator): 03H (ETX)
- 5) Status <BFM #28>

| | |
|-------------------------------|----------------------|
| b0 → M10: Sending complete | b8 → M18: RS(RTS) |
| b1 → M11: Receiving complete | b9 → M19: ER(DTR) |
| b2 → M12: Receiving timeout | b10 → M20: Undefined |
| b3 → M13: Error occurrence | b11 → M21: Undefined |
| b4 → M14: Receiving suspended | b12 → M22: DR(DSR) |
| b5 → M15: Undefined | b13 → M23: CD(DCD) |
| b6 → M16: Sending | b14 → M24: CS(CTS) |
| b7 → M17: Receiving | b15 → M25: CI(RI) |
- 6) Number of bytes to be sent <BFM #1000>
9 bytes
- 7) Send data buffer <BFM #1001 and later>
The send data "Test data" in ASCII codes is provided to 9 bytes (as specified in BFM#1000).

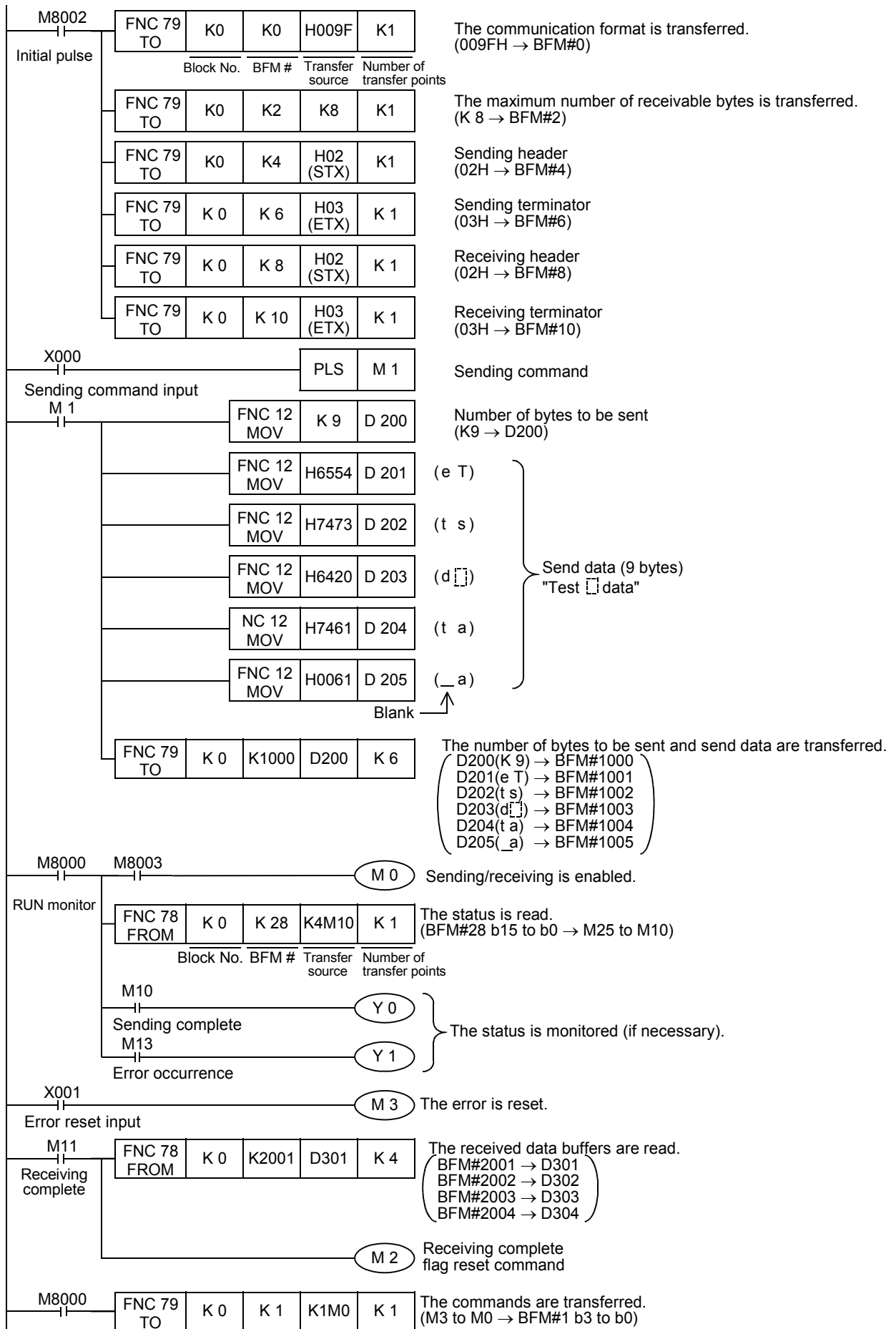


- 8) Receive data buffer <BFM #2001 and later>
Eight bytes specified by the maximum number of receivable bytes (BFM #2) are read to data registers D301 to D304 in the PLC.

3. Operation chart



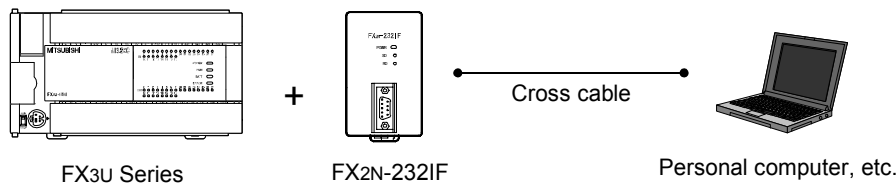
4. Sequence program example



6.2 Sending/Receiving 8-Bit Buffer Length Data

In this example, the 8-bit buffer length data is sent and received between the 232IF and equipment with the terminal specifications. In this example, ASCII codes stored in the data registers D201 to D209 in the PLC are sent to the external equipment, and the data received from the external equipment is stored to data registers D301 to D308 in the PLC.

1. System configuration

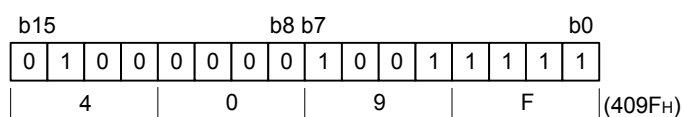


2. Example of setting buffer memory

Suppose that each buffer memory not described here is set to the initial value.

1) Communication format <BFM #0>

| Bit | Contents | Setting |
|----------------------|--|--|
| b0 | Data length | (1) : 8-bit |
| b1 b2 | Parity | (1,1) : Even |
| b3 | Stop bit | (1) : 2-bit |
| b4 b5 b6 b7 | Baud rate | (1001) : 19200 bps |
| b8 b9 | Control line | (00) : Not provided |
| b10 b11 | CR and LF addition | (00) : Not provided |
| b12 b13 | Absence/presence of check sum and ASCII-Hexadecimal conversion | (00) : Not provided |
| b14 | Send/receive data buffer data length | (0) : 8-bit ← Item to specify 8-bit data |
| b15 | Undefined | — |



2) Command <BFM #1>

- M0 → b0: Sending/receiving enable (ER ON)
- M1 → b1: Sending command
- M2 → b2: Receiving complete flag reset command
- M3 → b3: Error reset

3) Maximum number of receivable bytes <BFM #2>

8 bytes

4) Header and terminator <BFM #4 to 11>

- BFM #4 and 8 (sending header and receiving header): 02H (STX)
- BFM #6 and 10 (sending terminator and receiving terminator): 03H (ETX)

5) Status <BFM #28>

| | |
|-------------------------------|----------------------|
| b0 → M10: Sending complete | b8 → M18: RS(RTS) |
| b1 → M11: Receiving complete | b9 → M19: ER(DTR) |
| b2 → M12: Receiving timeout | b10 → M20: Undefined |
| b3 → M13: Error occurrence | b11 → M21: Undefined |
| b4 → M14: Receiving suspended | b12 → M22: DR(DSR) |
| b5 → M15: Undefined | b13 → M23: CD(DCD) |
| b6 → M16: Sending | b14 → M24: CS(CTS) |
| b7 → M17: Receiving | b15 → M25: CI(RI) |

6) Number of bytes to be sent <BFM #1000>
9 bytes

7) Send data buffer <BFM #1001 and later>

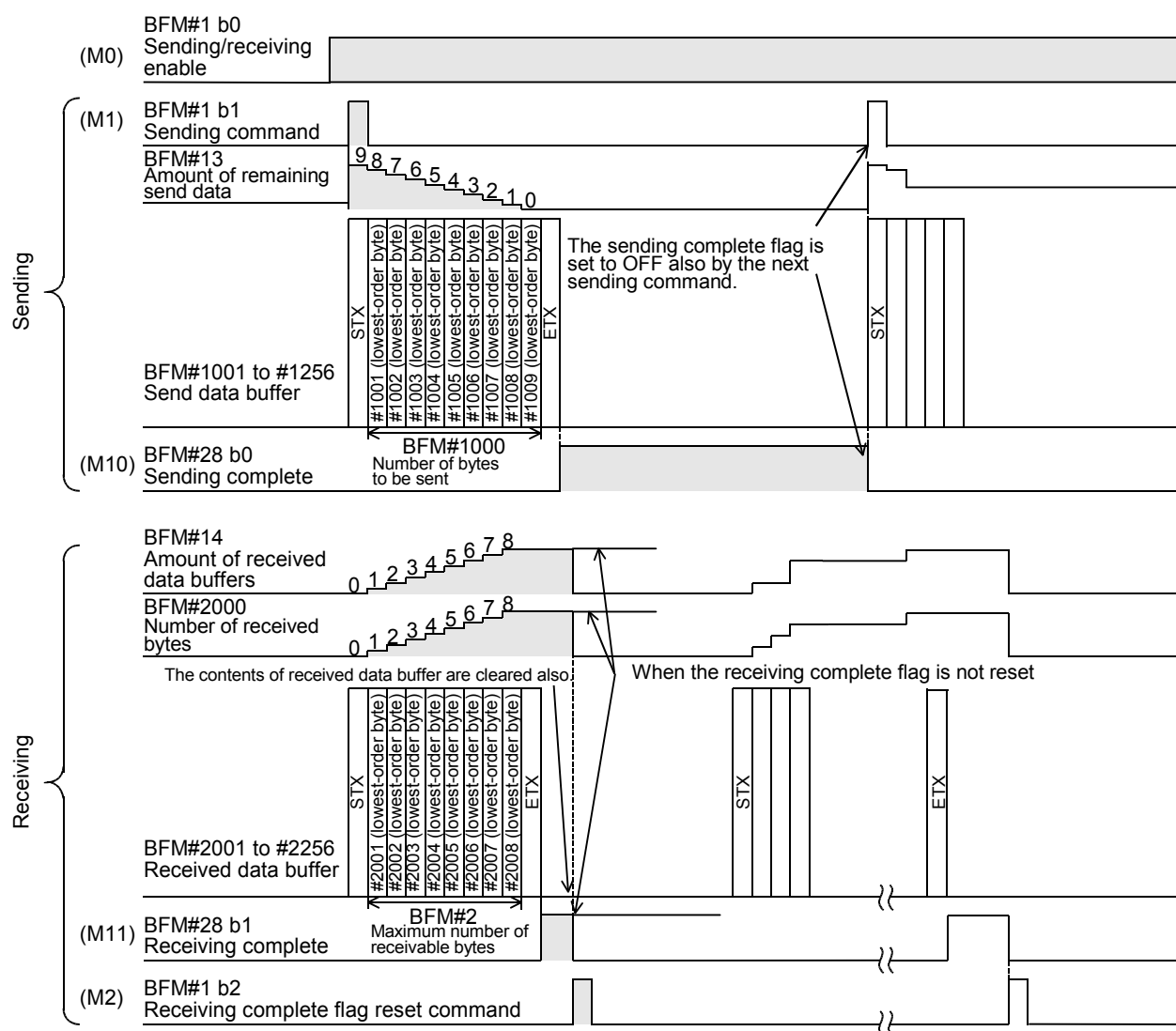
The send data "Test data" in ASCII code is provided to 9 bytes (as specified in BFM #1000).

| | | | | | |
|------------|---------------|--------------|----------|------------|----------|
| (BFM#1001) | highest-order | lowest-order | 1st byte | (BFM#1006) | 6th byte |
| | Ignored | T (54H) | | | Ignored |
| (BFM#1002) | | | 2nd byte | (BFM#1007) | 7th byte |
| | Ignored | e (65H) | | | Ignored |
| (BFM#1003) | | | 3rd byte | (BFM#1008) | 8th byte |
| | Ignored | s (73H) | | | Ignored |
| (BFM#1004) | | | 4th byte | (BFM#1009) | 9th byte |
| | Ignored | t (74H) | | | Ignored |
| (BFM#1005) | | | 5th byte | | |
| | Ignored | [] (20H) | | | |
| | | | Space | | |

8) Receive data buffer <BFM #2001 and later>

Eight bytes specified by the maximum number of receivable bytes (BFM #2) are read to data registers D301 to D308 in the PLC.

3. Operation chart



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol (RS/R52 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

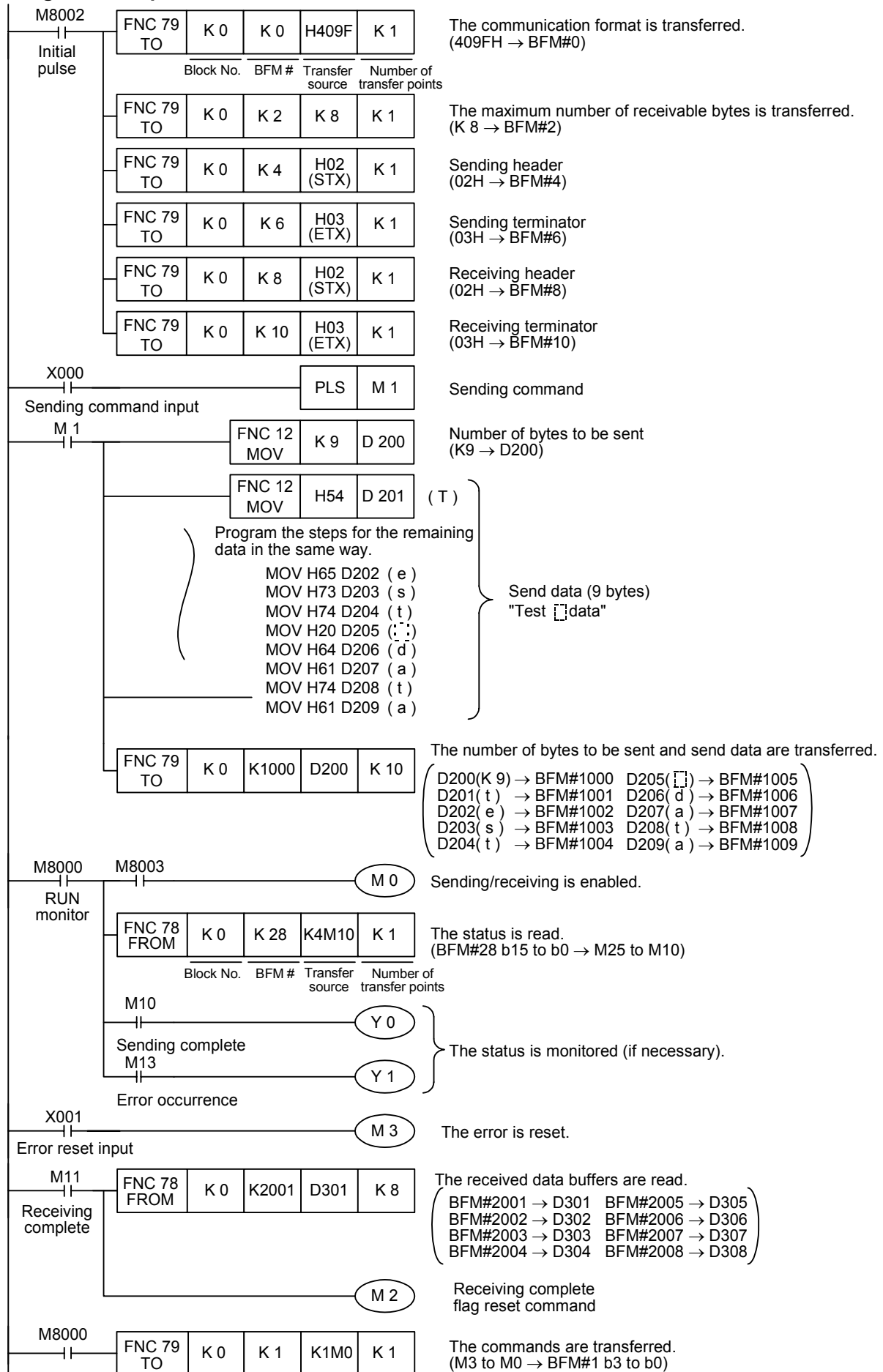
I

Remote Maintenance

Apx.

Discontinued models

4. Program example



7. Troubleshooting

7.1 Check Items

- 1) Check the POWER LED of the 232IF.
 - While the POWER LED is ON, the drive power is being supplied normally.
 - If the POWER LED is OFF, the drive power is not being supplied normally.
- 2) Verify that the power supply is correctly wired to terminals of the 232IF.
- 3) Check the SD LED and RD LED of the 232IF.
 - If the RD LED does not turn ON when the 232IF receives data or if the SD LED does not turn ON when the 232IF sends data, check the connection and wiring.
 - If the RD LED turns ON when the 232IF receives data or if the SD LED turn ON when the 232IF sends data, the installation and wiring are normal.
- 4) Verify that the communication setting (BFM #0) in the 232IF is aligned correctly with the communication setting in the external equipment. If the communication setting is not aligned correctly, align it.
- 5) Check the timing at which data is sent and received. For example, when sending data, verify that the external equipment is ready to receive.
- 6) When the terminator is not used, verify that the quantity of data to be sent matches the receivable data quantity. If the quantity of send data may vary, use the terminator.
- 7) Verify that the external equipment is operating normally.
- 8) Verify that the adopted data format is uniform. If the data format is different, modify it.

7.2 Error Codes

When an error occurs while data is being sent or received, the 232IF sets bit 3 of the BFM #28 to ON, and stores the corresponding error code to the BFM #29.

| Code | Contents | Cause and countermeasures |
|------|--|---|
| 0 | No error | — |
| 1 | Receiving parity error, overrun error or framing error | The communication format such as the baud rate does not agree. The control timing does not agree. |
| 2 | Undefined | — |
| 3 | Defective received character | The received data is not ASCII code. |
| 4 | Receiving sum check error | The sent sum does not agree with the received sum result (BFM #16). |
| 5 | Receive data buffer overflow (only in interlink connection mode) | The number of received bytes exceeds "512+30" bytes. Decrease the maximum number of receivable bytes (BFM #2), and increase the preliminary receive data buffer area. |
| 6 | Baud rate setting error | Non-existing baud rate is specified. |
| 7 | Receiving CR error | CR is not located in the specified position. |
| 8 | Receiving LF error | LF is not located in the specified position. |
| 9 | Head sending/receiving terminator setting error | The head terminator is something other than 01H to 1FH. |
| 10 | Receiving terminator error | The terminator is not located in the specified position. Or the terminator does not agree. |
| 11 | Undefined | — |
| 12 | Transmission order error | The transmission order does not agree. |

MEMO

FX Series Programmable Controllers

User's Manual [Programming Communication]

Foreword

This manual explains "programming communication" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit. Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

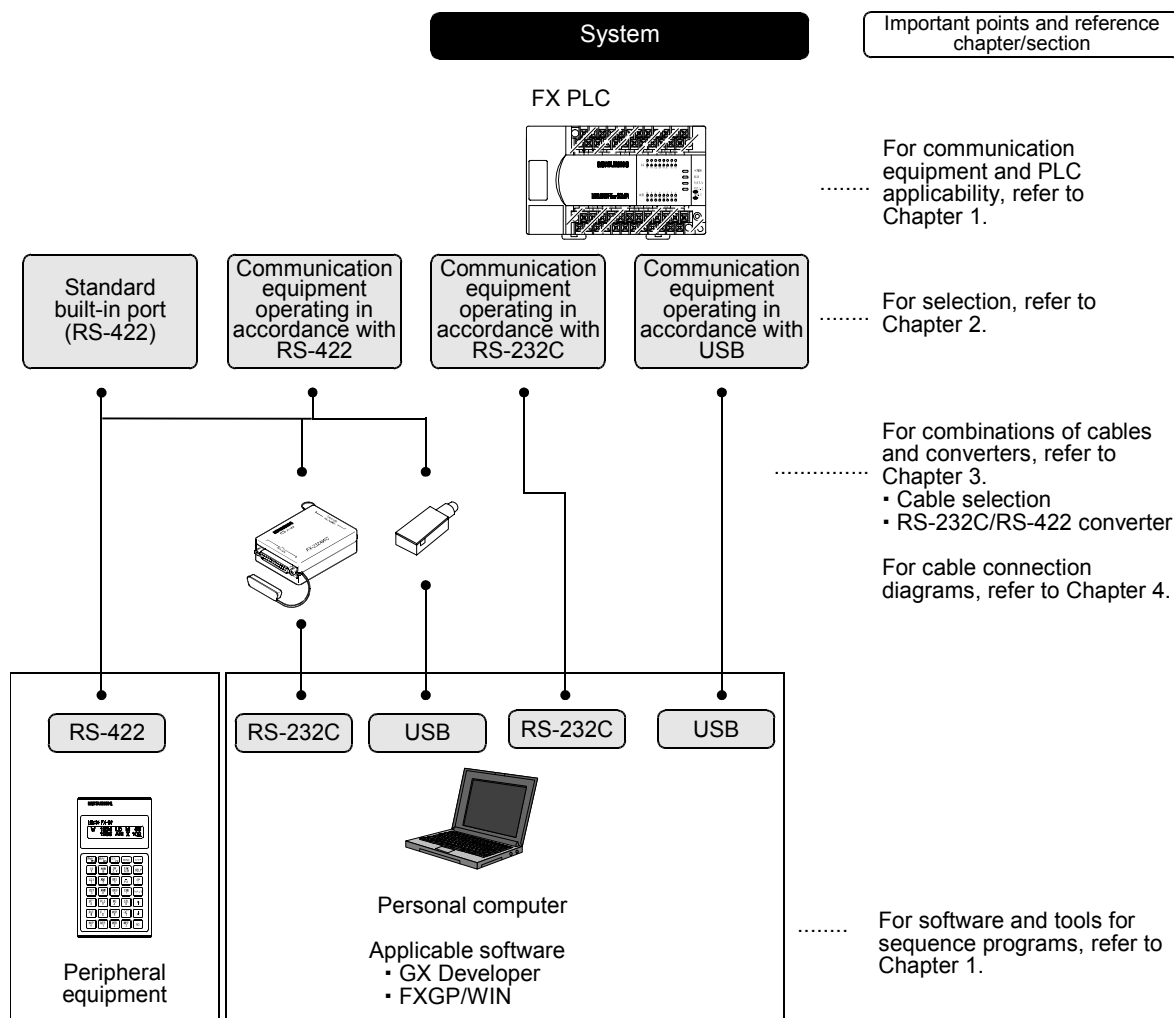
1. Outline

This chapter explains programming communication.

1.1 Outline of System

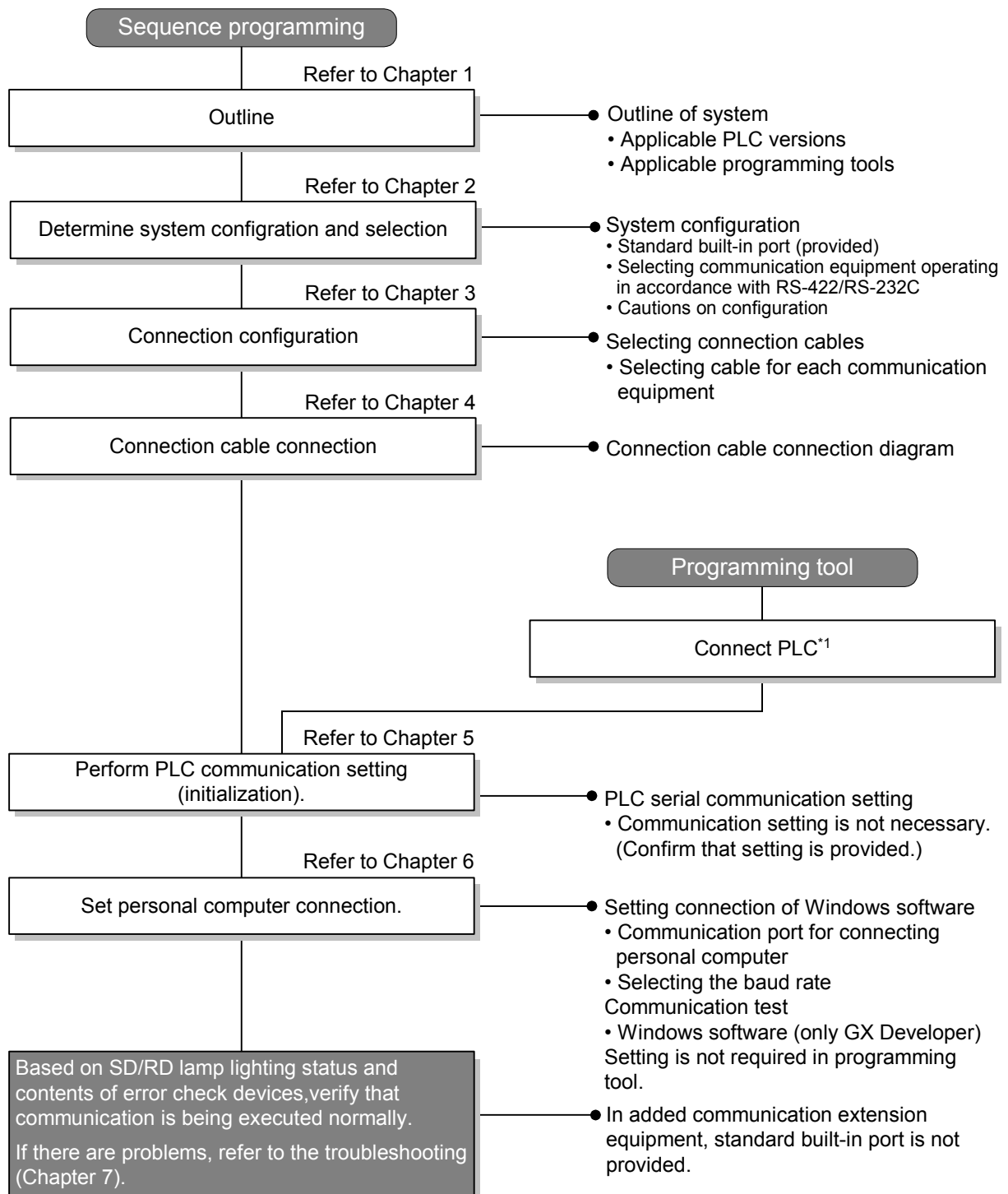
Programming communication transfers programs and monitors devices when a PLC programming tool is connected.

- 1) A PLC can be directly connected to the RS-232C port in a personal computer with one cable.
- 2) Sequence programs can be transferred and devices can be monitored through the USB port in a personal computer.
This function is not provided for the FX2(FX) and FX2c Series.
- 3) It is possible to monitor devices using one programming tool, and change programs using another programming tool.
This function is not provided for the FX2(FX), FX2c, and FX0N Series.
- 4) Two HMIs or one HMI and one programming tool can be connected at the same time.
This function is not provided in the FX2(FX), FX2c, and FX0N Series.



1.2 Procedures Before Operation

The flow chart below shows the programming communication setting procedures up until data link:



*1 For the programming tool to PLC connection procedure, refer to this manual or the respective programming tool manual.
For details on operation methods, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

The communication types are applicable in the following versions.

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| PLC | Standard built-in port in accordance with RS-422 | Optional communication equipment operating in accordance with RS-422 (-BD) | Optional communication equipment operating in accordance with RS-232C | | Optional communication equipment operating in accordance with USB (-BD)*1 | Remarks |
|----------------------|--|--|---|-------|---|--|
| | | | (-BD) | (ADP) | | |
| FX3UC(D, DSS) Series | ✓ | — | — | ✓ | — | Programming communication is provided in all of the standard built-in port and optional communication equipment operating in accordance with RS-422/RS-232C/USB. |
| FX3UC-32MT-LT | ✓ | ✓ | ✓ | ✓ | ✓ | |
| FX3U Series | ✓ | ✓ | ✓ | ✓ | ✓ | |
| FX2NC Series | ✓ | — | — | ✓ | — | |
| FX2N Series | ✓ | ✓ | ✓ | ✓ | — | |
| FX1NC Series | ✓ | — | — | ✓ | — | |
| FX1N Series | ✓ | ✓ | ✓ | ✓ | — | |
| FX1S Series | ✓ | ✓ | ✓ | ✓ | — | |
| FX0N Series | ✓ | — | — | ✓ | — | Programming communication is provided in all of the standard built-in port, but is not provided in any optional communication equipment operating in accordance with RS-422/RS-232C/USB. |
| FX0S Series | ✓ | — | — | — | — | |
| FX0 Series | ✓ | — | — | — | — | |
| FX2C Series | ✓ | — | — | ✓ | — | |
| FX2(FX) Series | ✓ | — | — | ✓ | — | |
| FX1 Series | ✓ | — | — | — | — | |

*1. When using USB communication with a model that does not support USB communication equipment (-BD), use the FX-USB-AW.
However, FX2(FX), FX2C and FX1 PLCs do not support the FX-USB-AW.

1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description on system configuration, etc. in this manual for maintenance.

| PLC | Date when production was stopped | Remarks |
|----------------|----------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2C Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

1.4 Programming Tool Applicability

1.4.1 For applicable versions

The programming tool is applicable for each FX Series from the version shown:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.00 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXC | ✓ (Ver. 4.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 5.00 or later) | |
| FX-20P(-SET0) FX-20P-MFXD | ✓ (Ver. 5.00 or later) | |
| FX-10P(-SET0) | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD F940GOT-*WD F940GOT-*BD-H F940GOT-*BD-RH | ✓ (Refer to right column) | F940WGOT-TWD (Ver. 1.00 or later) F940GOT-LWD, F940GOT-SWD (Ver. 1.00 or later) F940GOT-LBD-H, F940GOT-SBD-H (Ver. 1.00 or later) F940GOT-LBD-RH, F940GOT-SBD-RH (Ver. 1.00 or later) |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXC-E | ✓ (Ver. 3.00 or later) | |
| FX-10P-E | ✓ (Ver. 3.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |
| FX-20P-E(-SET0) FX-20P-MFXD-E | ✓ (Ver. 4.00 or later) | |
| FX-10P-E | ✓ (Ver. 4.00 or later) | |
| GOT-F900 Series display units F940WGOT-TWD-E F940GOT-*WD-E F940GOT-*BD-H-E F940GOT-*BD-RH-E | ✓ (Refer to right column.) | F940WGOT-TWD-E (Ver. 1.00 or later) F940GOT-LWD-E, F940GOT-SWD-E (Ver. 1.00 or later) F940GOT-LBD-H-E, F940GOT-SBD-H-E (Ver. 1.00 or later) F940GOT-LBD-RH-E, F940GOT-SBD-RH-E (Ver. 1.00 or later) |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

1.4.2 For non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set. In this case, however, programming is enabled only in the ranges provided for the alternative PLC model such as instructions and program size.

| Model to be programmed | Model to be set | Priority: High → Low | | | |
|------------------------|-----------------|----------------------|---------|---|---------|
| FX3UC Series | FX3UC | → | FX2N | → | FX2(FX) |
| FX3U Series | FX3U, FX3UC | → | FX2N | → | FX2(FX) |
| FX2NC Series | FX2NC, FX2N | → | FX2(FX) | | |
| FX2N Series | FX2N | → | FX2(FX) | | |
| FX1NC Series | FX1NC, FX1N | → | FX2N | → | FX2(FX) |
| FX1N Series | FX1N | → | FX2N | → | FX2(FX) |
| FX1S Series | FX1S | → | FX2(FX) | | |
| FX0N Series | FX0N | → | FX2(FX) | | |
| FX0S Series | FX0S | → | FX2(FX) | | |
| FX0 Series | FX0 | → | FX2(FX) | | |
| FX2C Series | FX2C, FX2(FX) | → | FX2(FX) | | |
| FX2(FX) Series | FX2(FX) | → | FX2(FX) | | |
| FX1 Series | FX1 | | | | |


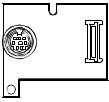
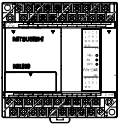
2. System Configuration and Selection

This chapter explains the system configuration and selection of communication equipment operating in accordance with RS-422, RS-232C or USB required by FX PLCs.

2.1 System Configuration

This section outlines the system configuration required to use programming communication. Connect (optional) communication equipment operating in accordance with RS-422, RS-232C, USB, or the FX PLC main unit.

2.1.1 For communication equipment operating in accordance with RS-422

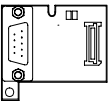

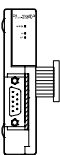
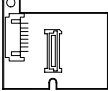
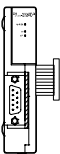
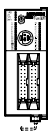
| Communication equipment operating in accordance with RS-422 | FX PLC | Important point in selection | Total extension distance |
|---|--|---|--------------------------|
| 1 Not required |  | The standard port built in a PLC is used. | 30 m (98' 5") |
| 2  Communication board | +  | This is the communication board built into the PLC, reducing the installation area. | 50 m (164' 0") |

For communication equipment combinations for each FX Series, refer to the next section.

| | |
|------|---|
| A | Common Items |
| B | N:N Network |
| C | Parallel Link |
| D | Computer Link |
| E | Inverter Communication |
| F | Non-Protocol Communication (RS/RST Instruction) |
| G | Non-Protocol Communication (FX2N-232IF) |
| H | Programming Communication |
| I | Remote Maintenance |
| Apx. | Discontinued models |

2.1.2 For communication equipment operating in accordance with RS-232C

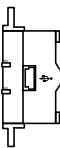
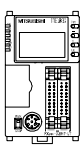
1, **2** and **3** indicate the communication equipment combination patterns.

| Communication equipment operating in accordance with RS-232C | FX PLC | Important point in selection | Total extension distance |
|--|--------|--|--------------------------|
| 1  Communication board | + |  This is the communication board built into the PLC, reducing the installation area. | 15 m (49' 2") |
| 2  Communication adapter | + |  Connector conversion board | 15 m (49' 2") |
| 3  Communication adapter | + |  Attach the communication adapter to the left side of the main unit. | 15 m (49' 2") |



For communication equipment combinations for each FX Series, refer to the next section.

2.1.3 For communication equipment operating in accordance with USB

| Communication equipment operating in accordance with USB | FX PLC | Important point in selection | Total extension distance |
|--|--------|--|--------------------------|
|  Communication board | + |  This is the communication board built into the PLC, reducing the installation area. | 5 m (16' 4") |


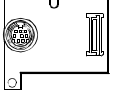
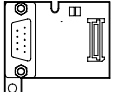
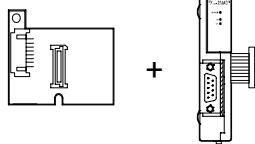
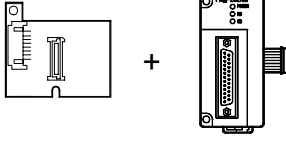
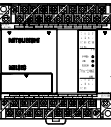
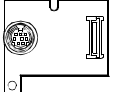
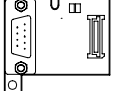
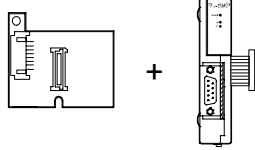
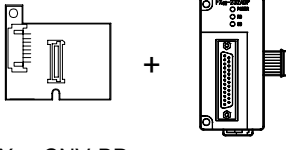


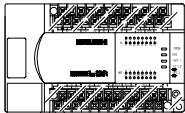

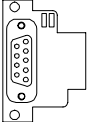
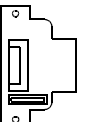
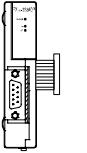
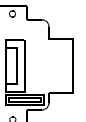
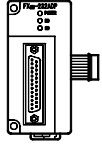
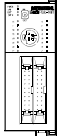
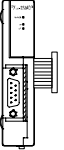
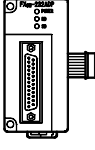
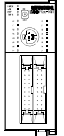
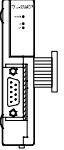
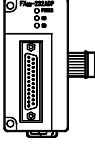
For communication equipment combinations for each FX Series, refer to the next section.


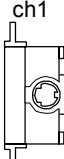
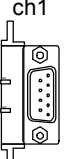
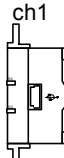

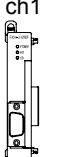

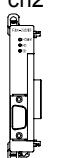

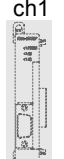
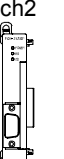
2.2 Applicable FX PLC and Communication Equipment

Select a communication equipment combination, and put a check mark in the "Check" column.
During selection, pay attention to the following:

- In the table below, only the outside dimensions are different between the units shown in "FX2NC-232ADP/FX0N-232ADP".
Select either one.
- Only one unit of communication equipment can be connected.
- In the FX0, FX0S and FX0N Series, only the standard built-in port (8-pin MINI-DIN) is provided.
- In the FX1, FX2(FX), and FX2C Series, only the standard built-in port (25-pin D-Sub type) is provided.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX1S Standard built-in port (8-pin MINI-DIN) |  FX1N-422-BD (8-pin MINI-DIN) | 50 m (164' 0") | |
| |  FX1N-232-BD (9-pin D-Sub) | 15 m (49' 2") | |
| |  +  FX1N-CNV-BD FX2NC-232ADP (9-pin D-Sub) FX1N-CNV-BD FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |
|  FX1N Standard built-in port (8-pin MINI-DIN) |  FX1N-422-BD (8-pin MINI-DIN) | 50 m (164' 0") | |
| |  FX1N-232-BD (9-pin D-Sub) | 15 m (49' 2") | |
| |  +  FX1N-CNV-BD FX2NC-232ADP (9-pin D-Sub) FX1N-CNV-BD FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX2N Standard built-in port (8-pin MINI-DIN) |  FX2N-422-BD (8-pin MINI-DIN) | 50 m (164' 0") | |
| |  FX2N-232-BD (9-pin D-Sub) | 15 m (49' 2") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-232ADP (9-pin D-Sub) FX2N-CNV-BD FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |
|  FX1NC Standard built-in port (8-pin MINI-DIN) |  /  FX2NC-232ADP (9-pin D-Sub) FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |
|  FX2NC Standard built-in port (8-pin MINI-DIN) |  /  FX2NC-232ADP (9-pin D-Sub) FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  <p>FX3U</p> <p>Standard built-in port (8-pin MINI-DIN)</p> | When using channel 1 (ch 1) | | |
| |  <p>ch1</p> <p>FX3U-422-BD (8-pin MINI-DIN)</p> | 50 m (164' 0") | |
| |  <p>ch1</p> <p>FX3U-232-BD (9-pin D-Sub, male)</p> | 15 m (49' 2") | |
| |  <p>ch1</p> <p>FX3U-USB-BD (MINI-USB B)</p> | 5 m (16' 4") | |
| |  <p>FX3U-CNV-BD</p> <p>+</p>  <p>ch1</p> <p>FX3U-232ADP(-MB) (9-pin D-Sub, male)</p> | 15 m (49' 2") | |
| | When using channel 2 (ch 2) | | |
| |  <p>ch1</p> <p>FX3U-□-BD (Where □ represents 232, 422, 485 and USB)</p> <p>+</p>  <p>ch2</p> <p>FX3U-232ADP(-MB) (9-pin D-Sub, male)</p> | 15 m (49' 2") | |
| |  <p>FX3U-CNV-BD</p> <p>+</p>  <p>ch1</p> <p>FX3U-□ADP(-MB) (Where □ represents 232 and 485)</p> <p>+</p>  <p>ch2</p> <p>FX3U-232ADP(-MB) (9-pin D-Sub, male)</p> | 15 m (49' 2") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

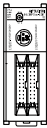



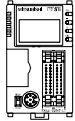
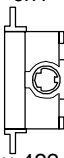
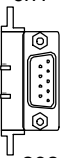

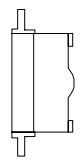
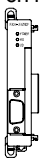
Programming Communication

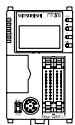


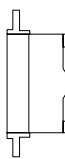

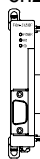
I

Remote Maintenance

Apx.

Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  <p>FX3UC (D, DSS)</p> <p>Standard built-in port (8-pin MINI- DIN)</p> | When using channel 1 (ch 1) | | |
| |  <p>ch1</p> <p>FX3U-232ADP(-MB) (9-pin D-Sub, male)</p> | 15 m (49' 2") | |
| | When using channel 2 (ch 2) | | |
| |  <p>ch1</p> <p>FX3U-□ADP(-MB) (Where □ represents 232 and 485)</p> <p>+</p>  <p>ch2</p> <p>FX3U-232ADP(-MB) (9-pin D-Sub, male)</p> | 15 m (49' 2") | |
|  <p>FX3UC-32MT-LT</p> <p>Standard built-in port (8-pin MINI- DIN)</p> | When using channel 1 (ch 1) | | |
| |  <p>ch1</p> <p>FX3U-422-BD (8-pin MINI-DIN)</p> | 50 m (164' 0") | |
| |  <p>ch1</p> <p>FX3U-232-BD (9-pin D-Sub, male)</p> | 15 m (49' 2") | |
| |  <p>ch1</p> <p>FX3U-USB-BD (MINI-USB B)</p> | 5 m (16' 4") | |
| |  <p>FX3U-CNV-BD</p> <p>+</p>  <p>ch1</p> <p>FX3U-232ADP(-MB) (9-pin D-Sub, male)</p> | 15 m (49' 2") | |

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|--|--------------------------|-------|
|  FX3UC-32MT-LT Standard built-in port (8-pin MINI-DIN) | When using channel 2 (ch 2) <div style="display: flex; align-items: center; justify-content: center;"> <div style="text-align: center;">  ch1 FX3U-□-BD (Where □ represents 232, 422, 485 and USB) </div> <div style="font-size: 2em; margin: 0 10px;">+</div> <div style="text-align: center;">  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) </div> </div> | 15 m (49' 2") | |
| | <div style="display: flex; align-items: center; justify-content: center;"> <div style="text-align: center;">  FX3U-CNV-BD </div> <div style="font-size: 2em; margin: 0 10px;">+</div> <div style="text-align: center;">  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485) </div> <div style="font-size: 2em; margin: 0 10px;">+</div> <div style="text-align: center;">  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) </div> </div> | 15 m (49' 2") | |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

2.3 Caution on Selection

Some caution should be observed when using a programming tool with optional FX PLC communication equipment.

Consider the following contents during selection.

2.3.1 When using 422BD

1. Current consumption at 5V DC of the expansion board

When the 422BD is attached to a PLC, it consumes the following current:

- 1) For FX3U and FX3UC PLCs
The FX3U-422-BD consumes 20 mA at 5V DC from the FX3U/FX3UC-32MT-LT PLC.
- 2) For FX2N PLCs
The FX2N-422-BD consumes 60 mA at 5V DC from the FX2N PLC.

2. Current consumption of the special extension equipment and peripheral equipment

Make sure that the current consumption at 5V DC including the 422BD described above, special extension equipment, and peripheral equipment shown below does not exceed the power capacity at 5V DC in the FX2N/FX3U/FX3UC PLC.

| Peripheral equipment | Connection cable | Current consumption at 5V DC*1 |
|--|--|--------------------------------|
| FX-20P(-E) | FX-20P-CAB0 or FX-20P-CAB + FX-20P-CADP | 180 mA |
| FX-10P(-E) | | 120 mA |
| Personal computer (for programming) | <F2-232CAB (for 25-pin D-Sub), F2-232CAB-1 (for 9-pin D-Sub) or F2-232CAB-2 (for 14-pin half-pitch)> + FX-232AW(C) + FX-422CAB0 | 220 mA |
| | <F2-232CAB (for 25-pin D-Sub), F2-232CAB-1 (for 9-pin D-Sub) or F2-232CAB-2 (for 14-pin half-pitch)> + FX-232AWC-H + FX-422CAB0 | 120 mA |
| | USB cable (for connecting personal computer: A plug, male type) (for connecting FX-USB-AW: MINI B plug, male type) + FX-USB-AW | 15 mA |
| FX-10DU(-E) | FX-20P-CAB0 or FX-20P-CAB + FX-20P-CADP | 220 mA |
| FX-20DU(-E) | FX-20DU-CAB0 | 180 mA |
| FX-10DM(-E) | FX-20P-CAB0 or FX-20P-CAB + FX-20P-CADP | 220 mA |
| FX-25DU(-E), FX-30DU(-B)(-E), FX-40DU(-B)(-ES), FX-40DU-TK(B)(-E), FX-50DU-TK(S)(-E), and ET-50 Series | FX-50DU-CAB0(-1M, -10M, -20M, -30M) | 0 mA |
| | FX-40DU-CAB(-10M, -20M, -30M) + FX-422AW0 | 160 mA |
| F940GOT-SWD(LWD)(-E), F930GOT-BWD(-E), ET-940 Series F930GOT-BBD-K(-E), and F920GOT-BBD-K | FX-50DU-CAB0(-1M, -10M, -20M, -30M, L) | 0 mA |
| F940 Handy GOT (RH type) | F9GT-H(RH)CAB2-150 + F9GT-H(RH)CAB-3M(-10M) or F9GT-HCAB-3M(-10M) + F9GT-HCNB + FX-50DU-CAB0(-1M) | 0 mA |
| F920GOT-BBD5-K | FX-50DU-CAB0(-1M) | 220 mA |
| F920 Handy GOT RH type | F9GT-HCAB2-150, F9GT-HCAB-3M(-10M) | 0 mA |
| GOT-A900 Series (CPU direct connection type) | FX9GT-CAB0(-150, -10M) | 0 mA |
| GOT1000 Series (CPU direct connection type) | GT01-C□R4-8P (Where □ represents 10, 30, 100, or 300.) | 0 mA |

*1. The power consumption of the FX3U-422-BD and FX2N-422-BD is not included.

3. Connection of the FX-2PIF

The FX-2PIF cannot be connected to the 422BD.
Connect it to the standard port.

2.3.2 When using 232BD or 232ADP

When the 232BD or 232ADP is attached to a PLC, it consumes the current shown in the table below. Make sure that the power capacity of 5V DC in the FX2N/FX3U/FX1NC/FX2NC/FX3UC PLC is not exceeded.

✓: Applicable

—: Not attachable

| Model name | Power consumption at 5 VDC | FX2N | FX3U | FX1NC | FX2NC | FX3UC (D, DSS) | FX3UC-32MT-LT |
|------------------|----------------------------|------|------|-------|-------|----------------|---------------|
| FX3U-232-BD | 20 mA | — | ✓ | — | — | — | ✓ |
| FX2N-232-BD | 20 mA | ✓ | — | — | — | — | — |
| FX3U-232ADP(-MB) | 30 mA | — | ✓ | — | — | ✓ | ✓ |
| FX2NC-232ADP | 100 mA | ✓ | — | ✓ | ✓ | — | — |
| FX0N-232ADP | 200 mA | ✓ | — | ✓ | ✓ | — | — |

2.3.3 Other cautions

1. For FX1S, FX1N, FX1NC and FX2N (whose version is before Ver. 2.00) PLCs

- 1) Verify that the communication format is in the initial status (D8120 = K0).
Check the communication parameters using the peripheral equipment.
If the communication is set so that non-protocol procedure (RS instruction) or a dedicated protocol is used, clear the setting to "0" using the peripheral equipment.
- 2) If RS instruction is used in the program, delete it, turn OFF the PLC power, and then turn it ON again.

2. For FX2N (Ver. 2.00 or later) and FX2NC (versions earlier than Ver. 3.00) PLCs

- 1) Verify that the communication format is in the initial status (D8120 = K0).
Check the communication parameters using the peripheral equipment.
If the communication is set so that non-protocol procedure (RS instruction) or a dedicated protocol is used, clear the setting to "0" using the peripheral equipment.
- 2) If RS instruction is used in the program, do not execute it. If it is executed, the PLC operates according to RS instruction.

3. For FX2N (Ver. 3.00 or later) and FX2NC (Ver. 3.00 or later) PLCs

- 1) Verify that the communication format is in the initial status (D8120 = K0).
Check the communication parameters using the peripheral equipment.
If the communication is set so that non-protocol procedure (RS instruction) or a dedicated protocol is used, clear the setting to "0" using the peripheral equipment.
- 2) If RS instruction is used in the program, do not execute it. If it is executed, the PLC operates according to RS instruction.
- 3) If EXTR instruction is used in the program, delete it, turn OFF the PLC power, and then turn it ON again.

4. For FX3U and FX3UC PLCs

- 1) Verify that the communication format for the communication port used in programming communication is set correctly (D8120, D8400, D8420 = K0).
Check whether the communication parameters are set correctly using the peripheral equipment.
- 2) Verify that the RS or RS2 instructions are not executed in the program for the communication port used in programming communication.
Do not execute RS and RS2 instructions.
- 3) If an inverter communication instruction is used in the program for the communication port used in programming communication, delete it, turn OFF the PLC power, and then turn it ON again.

3. Selecting Connection Cables

This chapter explains the connection cable selection method.

3.1 Connection Procedure

1 Checking the connector shape

Check the shape (male or female, etc.) of the connector of the connected programming tool (such as personal computer) and the shape of the connector of the PLC, and verify that connection is possible.

2 Connecting the cable connector to the programming tool

Check the shape of the cable connector for the programming tool, and connect the cable correctly.

3 Connecting the cable connector to the PLC

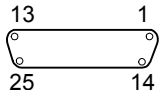
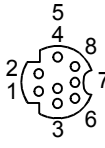
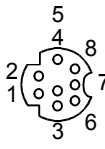
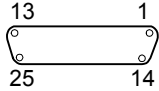
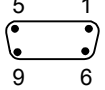

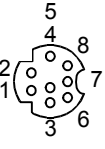
Check the cable connector for the PLC, and connect the cable correctly. The cable connector has one of the following shapes:

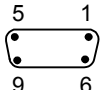
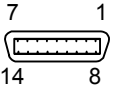
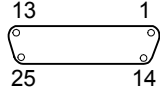
- 8-pin MINI-DIN, male
- 25-pin D-Sub, male
- 9-pin D-Sub, female
- 5-pin MINI-USB B plug, female

1. Selecting a connection cable

According to the combination of the connected programming tool and PLC (communication equipment), select the proper cable.

3.2 Connector Shape in Each Product

| Model name (series) | Connector shape |
|---|--|
| PLC | |
| FX1, FX2(FX) and FX2C PLCs |  25-pin D-Sub, female |
| FX0, FX0S, FX0N, FX1S, FX1N, FX2N, FX3U, FX1NC, FX2NC and FX3UC PLCs |  8-pin MINI-DIN, female |
| PLC (communication equipment) | |
| FX1N-422-BD FX2N-422-BD FX3U-422-BD |  8-pin MINI-DIN, female |
| FX0N-232ADP |  25-pin D-Sub, female |
| FX1N-232-BD FX2N-232-BD FX3U-232-BD FX2NC-232ADP FX3U-232ADP(-MB) |  9-pin D-Sub, male |
| FX3U-USB-BD |  5-pin MINI-USB B plug, female |
| Handy programming panel | |
| FX-10P(-E), FX-10P-SET0(-E), FX-20P(-E), FX-20P-SET0(-E) |  8-pin MINI-DIN, female |

| Model name (series) | Connector shape |
|--|--|
| Personal computer | |
| PC-AT compatible machine - DOS/V personal computer - Windows personal computer |  9-pin D-Sub, male |
| PC-9800 Series (NEC) - Notebook type personal computer |  14-pin Half-pitch, female |
| PC-9800 Series (NEC) - Desktop type personal computer |  25-pin D-Sub, female |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I


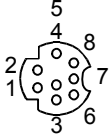
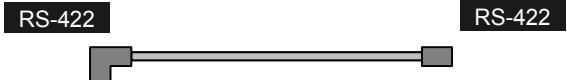
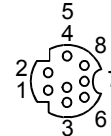

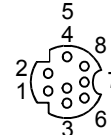

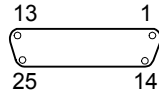
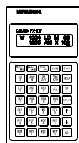
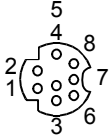

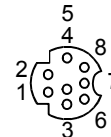
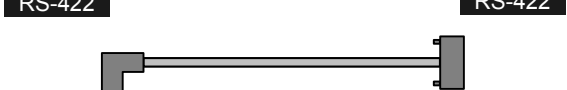
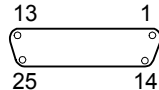
Remote Maintenance

Apx.

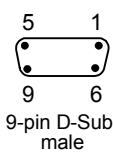
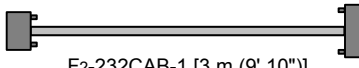
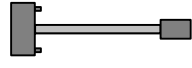
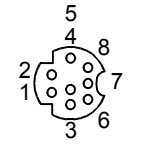
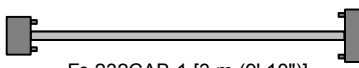
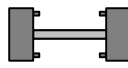
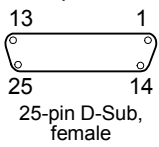
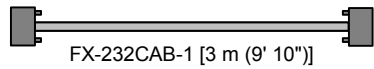
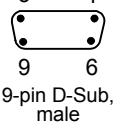
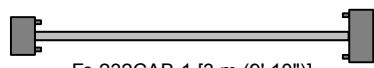
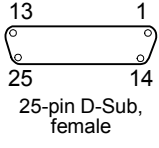

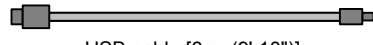
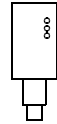
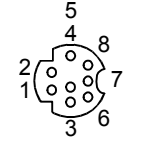


Discontinued models

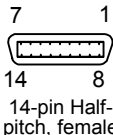
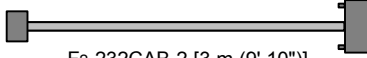


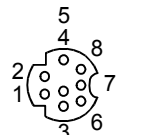
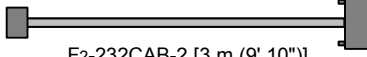


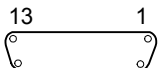
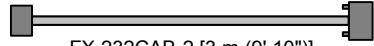
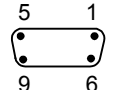

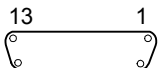
3.3 Combinations of Connection Cables

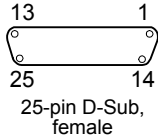
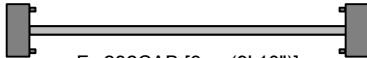


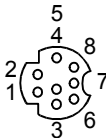
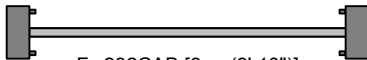

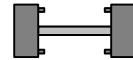
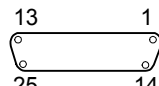
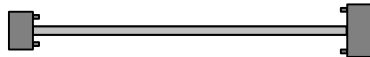
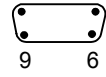
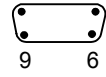
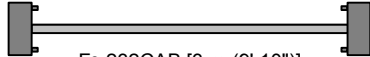
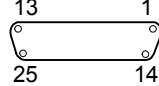
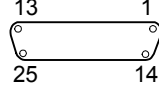
3.3.1 Handy programming panel

| Programming tool connector shape | Cable combination | PLC connector shape | Cable length |
|--|--|---|-------------------|
|  FX-10P(-E) FX-20P(-E)  8-pin MINI-DIN, female |  RS-422 FX-20P-CAB0 [1.5 m (4' 11")] ... sold separately | Standard built-in port FX1N-422-BD FX2N-422-BD FX3U-422-BD  8-pin MINI-DIN, female | 1.5 m (4' 11") |
| |  RS-422 FX-20P-CAB [1.5 m (4' 11")] ... supplied with FX-20P-CADP [0.3 m (0' 11")] ... sold separately | Standard built-in port  8-pin MINI-DIN, female | 1.8 m (5' 10") |
| |  RS-422 FX-20P-CAB [1.5 m (4' 11")] ... supplied with | Standard built-in port  25-pin D-Sub, female | 1.5 m (4' 11") |
|  FX-10P-SET0(-E) FX-20P-SET0(-E)  8-pin MINI-DIN, female |  RS-422 FX-20P-CAB0 [1.5 m (4' 11")] ... supplied with | Standard built-in port FX1N-422-BD FX2N-422-BD FX3U-422-BD  8-pin MINI-DIN, female | 1.5 m (4' 11") |
| |  RS-422 FX-20P-CAB [1.5 m (4' 11")] ... sold separately | Standard built-in port  25-pin D-Sub, female | 1.5 m (4' 11") |

3.3.2 Personal computer

| Programming tool connector shape | Cable combination | PLC connector shape | Cable length |
|--|---|--|----------------------------------|
| PC-AT compatible machine - DOS/V personal computer - Windows personal computer  9-pin D-Sub, male | RS-232C  F2-232CAB-1 [3 m (9' 10")] ... sold separately | RS-422  FX-422CAB0 [1.5 m (4' 11")] ... sold separately Standard built-in port FX1N-422-BD FX2N-422-BD FX3U-422-BD  8-pin MINI-DIN, female | 4.5 m (14' 9") |
| | RS-232C  F2-232CAB-1 [3 m (9' 10")] ... sold separately | RS-422  FX-422CAB [0.3 m (0' 11")] ... sold separately FX-422CAB-150 [1.5 m (4' 11")] ... sold separately Standard built-in port  25-pin D-Sub, female | 3.3 m (10' 9") 4.5 m (14' 9") |
| | RS-232C  FX-232CAB-1 [3 m (9' 10")] ... sold separately | RS-232C FX1N-232-BD FX2N-232-BD FX3U-232-BD FX2NC-232ADP FX3U-232ADP (-MB)  9-pin D-Sub, male | 3 m (9' 10") |
| | RS-232C  F2-232CAB-1 [3 m (9' 10")] ... sold separately | RS-232C FX0N-232ADP  25-pin D-Sub, female | 3 m (9' 10") |
| PC-AT compatible machine - Windows personal computer  USB A plug, female | USB  USB cable [3 m (9' 10")] ... supplied with | RS-422  FX-USB-AW Standard built-in port FX1N-422-BD FX2N-422-BD FX3U-422-BD  8-pin MINI-DIN, female | 3 m (9' 10") |
| | USB  USB cable [3 m (9' 10")] ... supplied with | USB FX3U-USB-BD  5-pin MINI-USB B plug, female | 5 m (16' 4") |

| Programming tool connector shape | Cable combination | PLC connector shape | Cable length |
|---|--|--|--|
| PC-9800 Series (NEC) - Notebook type personal computer  14-pin Half- pitch, female | <div> <div>RS-232C</div>  <div>F2-232CAB-2 [3 m (9' 10")] ... sold separately</div> </div> <div>  <div>FX-232AW FX-232AWC FX-232AWC-H</div> </div> <div> <div>RS-422</div>  <div>FX-422CAB0 [1.5 m (4' 11")] ... sold separately</div> </div> | Standard built-in port FX1N-422-BD FX2N-422-BD FX3U-422-BD  8-pin MINI-DIN, female | 4.5 m (14' 9") |
| | <div> <div>RS-232C</div>  <div>F2-232CAB-2 [3 m (9' 10")] ... sold separately</div> </div> <div>  <div>FX-232AW FX-232AWC FX-232AWC-H</div> </div> <div> <div>RS-422</div>  <div>FX-422CAB [0.3 m (0' 11")] ... sold separately FX-422CAB-150 [1.5 m (4' 11")] ... sold separately</div> </div> | Standard built-in port  25-pin D-Sub, female | 3.3 m (10' 9") 4.5 m (14' 9") |
| | <div> <div>RS-232C</div>  <div>FX-232CAB-2 [3 m (9' 10")] ... sold separately</div> </div> <div> <div>RS-232C</div> </div> | FX1N-232-BD FX2N-232-BD FX3U-232-BD FX2NC-232ADP FX3U-232ADP (-MB)  9-pin D-Sub, male | 3 m (9' 10") |
| | <div> <div>RS-232C</div>  <div>F2-232CAB-2 [3 m (9' 10")] ... sold separately</div> </div> <div> <div>RS-232C</div> </div> | FX0N-232ADP  25-pin D-Sub, female | 3 m (9' 10") |

| Programming tool connector shape | Cable combination | PLC connector shape | Cable length | |
|--|--|--|--|-----------------------------|
| <div>PC-9800 Series (NEC) - Desktop type personal computer</div> <div><div>25-pin D-Sub, female</div></div> | <div><div>RS-232C</div><div><div>F2-232CAB [3 m (9' 10")] ... sold separately</div></div><div><div>FX-232AW FX-232AWC FX-232AWC-H</div></div><div><div>RS-422</div><div><div>FX-422CAB0 [1.5 m (4' 11")] ... sold separately</div></div></div></div> | <div>Standard built-in port</div> <div>FX1N-422-BD FX2N-422-BD FX3U-422-BD</div> <div><div>8-pin MINI-DIN, female</div></div> | <div>4.5 m (14' 9")</div> | |
| | <div><div>RS-232C</div><div><div>F2-232CAB [3 m (9' 10")] ... sold separately</div></div><div><div>FX-232AW FX-232AWC FX-232AWC-H</div></div><div><div>RS-422</div><div><div>FX-422CAB [0.3 m (0' 11")] ... sold separately FX-422CAB-150 [1.5 m (4' 11")] ... sold separately</div></div></div></div> | <div>Standard built-in port</div> <div><div>25-pin D-Sub, female</div></div> | <div>3.3 m (10' 9") 4.5 m (14' 9")</div> | |
| | <div><div>RS-232C</div><div><div>F2-232CAB-1 [3 m (9' 10")] ... sold separately</div></div></div> | <div><div>RS-232C</div><div><div>9-pin D-Sub, male</div></div></div> | <div>FX1N-232-BD FX2N-232-BD FX3U-232-BD FX2NC-232ADP FX3U-232ADP (-MB)</div> <div><div>9-pin D-Sub, male</div></div> | <div>3 m (9' 10")</div> |
| | <div><div>RS-232C</div><div><div>F2-232CAB [3 m (9' 10")] ... sold separately</div></div></div> | <div><div>RS-232C</div><div><div>25-pin D-Sub, female</div></div></div> | <div>FX0N-232ADP</div> <div><div>25-pin D-Sub, female</div></div> | <div>3 m (9' 10")</div> |

 Standard built-in
port
FX1N-422-BD
FX2N-422-BD
FX3U-422-BD

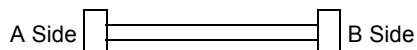

 8-pin MINI-DIN,
female
 4.5 m
(14' 9")

4. Connection Cables and Interfaces

4.1 Simplified Tables

4.1.1 Cable connector shape correspondence table

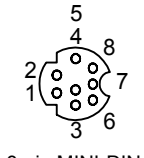
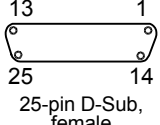
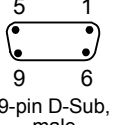
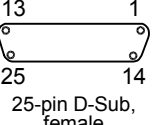

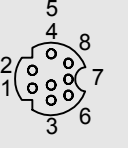

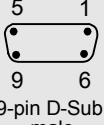
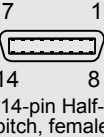
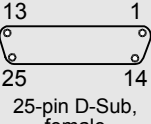
From the shape of connectors at both ends of a cable, the cable model name can be known.



| | B Side | | | | |
|-----------------------------------|--------------------------|--|-------------------------|--------------------------|--------------------------|
| A Side | 8-pin MINI-DIN, male | 5-pin MINI-USB B plug, male | 9-pin D-Sub, female | 25-pin D-Sub, male | 25-pin D-Sub, female |
| 8-pin MINI-DIN, male | FX-20P-CAB0 | — | — | FX-20P-CAB FX-422CAB0 | FX-20P-CADP |
| 5-pin MINI-USB B plug, female | FX-USB-AW (converter) | — | — | — | — |
| USB A plug, male | — | USB cable Provided as an accessory of FX- USB-AW and FX3U-USB-BD | — | — | — |
| 9-pin D-Sub, female | — | — | FX-232CAB-1 | F2-232CAB-1 | — |
| 14-pin Half-pitch, male | — | — | FX-232CAB-2 | F2-232CAB-2 | — |
| 25-pin D-Sub, male | — | — | F2-232CAB-1 | F2-232CAB | — |

4.1.2 Cable combination simplified table

From the shape of the programming tool connector and PLC connector, combinations of the cable, converter and communication equipment can be checked.

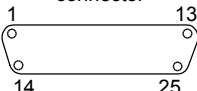
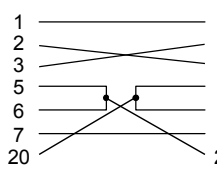
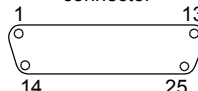
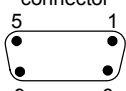
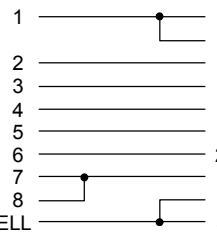
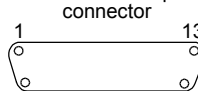
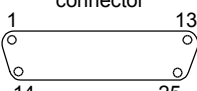
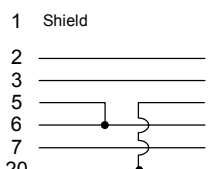
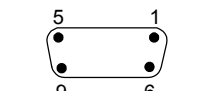
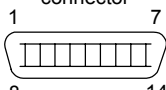
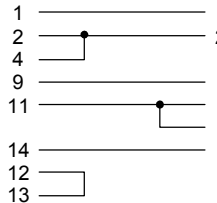
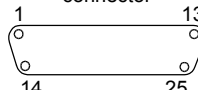
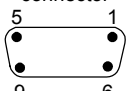
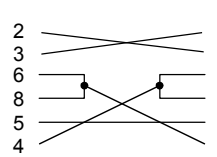
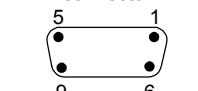
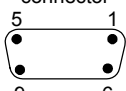
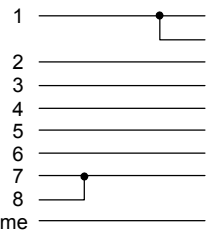
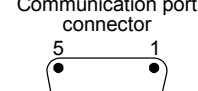
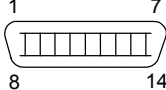
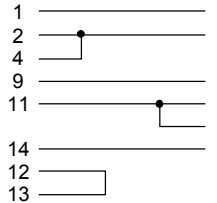
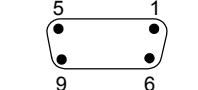
| Interface | | RS-422 | | RS-232C | | USB |
|-------------------------------|--|---|---|---|---|--|
| Standard port | | FX0,FX0S,FX0N FX1S,FX1N,FX2N FX1NC,FX2NC FX3U,FX3UC | FX1,FX2(FX) FX2C,A,QnA | — | — | — |
| Communication equipment | | FX1N-422-BD FX2N-422-BD FX3U-422-BD | — | FX1N-232-BD FX2N-232-BD FX3U-232-BD FX2NC-232ADP FX3U-232ADP (-MB) | FX0N-232ADP | FX3U-USB-BD |
| Connector in PLC | | | | | | |
| | |  8-pin MINI-DIN, female |  25-pin D-Sub, female |  9-pin D-Sub, male |  25-pin D-Sub, female |  5-pin MINI-USB B plug, female |
| Connector in programming tool |  8-pin MINI-DIN, female | FX-20P-CAB0 or FX-20P-CAB + FX-20P-CADP | FX-20P-CAB | — | — | — |
| |  USB A plug, female | FX-USB-AW + USB cable (included) | — | — | — | USB cable (included) |
| |  9-pin D-Sub, male | F2-232CAB-1 + FX-232AW FX-232AWC FX-232AWC-H + FX-422CAB0 | F2-232CAB-1 + FX-232AW FX-232AWC FX-232AWC-H + FX-422CAB or FX-422CAB-150 | FX-232CAB-1 | F2-232CAB-1 | — |
| |  14-pin Half-pitch, female | F2-232CAB-2 + FX-232AW FX-232AWC FX-232AWC-H + FX-422CAB0 | F2-232CAB-2 + FX-232AW FX-232AWC FX-232AWC-H + FX-422CAB or FX-422CAB-150 | FX-232CAB-2 | F2-232CAB-2 | — |
| |  25-pin D-Sub, female | F2-232CAB + FX-232AW FX-232AWC FX-232AWC-H + FX-422CAB0 | F2-232CAB + FX-232AW FX-232AWC FX-232AWC-H + FX-422CAB or FX-422CAB-150 | F2-232CAB-1 | F2-232CAB | — |



4.2 Cable Connection Diagrams

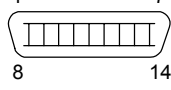
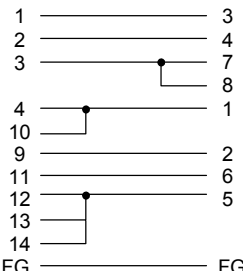
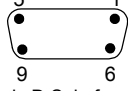
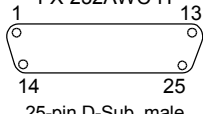
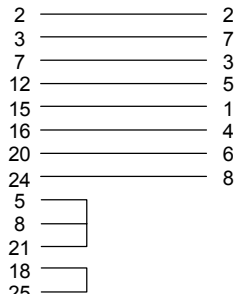
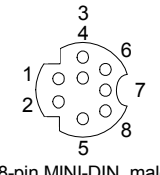
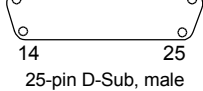
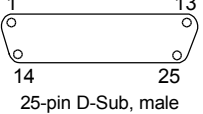
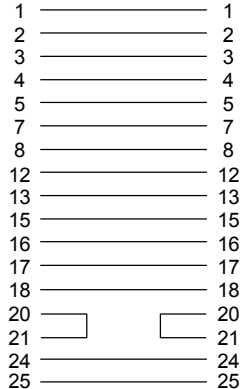
This section explains cable connection diagrams required for connection.

4.2.1 Personal computer connection cable - No. A

 : Female type  : Male type The connector shape indicates the engagement surface.

| No. | Cable model name | Application | Connection diagram | Application |
|-----|--|---|--|--|
| A-1 | F2-232CAB | RS-232C connection Personal computer connector  25-pin D-Sub, male |  | Communication port connector  25-pin D-SUB, male |
| A-2 | Commercial cable* ¹ Reverse (cross) type | RS-232C connection Personal computer connector  9-pin D-Sub, female * ¹ Interlink supporting cables are not applicable. |  | Communication port connector  25-pin D-Sub, male |
| A-3 | F2-232CAB-1 | RS-232C connection Personal computer connector  25-pin D-Sub, male |  | Communication port connector  9-pin D-Sub, female |
| A-4 | F2-232CAB-2 | RS-232C connection Personal computer connector  14-pin Half-pitch |  | Communication port connector  25-pin D-Sub, male |
| A-5 | FX-232CAB-1 | RS-232C connection Personal computer connector  9-pin D-Sub, female |  | Communication port connector  9-pin D-Sub, female |
| A-6 | Commercial cable* ¹ Reverse (cross) type | RS-232C connection Personal computer connector  9-pin D-Sub, female * ¹ Interlink supporting cables are not applicable. |  | Communication port connector  9-pin D-Sub, female |
| A-7 | FX-232CAB-2 | RS-232C connection Personal computer connector  14-pin Half-pitch |  | Communication port connector  9-pin D-Sub, female |

 : Female type
  : Male type
 The connector shape indicates the engagement surface.

| No. | Cable model name | Application | Connection diagram | Application |
|------|--|---|---|--|
| A-8 | <div>RS-232C connection</div> Commercial cable* ¹ Reverse (cross) type | Personal computer connector  14-pin Half-pitch |  | Communication port connector  9-pin D-Sub, female |
| | | * ¹ Interlink supporting cables are not applicable. | | |
| A-9 | <div>RS-422 connection</div> FX-422CAB0 | Converter FX-232AW, FX-232AWC, FX-232AWC-H  25-pin D-Sub, male |  |  8-pin MINI-DIN, male |
| A-10 | <div>RS-422 connection</div> FX-422CAB [0.3 m (0' 11")] FX-422CAB-150 [1.5 m (4' 11")]  25-pin D-Sub, male | Converter FX-232AW, FX-232AWC, FX-232AWC-H  25-pin D-Sub, male |  | |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication
(RS/R52 Instruction)



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Non-Protocol Communication
(FX2N-232IF)

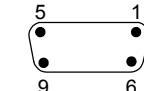
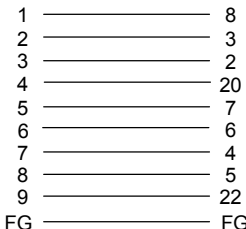
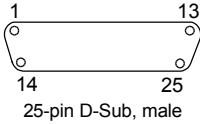
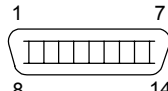
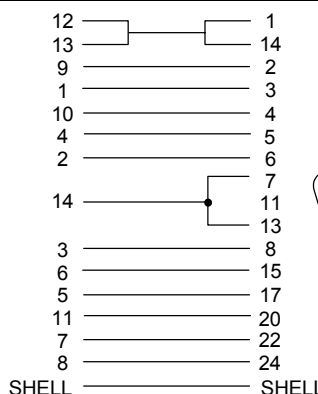
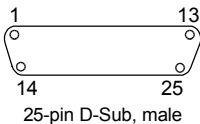
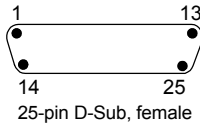
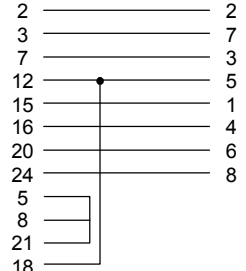
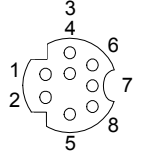
H
Programming Communication

I
Remote Maintenance



Apx.
Discontinued models

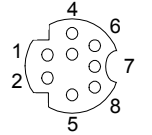
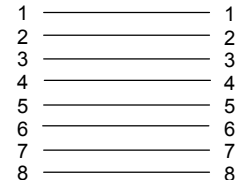
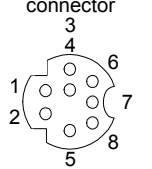
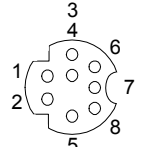
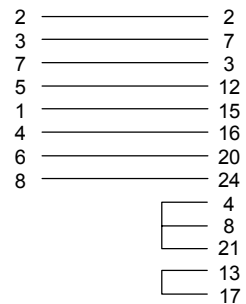
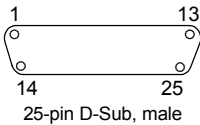
4.2.2 Connector conversion cable (commercial product) - No. B

 : Female type
  : Male type
 The connector shape indicates the engagement surface.

| No. | Cable model name | Application | Connection diagram | Application |
|-----|---|---|--|---|
| B-1 | <div style="border: 1px solid black; padding: 2px; display: inline-block;">RS-232C connection</div> Connector conversion cable (normal type) |  9-pin D-Sub, female |  |  25-pin D-Sub, male |
| B-2 | <div style="border: 1px solid black; padding: 2px; display: inline-block;">RS-232C connection</div> Connector conversion cable (normal type) |  14-pin Half-pitch |  |  25-pin D-Sub, male |
| B-3 | <div style="border: 1px solid black; padding: 2px; display: inline-block;">RS-422 connection</div> FX-20P-CADP |  25-pin D-Sub, female |  |  8-pin MINI-DIN, male |

4.2.3 FX-10P/FX-20P connection cable - No. C

 : Female type
  : Male type
 The connector shape indicates the engagement surface.

| No. | Cable model name | Application | Connection diagram | Application |
|-----|---|---|--|---|
| C-1 | <div style="border: 1px solid black; padding: 2px; display: inline-block;">RS-422 connection</div> FX-20P-CAB0 | Programming tool  8-pin MINI-DIN, male |  | Communication port connector  8-pin MINI-DIN, male |
| C-2 | <div style="border: 1px solid black; padding: 2px; display: inline-block;">RS-422 connection</div> FX-20P-CAB | Programming tool  8-pin MINI-DIN, male |  |  25-pin D-Sub, male |

5. Communication Setting (Initialization) in FX Programmable Controller

This chapter explains the communication setting method for executing programming communication using optional communication equipment operating in accordance with RS-422 or RS-232C.
 The setting described here is not required when the standard built-in port is used.
 When executing programming communication on ch2 in the FX3U/FX3UC PLC, check the contents of D8420 using the procedure described below.

5.1 Check Procedure

1 Monitoring D8120

Turn ON the PLC power while it is in STOP mode, and monitor D8120.

1. **When the value of D8120 is "0"**
 The communication setting is not provided.
2. **When the value of D8120 is any value other than "0"**
 The communication setting is provided.

2 Checking absence/presence of the parameter setting

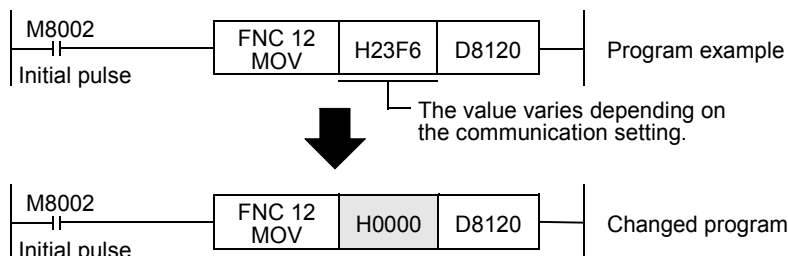
Check absence/presence using GX Developer or FXGP/WIN.

- 1) GX Developer operating procedure (For details, refer to Section 5.2.)
- 2) FXGP/WIN operating procedure (For details, refer to Section 5.3.)

3 Checking absence/presence of sequence program setting

Check whether or not a write instruction is programmed for D8120.

1. **When such an instruction is programmed**
 Program example:
 Change the program as shown below, and then change the PLC mode from STOP to RUN.



2. **When such an instruction is not programmed**
 Proceed to the next step.

4 Monitor D8120 again, and confirming that its value is "0"

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol (RS422 Instruction)

G
Non-Protocol (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

5.2 Communication Setting Using Parameter Method (GX Developer)

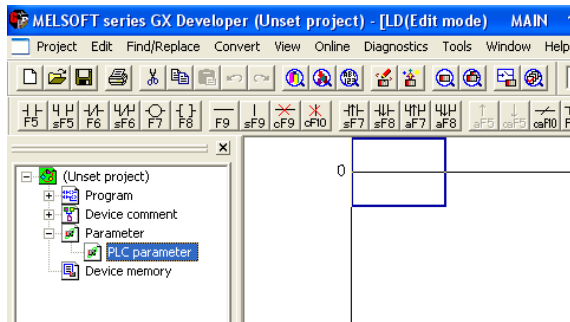
Two software packages, GX Developer and FXGP/WIN for Windows, are applicable to the parameter method. This section explains the parameter method using GX Developer.

5.2.1 Operating procedure

This subsection explains the serial communication setting method. Suppose that GX Developer is already started up.

1 Opening the parameter setting window

Double-click [Parameter]-[PLC parameter] from the project tree.



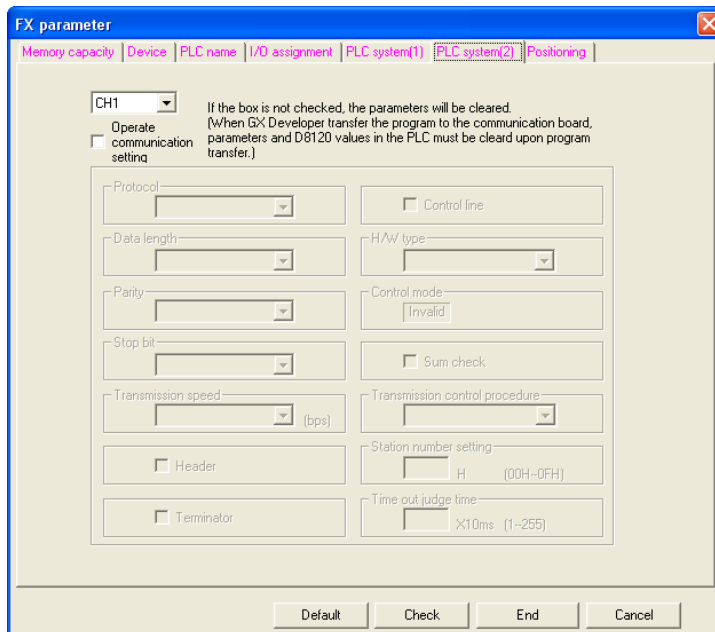
If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Setting the serial communication (parameters)

Click the [PLC system(2)] tab on the dialog box.

Select a channel to be used, and make sure that the "Operate communication setting" box is cleared.

If a check mark is there, clear it.



3 Writing parameters and program to the PLC

Select [Online] - [Write to PLC] from the toolbar, put a check mark (✓) next to "Parameter" and "Program", and then click [Execute].

5.3 Communication Setting Using Parameter Method (FXGP/WIN)

Two software packages, GX Developer and FXGP/WIN for Windows, are applicable to the parameter method. This section explains the parameter method using FXGP/WIN.
Ch 2 cannot be set using FXGP/WIN.

5.3.1 Operating procedure

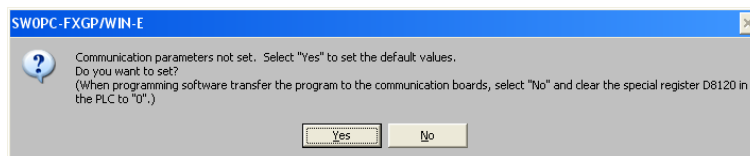
This subsection explains the serial communication setting method. Suppose that FXGP/WIN is already started up.

1 Adjusting serial setting (parameter)

Select [Option] - [Serial setting (parameter)] from the toolbar.
The following dialog box appears according to absence/presence of parameter settings.

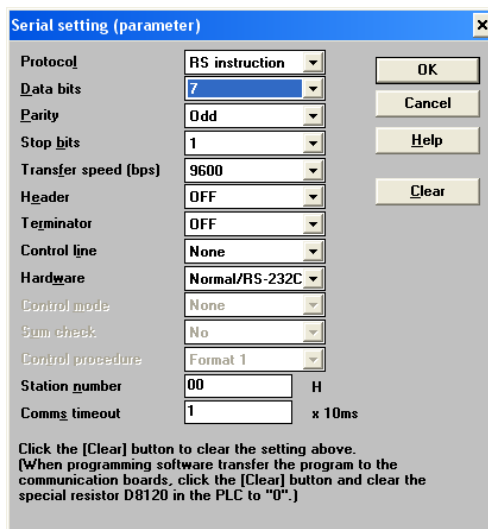
1. When there are no parameter settings

The dialog box shown below appears to indicate that there are no communication settings.
Click the [No] button.
In this case, the next step is not required.



2. When there are already parameter settings

The dialog box shown below appears to indicate that there are communication settings.
Click the [Clear] button to delete the communication settings from parameters.
Transfer parameters to the PLC using the following step.



2 Writing a sequence program (parameters) to the PLC

Select [PLC] - [Transfers] - [Write] from the toolbar, and click [OK].

6. Connection Setting for Personal Computer

This chapter explains the setting method for connecting a personal computer and a PLC. Two software packages, GX Developer and FXGP/WIN for Windows, are applicable. The setting method is different between the two software packages.

6.1 Connection Setting (GX Developer)

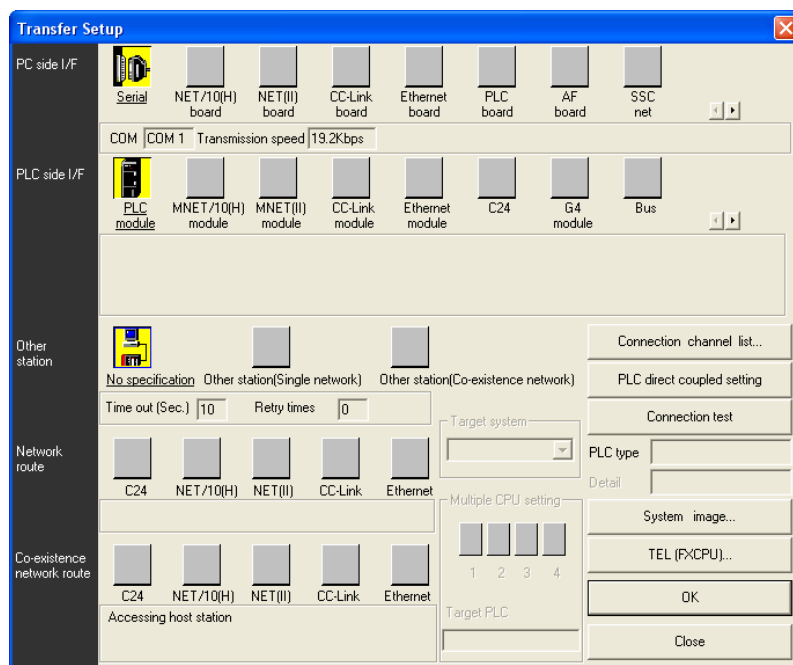
GX Developer, Windows software for personal computers, has the following items to be set. Set each item according to the connection status.

- RS-232C or USB
- Communication port
- Transmission speed
- CPU unit (provided only in FX3U and FX3UC PLCs)
This setting is required to use the transparent function in the GOT-F900 display unit (described later).
- Communication time check
- Number of retries

Each set item can be checked and changed on the connection destination specification window. Display the connection destination specification window using the following procedure.

1 Selecting [Online] - [Transfer Setup] from the toolbar.

The window below appears.




Caution

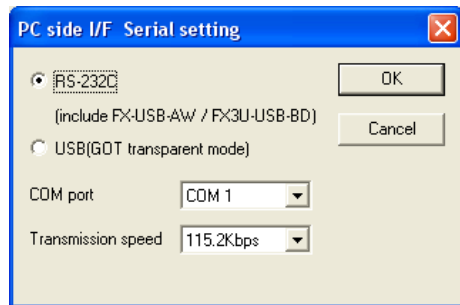
While the monitor function window is displayed, [Transfer Setup] cannot be selected.

6.1.1 Setting RS-232C or USB, communication port, and transmission speed

The setting procedures for RS-232C/USB, communication port and transmission speed are described below:

1 Displaying the "PC side I/F Serial setting" window.

Double-click the "Serial" icon  on the connection destination specification window. The window below appears.



2 Selecting "RS-232C" or "USB"

1. Connection for selecting "RS-232C (include FX-USB-AW/FX3U-USB-BD)"

Connect the PLC to the RS-232C port in the personal computer.

Connect the PLC to the USB port in the personal computer using the FX-USB-AW or FX3U-USB-BD.

2. Connection for selecting "USB" (GOT transparent function)

Connect the PLC to the USB port in the personal computer using the transparent function at the USB port in the GOT1000 Series.

3 Setting the communication port and transmission speed

Set these items according to the connection status.

When "USB" is selected in step 2 above, it is not necessary to set "COM port" and "Transmission speed".

COM port: Select the communication port in the personal computer to be used (among COM1 to COM63).

Transmission speed: Set the communication speed with the FX PLC.

The applicable transmission speed varies depending on each FX PLC. Refer to the table below.

| Communication speed | FX0, FX0S | FX0N | FX1 | FX2(FX), FX2c | FX1S | FX1N, FX1NC | FX2N, FX2NC | FX3U, FX3UC*1 |
|---------------------|-----------|------|-----|---------------|------|-------------|-------------|---------------|
| 9.6 kbps | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| 19.2 kbps | — | — | — | — | — | ✓ | ✓ | ✓ |
| 38.4 kbps | — | — | — | — | — | — | — | ✓ |
| 57.6 kbps | — | — | — | — | — | — | — | ✓ |
| 115.2 kbps | — | — | — | — | — | — | — | ✓ |


*1. For achieving communication at 38.4, 57.6, or 115.2 kbps in an FX3U/FX3UC PLC, the FX-232AWC-H, FX-USB-AW, or FX3U-USB-BD is required.

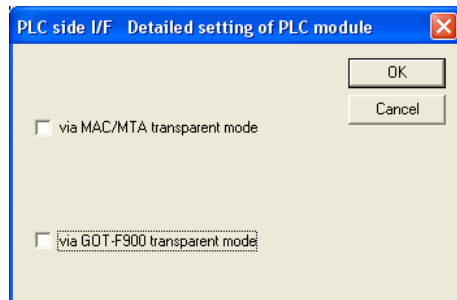
6.1.2 Setting CPU unit (in FX3U and FX3UC)

This setting is required to use the transparent function (two-port interface function) of the GOT-F900 Series in an FX3U/FX3UC PLC.

The setting procedure is described below:

1 Displaying the CPU unit detailed setting window

Double-click the "PLC module" icon  on the connection destination specification window. The window below appears.



2 Setting the CPU unit

Put a check mark next to "via GOT-F900 transparent mode".


Caution

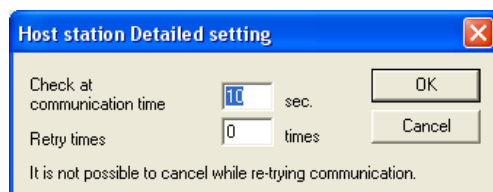
It is not necessary to put a check mark here when not using the transparent function (two-port interface function) of the GOT-F900 Series.

6.1.3 Setting communication time check and number of retries

The setting procedure for the communication time check and number of retries is described below:

1 Displaying the communication time check/number of retries setting window

Double-click the "No specification" icon  on the connection destination specification window. The window below appears.



2 Setting the communication time check and number of retries

Check at communication time: Set the time for evaluating error (1 to 9999 sec). If data from the PLC is not received within this time, it is regarded as error.

Initial value: 10 sec

Retry times: Set the number of retries to be executed when a communication error has occurred (0 to 5).

Initial value: 0

Set the items above if necessary.

6.2 Connection Setting (FXGP/WIN)

FXGP/WIN, Windows software for personal computers, has the following set items. Set each item according to the connection status.

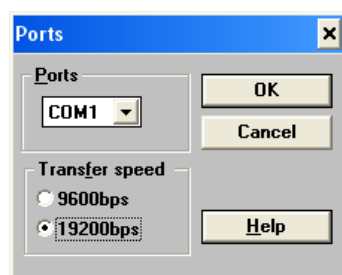
- Communication port
- Transmission speed

6.2.1 Setting communication port and transmission speed

The setting procedure for the communication port and transmission speed is described below:

1 Displaying the communication port/transmission speed setting window

Select [PLC] - [Ports] from the toolbar. The window below appears.



2 Setting the communication port and transmission speed

Set these items according to the connection status.

Ports: Select the communication port in the personal computer to be used (among COM1 to COM9).

Transfer speed: Set the communication speed with the FX PLC.

The applicable transmission speed varies depending on the FX Series. Refer to the table below.

| Communication speed | FX0, FX0S | FX0N | FX1 | FX2(FX), FX2C | FX1S | FX1N, FX1NC | FX2N, FX2NC | FX3U, FX3UC*1 |
|---------------------|-----------|------|-----|------------------|------|----------------|----------------|------------------|
| 9.6 kbps | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ | ✓ |
| 19.2 kbps | — | — | — | — | — | ✓ | ✓ | ✓ |
| 38.4 kbps | — | — | — | — | — | — | — | — |
| 57.6 kbps | — | — | — | — | — | — | — | — |
| 115.2 kbps | — | — | — | — | — | — | — | — |

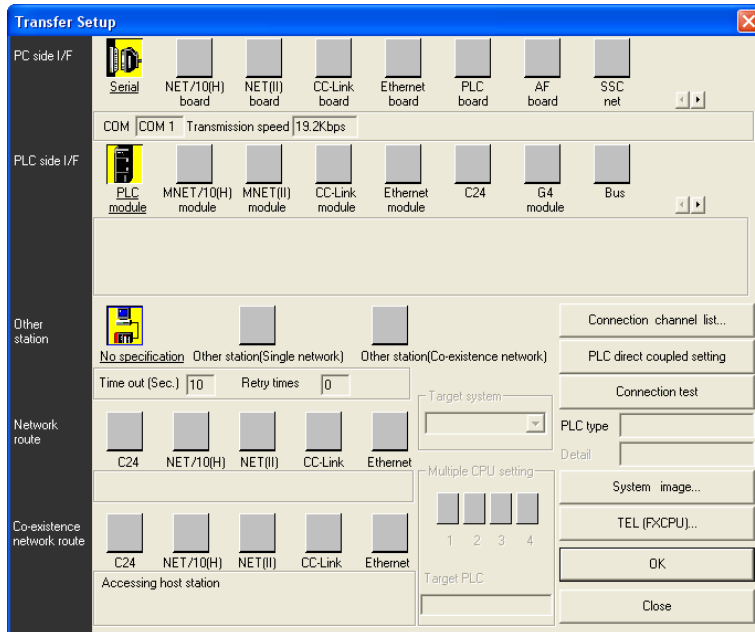
*1. The FX3U/FX3UC Series cannot be selected. Select the FX2N Series, and then create the program.

6.3 Communication Test (Only in GX Developer)

GX Developer, Windows software for personal computers, has a function to test communication with PLC. Execute the communication test using the following procedure:

1 Selecting [Online]-[Transfer Setup] from the toolbar.

The window below appears.

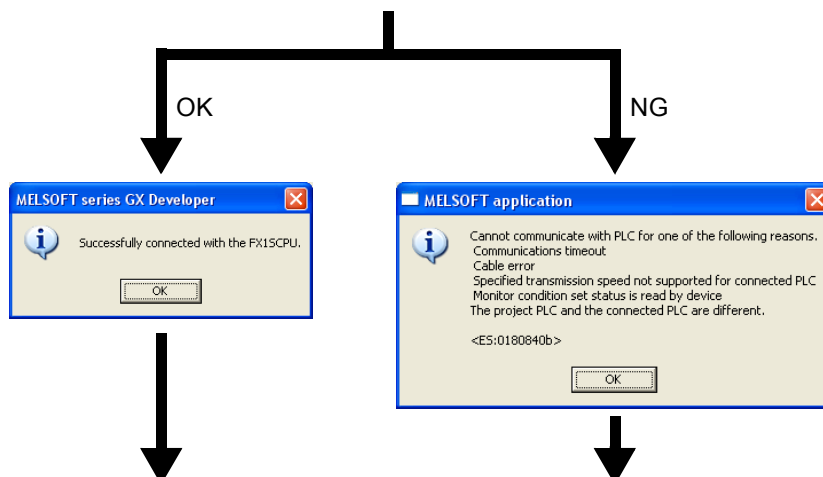


Caution

While the monitor function window is displayed, [Transfer Setup] cannot be selected.

2 Executing the communication test

Click [Connection test] to execute the communication test.



The communication test finished normally

Verify that the connection method is correct:

- Port (COM) number in the personal computer
- Cable configuration

Click [OK].

7. Troubleshooting

This chapter explains troubleshooting.

7.1 Checking PLC Version Applicability

When executing programming communication using an FX PLC and communication equipment operating in accordance with RS-422 or RS-232C, verify that the FX PLC is an applicable version.

→ For the version applicability check, refer to Section 1.3.

7.2 Checking Programming Tool Applicability

Verify that the programming tool version is applicable for programming communication.

→ For the version applicability check, refer to Section 1.4.

7.3 Checking Communication Status Based on LED Indication

Check the status of the "RXD (RD)" and "TXD (SD)" indicator LEDs provided in the optional equipment.

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RXD (RD) | TXD (SD) | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received. |
| Off | Off | Data is not sent nor received. |

7.4 Checking Installation

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ For the mounting method, refer to the respective communication equipment manual.

7.5 Checking Parameters in PLC

1. Checking the communication setting

Verify that non-protocol communication or computer link communication is not set in the parameters of the FX PLC. If such communication is already set, programming communication with optional communication equipment cannot be used.

→ For the setting of parameters in the PLC, refer to Chapter 5.

7.6 Checking Sequence Program

1. Checking the contents of the communication setting

Verify that no communication format (D8120 and D8420, N:N Network: D8173 to D8180, and Parallel Link: M8070 and M8071) is being used in the sequence program.

If any communication format is being used in the sequence program, communication will not function correctly.

2. Presence of VRRD and VRSC instructions (except FX3U and FX3UC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program.

If these instructions are used, delete them, turn OFF the PLC power, and then turn it ON again.

3. Presence of RS instruction (except FX3U and FX3UC PLCs)

Verify that the RS instruction is not used in the program.

If this instruction is used, delete it, turn OFF the PLC power, and then turn it ON again.

4. Presence of RS and RS2 instructions (in FX3U and FX3UC PLCs)

Verify that the RS and RS2 instructions are not being used for the same channel.

If these instructions are used for the same channel, revise them, turn OFF the PLC power, and then turn it ON again.

5. Presence of EXTR instruction (in FX2N and FX2NC PLCs)

Verify that the EXTR instruction is not used in the program.

If this instruction is used, delete it, turn OFF the PLC power, and then turn it ON again.

6. Presence of IVCK, IVDR, IVRD, IVWR, and IVBWR instructions (in FX3U and FX3UC PLCs)

Verify that the IVCK, IVDR, IVRD, IVWR and IVBWR instructions are not being used for the same channel.

If these instructions are used for the same channel, revise them, turn OFF the PLC power, and then turn it ON again.

7.7 Checking Programming Tool Setting

Verify that the setting contents in the programming tool are correct.

1. Checking the communication port

Verify that the communication port is set correctly.

2. Checking the transmission speed

Verify that the transmission speed is set correctly.

→ For the programming tool setting, refer to Chapter 6.

7.8 Checking Absence/Presence of Errors

1. Checking M8062 (except FX3u and FX3uc PLCs)

When a communication error occurs in the standard built-in port, M8062 turns ON and D8062 stores the corresponding error code.

2. Checking the error code (D8062)

D8062 stores either of the following error codes:

| | Error code | Contents of error |
|-------|------------|--|
| D8062 | 6201 | Parity error, overrun error or framing error |
| | 6202 | Defective communication character |
| | 6203 | Communication data sum mismatch |
| | 6204 | Defective data format |
| | 6205 | Defective command |

3. Checking M8063 and M8438

When a communication errors occur in optional communication equipment, M8063 turns ON and D8063 stores the corresponding error code during communication using ch1, and M8438 turns ON and D8438 stores the corresponding error code during communication using ch2.

4. Checking the error code

D8063 and D8438 store either of the following error codes:

| Error code | | Contents of error |
|-------------|-------------|--|
| D8063 (ch1) | D8438 (ch2) | |
| 6301 | 3801 | Parity error, overrun error or framing error |
| 6302 | 3802 | Defective communication character |
| 6303 | 3803 | Communication data sum mismatch |
| 6304 | 3804 | Defective data format |
| 6305 | 3805 | Defective command |
| 6306 | 3806 | Monitoring timeout |
| 6307 | 3807 | Modem initialization error |
| 6308 | 3808 | N:N Network parameter error |
| 6312 | 3812 | Parallel link parameter error |
| 6313 | 3813 | Parallel link sum error |
| 6314 | 3814 | Parallel link format error |
| 6320 | 3820 | Error in communication with inverter |

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

MEMO

FX Series Programmable Controllers

User's Manual [Remote Maintenance]

Foreword

This manual explains "remote maintenance" provided for the MELSEC-F FX Series Programmable Controllers and should be read and understood before attempting to install or use the unit. Store this manual in a safe place so that you can take it out and read it whenever necessary. Always forward it to the end user.

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A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

1. Outline

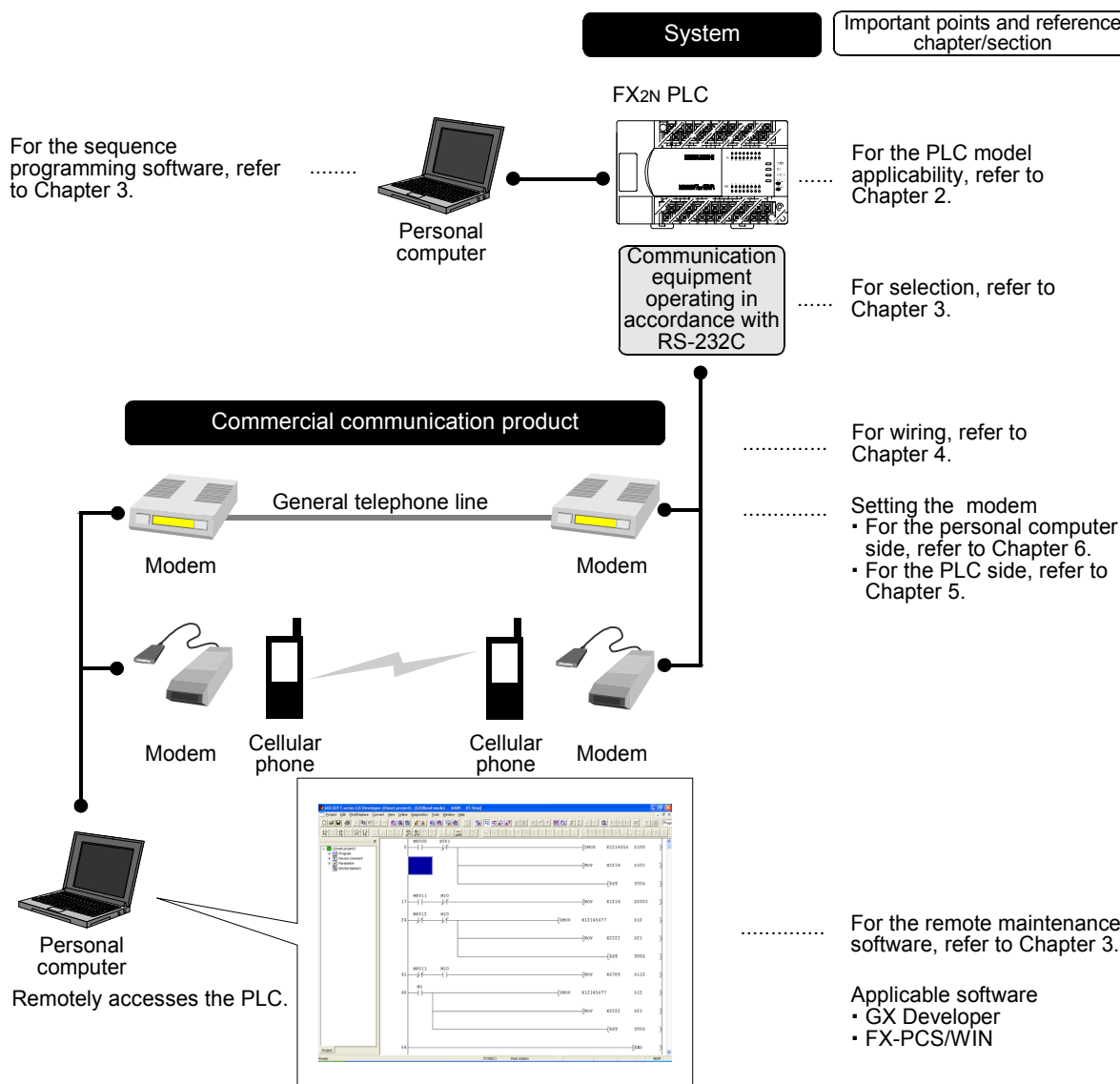
This chapter explains remote maintenance.

1.1 Outline of System

Remote maintenance performs program transfer and device monitoring using Windows programming software with a PLC connected to the telephone line by way of a modem.

1.1.1 Maintenance for programs in PLC

- 1) Sequence programs can be changed by transferring and writing programs during RUN.
- 2) Maintenance can be performed by device monitoring, PLC diagnosis, forced ON/OFF and changing set values and current values.
- 3) A line can be established from a personal computer to a modem connected to a PLC.

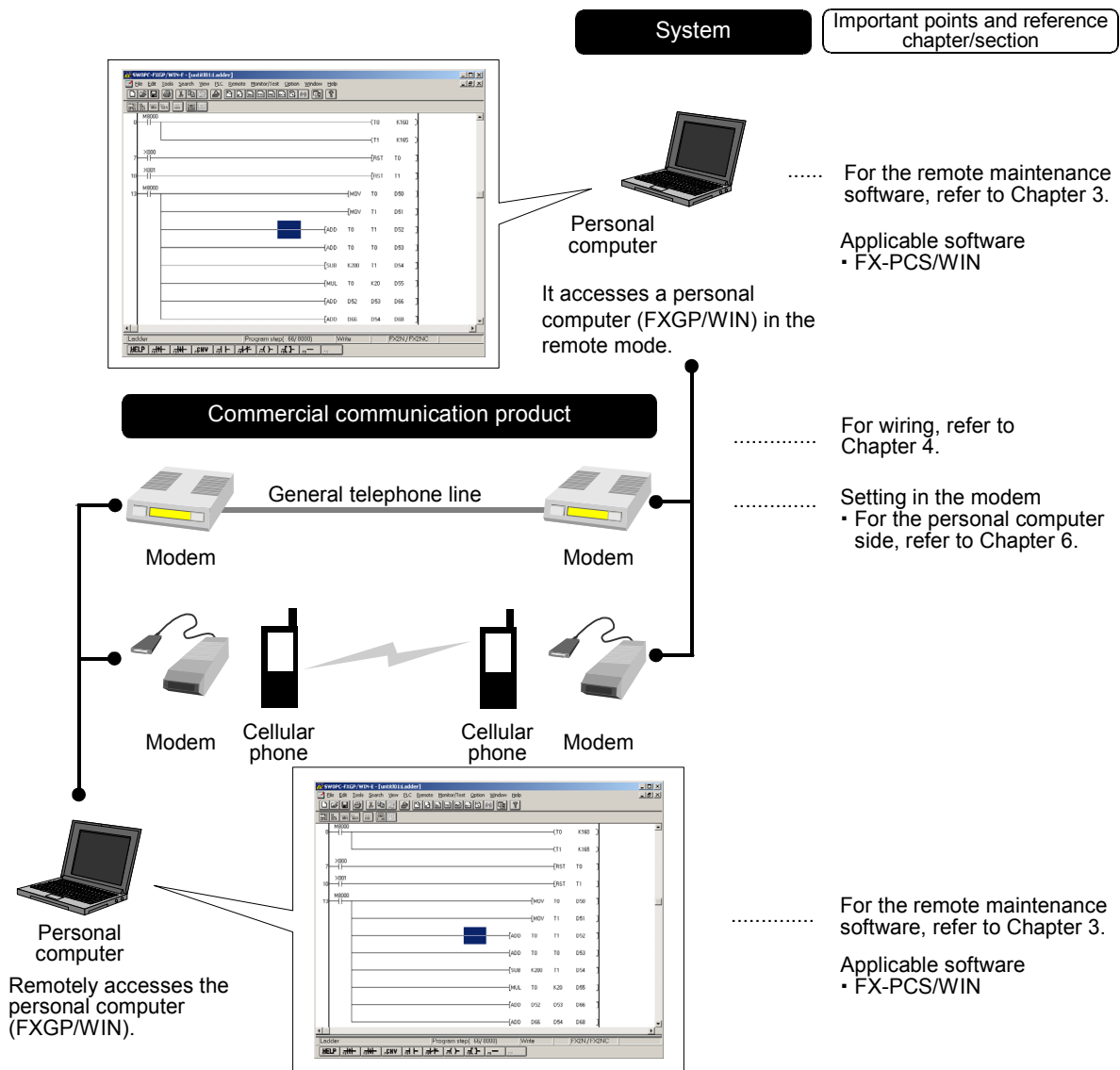


1.1.2 File transfer between personal computers (supported only by FXGP/WIN)

This manual does not describe the operating procedure for this function, but the modem setting contents and setting procedure in personal computers can be used as reference.

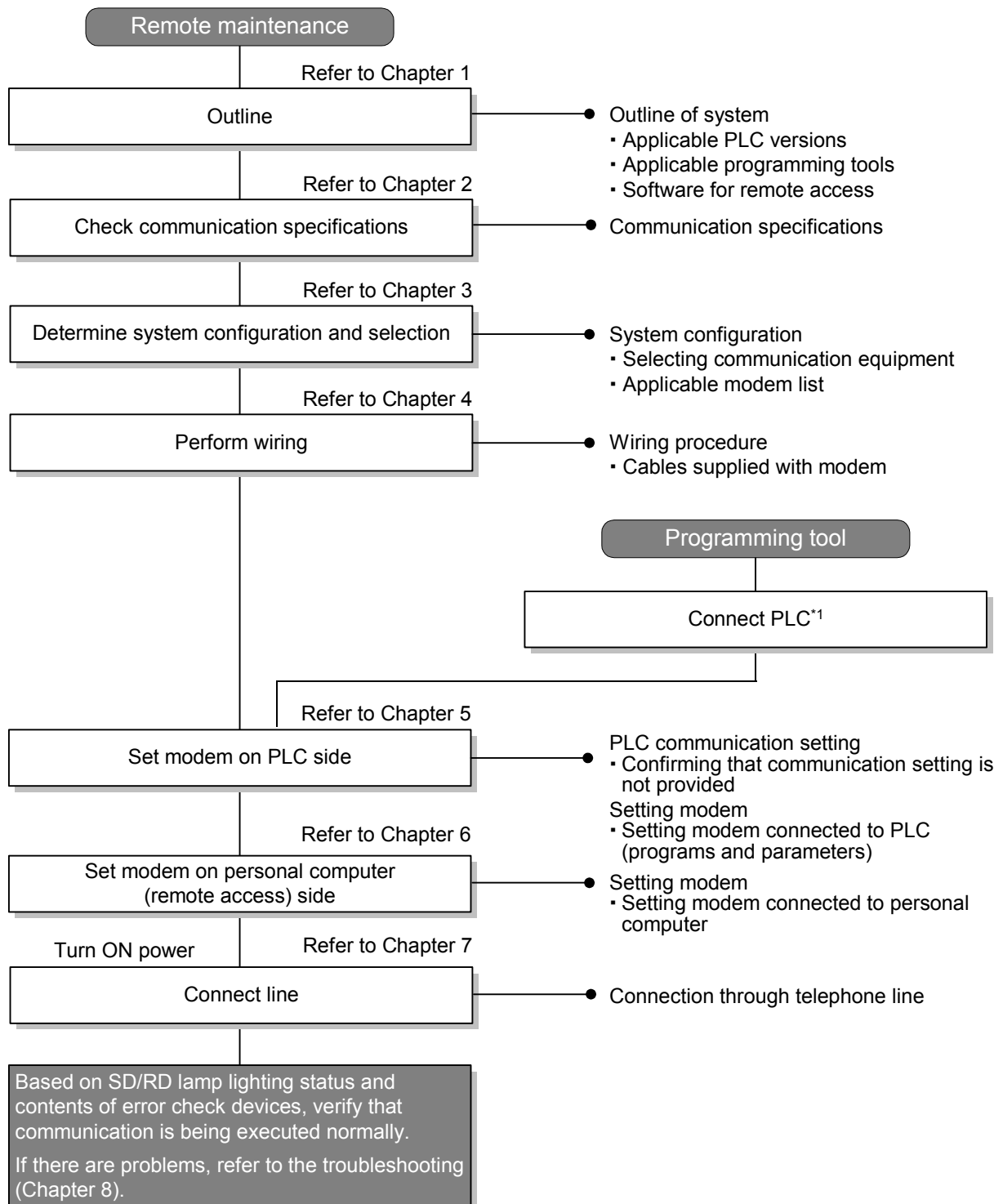
For the detailed explanation of this function, refer to the "FX-PCS/WIN SOFTWARE MANUAL."

1) Transferring sequence program files between personal computers



1.2 Procedures Before Operation

The flow chart below shows the remote maintenance setting procedures up until communication:



*1 For the programming tool to PLC connection procedure, refer to the "Programming Communication" section in this manual or the respective programming tool manual.
For details on operating procedures, refer to the respective programming tool manual.

1.3 Communication Type Applicability in PLC

1.3.1 Applicable versions

The communication types are applicable in the following versions.

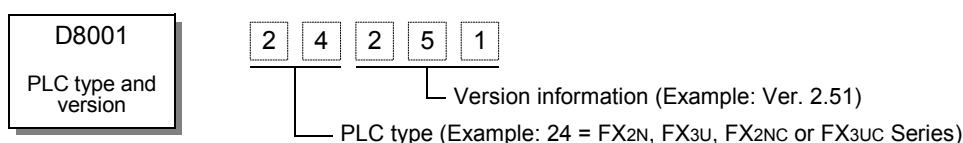
✓: Applicable (If applicable versions are limited, they are described inside ().)

—: Not applicable

| PLC | Applicability (applicable version) | Remarks |
|----------------|------------------------------------|--|
| FX3UC Series | ✓ | |
| FX3U Series | ✓ | |
| FX2NC Series | ✓ | |
| FX2N Series | ✓ | ME3314 (OMRON) is applicable to Ver. 2.01 and later. |
| FX1NC Series | ✓ | |
| FX1N Series | ✓ | |
| FX1S Series | ✓ | |
| FX0N Series | — | This function is not available |
| FX0S Series | — | This function is not available |
| FX0 Series | — | This function is not available |
| FX2C Series | — | This function is not available |
| FX2(FX) Series | — | This function is not available |
| FX1 Series | — | This function is not available |

1. Version check

The D8001(decimal) special data register contains information for determining the PLC version.



1.3.2 Products whose production was stopped

The table below shows FX series whose production (main unit, communication equipment, etc.) was stopped. Use the description of system configuration, etc. in this manual for maintenance.

| PLC | Products whose production was stopped | Remarks |
|----------------|---------------------------------------|---|
| FX0 Series | June 30, 2002 | Maintenance is offered within 7 years from the end of production (until June 30, 2009). |
| FX2C Series | | |
| FX2(FX) Series | | |
| FX1 Series | | |

1.4 Programming Tool Applicability

1.4.1 Programming tool for setting modem connected to PLC

The tables below show programming tools applicable for modem setting using parameters and sequence programs.

→ For programming software on remote maintenance, refer to Subsection 1.4.2

For applicable versions

The programming tool is applicable for each FX Series from the version shown:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)

—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|---------------------------------------|---------------------------------------|------------------------------------|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.10 or later) | |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 5.00 or later) | |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)

—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|----------------------------------|---------------------------------------|------------------------------------|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX1S, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |

In the case of non-applicable versions (setting an alternative model)

Even software not applicable to a PLC can create programs when an alternative model is set.

In this case, however, programming is enabled only in the ranges provided for the alternative PLC model such as instructions and program size.

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name | Applicability (applicable version) | Remarks |
|--|---------------------------------------|--|
| FX1s, FX1N, FX3U, FX1NC and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | For FX3U and FX3UC PLC The models "FX3U" and "FX3UC" cannot be selected. |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.10 or later) | "FX2N" can be selected and set as the alternative model. The PP modem mode (ch1) and PP modem mode (ch2) cannot be set. |
| FX-PCS-KIT/98 SW1PC-FXGP/98(-3,-5) | ✓ (Ver. 4.00 or later) | For FX1N and FX1NC PLC |
| FX-PCS/98-3 SW1PC-FXGP/98-3 | ✓ (Ver. 4.00 or later) | The models "FX1N" and "FX1NC" cannot be selected. "FX2N" or "FX2NC" can be selected and set as the alternative model. |
| FX-PCS-KIT/V-3 SW1-PC-FXGP/V3 | ✓ (Ver. 2.00 or later) | For FX1s PLC |
| FX-A7PHP-KIT SW1RX-GPPFX | ✓ (Ver. 3.00 or later) | The versions on the left are not applicable. The versions shown in the table above are applicable. |
| FX2N and FX2NC PLCs | | |
| The versions applicable to FX2N and FX2NC PLCs shown in the table above can be used. | | |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name | Applicability (applicable version) | Remarks |
|--|---------------------------------------|---|
| FX1s, FX1N, FX3U, FX1NC and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | For FX3U and FX3UC PLC The models "FX3U" and "FX3UC" cannot be selected. "FX2N" can be selected and set as the alternative model. The PP modem mode (ch1) and PP modem mode (ch2) cannot be set. |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | For FX1N and FX1NC PLC The models "FX1N" and "FX1NC" cannot be selected. "FX2N" or "FX2NC" can be selected and set as the alternative model. For FX1s PLC The versions on the left are not applicable. The versions shown in the table above are applicable. |
| FX2N and FX2NC PLCs | | |
| The versions applicable to FX2N and FX2NC PLCs shown in the table above can be used. | | |

Other programming tools not shown above are not applicable.

1.4.2 Programming software for remote maintenance

The table below shows programming software for the personal computer which uses remote access.

→ For the applicability of programming tools for setting the modem, refer to Subsection 1.4.1.

In the case of applicable versions

The programming software is applicable from the following versions:

1. Japanese versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|----------------------------------|---------------------------------------|---|
| FX3U and FX3UC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" When connecting the programming software to a PLC in which the PP modem mode (ch1) or PP modem mode (ch2) is set, use Ver. 8.18U or later. |
| FX2N and FX2NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 2.10 or later) | |
| FX1s, FX1N and FX1NC PLCs | | |
| GX Developer SW□D5C(F)-GPPW-J | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN SW0PC-FXGP/WIN | ✓ (Ver. 4.00 or later) | |

2. English versions

✓: Applicable (If applicable versions are limited, they are described inside ().)
—: Not applicable

| Model name (Software name) | Applicability (applicable version) | Remarks |
|----------------------------------|---------------------------------------|---|
| FX3U and FX3uc PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW8 P or later) Ver. 8.13P | Select the model "FX3U/FX3UC" When connecting the programming software to a PLC in which the PP modem mode (ch1) or PP modem mode (ch2) is set, use Ver. 8.18U or later. |
| FX2N and FX2nc PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW2 A or later) | Select the model "FX2N/FX2NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 1.00 or later) | |
| FX1s, FX1N and FX1nc PLCs | | |
| GX Developer SW□D5C(F)-GPPW-E | ✓ (Ver. SW5 A or later) | Select the model "FX1S/FX1N/FX1NC" |
| FX-PCS/WIN-E SW0PC-FXGP/WIN-E | ✓ (Ver. 3.00 or later) | |

3. In the case of non-applicable versions

A non-applicable programming software version cannot offer remote maintenance.

If your programming software is a non-applicable version, upgrade versions.

To upgrade versions, contact your dealer.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RSRS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

1.4.3 Cautions on using FXGP/WIN

1. When FXGP/WIN is used in the following Windows environment, remote maintenance cannot be used:

- Windows NT4.0
- Windows 2000
- Windows XP

2. For FX3U and FX3UC Series

The models "FX3U" and "FX3UC" cannot be selected.

"FX2N" can be selected and set as the alternative model.

However, FXGP/WIN cannot be connected to a PLC in which the PP modem mode is set.

2. Specifications

This chapter explains the communication specifications and performance.

2.1 Communication Specifications (Reference)

Communication is executed according to the (fixed) specifications shown in the table below. Specification items such as baud rate cannot be changed.
Only modems supporting the communication specifications below can be used.

| Item | Modem mode | | Remarks | |
|----------------------------------|----------------------------------|-------|---|--------------|
| Transmission standard | RS-232C standard | | | |
| Maximum total extension distance | 15 m (49' 2") or less | | | |
| Protocol type | Modem mode | | | |
| Communication method | Half-duplex, asynchronous system | | | |
| Baud rate | 9600 bps | | Modem ↔ PLC Modem ↔ Personal computer | |
| Character format | 1-bit | | When PP modem mode (ch1) or PP modem mode (ch2) is set, "Data bit: 8-bit" and "Parity bit: Not provided" are set automatically. | |
| | | | | Start bit |
| | Data bit | 7-bit | | 8-bit |
| | Parity bit | Even | | Not provided |
| | Stop bit | 1-bit | | |
| Header | Fixed | | | |
| Terminator | | | | |
| Control line | Not provided | | | |
| Sum check | Fixed | | | |
| Applicable FX Series | | | | |
| FX3UC Series | ✓ | ✓ | | |
| FX3U Series | ✓ | ✓ | | |
| FX2NC Series | ✓ | — | | |
| FX2N Series | ✓ | — | | |
| FX1NC Series | ✓ | — | | |
| FX1N Series | ✓ | — | | |
| FX1S Series | ✓ | — | | |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS/R2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

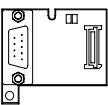
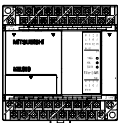
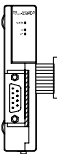
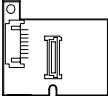

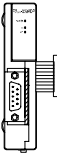
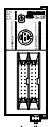
3. System Configuration and Selection

This chapter explains the configuration of communication equipment operating in accordance with RS-232C and selection of the system required by FX PLCs.

3.1 System Configuration

This section outlines the system configuration required to use remote maintenance.
Connect (optional) equipment operating in accordance with RS-232C to the FX PLC main unit.

1, **2** and **3** indicate the communication equipment combination patterns.

| Communication equipment operating in accordance with RS-232C | FX PLC | Important point in selection | Total extension distance |
|--|--|---|--------------------------|
| 1  Communication board | + |  This is the communication board built into the PLC, reducing the installation area. | 15 m (49' 2") |
| 2  Communication adapter | +  Connector conversion board |  Attach the connector conversion board to the main unit, and then attach the communication adapter to the left side of the main unit. | 15 m (49' 2") |
| 3  Communication adapter | + |  Attach the communication adapter to the left side of the main unit. | 15 m (49' 2") |


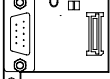
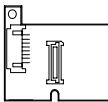
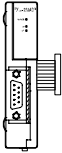
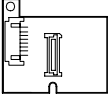
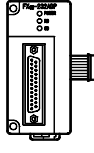
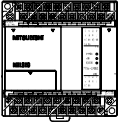
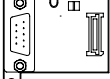
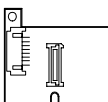
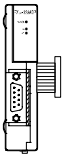
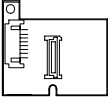
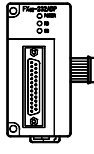
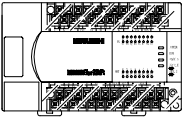
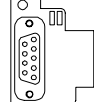
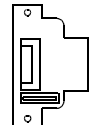
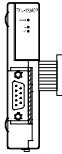
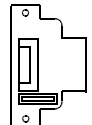
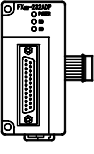
The total extension distance should conform to the modem specifications in both cases in which a cable supplied with the modem is used and which another prepared cable is used.

For communication equipment combinations for each FX Series, refer to the next page.

3.2 Setting Applicable FX PLC and Communication Equipment

Select a communication equipment combination, and put a check mark in the "Check" column.
During selection, pay attention to the following:

- In the table below, only the outside dimensions and D-SUB connector shape are different between units shown in "FX2NC-232ADP/FX0N-232ADP". Select either one.
- Remote maintenance is not provided for the FX0, FX0S, FX0N, FX1, FX2(FX) and FX2C Series.

| FX Series | Communication equipment (option) | Total extension distance | Check |
|---|---|--------------------------|-------|
|  FX1S |  FX1N-232-BD (9-pin D-Sub) | 15 m (49' 2") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-232ADP (9-pin D-Sub) FX1N-CNV-BD FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |
|  FX1N |  FX1N-232-BD (9-pin D-Sub) | 15 m (49' 2") | |
| |  +  /  +  FX1N-CNV-BD FX2NC-232ADP (9-pin D-Sub) FX1N-CNV-BD FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |
|  FX2N |  FX2N-232-BD (9-pin D-Sub) | 15 m (49' 2") | |
| |  +  /  +  FX2N-CNV-BD FX2NC-232ADP (9-pin D-Sub) FX2N-CNV-BD FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

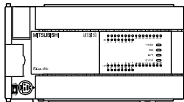
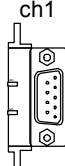



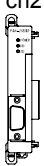


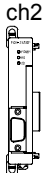
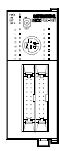
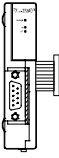
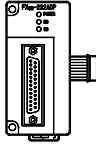
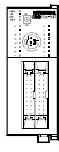
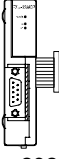
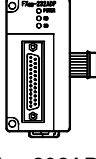
F
Non-Protocol Communication (RS/RSS2 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

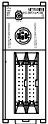

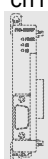

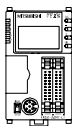





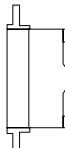


H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|---|--------------------------|-------|
|  FX3U | When using channel 1 (ch 1) | | |
| |  ch1 FX3U-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  ch1 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2)*1 | | |
| |  ch1 FX3U-□-BD (Where □ represents 232, 422, 485 and USB) +  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  ch1 FX3U-□ADP(-MB) (Where □ represents 232 and 485) +  ch2 FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX1NC |  FX2NC-232ADP (9-pin D-Sub) /  FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |
|  FX2NC |  FX2NC-232ADP (9-pin D-Sub) /  FX0N-232ADP (25-pin D-Sub) | 15 m (49' 2") | |

*1. When using ch2 in an FX3U PLC, it can be set only in the PP modem mode (ch2).

| FX Series | Communication equipment (option) | Total extension distance | Check |
|--|---|--------------------------|-------|
|  FX3UC (D, DSS) | When using channel 1 (ch 1) | | |
| |  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2)*¹ | | |
| |  FX3U-□ADP(-MB) (Where □ represents 232 and 485) +  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
|  FX3UC-32MT-LT | When using channel 1 (ch 1) | | |
| |  FX3U-232-BD (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  FX3U-232ADP (9-pin D-Sub, male) | 15 m (49' 2") | |
| | When using channel 2 (ch 2)*¹ | | |
| |  FX3U-□-BD (Where □ represents 232, 422, 485 and USB) +  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |
| |  FX3U-CNV-BD +  FX3U-□ADP(-MB) (Where □ represents 232 and 485) +  FX3U-232ADP(-MB) (9-pin D-Sub, male) | 15 m (49' 2") | |

*1. When using ch2 in an FX3UC PLC, it can be set only in the PP modem mode (ch2).

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

3.3 Selecting Modem

In FX PLCs, the modems PV-AF288 (manufactured by AIWA) and ME3314B (manufactured by OMRON) are applicable.

When "user registration mode," "PP modem mode (ch1)," or "PP modem mode (ch2)" is selected in the modem initialization setting in an FX PLC, other modems are also applicable.

The tables below show the communication specifications in the "user registration mode," "PP modem mode (ch1)," and "PP modem mode (ch2)." Select a modem supporting the communication specifications shown below.

1. User registration mode

| Item | Contents |
|----------------------|----------------------------------|
| Communication method | Half-duplex, asynchronous system |
| Baud rate | 9600 bps |
| Start bit | 1-bit |
| Data bit | 7-bit |
| Parity bit | Even |
| Stop bit | 1-bit |
| Control line | Not provided |

If the modem used does not support the communication specifications shown above, communication is not possible.

2. PP modem mode (ch1) and PP modem mode (ch2)

| Item | Contents |
|----------------------|----------------------------------|
| Communication method | Half-duplex, asynchronous system |
| Baud rate | 9600 bps |
| Start bit | 1-bit |
| Data bit | 8-bit |
| Parity bit | Not provided |
| Stop bit | 1-bit |
| Control line | Not provided |

If the modem used does not support the communication specifications shown above, communication is not possible.

3.3.1 List of modems whose operations are confirmed

The tables below show already tested modems and their associated AT command.

1. Modem on the PLC side

The PLC has a command to initialize the PV-AF288 (manufactured by AIWA) and ME3314B (manufactured by OMRON). This command can be used only by setting parameters using the GX Developer or FXGP/WIN software.

For other modems, input and set the AT command shown below in ASCII code to a data register (D1000 and later usually, and D200 or later in the FX1S PLC).

→ For the setting procedure, refer to Chapter 5.

| Manufacturer | AT command setting for modem on PLC side | | AT command | Remarks |
|----------------------------|--|------------------------------|------------|---|
| Modem model name | GX Developer (SW□D5C-GPPW) | FX-PCS/WIN | | |
| Manufactured by I/O DATA | | | | |
| DFML-K56F | Input AT command shown on right | ATE0Q1S0=2&D0&K0&W0&Y0\Q0%C3 | | |
| Manufactured by AIWA | | | | |
| PV-AF288 | Select AIWA modem (PV-AF288) | ATE0S0=2Q1&D0&M5\Q0\J0&W | | |
| PV-BF5606 | Input AT command shown on right | ATE0S0=2&D0Q1&K0&W | | |
| Manufactured by OMRON | | | | |
| ME3314B | Select OMRON modem (ME3314B) | ATE0S0=2Q1&D0&H0&R1S15=8&W | | In FX2N PLCs, Ver. 2.01 and later are applicable. |
| ME5614E | Input AT command shown on right | ATE0S0=2&D0Q1&K0&W | | Modem version: F/W Ver. 2.300 |
| ME5614E2 | | | | |
| ME5614D | Input AT command shown on right | ATE0S0=2&D0Q1&K0&W | | Modem version: F/W Ver. 2.300 |
| Manufactured by NTT DoCoMo | | | | |
| 96F1 | Input AT command shown on right | ATE0S0=2&D0\Q1 | | |
| 96F2 | Input AT command shown on right | ATE0S0=2&D0\Q1Q1 | | |

2. Modem on the personal computer side for remote access

The table below shows modems whose operations are already confirmed. Input and set the AT command shown below using a programming tool in the personal computer on the remote access side.

FXGP/WIN has a command to initialize the PV-AF288, PV-AF3360 (manufactured by AIWA), ME3314B, ME5614D and ME5614E (manufactured by OMRON). This command can be used only by setting a parameter.

→ For the setting procedure, refer to Chapter 6.

| Manufacturer | AT command setting for modem on personal computer side for remote access | | Remarks |
|----------------------------|--|--|-----------------------------------|
| Modem model name | GX Developer (SW□D5C-GPPW) | FX-PCS/WIN | |
| Manufactured by AIWA | | | |
| PV-AF288 | — | Select this model (AT command is shown for reference) ATE0S0=2Q0V1&M4\J0\Q0 | |
| PV-AF3360 | — | Select this model (AT command is shown for reference) ATE0S0=2Q0V1S15=8&H0&R1 | |
| PV-BF5606 | ATE0S0=2&K0&D0 | Select this model (AT command is shown for reference) ATE0S0=2&K0 | |
| Manufactured by OMRON | | | |
| ME3314B | — | Select this model (AT command is shown for reference) ATE0S0=2Q0V1S15=8&H0&R1 | |
| ME5614E | ATE0S0=2&K0&D0 | Select this model (AT command is shown for reference) ATE0S0=2&K0W0 | Modem version: F/W Ver. 2.300 |
| ME5614E2*1 | | | |
| ME5614D | ATE0S0=2&K0&D0 | Select this model (AT command is shown for reference) ATE0S0=2&K0W0 | Modem version: F/W Ver. 2.300 |
| Manufactured by NTT DoCoMo | | | |
| 96F1 | ATQ0V1E1S0=0 | ATQ0V1E1S0=0 | SW□D5C-GPPW version: before SW3 |
| 96F2 | ATQ0V1E1 | ATQ0V1E1 | SW□D5C-GPPW version: before SW3 |
| | ATQ0V1E1\Q1 | | SW□D5C-GPPW version: SW4 or later |

*1. When used the FXGP/WIN, select the model "ME5614E".

4. Wiring

This chapter explains the wiring.

4.1 Wiring Procedure

1 Turning OFF the PLC power

Before starting any wiring work, make sure that the PLC power is OFF.

2 Checking the connector shape

When a cable is included with the modem, check the shape of the RS-232C connector in the personal computer to be connected, the shape of the connector in the communication equipment operating in accordance with RS-232C for the PLC, and male or female type.

3 Connecting the RS-232C ports in the modem and the PLC with a cable

Check the shape of the connector (number of pins) in the communication equipment operating in accordance with RS-232C to be connected to the PLC. Each cable has either connector shape:

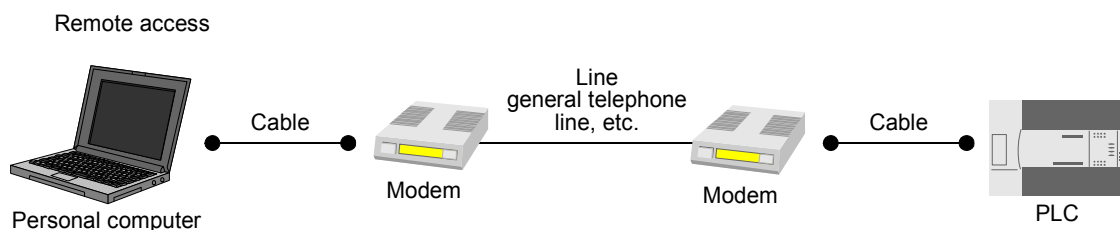
- 9-pin D-Sub, female
- 25-pin D-Sub, male

4 Connecting the personal computer and the modem with a cable for remote access

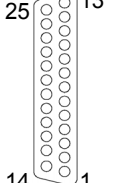

Check the shape of the RS-232C connector (number of pins) on the personal computer for remote access.

4.2 Connection Diagram

1. To connect the modem, use a cable included with the modem or cable described in the modem manual.



2. The table below shows the pin arrangement in the communication equipment operating in accordance with RS-232C for the FX PLC.

| FX0N-232ADP | | FX1N-232-BD, FX2N-232-BD, FX2NC-232ADP, FX3U-232-BD, FX3U-232ADP(-MB) | | Signal name | Function |
|---|----|---|-----|-------------|-----------------------------|
| 25-pin D-Sub, female | | 9-pin D-Sub, male | | | |
|  | — |  | 1*1 | CD | Receiving carrier detection |
| | 3 | | 2 | RD (RXD) | Receive data input |
| | 2 | | 3 | SD (TXD) | Send data output |
| | 20 | | 4 | ER (DTR) | Data terminal ready |
| | 7 | | 5 | SG (GND) | Signal ground |
| | 6 | | 6 | DR (DSR) | Data set ready |

*1. The FX2NC-232ADP does not use the CD signal.

5. How to Setup Modems on the PLC Side

This chapter explains how to set parameters for initialization using the AT command and set the communication specifications including the transmission speed for a modem connected to the PLC. The setting method using GX Developer and the setting method using FXGP/WIN are explained.

→ For applicable programming tools, refer to Subsection 1.4.2.

5.1 Setting Using GX Developer

This section explains the modem initialization setting and communication setting methods. Suppose that GX Developer is already started up.

5.1.1 Setting communication by way of RS-232C port

It is not necessary to set the serial communication with a modem.

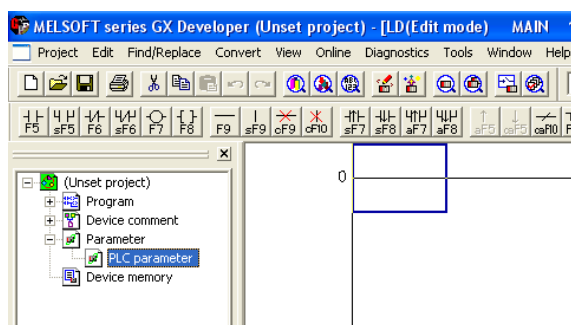
However, it is necessary to verify that another communication type is not used and whether the communication setting is correct using the following procedure.

In FX PLCs, the communication setting can be executed using either of the following two methods:

- 1) Writing the value "0" to the data register D8120 using a sequence program
If another communication type is already set for another application, delete the sequence program which writes a value to D8120.
When setting remote maintenance to ch2 in an FX3U/FX3UC PLC, write the value "0" to the data register D8420.
- 2) Setting parameters using a sequence programming tool
By using the following procedure, verify that another communication type is not set.

1 Opening the PLC parameter setting window

Double-click [Parameter]-[PLC parameter] from the project tree.



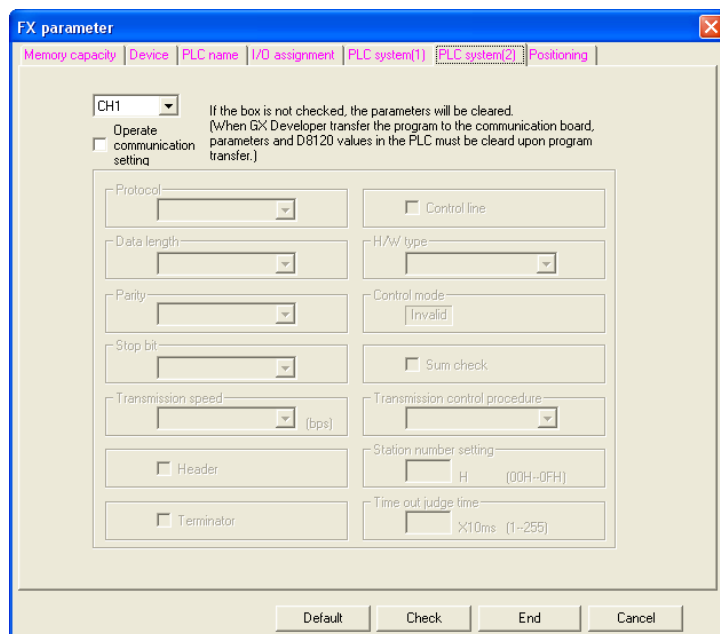
If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Checking the serial communication (parameter) setting

Click the [PLC system(2)] tab on the dialog box.

Make sure that the "Operate communication setting" box is cleared, and click the [End] button.

If a check mark is there, clear it, and then click the [End] button.



The image shows the 'FX parameter' dialog box with the 'PLC system(2)' tab selected. The 'Operate communication setting' checkbox is unchecked. The dialog contains various communication parameters:

- CH1** (dropdown menu)
- Operate communication setting** (checkbox, unchecked)
- Protocol** (dropdown menu)
- Data length** (dropdown menu)
- Parity** (dropdown menu)
- Stop bit** (dropdown menu)
- Transmission speed** (dropdown menu, units in bps)
- Header** (checkbox, unchecked)
- Terminator** (checkbox, unchecked)
- Control line** (checkbox, unchecked)
- H/W type** (dropdown menu)
- Control mode** (dropdown menu, set to 'Invalid')
- Sum check** (checkbox, unchecked)
- Transmission control procedure** (dropdown menu)
- Station number setting** (dropdown menu, set to 'H (00H-0FH)')
- Time out judge time** (dropdown menu, set to 'X10ms (1-255)')

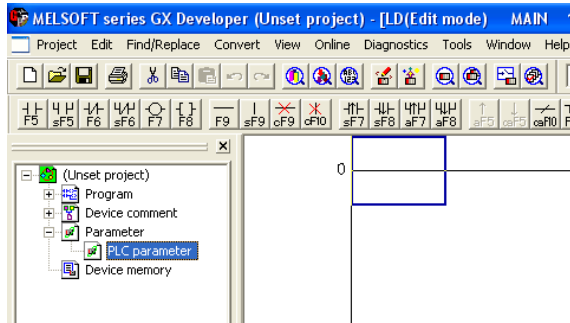
At the bottom of the dialog are four buttons: **Default**, **Check**, **End**, and **Cancel**.

5.1.2 Modem initialization setting using parameter method

This subsection explains how to select the AT command for initialization registered in the PLC and how to set the AT command for an unregistered modem.

1 Opening the PLC parameter setting window

Double-click [Parameter] - [PLC parameter] from the project tree.

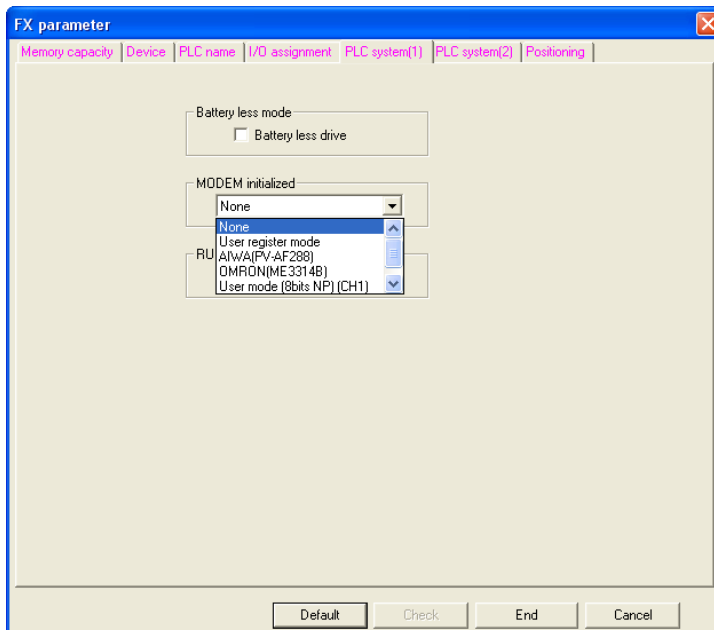


If the project tree is not displayed, select [View] - [Project data list] from the toolbar.

2 Selecting the modem initialization method

Click the [PLC system(1)] tab on the dialog box.

Select a modem to be connected in "MODEM initialized," and click the [End] button.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/R2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

| Set item | Description | Modem model name | Manufacturer |
|------------------------------|---|--------------------|--------------|
| None | Select this item when remote maintenance is not used. | — | — |
| User register mode | Select this item when the modem to be used is not registered. | Unregistered modem | — |
| AIWA(PV-AF288) | Select the corresponding item when either modem is to be used. | PV-AF288 | AIWA |
| OMRON(ME3314B) | | ME3314B | OMRON |
| User mode (8bits NP) (CH1)*1 | Select this item when the modem to be used satisfying the PP modem mode specifications is not registered. | Unregistered modem | — |
| User mode (8bits NP) (CH2)*1 | Select this item when remote maintenance is executed in ch2. | Unregistered modem | — |

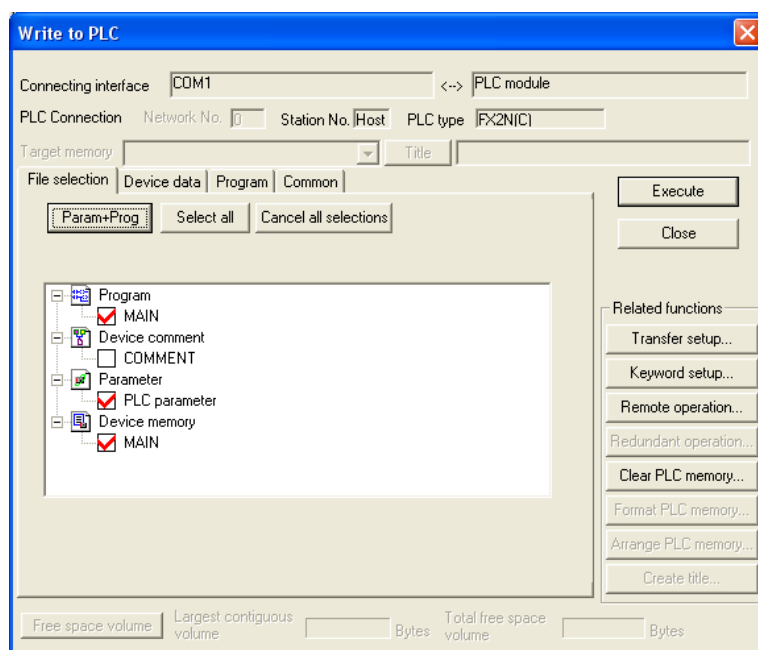
*1. When an FX3U/FX3UC PLC is used

3 Setting the AT command for the unregistered modem

When "User register mode," "User mode (8bits NP) (CH1)," or "User mode (8bits NP) (CH2)" is selected in "MODEM initialized", the AT command setting is required. For the AT command setting method for unregistered modems, refer to Subsection 5.1.3.
The AT command setting is not required when "AIWA[PV-AF288]" or "OMRON(ME3314B)" is selected.

4 Writing the parameter and program to the PLC

Select [Online]-[Write to PLC] from the toolbar.
Click [Parameter]-[PLC parameter] in the tree.
When the AT command is set for an unregistered modem, next put a check mark next to "Device memory"-"MAIN."
After placing the check mark, click the [Execute] button to write the contents to the FX PLC.



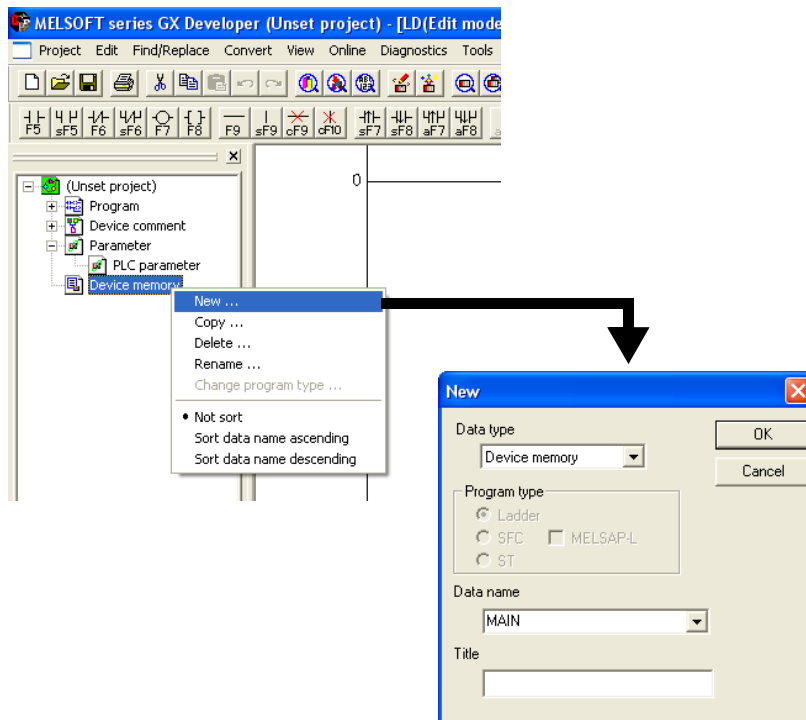
5.1.3 Setting AT command for unregistered modem

Only when "MODEM initialized" is set to "User register mode," "User mode [8bits NP][CH1]," or "User mode [8bits NP][CH2]," execute the following setting.

(The modem initialization setting depends on the setting contents of the [PLC system(1)] tab displayed when [Parameter] - [PLC parameter] is selected in the project tree.)

1 Newly adding a device memory

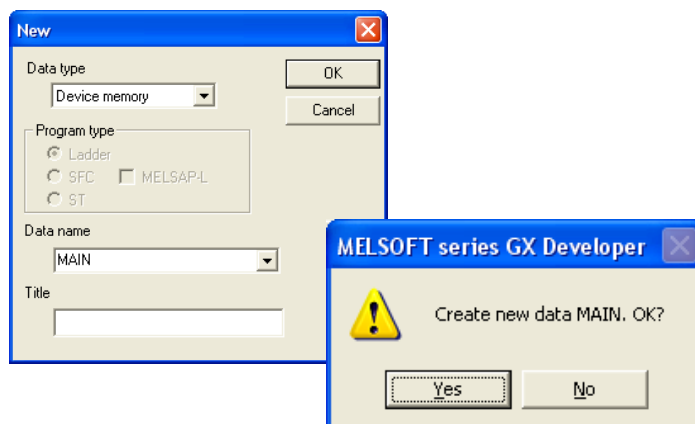
Select "Device memory" in the project tree, right-click it to display the submenu, and select "New...".



Click the [OK] button on the "New" dialog box.

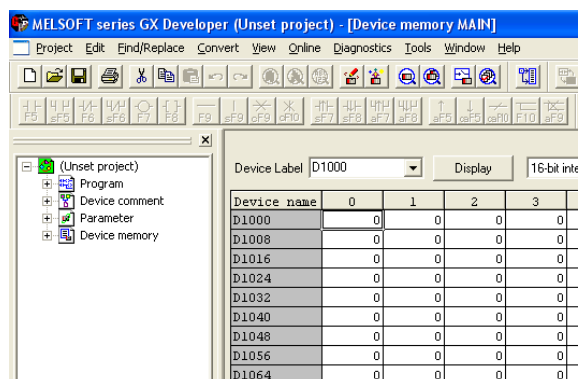
2 Creating the MAIN data

Click the [Yes] button.



3 Displaying the device list

Input the head number of devices used to set the AT command to "Device Label," and click the [Display] button.

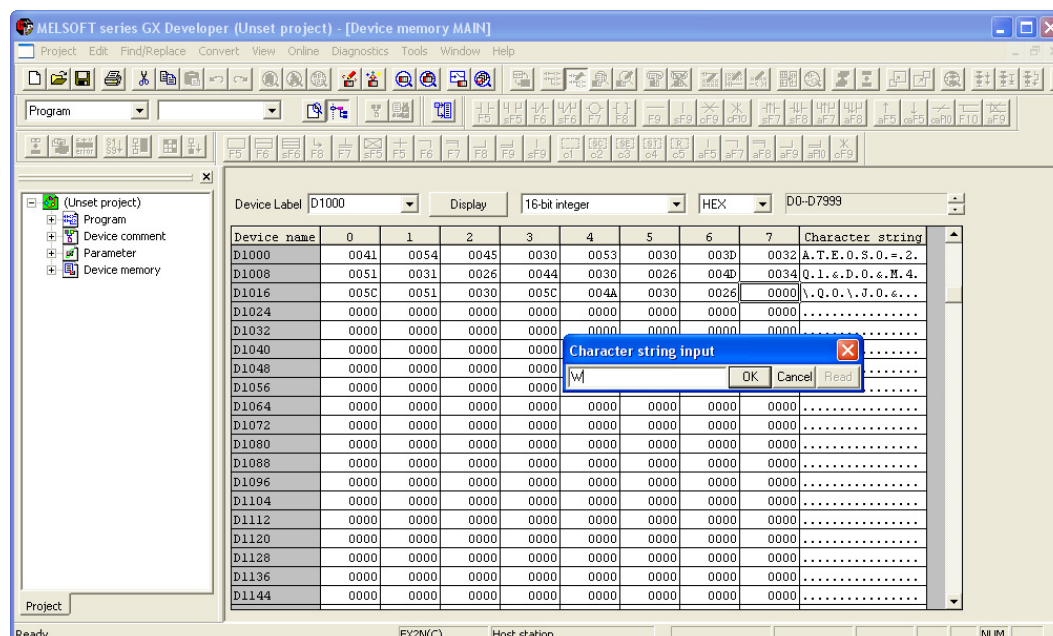


The device (data register) number to be set varies depending on the FX Series as shown below:

| FX Series | Device range |
|----------------|----------------|
| FX3U/FX3UC PLC | D1000 to D1059 |
| FX2N/FX2NC PLC | D1000 to D1059 |
| FX1N/FX1NC PLC | D1000 to D1059 |
| FX1S PLC | D200 to D255 |

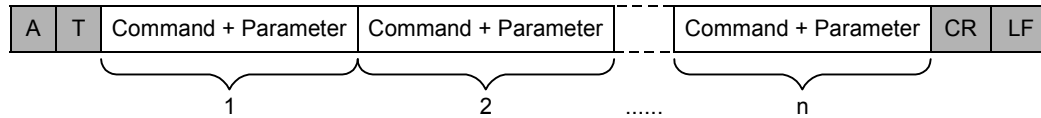
4 Inputting the AT command

Input the AT command to D1000 (D200 For FX1S PLC) and later. Input one character to one word. Double-click the data register to be input to display the "Character string input" dialog box. Input one (half-width) character, and click the [OK] button.



1. AT command structure

For initializing a modem, use the AT command developed by Hayes.
The Hayes AT command is generally expressed in the following format:



For details on the AT command, refer to the manual of the modem to be used.

2. Input example of the AT command for initialization, Example: ATE0S0 = 2Q1&D0&M4\Q0\J0&W

| Data register No. | ASCII code | Hexadecimal value |
|-------------------|------------|-------------------|
| D1000 | A | 41 |
| D1001 | T | 54 |
| D1002 | E | 45 |
| D1003 | 0 | 30 |
| D1004 | S | 53 |
| D1005 | 0 | 30 |
| D1006 | = | 3D |
| D1007 | 2 | 32 |
| D1008 | Q | 51 |
| D1009 | 1 | 31 |
| D1010 | & | 26 |
| D1011 | D | 44 |
| D1012 | 0 | 30 |

| Data register No. | ASCII code | Hexadecimal value |
|-------------------|------------|-------------------|
| D1013 | & | 26 |
| D1014 | M | 4D |
| D1015 | 4 | 34 |
| D1016 | \ | 5C |
| D1017 | Q | 51 |
| D1018 | 0 | 30 |
| D1019 | \ | 5C |
| D1020 | J | 4A |
| D1021 | 0 | 30 |
| D1022 | & | 26 |
| D1023 | W | 57 |
| D1024 | CR | 0D |
| D1025 | LF | 0A |

5 Inputting "CR" and "LF"

It is necessary to input "CR" and "LF" at the end of the AT command.
Input "000D" and "000A" (hexadecimal values) to data registers respectively.

Device Label

| Device name | 0 | 1 | 2 | 3 |
|-------------|------|------|------|------|
| D1000 | 0041 | 0054 | 0045 | 0030 |
| D1008 | 0051 | 0031 | 0026 | 0044 |
| D1016 | 005C | 0051 | 0030 | 005C |
| D1024 | 000D | 000A | 0000 | 0000 |
| D1032 | 0000 | 0000 | 0000 | 0000 |
| D1040 | 0000 | 0000 | 0000 | 0000 |

If "CR (0DH)" and "LF (0AH)" are not input at the end of the AT command, remote maintenance is not possible.

5.2 Setting Using FXGP/WIN

This section explains the modem initialization setting and communication setting methods.

5.2.1 Setting communication by way of RS-232C port

It is not necessary to set the serial communication with a modem.

However, it is necessary to verify that another communication type is not used and whether the communication setting is correct using the following procedure.

In FX PLCs, the communication setting can be executed using either of the following two methods:

- 1) Writing the value "0" to the data register D8120 using a sequence program
If another communication type is already set for another application, delete the sequence program which writes a value to D8120.
- 2) Setting parameters using a sequence programming tool
By using the following procedure, verify that the communication setting is not provided.

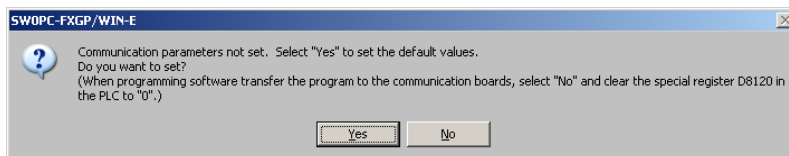
1 Checking the serial setting (parameter)

Select [Option]-[Serial setting (parameter)] from the toolbar.

The following dialog box appears according to absence/presence of parameter setting.

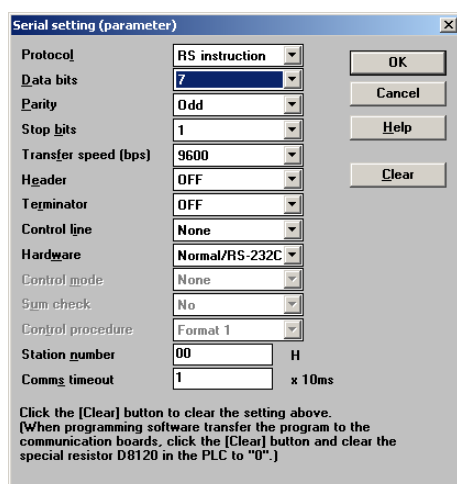
1. When there is no parameter setting

The dialog box shown below appears to indicate that there is no communication setting.
Click the [No] button.



2. When there are already parameter settings

The dialog box shown below appears to indicate that the communication setting is being used.
Click the [Clear] button.



5.2.2 Modem initialization setting using parameter method

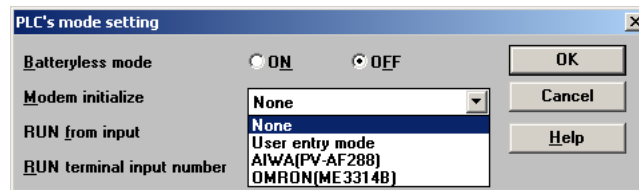
This subsection explains how to select the AT command for initialization registered in advance in the PLC and how to set the AT command for an unregistered modem.

1 Setting the PLC mode

Click [Option] - [PLC's mode setting] from the toolbar.

2 Selecting the modem initialization method

Select a modem to be connected in "Modem initialize", and click the [OK] button.



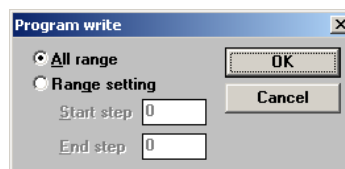
| Set item | Description | Modem model name | Manufacturer |
|-----------------|---|--------------------|--------------|
| None | Select this item when remote maintenance is not used. | — | — |
| User entry mode | Select this item when the modem to be used is not registered. | Unregistered modem | — |
| AIWA(PV-AF288) | Select corresponding item when either modem is to be used. | PV-AF288 | AIWA |
| OMRON(ME3314B) | | ME3314B | OMRON |

3 Setting the AT command for an unregistered modem

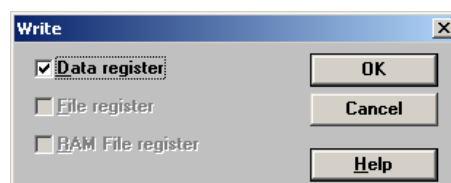
When "User entry mode" is selected in "Modem initialize", the AT command setting is required. For the AT command setting method for unregistered modems, refer to Subsection 5.2.3. The AT command setting is not required when "AIWA(PV-AF288)" or "OMRON(ME3314B)" is selected.

4 Writing the program to the PLC

Click [PLC] - [Transfers] - [Write] from the toolbar to display the "Program write" dialog box. Select "All range", and click the [OK] button.



When the AT command is set for an unregistered modem, transfer the register also. Click [PLC] - [Register data transfers] - [Write] from the toolbar to display the "Write" dialog box. Place a check mark (✓) next to "Data register", and click the [OK] button.

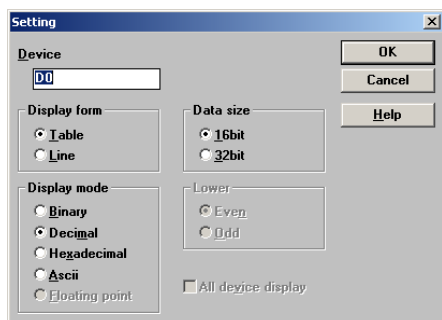


5.2.3 Setting AT command for unregistered modem

Only when "User entry mode" is selected in "Modem initialize", execute the following setting.
(The modem initialization setting depends on the setting contents of the window displayed when [Option] - [PLC's mode setting] is selected from the toolbar.)

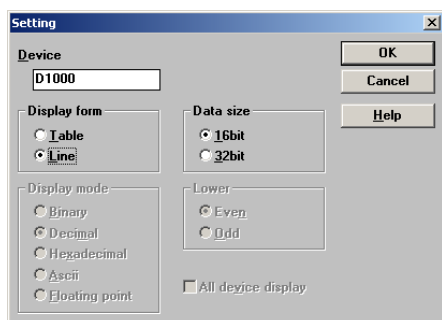
1 Displaying the device list

Select [View] - [Register view] from the toolbar.



2 Executing the display setting

Select the set items as shown in the table below, and click the [OK] button.



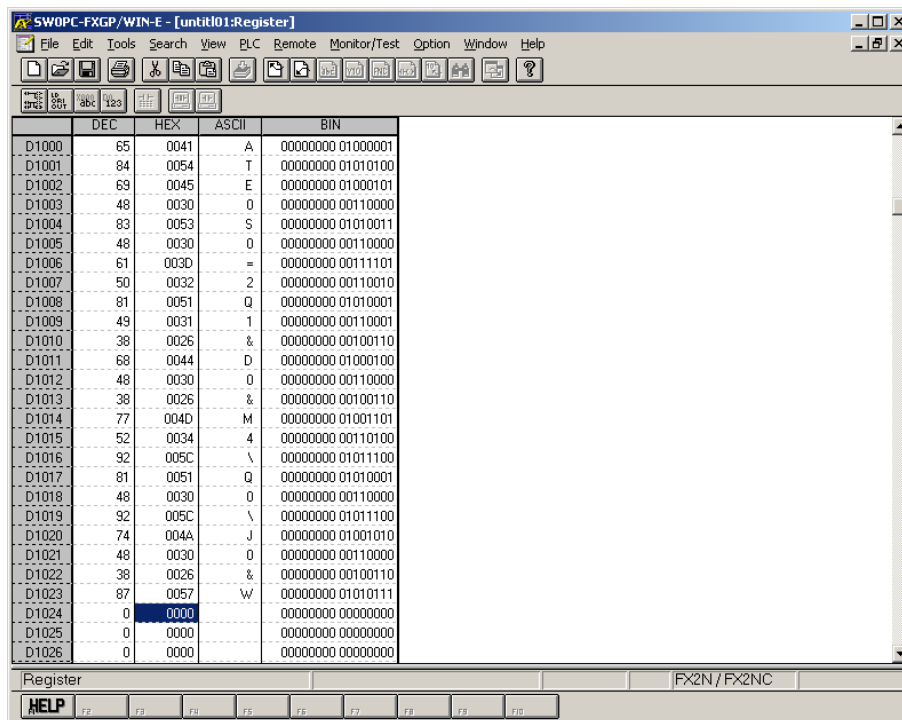
| Item | Contents of setting |
|--------------|---------------------|
| Display form | Line |
| Data size | 16bit |

The device (data register) number to be set varies depending on the FX Series as shown below:

| FX Series | Device range |
|----------------|----------------|
| FX3U/FX3UC PLC | D1000 to D1059 |
| FX2N/FX2NC PLC | D1000 to D1059 |
| FX1N/FX1NC PLC | D1000 to D1059 |
| FX1S PLC | D200 to D255 |

3 Inputting the AT command

Input the AT command to the "ASCII" column of D1000 and later. Input one (half-width) character to one word.



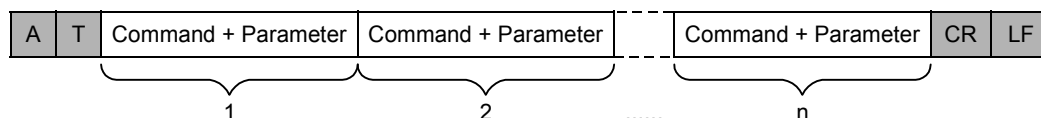
Make sure to input "CR (0DH)" and "LF (0AH)" at the end of the AT command. If they are not input, remote maintenance is not possible.

The "CR" and "LF" input method is explained in the next step.

1. AT command structure

For initializing a modem, use the AT command developed by Hayes.

The Hayes AT command is generally expressed in the following format:



For details on the AT command, refer to the manual of the modem to be used.

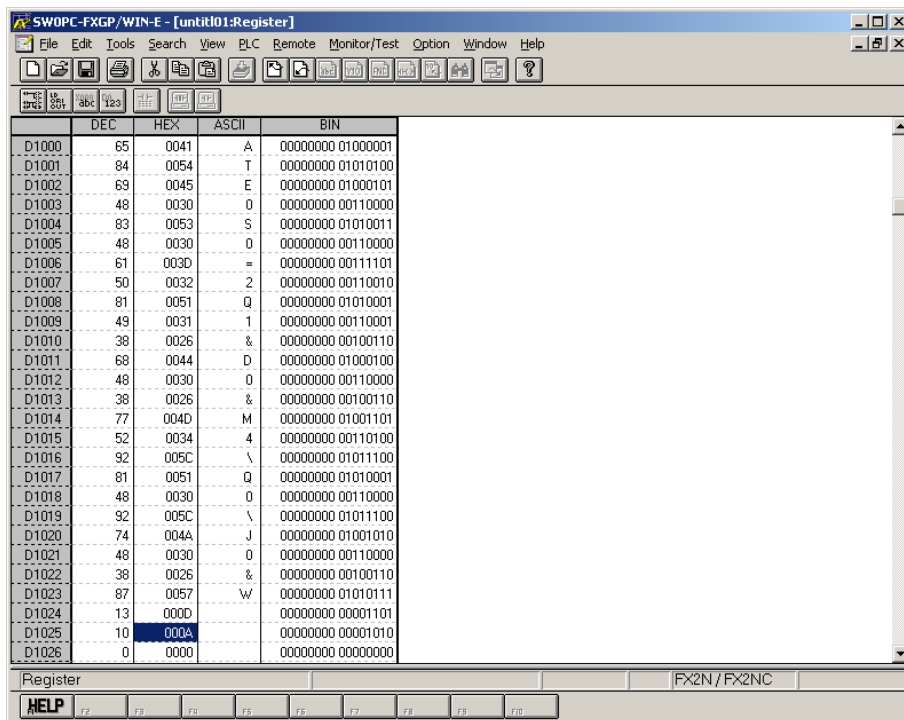
2. Input example of the AT command for initialization, Example: ATE0S0 = 2Q1&D0&M4\Q0\J0&W

| Data register No. | ASCII code | Hexadecimal value |
|-------------------|------------|-------------------|
| D1000 | A | 41 |
| D1001 | T | 54 |
| D1002 | E | 45 |
| D1003 | 0 | 30 |
| D1004 | S | 53 |
| D1005 | 0 | 30 |
| D1006 | = | 3D |
| D1007 | 2 | 32 |
| D1008 | Q | 51 |
| D1009 | 1 | 31 |
| D1010 | & | 26 |
| D1011 | D | 44 |
| D1012 | 0 | 30 |

| Data register No. | ASCII code | Hexadecimal value |
|-------------------|------------|-------------------|
| D1013 | & | 26 |
| D1014 | M | 4D |
| D1015 | 4 | 34 |
| D1016 | \ | 5C |
| D1017 | Q | 51 |
| D1018 | 0 | 30 |
| D1019 | \ | 5C |
| D1020 | J | 4A |
| D1021 | 0 | 30 |
| D1022 | & | 26 |
| D1023 | W | 57 |
| D1024 | CR | 0D |
| D1025 | LF | 0A |

4 Inputting "CR" and "LF"

It is necessary to input "CR" and "LF" at the end of the AT command.
Input "000D" and "000A" (hexadecimal values) to data registers respectively.



If "CR (0DH)" and "LF (0AH)" are not input at the end of the AT command, remote maintenance is disabled.

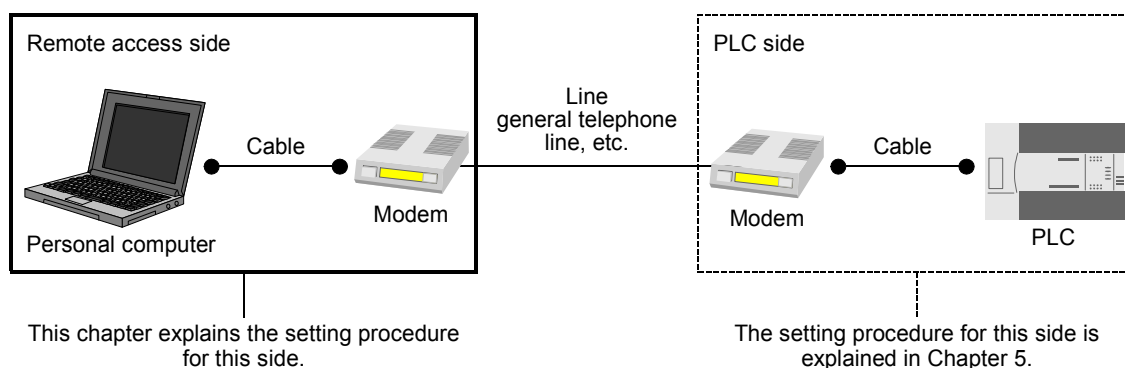
5.3 Cautions on Use

1. Cautions on inputting the AT command for initialization to the PLC

- 1) The AT command finishes sending when "0" (hexadecimal value) is read.
- 2) When creating a sequence program, make sure that the input area for the modem initialization command is different from the data register area used by general sequence programs.
- 3) Make sure to input "CR (0DH)" and "LF (0AH)" at the end of the AT command. If they are not input, remote maintenance is disabled.

6. How to Setup Modems on the Personal Computer Side for Remote Access

This chapter explains how to set a modem connected to the personal computer for remote access. The setting method using GX Developer and the setting method using FXGP/WIN are explained respectively.
 → For applicable programming tools, refer to Subsection 1.4.2.



6.1 Setting Using GX Developer

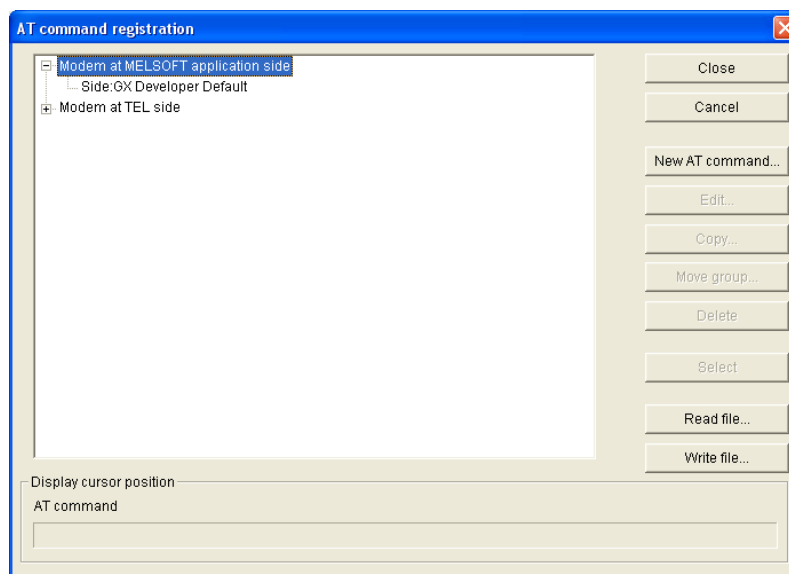
This section explains the line connection setting method using GX Developer.

6.1.1 Registering AT command for connected modem

This subsection explains how to register the AT command for initializing a modem connected to the personal computer.

1 Setting the AT command

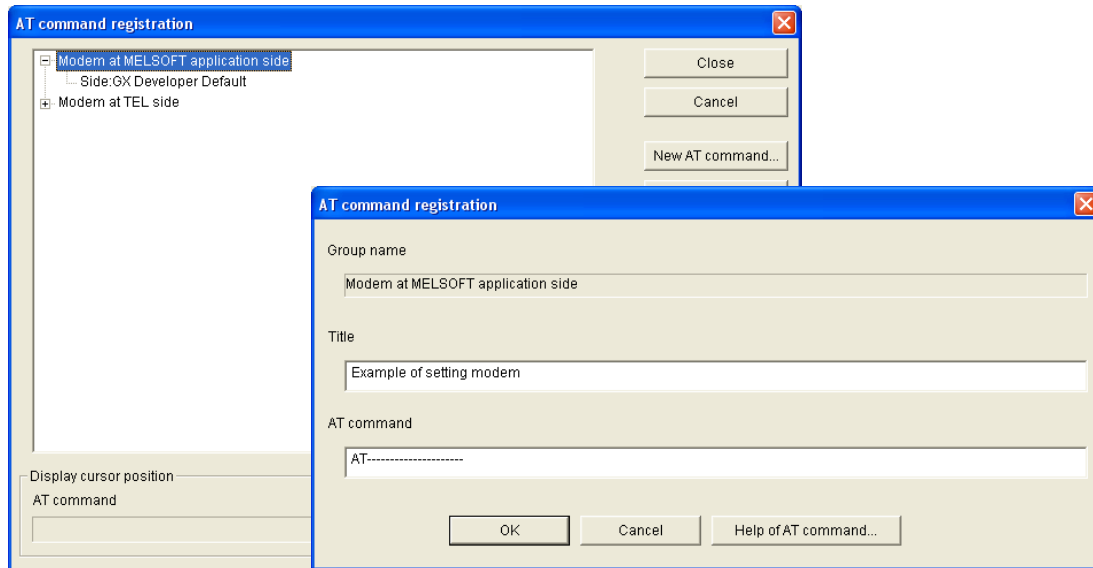
Select [Tools] - [Set TEL data] - [AT command registration] from the toolbar to display the following dialog box.



2 Registering the AT command for the connected modem

Select "Modem at MELSOFT application side" in the tree, and click the [New AT command] button.
Input "Title" and "AT command," and click the [OK] button.

- Input a name easy to understand such as the modem model name to "Title."
- Input "AT command" while referring to the description below.



1. In the case of a modem whose operation is confirmed

For such a modem, input the following AT command.

| Modem manufacturer name | Modem model name | AT command set value | Remarks |
|-------------------------|------------------|--|-------------------------------|
| AIWA | PV-BF5606 | ATE0S0=2&K0&D0 | |
| OMRON | ME5614E | ATE0S0=2&K0&D0 | Modem version: F/W Ver. 2.300 |
| OMRON | ME5614D | ATE0S0=2&K0&D0 | Modem version: F/W Ver. 2.300 |
| NTT DoCoMo | 96F1 | ATQ0V1E1S0=0 (former than SW3) | |
| NTT DoCoMo | 96F2 | ATQ0V1E1 (former than SW3) ATQ0V1E1\Q1 (SW4 or later) | |

2. In the case of any other modem (whose operation is not confirmed)

Click the [Help of ATcommand] button.

Refer to the contents of the help and the manual of the connected modem, create the AT command.

3. Contents of help for the AT command

The table below shows the contents of description about [Help of ATcommand].

Setting example: AT&C1Q0V1N3&D0&K0

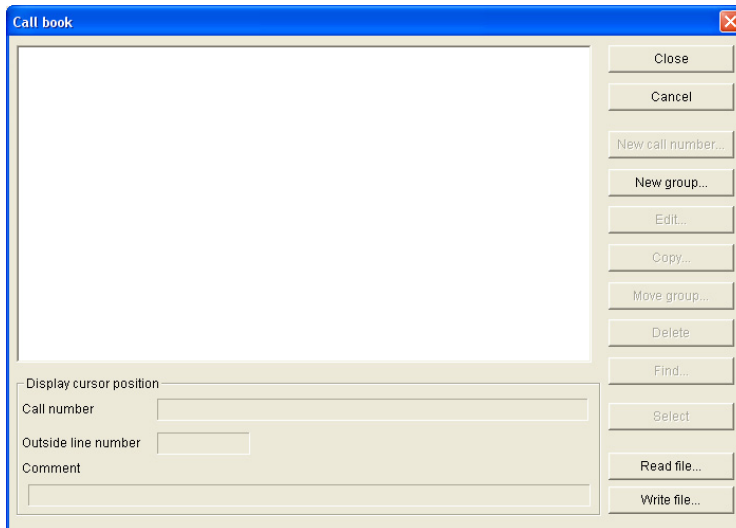
| AT command | Description |
|---------------------|--|
| AT&Cn | Set the mode in which the CD signal is set to ON when the carrier from the counterpart is received. |
| ATQn | Set the AT command so that the result code for the AT command is sent back. |
| ATVn | Set the AT command so that the response to the AT command is given in a character string. |
| AT\Nn | The MNP automatic selection mode is recommended. When the MNP block size is a set item, "128 bytes maximum per block" is general. When the MNP automatic selection mode cannot be specified, specify the direct mode in the asynchronous communication mode. |
| AT&Dn | Set the ER signal to "normally ON." |
| AT&Kn (AT&Hn&In&Rn) | Set "no flow control." |
| AT&Xn | When a converter is used, set "no dial tone." It is not necessary to set this item when a converter is not used. |

6.1.2 Creating telephone directory (if necessary)

This subsection explains the method to register the telephone number of the counterpart (line connected to the modem of the desired PLC).

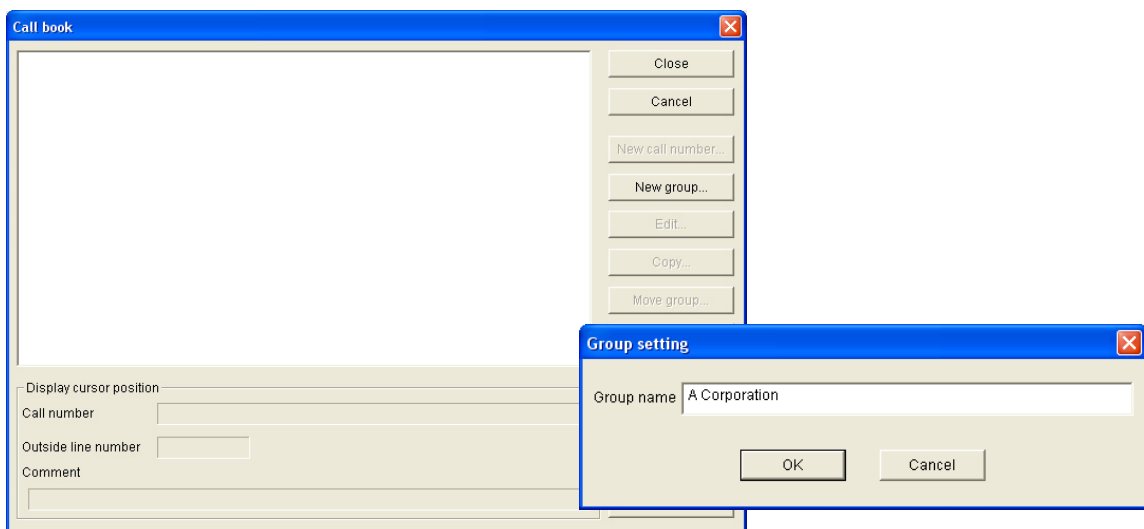
1 Displaying the telephone directory dialog box

Select [Tools] - [Set TEL data] - [Call book] from the toolbar to display the following dialog box.



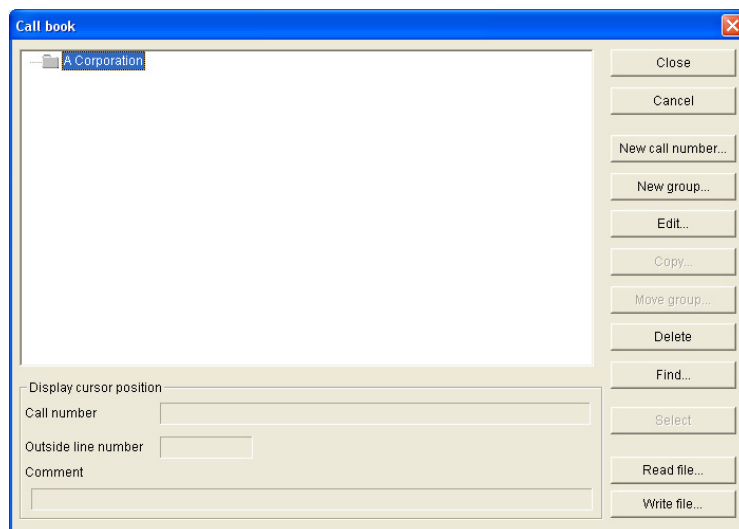
2 Creating the group name

Click the [New group] button to display the "Group setting" dialog box. Input a group name (example: A Corporation) to which the telephone numbers belong, and click the [OK] button.



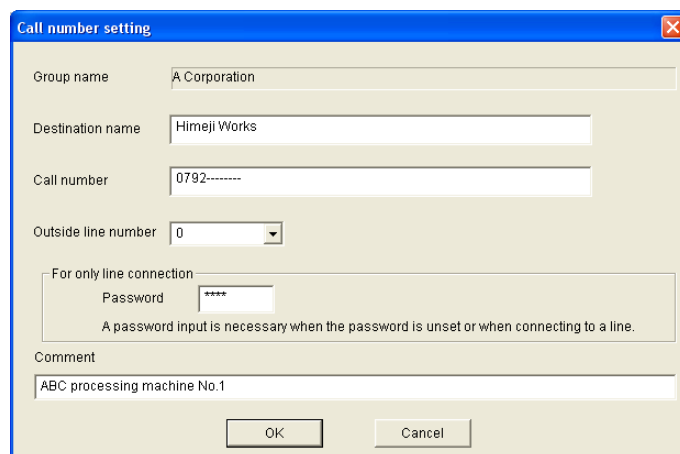
3 Selecting a group name to which the counterpart telephone number will be registered

Click and select an already created group name (example: A Corporation).
Click the [New call number] button.



4 Inputting the name, telephone number, etc.

Input required items, and click [OK].
If there is another counterpart to be registered, repeat from step 2 above.



→ For details, refer to the "GX Developer Operating Manual."

6.2 Setting Using FXGP/WIN

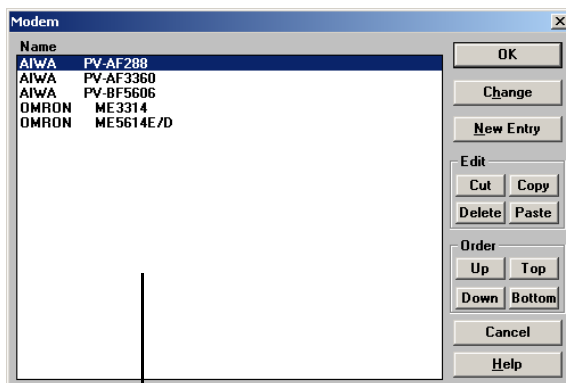
This section explains the line connection method using FXGP/WIN.

6.2.1 Registering AT command for connected modem

This subsection explains how to register the AT command for initializing a modem connected to the personal computer for remote access.

1 Setting the AT command

Select [Remote] - [Environment] - [Modem] from the toolbar to display the following dialog box.



Registered modems are displayed.

2 Registering the AT command for the connected modem

1. When the connected modem is shown in the list

Select the modem model name, and click the [OK] button.

→ Proceed to step 4.

2. When the connected modem is not shown in the list

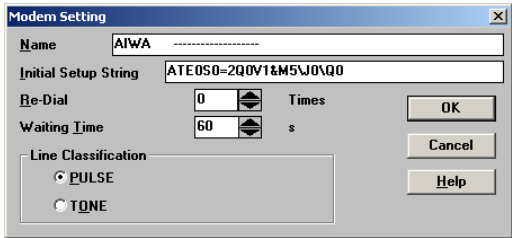
It is necessary to create the AT command for the modem, and register it.

→ Proceed to step 3.

3 Newly creating the AT command for the modem

Click the [New Entry] button.
Input "Name" and "Initial Setup String," and then click the [OK] button.

- To "Name," input a name easy to understand such as the modem model name.
- To "Initial Setup String," input proper contents while referring to the description below.



Input the AT command while referring to the description below.

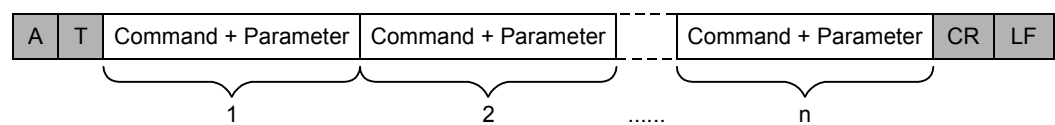
1. In the case of a modem whose operation is confirmed

For a modem whose operation is confirmed, input the following AT command:

| Modem manufacturer | Modem model name | AT command set value |
|--------------------|------------------|-------------------------|
| AIWA | PV-AF288 | ATE0S0=2Q0V1&M4\J0\Q0 |
| AIWA | PV-AF3360 | ATE0S0=2Q0V1S15=8&H0&R1 |
| AIWA | PV-BF5606 | ATE0S0=2&K |
| OMRON | ME3314B | ATE0S0=2Q0V1S15=8&H0&R1 |
| OMRON | ME5614E | ATE0S0=2&K0W0 |
| OMRON | ME5614D | ATE0S0=2&K0W0 |
| NTT DoCoMo | 96F1 | ATQ0V1E1S0=0 |
| NTT DoCoMo | 96F2 | ATQ0V1E1 |

2. AT command structure

For initializing a modem, use the AT command developed by Hayes.
The Hayes AT command is generally expressed in the following format:



For details on the AT command, refer to the manual of the modem to be used.

3. Setting contents of the AT command

When the PLC power is turned ON, the PLC sends the AT command to the modem to initialize the modem. For reference, the table below shows the set items and setting contents of the AT commands for modems which are registered in advance in FXGP/WIN.

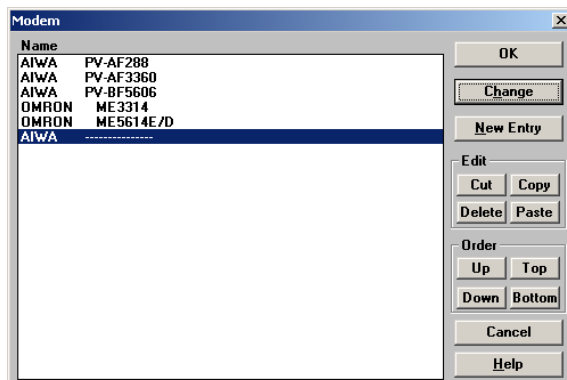
The set items and setting contents may vary depending on each modem. For actual setting contents, refer to the manual of the modem to be used.

| Set item | PV-AF288 (AIWA) | PV-AF3360 (AIWA) | ME3314B (OMRON) |
|---|--|-----------------------|-------------------------|
| | ATE0S0=2Q0V1&M4\J0\Q0 | ATE0S0=2Q0V1&M4\J0\Q0 | ATE0S0=2Q0V1S15=8&H0&R1 |
| Command echo | E0 (not provided) | E0 (not provided) | E0 (not provided) |
| Number of times of calling in automatic receiving | S0 = 2 (twice) | S0 = 2 (twice) | S0 = 2 (twice) |
| Result code display | Q0 (provided) | Q0 (provided) | Q0 (provided) |
| Result code format | V1 (character, word) | V1 (character, word) | V1 (character, word) |
| Communication mode | &M4 (MNP automatic) | &M4 (MNP automatic) | S15 = 8 (V. 42 bis) |
| Terminal speed fixing mode | \J0 (fixed) | \J0 (fixed) | — |
| Send data flow control | — | — | &H0 (not provided) |
| Terminal flow control method | \Q0 (not provided) | \Q0 (not provided) | &R1 (not provided) |
| Initialization to values set in factory before delivery | &F (FXGP/WIN sends "AT&F", and then sends the AT command above.) | | |

4

Displaying the selected modem

Verify that the desired modem is set, and click the [OK] button.



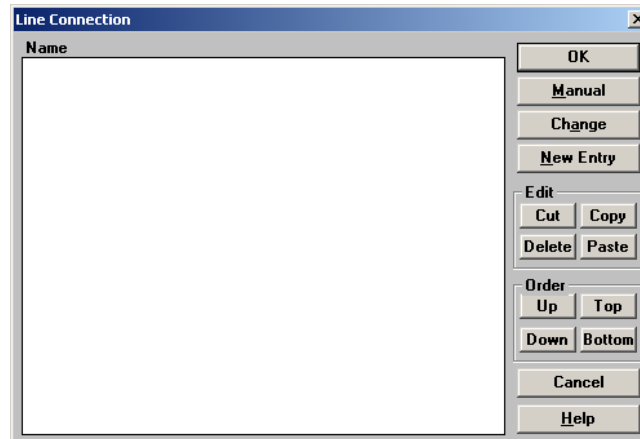
On this window, a newly registered modem is selected.

6.2.2 Registering line connection destination

This subsection explains how to register the telephone number of the line connection destination (line connected to the modem of the desired PLC).

1 Displaying the line connection dialog box

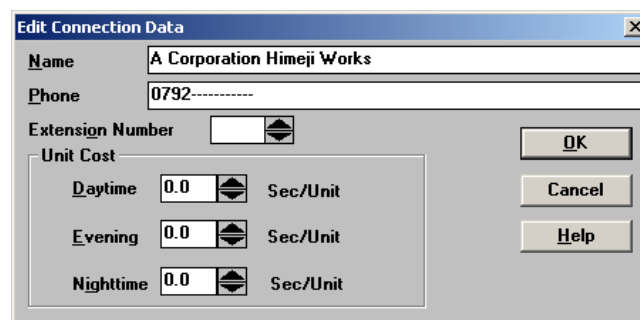
Select [Remote] - [Connect] - [to PLC] from the toolbar to display the following dialog box.



2 Inputting the telephone number of the line connection destination

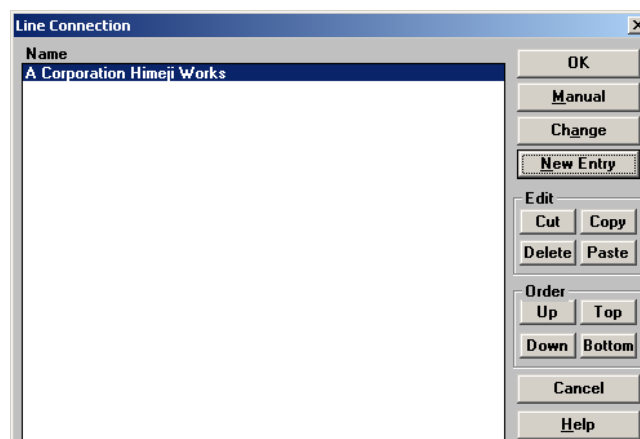
Click the [New Entry] button.

When the following dialog box appears, input the counterpart name and telephone number.



3 Registering the line connection destination

After inputting the telephone number, click the [OK] button to register it.



→ For details on set items, refer to the manual of FXGP/WIN.

7. Connecting Line

This chapter explains the line connection procedure for remote maintenance.

7.1 Preparing for Connection of PLC

For remote maintenance, it is necessary to properly establish the modem-to-PLC connection. Set the PLC using the following procedure.

1 Setting initialization for the modem on the PLC side

Set the AT command for the modem to be connected to the PLC.

→ For details, refer to Chapter 6.

2 Turning OFF the PLC power

After inputting the AT command to the PLC, turn OFF the PLC power.

3 Connecting the modem

Connect the communication equipment of the PLC to the modem.

→ For details, refer to Chapter 4.

4 Turning ON the modem power

Turn ON the modem power connected to the PLC.

5 Turning ON the PLC power

After turning ON the power to the modem, turn ON the PLC power.

When the PLC power is turned ON, the TXD (SD) and RXD (RD) LEDs light instantaneously in the optional communication equipment operating in accordance with RS-232C, and the AT command is sent to the modem.

→ If these LEDs do not light, refer "Chapter 8. Troubleshooting".

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS485 Instructio)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

7.2 Line Connection Procedure

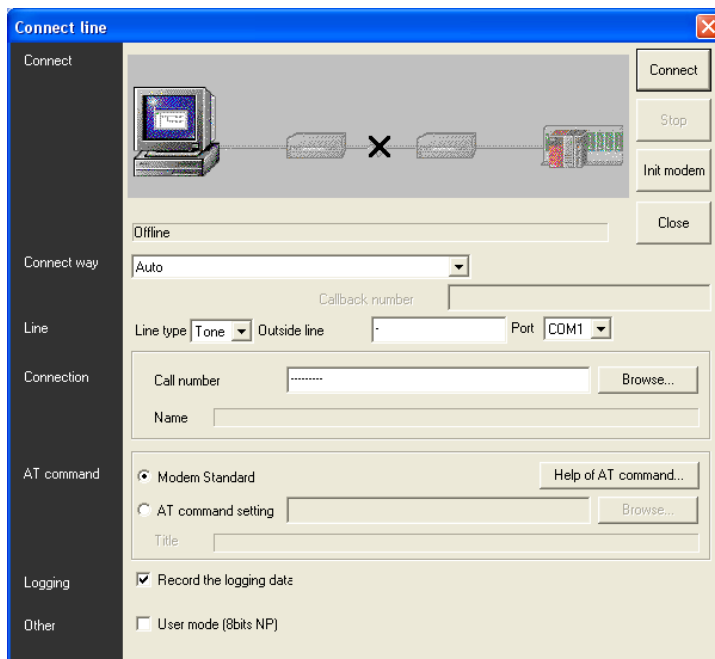
This section explains the procedure to connect a personal computer to a PLC using a telephone line. The connection procedure varies depending on the software used. Connect a telephone line suitable to the software used.

7.2.1 For GX Developer

This subsection explains the line connection procedure using GX Developer. Prepare for connection of the PLC, connect a modem to the communication port in the personal computer, and start up GX Developer.

1 Setting the line connection

Select [Tools] - [Set TEL data] - [Connect line] from the toolbar to display the following dialog box.



The line connection status is displayed.

2 Setting the connection method

Select "Auto".

3 Setting the line

Set each item as follows:

1. Line type

Set the type of line connected to the modem.

- In the case of general telephone, select the contracted line type (tone, pulse or ISDN).
- In the case of cellular phone, select "Tone".

2. Outside line

Set this item if necessary for making phone calls to outside lines.

3. Port

Select the communication port number in the personal computer connected to the modem.

4 Setting the connection destination

Set the telephone number of the counterpart (line number of the modem connected to the desired PLC).

When a telephone number has been set in advance in the telephone directory, it can be set using the [Browse] button.

→ For details on the telephone directory, refer to Subsection 6.1.2.

5 Setting the AT command

Set the AT command for the modem connected to the personal computer. When the AT command has been registered in advance, it can be set using the [Browse] button.

→ For details on the AT command registration, refer to Subsection 6.1.1.

6 Placing a check mark (✓) next to "Record the logging data"

Put a check mark here when storing the log at the line connection to a file.

The log at the line connection is recorded in the following log file:

- Storage destination: GX Developer installation destination\log (default: Melsec\Gppw\log)
- Log file name: Date.log (example: 980929.log)

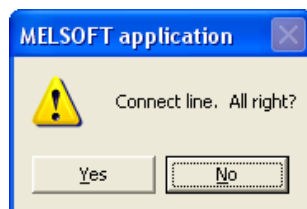
7 Setting others

When "User mode (8bits NP) (CH1)" or "User mode (8bits NP) (CH2)" is selected in "Init modem", place a check mark (✓) next to "User mode (8bits NP)".

8 Connecting the line

Click the [Connect] button to display the following dialog box.

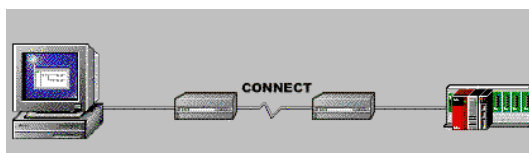
Click the [Yes] button to execute line connection and make a call from the modem connected to the personal computer.



9 Checking the line connection status

1. When the line is connected

When the line is connected, the connection status shown below is displayed on the line connection dialog box.



A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

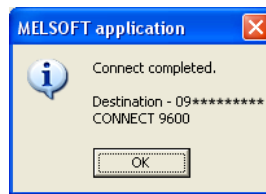
I

Remote Maintenance

Apx.

Discontinued models

When connection is completed, the following dialog box appears to indicate the telephone number of the connection destination and the communication speed.

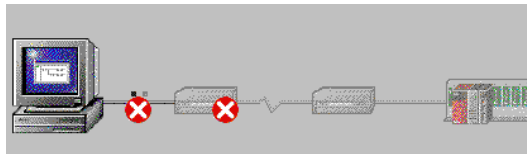


Confirm the contents, and click the [OK] button to close the dialog box.

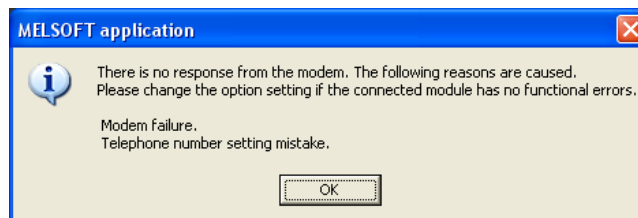
→ Proceed to step 10.

2. When the line cannot be connected

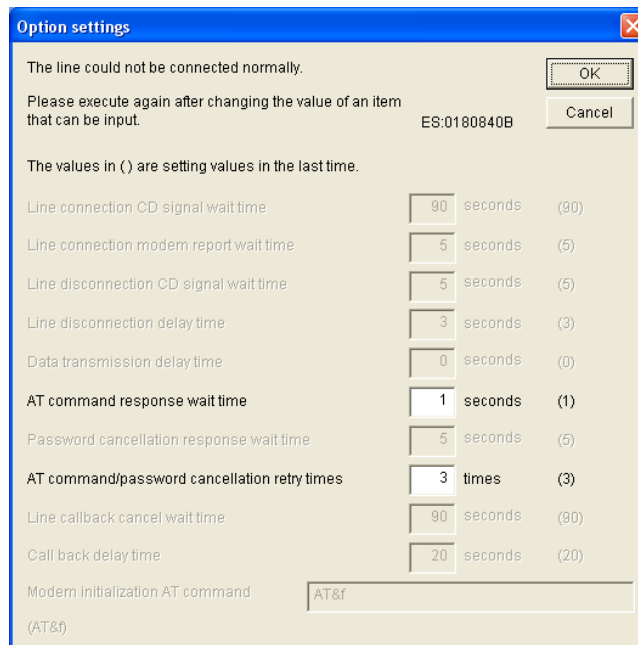
When the line cannot be connected, the following figure is displayed on the line connection dialog box.
(Example: When no response is given by the modem connected to the personal computer)



And the following dialog box appears.



Click the [OK] button to display the option settings dialog box.



Change the waiting time and number of retries, and then click the [OK] button to close the dialog box.
Check the telephone number and AT command, and then execute connection again.

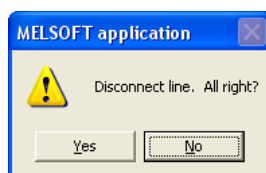
→ If line connection is disabled, refer to "Chapter 8. Troubleshooting".

10 Executing remote maintenance

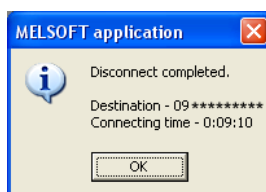
Read and write sequence programs, and monitor devices.

11 Disconnecting the line

To disconnect the line, select [Tools] - [Set TEL data] - [Disconnection] from the toolbar.
When the following dialog box appears, click the [Yes] button to disconnect the line.



When line disconnection is finished, the following dialog box appears to indicate the connection destination telephone number and line use time.



Click the [OK] button to close the dialog box.

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RSRS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

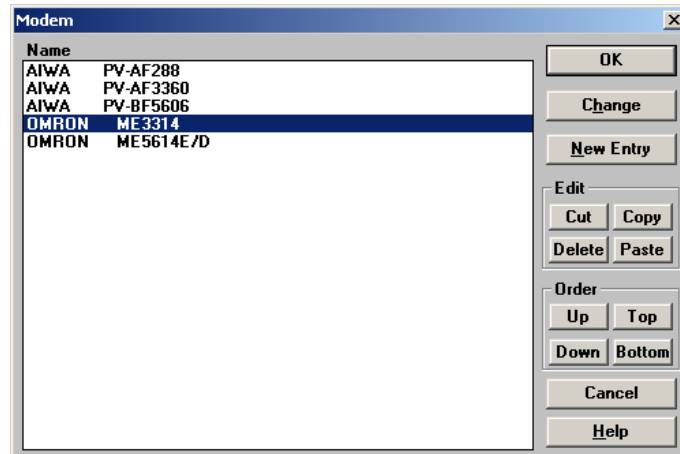
Discontinued models

7.2.2 For FXGP/WIN

This subsection explains the line connection procedure using FXGP/WIN. Prepare for connection of the PLC, connect a modem to the communication port in the personal computer, and then start up FXGP/WIN.

1 Setting the modem to be used

Select [Remote] - [Environment] - [Modem] from the toolbar to display the following dialog box.



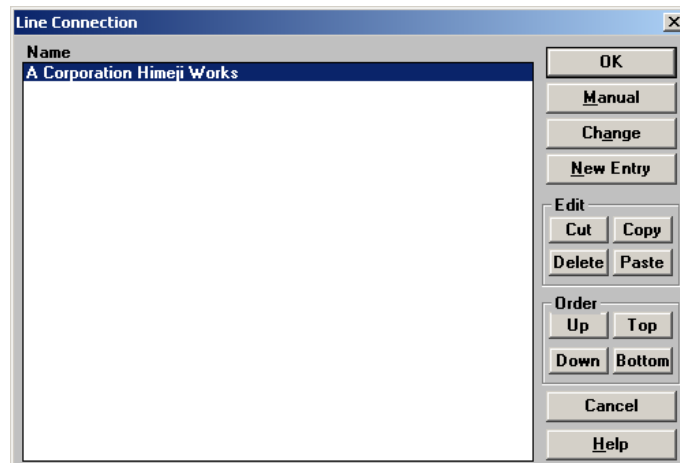
Select the modem to be used, and click the [OK] button.

If the modem to be used is not displayed, click the [New Entry] button, and register the AT command for the modem.

→ For details on AT command registration, refer to Subsection 6.2.1.

2 Connecting the connection destination

Select [Remote] - [Connect] - [to PLC] from the toolbar to display the following dialog box.



Select the connection destination, and click the [OK] button.

If the connection destination is not displayed, click the [New Entry] button, and register the connection destination.

→ For details on connection destination registration, refer to Subsection 6.2.2.

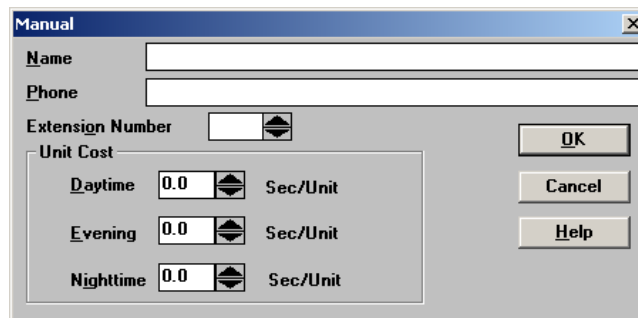
→ Proceed to step 4.

When directly setting a telephone number, click the [Manual] button.

→ Proceed to the next step.

3 Executing manual connection

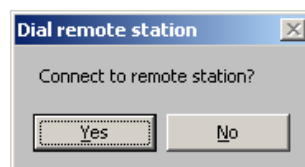
Click the [Manual] button to display the following dialog box.



Set "Name" and "Phone", and click the [OK] button.

4 Checking the line connection status

When the [OK] button is clicked, the following dialog box appears.

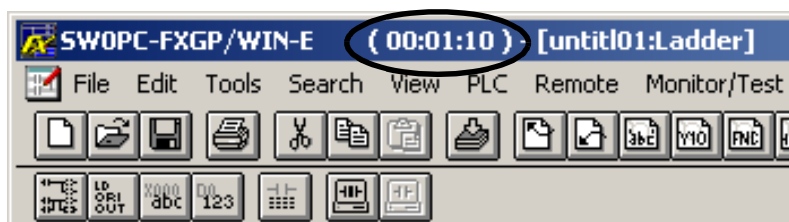


Click the [Yes] button to display the message box "Executing!" and make a call from the modem connected to the personal computer.

5 Checking the line connection status

1. When the line is connected

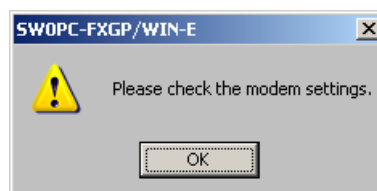
When connection is completed, the message box "Executing!" is closed, and the line connection time is displayed on the title bar as shown below:



→ Proceed to step 6.

2. When the line cannot be connected

When the line cannot be connected, the message box "Executing!" is closed, and the following dialog box appears.



Click the [OK] button to close the dialog box.

Check the telephone number and AT command, and then execute connection again.

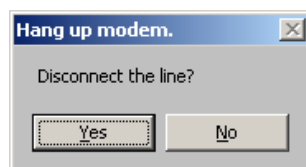
→ If line connection is disabled, refer to "Chapter 8. Troubleshooting".

6 Executing remote maintenance

Read and write sequence programs, and monitor devices.

7 Disconnecting the line

To disconnect the line, select [Remote] - [Disconnect] from the toolbar.
When the following dialog box appears, click the [Yes] button to disconnect the line.



When the line is disconnected, the line connection time on the title bar disappears.



8. Troubleshooting

This chapter explains troubleshooting.

8.1 Checking FX PLC Applicability

Verify that the FX PLC main unit version is applicable to remote maintenance.

→ **For the version applicability check, refer to Section 1.3.**

8.2 Checking Programming Tool Applicability

Verify that the programming tool version is applicable to remote maintenance.

→ **For the version applicability check, refer to Section 1.4.**

FXGP/WIN cannot use remote maintenance when it is used in the following Windows:

- Windows NT4.0
- Windows 2000
- Windows XP

8.3 Checking Communication Status Based on LED Indication

Check the status of the "RXD (RD)" and "TXD (SD)" indicator LEDs provided in the optional equipment

| LED status | | Operation status |
|------------|----------|------------------------------------|
| RXD (RD) | TXD (SD) | |
| Flashing | Flashing | Data is being sent or received. |
| Flashing | Off | Data is received, but is not sent. |
| Off | Flashing | Data is sent, but is not received |
| Off | Off | Data is not sent nor received. |

When the power is turned ON, the FX PLC transfers the AT command to the connected modem. At this time, the "RXD (RD)" and "TXD (SD)" indicator LEDs in the communication equipment light instantaneously. If modem initialization is not set in parameters in the FX PLC, however, these LEDs do not light. If the wiring and/or modem specifications are different, these LEDs flash several times, but the FX PLC does not transfer the AT command.

8.4 Checking Installation

1. Mounting status

If the communication equipment is not securely connected to the PLC, communication is not possible.

→ **For the mounting method, refer to the respective communication equipment manual.**

8.5 Checking Modem Specifications

In a modem in which the following communication specifications are not applicable, remote maintenance can be used.

Check the modem specifications.

1. In the case of user registration mode

| Item | Contents |
|----------------------|----------------------------------|
| Communication method | Half-duplex, asynchronous system |
| Baud rate | 9600 bps |
| Start bit | 1-bit |
| Data bit | 7-bit |
| Parity bit | Even |
| Stop bit | 1-bit |
| Control line | Not provided |

2. PP modem mode (ch1) and PP modem mode (ch2)

| Item | Contents |
|----------------------|----------------------------------|
| Communication method | Half-duplex, asynchronous system |
| Baud rate | 9600 bps |
| Start bit | 1-bit |
| Data bit | 8-bit |
| Parity bit | Not provided |
| Stop bit | 1-bit |
| Control line | Not provided |

8.6 Checking Setting in PLC

Check the parameters, AT command and sequence programs in the PLC.

After changing any parameters, make sure to turn OFF the PLC power, and then turn it ON again.

8.6.1 Checking parameters in PLC

1. Checking the communication setting

Verify that non-protocol communication, computer link communication, etc. are not set in the parameters of the FX PLC. If such communication is already set, remote maintenance cannot be used.

2. Checking the modem initialization setting

Verify that the modem initialization is selected correctly in parameters in the FX PLC.

If the modem initialization is not set correctly, normal communication is not possible.

→ For the parameter settings of the PLC, refer to Chapter 5.

8.6.2 Checking AT command setting

The AT command is required when "user registration mode", "PP modem mode (ch 1)" or "PP modem mode (ch 2)" is selected in the modem initialization setting. When such a mode is set, check the following contents.

1. Checking data registers

The head device number and device range of data registers used for setting the AT command vary depending on the FX Series.

Check the data register numbers in which the AT command is set.

| FX Series | Device range |
|----------------|----------------|
| FX3U/FX3UC PLC | D1000 to D1059 |
| FX2N/FX2NC PLC | D1000 to D1059 |
| FX1N/FX1NC PLC | D1000 to D1059 |
| FX1s PLC | D200 to D255 |

Use consecutive data registers from the head device number. If a numeric value is not set in a data register, the data registers after it are not transferred.

2. Checking the contents of the AT command

If the contents of the AT command are not correct, remote maintenance cannot be used.

Verify that the setting contents are correct.

As reference, the table below shows the set items and their contents of the AT commands already registered in PLCs.

| Set item | PV-AF288 (AIWA) ATE0S0 = 2Q1&D0&M5\Q0\J0&W | ME3314B (OMRON) ATE0S0 = 2Q1&D0&H0&R1S15=8&W |
|---|---|---|
| Command echo | E0 (not provided) | E0 (not provided) |
| Number of times of calling in automatic receiving | S0 = 2 (twice) | S0 = 2 (twice) |
| Result code display | Q1 (not provided) | Q1 (not provided) |
| DTR control | &D (normally ON) | &D (normally ON) |
| Communication mode | &M5 (V. 42 bis) | S15 = 8 (V. 42 bis) |
| Terminal flow control method | \Q0 (not provided) | &R1 (not provided) |
| Send data flow control | — | &H0 (not provided) |
| Terminal speed fixing mode | \J0 (fixed) | — |
| Writing to nonvolatile memory | &W | &W |

3. Checking "CR (H0D)" and "LF (H0A)"

Make sure to input "CR (H0D)" and "LF (H0A)" at the end of the AT command. If they are not input, the AT command cannot be transferred.

→ For the AT command setting for the PLC, refer to Chapter 5.

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (RS485 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

8.6.3 Checking sequence program

1. Checking the contents of the communication setting

Verify that no communication format (D8120, N:N Network: D8176 to D8180, and Parallel Link: M8070 and M8071) is being used in the sequence program.

If any communication format is being used in the sequence program, communication will not function correctly.

2. Presence of VRRD and VRSC instructions (except FX3U and FX3UC PLCs)

Verify that the VRRD and VRSC instructions are not used in the program.

If these instructions are used, delete them, turn OFF the PLC power, and then turn it ON again.

3. Presence of RS instruction (except FX3U and FX3UC PLCs)

Verify that the RS instruction is not used in the program.

If this instruction is used, delete it, turn OFF the PLC power, and then turn it ON again.

4. Presence of RS and RS2 instructions (in FX3U and FX3UC PLCs)

Verify that the RS and RS2 instructions are not being used for the same channel.

If these instructions are used for the same channel, revise them, turn OFF the PLC power, and then turn it ON again.

5. Presence of EXTR instruction (in FX2N and FX2NC PLCs)

Verify that the EXTR instruction is not used in the program.

If this instruction is used, delete it, turn OFF the PLC power, and then turn it ON again.

6. Presence of IVCK, IVDR, IVRD, IVWR, and IVBWR instructions (in FX3U and FX3UC PLCs)

Verify that the IVCK, IVDR, IVRD, IVWR and IVBWR instructions are not being used for the same channel.

If these instructions are used for the same channel, revise them, turn OFF the PLC power, and then turn it ON again.

8.7 Checking Programming Tool Setting

Verify that the setting contents in the programming tool are correct.

1. Checking the telephone number

Verify that the telephone number of the connection destination is set correctly.

2. Checking the AT command setting

Verify that the AT command is set correctly for the registered modem.

3. Checking the communication port

Verify that the communication port connected to the modem is set correctly.

→ For the programming tool setting, refer to Chapter 6.

8.8 Checking Absence/Presence of Errors

In FX3U and FX3UC Series, an error occurs when modem initialization is not possible.
Verify that an error has not occurred.

1. Checking M8063

When a communication error occurs, M8063 turns ON and D8063 stores the corresponding error code.

2. Checking the error code

D8063 stores one of the following error codes:

| | Error code | Contents of error |
|-------|------------|--|
| D8063 | 6301 | Parity error, overrun error or framing error |
| | 6302 | Defective communication character |
| | 6303 | Communication data sum mismatch |
| | 6304 | Defective data format |
| | 6305 | Defective command |
| | 6306 | Monitoring timeout |
| | 6307 | Modem initialization error |
| | 6308 | N:N Network parameter error |
| | 6312 | Parallel link character error |
| | 6313 | Parallel link sum error |
| | 6314 | Parallel link format error |
| | 6320 | Error in communication with inverter |

When modem initialization is disabled, D8063 stores the error code 6307.
If D8063 stores any error code shown above, check the following items:

- Wiring
- Modem specifications

A

Common Items

B

N:N Network

C

Parallel Link

D

Computer Link

E

Inverter Communication

F

Non-Protocol Communication (RS/RSS2 Instruction)

G

Non-Protocol Communication (FX2N-232IF)

H

Programming Communication

I

Remote Maintenance

Apx.

Discontinued models

9. Related Information

9.1 ASCII Code Table

1. ASCII code table (7-bit code expressed in hexadecimal)

| Hexadecimal | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|-------------|-----|-----|----|---|---|-----|---|-----|
| 0 | | DLE | SP | 0 | @ | P | ` | p |
| 1 | SOH | DC1 | ! | 1 | A | Q | a | q |
| 2 | STX | DC2 | " | 2 | B | R | b | r |
| 3 | ETX | DC3 | # | 3 | C | S | c | s |
| 4 | EOT | DC4 | \$ | 4 | D | T | d | t |
| 5 | ENQ | NAK | % | 5 | E | U | e | u |
| 6 | ACK | SYN | & | 6 | F | V | f | v |
| 7 | BEL | ETB | ' | 7 | G | W | g | w |
| 8 | BS | CAN | (| 8 | H | X | h | x |
| 9 | HT | EM |) | 9 | I | Y | i | y |
| A | LF | SUB | * | : | J | Z | j | z |
| B | VT | ESC | + | ; | K | [| k | { |
| C | FF | FS | , | < | L | *1 | l | |
| D | CR | GS | - | = | M |] | m | } |
| E | SO | RS | . | > | N | ^ | n | ~ |
| F | SI | US | / | ? | O | _ | o | DEL |

*1. \ (ASCII CODE:5C) symbol is displayed as "¥" in Japanese.

2. Examples of ASCII codes

| Decimal | ASCII (hexadecimal) |
|---------|------------------------|
| 0 | 30 |
| 1 | 31 |
| 2 | 32 |
| 3 | 33 |
| 4 | 34 |
| 5 | 35 |
| 6 | 36 |
| 7 | 37 |
| 8 | 38 |
| 9 | 39 |
| | |
| | |
| | |

| Symbol | ASCII (hexadecimal) |
|--------|------------------------|
| # | 23 |
| & | 26 |
| = | 3D |
| *1 | 5C |
| | |

| Alphabet | ASCII (hexadecimal) | Alphabet | ASCII (hexadecimal) |
|----------|------------------------|----------|------------------------|
| A | 41 | N | 4E |
| B | 42 | O | 4F |
| C | 43 | P | 50 |
| D | 44 | Q | 51 |
| E | 45 | R | 52 |
| F | 46 | S | 53 |
| G | 47 | T | 54 |
| H | 48 | U | 55 |
| I | 49 | V | 56 |
| J | 4A | W | 57 |
| K | 4B | K | 58 |
| L | 4C | Y | 59 |
| M | 4D | Z | 5A |

| Code | ASCII (hexadecimal) |
|------|------------------------|
| STX | 02 |
| ETX | 03 |
| LF | 0A |
| CR | 0D |
| | |
| | |
| | |
| | |
| | |
| | |

*1. \ (ASCII CODE:5C) symbol is displayed as "¥" in Japanese.

Appendix A: Discontinued models

The table below shows discontinued models of MELSEC-F Series PLCs and programming tools described in this manual.

| Discontinued model | Production stop date | Repair acceptance period |
|--------------------|----------------------|--------------------------|
| FX1 | June 30, 2002 | Until June 30, 2009 |
| FX2(FX) | June 30, 2002 | Until June 30, 2009 |
| FX2C | June 30, 2002 | Until June 30, 2009 |
| FX0 | June 30, 2002 | Until June 30, 2009 |
| FX0S | January 31, 2006 | Until January 31, 2013 |
| FX0N | January 31, 2006 | Until January 31, 2013 |
| FX-232ADP | June 30, 2002 | Until June 30, 2009 |
| FX-485ADP | June 30, 2002 | Until June 30, 2009 |
| FX2-40AW | June 30, 2002 | Until June 30, 2009 |
| FX2-40AP | June 30, 2002 | Until June 30, 2009 |
| FX0N-485ADP | January 31, 2006 | Until January 31, 2013 |
| FX0N-232ADP | January 31, 2006 | Until January 31, 2013 |
| FX-232AW | September 30, 2004 | Until September 30, 2011 |
| FX-232AWC | June 30, 2004 | Until June 30, 2011 |
| FX-232DOPA | April 30, 2006 | Until April 30, 2013 |
| FX-25DU | September 30, 2002 | Until September 30, 2009 |
| FX-30DU(-B) | September 30, 2002 | Until September 30, 2009 |
| FX-40DU(-B) | September 30, 2002 | Until September 30, 2009 |
| FX-40DU-TK(B) | September 30, 2002 | Until September 30, 2009 |
| FX-50DU-TK(S) | September 30, 2002 | Until September 30, 2009 |

A
Common Items

B
N:N Network

C
Parallel Link

D
Computer Link

E
Inverter Communication

F
Non-Protocol Communication (FS/R52 Instruction)

G
Non-Protocol Communication (FX2N-232IF)

H
Programming Communication

I
Remote Maintenance

Apx.
Discontinued models

MEMO

Warranty

Please confirm the following product warranty details before using this product.

1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company. However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing on-site that involves replacement of the failed module.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place. Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- 1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- 2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 - a) Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 - b) Failure caused by unapproved modifications, etc., to the product by the user.
 - c) When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 - d) Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 - e) Relay failure or output contact failure caused by usage beyond the specified Life of contact (cycles).
 - f) Failure caused by external irresistible forces such as fires or abnormal voltages, and Failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 - g) Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 - h) Anyother failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

2. Onerous repair term after discontinuation of production

- 1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued.
Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- 2) Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user or third person by Failures of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

6. Product application

- 1) In using the Mitsubishi MELSEC programmable logic controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable logic controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- 2) The Mitsubishi programmable logic controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for Railway companies or Public service purposes shall be excluded from the programmable logic controller applications.
In addition, applications in which human life or property that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices, manned transportation, equipment for recreation and amusement, and safety devices, shall also be excluded from the programmable logic controller range of applications.
However, in certain cases, some applications may be possible, providing the user consults their local Mitsubishi representative outlining the special requirements of the project, and providing that all parties concerned agree to the special circumstances, solely at the users discretion.

USER'S MANUAL - Data Communication Edition

FX SERIES PROGRAMMABLE CONTROLLERS



HEAD OFFICE: TOKYO BUILDING, 2-7-3 MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN
HIMEJI WORKS: 840, CHIYODA CHO, HIMEJI, JAPAN

| | |
|------------|--------------|
| MODEL | FX-U-COMMU-E |
| MODEL CODE | 09R715 |